

The Role Of Classical Mechanics In ***Mangalyaan*** Mars Orbital Mission (MOM)

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1.) Basic Mars Orbital Mission Information

->is a space probe orbiting Mars.

->It was launched on 5 November 2013, at Satish Dhawan Space Centre (Sriharikota), using a Polar Satellite Launch Vehicle (PSLV) rocket C25 by the Indian Space Research Organization (ISRO, the fourth space agency to reach Mars).

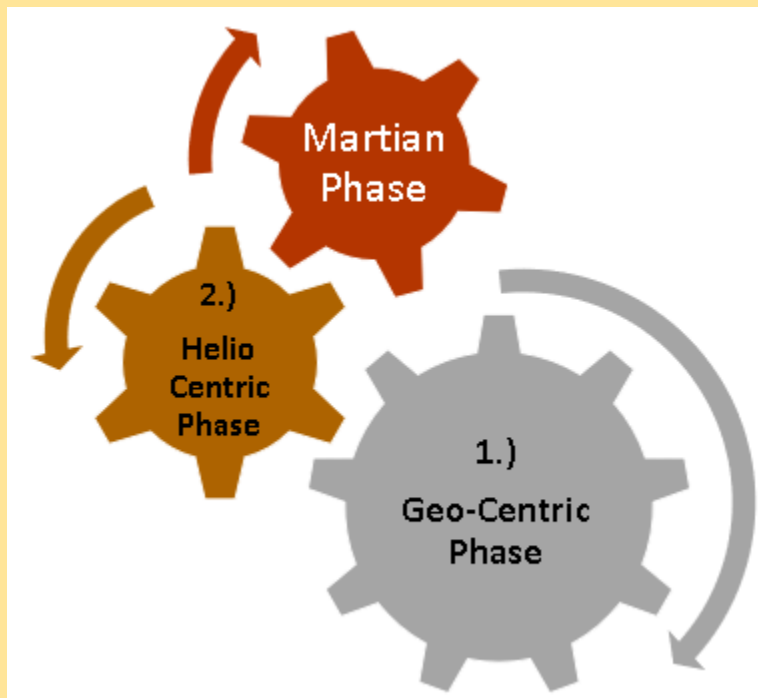
->India's first interplanetary mission

->Made India the first Asian nation to reach Martian orbit and the first nation in the world to do so on its maiden attempt

2.) Flow of the Mission



3.) Mission Profile



1.>Geo Centric Phase

A geocentric orbit or Earth orbit involves any object *orbiting the Earth*, such as the Moon or artificial satellites.

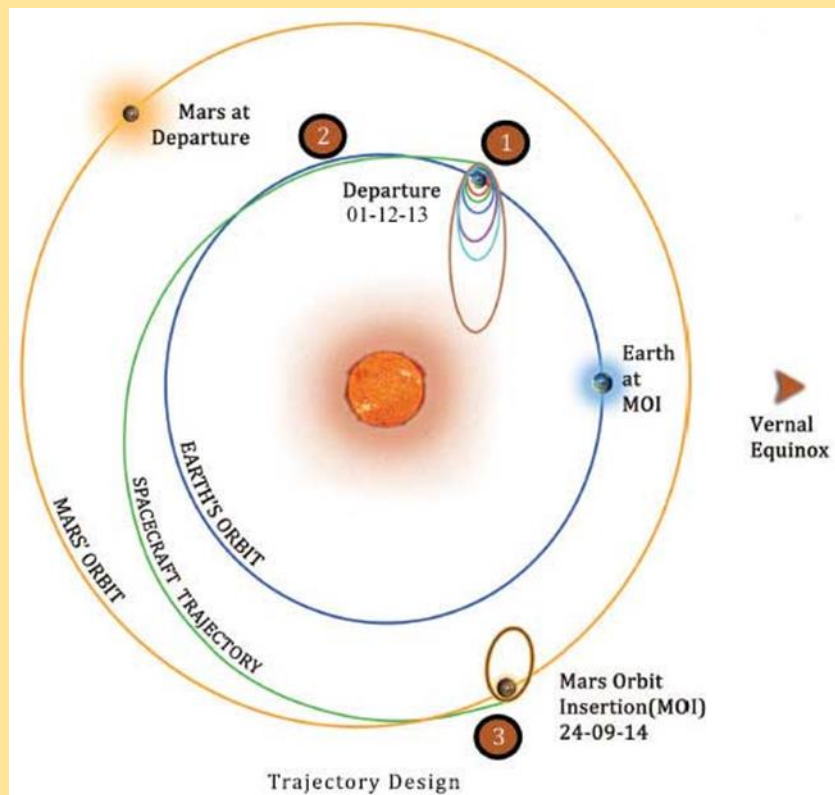
The spacecraft is injected into an *Elliptic Parking Orbit* by the launcher. With six main engine burns, the spacecraft is gradually maneuvered into a departure hyperbolic trajectory with which it escapes from the **Earth's Sphere of Influence (SOI)** with Earth's orbital velocity + V boost.

