Value Set Analysis in LLVM

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Value Set Analysis

Bounded Set Analysis:

$$Var \rightarrow \{a, b, c, ...\}_n$$

Interval Analysis:

$$Var \rightarrow [a:b]_n$$

Strided Interval Analysis:

$$Var \rightarrow s[a:b]_n$$

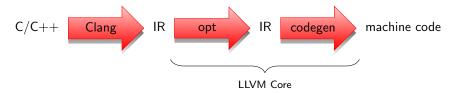
SSA \Rightarrow sufficient to store the abstract value for each variable once per basic block:¹

$$\mathcal{D}: BB o Var o Val$$

¹The need to store it not just once only arises to preserve information at conditional branches.

Passes in LLVM

LLVM's analysis and optimization framework opt:



using existing passes (from command line):

opt -load -mem2reg -o hello-opt.bc < hello.bc

running user passes:

opt -load llvm/lib/llvm-vsa.so -vsapass -o hello.bc < hello.bc

Passes in LLVM (cont.)

Creating user passes:

• inherit from existing passes (module, function, block):

```
struct ThisPass : public ModulePass {}
```

• specify required passes, which have to be run in advance:

```
void ThisPass::getAnalysisUsage(AnalysisUsage &AU) override {
  AU.setPreservesAll();
  AU.addRequired<OtherPass>();
}
```

perform analysis by using/accessing results of other passes:

```
bool ThisPass::runOnModule(Module &M) override {
   auto& other_result =
     getAnalysis<OtherPass>(function).getResult();
   /* ... perform analysis and fill result ... */

   // Return if the pass modified the bitcode (no)
   return false;
}
```

make results available for other pass (optional):

```
ThisResult& ThisPass::getResult(){    return result;    }
```

Example

```
int main(int argc, char const *argv[]) {
    unsigned a = 0, b = 12, c = rand();
    while (a < b) \{ a+=4; b-=2; \}
    if(a>6 && b<6){
        switch (a) {
            case 6: b = 99; break;
                                                       // reachable?
            case 12:
            case 13: b = a*2; break;
            default:
                c = c%18:
   } else {
       a = 88;
    }
    printf("%d\n", a);
                                 // what will/might be printed out?
    printf("%d\n", b);
    printf("%d\n", c);
```

LLVM's Intermediate Representation IR

```
define dso_local i32 @main(i32 %argc, i8** %argv) #0 {
entry:
   br label %while.cond
while.cond:
   %a.0 = phi i32 [ 0, %entry ], [ %add, %while.body ]
   %b.0 = phi i32 [ 12, %entry ], [ %sub, %while.body ]
   %cmp = icmp ult i32 %a.0, %b.0
   br i1 %cmp, label %while.body, label %while.end
while.body:
   %add = add i32 %a.0, 4
   %sub = sub i32 %b.0, 2
   br label %while.cond
while.end:
   %call = call i32 @rand() #3
   %cmp1 = icmp ugt i32 %a.0, 6
   br il %cmpl, label %land.lhs.true, label %if.else
land.lhs.true:
   %cmp2 = icmp ult i32 %b.0, 6
   br i1 %cmp2, label %if.then, label %if.else
```

... and many more lines of code

Content of the Lab

Tasks:

- implement abstract domains that suitably represent value sets
- develop a new analysis tool in LLVM to determine the value set of each variable, using visitor and fixpoint algorithm (worklist) ▷ VSAPass
- make results accessible via API: VSAResult and VSAResultValue
- compare results with LLVM's LazyValueInfo

Future work:

- widening and narrowing
- inter-procedural analysis
- memory access
 - unknowns (ops, return values and arguments of functions) treated as: \top

Part 1: **Abstract Domain**

Background to LLVM Integer Types

- In LLVM the type of *N*-bit integers is the set $iN := \{0,1\}^N$, for $N \in \{1,\ldots,2^{23}-1\}$.
- "i $N \cong \mathbb{Z}/2^N$ "
- In the in-memory-representation, these types are represented by the LLVM class APInt.
- This type is used for both signed and unsigned integers.
- We use APInt in our implementation of abstract domains.

LLVM Integer Operations

Arithmetic Operations:

In LLVM there are separate div and rem operations for signed and unsigned integers. For add, sub and mul, there is no such distinction needed.

