

LABORATORY JOURNAL

*Submitted in partial fulfillment of the requirement
For the Subject*

“DIGITAL COMMUNICATION” (EC 209)

: Prepared & Submitted By :

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(Admission No. U19CS012)**

**B. TECH. II (CSE) 3rd Semester
(Academic Year : 2020-21)
ONLINE MODE**

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(Aug to Dec - 2020)

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ELECTRONICS ENGINEERING DEPARTMENT
Academic Year : 2020-21



SUB : DIGITAL COMMUNICATION (EC209)

CERTIFICATE

This is to certify that the **Laboratory Journal** is prepared & submitted by
B. Tech. II (CSE-3rd Semester) student **Mr. BHAGYA VINOD RANA** bearing
Admission No.U19CS012 in the partial fulfillment of the requirement for the **Subject**
Digital Communication (EC209) through **ONLINE MODE**.

We, certify that the work is comprehensive, complete and fit for evaluation.

Laboratory Teachers :

Name	Signature with date
------	---------------------

1. Prof. N. B. Kanirkar
2. Prof. M. C. Patel
3. Mr. Abhishek Tripathi

Aug-Dec. 2020.

DIGITAL COMMUNICATION (EC209)
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LIST OF EXPERIMENTS
ONLINE MODE

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- Submitted By

Admission Number : U19CS012
B.Tech. II (CSE) 3rd Semester

EXPERIMENT No: 01

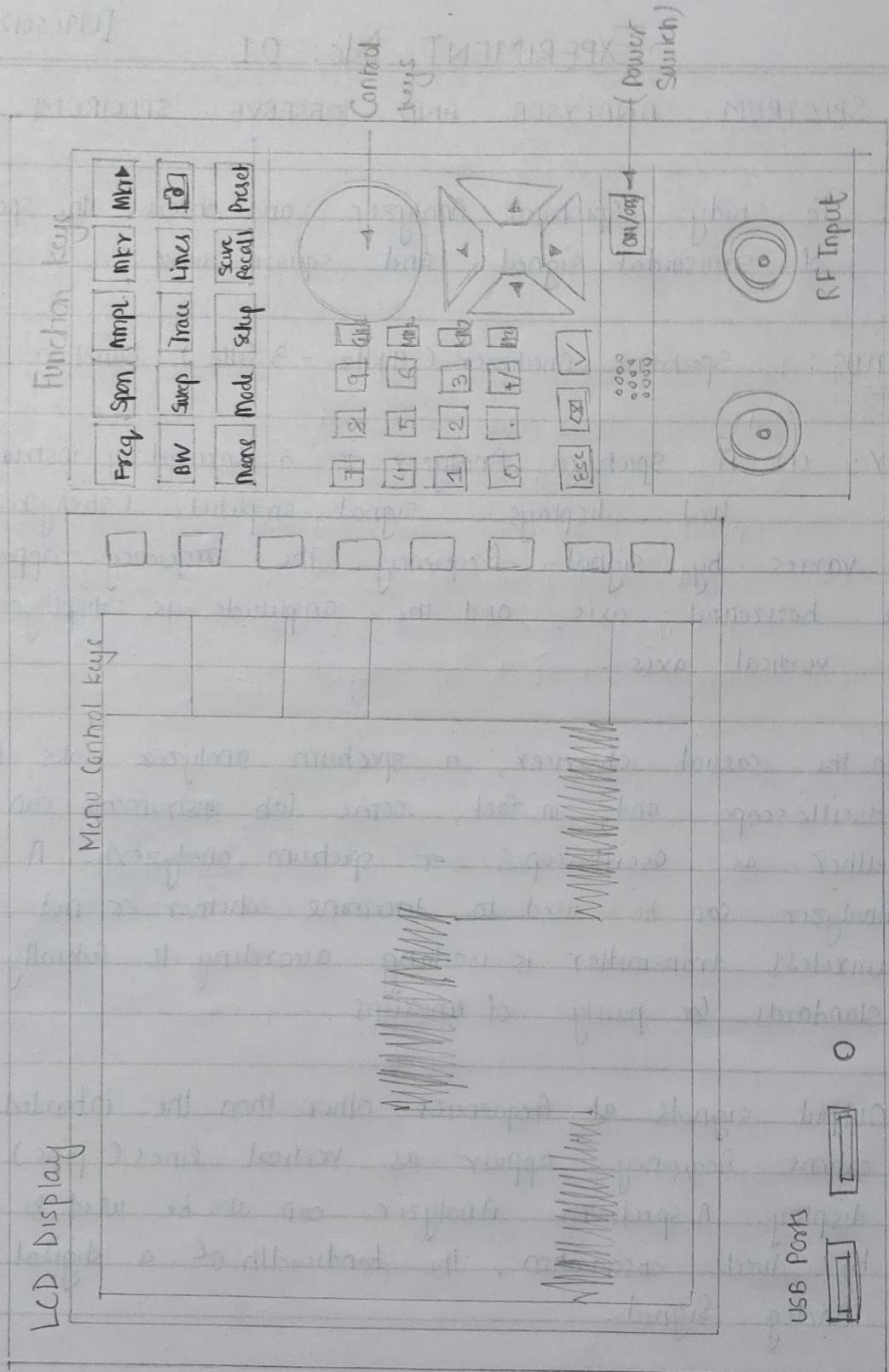
SPECTRUM ANALYSER AND OBSERVE SPECTRUM

- (*) **AIM:** To study Spectrum Analyzer and observe the spectrum of sinusoidal signal and square wave.
- (*) **APPARATUS:** Spectrum Analyzer (9 kHz - 3 GHz) Function Generator
- (*) **THEORY:** (1) A spectrum Analyzer is a laboratory instrument that displays signal amplitude (strength) as it varies by signal frequency. The frequency appears on the horizontal axis, and the amplitude is displayed on the vertical axis.
- (2) To the casual observer, a spectrum analyzer looks like an oscilloscope and, in fact, some lab instruments can function either as oscilloscopes or spectrum analyzers. A spectrum Analyzer can be used to determine whether or not a wireless transmitter is working according to federally defined standards for purity of emissions.
- (3) Output signals at frequencies other than the intended communications frequency appear as vertical lines (pips) on the display. A spectrum Analyzer can also be used to determine, by direct observation, the bandwidth of a digital or Analog Signal.
- (4) A spectrum Analyzer interface is a device that can be connected to a wireless receiver or a personal computer to allow visual detection and analysis of electromagnetic signals over a defined band of frequencies.

MIA

THOL

Spectrum Analyzer



FEATURES OF LAB INSTRUMENT GSP-830 (GWINSTEK):

- ✓ 5 markers with delta marker & peak functions
- ✓ 3 trace
- ✓ split windows with separate settings
- ✓ 6.4" TFT color LCD, 640 x 480 resolution
- ✓ AC/DC/ battery - multi-mode power operator
- ✓ AutoSet
- ✓ 9 kHz - 3 GHz frequency range

FREQUENCY SELECTION AND THEIR SELECTION METHODS

(1) FREQUENCY :

Frequency / Span : The frequency key, together with span key sets the frequency scale.

View Signal (Center & Span) : Center and span method defines the center frequency & the left/right bandwidth ('span') to locate the signal.

Setting Frequency adjustment Step : Frequency adjustment step defines the arrow keys resolution for center, start and stop frequency

Panel Operation:

- ✓ Press frequency key
- ✓ press F4 (step) scroll nabe.
- ✓ Enter the value using numerical and unit keys, arrow keys &

(2) RANGE : 9 KHz to 3 GHz

(3) Set Center Frequency :

Panel Operation:

- ✓ Press frequency key
- ✓ press F1 (center)
- ✓ Enter the value using numerical and unit keys, arrow keys and scroll nabe.

(4) Set Frequency Span :

Panel operation:

- ✓ Press span key
- ✓ press F1 (span)
- ✓ Enter the value using numerical and unit keys, arrow keys and scroll nabe.

(5) View Signal (Start & Stop)

✓ Start and stop method defines the beginning and end of the frequency range.

✓ Arrow keys and scroll nabe resolution: 1/10 of span.

(6) Set start frequency

Panel Operation:

- ✓ Press frequency key
- ✓ Press F2 (start)
- ✓ Enter the value using numerical and unit keys, arrow keys and scroll nabe.

(7) Set Stop Frequency:

Panel operation:

- ✓ Press Frequency key
- ✓ press F3 (stop)
- ✓ Enter the value using numerical and unit keys, arrow keys and scroll wheel.

(8) Full or zero span:

Full or zero span setting set the span to extreme values : 3 GHz (full) or 0 kHz (zero) They provide faster ways to view signals in certain signals such as in time domains (0 span) for viewing modulation or in full span for viewing signals with unknown frequencies.

(9) Display full frequency span

Panel operation

- ✓ Press the span key
- ✓ Press F2 (full span)
- ✓ Range : 3 GHz (fixed)
- ✓ Full span also sets these parameters to fixed values
- ✓ Center frequency : 1.5 GHz
- ✓ Start frequency : 0 kHz
- ✓ Stop frequency : 3 GHz

(10) zero Span Display Panel operations

- ✓ Zero span display can be obtained by pressing F3 Key
- ✓ Start frequency & Stop frequency remains same as center freqency
- ✓ Note: Last span setting can be recalled by F4 key

AMPLITUDE SELECTION AND SETTING Methods

(1) AMPLITUDE

Amplitude key sets vertical attribute of the display, including the upper limit (reference level), vertical range (amplitude scale), vertical unit and compensation for external gain or loss (extermal offset).

(2) Set Vertical Scale

Vertical display scale is defined by reference amplitude, amplitude range, measurement unit and external gain/loss.

(3) Set Reference amplitude

- ✓ The reference level defines the amplitude at the top of the displayed range.

Panel operations:

- ✓ Press amplitude key
- ✓ Press F1 (reference level)
- ✓ Enter the value using numerical and unit keys, arrow keys and scroll knob.

Arrow keys, and scroll knob, scroll knob resolution: vertical scale.

Range:

dBm : -110 to +20 dBm, 0.1 dBm resolution

dBmV : -63.1 to 66.99 dBmV, 0.01 dB resolution

dBμV : -3.01 to 126.99 dBμV, 0.01 dB resolution.

(4) Select amplitude scale

> Panel operation:

Press Amplitude key

Press F2 (Scale dB/div)

Repeatedly to select the scale

> Range: 10, 5, 2, 1 dB/div

> Panel operation:

Press Amplitude key

Press F3 (Units)

Select and press the unit from F1 (dBm), F2 (dBm)
and F3 (dB μ V)

Press F6 (return) to go back to previous menu.

dBm = -110 to +20 dBm, 0.1 dBm resolution

dBmV = -63.1 to 66.99 dBmV, 0.01 dB resolution

dB μ V = -3.01 to 126.99 dB μ V, 0.01 dB resolution

Set external offset level

(5) Background

External offset compensates the amplitude gain or loss caused by an external network or devices.

Panel operations:

1. Press Amplitude key

2. Press F4 (external gain)

3. Enter the value using numerical and unit keys,
arrow keys and scroll knob

> Range :

-20 dB to +20 dB, 0.1 dB resolution

> TCON :

- The amplitude icon appears at the bottom of IN display when the external offset changes.
- To check whether Spectrum analyzer working properly
- Generate Auxiliary Signal : Press system key, press auxiliary signal, select an option from side given menu, following signal will generate. It generate 10 MHz signal with 10 dB amplitude.

Observation Table :

Next Pages →

Spectrum Diagrams (waveforms)

- (*) Conclusion : Hence, we have successfully verified and analysed the spectrum of sinusoidal signal and square wave for different frequency and amplitude.

Observation Table

Waveform : SINE

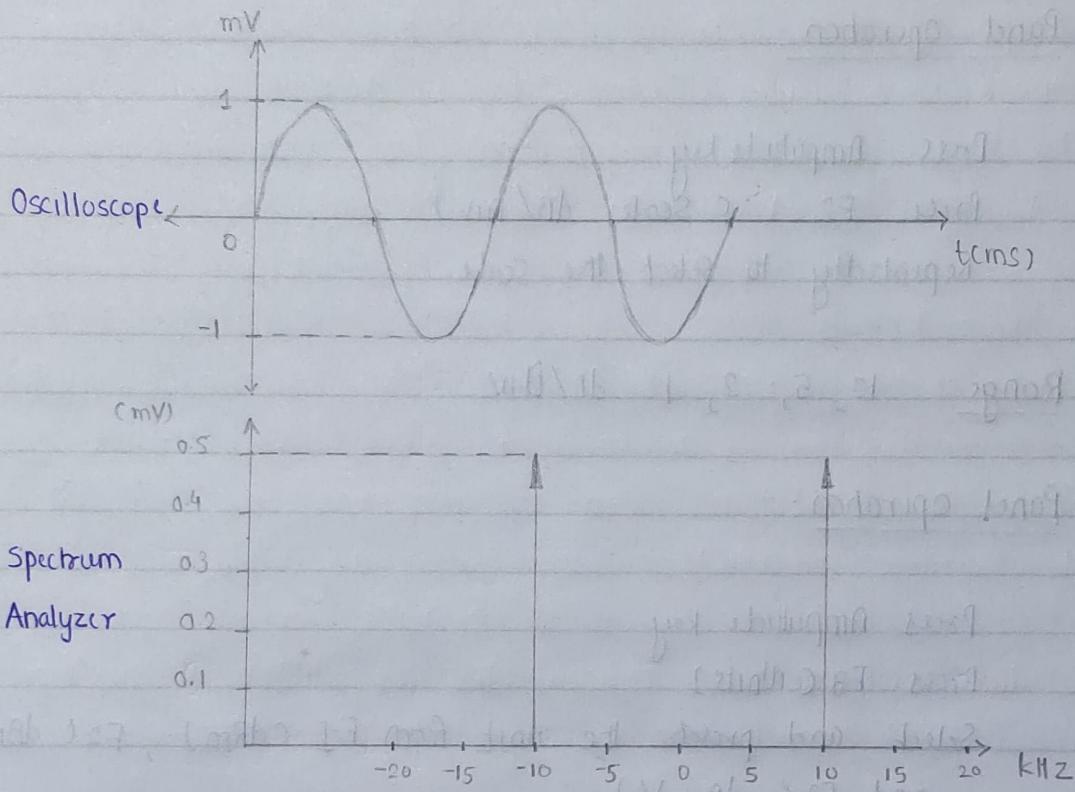
Sr. No.	Frequency (KHz)	Amplitude (mV)
1	10	1
2	15	1.12
3	15	2.10
4	12.5	2.10
5	12.5	0.5

Waveform: SQUARE

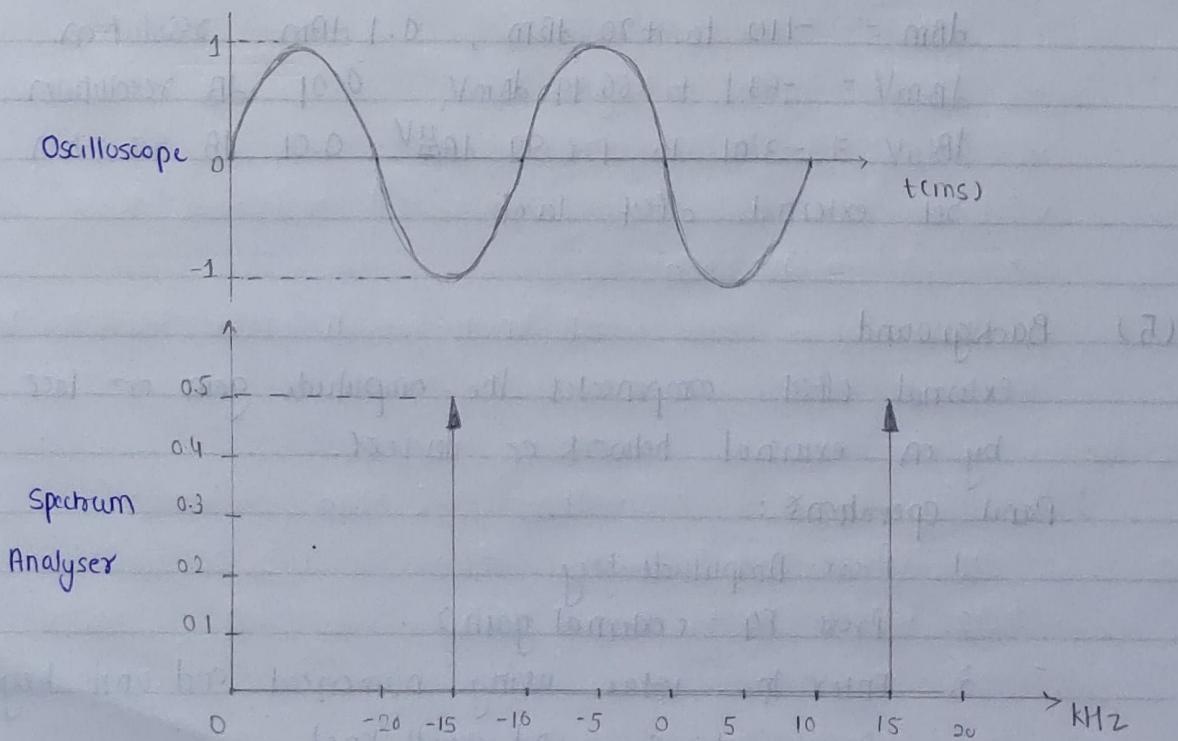
Sr. No.	Frequency (KHz)	Amplitude (mV)
1	10	1
2	5	1
3	10	2
4	12.5	1
5	12.5	2

SINE WAVE

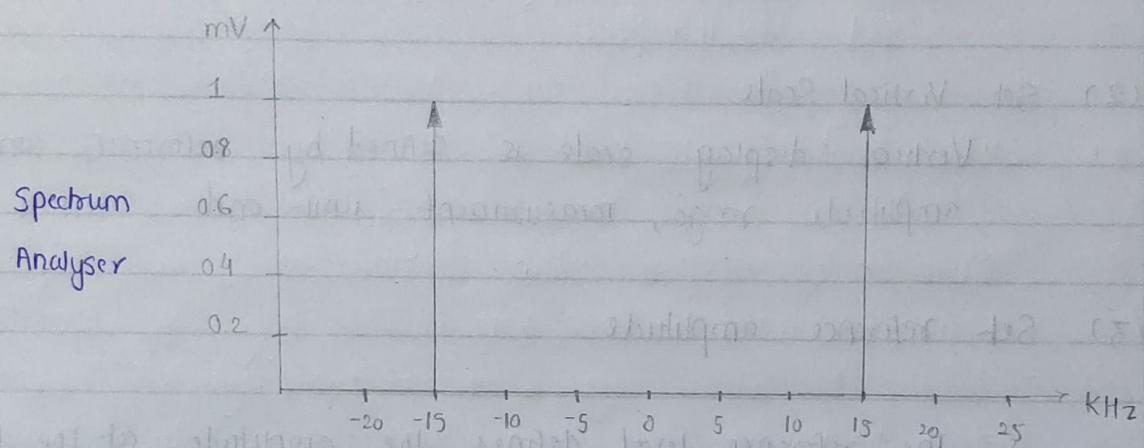
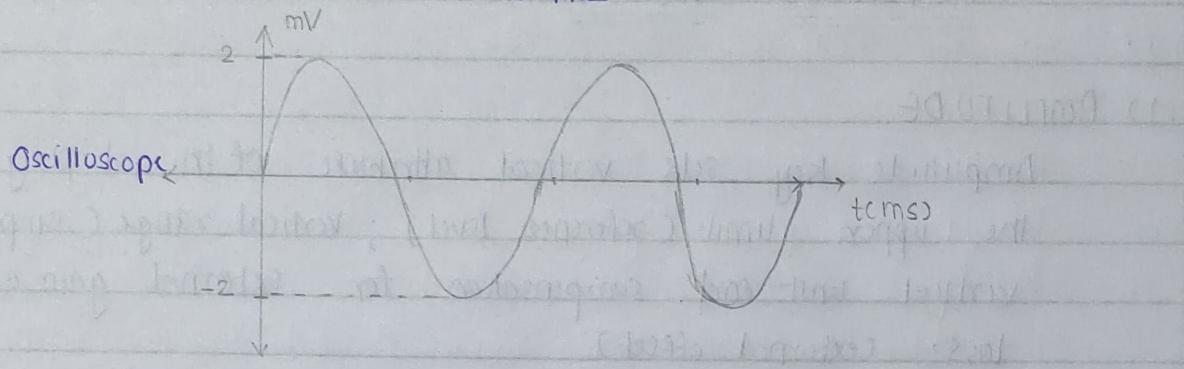
1. > $A = 1 \text{ mV}$ $f = 10 \text{ kHz}$



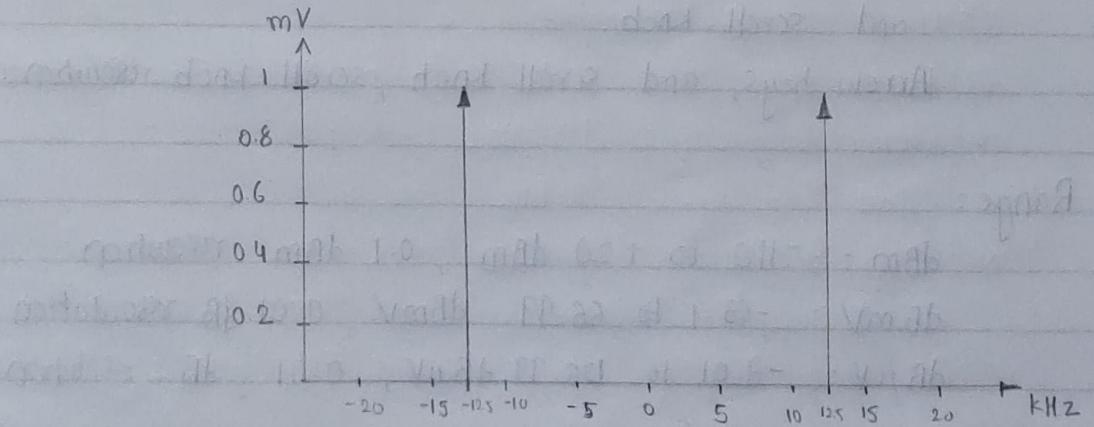
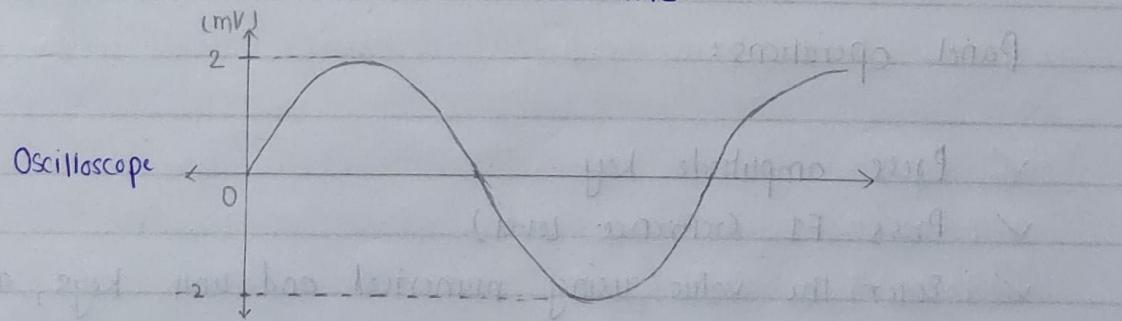
2. > $A = 1 \text{ mV}$ $f = 15 \text{ kHz}$



