



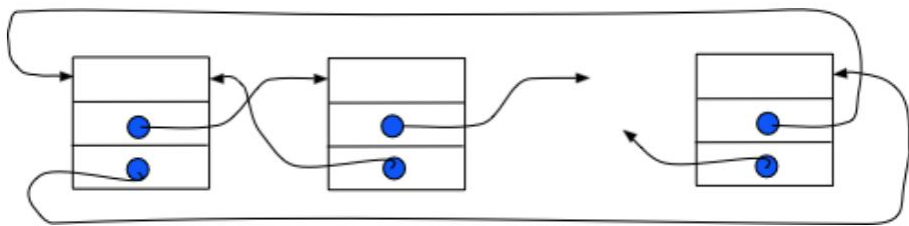
UNIVERSITY OF  
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# CS225 Review

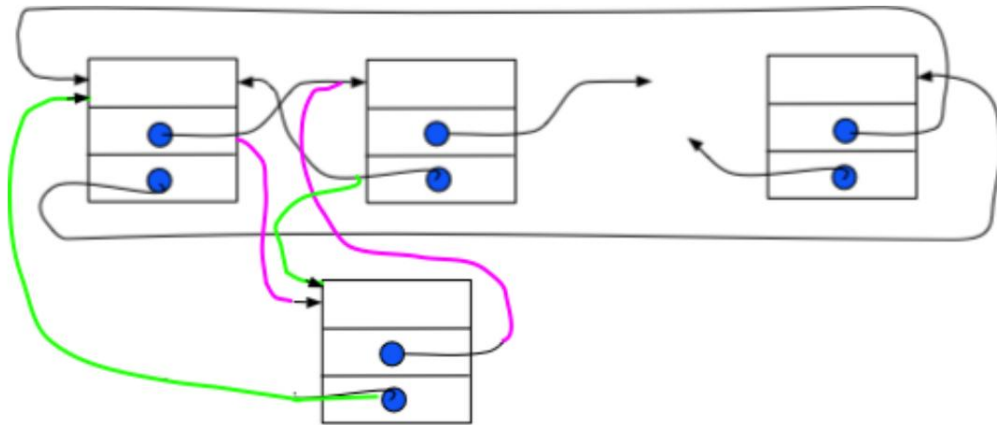
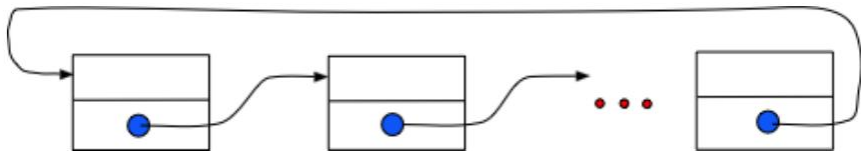
2023/05/29

constructor default value 只在头文件  
出现 default value custom constructor 就不能有 default constructor

Doubly linked list:



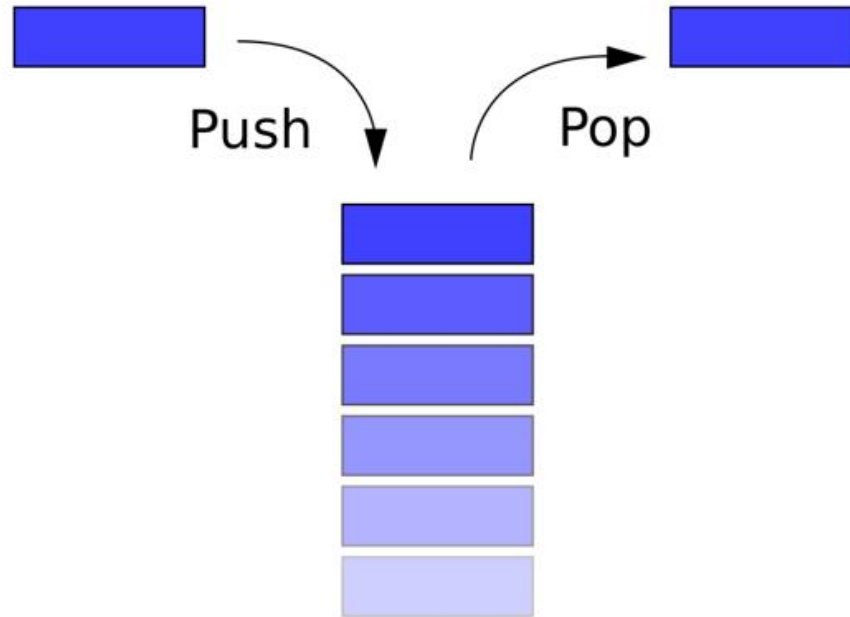
Singly linked list:

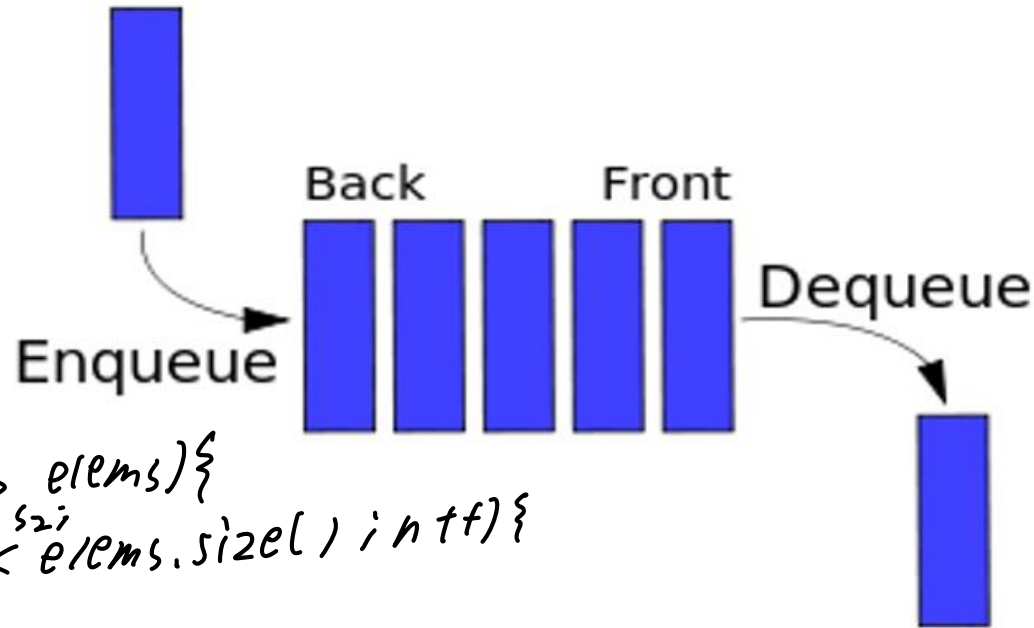


```
template<class T>
class LinkedList {
private:
    class listNode{
    public:
        listNode():next(NULL){}
        T data;
        listNode * next;
    };
    listNode * head;
public:
    // constructors, destructor, and other member functions
    ...
    void reverse();
};
```

Analyze the running time of the function `reverse()`. You should state the **worst-case time complexity** of your code when operating on a list with  $n$  nodes and briefly explain why it would take that much time.

$O(n)$





```

FIFO(vector<int> elems){
    stack<int> s1, s2;
    for (n=0; n < elems.size(); n++) {
        s1.push(elems[n]);
    }
    FIFO_helper(s1, s2);
}

FIFO_helper(stack<int> &s1, stack<int> &s2) {
    if (s1.empty()) return;
    s2.push(s1.top());
    s1.pop();
    FIFO_helper(s1, s2);
}
    
```

$e_1 = s_1.top();$

$s_2.push(e_1)$

$\wedge$

$s_1.pop();$

$\text{FIFO\_helper}(s_1, s_2);$

$s_1.push(e_1);$

}

Explain how to implement a FIFO queue using two stacks so that each FIFO operation takes amortised constant time.

