#### Model validation

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### Outline

- Normal distribution
- Linear models ...

## Recap

Recall:

$$y_i = \alpha + \mathbf{x}_i \boldsymbol{\beta} + \boldsymbol{\epsilon}_i \sim \mathcal{N}(0, \sigma^2)$$

- ▶ the systematic component: the regression line
- ▶ the random component: leftover stuff

### Models make assumptions

Our models make assumptions. Sometimes, these are realistic.

All models are wrong, but some are useful

Is is important to:

- Know which assumptions your model makes
- Assess if they are realistic
- Determine if they are violated

#### Tests make assumptions too

But more on that later

### Linear regression assumptions

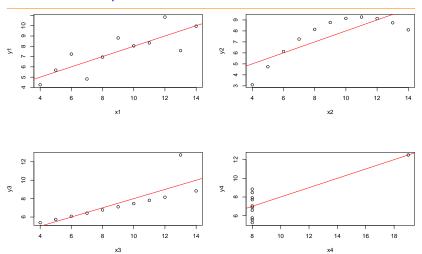
$$y_i = \alpha + \sum_{k=1}^p x_{ik} \beta_k + \epsilon_i \sim \mathcal{N}(0, \sigma^2)$$

- Linearity
- Normality: normally distributed errors
- Homoscedastcity: same variance for all errors
- Independence of errors
- $\blacktriangleright$  Lack of perfect multicollinearity  $(\mathbf{x}_1 
  eq \mathbf{x}_2)$
- No outliers
- No error in the explanatory variables

- Linearity: Eek
- Normality: cannot trust tests and confidence intervals
- Homoscedasticity: cannot trust tests and confidence intervals
- Independence of errors: Eek
- Lack of perfect multicollinearity
- No outliers: biased parameter estimates



### Anscombe's quartet



All of these regressions have the same parameter estimates

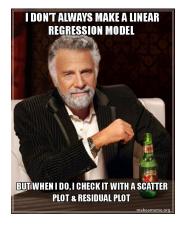
### Assumption checking: methods

#### Tests:

- Score test for non-constant error variance car::ncvTest
- Durbin-Watson test for Autocorrelated errors car::durbinWatsonTest
- Bonferroni outlier test car::outlierTest
- Shapiro-Wilk normality test shapiro.est

#### Rather: Residual plots

- plot(model)
- Various packages (e.g., car or DHARMa)



#### Errors vs. Residuals

The true model:

$$y_i = \alpha + \sum_{k=1}^{p} x_{ik} \beta_k + \epsilon_i \sim \mathcal{N}(0, \sigma^2)$$

The fitted model:

$$y_i = \hat{\alpha} + \sum_{k=1}^{P} x_{ik} \hat{\beta}_k + \hat{\epsilon}_i$$

$$\begin{aligned} & \blacktriangleright \ \epsilon_i = y_i - \alpha - \sum_{i=1}^n x_{ik} \beta \\ & \blacktriangleright \ \hat{\epsilon}_i = y_i - \hat{\alpha} - \sum_{i=1}^n x_{ik} \hat{\beta} \end{aligned}$$

Residuals are the **observed** deviation from the regression line.

In R

```
model \leftarrow lm(y~x)
residuals(model) # estimated random part
fitted(model) # estimated systematic part
```

### Standardised residuals

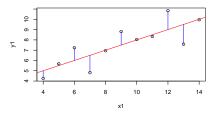
$$\frac{\hat{\epsilon_i}}{s\sqrt{1-h_i}}, \qquad \text{where } h_i \text{ is "influence"} \tag{1}$$

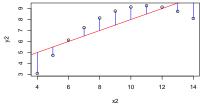
#### Studentized residuals

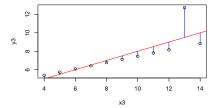
- omit observation i
- re-compute residual variance
- calculate standardised residual (with hat matrix)

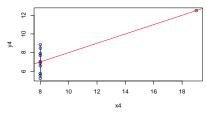
rstand or rstudent

# Anscombe's quartet









### Residual plots

Residual plots should have no discernible patterns.

- No curvature.
- No shapes whatsoever
- No outliers
- No change in variance

This can be difficult with few observations.