The SOI of earth ends at 918347 km from the surface of the earth beyond which the perturbing force on the orbiter is mainly due to *the Sun*.

One primary concern is how to get the spacecraft to Mars, on the *least amount of fuel*. ISRO uses a method of travel called a **Hohmann Transfer Orbit** – or a Minimum Energy Transfer Orbit – to send a spacecraft from Earth to Mars with the least amount of fuel possible.

A spacecraft enters orbit when its centripetal acceleration due to gravity is less than or equal to the centrifugal acceleration due to the horizontal component of its velocity.

The escape velocity required to pull free of Earth's gravitational field altogether and move into interplanetary space is about 11,200 m/s.



2. >Helio Centric Phase

Hohmann transfer orbit - An orbital maneuver that moves a spacecraft from one circular orbit to another using two engine impulses.

The spacecraft leaves Earth in a direction tangential to Earth's orbit and encounters Mars tangentially to its orbit. The flight path is roughly one half of an ellipse around sun.

Eventually it will intersect the orbit of Mars at *the exact moment* when Mars is there too. This trajectory becomes possible with certain allowances when the relative position of Earth, Mars and Sun form an angle of approximately 44°. Such an arrangement recurs periodically at intervals of **about 780 days**. Minimum energy opportunities for Earth-Mars occur in November 2013, January 2016, May 2018 etc.

Trans-Mars injection

A trans-Mars injection (TMI) is a heliocentric orbit in which a propulsive maneuver is used to set a spacecraft on a trajectory, also known as *Mars transfer orbit*, which will place it as far as Mars's orbit.

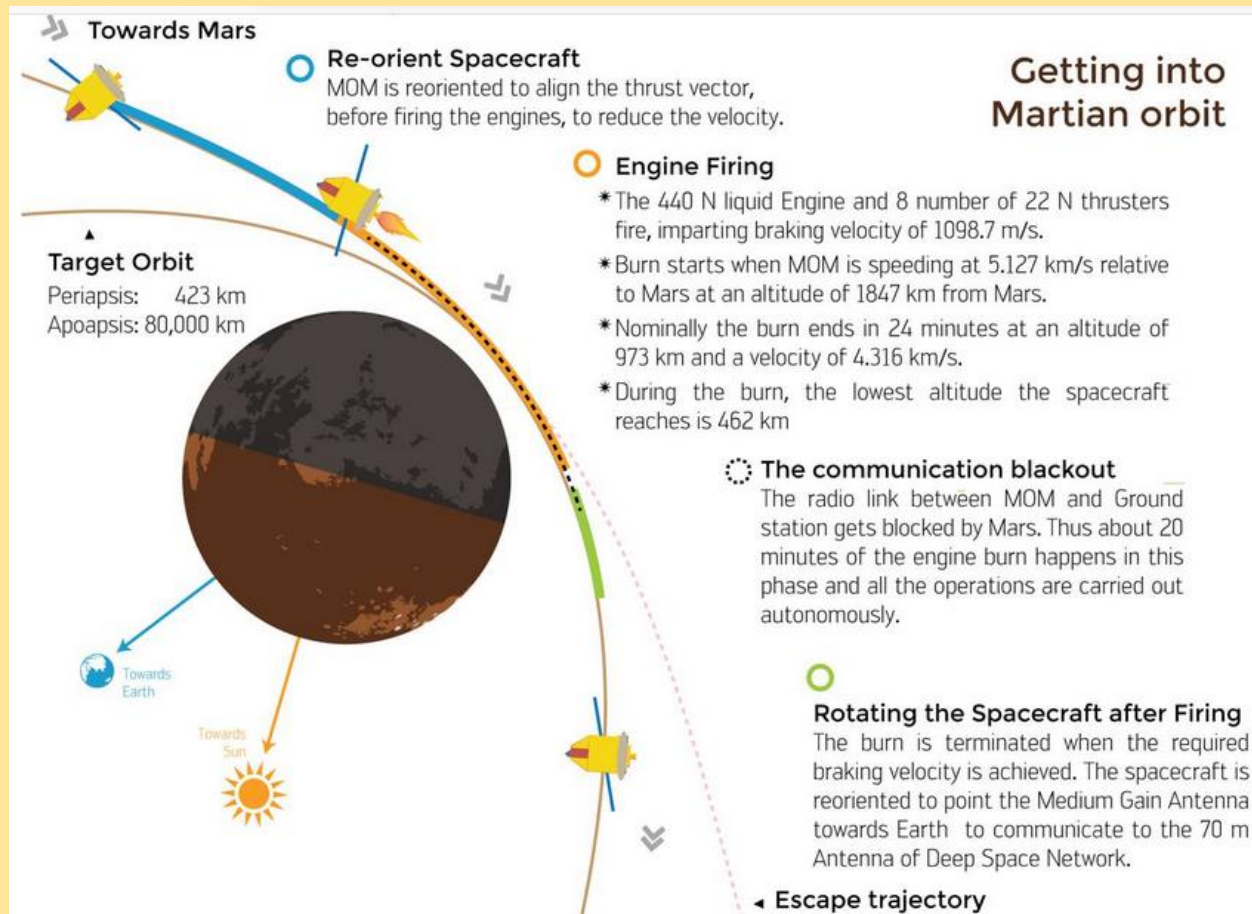
Every two years, low-energy transfer windows open up, which allow movement between planets with the lowest possible delta-v requirements.