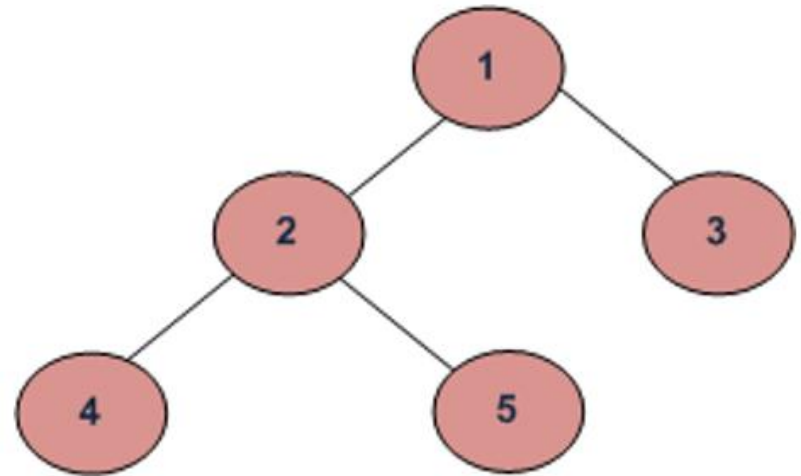
## Tree Traversals (Inorder, Preorder and Postorder)

Unlike linear data structures (Array, Linked List, Queues, Stacks, etc) which have only one logical way to traverse them, trees can be traversed in different ways.

(a) Inorder (Left, root, Right) : 4 2 5 1 3

(b) Preorder (root, Left, Right) : 1 2 4 5 3

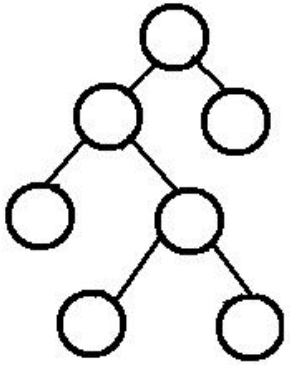
(c) Postorder (Left, Right, Root) : 4 5 2 3 1



