

SOLN. Q1 SAMPLES

T.1

BFS [A possible Soln]

Frige has (A)

Nodes Popped	States Added to Closed	Nodes Added to Frige.
(A)	A	(B) (C)
(B)	B	(A) (C) (E) (D)
(C)	C	(A) (B) (E)
(A)	—	—
(C)	—	—
(E)	E	(C) (B) (D) (F)
(D)	D	(B) (E) (F)
(A)	—	—
(B)	—	—

(E)		—		—
(C)		—		—
(B)		—		—
(D)		—		—
(F)				
==				

Goal Found

DFS [A Possible Solution]

Frige has (A)

Nodes Popped	States Added to Closed	Nodes Added to Frige
(A)	A	(B) (C)
(C)	C	(A) (B) (E)
(E)	E	(C) (B) (D) (F)

B

Goal Found.

IDS [A Possible Soln]

Set $l = 0$ Fringe has A/o --- Depth.

Nodes Popped	States added to closed	Nodes Added to Fringe
<u>A/o</u>	—	—
—	—	—

Search Failed

Set $l = 1$, Fringe has $(A/0)$

Nodes Popped	States added to closed	Nodes added to Fringe
$(A/0)$	A	$(B/1)$ $(C/1)$
$(C/1)$	—	—
$(B/1)$	—	—
—	—	—

Search Failed.

Set $l = 2$, Fringe has $(A/0)$

Nodes Popped	St in closed	Nodes in Fringe
$(A/0)$	A	$(B/1)$ $(C/1)$
$(C/1)$	C	$(A/2)$ $(B/2)$ $(E/2)$
$(E/2)$	—	—

$B_{1/2}$	—	—
$A_{1/2}$	—	—
$B_{1/1}$	B	$A_{1/2}$ $C_{1/2}$ $E_{1/2}$ $D_{1/2}$
$D_{1/2}$	—	—
$E_{1/2}$	—	—
$C_{1/2}$	—	—
$A_{1/2}$	—	—
—	—	—

Search Failed.

Set $l=3$. Any ~~the~~ has $(A/0)$

Nodes Popped	States Added to Cloud	Nodes Added to Tree.
$(A/0)$	A	$(B/1)$ $(C/1)$
$(C/1)$	C	$(A/2)$ $(B/2)$ $(E/2)$
$(E/2)$	E	$(C/3)$ $(B/3)$ $(D/3)$ $(F/3)$
$(F/3)$	—	—

Grail Ford.

VCS [A Possible Solution]

Frige has $(A/0) \dots g(n)$

Nodes Popped	States Added to Closed.	Nodes Added to Frige.
$(A/0)$	A	$(B/2)$ $(C/7)$
$(B/2)$	B	$(A/4)$ $(B/10)$ $(E/6)$ $(D/11)$
$(A/4)$	—	—
$(E/6)$	E	$(C/12)$ $(B/10)$ $(D/10)$ $(F/14)$
$(C/7)$	C	$(A/14)$ $(B/15)$ $(E/13)$
$(B/10)$	—	—
$(B/10)$	—	—
$(D/10)$	D	$(B/14)$ $(E/14)$ $(F/13)$
$(D/11)$	—	—
$(C/12)$	—	—