Transfer injections can place spacecraft into either a Hohmann transfer orbit or bi-elliptic transfer orbit. Trans-Mars injections can be either a single maneuver burn, such as used by the ISRO Mars Orbiter Mission.

3.> Martian Phase

The spacecraft arrives at the ***Mars Sphere of Influence*** (around 573473 km from the surface of Mars) in a hyperbolic trajectory. At the time the spacecraft reaches the closest approach to Mars (Periapsis), it is captured into planned orbit around Mars by *imparting ΔV retro* which is called the ***Mars Orbit Insertion (MOI) manoeuvre***.

The Earth-Mars trajectory is shown in the above figure. ISRO plans to launch the Mars Orbiter Mission during the November 2013 window utilizing minimum energy transfer opportunity.



An Areocentric orbit is an orbit around the planet Mars.

Formula

Orbital speed (how fast a satellite is moving through space) is calculated by multiplying the angular speed of the satellite by the orbital radius:

$$R_{syn} = \sqrt[3]{\frac{G(m_2)T^2}{4\pi^2}} [2]$$

G = Gravitational constant

m_2 = Mass of the celestial body

T = rotational period of the body

By this formula one can find the geostationary-analogous orbit of an object in relation to a given body, in this case, Mars, Areostationary orbit can be defined as approximately 17,032 km above the surface of the Mars equator after substituting all values.

4.) Classical Mechanics Concept

When used to move a spacecraft from orbiting one planet to orbiting another, the situation becomes somewhat more complex, but much less delta-v is required, due to the ***Oberth effect***, than the sum of the delta-v required to escape the first planet plus the delta-v required for a Hohmann transfer to the second planet.

For example, consider a spacecraft travelling from the Earth to Mars. At the beginning of its journey, the spacecraft will already have a certain velocity and kinetic energy associated with its orbit around Earth. During the burn the rocket engine applies its delta-v, but the kinetic energy increases as a square law (Concept of Classical Mechanics), until it is sufficient to escape the planet's gravitational potential, and then burns more so as to gain enough energy to get into the *Hohmann transfer orbit* (around the Sun). Because the rocket engine is able to make use of the initial kinetic energy of the propellant, far less delta-v is required over and above that needed to reach escape velocity, and the optimum situation is when the transfer burn is made at minimum altitude (low periapsis) above the planet. The delta-v needed is only 3.6 km/s, only about 0.4 km/s more than needed to escape Earth, even though this results in the spacecraft going 2.9 km/s faster than the Earth as it heads off for Mars.

