

# Value Set Analysis in LLVM

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Part 0:

# Introduction

# Value Set Analysis

## Bounded Set Analysis:

$$Var \rightarrow \{a, b, c, \dots\}_n$$

## Interval Analysis:

$$Var \rightarrow [a : b]_n$$

## Strided Interval Analysis:

$$Var \rightarrow s[a : b]_n$$

SSA: sufficient to store the abstract value for each variable once per basic block:<sup>1</sup>

$$\mathcal{D} : BB \rightarrow Var \rightarrow Val$$

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<sup>1</sup>The need to store it not just once only arises to preserve information at conditional branches.

# Passes in LLVM

LLVM's analysis and optimization framework `opt`:

Figure: stages of clang and LLVM

using existing passes (from command line):

```
opt -load -mem2reg -o hello-opt.bc < hello.bc
```

running user passes:

```
opt -load llvm/lib/llvm-vsa.so -vsapass -o hello.bc < hello.bc
```

# Passes in LLVM (cont.)

## Creating user passes:

- inherit from existing passes (module, function, block):

```
struct ThisPass : public ModulePass {}
```

- specify required passes, which have to be run in advance:

```
void ThisPass::getAnalysisUsage(AnalysisUsage &AU) override {  
    AU.setPreservesAll();  
    AU.addRequired<OtherPass>();  
}
```

- perform analysis by using/accessing results of other passes:

```
bool ThisPass::runOnModule(Module &M) override {  
    auto& other_result =  
        getAnalysis<OtherPass>(function).getResult();  
    /* ... perform analysis and fill result ... */  
  
    // Return if the pass modified the bitcode (no)  
    return false;  
}
```

- make results available for other pass (optional):

```
ThisResult& ThisPass::getResult(){ return result; }
```

# Content of the Lab

## Tasks:

- implement [abstract domains](#) that suitably represent value sets
- develop a new analysis tool in LLVM to determine the value set of each variable, using visitor and fixpoint algorithm (worklist) ▷ [VSAPass](#)
- make results accessible via API: [VSAResult](#) and [VSAResultValue](#)
- compare results with LLVM's [LazyValueInfo](#)

## Future work:

- widening and narrowing
- inter-procedural analysis
- memory access

unknowns (ops, return values and arguments of functions) treated as: [T](#)

Part 1:

# Abstract Domain

# Background to LLVM Integer Types

- In LLVM the type of  $N$ -bit integers is the set  $iN := \{0, 1\}^N$ , for  $N \in \{1, \dots, 2^{23} - 1\}$ .
- " $iN \cong \mathbb{Z}/2^N$ "
- In the in-memory-representation, these types are represented by the LLVM class APInt.
- This type is used for both signed and unsigned integers.
- We use APInt in our implementation of abstract domains.



# LLVM Integer Operations

## Arithmetic Operations:

In LLVM there are separate `div` and `rem` operations for signed and unsigned integers. For `add`, `sub` and `mul`, there is no such distinction needed.

- `<result> = add [nuw] [nsw] <bitWidth> <op1> <op2>`
- `<result> = sub [nuw] [nsw] <bitWidth> <op1> <op2>`
- `<result> = mul [nuw] [nsw] <bitWidth> <op1> <op2>`
- `<result> = udiv [exact] <bitWidth> <op1> <op2>`<sup>2</sup>
- `<result> = sdiv [exact] <bitWidth> <op1> <op2>`<sup>2</sup>
- `<result> = urem <bitWidth> <op1> <op2>`
- `<result> = srem <bitWidth> <op1> <op2>`

`nuw` : "no unsigned wrap", `nsw` : "no signed wrap"

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<sup>2</sup> exact-flag not used in our implementation.

# LLVM Integer Operations, Continued

## Bitwise Operations:

- `<result> = shl [nuw] [nsw] <bitWidth> <op1> <op2>`
- `<result> = lshr [exact] <bitWidth> <op1> <op2>`<sup>3</sup>
- `<result> = ashr [exact] <bitWidth> <op1> <op2>`<sup>3</sup>
- `<result> = and <bitWidth> <op1> <op2>`
- `<result> = or <bitWidth> <op1> <op2>`
- `<result> = xor <bitWidth> <op1> <op2>`

---

<sup>3</sup> exact-flag not used in our implementation.

