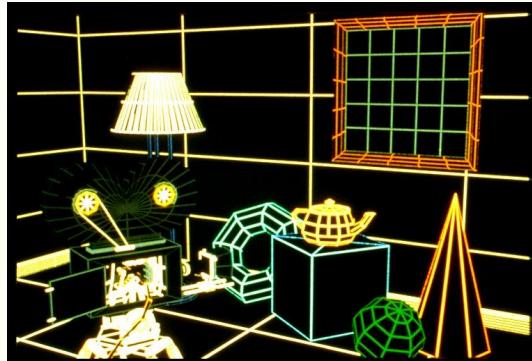


Texture Mapping



What adds visual realism?



Geometry only



Phong shading



*Phong shading +
Texture maps*



Textures Supply Rendering Detail



Without texture



With texture



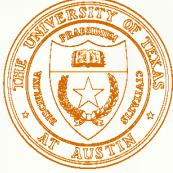
Textures Make Graphics Pretty



*Texture → detail,
detail → immersion,
immersion → fun*

Microsoft Flight Simulator X

CS 354



Texture mapping

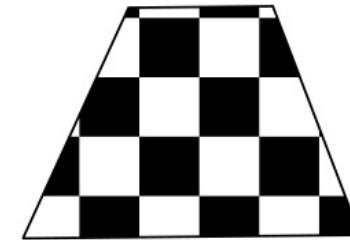
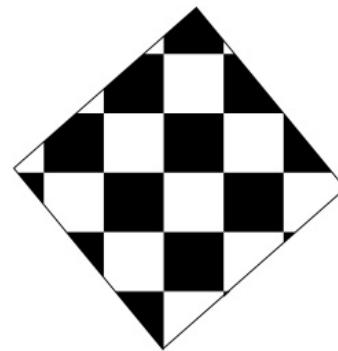
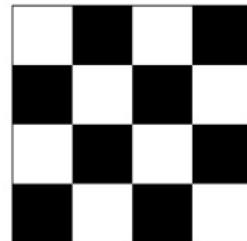


Texture mapping (Woo et al., fig. 9-1)

- Texture mapping allows you to take a simple polygon and give it the appearance of something much more complex.
 - Due to Ed Catmull, PhD thesis, 1974
 - Refined by Blinn & Newell, 1976
- Texture mapping ensures that “all the right things” happen as a textured polygon is transformed and rendered.



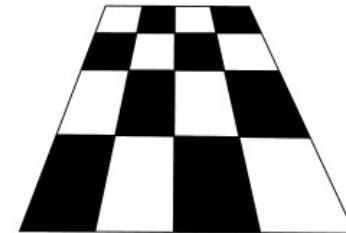
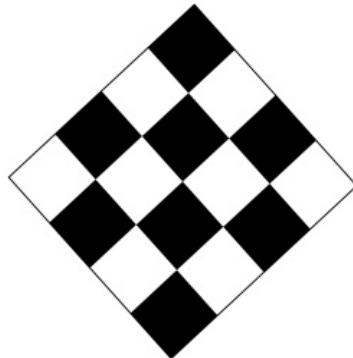
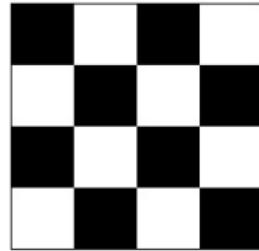
Non-parametric texture mapping



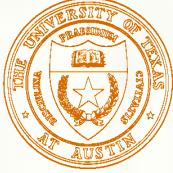
- With “non-parametric texture mapping”:
 - Texture size and orientation are fixed
 - They are unrelated to size and orientation of polygon
 - Gives cookie-cutter effect



Parametric texture mapping

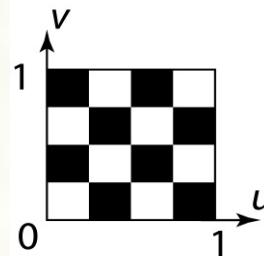


- With “parametric texture mapping,” texture size and orientation are tied to the polygon.
- Idea:
 - Separate “texture space” and “screen space”
 - Texture the polygon as before, but in texture space
 - Deform (render) the textured polygon into screen space
- A texture can modulate just about any parameter – diffuse color, specular color, specular exponent, ...

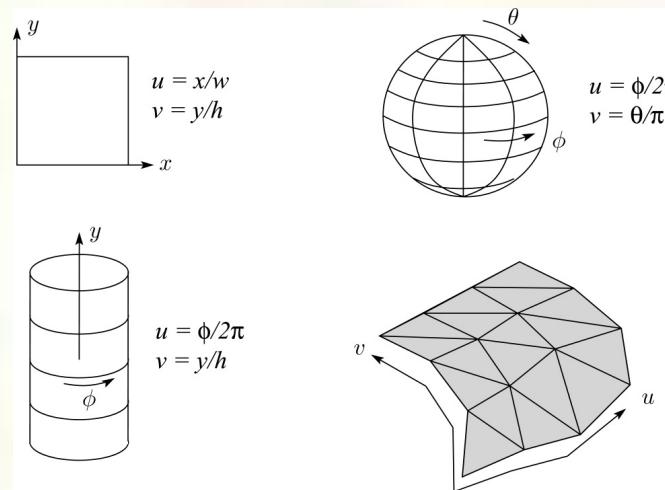


Implementing texture mapping

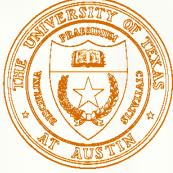
- A texture lives in its own abstract image coordinates parameterized by (u, v) in the range $([0..1], [0..1])$:



- It can be wrapped around many different surfaces:

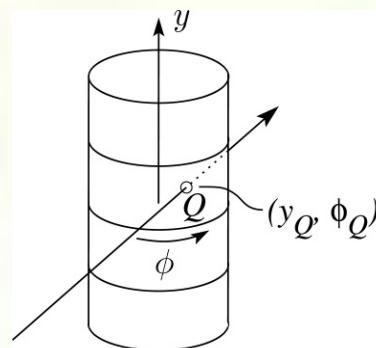


- Computing (u, v) texture coordinates in a ray tracer is fairly straightforward.
- Note: if the surface moves/deforms, the texture goes with it.