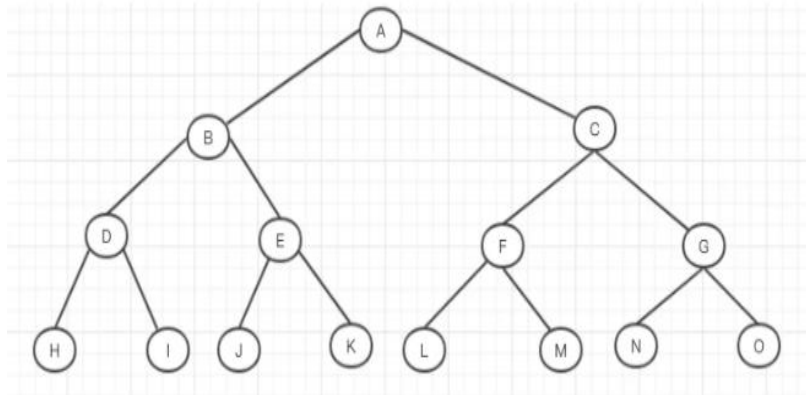
# Tree Definition



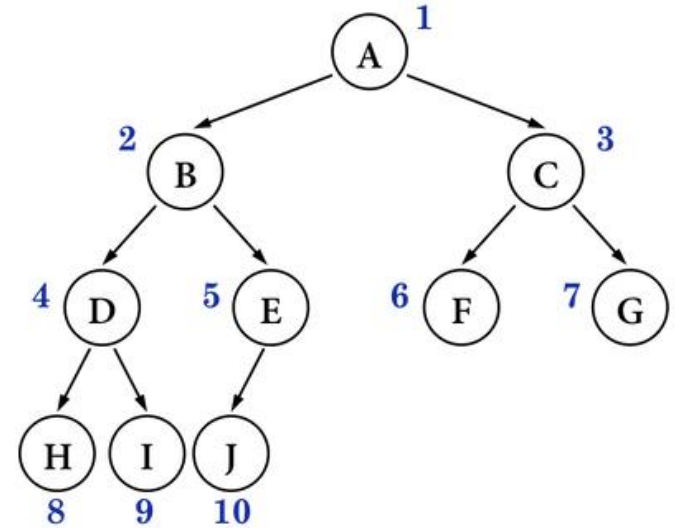
full binary tree



perfect binary tree

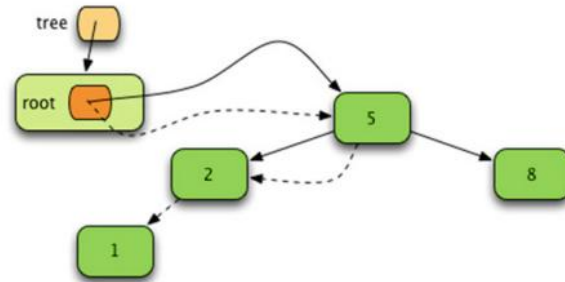


complete binary tree

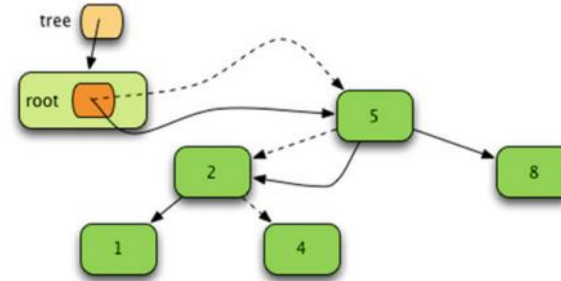




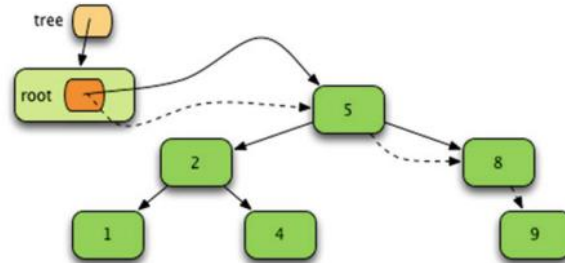
BST after insertion of 1



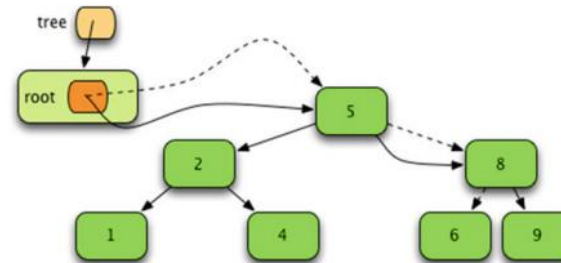
BST after insertion of 4

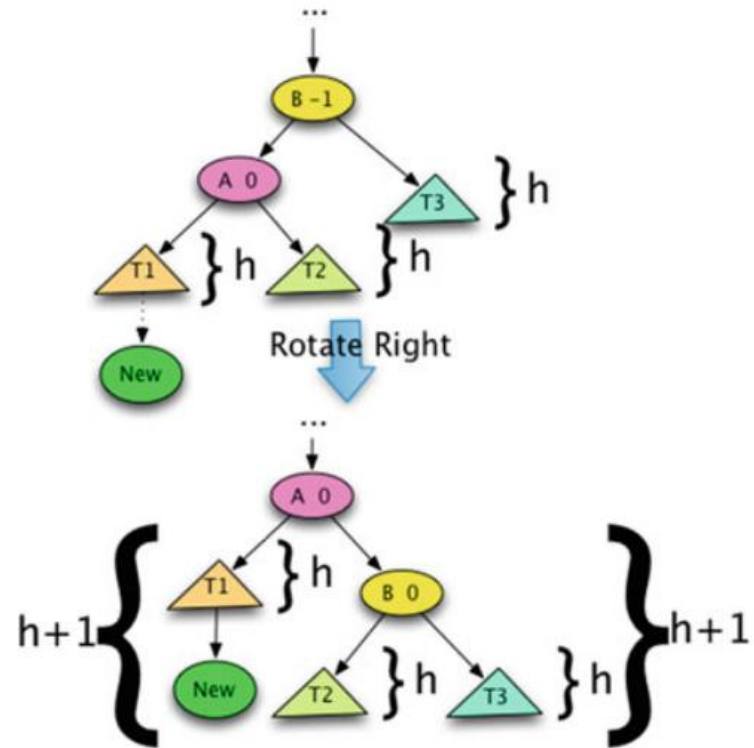
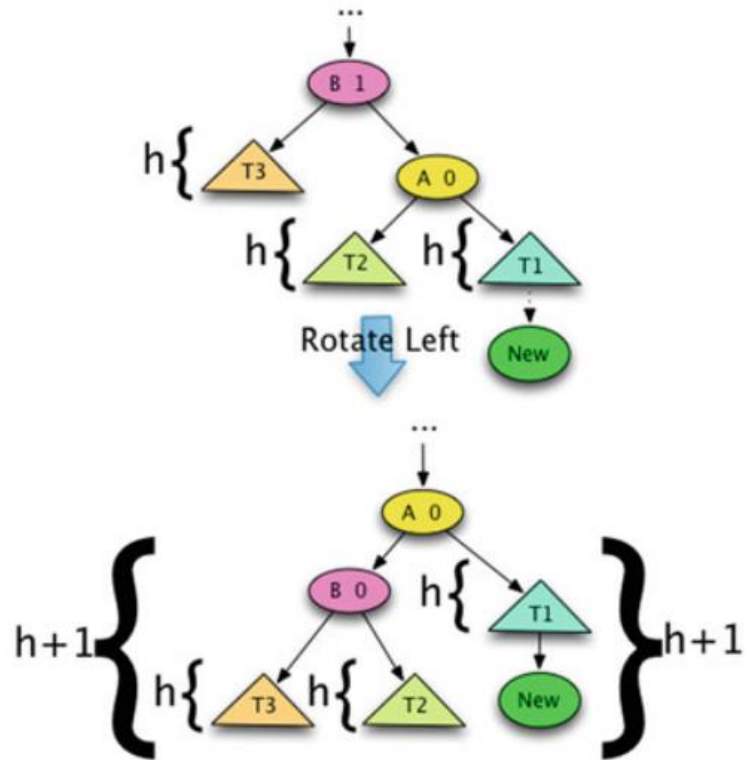


BST after insertion of 9



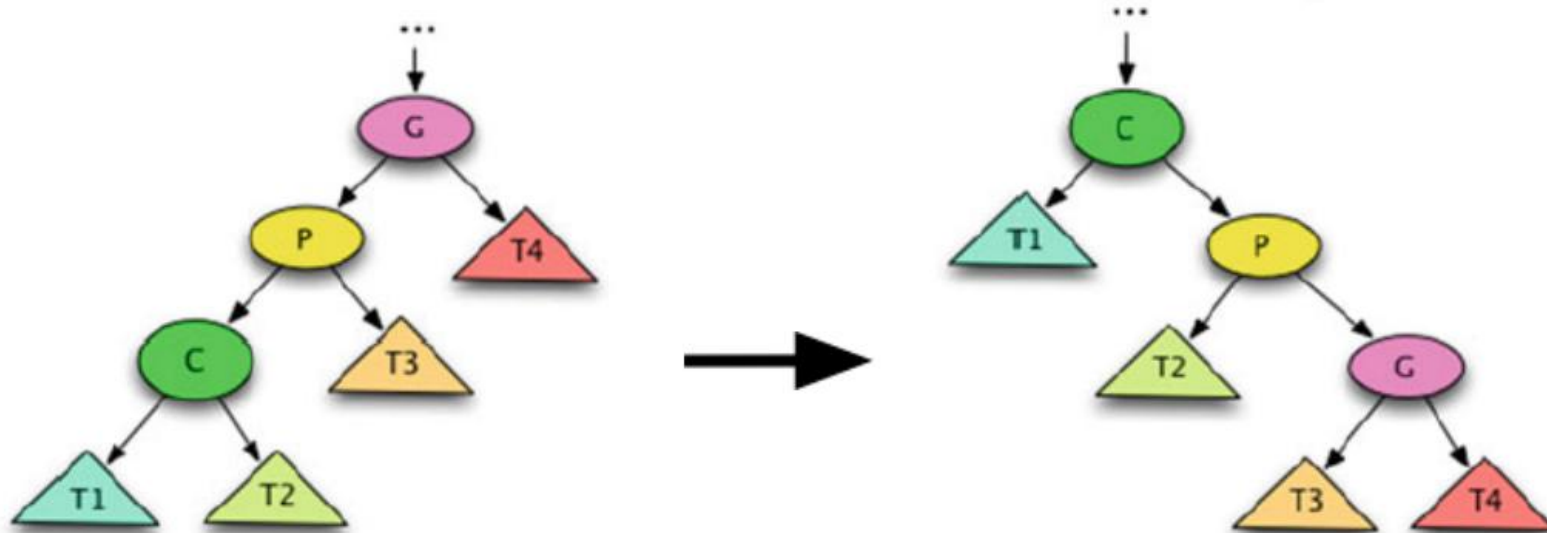
BST after insertion of 6





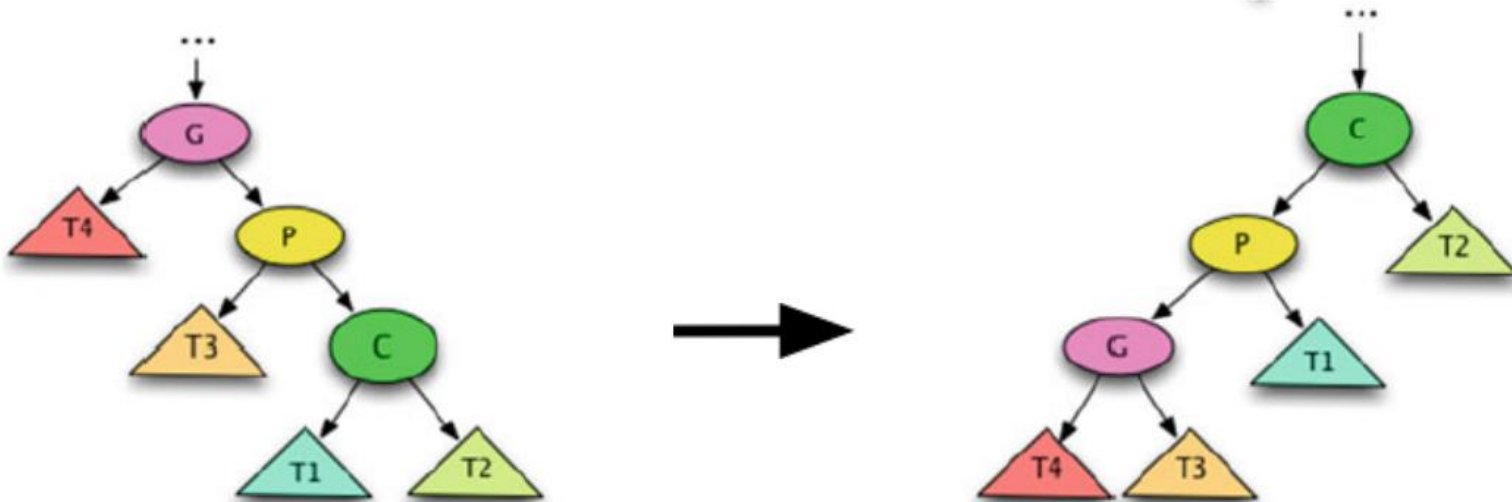
## Right-Right Splaying Operation

The *right-right splaying* operation cyclically swaps a node  $C$ , its parent  $P$ , and its grandparent  $G$