At the other end, the spacecraft will need a certain velocity to *orbit Mars*, which will actually be less than the velocity needed to continue orbiting the Sun in the transfer orbit, let alone attempting to orbit the Sun in a Mars-like orbit. Therefore, the spacecraft will have to **decelerate** in order for the *gravity of Mars to capture* it. This capture burn should optimally be done at low altitude to also make best use of ***Oberth effect***. Therefore, relatively small amounts of thrust at either end of the trip are needed to arrange the transfer compared to the free space situation.

However, with any Hohmann transfer, the alignment of the two planets in their orbits is crucial – the destination planet and the spacecraft must arrive at the same point in their respective orbits around the Sun at the same time. This requirement for alignment gives rise to the concept of launch windows.

angular alignment α (in radians) at the time of start between the source object and the target object shall be

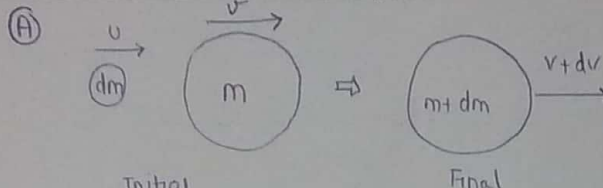
$$\alpha = \pi - \omega_2 t_H = \pi \left(1 - \frac{1}{2\sqrt{2}} \sqrt{\left(\frac{r_1}{r_2} + 1 \right)^3} \right).$$

Finding Out Its Suitable Orbit?? FUEL SAVED BY CLASSICAL MECH CONCEPT!!

Launch opportunities for a fuel-saving Hohmann transfer orbit (an elliptical orbit used to transfer between two circular orbits of different radii around the same body in the same plane) occur every 26 months. The Hohmann transfer orbit uses the lowest possible amount of energy in traveling between these orbits.

VARIABLE MASS SYSTEM

(A)



Initial Final

$$F_{ext} dt = (m+dm)(v+dv) - (dm)u - mv$$

$$= \cancel{mv} + m(dv) + (dm)v + \underbrace{(dm)(dv)}_{\text{neglect}} - (dm)u - \cancel{mv}$$

$$F_{ext} dt = m(dv) + v(dm) - u(dm)$$

$$F_{ext} dt + \underbrace{\left(\frac{dm}{dt}\right)(u-v)}_{\text{[mass flow rate]}} = \underbrace{\left(m \left(\frac{dv}{dt}\right)\right)}_{\text{Thrust force}}$$

$$F_{ext} + \left(\frac{dm}{dt}\right) V_{rel} = \underbrace{(ma)}_{\text{(Total Thrust)}} = (F_{Thrust})$$

(Variable mass concept)

(B) ROCKET PROPULSION

$$F_{ext} + V_{rel} \left(\frac{dm}{dt}\right) = ma_T$$

Instantaneous

$$(-mg) + (-V_r)(-\mu) = ma_T$$

$$\begin{matrix} \uparrow \\ -mg + V_r \mu \end{matrix} = F_T$$

(Instant mass) (net Thrust)

Aim: to calc. velocity after time 't'

$$\frac{-mg + V_r \mu}{m_{inst}} = (a_T) \Rightarrow \frac{dv}{dt}$$

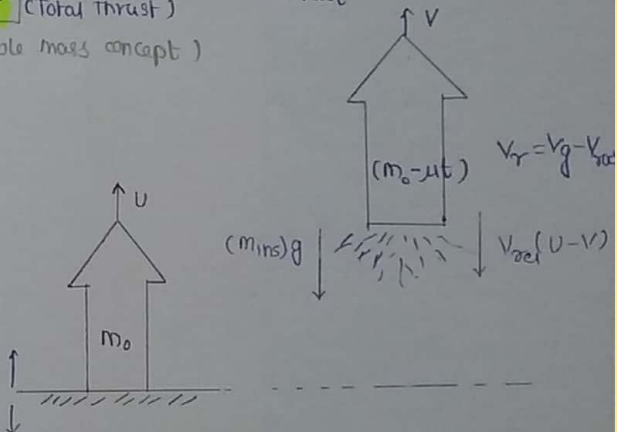
$$\int_0^t \left(-g + \frac{V_r \mu}{m_{inst}}\right) dt = \int_0^v dv$$

$$-gt + \int_0^t \frac{V_r \mu}{(m_0 - \mu t)} dt = (v - 0)$$

$$-gt + \frac{V_r \mu}{(-\mu)} \ln\left(\frac{m_0 - \mu t}{m_0 - \mu(0)}\right) = (v - 0)$$

$$-gt \mp \frac{V_r \mu}{\mu} \ln\left(\frac{m_0 - \mu t}{m_0}\right) = v - 0$$

$$\left[(v - gt) + V_r \ln\left(\frac{m_0}{m_0 - \mu t}\right) = v_{\text{rocket at any time}} \right]$$