- Residuals versus fitted:  $\hat{\epsilon}_i \ vs. \ \hat{\mu}_i$
- Observed versus theoretical quantiles:

$$Pr(X \leq y_i) \ vs. \ Pr(X \leq x)$$

- lackbox Cook's distance plot:  $\hat{\epsilon}_i \ vs. \ \hat{\mu}_i$
- Standardized residuals vs. fitted (Scale-location)
- Leverage and influence

### Leverage: hat matrix

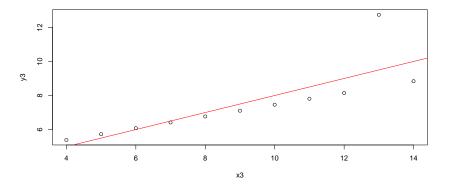
$$\hat{\mu}_i = \hat{\alpha} - \sum_{i=1}^n x_{ik} \hat{\beta}$$

but we can also write:

$$\hat{\mu} = \mathbf{H}\mathbf{y}$$

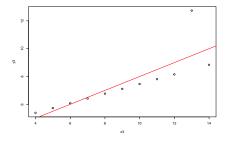
- H is the "hat" matrix
- $\blacktriangleright \ \mathbf{H} = \mathbf{X} (\mathbf{X}^{\top} \mathbf{X})^{-1} \mathbf{X}^{\top} \mathbf{y}$
- lacktriangle Its diagonal gives "leverage" and is between 0 and 1
- Leverage: observation that is far from others on the explanatory variable

### Influence



An observation that has undue impact on the regression line.

#### **Outliers**



- Outliers are observations far away from the regression line
- Can be erroneous
- Might be real data
- Remove with caution
- Better: sensitivity analysis

#### Cook's distance

Cook's distance: how much the fitted values change if we remove an observation

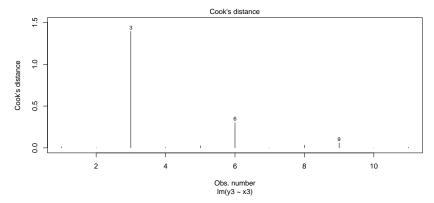
$$D_j = \frac{\sum_{i=1}^n (\hat{y}_i - \hat{y}_{i(-j)})^2}{\sigma^2}$$

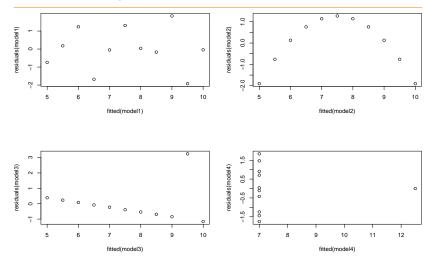
- $ightharpoonup \hat{y}_i$  prediction
- $m{\hat{y}}_{i(-j)}$  prediction for model with data point j removed
- $ightharpoonup \sigma^2$  residual variance

#### What is influential?

Large values of  $D_i$  mean a large influence

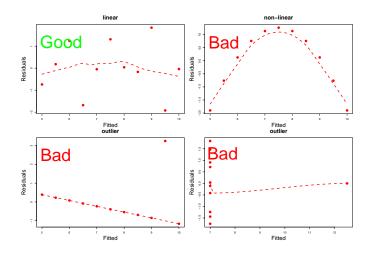
Usually  $D_i>1$ , or 4/n



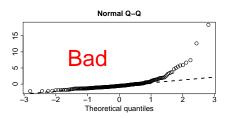


What do you see?

## Residual diagnostics: residuals vs. fitted

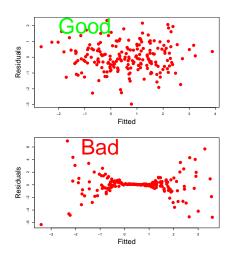






- 1. compare residuals to theoretical quantiles
- 2. points should follow the line

### Residual diagnostics: constant variance



- 1. compare residuals to fitted
- points should be randomly distributed

### Addressing assumption violations

- Curvature? Add quadratic term
- Outlier? Sensitivity analysis (if not error)
- Normality? GLM
- Constant variance? GLM

Alternative: data transformation

#### Data transformation

$$\mathbb{E}\{\mathsf{h}(y_i)|x_i\} = \alpha + \beta x_i \tag{2}$$

- $ightharpoonup h(\cdot)$  data transformation (e.g.  $\sqrt(\cdot)$  or  $\log(\cdot)$ )
- To stabilize variance
- To normalize residuals

#### Use a Generalised linear model instead

### Summary

Now we have a valid model, we can check **how** good it is (more on that tomorrow)