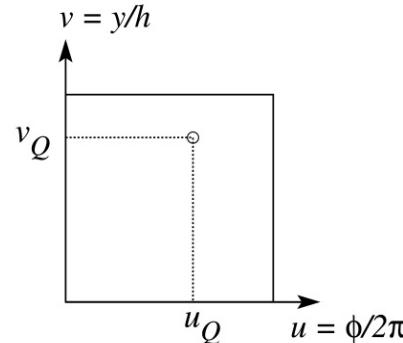


Mapping to texture image coords

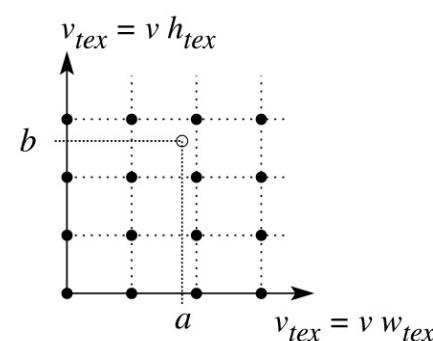
- The texture is usually stored as an image. Thus, we need to convert from abstract texture coordinate:
 (u, v) in the range $([0..1], [0..1])$
to texture image coordinates:
 (u_{tex}, v_{tex}) in the range $([0.. w_{tex}], [0.. h_{tex}])$



Ray intersection



Mapping to
abstract texture coords



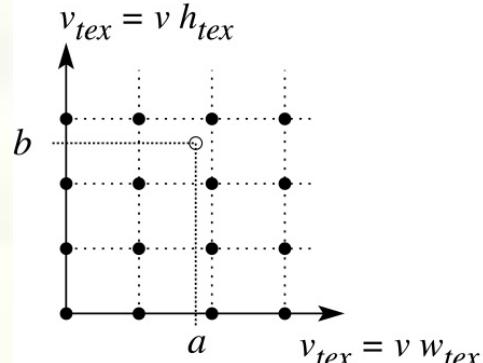
Mapping to
texture pixel coords

- Q:** What do you do when the texture sample you need lands between texture pixels?

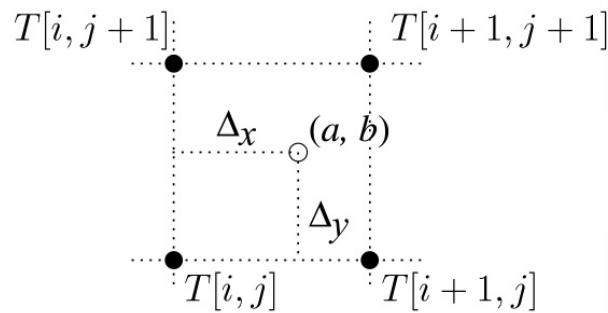


Texture resampling

- We need to resample the texture:



Mapping to
texture pixel coords



Close-up

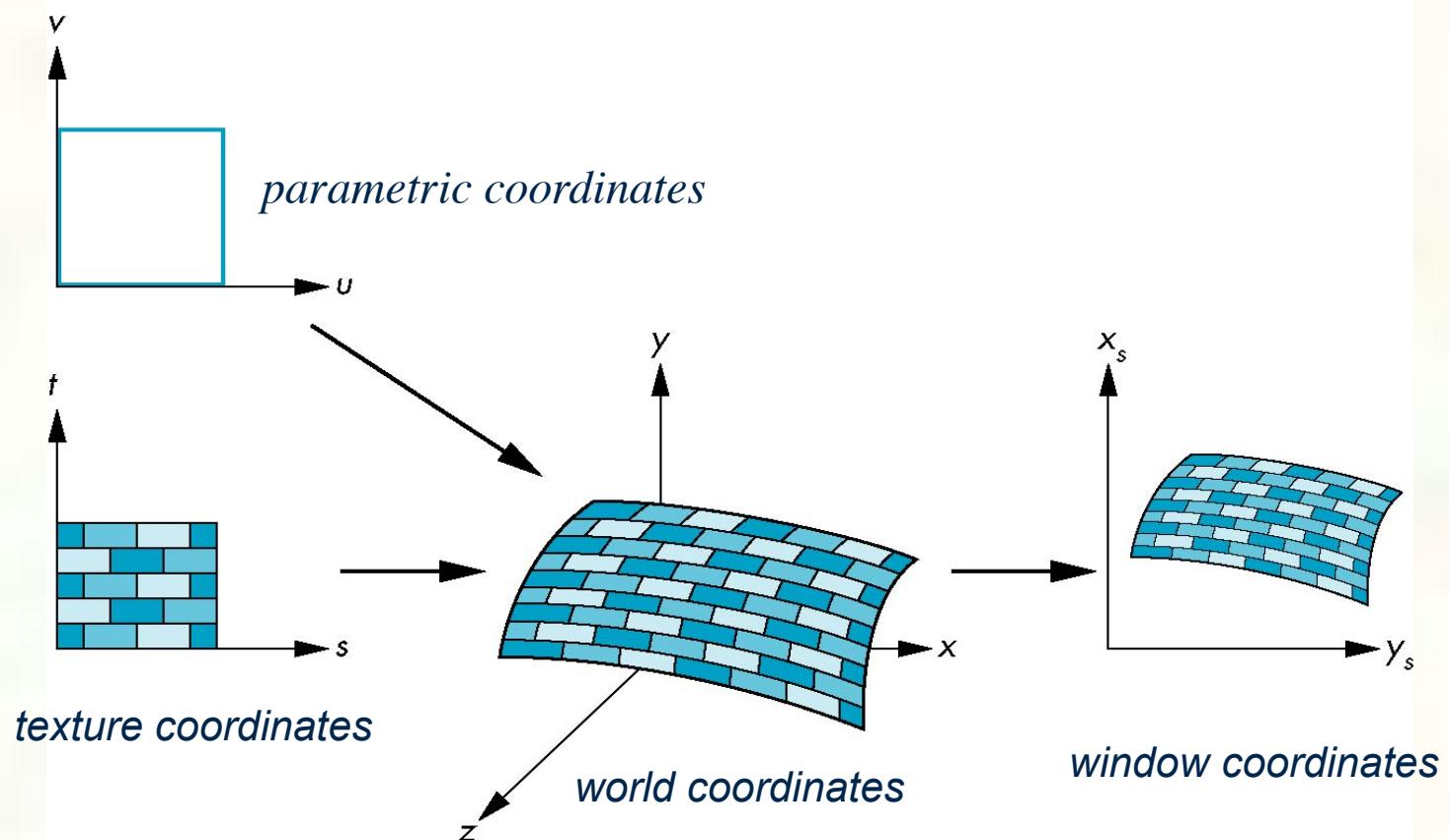
- A common choice is **bilinear interpolation**:

$$\begin{aligned}T(a, b) &= T[i + \Delta_x, j + \Delta_y] \\&= (1 - \Delta_x)(1 - \Delta_y)T[i, j] + \Delta_x(1 - \Delta_y)T[i + 1, j] \\&\quad + (1 - \Delta_x)\Delta_y T[i, j + 1] + \Delta_x\Delta_y T[i + 1, j + 1]\end{aligned}$$



Texture Coordinates

- Interpolated over rasterized primitives





Source of texture coordinates?