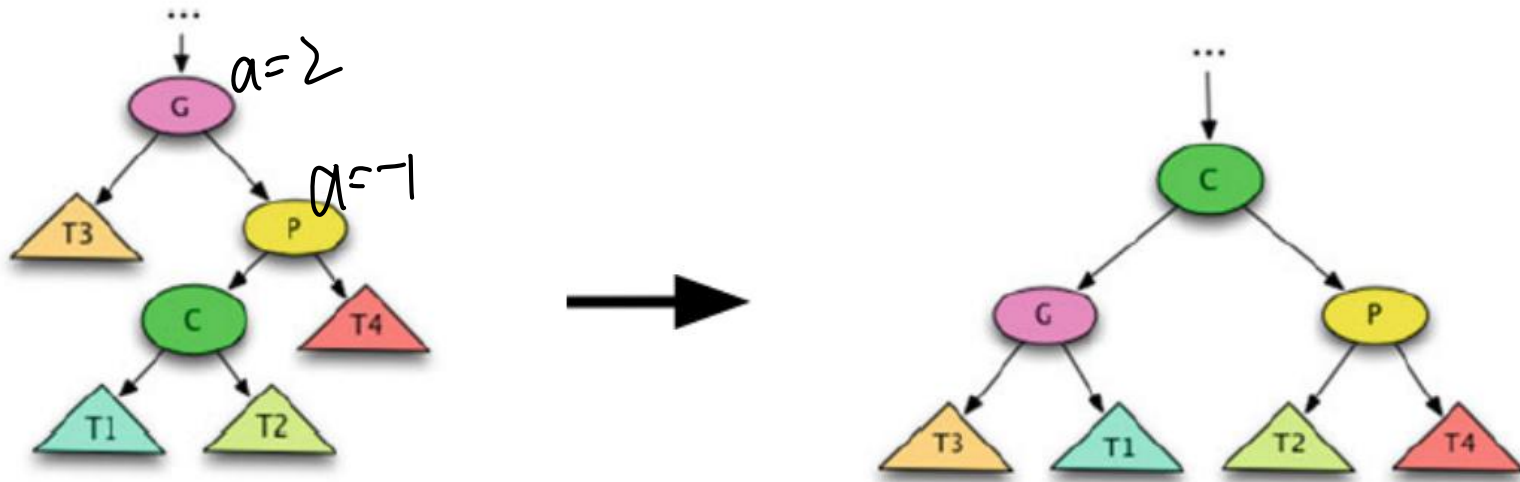
## Left-Left Splaying Operation

The *left-left splaying* operation is the inverse of the right-right splaying operation



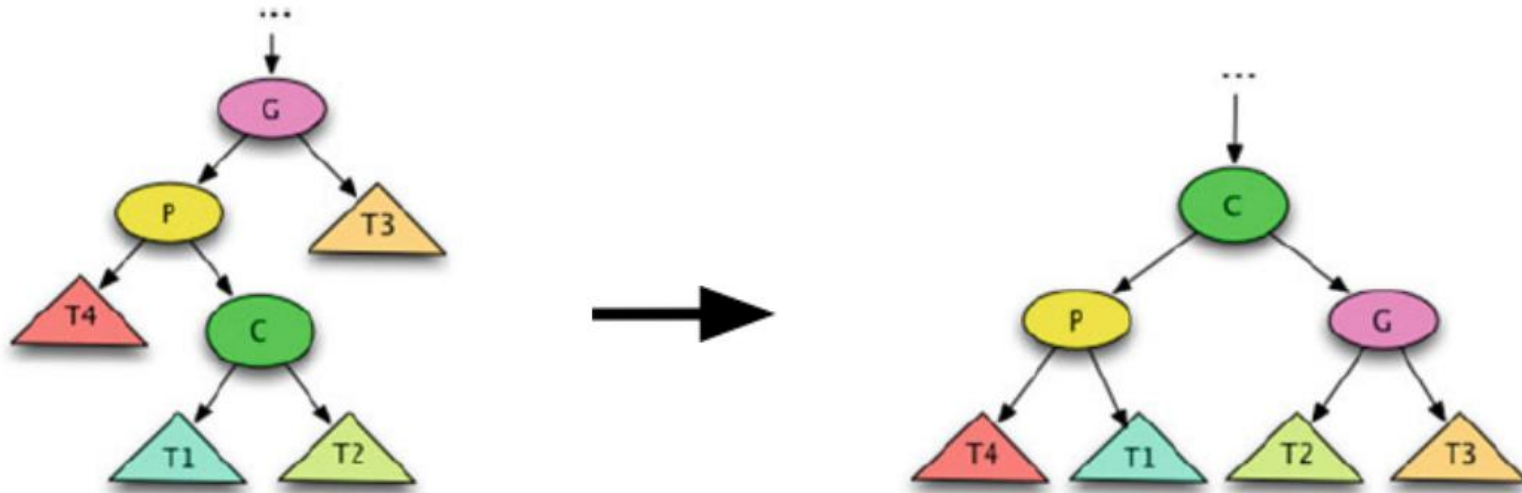
## Right-Left Splaying Operation

The *right-left splaying* operation swaps a node  $C$  to the top and make its grandparent  $G$  and its parent  $P$  its left and right successors, respectively



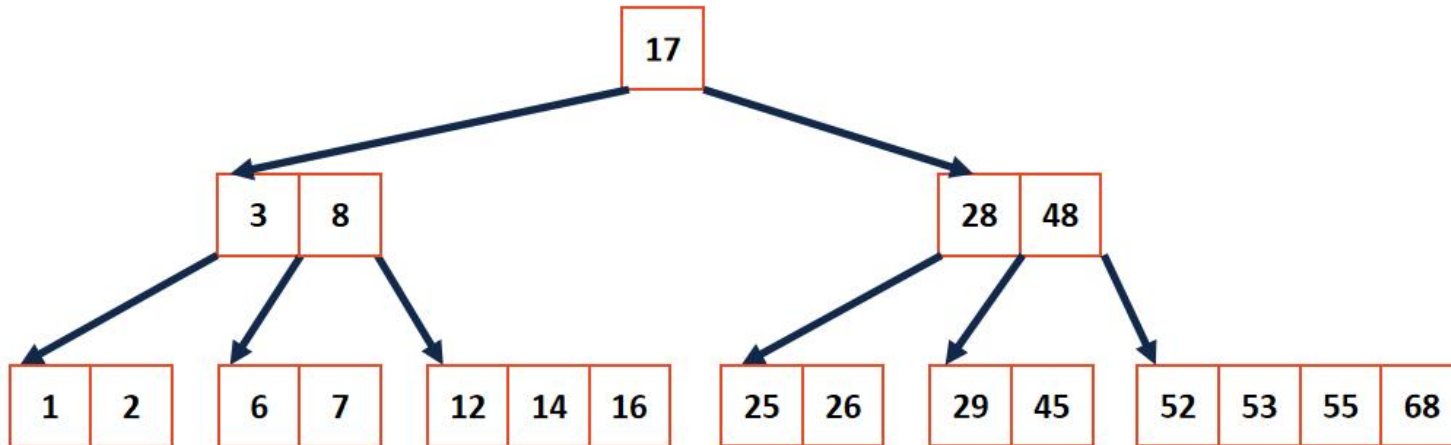
## Left-Right Splaying Operation

The *left-right splaying* operation swaps a node  $C$  to the top and make its parent  $P$  and its grandparent  $G$  its left and right successors, respectively

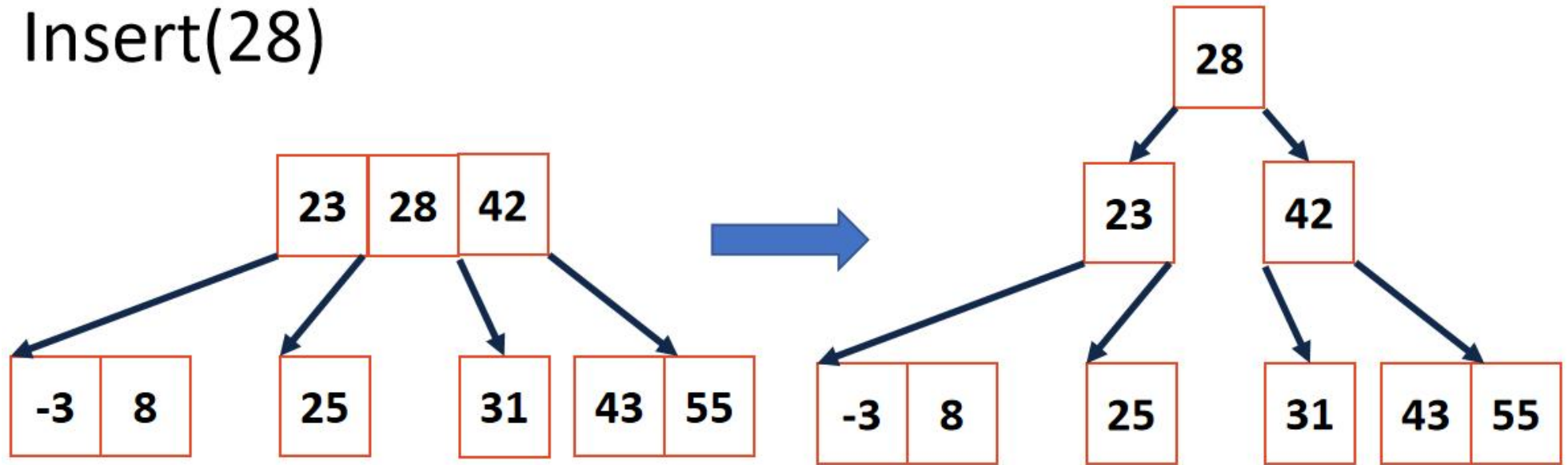


## Btree Properties

- All keys within a node are ordered
- All internal nodes have exactly **one more child than keys**
- All leaves are on the same level