- <result> = add [nuw] [nsw] <bitWidth> <op1> <op2>
- o <result> = sub [nuw] [nsw] <bitWidth> <op1> <op2>
- <result> = mul [nuw] [nsw] <bitWidth> <op1> <op2>
- <result> = udiv [exact] <bitWidth> <op1> <op2> 2
- <result> = sdiv [exact] <bitWidth> <op1> <op2> 2
- <result> = urem <bitWidth> <op1> <op2>
- <result> = srem <bitWidth> <op1> <op2>

nuw: "no unsigned wrap", nsw: "no signed wrap"

² exact-flag not used in our implementation.

LLVM Integer Operations (cont.)

Bitwise Operations:

- o <result> = shl [nuw] [nsw] <bitWidth> <op1> <op2>
- <result> = lshr [exact] <bitWidth> <op1> <op2> 3
- <result> = ashr [exact] <bitWidth> <op1> <op2> 3
- o <result> = and <bitWidth> <op1> <op2>
- o <result> = or <bitWidth> <op1> <op2>
- <result> = xor <bitWidth> <op1> <op2>

³ exact-flag not used in our implementation.

Bounded Set

- A bounded set represents a set of values up to a given cardinality k, or \top : $\mathrm{BS}_N \coloneqq \{M \in \mathcal{P}(\mathrm{i}N) \mid |M| \le k\} \dot{\cup} \{\top\}$
- ullet und \sqsubseteq on bounded sets essentially reduce to \cup and \subseteq on sets.
- Any set with more elements than k is over-approximated by \top .

•
$$\gamma_{BS_N} \colon \mathrm{BS}_N \to \mathcal{P}(\mathtt{i} N), \, b \mapsto \begin{cases} \mathtt{i} N, & \text{if } b = \top \\ b, & \text{otherwise} \end{cases}$$

Modular Strided Interval (MSI)

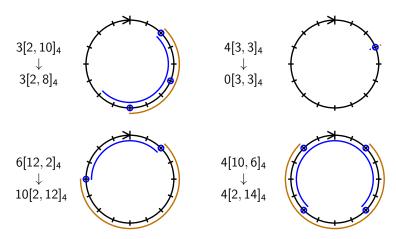
- Intervals:
 - ▶ I := [a, b], for $a, b \in \mathbb{Z}$
- Strided Intervals:
 - ▶ SI := s[a, b], for $a, b \in \mathbb{Z}$, $s \in \mathbb{N}$
- Modular Strided Intervals:
 - ▶ $MSI_N := \{s[\overline{a}, \overline{b}]_N \mid \overline{a}, \overline{b} \in \mathbb{Z}/2^N, s \in \{0, \dots, 2^N\}\} \dot{\cup} \{\bot\}$
 - $ightharpoonup \gamma_{\mathsf{MSI}_N} \colon \mathsf{MSI}_N o \mathcal{P}(\mathtt{i} N),$

$$i \mapsto \begin{cases} \emptyset, & \text{if } i = \bot \\ \{k + 2^N \mathbb{Z} \mid k \in \mathbb{Z}, a \leq k \leq c, k \equiv a \mod s\}, \ , & \text{if } i = s[\overline{a}, \overline{b}]_N \\ \text{where } c = \min\{x \in \mathbb{Z} \mid x \geq a, \\ x \equiv b \mod 2^N \} \end{cases}$$

- Examples:
 - * $12[15,63]_8 \xrightarrow{\gamma} \{15,27,39,51,63\} \subseteq \mathbb{Z}/2^8$
 - * $4[10,6]_4 \xrightarrow{\gamma} \{10,14,2,6\} \subseteq \mathbb{Z}/2^4$

Modular Strided Interval: Normalization

Note that some sets can be represented by muliple MSIs. Thus, we introduce a predicate *normal*, such that there is at most one *normalized* representation. Examples:



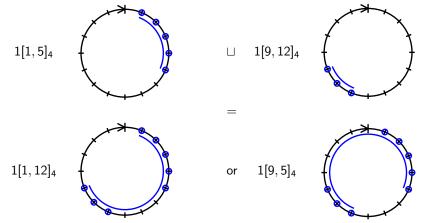
Modular Strided Interval: Normalization (cont.)

```
\begin{aligned} & \mathsf{normal}_{N}(s[\overline{a},\overline{b}]_{N}) \leftrightarrow (\\ & \overline{a} = \overline{b} \to s = 0 \\ & \land \overline{b} \in \gamma_{N}(s[\overline{a},\overline{b}]_{N}) \\ & \land \overline{a} = \min\{a' \in \{0 \dots 2^{N} - 1\}.\,\exists s',\overline{b}'.\,\gamma_{N}(s'[\overline{a'},\overline{b'}]_{N}) = \gamma_{N}(s[\overline{a},\overline{b}]_{N})\} + 2^{N}\mathbb{Z} \end{aligned}
```

Modular Strided Interval: Union

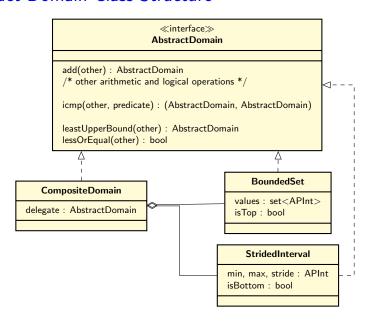
MSIs do not form a lattice, as, in general, there is no *least* upper bound of two elements.

Example:



Therefore we try to find a minimal upper bound wrt. $|\gamma(\cdot)|$.

Abstract Domain Class Structure



Application Interface

VSAResult

is_reachable(basic_block) : bool is_resultat_available(bb, value) : bool get_abstract_value() : VSAResultValue

VSAResultValue

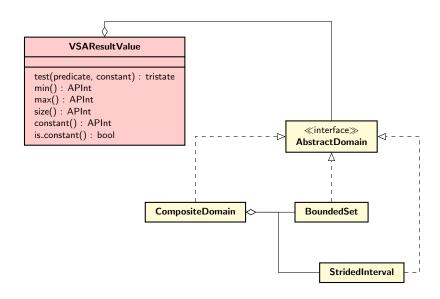
test(predicate, constant) : tristate min() : APInt

max() : APInt
size() : APInt
constant() : APInt
is_constant() : bool

after a successful pass: auto& res = vsap.get_result();

 query information related to basic block (reachable or not) and/or variable (abstract value)

Connection of the Results to the Internal Abstract Domain



Fixpoint Algorithm & Visitor

Data Structures

Data structures maintained during the analysis:

• state of each basic block (goal):

red: abstract domain

$$\mathcal{D}: BB o \underbrace{\left(\textit{Var} o \underbrace{\textit{Val}} \right)_{\perp}}_{\textit{state } \mathcal{D}_{\textit{BB}}}$$

branch conditions:

$$C: \underbrace{(BB \to XX)}_{edge} \to \underbrace{(Var \to Val)_{\perp}}_{C_{BB \to XX}}$$

 \rightarrow effect of a guard:

$$\mathcal{D}_{XX} \leftarrow \llbracket BB \, \rightarrow \, XX \rrbracket \, \mathcal{D}_{BB} = \mathcal{D}_{BB} \, \oplus \, \mathcal{C}_{BB \rightarrow XX}$$

Fixpoint Algorithm: Worklist

We maintain a worklist \mathcal{W} of basic blocks to be (re)evaluated.

Algorithm 1 Fixpoint algorithm

- 1: **procedure** FIXPOINT(Function)
- 2: \mathcal{W} .push(Function.front())
- 3: while $! \mathcal{W}.empty()$ then:
- 4: $visit \mathcal{W}.pop()$

Fixpoint algorithm terminates iff \mathcal{W} is empty: a fixpoint has been found.

Following initial and entry states are used (forward analysis):

$$\mathcal{D}_0: \mathit{BB} o \bot$$
 and $\mathcal{D}_{\mathit{entry}}: \mathit{BB} o (\mathit{Arg}_i o \top)$

push entry basic block of function

Visitor: (Entering) Basic Block

Visiting a basic block is a two-step process:

- lacktriangledown setting up the (temporary) input state \mathcal{N}_{BB} during entering
- visiting all its instructions