- Assigned ad-hoc by artist

- Tedious!
 - Has gift wrapping problem



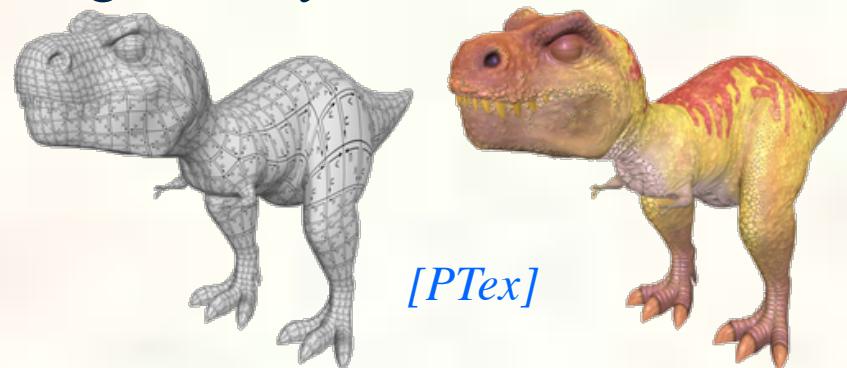
- Computed based on XYZ position

- Texture coordinate generation (“texgen”)
 - Hard to map to “surface space”
 - Function maps (x,y,z) to (s,t,r,q)



- From bi-variate parameterization of geometry

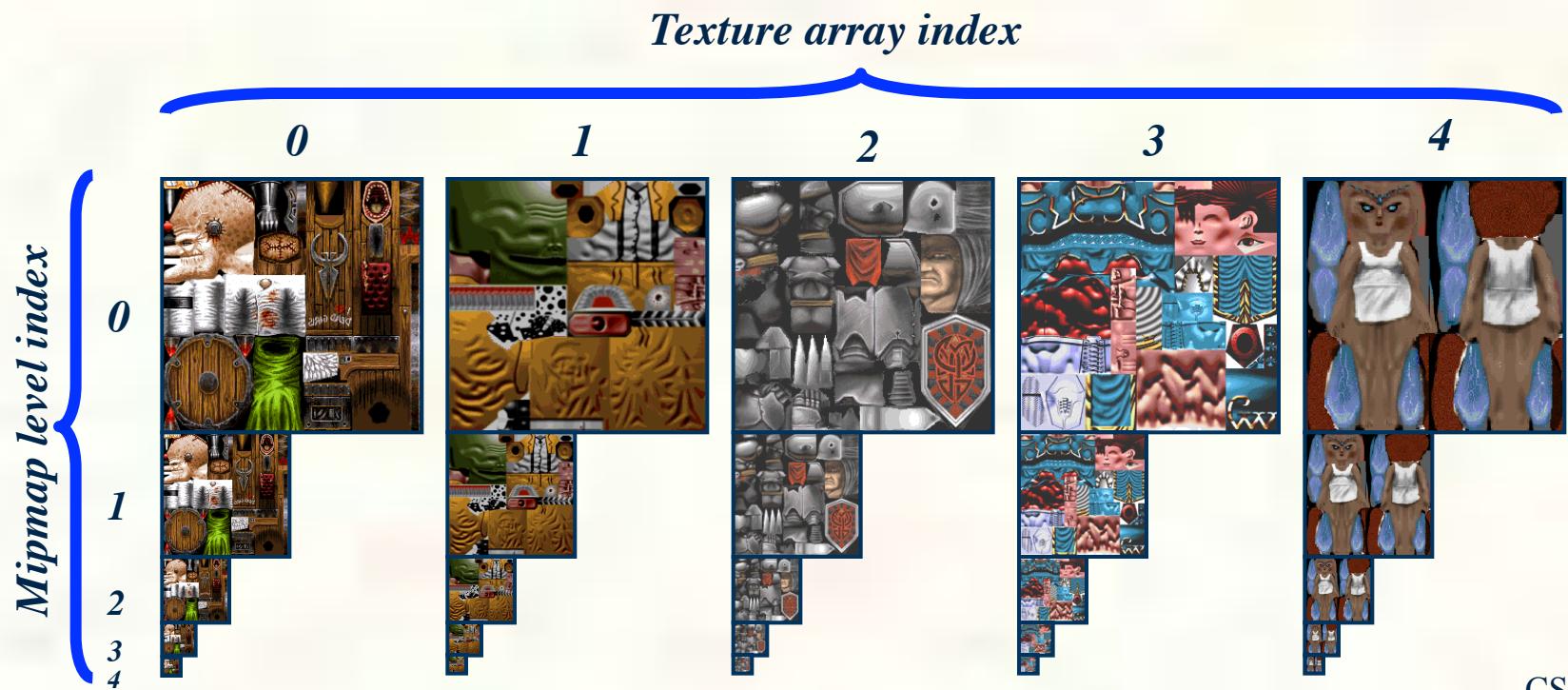
- Good when geometry is generated from patches
 - So (u,v) of patch maps to (x,y,z) and (s,t)

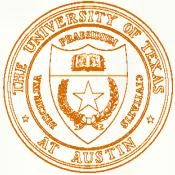




Texture Arrays

- Multiple skins packed in texture array
 - Motivation: binding to one multi-skin texture array avoids texture bind per object

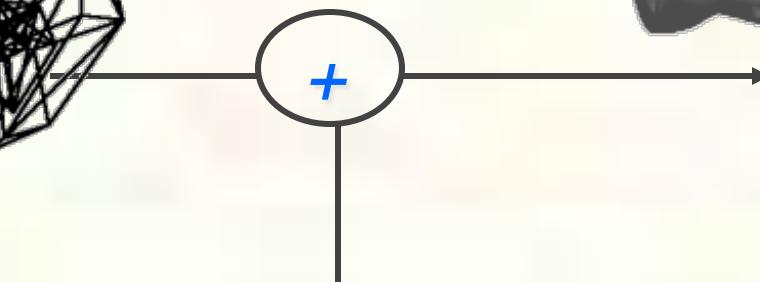




Textured Polygonal Models



*Key-frame
model
geometry*



*Decal
skin* *Result*

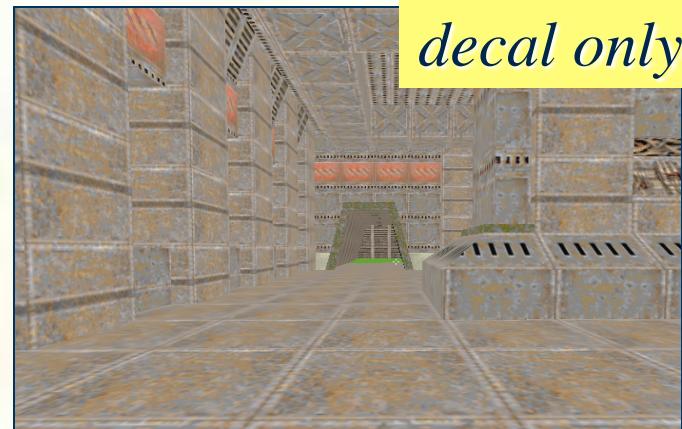


Multiple Textures



lightmaps only

✗
(modulate)



decal only



combined scene

* *Id Software's Quake 2 circa 1997*



Can define material by program

- A ‘surface shader’ computes the color of each ray that hits the surface.
- Example: Renderman surface shader

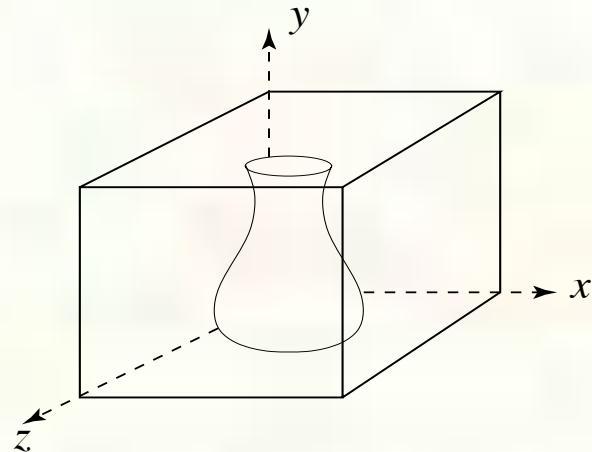
```
/*
 * Checkerboard
 */
surface checker(float Kd=.5, Ka=.1) {
    float smod = mod(10*s, 1);
    float tmod = mod(10*t, 1);
    if (smod < 0.5) {
        if (tmod < 0.5) Ci=Cs; else Ci=color(0,0,0);
    } else {
        if (tmod < 0.5) Ci=color(0,0,0); else Ci=Cs;
    }
    Oi = Os;
    Ci = Oi*Ci*(
        Ka*ambient() +
        Kd*diffuse(faceforward(normalize(N), I)));
}
```





Solid textures

- Q: What kinds of artifacts might you see from using a marble veneer instead of real marble?