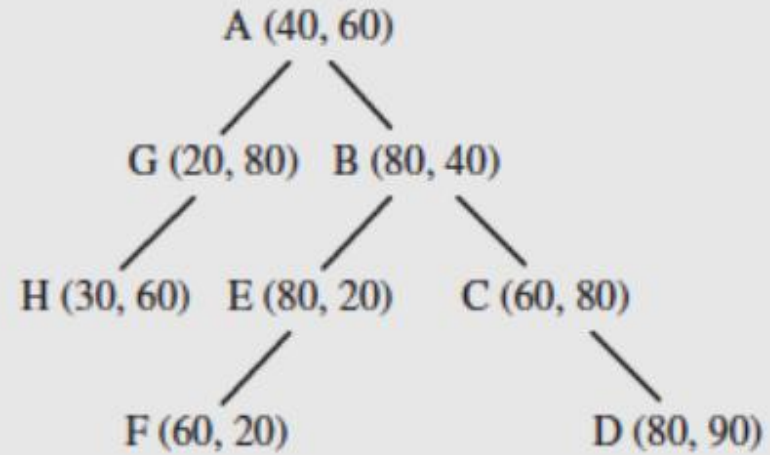
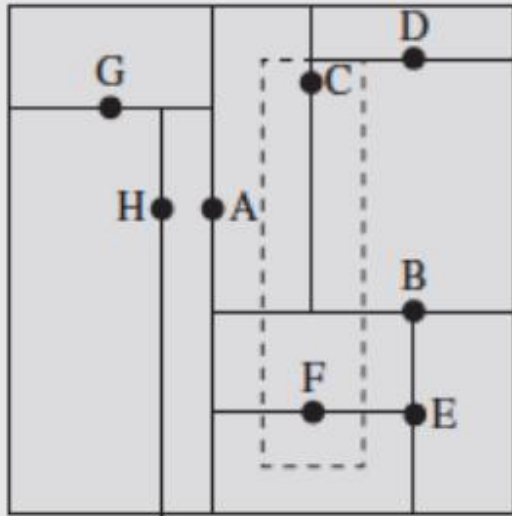


Insert(28)

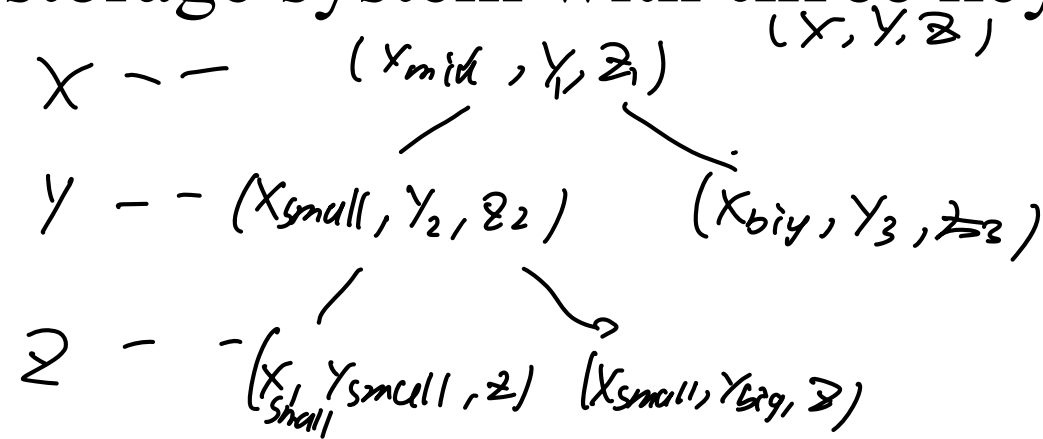




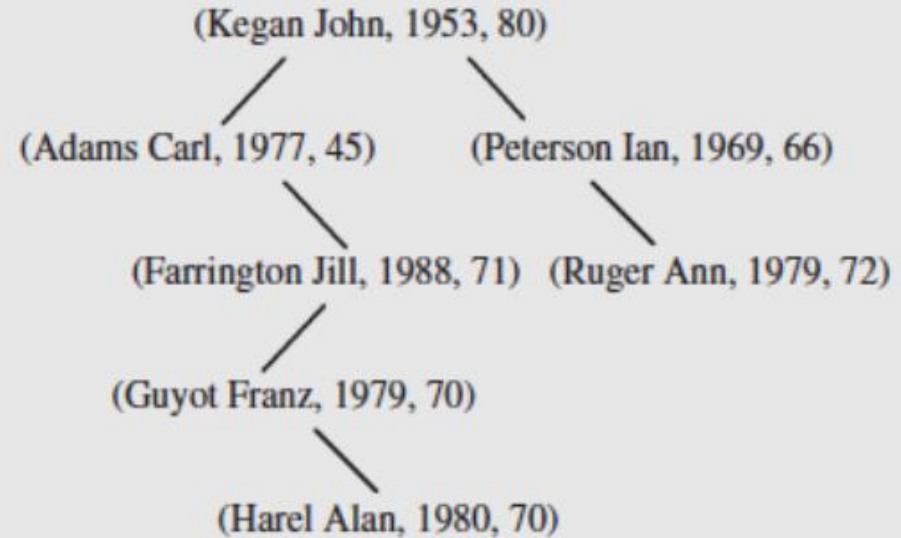




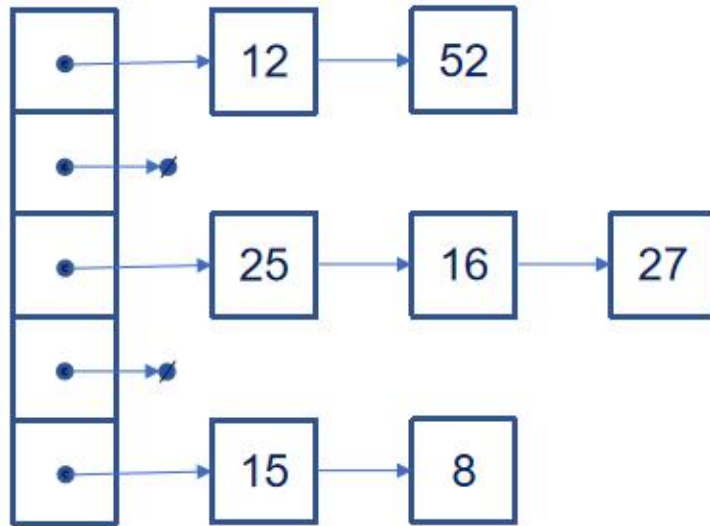
Describe in detail how to use KD tree to store a book storage system with **three** keys



Name	YOB	Salary (K)
Kegan, John	1953	80
Adams, Carl	1977	45
Peterson, Ian	1969	66
Farrington, Jill	1988	71
Ruger, Ann	1979	72
Guyot, Franz	1979	70
Harel, Alan	1980	70



## Open Hashing (Separate Chaining)



*closed hashing*  
**Linear Probing**

**Double Hashing**

# Analyze the advantages and disadvantages of linear probing and separate chaining in different situations

LP

advantage

① ~~更容易进行序列化 (serialize) 操作~~

② 当元素总数已知, 性能更好

disadvantage

① 需扩容 rehash 时间成本上升很大

② 当 hash function 不良, 其探测空时间成本高

③ 数组存在空槽, 内存浪费

④ 两两元素 should probe 两两空 slot 空间

SC

advantage:

① more convenient when often add elems or delete elems as no need to rehashing ✓

② 动态分配内存, 相比于 LP 浪费内存少 ✓

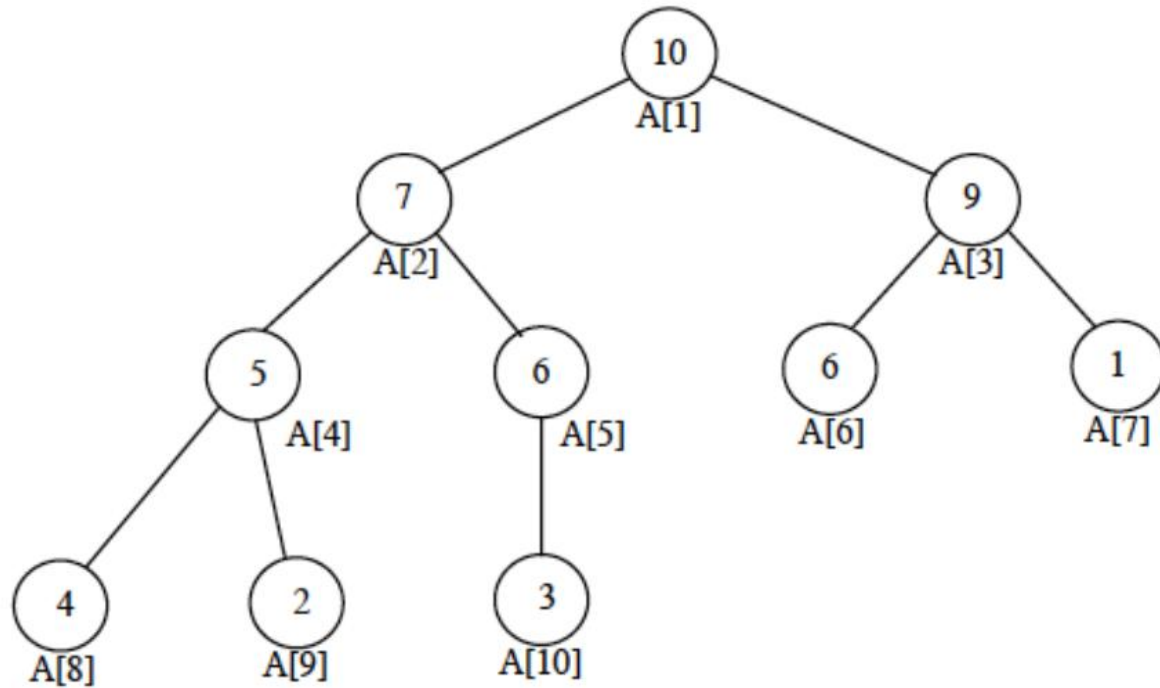
③ 删除元素更方便, 指针操作

disadvantage:

① 存储的元素动态随机分布于内存, 相比结构更紧凑的数组, hash 的遍历访问会带来额外的时间开销

② 当不用插入删除 elems, 性能更好

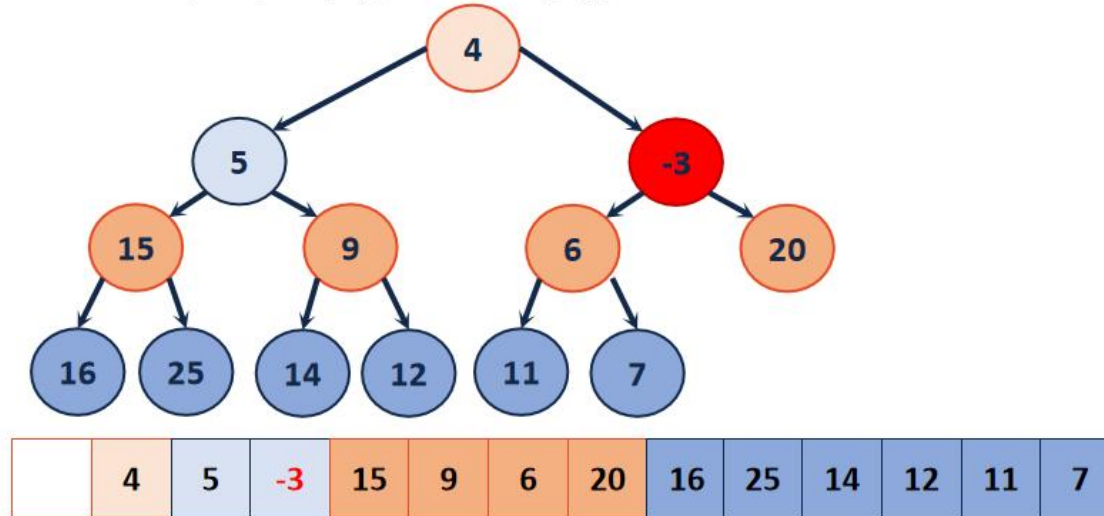
# Heap



$A = [10, 7, 9, 5, 6, 6, 1, 4, 2, 3]$

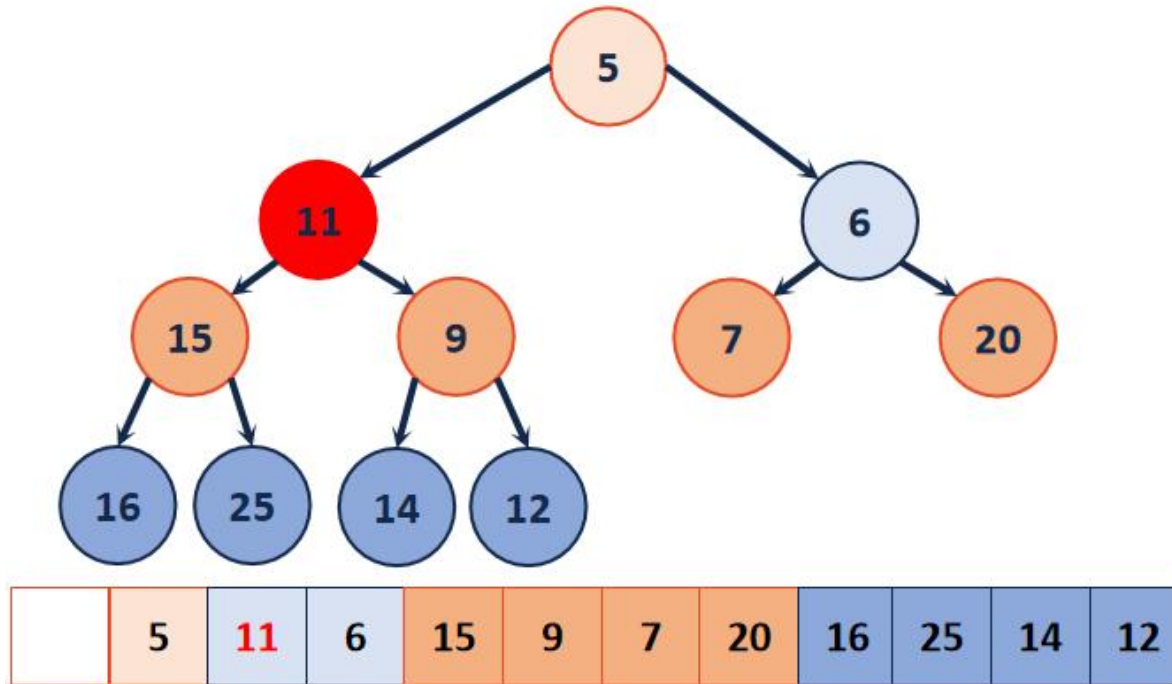
## heapifyUp(*i*)