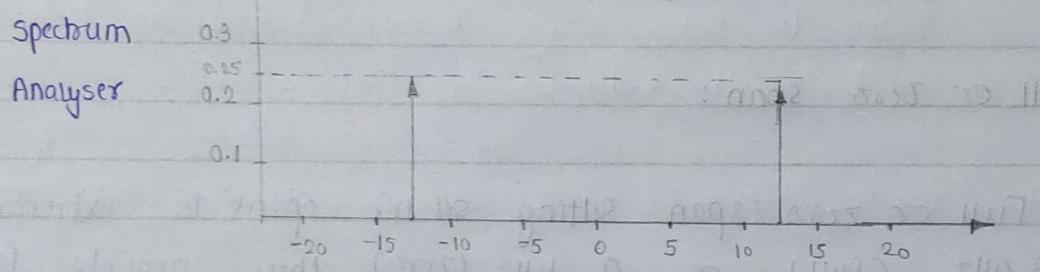
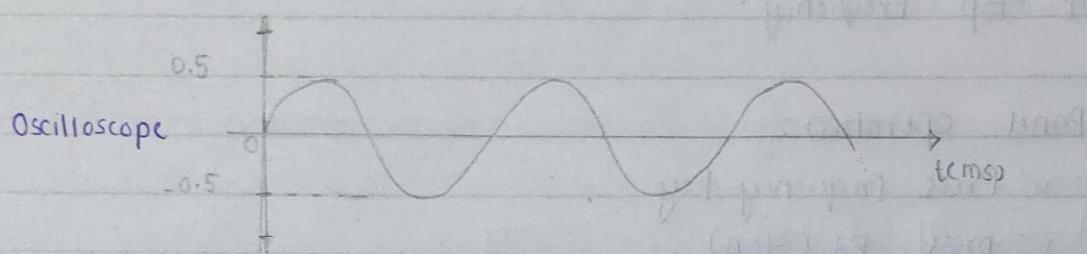
3.) $A = 2 \text{ mV}$ $f = 15 \text{ kHz}$



4.) $A = 2 \text{ mV}$ $f = 12.5 \text{ kHz}$

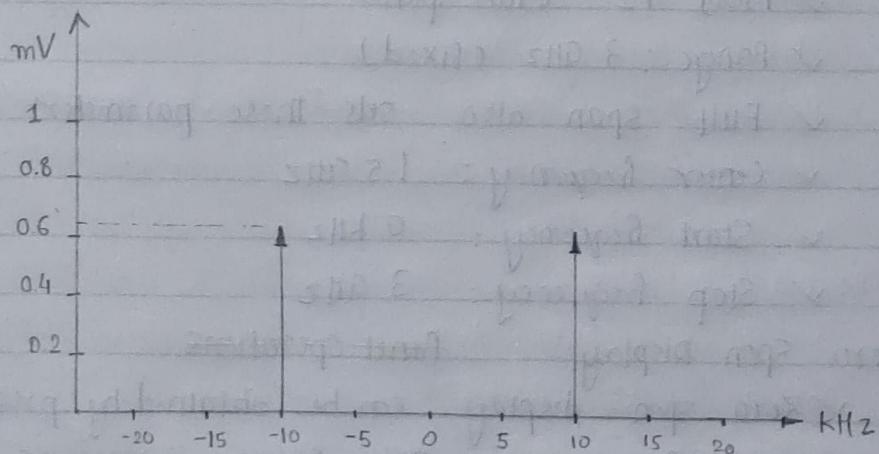
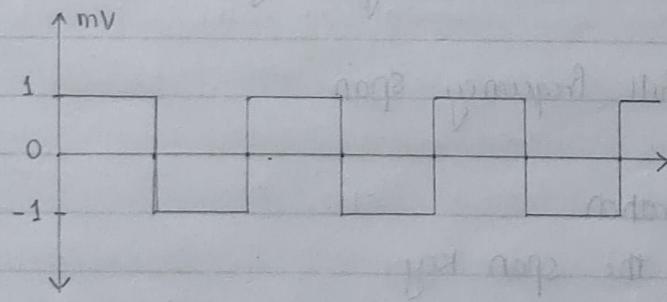


$$5. > A = 0.5 \text{ mV} \quad f = 12.5 \text{ kHz}$$

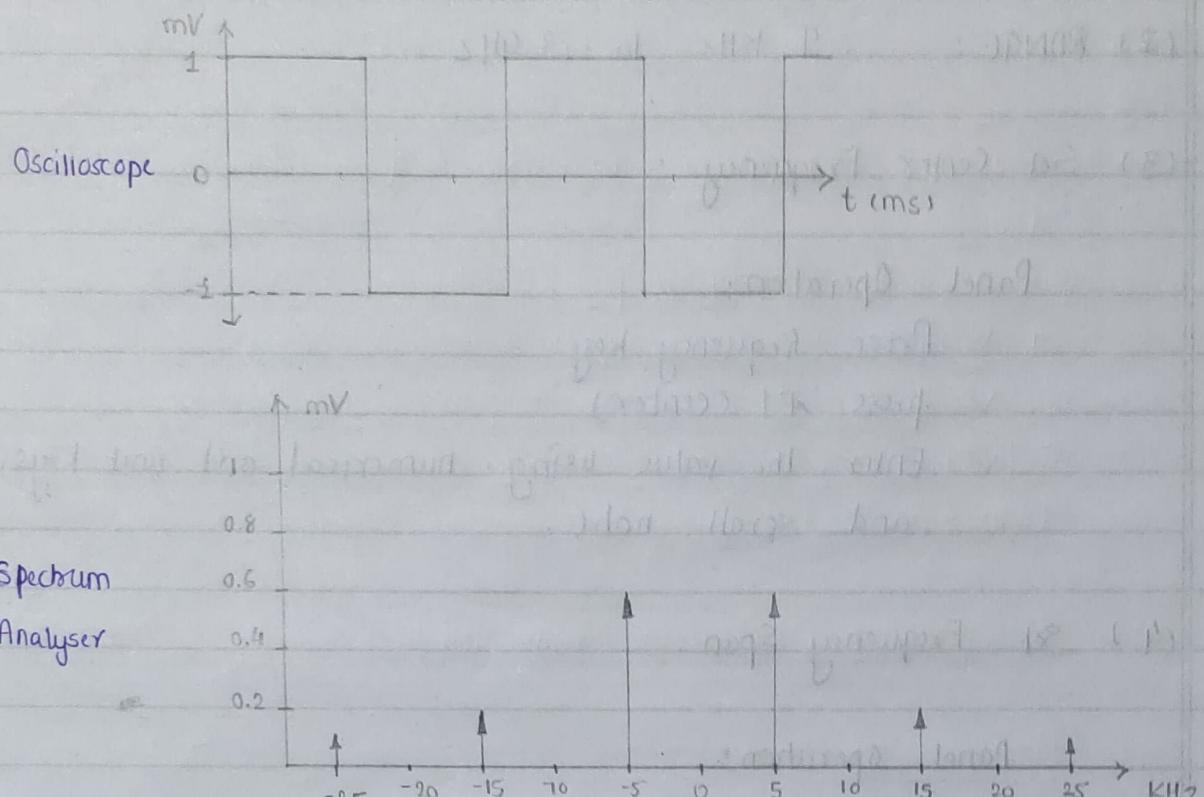


SQUARE WAVE

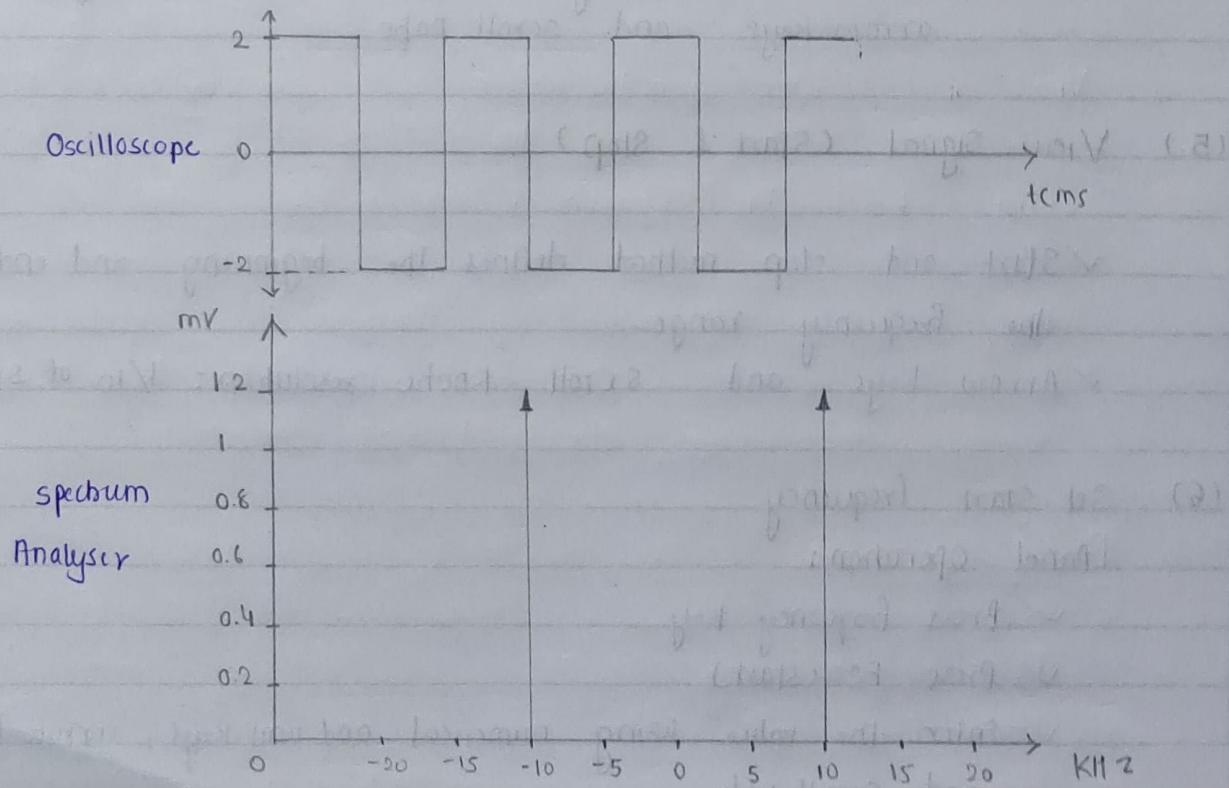
$$1. > A = 1 \text{ mV} \quad f = 10 \text{ kHz}$$



$$2.7 \quad A = 1 \text{ mV} \quad f = 5 \text{ kHz}$$



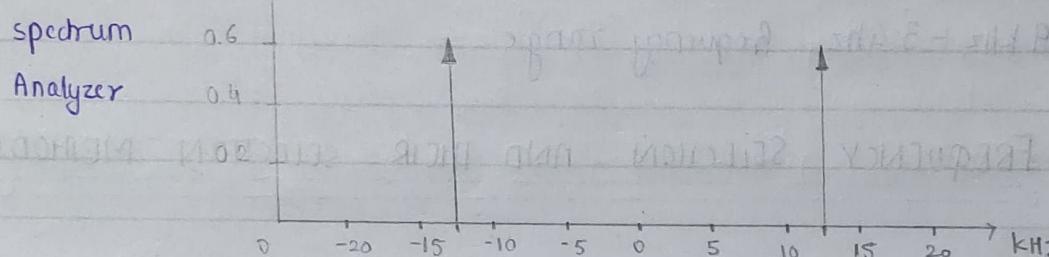
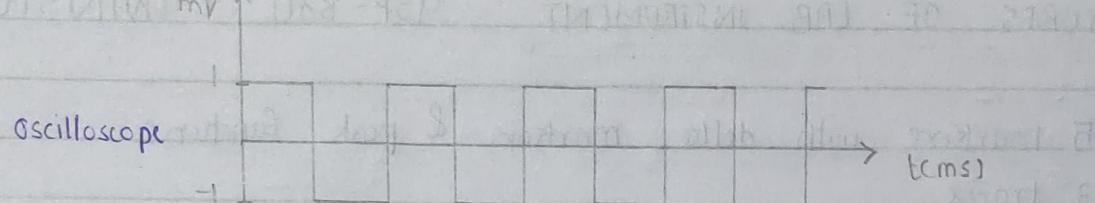
$$3.7 \quad A = 2 \text{ mV} \quad f = 10 \text{ kHz}$$



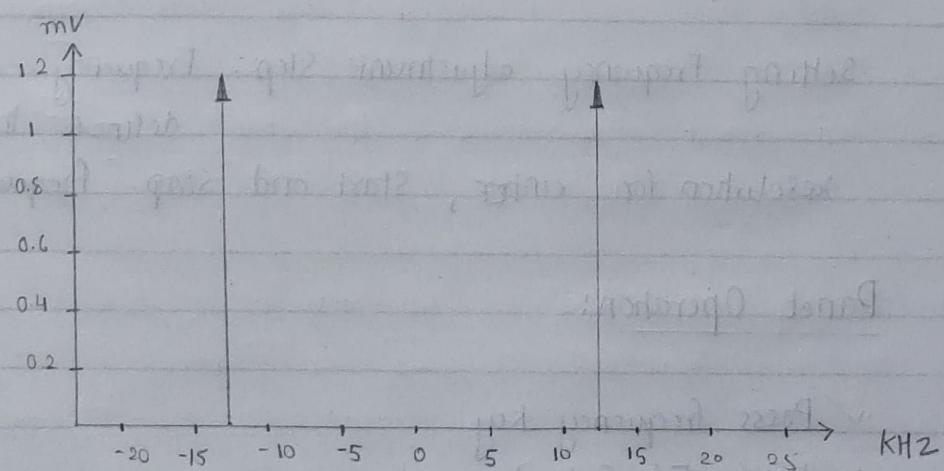
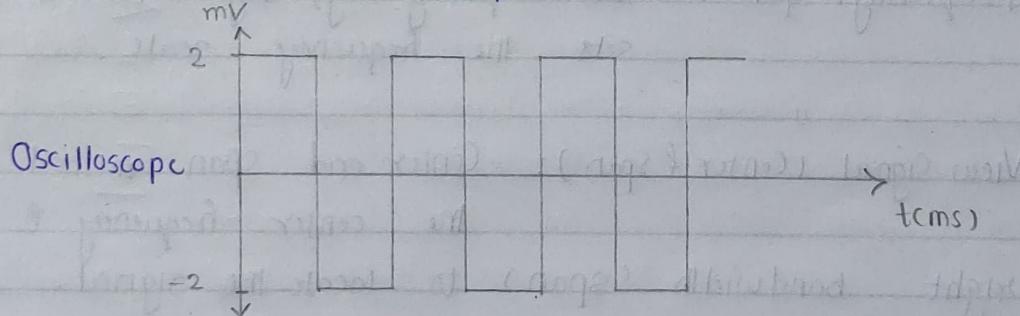
(B)

[U19CS012]

$$4> A = 1 \text{ mV} \quad f = 12.5 \text{ KHz}$$



$$5> A = 2 \text{ mV} \quad f = 12.5 \text{ KHz}$$



[U19CS012]

EXPERIMENT 2 :

SAMPLING AND RECONSTRUCTION OF SIGNAL
NYQUIST CRITERIA

> AIM: To perform sampling and reconstruction of signal and obtain its waveforms. Also verify the nyquist criteria.

> APPARATUS: Nyquist Applet (Software)

> THEORY:

(1) A continue-time signal can be stored in a digital computer, in the form of discrete (equidistant) points or samples.

The higher the sampling rate (or sampling frequency), the more accurate would be the stored information and the signal reconstruction from its samples.

However, high sampling rate produces a large volume of data to be stored and makes necessary the use of very fast analog to digital converter.

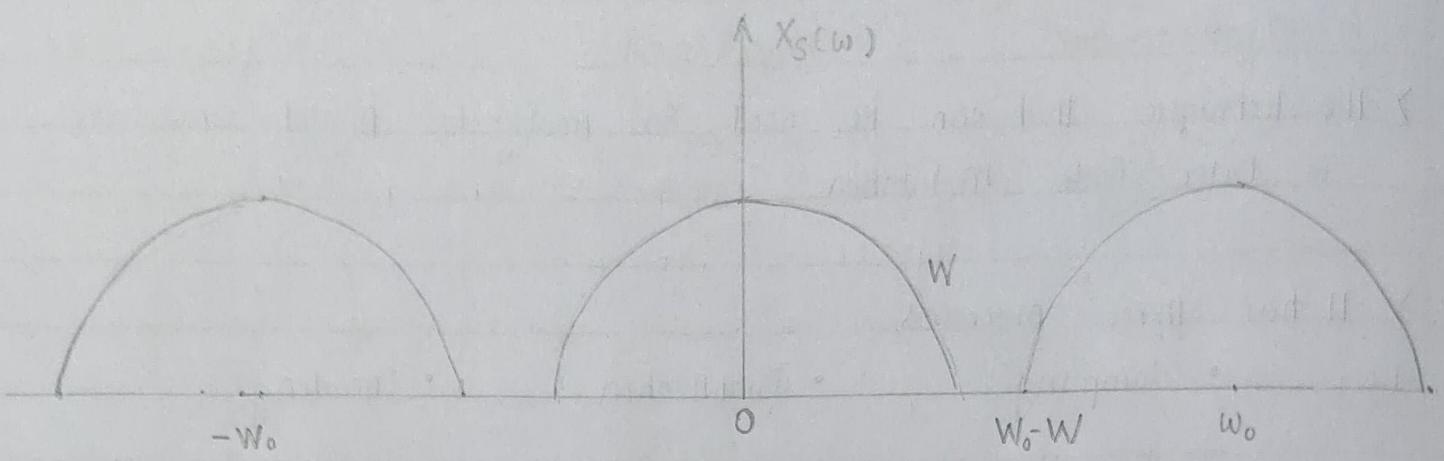
> Analog Signal: It is continuous time varying feature of the signal.

> Digital Signal: It represents data as sequence of discrete values at any given time, it can only take any one of the finite number of values.

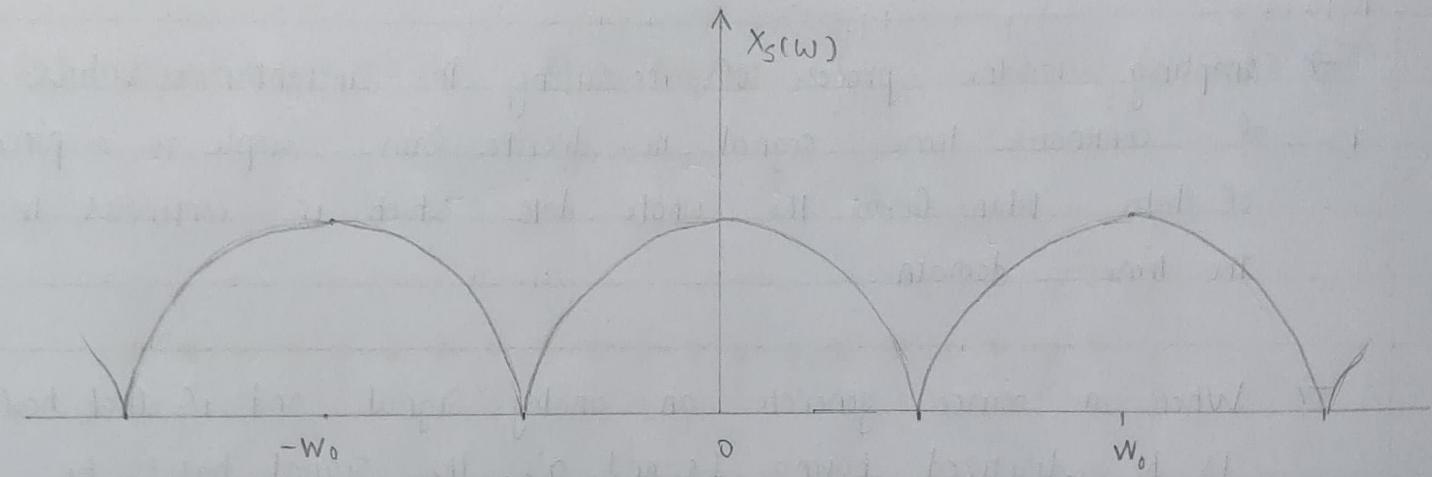
- > The technique that can be used for Analog to Digital conversion is Pulse Code Modulation
- > It has three processes
 - Sampling
 - Quantization
 - Encoding

(2) Sampling

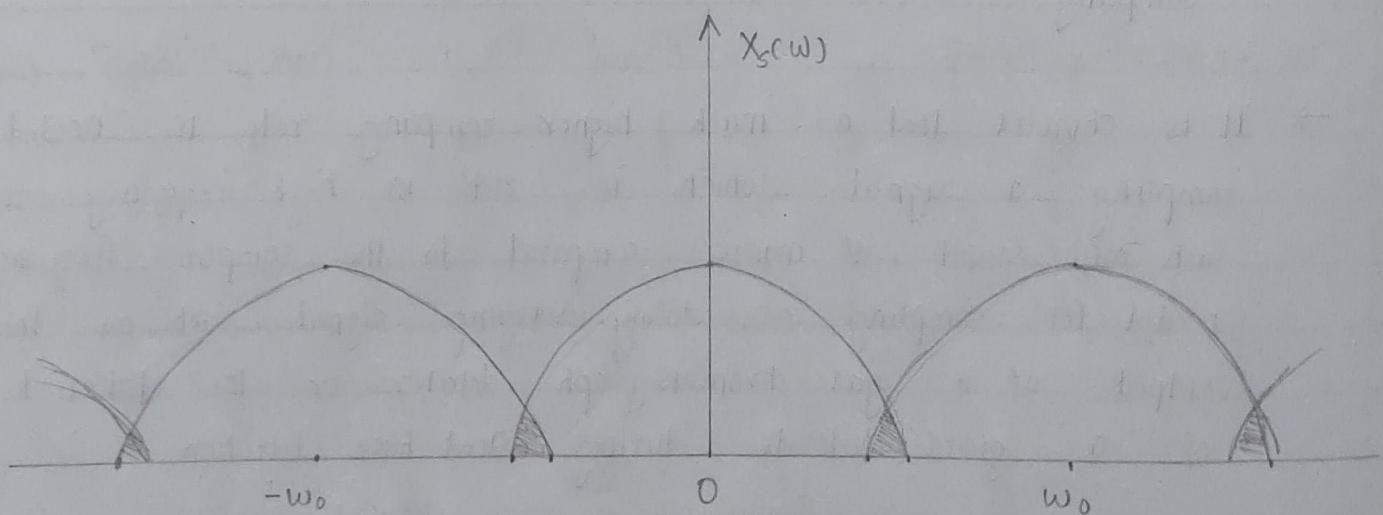
- Sampling is the process of measuring the instantaneous values of continuous-time signal in discrete form. Sample is a piece of data taken from the whole data which is continuous in the time domain.
- When a source generate an analog signal and if that has to be digitized, having 1's and 0's, the signal has to be discretized in time. This discretization of analog signal is called Sampling.
- It is obvious that a much higher sampling rate is needed for sampling a signal which is rich in high frequency components such as sound of music compared to the sampling frequency needed for sampling a slowly varying signal, such as the output of a gas-chromatograph detector or the potential of a glass-electrode during acid-base titration.



(a) Oversampling ($f_s > 2W$)



(b) Nyquist ($f_s = 2W$)



(c) Undersampling ($f_s < 2W$)

→ The minimum sampling frequency of a signal that it will not distort its underlying information should be double the frequency of its highest frequency component. This is the Nyquist Sampling Theorem.

(3) Nyquist Rate

→ suppose that a signal is band-limited and w is the highest frequency.

→ Therefore, for effective reproduction of the original signal the sampling rate should be twice the highest frequency

$$\therefore F_s = 2w$$

F_s : Sampling Rate

w : Highest frequency

This is Nyquist Rate and theorem is called Sampling theorem.

(A) condition 1: OVERSAMPLING ($F_s > 2w$)

If sampled at higher rate than $2w$ in the frequency domain

$$X_s(w) = \frac{1}{T_s} \sum_{n=-\infty}^{\infty} X(w - n\omega_0)$$

Here, the information is reproduced without any loss.
There is no mixing up hence recovery is possible.

(B) Condition 2 :

→ If the Sampling rate is equal to twice the frequency.

$$F_s = 2W$$

→ The information is retrieved without any loss. Hence, this is also a good sampling rate.