- One solution is to use **solid textures**:
 - Use model-space coordinates to index into a 3D texture
 - Like “carving” the object from the material
- One difficulty of solid texturing is coming up with the textures.



Solid textures (cont'd)

- Here's an example for a vase cut from a solid marble texture:



- *Solid marble texture by Ken Perlin, (Foley, IV-21)*



Displacement and Bump Mapping

- Use surface offsets stored in texture
 - Perturb or displace the surface
 - Shade on the resulting surface normals



$$\mathbf{P}(u, v)$$

$$\mathbf{S}(u, v) = \frac{\partial \mathbf{P}(u, v)}{\partial u} \quad \mathbf{T}(u, v) = \frac{\partial \mathbf{P}(u, v)}{\partial v}$$

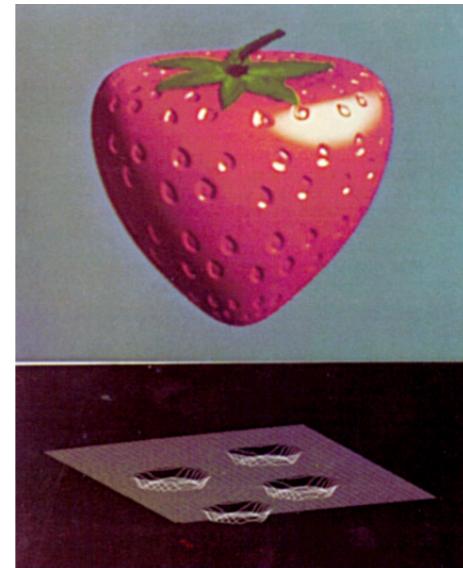
$$\mathbf{N}(u, v) = \mathbf{S} \times \mathbf{T}$$

■ Displacement

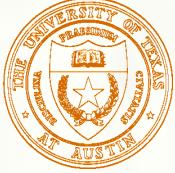
$$\mathbf{P}'(u, v) = \mathbf{P}(u, v) + h(u, v)\mathbf{N}(u, v)$$

■ Perturbed normal

$$\begin{aligned}\mathbf{N}'(u, v) &= \mathbf{P}'_u \times \mathbf{P}'_v \\ &= \mathbf{N} + h_u(\mathbf{T} \times \mathbf{N}) + h_v(\mathbf{S} \times \mathbf{N})\end{aligned}$$



From Blinn 1976



Normal Mapping

- Bump mapping via a normal map texture
 - Normal map – x,y,z components of actual normal
 - Instead of a height field 1 value per pixel
 - The normal map can be generated from the height field
 - Otherwise have to orient the normal coordinates to the surface



×



+



diffuse

decal

specular

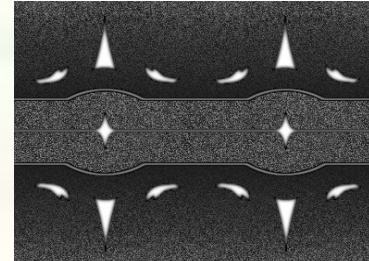
=



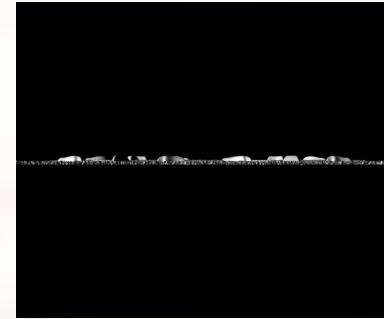
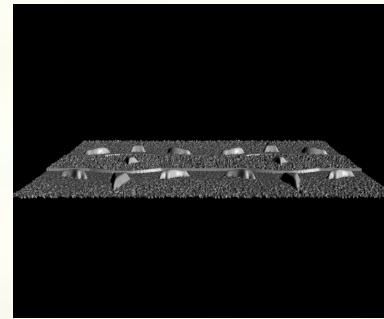
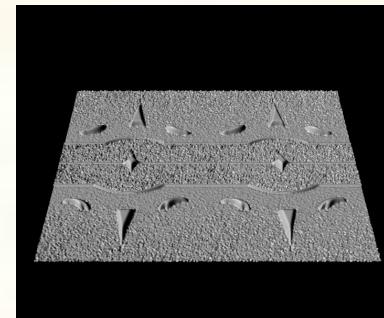
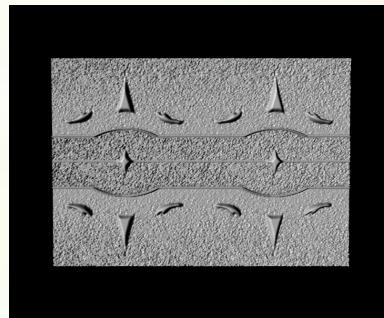


Displacement vs. bump mapping

- Input texture



- Rendered as displacement map over a rectangular surface





Displacement vs. bump mapping (cont'd)



Original rendering
cylinder



Rendering with bump map
wrapped around a

Bump map and rendering by Wyvern Aldinger

University of Texas at Austin CS354 - Computer Graphics Don Fussell

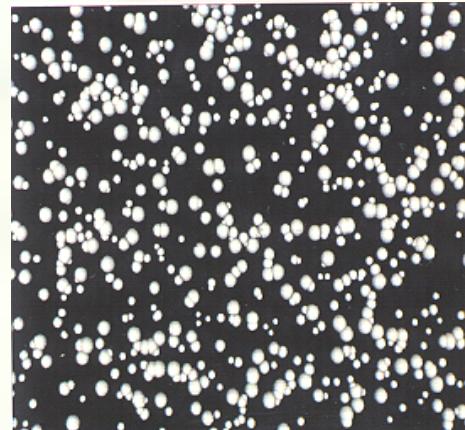


Bump mapping example

Texture #1
(diffuse color)



Texture #2
(bump map)