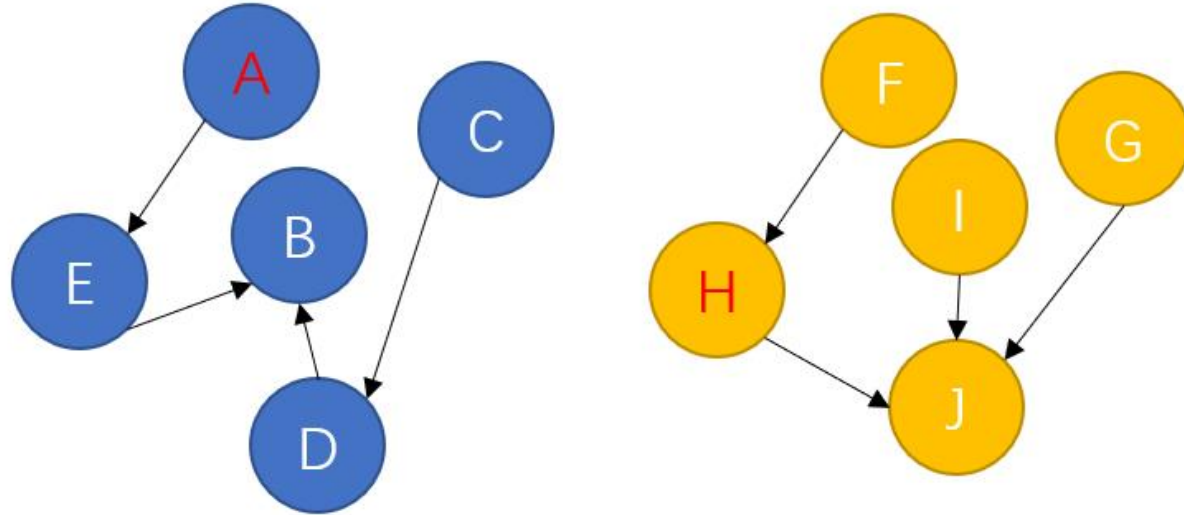
```
if i != rootIndex && A[i] < A[parent(i)]  
    swap(i, parent(i))  
    heapifyUp(parent(i))
```

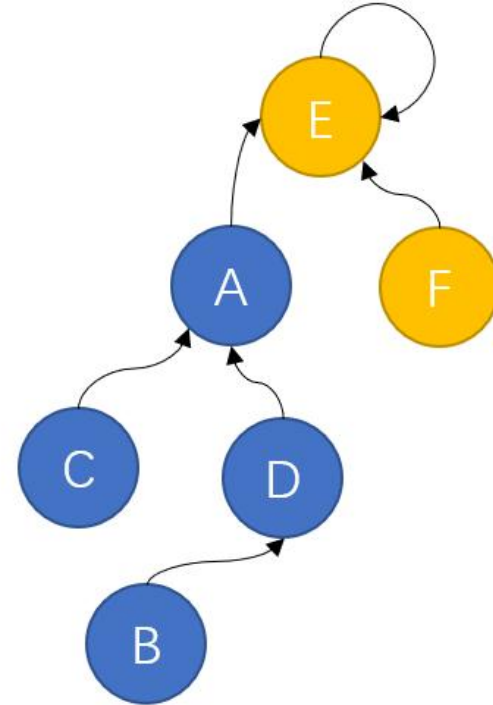
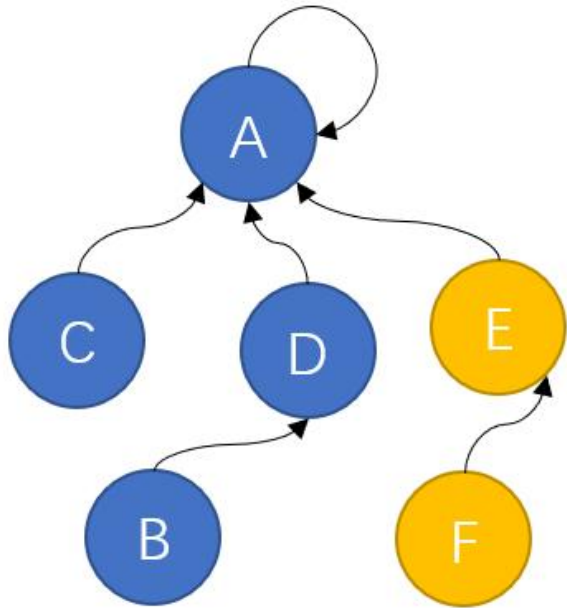


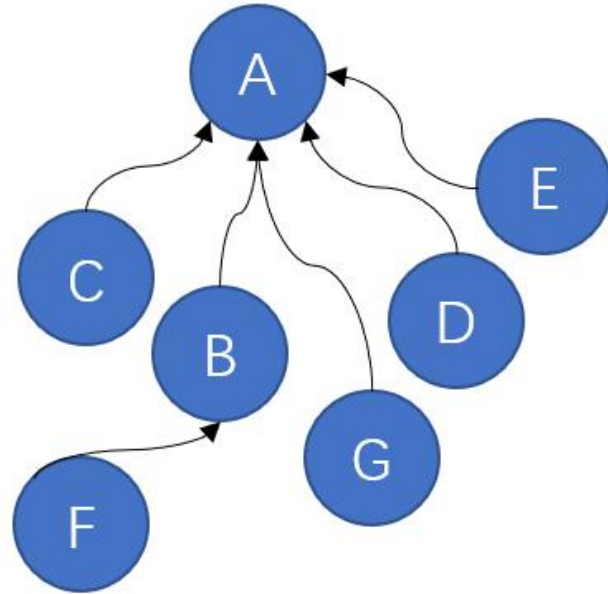
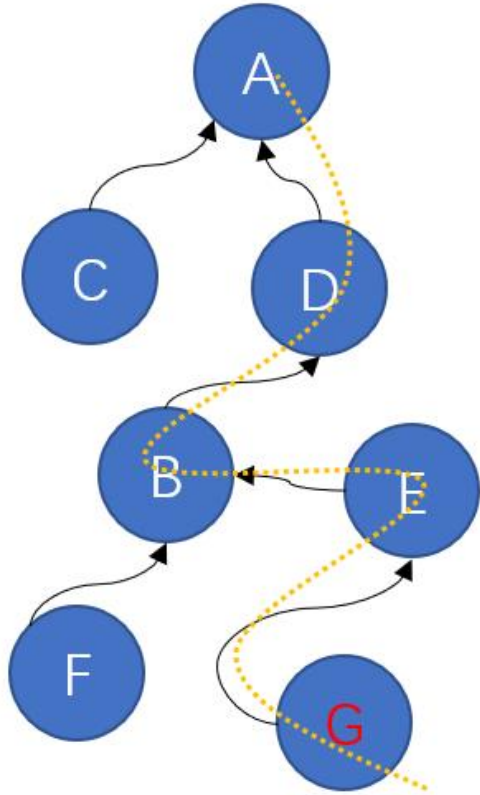