(C) Condition 3 : UNDERSAMPLING

$$F_s < 2W$$

→ The below pattern shows overlapping of information which leads to mixing up and loss of information. This unwanted phenomena of over-lapping is called Aliasing

(d) Aliasing : A high frequency component is taking on the identity of a low-frequency component in the spectrum of sampled version.

The effect of aliasing is reduced by :

- 1) The signal needs to be sampled at a rate slightly higher than the Nyquist rate.
- 2) In the Transmitter section of PCM, a low pass anti-Aliasing filter is employed to eliminate the unwanted high frequency components.

(4) Quantization : The method of sampling chooses few points on the analog signal and then these points are joined to round off the value of a near stabilized value is called quantization.

(5) Encoding :

- > The digitization of analog signal is done by encoder.
- > After each sample is quantized, the number of bits per sample is decided.
- > Each sample is changed to an n bit code.
- > Encoding is also used to minimize the bandwidth.

(6) Anti-Aliasing filter

- > Designing this filter is to determine the bandwidth required in the acquisition system. The maximum frequency of the input signal should be less than or equal to half of sampling rate.
- > This sets the cutoff frequency of the low-pass filter.
- > The order of a filter affects the steepness of the transition region roll-off and hence the width of the transition region.

A first order filter has a roll-off of 20 dB per decade, which means any signal having frequency above cut-off frequency will be attenuated at this rate.

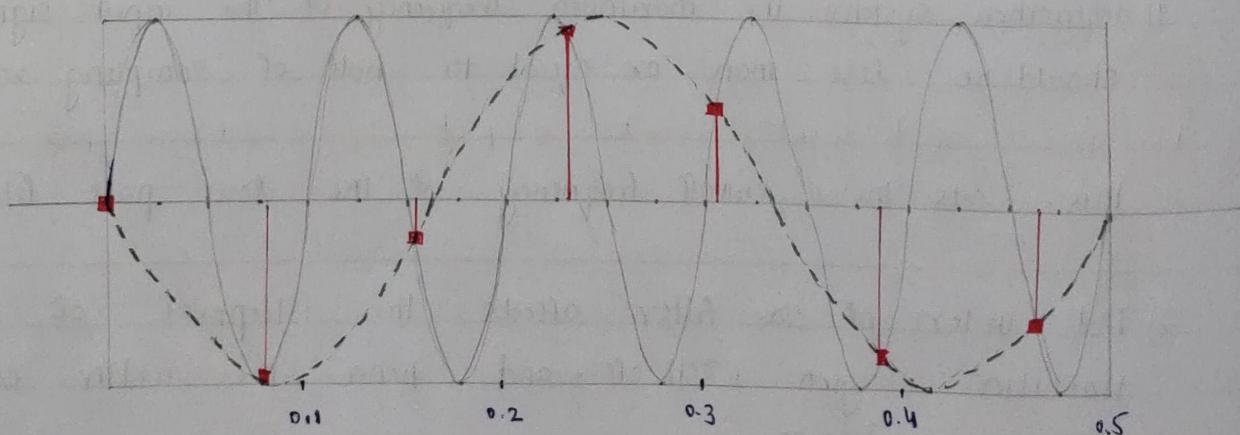
A filter of the n^{th} order will be have a roll-off rate of $n \times 20 \text{ dB/decade}$.

v Conclusion: Therefore, sampling and reconstruction of the signal has been performed successfully on Nyquist Applet (software) and Nyquist criteria has been verified.

Observation Table

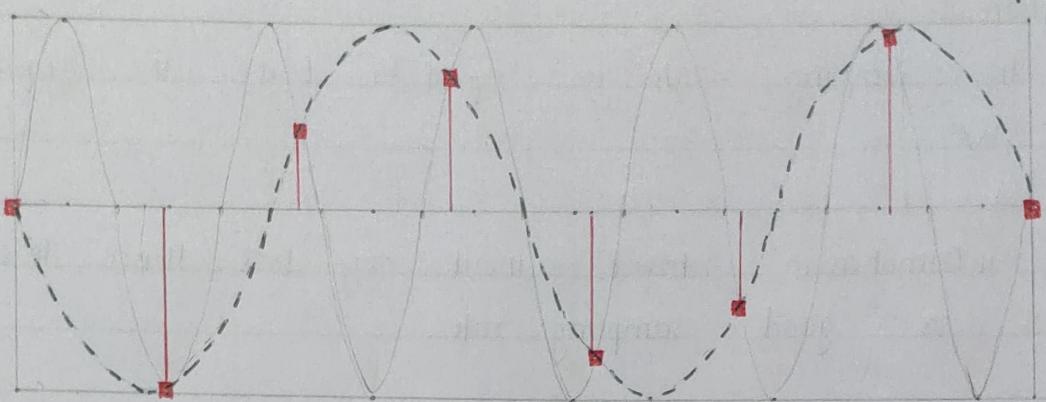
Signal Frequency (Hz)	Sampling Frequency (Hz)	Alias Frequency (Hz)
10	13	3
	14	4
	15	5
	20	-
	25	-
20	19	1
	22	2
	30	10
	40	-
	50	-

(1) Signal freq. (Hz) = 10.0 Alias freq. (Hz) 3.0 Sampling freq. (Hz) = 13.0

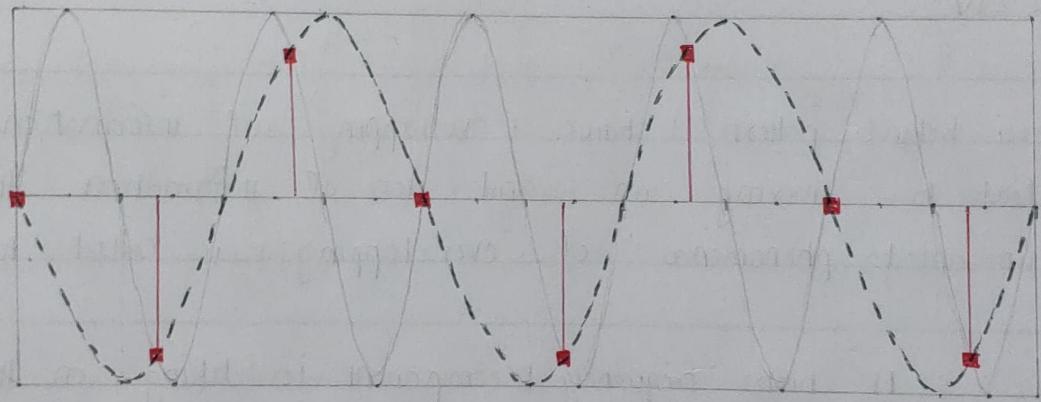


(1)

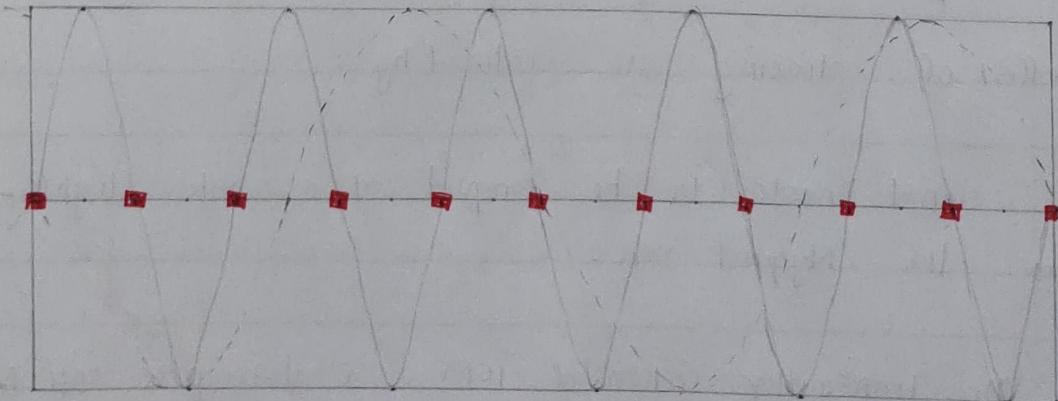
(2) Signal freq.(Hz) = 10.0 Alias freq.(Hz) = 4.0 Sampling freq.(Hz) = 14.0



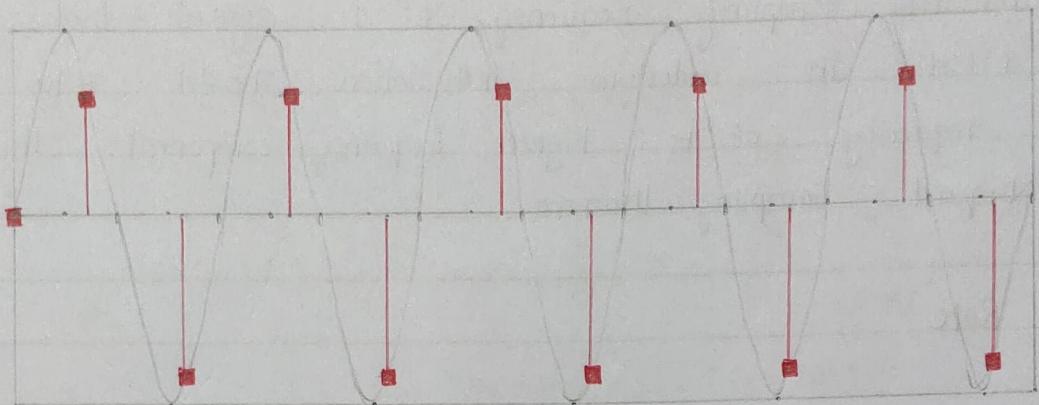
(3) Signal freq.(Hz) = 10.0 Alias freq.(Hz) = 5.0 Sampling freq.(Hz) = 15.0



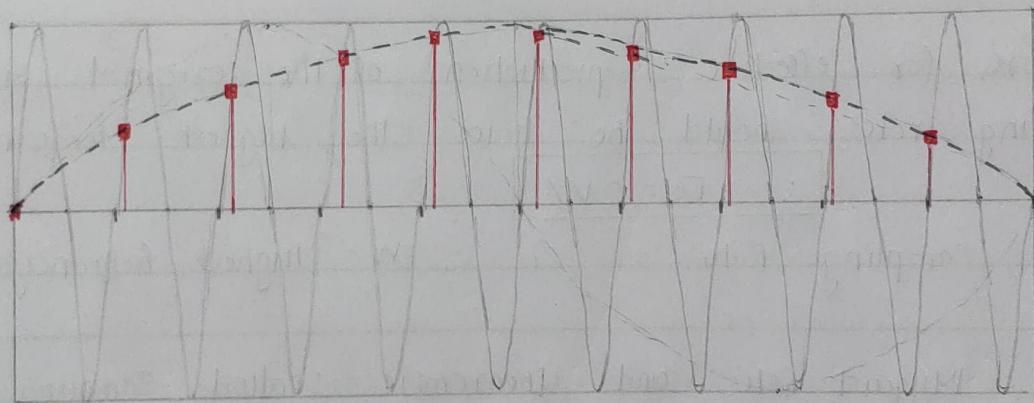
(4) Signal freq.(Hz) = 10.0 Alias freq.(Hz) = - Sampling freq.(Hz) = 20



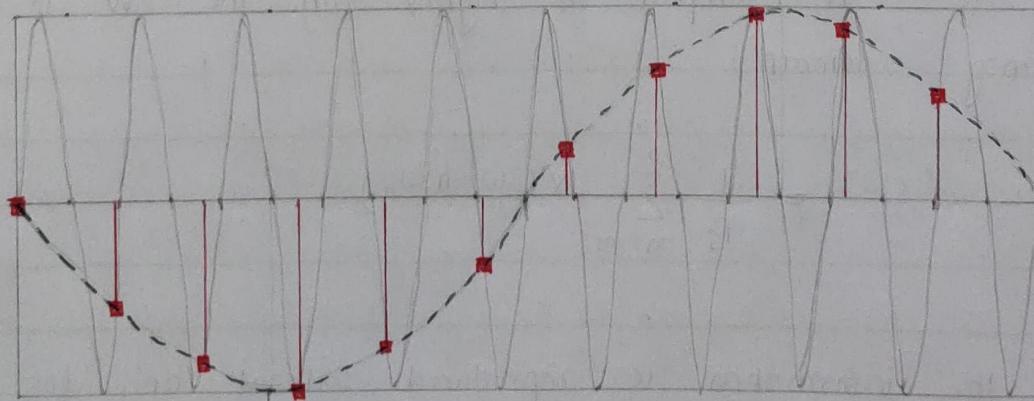
(5) Signal freq.(Hz) = 10.0 Alias freq.(Hz) = - Sampling freq.(Hz) = 25



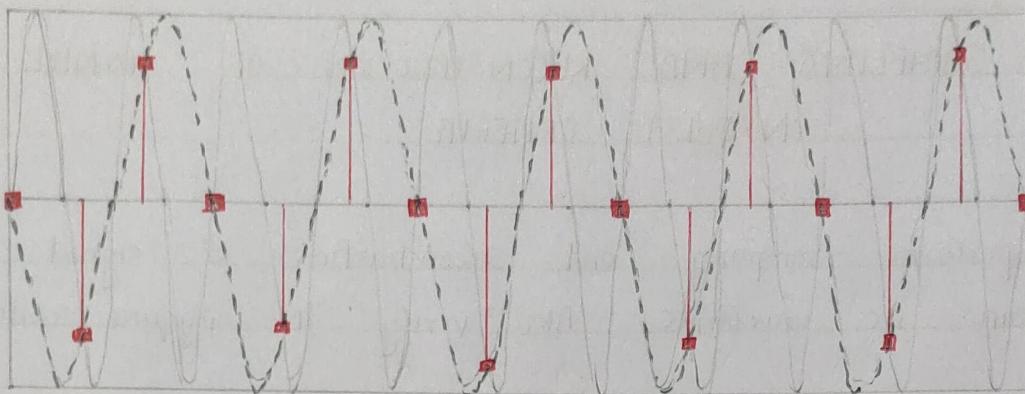
(6) Signal freq.(Hz) = 20.0 Alias freq.(Hz) = 1.0 Sampling freq.(Hz) = 19



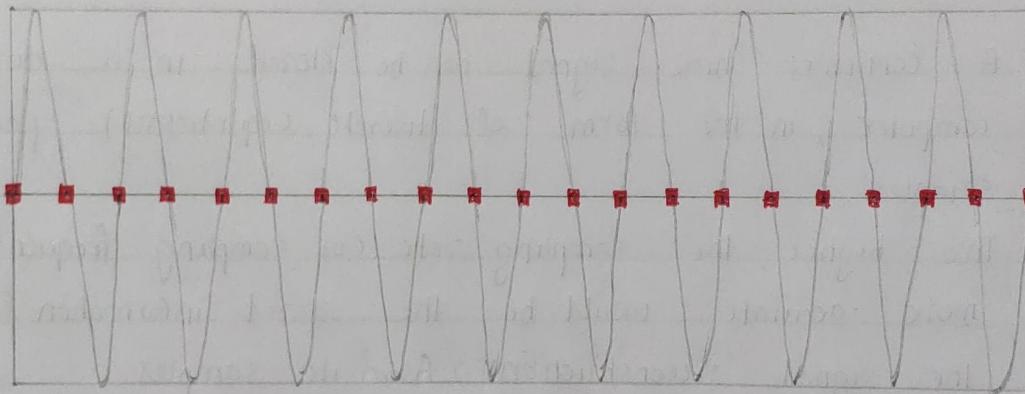
(7) Signal freq.(Hz) = 20.0 Alias freq.(Hz) = 2.0 Sampling freq.(Hz) = 22.0



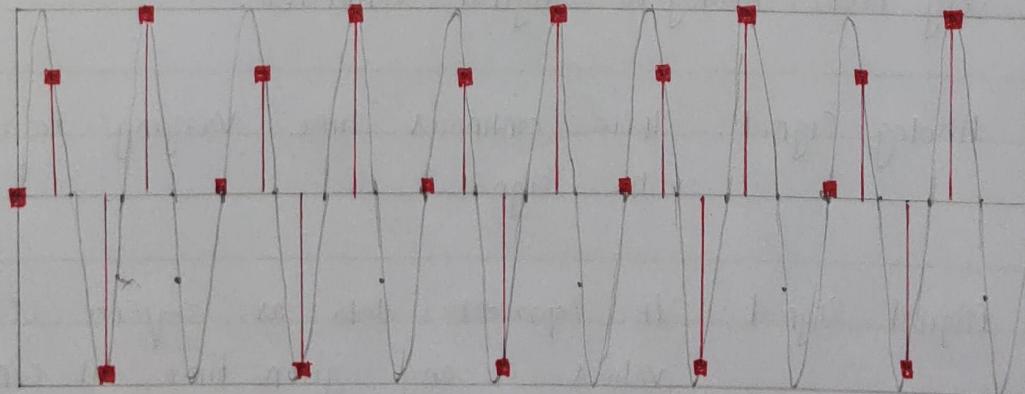
(8) Signal freq.(Hz) = 20.0 Alias freq.(Hz) = 10 Sampling freq.(Hz) = 30



(9) Signal freq.(Hz) = 20.0 Alias freq.(Hz) = - Sampling freq.(Hz) = 40



(10) Signal freq.(Hz) = 20.0 Alias freq.(Hz) = - Sampling freq.(Hz) = 50



EXPERIMENT 3 :

AMPLITUDE MODULATION

> AIM: Study of an Amplitude modulated (A.m.) scheme, depth of modulation, waveforms, spectra and trapezoidal display.

> APPARATUS: Lab Alive Software

> THEORY: 1. Classification of AM modulation

- Double side Band Suppressed carrier (DSB-SC)
- Double side Band with carrier (AM)
- Single side Band (SSB)
- Vestigial side Band (VSB)

2. AM

Let modulating signal be $m(t) = A_m \cos(2\pi f_m t)$, carrier ^{signal}
 $c(t) = A_c \cos(2\pi f_c t)$

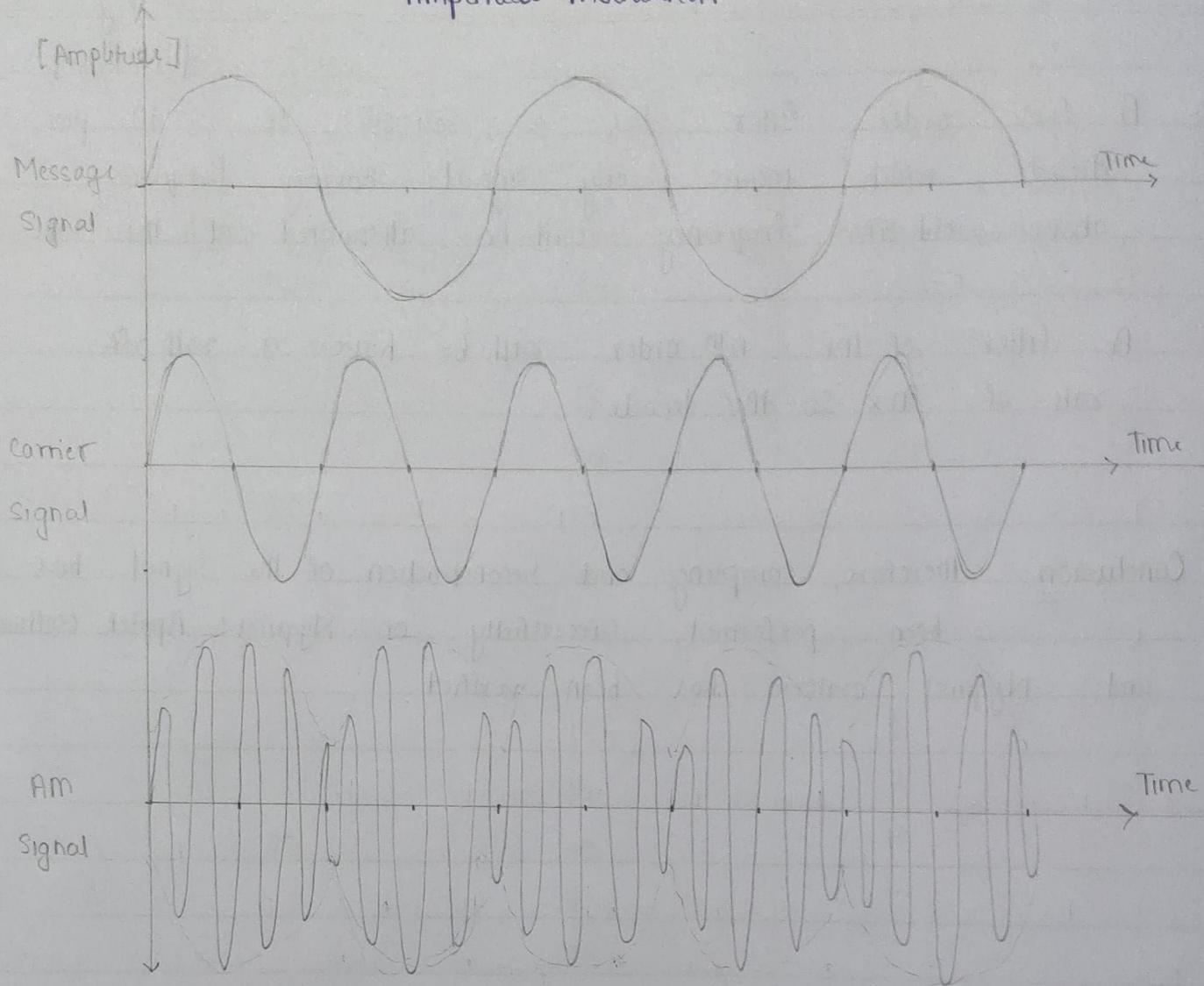
\therefore AM wave be $s(t) = [A_c + A_m \cos(2\pi f_m t)] \cos(2\pi f_c t)$

$$s(t) = A_c \left[1 + \frac{A_m}{A_c} \cos(2\pi f_m t) \right] \cos(2\pi f_c t)$$

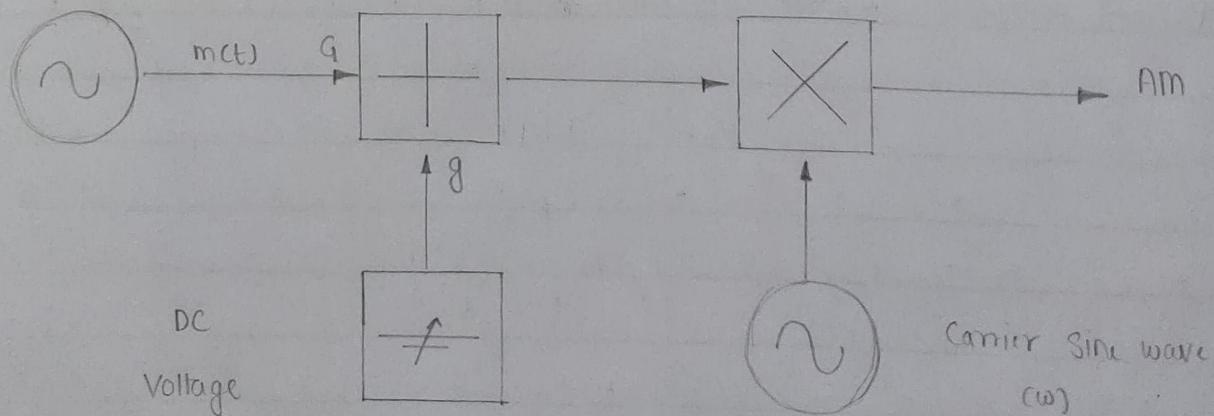
$$\text{Modulation index} = m = \frac{A_m}{A_c}$$

$$s(t) = A_c \cos(2\pi f_c t) + \frac{m}{2} A_c \cos(2\pi(f_c - f_m)t) + \frac{m}{2} A_c \cos(2\pi(f_c + f_m)t)$$

Amplitude Modulation



Schematic Block diagram for AM, Tx and Rx



3.) Measurement of 'm'

- The magnitude of 'm' can be measured directly from the AM display itself.
- maximum and minimum amplitudes of the transmission signals enter envelope, determine the modulation depth:

$$m = \frac{A_m}{A_c}$$

Max. Amplitude of modulated wave, $a = A_m + A_c$

Min. Amplitude of modulated wave, $b = A_c - A_m$

$$\therefore A_c = \frac{(a+b)}{2}, \quad A_m = \frac{(a-b)}{2}$$

$$\therefore m = \left(\frac{A_c}{A_m} \right)^{-1} = \left(\frac{(a+b)}{(a-b)} \right)^{-1} = \frac{(a-b)}{(a+b)}$$

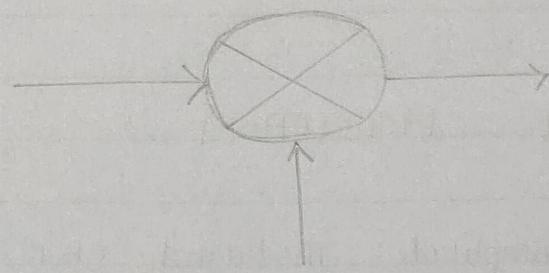
4.) Envelope Detector

- This non-coherent detection doesn't require a carrier recovery circuit. In its simplified form, it consists of a rectifier diode and a low pass filter.