Algorithm 2 Enter basic block BB

```
1: procedure Visit(BB)
```

- 2: $\mathcal{N}_{BB} = \coprod \{ \mathcal{D}_{XX} \oplus \mathcal{C}_{XX \to BB} \mid XX \in \text{prev}(BB) \land \mathcal{D}_{XX} \neq \bot \}$
- 3: **for each** $instruction \in instructions(BB)$:
- 4: visit instruction

Explicitly considered instructions:

- terminators: (un)conditional jumps, switches
- PHI nodes
- binary expressions

Visitor: Leaving Basic Block at Terminator

check for change of the local state and save it in \mathcal{D} :

```
Algorithm 3 Visit terminator
 1: procedure VISIT(Terminator)
        if \mathcal{N}_{BB} \sqsubseteq \mathcal{D}_{BB} then:
                                                      ▷ red: delegated to abstract domain
 2:
                                                                    3.
              return
     \mathcal{D}_{BB} \leftarrow \mathcal{N}_{RR}
 4.
        for each XX \in next(BB):
 5.
              if reachable(BB, XX) then:
 6.
                    \mathcal{W}.push(XX)
 7:
```

in the case of change ($\mathcal{N}_{BB} \not\sqsubseteq \mathcal{D}_{BB}$), push all reachable successors:

- unconditional branch: push all successors
- conditional branch/switch: check if $\exists (\# \to \bot) \in \mathcal{C}_{BB \to XX}$

Visitor: Conditional Branch

Algorithm 4 Visit conditional branch (terminator)

```
1: procedure VISIT(JMP (x \square y ? XX : YY))
2: if isVar(x) then:
3: C_{BB \to XX} \leftarrow C_{BB \to XX} \oplus \{x \to \mathcal{N}_{BB}[x] \square^{\#} \mathcal{N}_{BB}[y]\}
4: C_{BB \to YY} \leftarrow C_{BB \to YY} \oplus \{x \to \mathcal{N}_{BB}[x] ! \square^{\#} \mathcal{N}_{BB}[y]\}
5: if isVar(y) then:
6: ...
7: VISITTERMINATOR()
```

considered comparisons:

$$\Box \in \{=, \neq, <, \leq, \geq, >\}$$

Visitor: Switch

Algorithm 5 Visit switch (terminator)

```
1: procedure Visit (SWITCH [x = a : XX][x = b : YY][x = c : YY][default : ZZ])
```

- 2: $\mathcal{C}_{BB \to XX} \leftarrow \{x \to \mathcal{N}_{BB}[x] = a\}$
- 3: $\mathcal{C}_{BB\to YY} \leftarrow \{x \to (\mathcal{N}_{BB}[x] = b) \sqcup (\mathcal{N}_{BB}[x] = c)\}$
- 4: $C_{BB \to ZZ} \leftarrow \{x \to \mathcal{N}_{BB}[x] \setminus \{a, b, c\}\}$
- 5: VisitTerminator()

Visitor: Parallel Assignments at PHI Node

Algorithm 6 PHI node in basic block BB

- 1: **procedure** PHI($x \leftarrow [YY : y][ZZ : z]$)
- 2: $\mathcal{N}_{BB} \leftarrow \mathcal{N}_{BB} \oplus \{x \rightarrow (\mathcal{D}_{YY} \oplus C_{YY \rightarrow BB})[y] \sqcup (\mathcal{D}_{ZZ} \oplus C_{ZZ \rightarrow BB})[z]\}$

Visitor: Binary Expressions

Algorithm 7 Addition in basic block BB

- 1: **procedure** BINARY $(x \leftarrow y \Box z)$
- 2: $\mathcal{N}_{BB} \leftarrow \mathcal{N}_{BB} \oplus \{x \rightarrow \mathcal{N}_{BB}[y] \square^{\#} \mathcal{N}_{BB}[z]\}$

considered binary instructions:

$$\square \in \{+,\,-,\,\times,\,/,\,\%,\,\ll,\,\gg\}$$

Visitor: Memory access and Not-implemented Operations

Data in memory is considered unknown.

Algorithm 8 Load in basic block BB

- 1: **procedure** $Visit(x \leftarrow LOAD(...))$
- 2: $\mathcal{N}_{BB} \leftarrow \mathcal{N}_{BB} \oplus \{x \rightarrow \top\}$

Not-implemented operations of form $x \leftarrow \#$ are treated implicitly in the same way.

Part 3: Livedemo

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