## heapifyDown





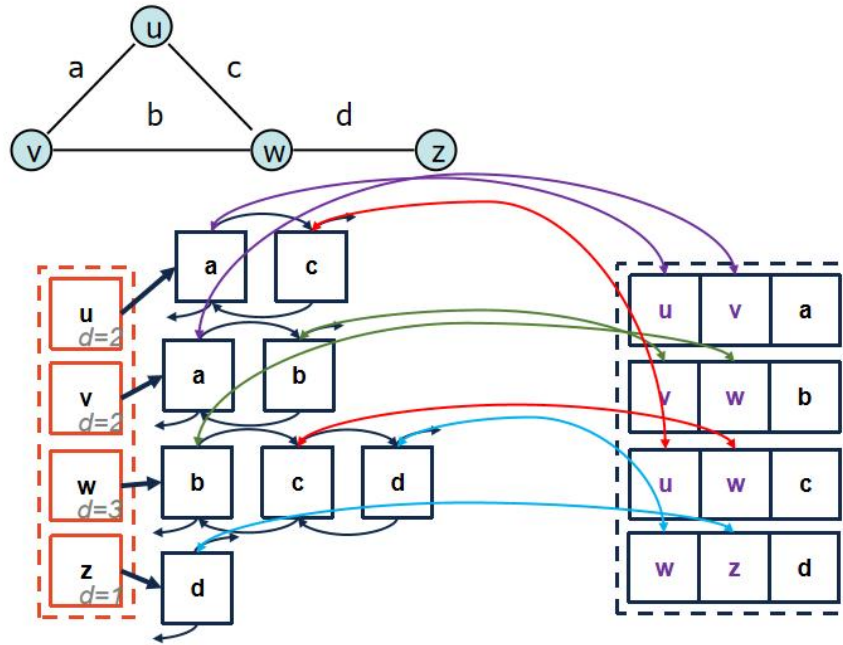


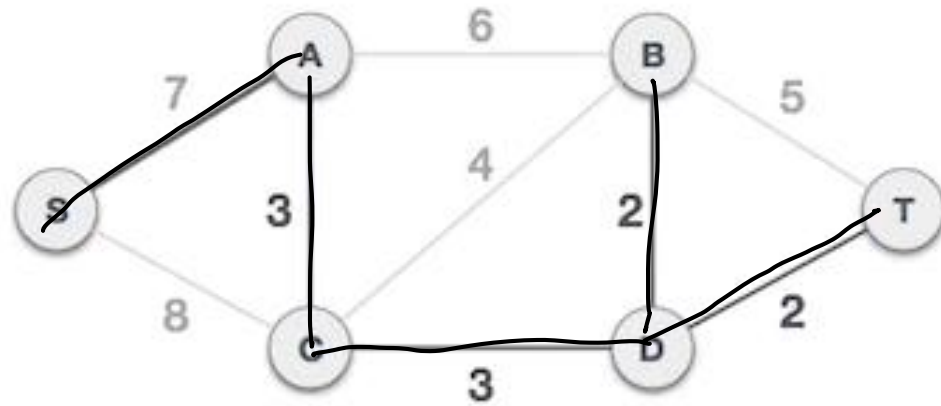


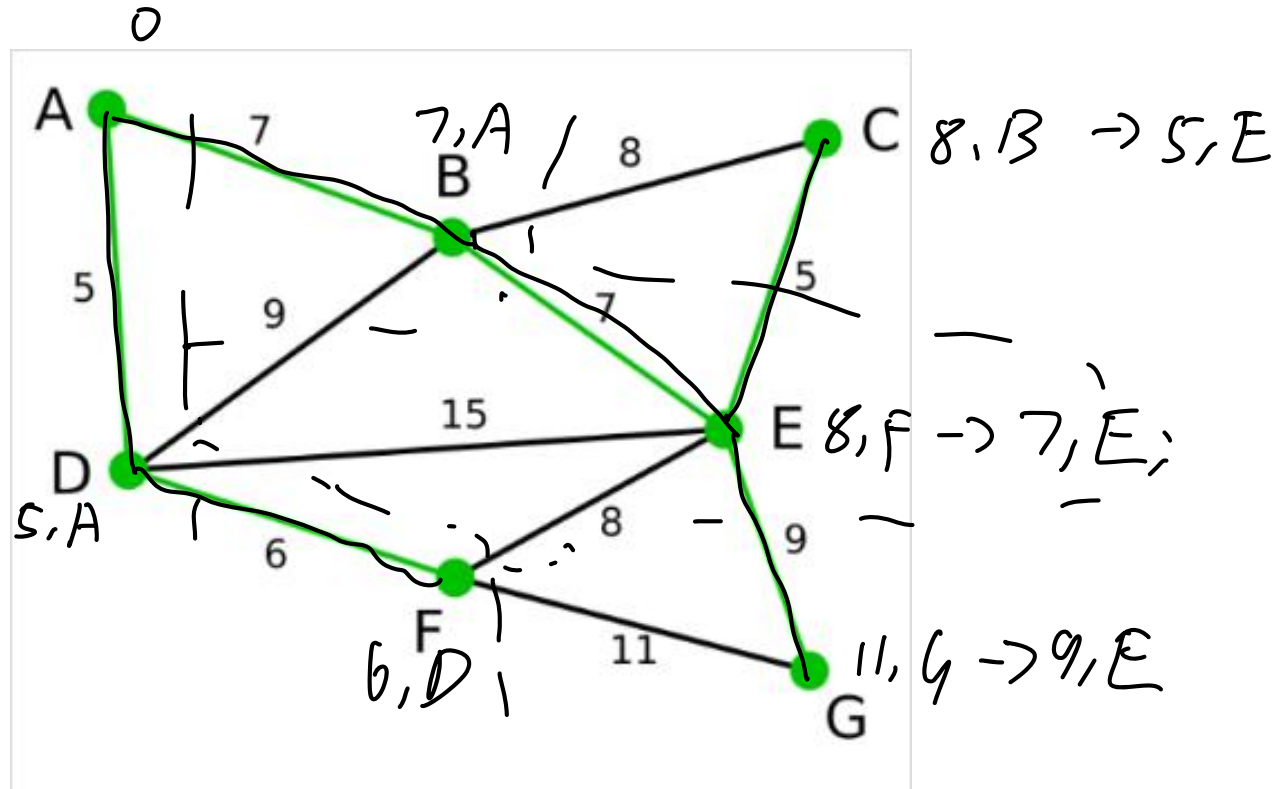
- Analyze and illustrate the worst-case complexity and
- γ amortized complexity of the disjoint set when using
  - ‘ uptree structure and path compression, respectively

*Handwritten notes:*  
M  
~~10~~ 10 y<sup>x</sup> ~~10~~

## Adjacency List







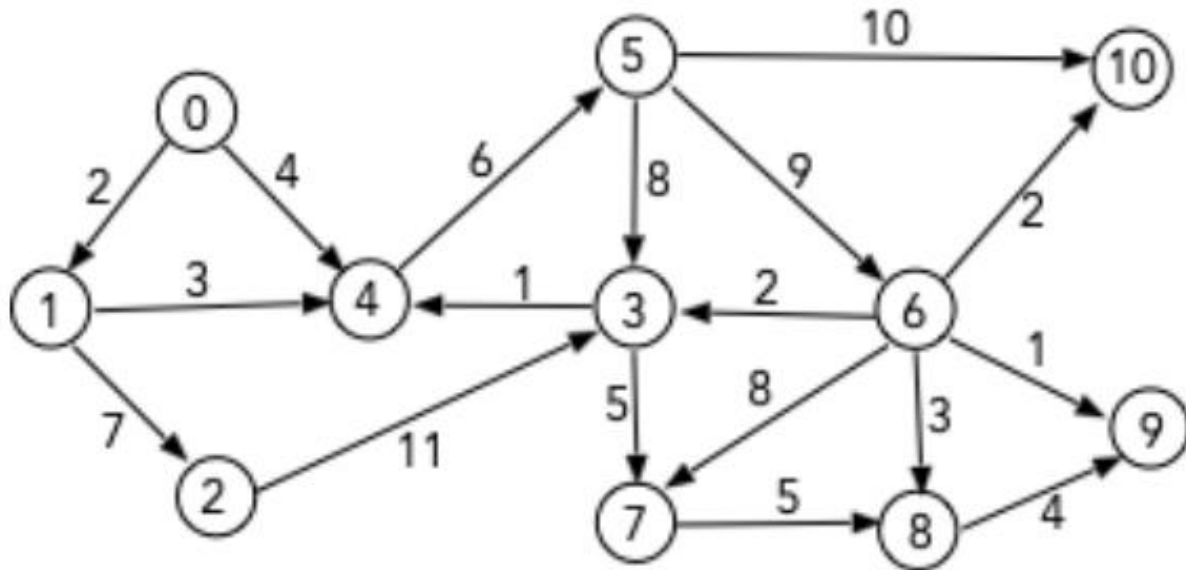


What happens in the case of Prim's and Kruskal's algorithms, if negative edge costs are permitted? Is it still sensible to talk about minimum spanning trees, if negative edge costs are permitted?

*if not negative cycle fine*

Show that if all edge costs are pairwise different, the minimum spanning tree is uniquely defined.

*Kruskal*



*Floyd:*

```
For (k = 1; k <= n; k++)  
  for (l = 1; l <= n; l++)  
    for (j = 1; j <= n; j++)  
      if (d[i][k] + d[k][j] < d[i][j])  
        d[i][j] = d[i][k] + d[k][j];
```



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**Good Luck & Have Fun**

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