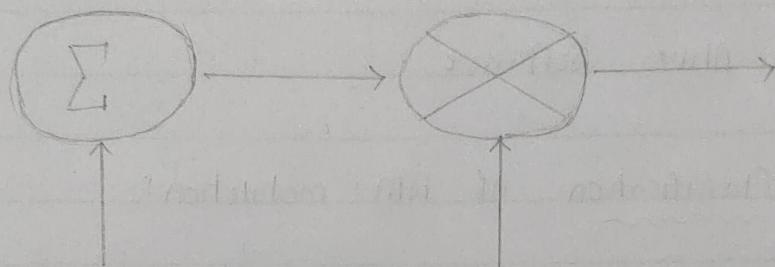
5.) Synchronous detector

- Am without a carrier. Envelope detection can't be deployed because the transmitted signal's envelope changes sign.
Transmit spectrum of DSB-SC.

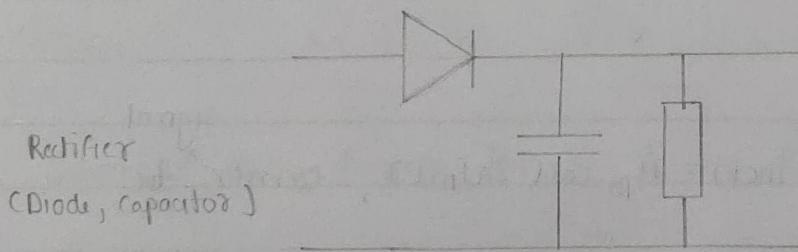
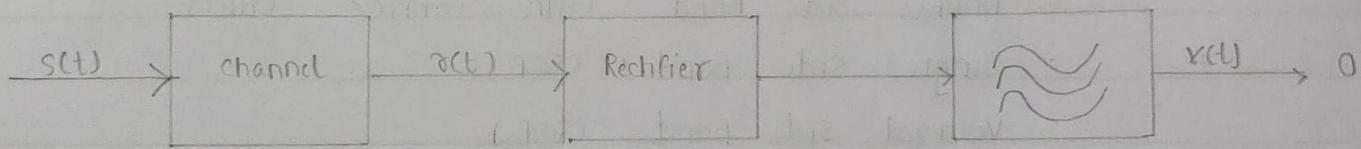
DSB - SC



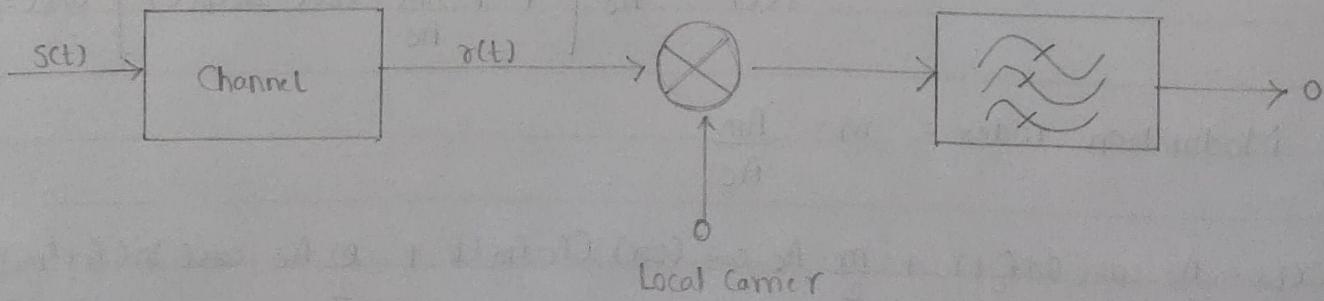
AM



Envelope Detector



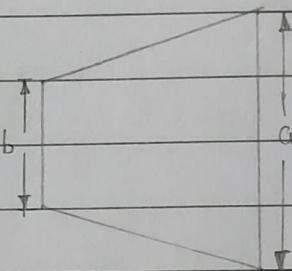
Synchronous Detector



6.) Trapezoid Method

- We can calculate 'm' in the time domain using an oscilloscope and the trapezoid method.

- The slope is placed in XY mode
 - X : modulating signal
 - Y : modulating signal



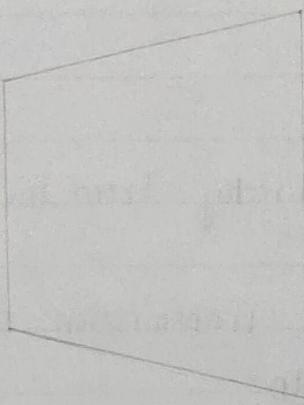
- The modulation index is then calculated from the vertical edge lengths using

$$m = \frac{(a - b)}{(a + b)}$$

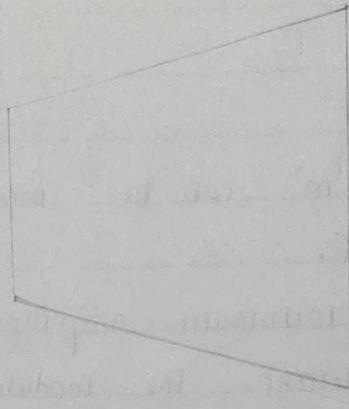
> PROCEDURE: In this online mode of practical, we perform the experiment on LabVIEW application.

- 1.) We will first execute the AM analyser simulator
- 2.) After executing the AM analyser simulator, click on the in the AM modulation window.
- 3.) For D.S.B. with carrier click on the D.C. and for D.S.B. with suppressed carrier off the D.C. output

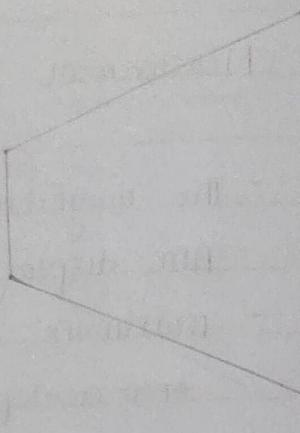
Trapezoid width is unaffected by modulation depth.



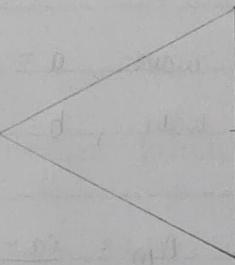
$$m = 0.1$$



$$m = 0.3$$



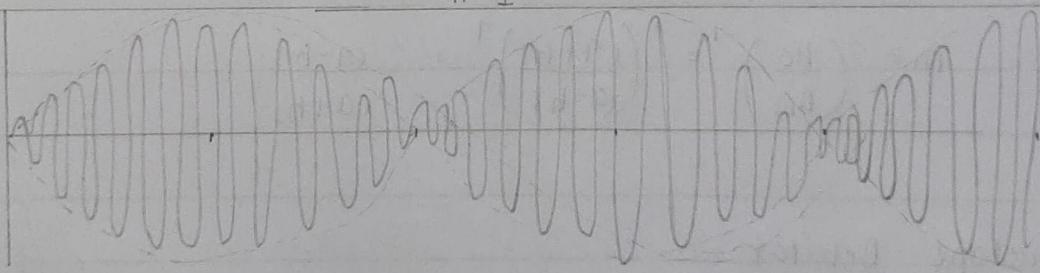
$$m = 0.5$$



$$m = 1$$

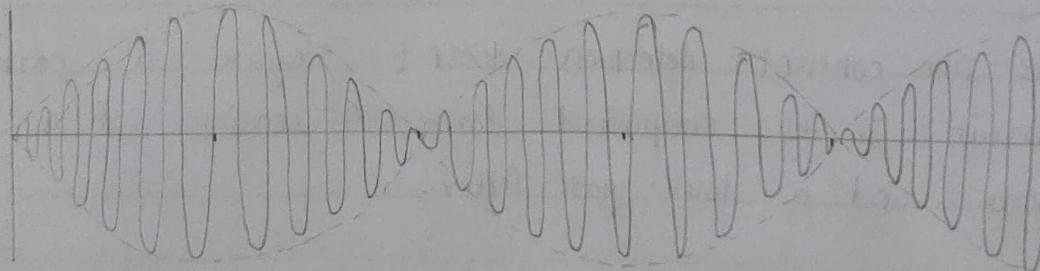
Modulation

Index = 0.5
($m < 1$)



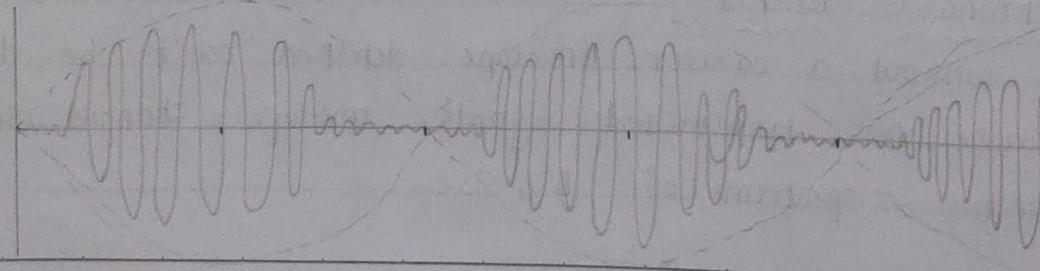
Modulation

Index = 1
($m = 1$)



Modulation

Index = 1.5
($m > 1$)

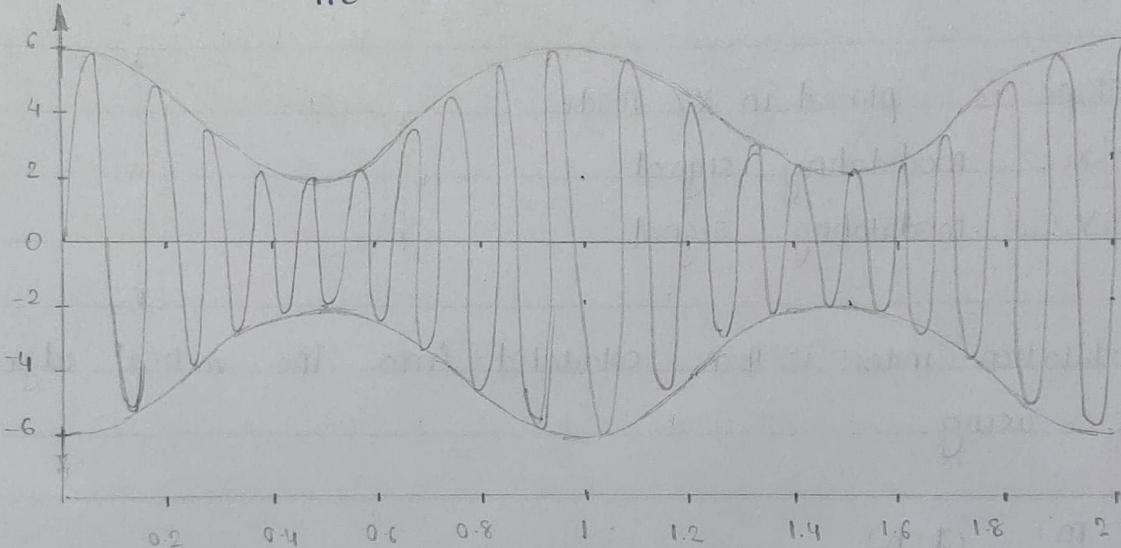


DOUBLE SIDE BAND WITH CARRIER

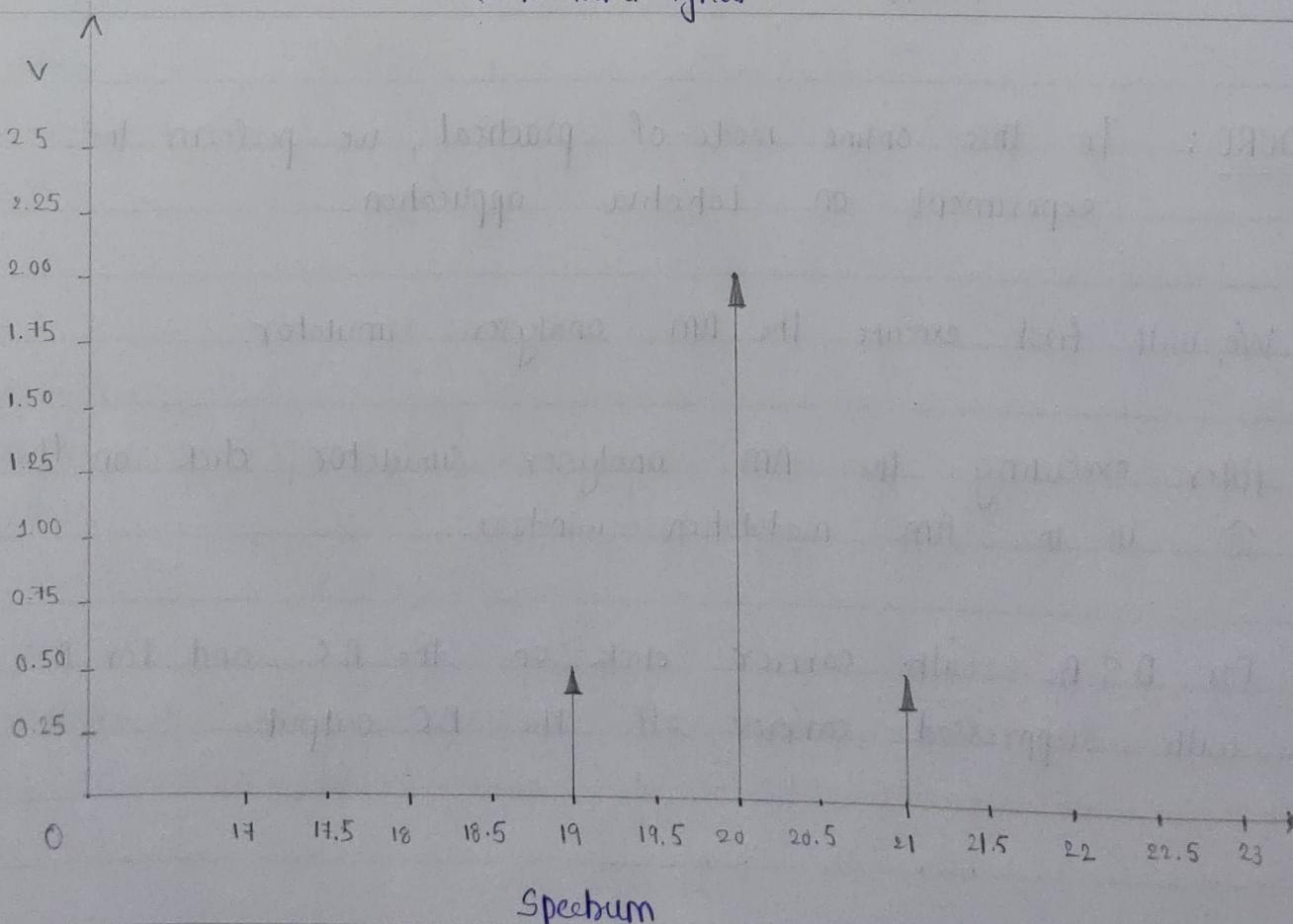
Observation

a) $m < 1$ Message = $A_m = 1V$ $f_m = 1 \text{ MHz}$ (Cosine)
 Carrier = $A_c = 2V$ $f_c = 20 \text{ MHz}$ (Cosine)
 $\hat{s} = A = 2V$ $f = 1 \text{ MHz}$ (DC on)

$$\mu = \frac{A_m}{A_c} = \frac{1}{2} = 0.5$$



Transmitted signal



Spectrum

(b) $m=1$

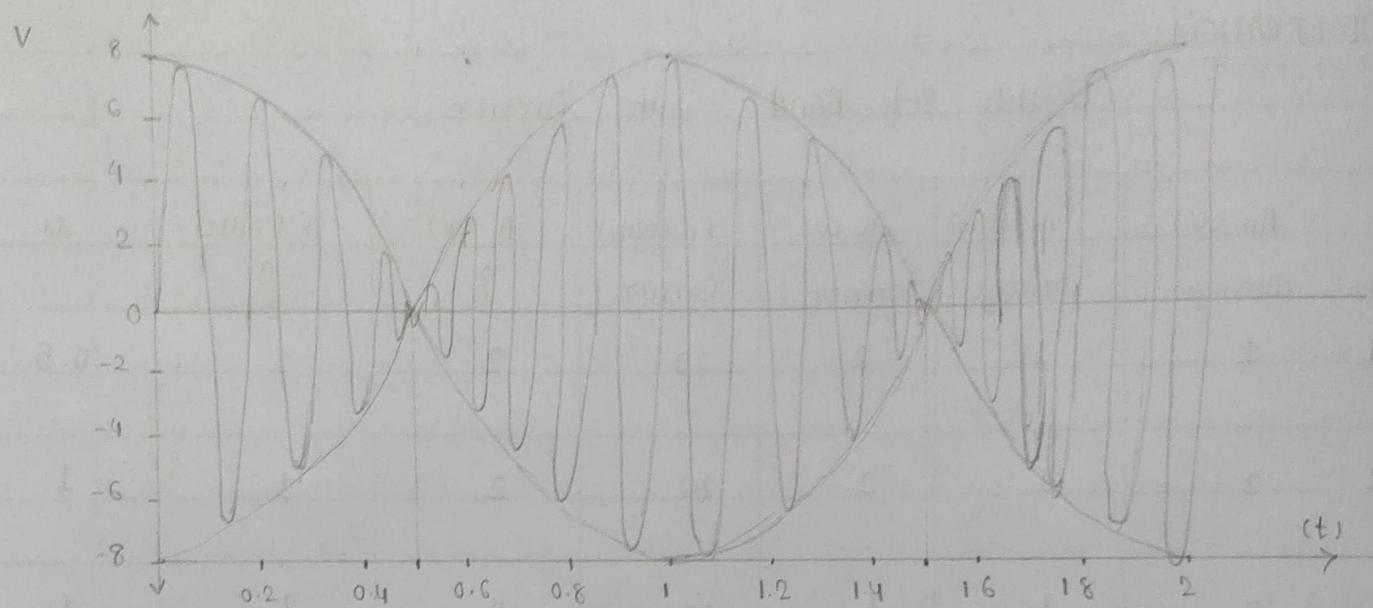
(8)

Message $A_m = 2V$ $f_m = 1\text{MHz}$ (cosine)

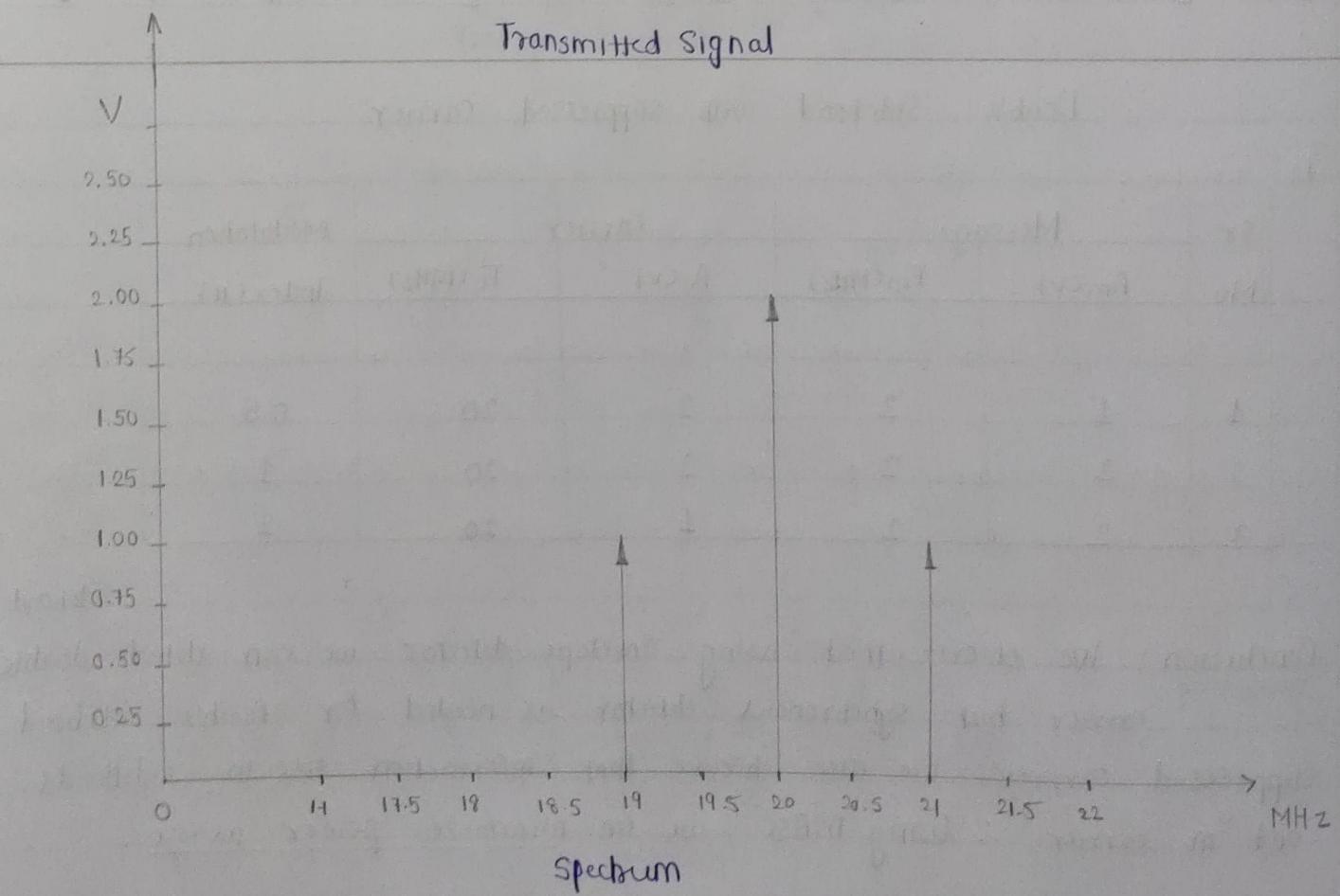
Carrier $A_c = 2V$ $f_c = 20\text{MHz}$ (cosine)