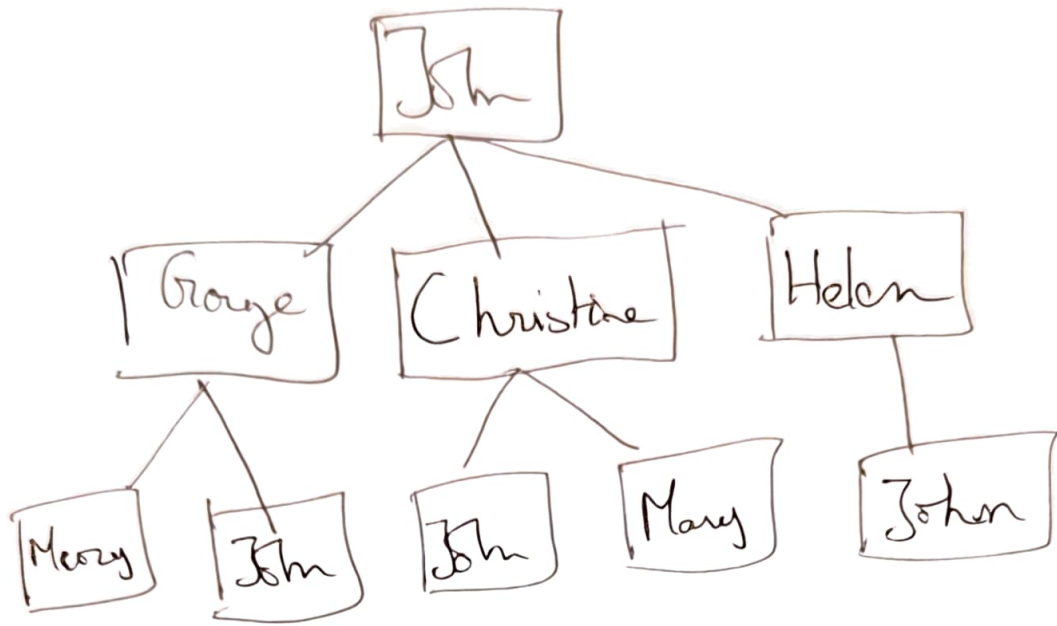


Goal Ford.

Task 2

- (i) Correct degree of separation requires path with fewest number of hops (Shallowest solution) since cost of any action is 1, BFS, UCS & IDS will give optimal solution.

(ii)



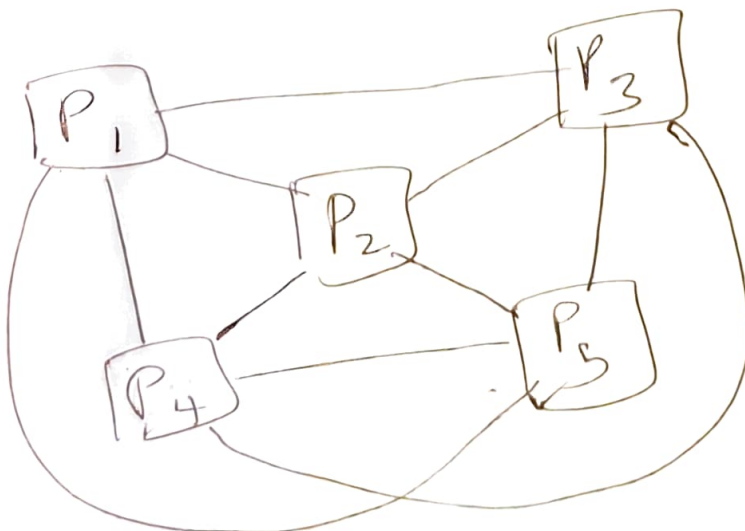
(iii)

No. As we can see above, the same state can be represented by many nodes.

(iv)



(v)



(vi)

For this we need to modify Tree Search with BFS for Graph search with BFS where the check against goal is done when a node is generated rather than when it is popped from the Queue.

T₃

H₁ NBT Admissible

$$h(B) \leq 17 \quad h(C) \leq 5$$

H₂ NBT Admissible

$$h(A) \leq 27 \quad h(B) \leq 17$$

$$h(C) \leq 5 \quad h(D) = 0$$

$$h(E) \leq 25 \quad h(F) \leq 9$$

H₃ & H₄ / Admissible As Is.

T₅

For Fig 4.

Consider 2, 1 as St.

~~4~~. 3 as Goal.

Greedy will explore fewer nodes
than A^*

Ex: 2, 1 \rightarrow 2, 2 \rightarrow 3, 2 \rightarrow 3, 3 \rightarrow 4, 3

But A^* : 2, 1; 2, 3; 3, 2; 3, 3; 3, 4; 4, 3; 4, 4

In all other scenarios, Greedy & A^* will explore
same set

Greedy performs better than or same as A^*

For Fig 5.

Depends on scenario

Greedy performs better than A^*

[E_x : 3,6 to 5,8]

worse than A^*

[E_x : 3,1 to 3,2]

are same as A^*

[E_x : 4,6 to 4,8]