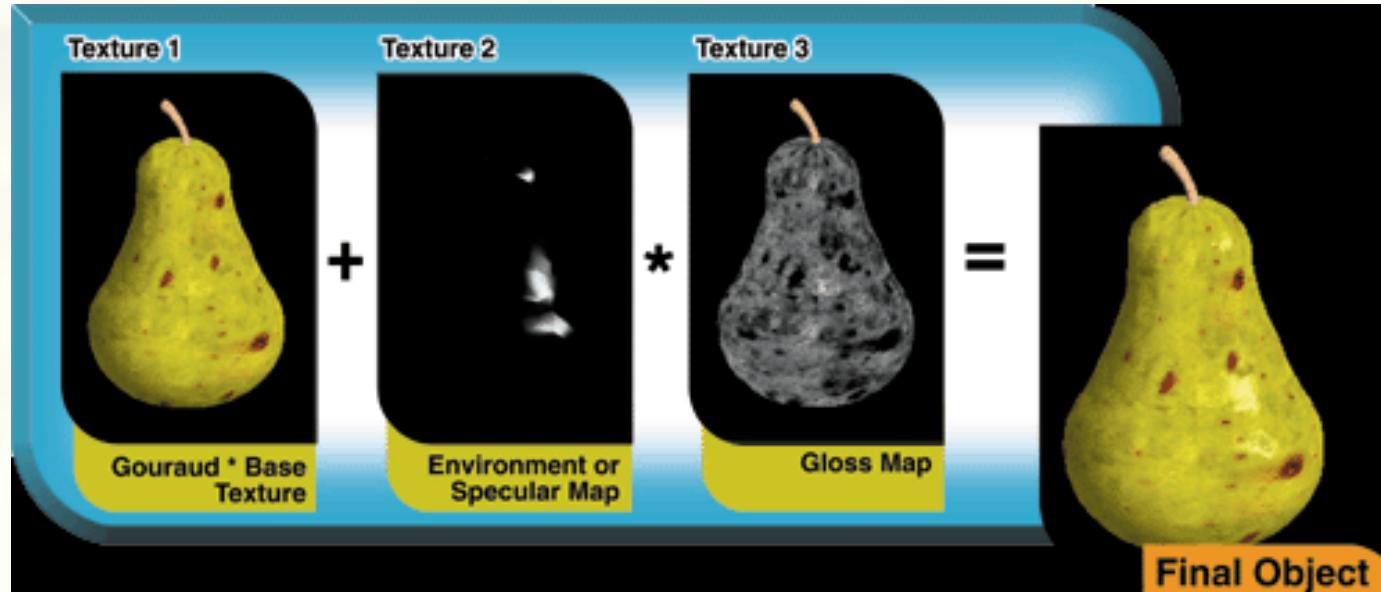
Rendered Image





Combining texture maps

- Using texture maps in combination gives even better effects.



*Diffuse
color*

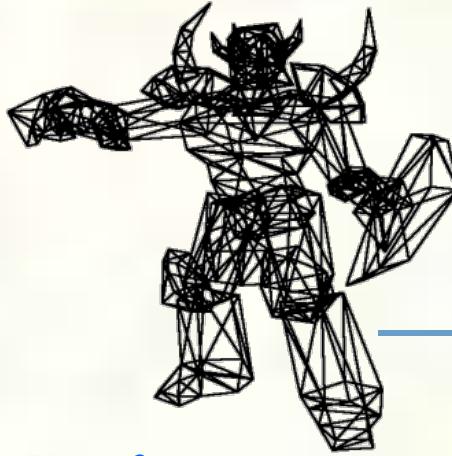
*Environment map
(not necessary
in ray tracer)*

*Specular
coefficient*

*Material
properties
(coefficients
in shading
equation)*



Multiple Textures



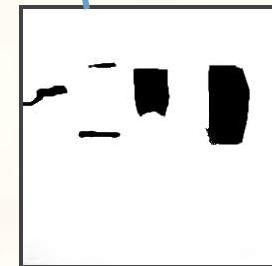
*Key-frame
model
geometry*



*Bump
skin
texture*



*Decal
skin
texture*



*Gloss
skin
texture*

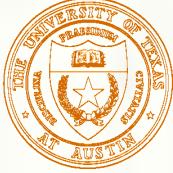
+



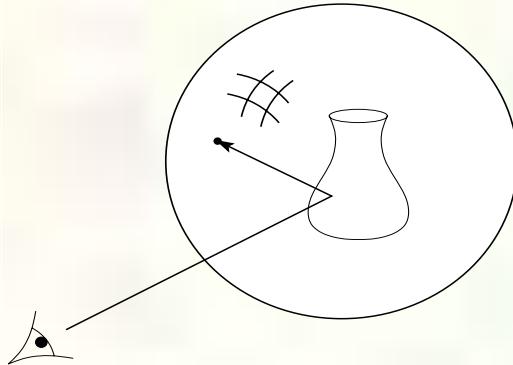
Multitexturing



Final result!



Environment mapping

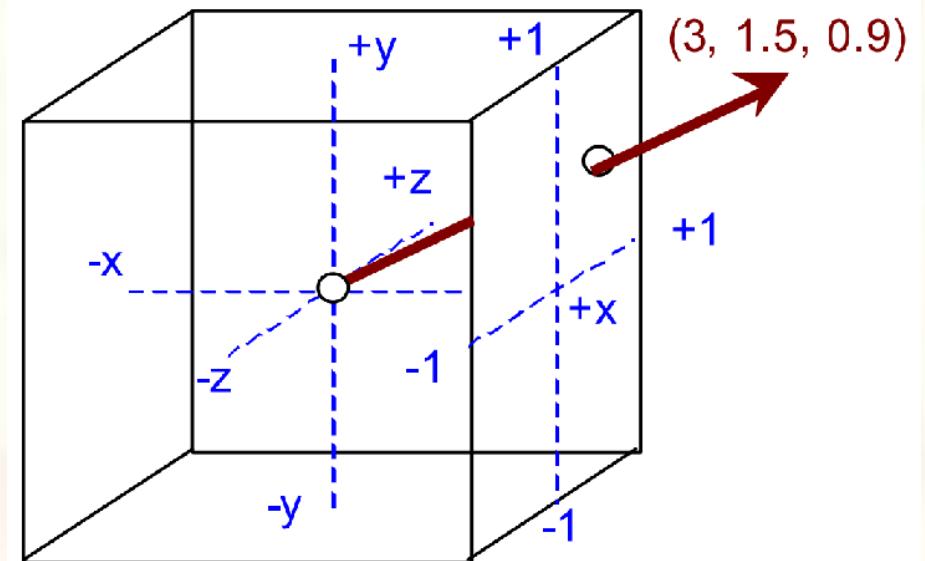
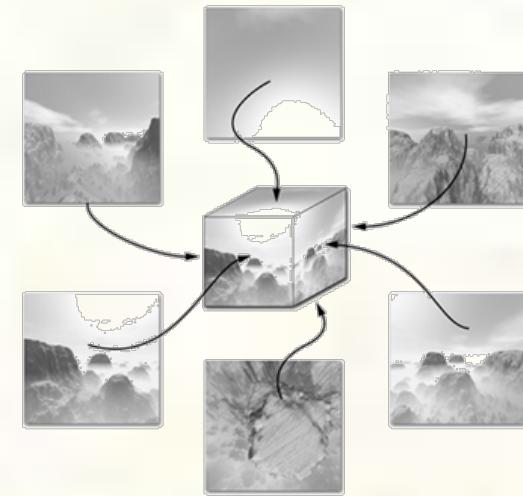


- In **environment mapping** (also known as **reflection mapping**), a texture is used to model an object's environment:
 - Rays are bounced off objects into environment
 - Color of the environment used to determine color of the illumination
 - Really, a simplified form of ray tracing
 - Environment mapping works well when there is just a single object – or in conjunction with ray tracing
- Under simplifying assumptions, environment mapping can be implemented in hardware.
- With a ray tracer, the concept is easily extended to handle refraction as well as reflection.