$\hat{A} = 2V$ $F = 1\text{MHz}$ (DC on)

$$\mu = \frac{A_m}{A_c} = 1$$



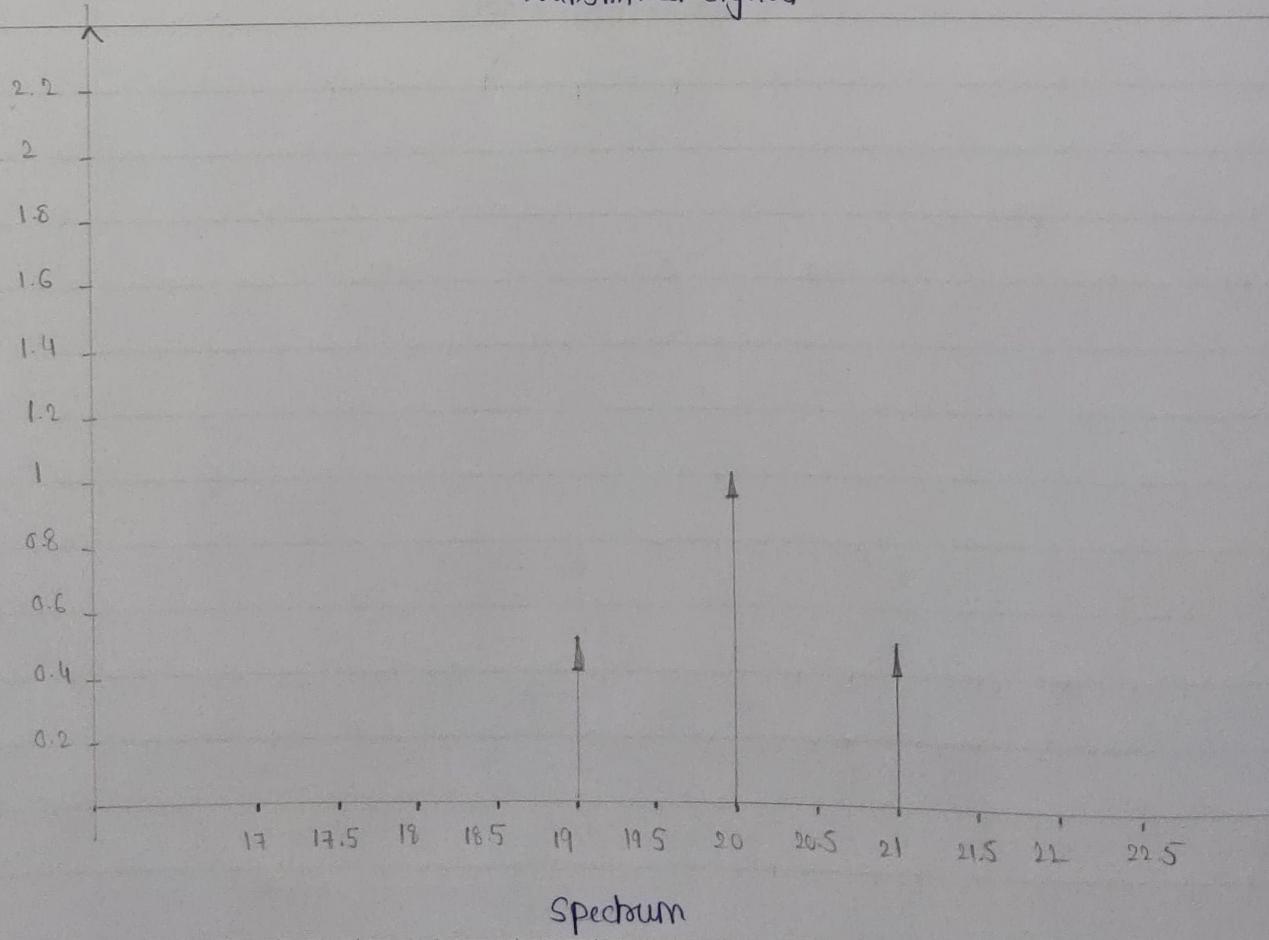
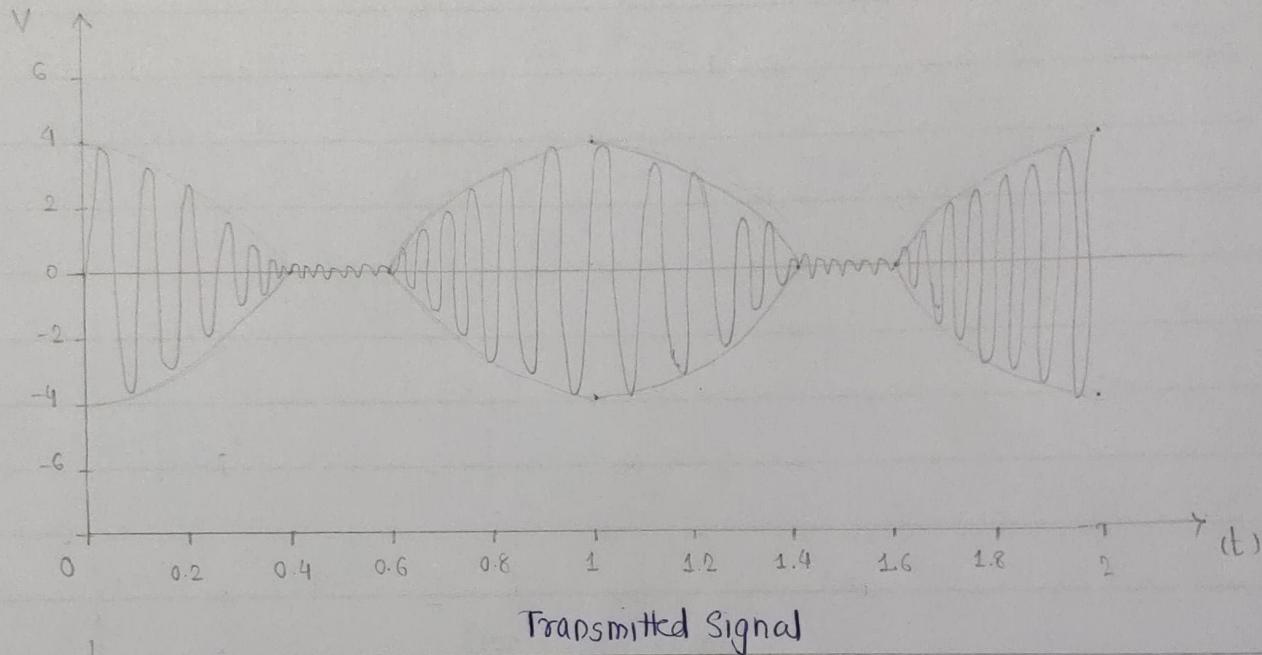
Transmitted Signal



Spectrum

c) $m > 1$ Message $A_m = 2V$ $F_m = 1 \text{ MHz}$ (cosine)
 Carrier $A_c = 1V$ $F_c = 20 \text{ MHz}$ (cosine)
 \hat{s} $A = 2V$ $F = 1 \text{ MHz}$ (~~DC on~~)

$$\mu = \frac{A_m}{A_c} = \frac{2}{1} = 2$$



DOUBLE SIDEBAND SUPPRESSED CARRIER [DC OFFSET OFF]

a) $m < 1$

Message
Carrier

$A_m = 1V$

$A_C = 2V$

$F_m = 2 \text{ MHz}$

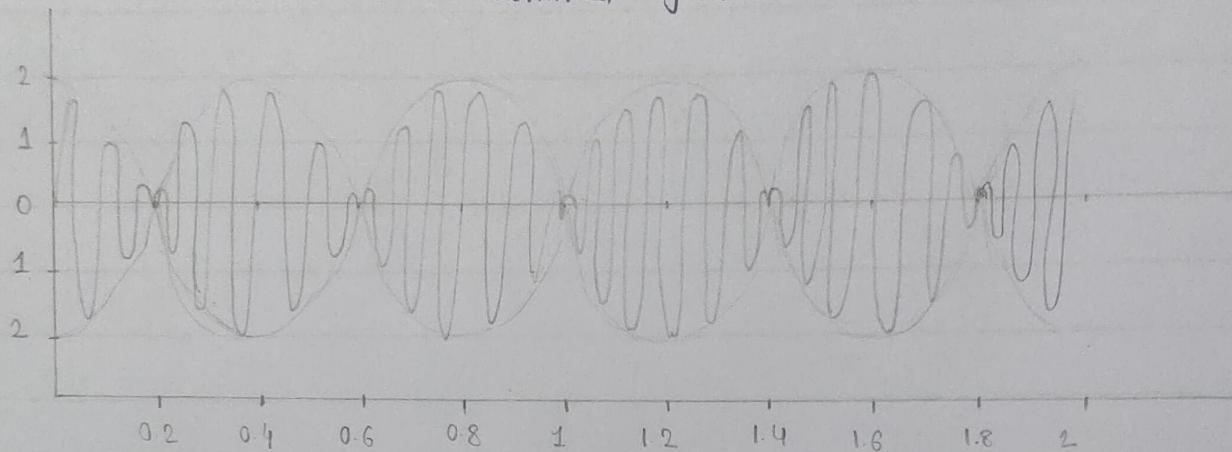
$F_C = 20 \text{ MHz}$

(cosine)

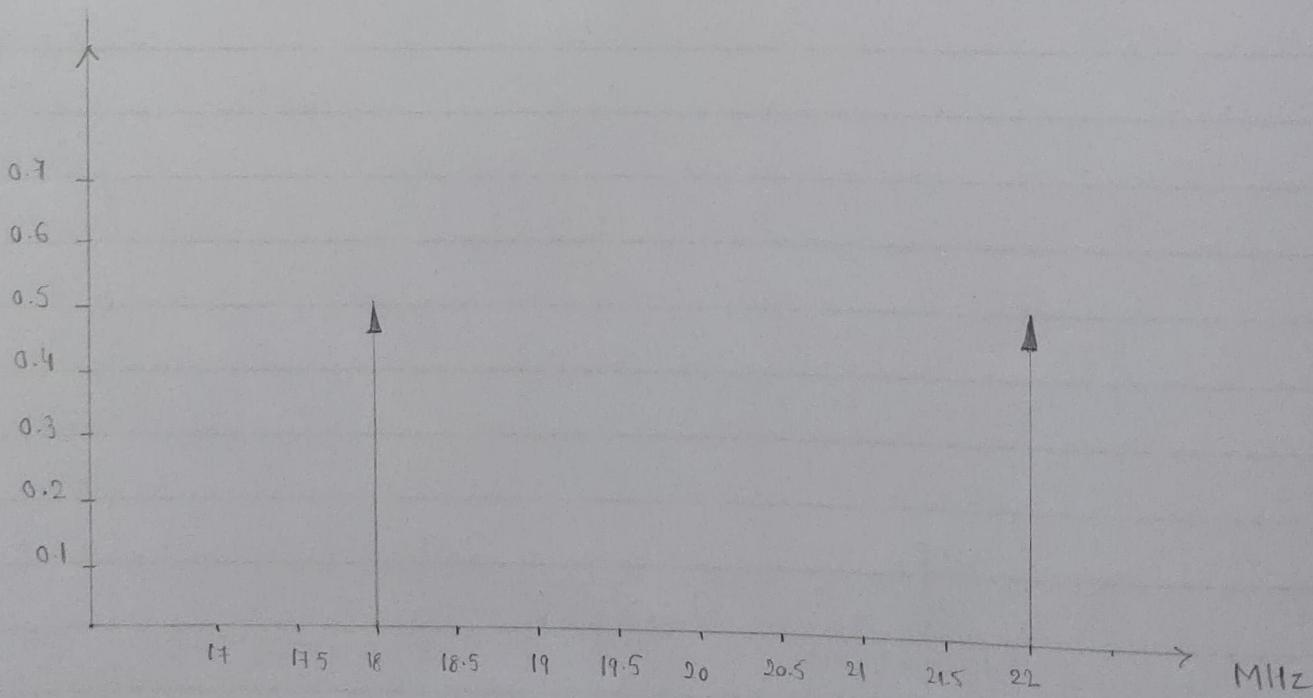
(cosine)

$$\mu = \frac{A_m}{A_C} = 0.5$$

Transmitted signal

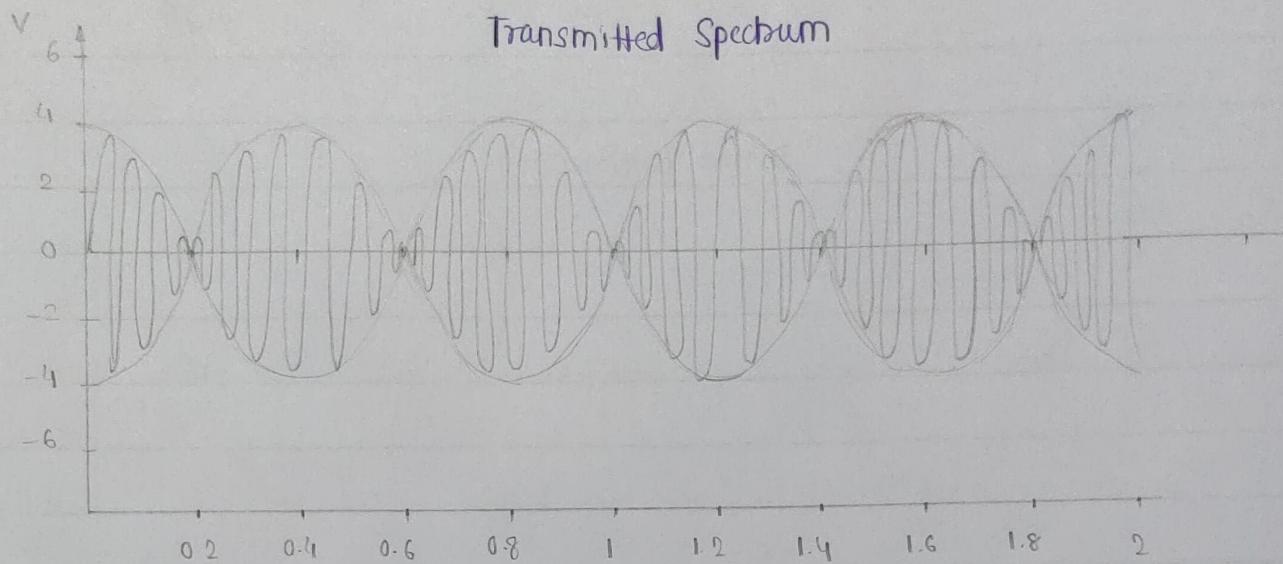


Spectrum

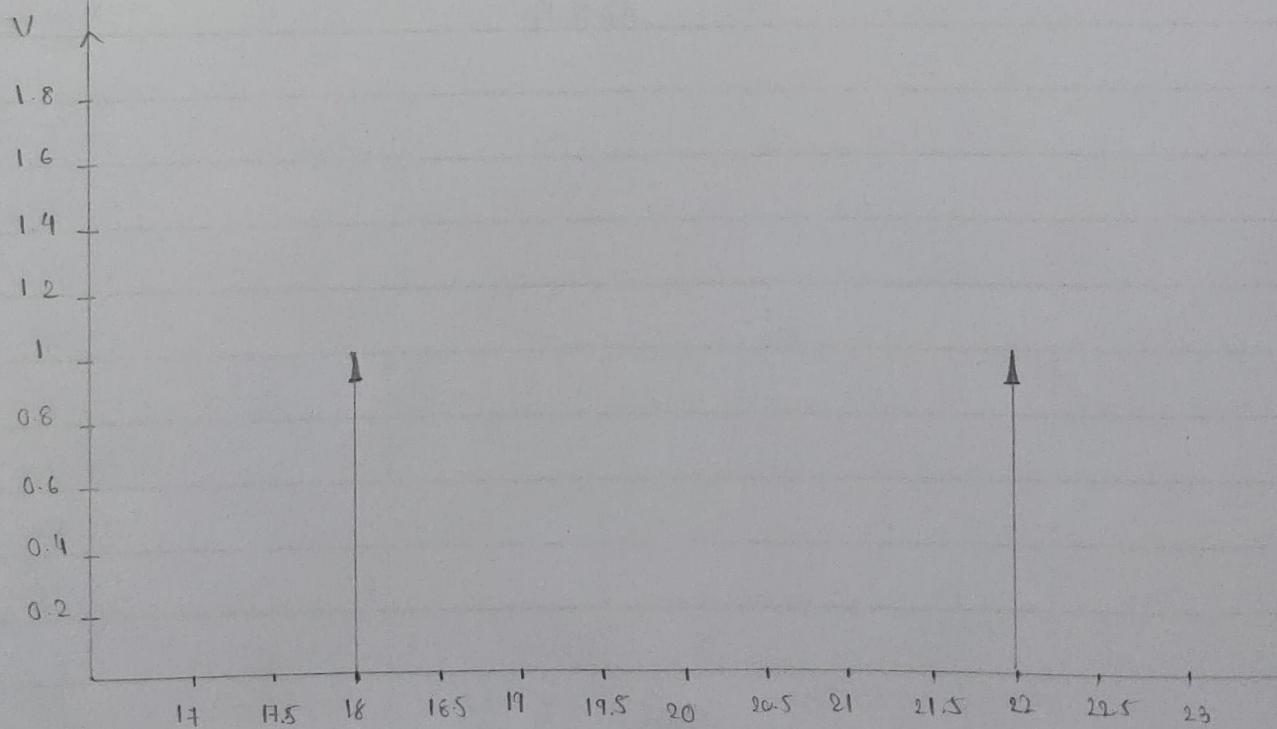


b) $m = 1$ Message $A_m = 2V$ $F_m = 2 \text{ MHz}$ (cosine)
 Carrier $A_c = 2V$ $F_c = 20 \text{ MHz}$ (cosine)

$$\mu = \frac{A_m}{A_c} = \frac{2}{2} = 1$$



Spectrum

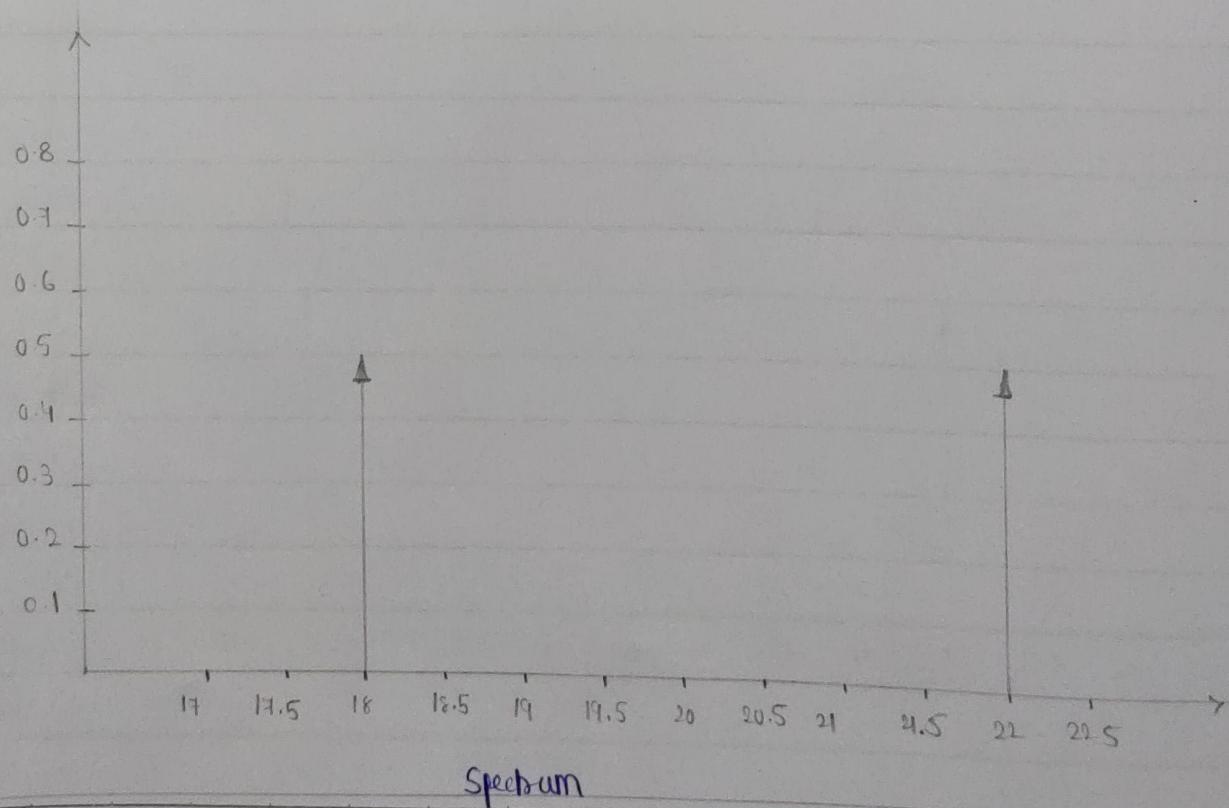
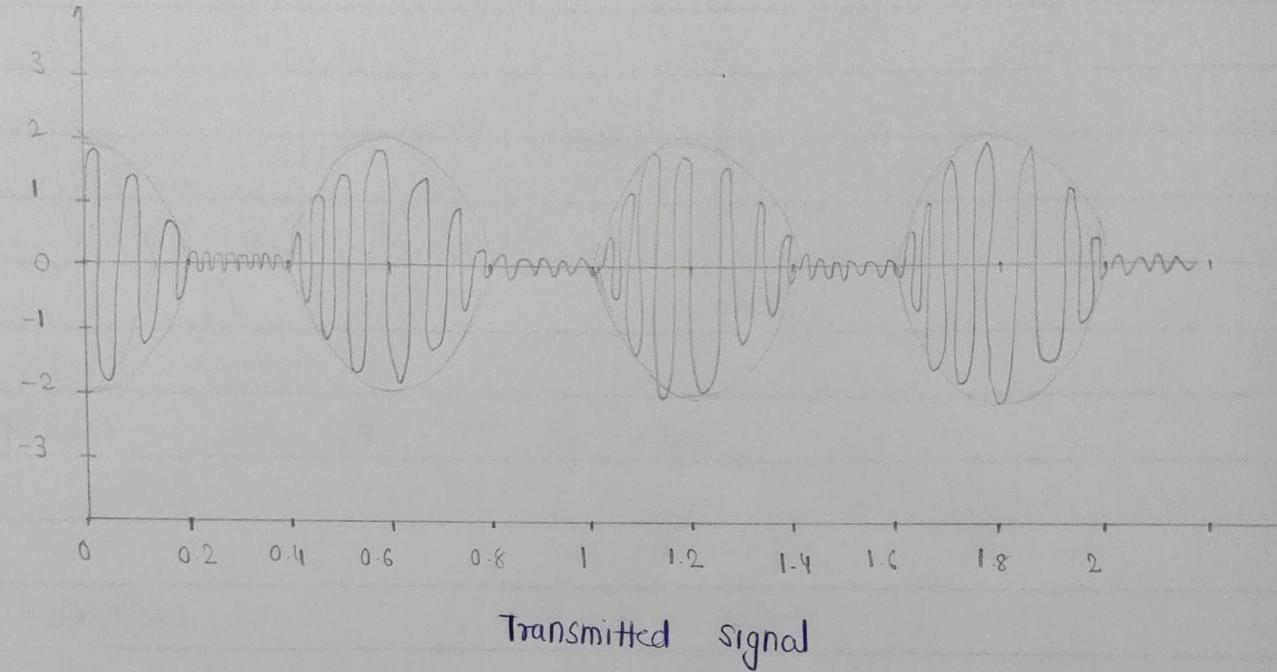


12/13

(12)

c) $m > 1$ Message $A_m = 2V$ $F_m = 2\text{ kHz}$ (cosine)
 Carrier $A_c = 1V$ $F_c = 20\text{ kHz}$ (cosine)

$$\mu = \frac{A_m}{A_c} = \frac{2}{1} = 2$$



4.) For the different value of m observe the transmitted signal using oscilloscope and spectrum analyzer.

> OBSERVATION:

Double Side Band with Carrier

Sr. No.	A_m (V)	F_m (MHz)	A_c (V)	F_c (MHz)	A (V)	F (MHz)	μ
Message	Message	carrier	Carrier		\hat{s}	\hat{s}	
1	1	1	2	20	2	1	0.5
2	2	1	2	20	2	1	1
3	2	1	1	20	2	1	1

Double Sideband with suppressed Carrier

Sr. No.	Message	Carrier	Modulation Index (μ)	
	A_m (V)	F_m (MHz)	A_c (V)	F_c (MHz)
1.	1	2	2	20
2.	2	2	2	20
3.	2	2	1	20

sideband with

> Conclusion: We observe that using envelope detector we can detect double sideband with carrier but synchronous detector is needed for Double sideband suppressed carrier. We also observe that information lies in sidebands and in carrier. ∴ Using DSBSC, we can minimize power usage.