# Bounded Set

- A bounded set represents a set of values up to a given cardinality  $k$ , or  $\top$ :  
$$\text{BS}_N := \{M \in \mathcal{P}(\mathfrak{i}N) \mid |M| \leq k\} \dot{\cup} \{\top\}$$
- $\sqcup$  and  $\sqsubseteq$  on bounded sets essentially reduce to  $\cup$  and  $\subseteq$  on sets.
- Any set with more elements than  $k$  is over-approximated by  $\top$ .
- $\gamma_{\text{BS}_N}: \text{BS}_N \rightarrow \mathcal{P}(\mathfrak{i}N), b \mapsto \begin{cases} \mathfrak{i}N, & \text{if } b = \top \\ b, & \text{otherwise} \end{cases}$

# Modular Strided Interval

- Intervals:

- ▶  $I := [a, b]$ , for  $a, b \in \mathbb{Z}$

- Strided Intervals:

- ▶  $SI := s[a, b]$ , for  $a, b \in \mathbb{Z}, s \in \mathbb{N}$
- ▶  $\gamma_{SI}, s[a, b] \mapsto \{k \in \mathbb{Z} \mid a \leq k \leq b, k \equiv a \pmod{s}\}$

- Modular Strided Intervals:

- ▶  $MSI_N := \{\bar{s}[\bar{a}, \bar{b}]_N \mid \bar{a}, \bar{b}, \bar{s} \in \mathbb{Z}/2^N\} \dot{\cup} \{\perp\}$
- ▶  $\gamma_{MSI_N}, s[a, b]_N \mapsto \{k + 2^N \mathbb{Z} \mid k \in \mathbb{Z}, a \leq k \leq z, k \equiv a \pmod{s}\}$ ,  
where  $z = \min\{l \in \mathbb{Z} \mid l \geq a, l \equiv b \pmod{2^N}\}$
- ▶ Examples:
  - ★  $12[15, 63]_8 \xrightarrow{\gamma} \{15, 27, 39, 51, 63\} \subseteq \mathbb{Z}/2^8$
  - ★  $4[10, 6]_4 \xrightarrow{\gamma} \{10, 14, 2, 6\} \subseteq \mathbb{Z}/2^4$

# Modular Strided Interval: Normalization

Note that the representation of a set by a modular strided interval may not be unique. Thus, we introduce a predicate *normal*, such that there is always a unique *normalized* representation. Example:

$$\text{normal}_N(\bar{s}[\bar{a}, \bar{b}]_N) \leftrightarrow ($$

$$\bar{s} = 0 \leftrightarrow \bar{a} = \bar{b}$$

$$\wedge \bar{b} \in \gamma_N(\bar{s}[\bar{a}, \bar{b}]_N)$$

$$\wedge \bar{a} = \min\{a' \in \{0 \dots 2^N - 1\}. \gamma_N(\bar{s}[\bar{a}', \bar{b}]_N) = \gamma_N(\bar{s}[\bar{a}, \bar{b}]_N)\} + 2^N \mathbb{Z}$$

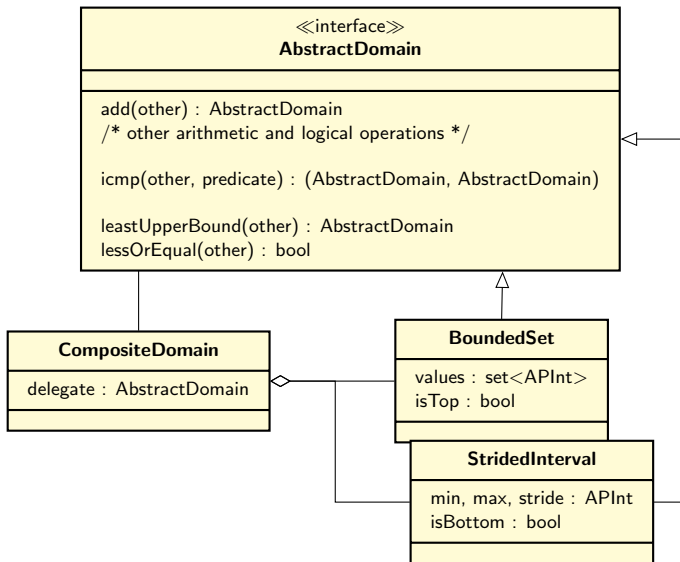
)

# Modular Strided Interval: Union

Modular strided intervals do not form a lattice, as, in general, there is no least upper bound of two elements.