CLASSICAL MECHANICS CONCEPTS

(A) Keplers Law of Planetary motion

Law of Elliptical orbit

(Every planet moves in an elliptical orbit around the sun, at one focus)

Law of Areas

(radius vector (sun to planet))

swepts out Equal area

in equal time. $\left(\frac{dA}{dt} = \frac{J}{2m} = \text{const}\right)$

Harmonic Law

$$\left(\text{period of revolution of planet}\right)^2 \propto \left(\text{semi-major axis}\right)^3$$

$$[T^2 \propto a^3]$$

(B) Satellite 'mom' is under influence of Gravitational Force which is an Inverse square Law force. Hence, we can deduce Kepler's Law around sun on basis of Inverse Square Law.

ORBIT Eqⁿ $\left[\frac{l}{r} = 1 + e \cos(\theta - \theta')\right] \quad \frac{J^2}{mK} = l \quad \frac{J^2 A}{mK} = e$

$$\left[e = \sqrt{1 + \frac{2EJ^2}{mK^2}}\right] \text{ con. Eqⁿ of conic with one focus at origin \& eccentricity 'e'}$$

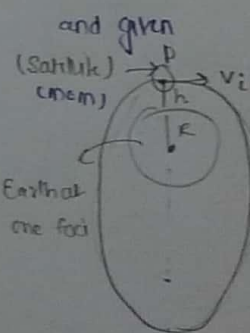
value of e decides orbit

$e > 1$	Hyperbola	$E > 0$
$e = 1$	Parabola	$E = 0$
$e < 1$	Ellipse	$E < 0$
$e = 0$	Circle	$E = -\frac{mk^2}{2J^2}$

(C) In order to launch satellite to stable orbit, it is taken to altitude h , necessary orbiting velocity = Insertion velocity (V_i)

$$E = \frac{1}{2} m (V_i)^2 + \left(-\frac{Gmm}{R+h}\right)$$

orbit will be based on Energy of Rocket 'mom'.



Total Energy determines the size of orbit.

However, Shape of eccentricity $\begin{cases} \text{Total Energy 'E'} \\ \text{determined by} \\ \text{Angular momentum 'J'} \end{cases}$

(D) Rocket has many stages after its launch in vertical direction (gradually get carried). As fuel of first, second and third stage is exhausted they are dropped and imparting satellite extra kinetic energy to revolve or leave the planet.

5.) Conclusion

Specifically, if u r asking about classical mechanics...then everything, every step, even starting from the word itself - "journey to the mars" classical mechanics starts its action.

As we all know Classical mechanics is the study of the motion of bodies, of which Circular motion by which a body executes a circular orbit about another fixed body, 2 body central force problem, the law of orbits, Kepler's Law Governing the Planetary Motion.

The orbital motion between sun and mars, along with the earth's motion is considered in such a way that our MOM should be injected to finally lock to orbit around mars. this type of opportunity we get roughly once in 2 years, also the journey from earth to mars would take around 300 days.

So, the Journey of Classical Mechanics Started from the Rocket: -

its build up, trajectory, motion, propelling system, finding out its suitable orbit, escape velocity everything has got to seek help of classical mechanics.

On the other hand, relation of mars, earth and suns motion, its location at certain time, its rotation, revolution, gravity which plays major role in fixing orbit for the ship, landing technique, descent speed, exhaust force too demand concepts of classical mechanics.

The Mars Mission has three Phases: -

→Geocentric phase ("Earth orbit" involves any object orbiting the Earth)

→Heliocentric phase ("circumsolar orbit" is an orbit around the barycenter of the Solar System, which is usually located within or very near the surface of the Sun.) [Trans-Mars injection]

→An Areocentric phase ("Mars Orbit" is an orbit around the planet Mars)

We also Discussed How the Exact Calculations were made to make the Best Possible Use of the Opportunities the were created by the Trajectories, so that M.O.M Probe can Reach Mars in Least Fuel.

This was the Whole Mission That Accelerated the Indian Space Program to Greater Heights.