EXPERIMENT 4:

[U19CS012]

FREQUENCY MODULATION AND
DEMODULATION

AIM: To study Frequency Modulation (F.M.) and Frequency demodulation with its Application

APPARATUS REQUIRED: LabAlive Software, MATLAB Software (online Mode)

THEORY:

(1) Angle Modulation is the process in which the frequency or phase of the carrier varies according to message signal.

(2) The standard equation of the Angle modulated wave is

$$s(t) = A_c \cos(\theta_i(t))$$

where A_c = Amplitude of the modulated wave / carrier signal

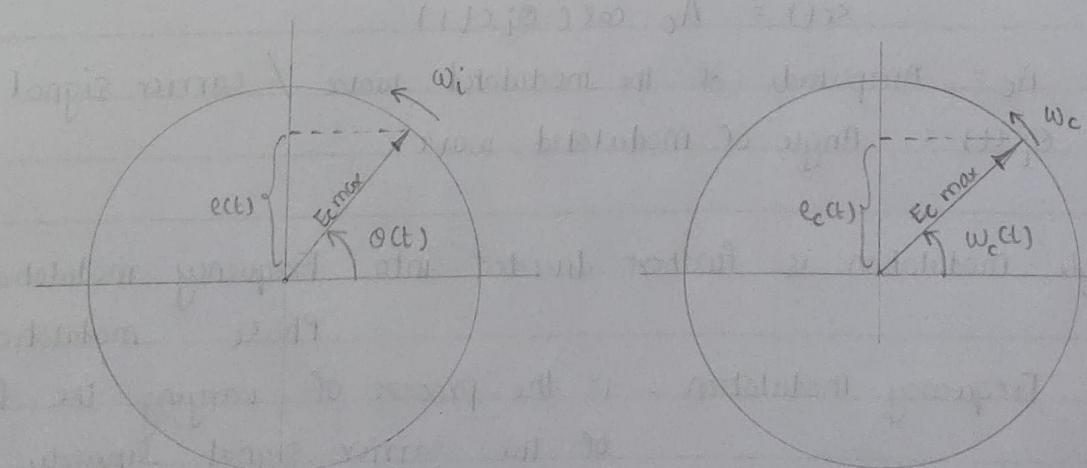
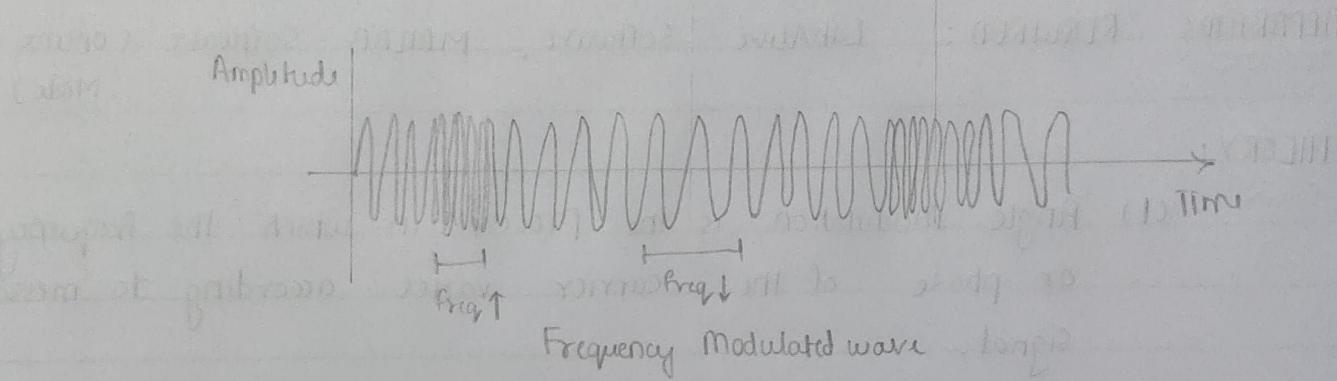
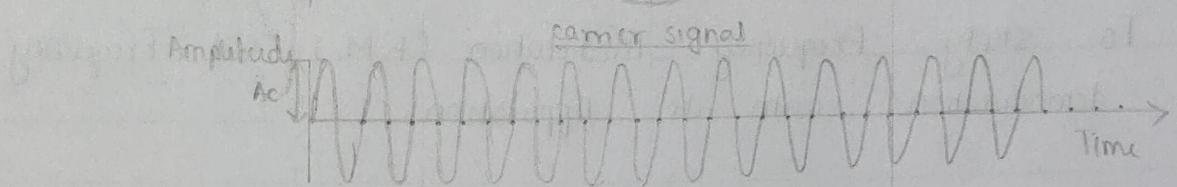
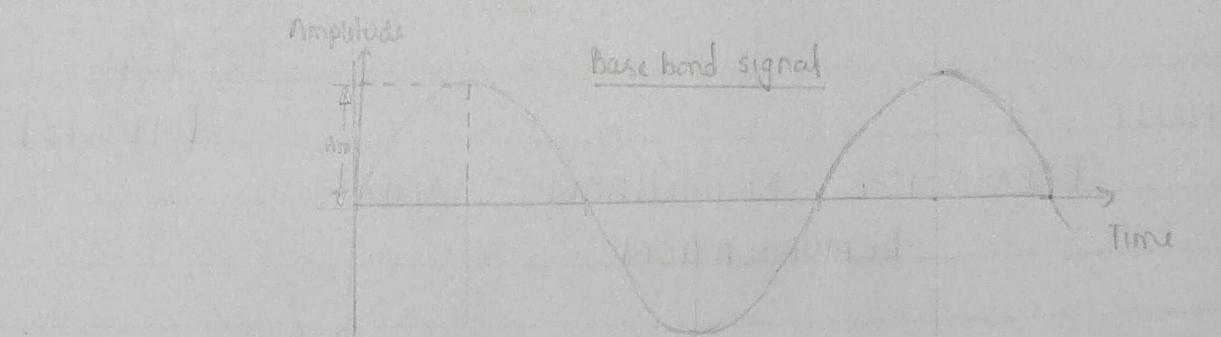
$\theta_i(t)$ = Angle of modulated wave.

(3) Angle modulation is further divided into Frequency modulation and Phase modulation

(i) Frequency modulation : is the process of varying the frequency of the carrier signal linearly with message signal.

(ii) Phase modulation : is the process of varying the phase of carrier signal linearly with message signal.

(2)



(a)

Instantaneous
angular velocity
 $w_c(t)$

Rotating phasor
representation

of carrier of amplitude $E_{c\max}$

(b)

at constant

angular velocity (w_c)

(4) As the frequency of modulated wave increases, when the Amplitude of the modulating or message signal increases.

Similarly, the frequency of modulated wave decreases, when the amplitude of the modulating signal decreases.

Note: The frequency of modulated (carrier) wave remains constant and is equal to frequency of carrier signal, when Amplitude of modulating signal is zero.

(5) Mathematically,

The equation for instantaneous frequency (f_i) in FM modulation

$$f_i = f_c + (K_f)(m(t)) \quad \begin{array}{l} \text{①} \\ \text{message signal} \\ \text{frequency sensitivity} \\ \text{carrier frequency} \end{array}$$

(6) We know relationship between w_i and $\theta_i(t)$.

$$[w_i = \frac{d(\theta_i)}{dt}] \quad \text{②}$$

$$2\pi f_i = \frac{d(\theta_i)}{dt}$$

$$\theta_i(t) = 2\pi \int (f_i) dt$$

Substitute f_i from eqn ①

$$\theta_i(t) = 2\pi \int (f_c + K_f m(t)) dt$$

$$\theta_i(t) = 2\pi f_c t + 2\pi K_f \int m(t) dt \quad \text{③}$$

Substitute $\theta_i(t)$ value in standard eqn of Angle Modulated wave;

$$s(t) = A_c \cos [2\pi f_c t + 2\pi K_f \int m(t) dt] \quad \begin{array}{l} \text{(Eqn of FM} \\ \text{wave)} \end{array}$$

(7) Finally, Equation of F.M. wave

$$s(t) = A_c \cos (2\pi f_c t + 2\pi k_f \int m(t) dt) \quad (4)$$

If modulating signal $m(t) = A_m \cos(2\pi f_m t)$, then eqn of F.M.

$$s(t) = A_c \cos (2\pi f_c t + \beta \sin(2\pi f_m t)) \quad (5)$$

$$\beta = \frac{k_f A_m}{f_m} = \frac{\Delta f}{f_m} = \text{modulation index}$$

(8) The difference between FM modulated frequency (instantaneous frequency) and normal carrier frequency is termed as Frequency Deviation. It is denoted by $[\Delta f = f_i - f_c = k_f A_m]$ and is equal to product of k_f and A_m .

(9) FM can be divided into Narrowband F.M. and Wideband F.M. based on values of modulating index. (β)

(10) The amount of change in carrier frequency produced, by the amplitude of input modulating signal, is called frequency deviation.

carrier frequency swings between f_{\max} and f_{\min} as input varies.

freq. deviation

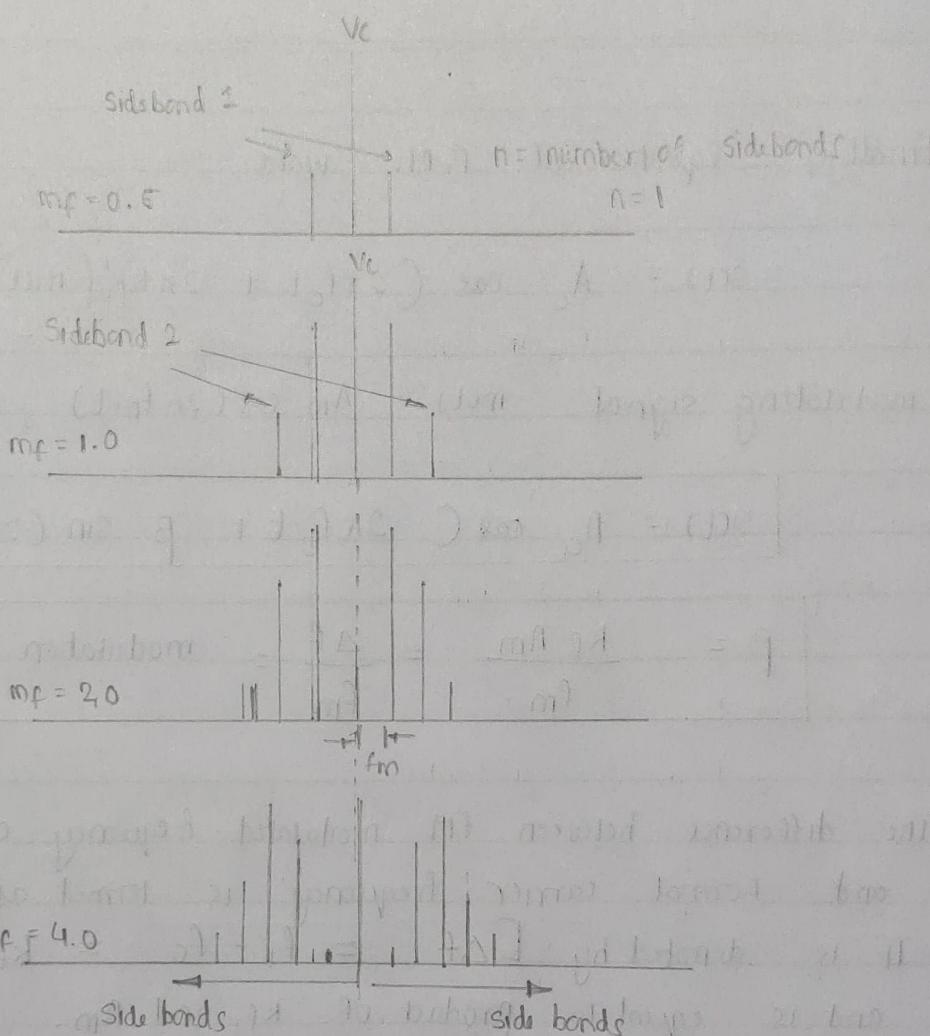
$$fd = f_{\max} - f_c = f_c - f_{\min}$$

(MHz) f_c 100

N.i.k

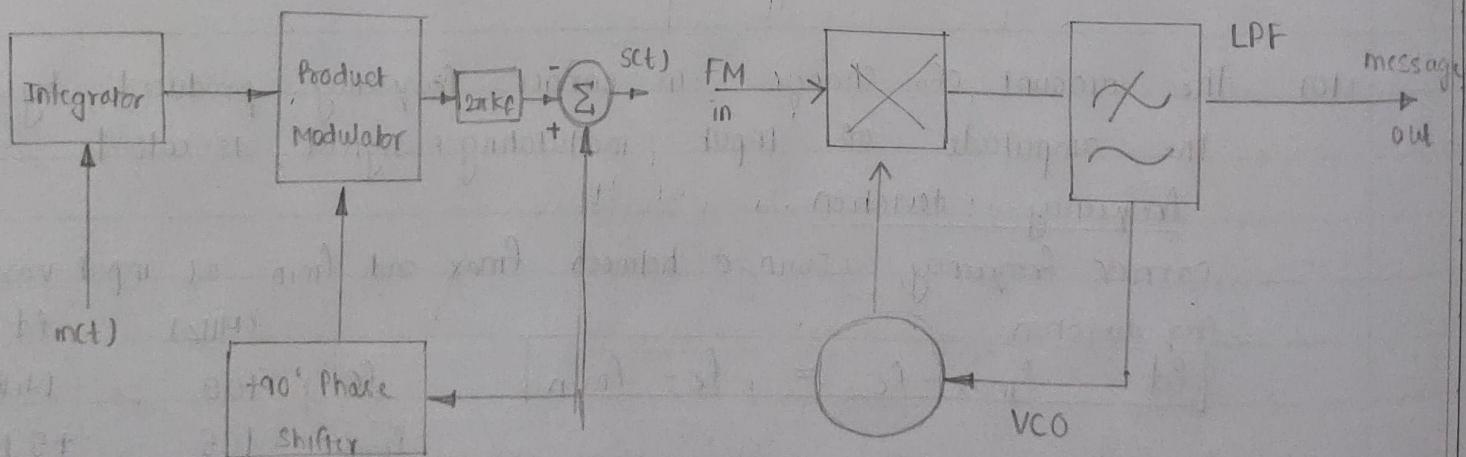
f_{\max} 105 +5 MHz

f_{\min} 95 -5 MHz



How spectrum F.M. varies with m_f

(Q) What is the relation between m_f and Δf ?



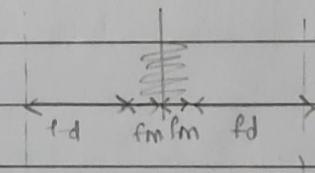
Block diagram of FM modulator and demodulator

(11) F.M. signal spectrum is quite complex and will have infinite number of sideband as shown in figure.

This figure gives an idea, how the spectrum expands as the modulation index increases.

Sidebands are separated from carrier by $f_c + f_m$, $f_c \pm 2f_m$, $f_c \pm 3f_m$, and so on...

$$\text{Bandwidth} = 2 * (f_m + \Delta f)$$



(12) In F.M., carrier Amplitude is constant,

∴ Transmitted Power is constant.

& Transmitted Power does not depend on modulation index.

(13) F.M. has better noise immunity. FM is rugged/ robust against noise. ∴ The quality of FM will be good even in presence of noise.

(14) Applications & Advantages of F.M.

(A) FM is resilient to noise and interference. ∴ It is used for high quality broadcast transmission.

(B) FM is ideal for mobile radio communication application including more general two-way radio communication or portable applications where signal levels are likely to vary considerably.

(magnetic tape record system)
synthesis

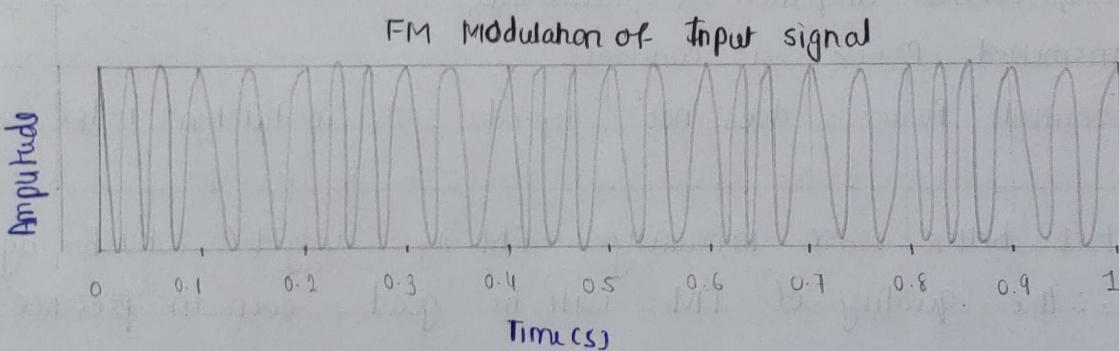
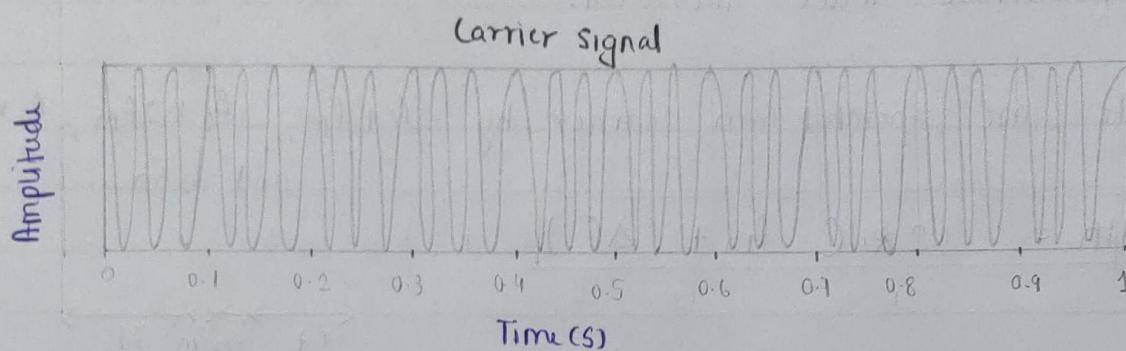
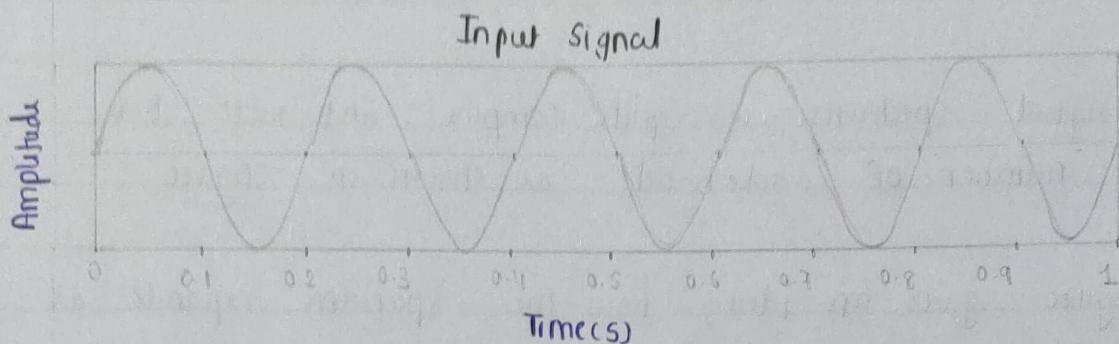
(C) Radar, Telemetry, observing infants for seizure through EEG, music

> MATLAB Code:

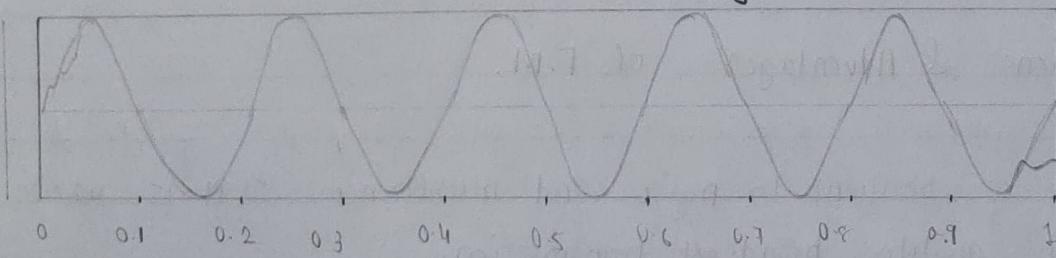
```
% Plot the frequency modulated signal  
fc = 30 ;  
fm = 5 ;  
ts = 1 / (10 * fc) ;  
fs = (1 / ts) ;  
fdev = 10 ; % Frequency deviation  
t = 0 : ts : 1 ;  
m = sin( 2 * pi * fm * t) ;  
c = cos( 2 * pi * fc * t) ;  
% y = cos( w0 * t + (Kf * 2 * pi * cumsum(m)).* ts ) ;  
y = fmmod (m, fc, fs, fdev) ;  
figure ;  
subplot (5,1,1)  
plot (t,m)  
title ('Input signal')  
xlabel ('Time (s)')  
ylabel ('Amplitude')  
subplot (5,1,2)  
plot (t,c)  
title ('Carrier signal')  
xlabel ('Time (s)')  
ylabel ('Amplitude')  
subplot (5,1,3)  
plot (t,y)  
title ('FM Modulation of input signal')  
xlabel ('Time (s)')  
ylabel ('Amplitude')
```

MATLAB OUTPUT

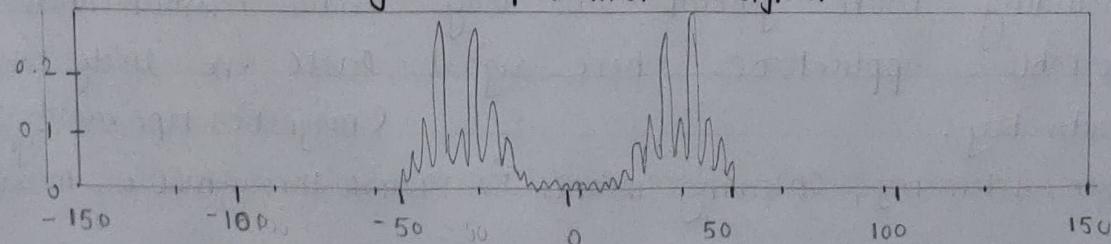
⑧



Demodulation of FM signal



Magnitude spectrum of FM Signal



[U19S012]

1. Demodulation

```
z = fm demod (y, fc, fs, fdev);  
subplot (5, 1, 4)  
plot (t, z)  
title ('Demodulated FM signal');
```

2. Plot the frequency spectra

```
a = fftshift (fft (y)) * ts;  
delta = fs / length (a);  
f = -fs/2; delta: fs/2 - delta;  
subplot (5, 1, 15)  
plot (f, abs (a))  
title ('Magnitude spectrum of FM signal');
```