Example:

# Abstract Domain Class Structure



# Application Interface

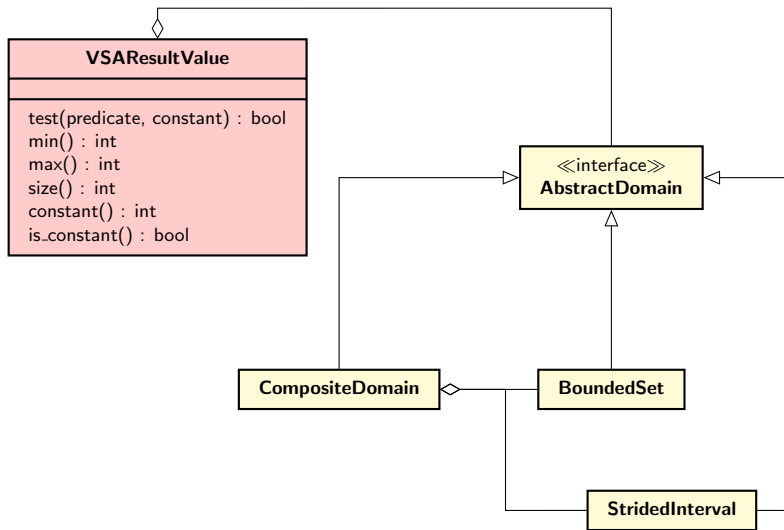
VSAResult
<code>is_reachable(basic_block) : bool</code> <code>is_resultat_available(bb, value) : bool</code> <code>get_abstract_value() : VSAResultValue</code>

VSAResultValue
<code>test(predicate, constant) : tristate</code> <code>min() : int</code> <code>max() : int</code> <code>size() : int</code> <code>constant() : int</code> <code>is_constant() : bool</code>

- after a successful pass:  
`auto& res = vsap.get_result();`
- query information related to  
basic block (reachable or not)  
and/or variable (abstract value)



# Connection of the Results to the Internal Abstract Domain



Part 2:

## **Fixpoint Algorithm & Visitor**

# Data Structures

Data structures maintained during the analysis:

- **state** of each basic block (goal):

red: abstract domain

$$\mathcal{D} : BB \rightarrow \underbrace{(Var \rightarrow \textcolor{red}{Val})}_{\text{state } \mathcal{D}_{BB}} \perp$$

- **branch conditions:**

$$\mathcal{C} : \underbrace{(BB \rightarrow XX)}_{\text{edge}} \rightarrow \underbrace{(Var \rightarrow \textcolor{red}{Val})}_{\mathcal{C}_{BB \rightarrow XX}} \perp$$

→ effect of a guard:

$$\mathcal{D}_{XX} \leftarrow \llbracket BB \rightarrow XX \rrbracket \mathcal{D}_{BB} = \mathcal{D}_{BB} \oplus \mathcal{C}_{BB \rightarrow XX}$$

# Fixpoint Algorithm: Worklist

We maintain a **worklist**  $\mathcal{W}$  of basic blocks to be (re)evaluated.

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**Algorithm 1** Fixpoint algorithm

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```
1: procedure FIXPOINT(Function)
2:    $\mathcal{W}.\text{push}(\text{Function}.\text{front}())$             $\triangleright$  push entry basic block of function
3:   while ! $\mathcal{W}.\text{empty}()$  then:
4:     visit  $\mathcal{W}.\text{pop}()$ 
```

---

Fixpoint algorithm terminates iff  $\mathcal{W}$  is empty: a fixpoint has been found.

Following **initial and boundary conditions** are used (forward analysis):

$$\mathcal{D}_0 : BB \rightarrow \perp \quad \text{and} \quad \mathcal{D}_{BC} : BB \rightarrow (Var \rightarrow \top)$$

# Visitor: (Entering) Basic Block

Visiting a basic block is a two-step process:

- 1 setting up the (temporary) input state  $\mathcal{N}_{BB}$  during entering
- 2 visiting all its instructions

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## Algorithm 2 Enter basic block BB

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```
1: procedure VISIT(BB)
2:    $\mathcal{N}_{BB} = \bigsqcup \{ \mathcal{D}_{XX} \oplus \mathcal{C}_{XX \rightarrow BB} \mid XX \in \text{prev}(BB) \wedge \mathcal{D}_{XX} \neq \perp \}$ 
3:   for each instruction  $\in$  instructions(BB):
4:     visit instruction
```

---

Explicitly considered instructions:

- terminators: (un)conditional jumps, switches
- PHI nodes
- binary expressions

# Visitor: Leaving Basic Block at Terminator

check for change of the local state and save it in  $\mathcal{D}$ :

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## Algorithm 3 Visit terminator

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```
1: procedure VISIT(Terminator)
2:   if  $\mathcal{N}_{BB} \sqsubseteq \mathcal{D}_{BB}$  then:                                ▷ red: delegated to abstract domain
3:     return                                                    ▷ state has not changed
4:    $\mathcal{D}_{BB} \leftarrow \mathcal{N}_{BB}$ 
5:   for each  $XX \in \text{next}(BB)$ :
6:     if  $\text{reachable}(BB, XX)$  then:
7:        $\mathcal{W}.\text{push}(XX)$ 
```

---

in the case of change ( $\mathcal{N}_{BB} \not\sqsubseteq \mathcal{D}_{BB}$ ), push all reachable successors:

- unconditional branch: push all successors
- conditional branch/switch: check if  $\exists(\# \rightarrow \perp) \in \mathcal{C}_{BB \rightarrow XX}$

# Visitor: Conditional Branch

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**Algorithm 4** Visit conditional branch (terminator)

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```
1: procedure VISIT(JMP ( $x \square y ? XX : YY$ ))
2:   if isVar( $x$ ) then:
3:      $C_{BB \rightarrow XX} \leftarrow C_{BB \rightarrow XX} \oplus \{x \rightarrow \mathcal{N}_{BB}[x] \square^{\#} \mathcal{N}_{BB}[y]\}$ 
4:      $C_{BB \rightarrow YY} \leftarrow C_{BB \rightarrow YY} \oplus \{x \rightarrow \mathcal{N}_{BB}[x] !\square^{\#} \mathcal{N}_{BB}[y]\}$ 
5:   if isVar( $y$ ) then:
6:     ...
7:   VISITTERMINATOR()
```

---

considered comparisons:

$$\square \in \{=, \neq, <, \leq, \geq, >\}$$

## Visitor: Switch

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### Algorithm 5 Visit switch (terminator)

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```
1: procedure VISIT(SWITCH [ $x = a : XX$ ][ $x = b : YY$ ][ $x = c : YY$ ][default :  $ZZ$ ])
2:    $\mathcal{C}_{BB \rightarrow XX} \leftarrow \{x \rightarrow \mathcal{N}_{BB}[x] =^{\#} a\}$ 
3:    $\mathcal{C}_{BB \rightarrow YY} \leftarrow \{x \rightarrow \mathcal{N}_{BB}[x] =^{\#} b \sqcup c\}$ 
4:    $\mathcal{C}_{BB \rightarrow ZZ} \leftarrow \{x \rightarrow \mathcal{N}_{BB}[x] \setminus \{a, b, c\}\}$ 
5:   VISIT_TERMINATOR()
```

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## Visitor: Parallel Assignments at PHI Node

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**Algorithm 6** PHI node in basic block BB

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- 1: **procedure** PHI( $x \leftarrow [YY : y][ZZ : z]$ )
  - 2:  $\mathcal{N}_{BB} \leftarrow \mathcal{N}_{BB} \oplus \{x \rightarrow (\mathcal{D}_{YY} \oplus C_{YY \rightarrow BB})[y] \sqcup (\mathcal{D}_{ZZ} \oplus C_{ZZ \rightarrow BB})[z]\}$
-

# Visitor: Binary Expressions

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**Algorithm 7** Addition in basic block BB

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- 1: **procedure** BINARY( $x \leftarrow y \square z$ )
  - 2:  $\mathcal{N}_{BB} \leftarrow \mathcal{N}_{BB} \oplus \{x \rightarrow \mathcal{N}_{BB}[y] \square^{\#} \mathcal{N}_{BB}[z]\}$
- 

considered binary instructions:

$$\square \in \{+, -, \times, /, \%, \ll, \gg\}$$

# Visitor: Memory access and Not-implemented Operations

Data in memory is considered unknown.

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**Algorithm 8** Load in basic block BB

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- 1: **procedure** BINARY( $x \leftarrow \text{LOAD}(\dots)$ )
  - 2:    $\mathcal{N}_{BB} \leftarrow \mathcal{N}_{BB} \oplus \{x \rightarrow \top\}$
- 

Not-implemented operations of form  $x \leftarrow \#$  are treated **implicitly** in the same way.

Part 3:

**Livedemo**

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