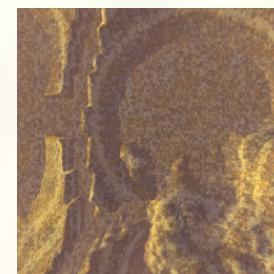
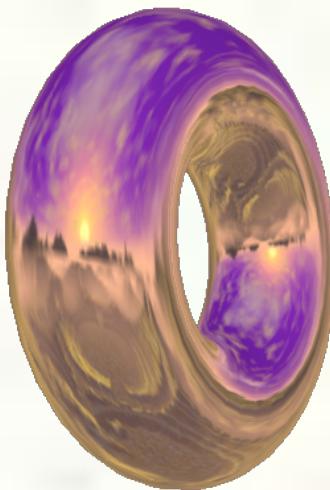
Cube Map Textures

- Instead of one 2D images
 - Six 2D images arranged like the faces of a cube
 - $+X, -X, +Y, -Y, +Z, -Z$
- Indexed by 3D (s, t, r) un-normalized vector
 - Instead of 2D (s, t)
 - Where on the cube images does the vector “poke through”?
 - That’s the texture result



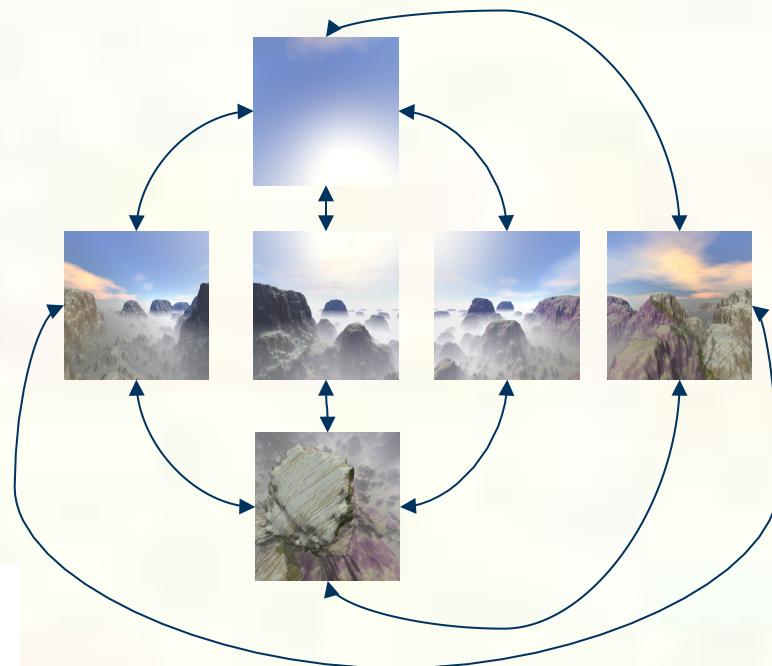


More Cube Mapping





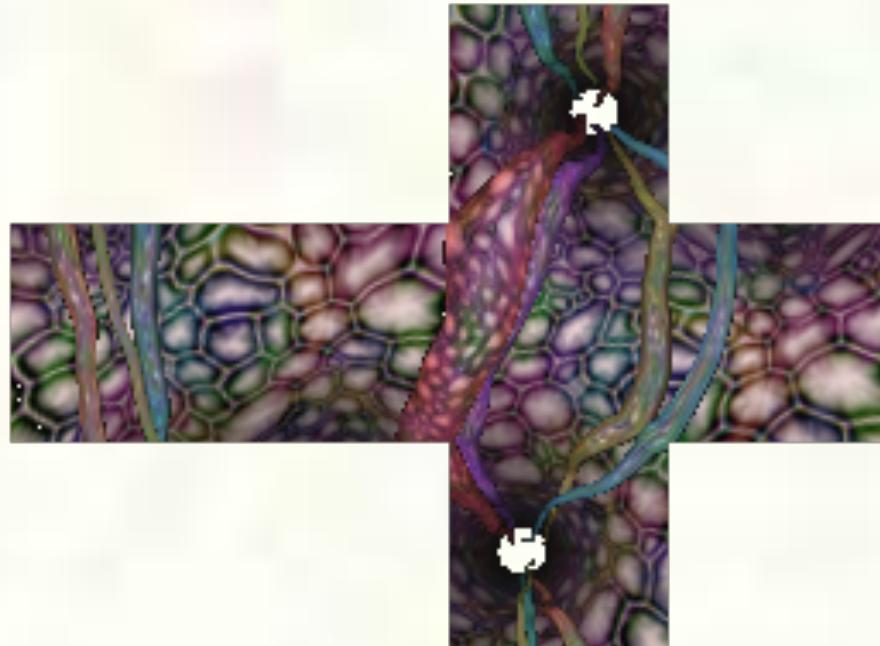
Omni-directional Lighting



*Access texture
by surface reflection
vector*



Dynamic Cube Map Textures

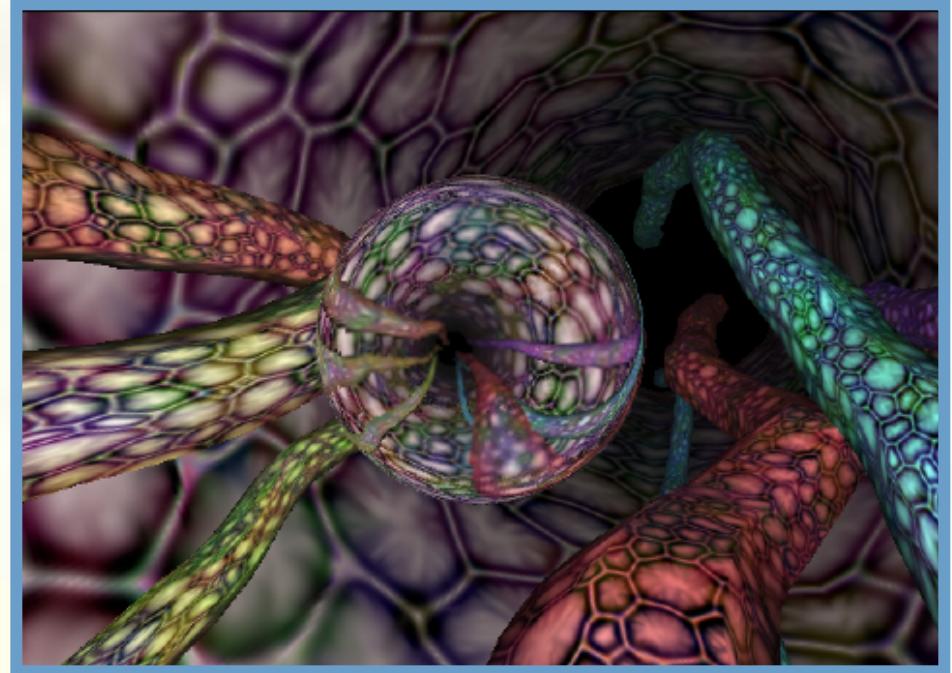


*Dynamically created
cube map image*

Image credit:

*“Guts” GeForce 2 GTS demo,
Thant Thessman*

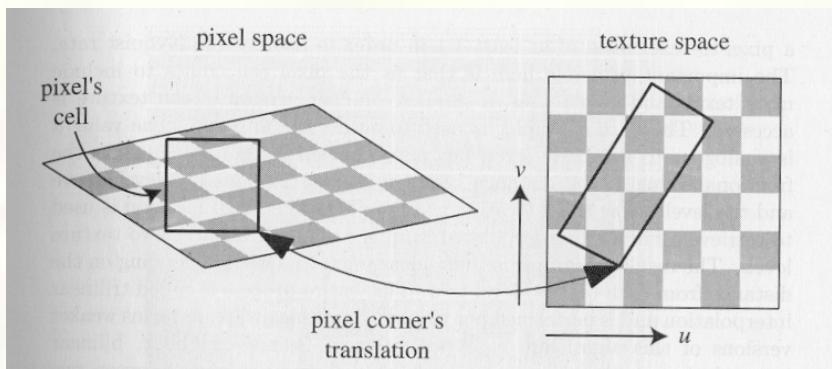
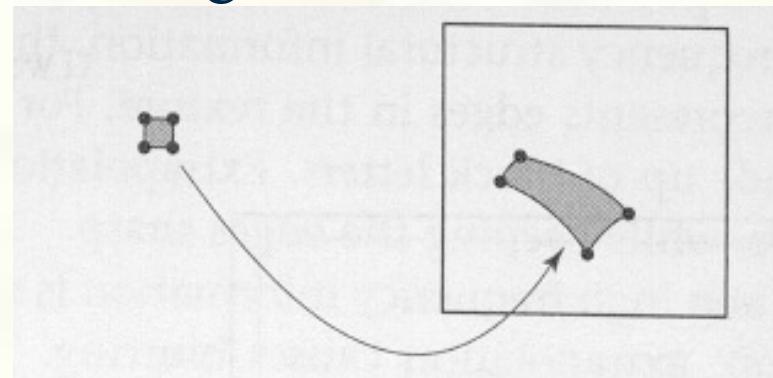
Rendered scene





How do we anti-alias textures?

- We could just super-sample.
- But textures (and shader programs) are a special case; we can use true area integration!



- *Approximate footprint as parallelogram*
- *Determine this approximate footprint using discrete differences*



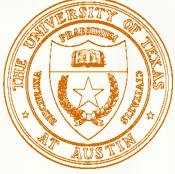
Pre-filtered Image Versions

- Base texture image is say 256x256
 - Then down-sample 128x128, 64x64, 32x32, all the way down to 1x1



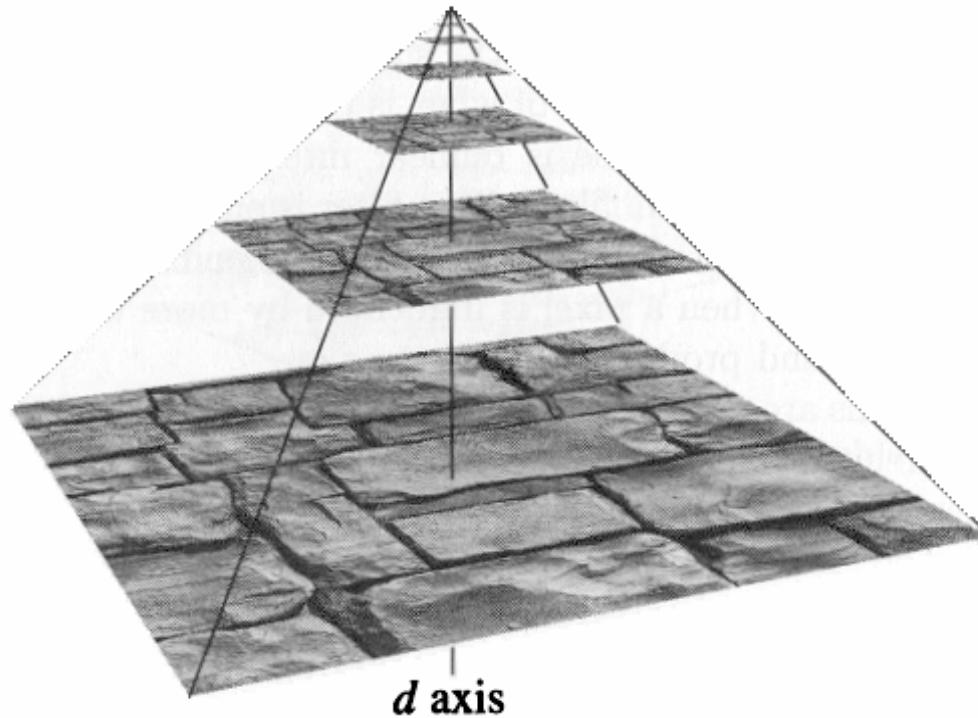
Trick: When sampling the texture, pixel the mipmap level with the closest mapping of pixel to texel size

Why? Hardware wants to sample just a small (1 to 8) number of samples for every fetch—and want constant time access

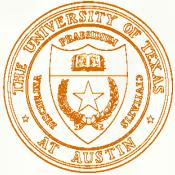


Cost of filtering can be reduced

- Store a pyramid of pre-filtered images:

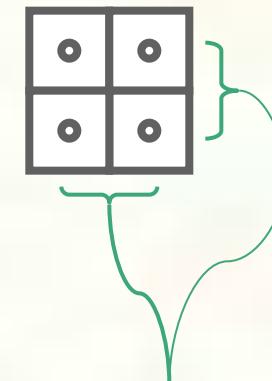


- During texture lookup, read from appropriate level of the pyramid.

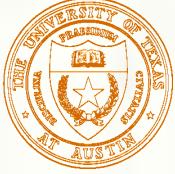


Mipmap LOD Selection

- Tri-linear mip-mapping means compute appropriate mipmap level
- Hardware rasterizes in 2x2 pixel entities
 - Typically called quad-pixels or just *quad*
 - Finite difference with neighbors to get change in u and v with respect to window space
 - Approximation to $\partial u / \partial x$, $\partial u / \partial y$, $\partial v / \partial x$, $\partial v / \partial y$
 - Means 4 subtractions per quad (1 per pixel)
- Now compute approximation to gradient length
 - $p = \max(\sqrt{(\partial u / \partial x)^2 + (\partial u / \partial y)^2}, \sqrt{(\partial v / \partial x)^2 + (\partial v / \partial y)^2})$



one-pixel separation



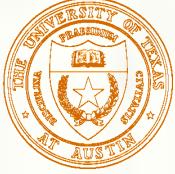
LOD Bias and Clamping

- Convert p length to power-of-two level-of-detail and apply LOD bias
 - $\lambda = \log_2(p) + \text{lodBias}$
- Now clamp λ to valid LOD range
 - $\lambda' = \max(\min\text{LOD}, \min(\max\text{LOD}, \lambda))$