> CONCLUSION: We have successfully verified and understood
~~~~~ the concept of Frequency modulation and demodulation  
using MATLAB and also learnt various applications of FM.

x

## EXPERIMENT 5 :

[U19CS012]

PULSE AMPLITUDE MODULATION (P.A.M.)

PULSE POSITION MODULATION (P.P.M.)

PULSE WIDTH MODULATION (P.W.M.)

AIM : To examine pulse Amplitude modulation (PAM), Pulse Position Modulation (PPM) and Pulse width Modulation (PWM) and verify and draw the resultant waveform.

APPARATUS : MATLAB software online

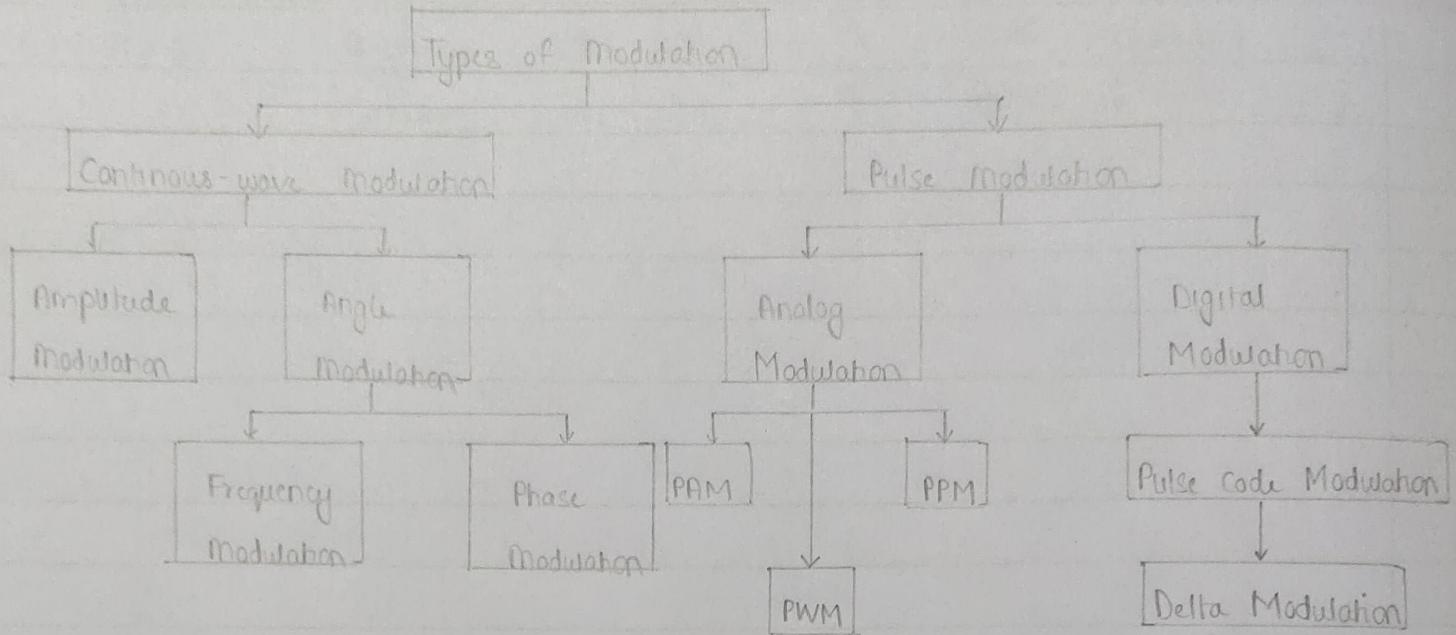
## THEORY :

1.) Pulse modulation is a type of modulation in which the signal is transmitted in the form of pulses.

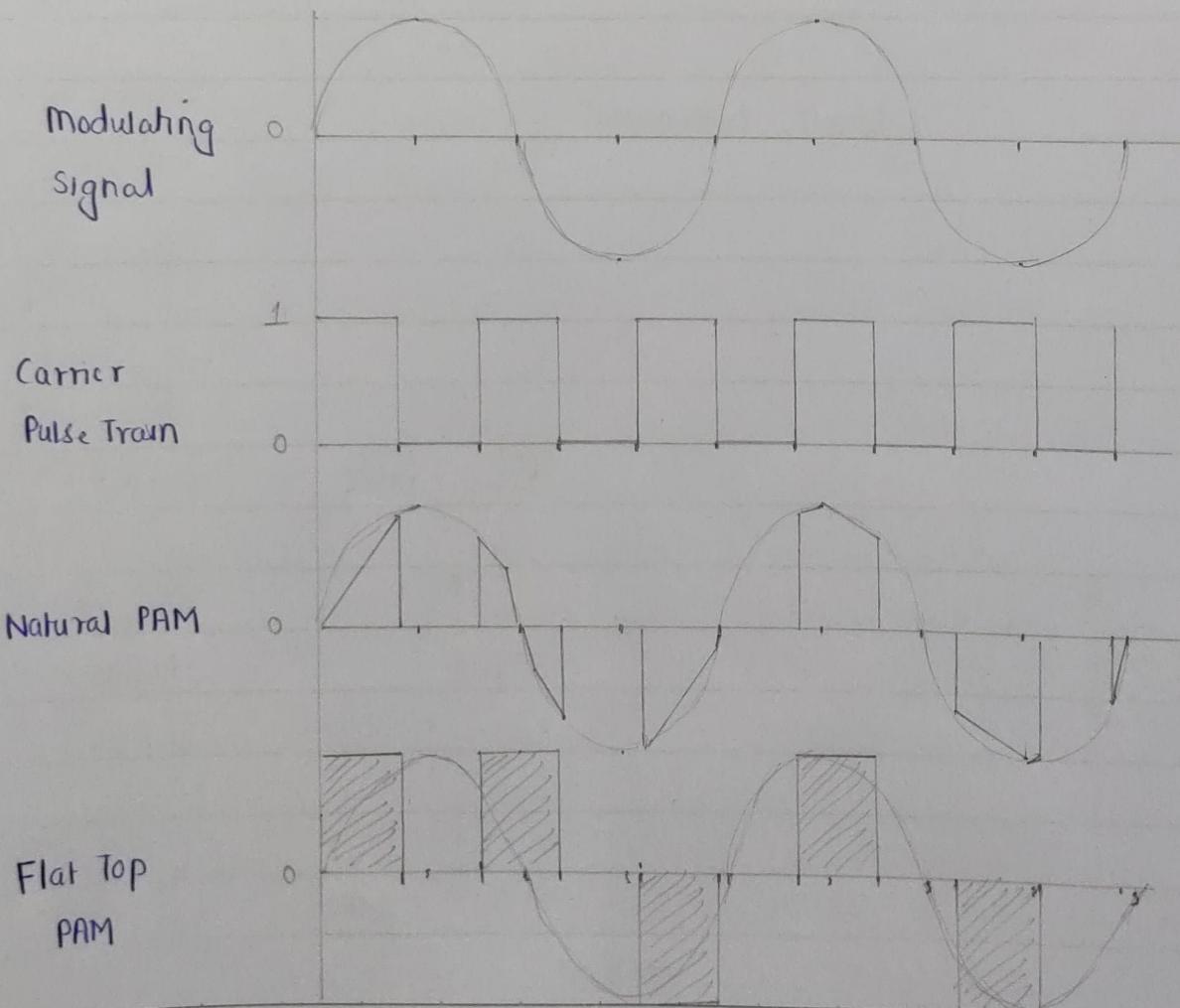
In Pulse Modulation, continuous signals are sampled at regular intervals. Pulse modulation is further divided into Analog and Digital communication. and further analog and digital modulation is subdivided in PAM, PWM, PPM (analog) and PCM, DPCM (digital).

## 2.) Pulse Amplitude Modulation (PAM) :

→ In PAM, a pulse signal is used to sample an analog signal. The result is a train of constant-width pulses. The amplitude of each pulse is proportional to the amplitude of the message signal at the time of sampling. The PAM signal follows the amplitude of the original signal, as the signal traces on the path of the whole wave.



### Natural Sampling and Flat Top Sampling



→ PAM signal generation: We can generate PAM signal by two types of sampling process.

Natural Sampling: For a PAM signal produced with natural sampling, the sampled signal follows the waveform of the input signal during the time that each sample is taken.

Flat-top Sampling: In this type of sampling, a sample and hold circuit is used to hold the amplitude of each pulse at a constant level.

### 3) Pulse Width Modulation (PWM)

→ In this type, the amplitude is maintained constant but the duration or length or width of each pulse is varied in accordance with instantaneous value of analog signal.

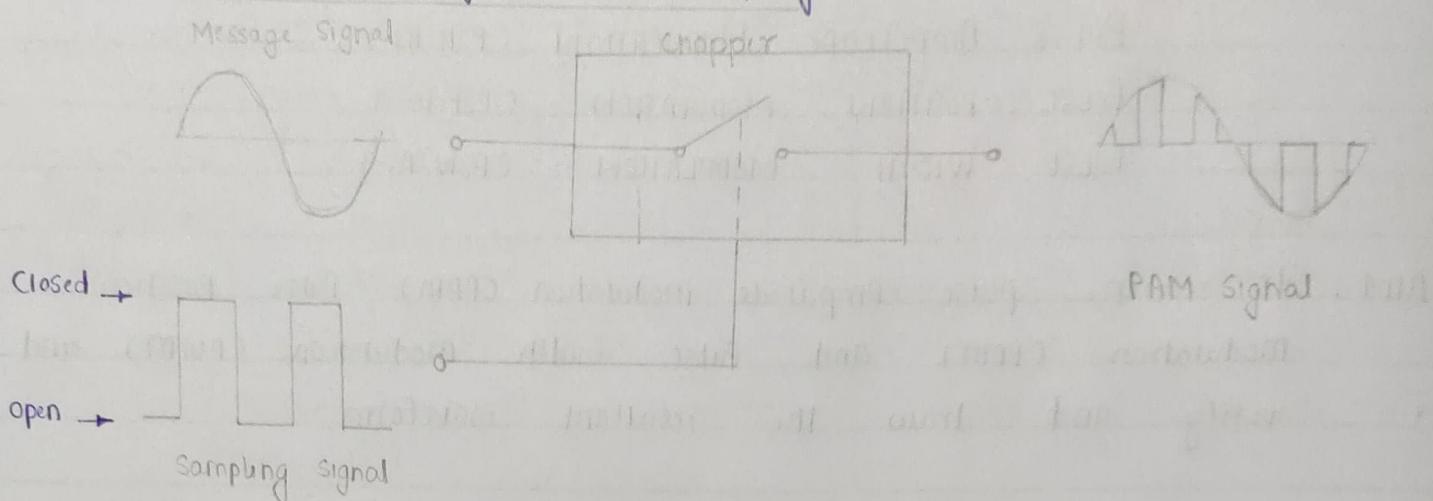
### 4) Pulse Position Modulation (PPM)

→ In this type of modulation, both the amplitude and width of the pulse are kept constant. we vary the position of each pulse according to the instantaneous sampled value of the message signal.

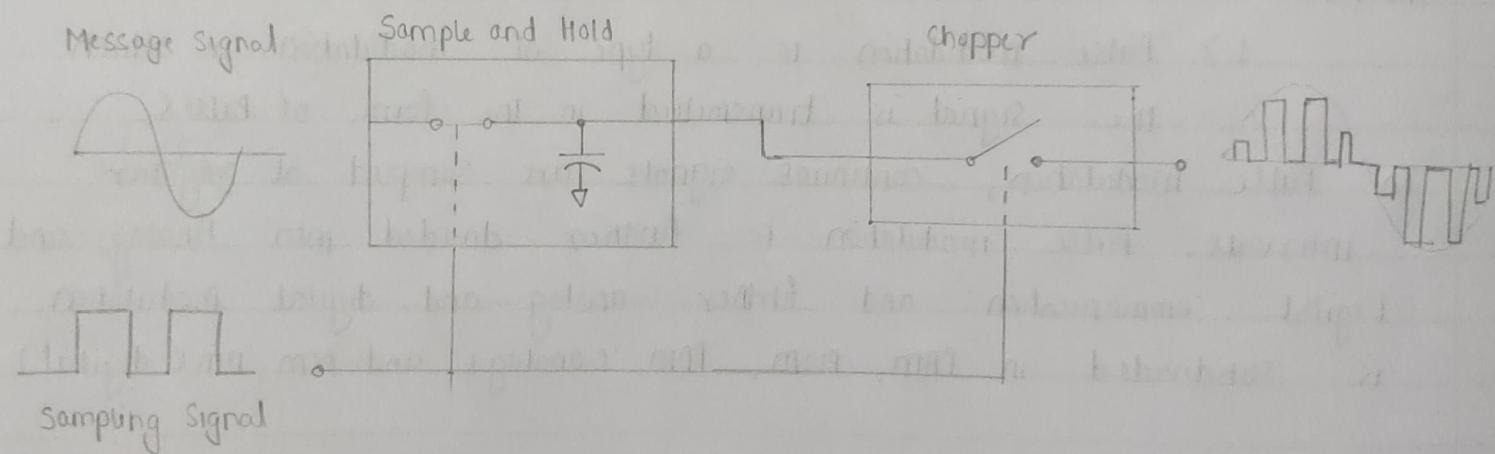
→ PPM is further modification of PWM

(4)

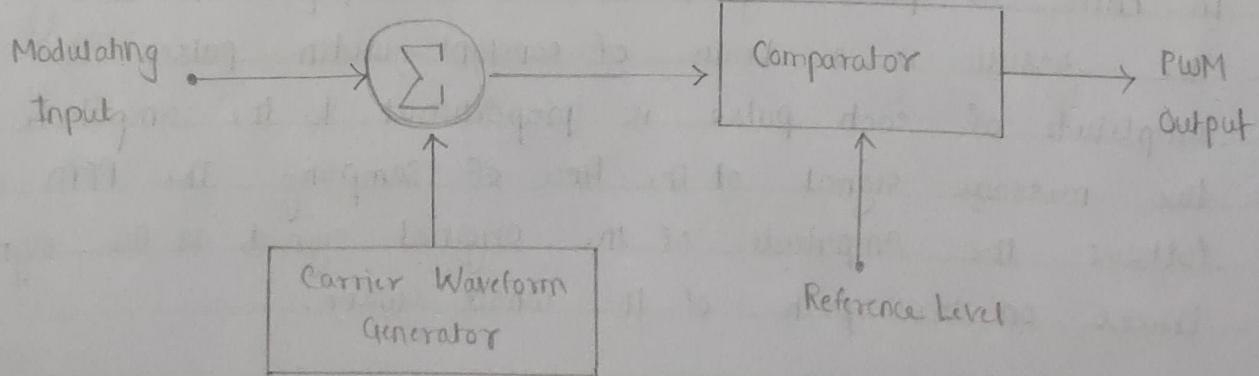
### Generation of PAM by Natural Sampling:



### Generation of PAM Signal by Flat-top Sampling



### Generation of PWM Signal

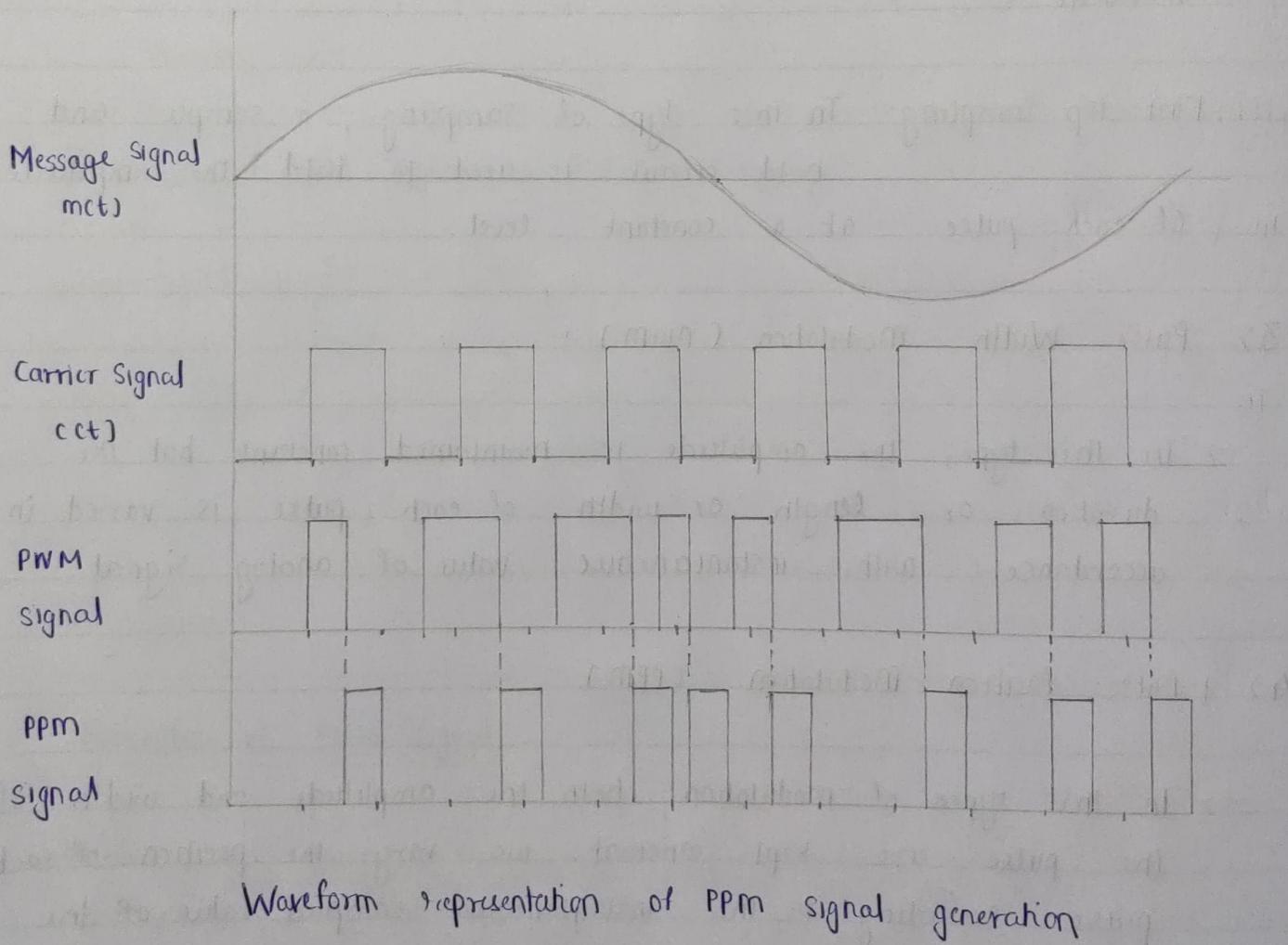
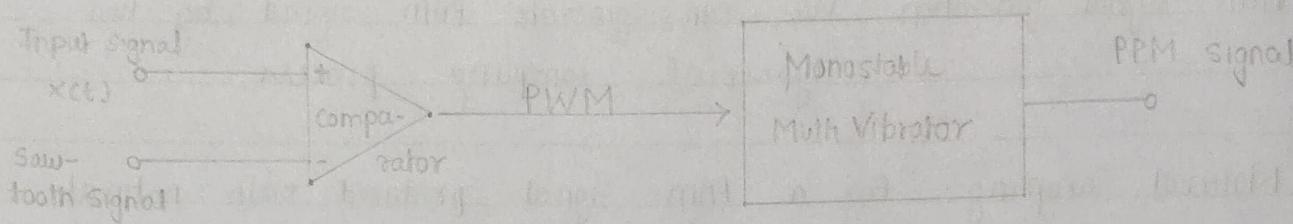


## 5.) Comparison of PAM, PWM and PPM:

| No. | Pulse Amplitude Modulation (PAM)                                                                                                                                                                                                                           | Pulse Width Modulation (PWM)                                          | Pulse Position Modulation (PPM)                                                       |
|-----|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----------------------------------------------------------------------|---------------------------------------------------------------------------------------|
| 1.) | Amplitude of the pulse is proportional to amplitude of modulating signal.                                                                                                                                                                                  | Width of the pulse is proportional to amplitude of modulating signal. | The relative position of the pulse is proportional to amplitude of modulating signal. |
| 2.) | Bandwidth of the transmission channel depends on the pulse width.                                                                                                                                                                                          | Here, it depends on the rise time of the pulse.                       | Here, it depends on Rising time of the pulse.                                         |
| 3.) | Instantaneous power of transmitter varies.                                                                                                                                                                                                                 | Instantaneous power of transmitter varies.                            | Instantaneous power of the transmitter is constant.                                   |
| 4.) | Noise interference is high.                                                                                                                                                                                                                                | Noise interference is minimum.                                        | Noise interference is minimum.                                                        |
| 5.) | System is complex to implement.                                                                                                                                                                                                                            | System is simple to implement.                                        | System is simple to implement.                                                        |
| 6.) | Similar to Amplitude Mod.                                                                                                                                                                                                                                  | Similar to Frequency Mod.                                             | Similar to Phase Mod.                                                                 |
| >   | CONCLUSION: We successfully examined Pulse Amplitude Modulation, Pulse Position Modulation, Pulse width modulation and also verified their waveforms. We also illustrated circuits for PAM and PWM. We performed our experiment successfully using MATLAB. |                                                                       |                                                                                       |

(6)

## Generation of PPM Signal



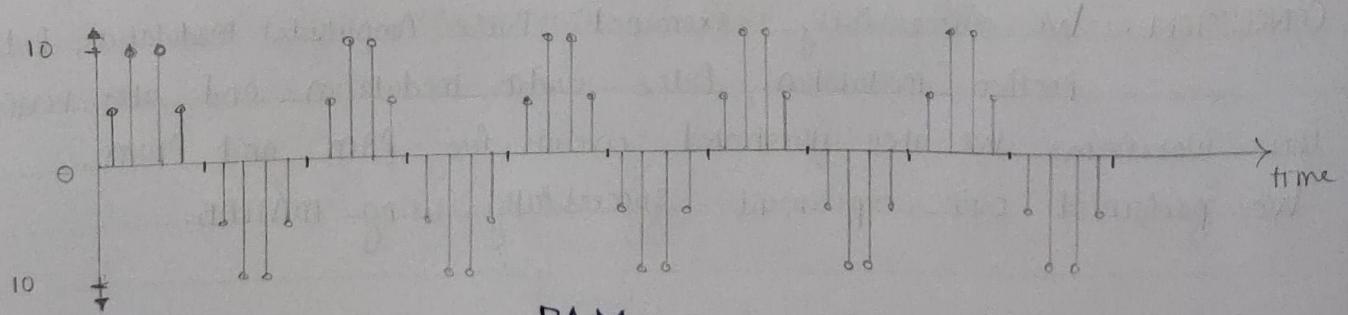
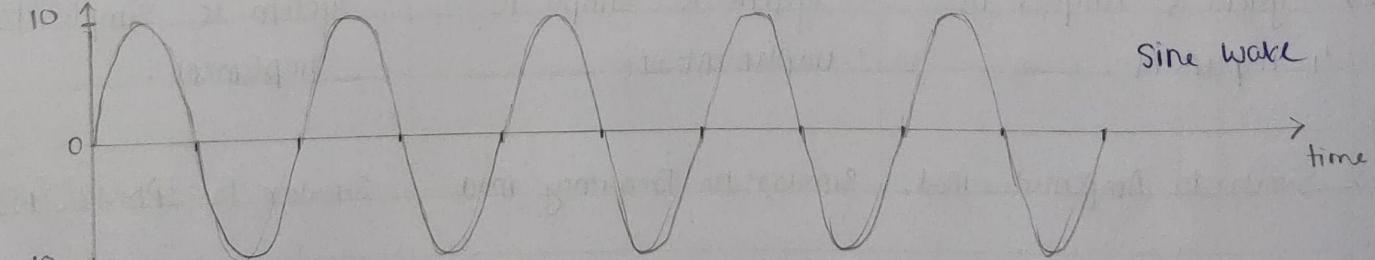
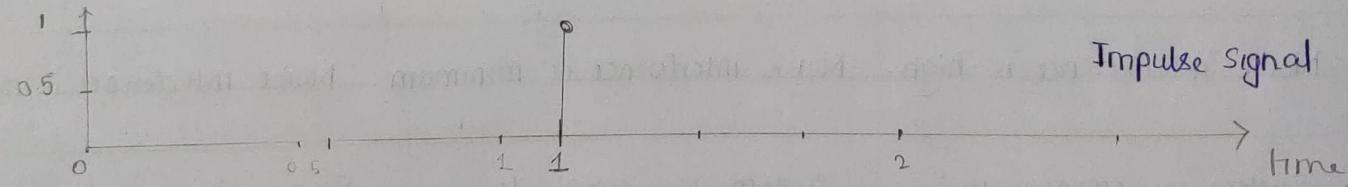
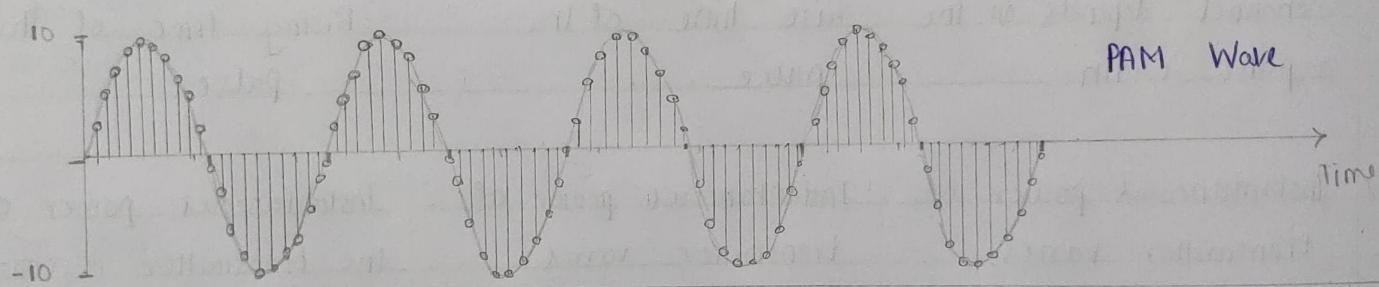
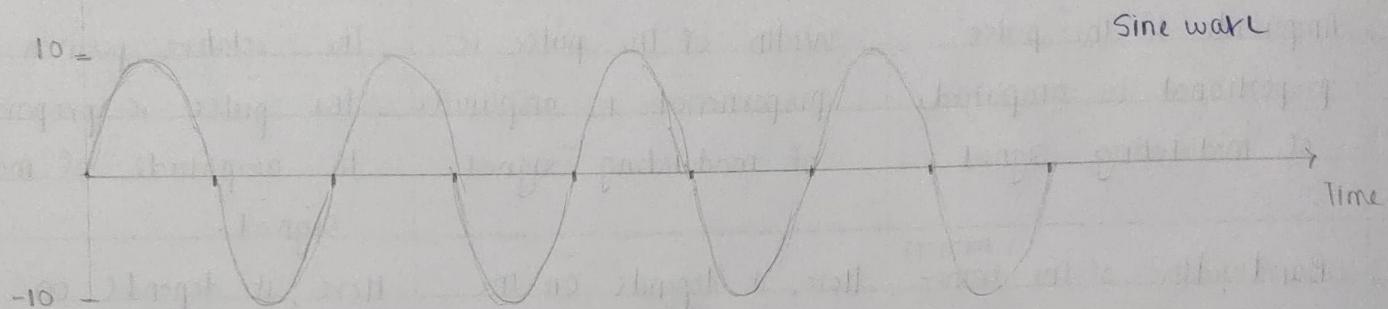
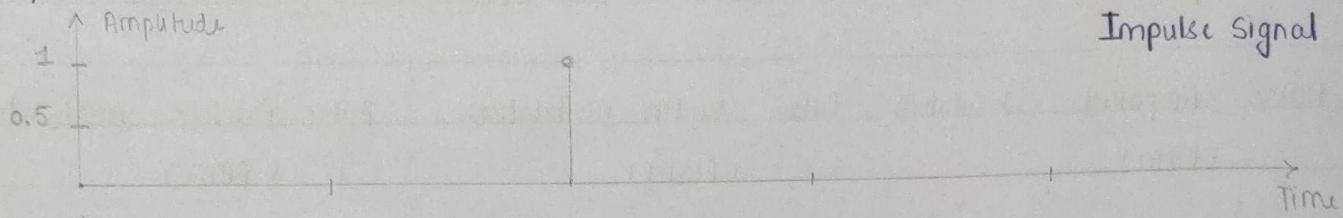
## MATLAB CODE :

