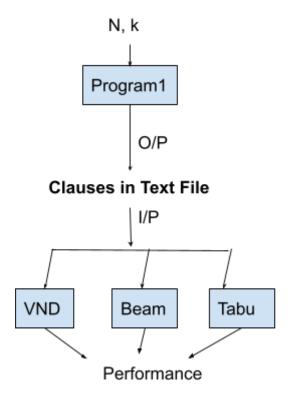
CS 312: Artificial Intelligence Assignment 3

Heuristic Search Algorithms

Domain: Uniform Random-4-SAT is a family of SAT problems distributions obtained by randomly generating 4-CNF formulae in the following way: For an instance with n=4 variables and k=5 clauses, each of the k clauses is constructed from 4 literals which are randomly drawn from the 2n possible literals (the n variables and their negations) such that each possible literal is selected with the same probability of 1/2n. Clauses are not accepted for the construction of the problem instance if they contain multiple copies of the same literal or if they are tautological (i.e., they contain a variable and its negation as a literal). Each choice of n and k thus induces a distribution of Random-4-SAT instances. Uniform Random-4-SAT is the union of these distributions over all n and k.

Firstly generate your formula for N = 4 and k = 5. Please write your clauses in the text file and each clause should be written in a different line of the text file. Then input the formula to three algorithms.



Implement:

- 1. **Variable neighborhood descent :** Modify Hill-Climbing Search to switch to a denser neighborhood function when stuck at a local optimum.
- 2. **Beam Search:** Code for different beam lengths
- 3. **Tabu Search**: Implement tabu search and find an optimum tabu tenure value for the domain.

Evaluation Criteria: (Total: 50 Points)

Correctness: 15

Report: 10

Code Quality: 5

NOTE:

- 1. Due date for Assignment is 11:59 PM 11 Jan 2022.
- 2. Submit the following files named with your group number.
 - a. Code: <group_number>.py
 - b. Input file if there (input.txt)
 - c. Report: <group_number>.pdf
 - d. **Readme.txt** (How to execute your program)
- 3. Mode of submission is moodle.
- 4. We will run a plagiarism check for all the submissions, If found copied, 0% score will be awarded.
- 5. Penalty of 10% will be issued per day if the deadline is not met.

Report Format:

- 1. Brief description about the domain:
 - a. State space
 - b. Start node and goal node
 - c. MOVEGEN and GOALTEST algorithm
- 2. Heuristic functions considered
- 3. Beam search analysis for different beam lengths
- 4. Tabu search for different values of tabu tenure
- 5. Comparison of Variable neighborhood descent, Beam Search, Tabu Search: Nodes explored by each.