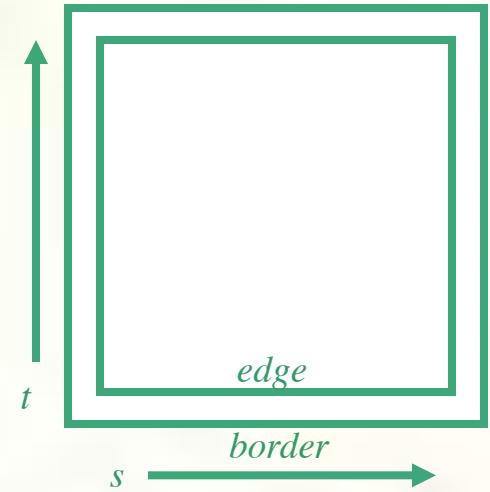
Determine Levels and Interpolant

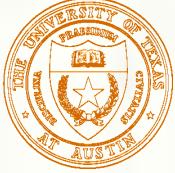
- Determine lower and upper mipmap levels
 - $b = \text{floor}(\lambda')$ is bottom mipmap level
 - $t = \text{floor}(\lambda' + 1)$ is top mipmap level
- Determine filter weight between levels
 - $w = \text{frac}(\lambda')$ is filter weight



Determine Texture Sample Point

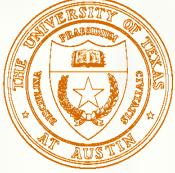
- Get (u, v) for selected top and bottom mipmap levels
 - Consider a level l which could be either level t or b
 - With (u, v) locations (u_l, v_l)
- Perform `GL_CLAMP_TO_EDGE` wrap modes
 - $u_w = \max(1/2 * \text{widthOfLevel}(l), \min(1 - 1/2 * \text{widthOfLevel}(l), u))$
 - $v_w = \max(1/2 * \text{heightOfLevel}(l), \min(1 - 1/2 * \text{heightOfLevel}(l), v))$
- Get integer location (i, j) within each level
 - $(i, j) = (\text{floor}(u_w * \text{widthOfLevel}(l)), \text{floor}(v_w *))$





Determine Texel Locations

- Bilinear sample needs 4 texel locations
 - $(i_0, j_0), (i_0, j_1), (i_1, j_0), (i_1, j_1)$
- With integer texel coordinates
 - $i_0 = \text{floor}(i - 1/2)$
 - $i_1 = \text{floor}(i + 1/2)$
 - $j_0 = \text{floor}(j - 1/2)$
 - $j_1 = \text{floor}(j + 1/2)$
- Also compute fractional weights for bilinear filtering
 - $a = \text{frac}(i - 1/2)$
 - $b = \text{frac}(j - 1/2)$



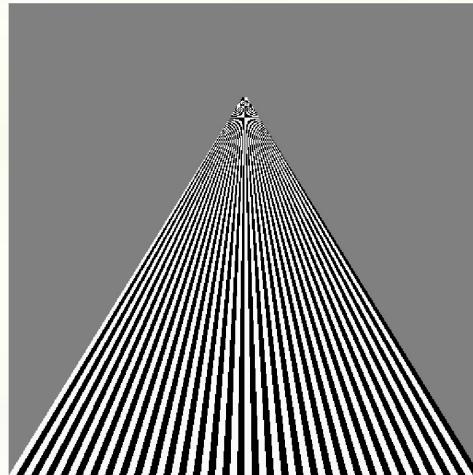
Determine Texel Addresses

- Assuming a texture level image's base pointer, compute a texel address of each texel to fetch
 - Assume $\text{bytesPerTexel} = 4$ bytes for RGBA8 texture
- Example
 - $\text{addr00} = \text{baseOfLevel}(l) + \text{bytesPerTexel} * (\text{i0} + \text{j0} * \text{widthOfLevel}(l))$
 - $\text{addr01} = \text{baseOfLevel}(l) + \text{bytesPerTexel} * (\text{i0} + \text{j1} * \text{widthOfLevel}(l))$
 - $\text{addr10} = \text{baseOfLevel}(l) + \text{bytesPerTexel} * (\text{i1} + \text{j0} * \text{widthOfLevel}(l))$
 - $\text{addr11} = \text{baseOfLevel}(l) + \text{bytesPerTexel} * (\text{i1} + \text{j1} * \text{widthOfLevel}(l))$
- More complicated address schemes are needed for good texture locality!

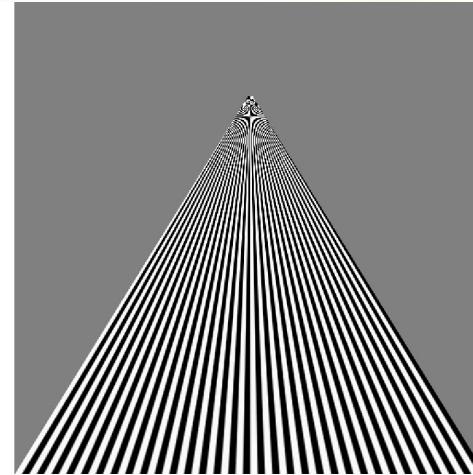


Mipmap Texture Filtering

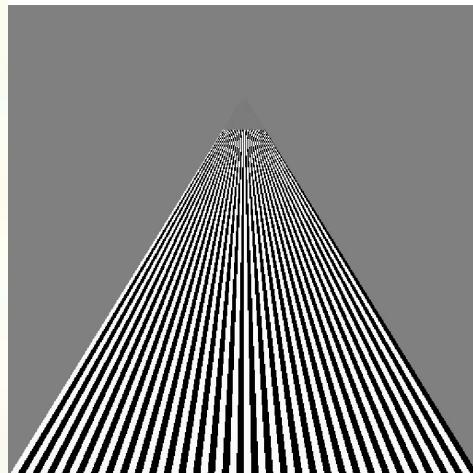
*point
sampling*



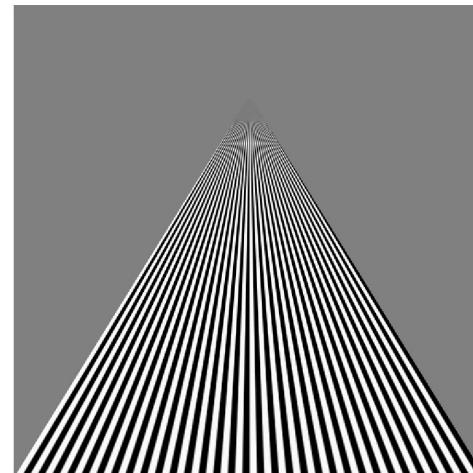
*linear
filtering*

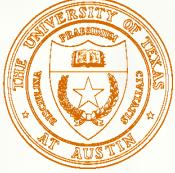


*mipmapped
point
sampling*



*mipmapped
linear
filtering*





Anisotropic Texture Filteringing

- Standard (isotropic) mipmap LOD selection
 - Uses magnitude of texture coordinate gradient (not direction)
 - Tends to spread blurring at shallow viewing angles
- Anisotropic texture filtering considers gradients direction
 - Minimizes blurring



Isotropic



Anisotropic