```
% PAM using Ideal Sampling  
clc;  
close all;  
clear all;  
a = input('Enter the amplitude = ');  
f = input('Enter the frequency = ');  
t = 0 : 0.02 : 2;  
x1 = 1; % generation of impulse signal  
x2 = a * sin(2 * pi * f * t); % generation of sine wave  
y = x1 * x2; % modulation step  
subplot(3,1,1); % for impulse signal plot  
stem(x1);  
title('Impulse Signal');  
xlabel('Time');  
ylabel('Amplitude');  
subplot(3,1,2); % for sine wave plot  
plot(t, x2);  
title('Sine Wave');  
xlabel('Time');  
ylabel('Amplitude');  
subplot(3,1,3); % for PAM waveplot  
stem(t, y);  
title('PAM wave');  
xlabel('Time');  
ylabel('Amplitude');
```

# PAM with Ideal Sampling

⑧

$$1.7 \quad A = 1V \quad f = 2\text{Hz}$$



% PAM using Natural Sampling

clc ; clear all ; close all ;

fc = 100

fm = fc / 10

fs = 100 \* fc

t = 0 : 1/fs : 4/fm ;

Msg\_sgl = cos( 2\*pi \* fm \* t) ;

Carr\_sgl = 0.5 \* square (2\*pi\*fc\*t) + 0.5

Mod\_sgl = Msg\_sgl \* Carr\_sgl ;

tt = [] ;

for i=1 : length(Mod\_sgl) ;

if Mod\_sgl(i) == 0 ;

tt = [tt, Mod\_sgl(i)] ;

else

tt = [tt, Mod\_sgl(i) + 2] ;

end end

figure(1)

Message

Carrier

PAM Modulated

subplot(4,1,1);

subplot(4,1,2);

subplot(4,1,3);

plot(t, Msg\_sgl);

plot(t, Carr\_sgl);

plot(t, Mod\_sgl);

title('Message Signal');

title('Carrier Signal');

title('PAM Modulated signal')

xlabel('Time period');

xlabel('Time period');

xlabel('Time period')

ylabel('Amplitude');

ylabel('Amplitude');

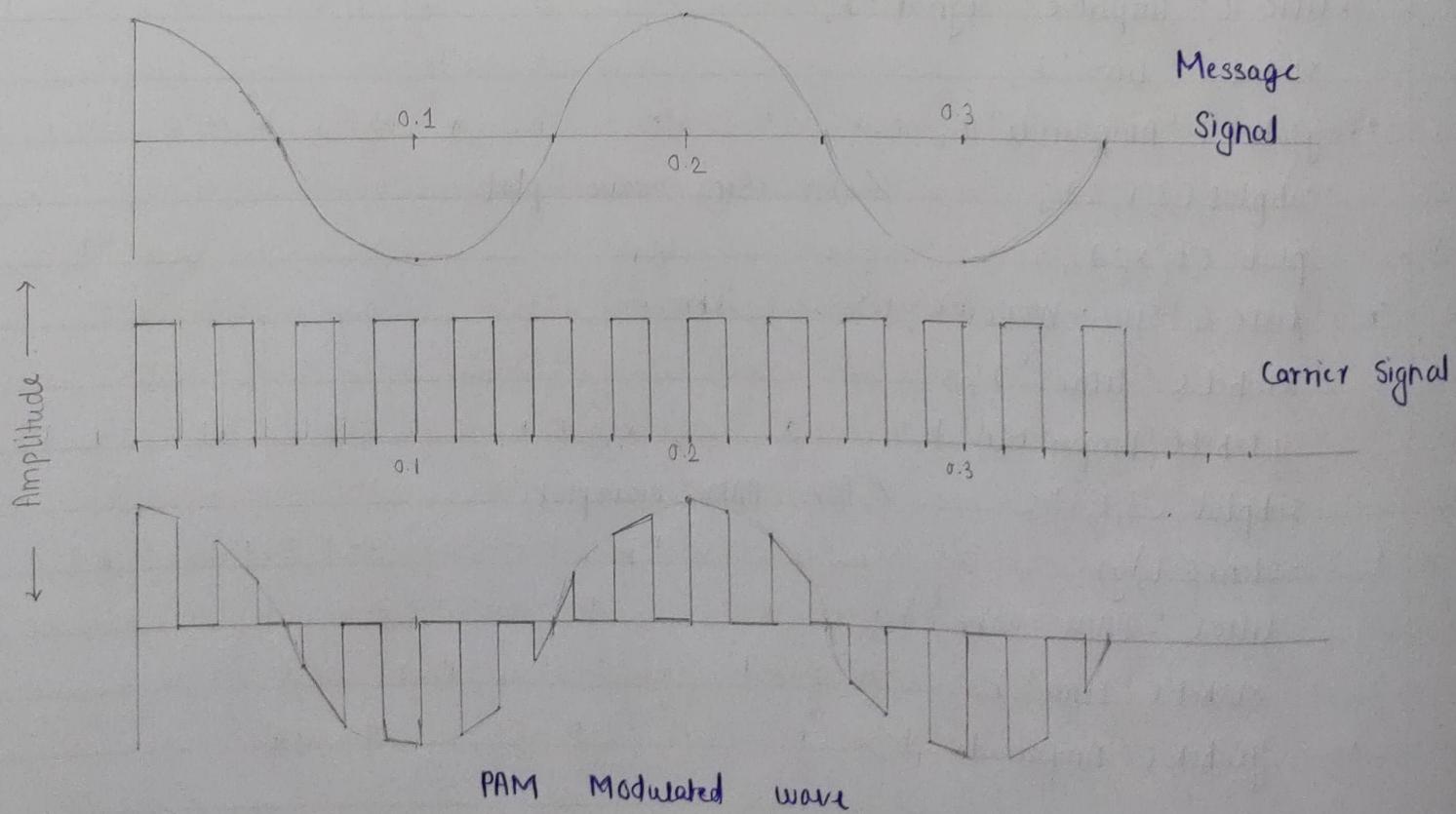
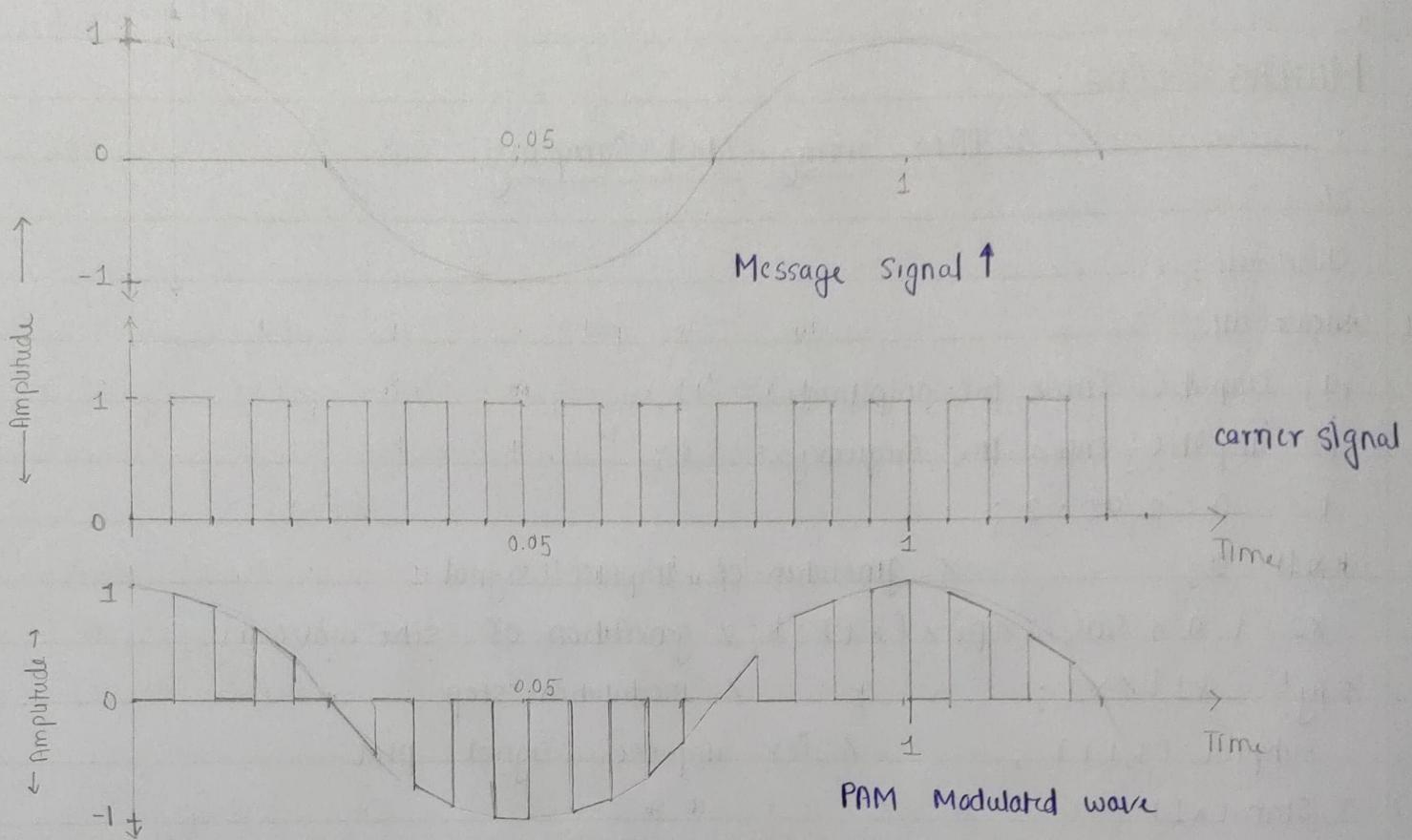
ylabel('Amplitude')

# PAM Using Square Wave

I)  $F_c = 100$     $F_m = 10$     $F_s = 10,000$

(Natural Sampling)

10



## % PWM Signal

clc;

close all;

clear all;

t = 0 : 0.0001 : 1;

s = sawtooth(2\*pi\*10\*t + pi);

m = 0.75 \* sin(2\*pi\*1\*t);

n = length(s)

for i=1:n

if ( m(i) >= s(i) )

pwm(i) = 1;

else if ( m(i) <= s(i) )

pwm(i) = 0;

end

end

plot(t, pwm, 'g', t, m, 'r', t, s, 'b');

ylabel('Amplitude');

axis([0 1 -1.5 1.5]);

xlabel('Time index');

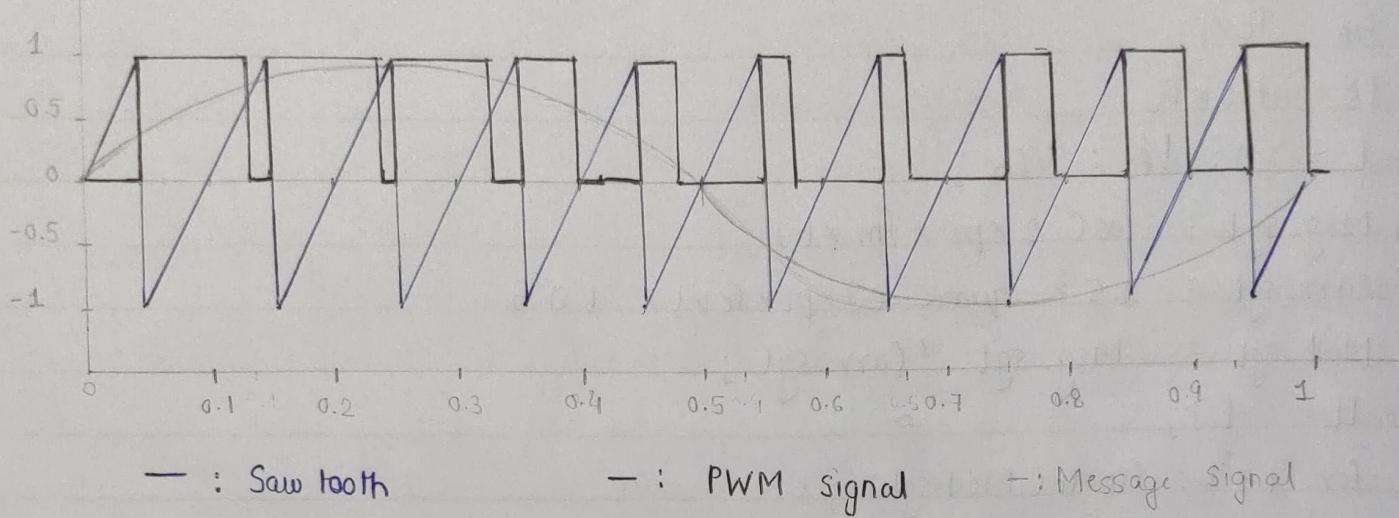
title('PWM Wave');

grid on;

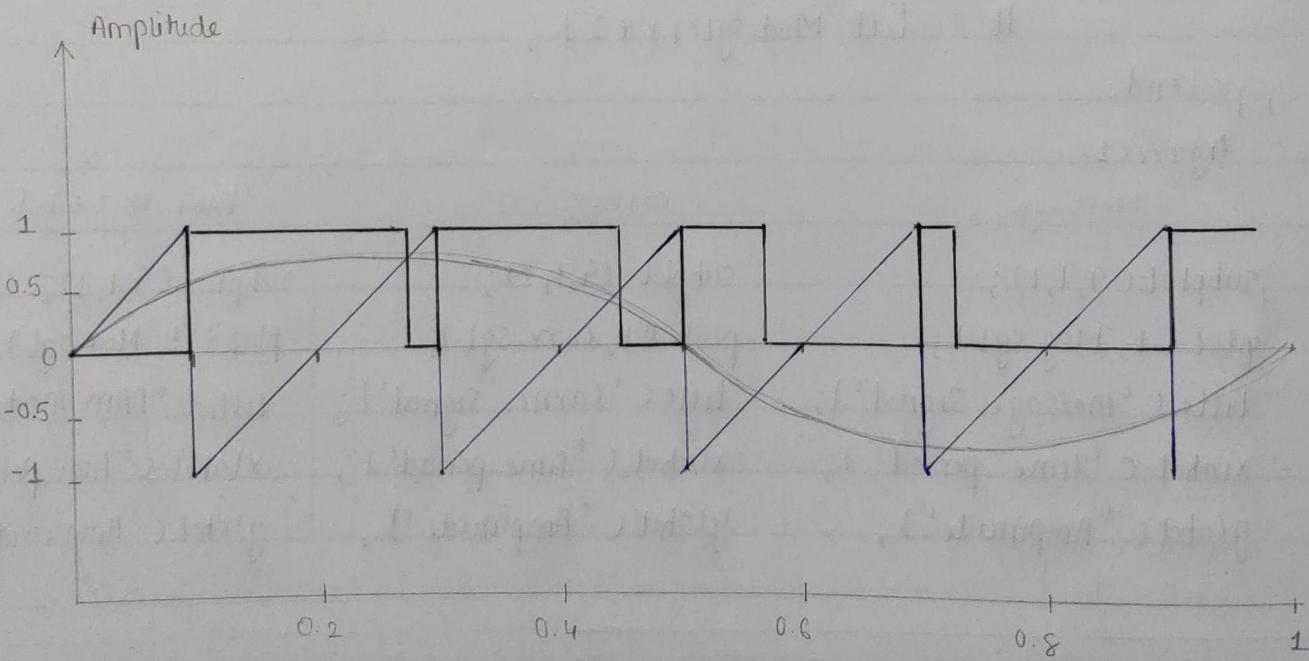
# PWM

12

$$1) \quad S = \text{sawtooth}(2\pi \times 10 \times t + \pi);$$



$$2) \quad S = \text{sawtooth}(2\pi \times 5 \times t + \pi);$$



— : saw tooth

- : PWM signal

- : Message signal

[019CS012]

% PPM Signal

clc;

clear all;

close all;

fc = 10;

fs = 100;

fm = 2;

t = 0: 1/fs : ((2/fm) - (1/fs));

X = 0.5 \* cos(2\*pi\*fm\*t) + 0.5

Y = modulate(X, fc, fs, 'ppm');

subplot(2, 2, 1);

plot(x);

title('msg signal')

subplot(2, 2, 2)

plot(Y);

axis([0 20 -0.2 1.2]);

title('PPM');

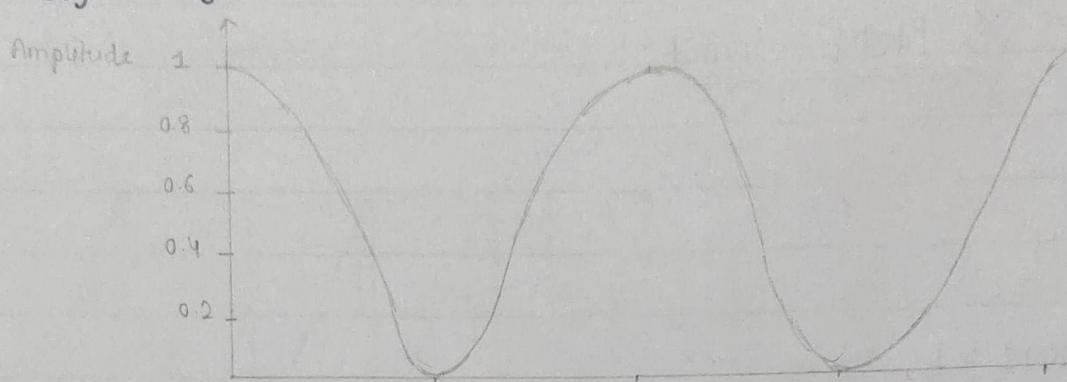
> CONCLUSION: We have successfully examined Pulse Amplitude Modulation  
 Pulse Position Modulation, Pulse width Modulation  
and also verified their waveforms using MATLAB.

### PPM Signal

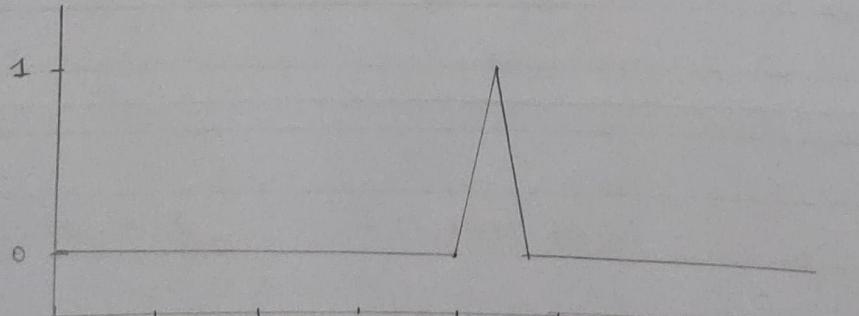
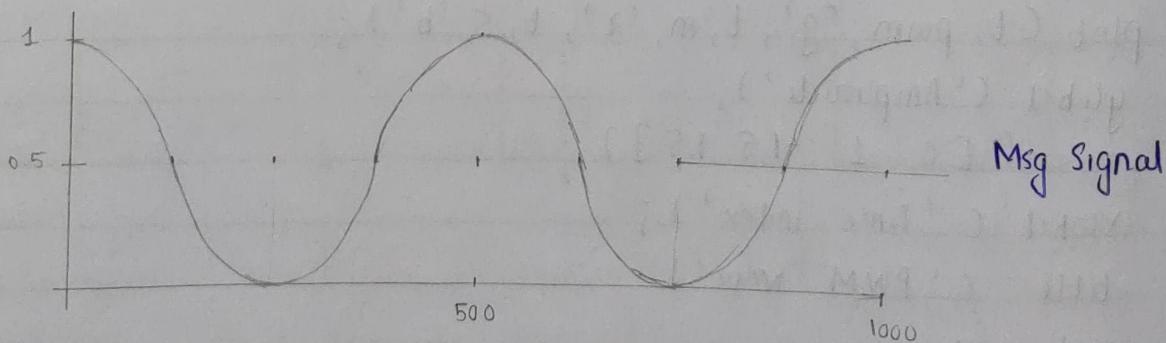
$$1.) \quad F_c = 10$$

$$F_s = 100$$

$$F_m = 2$$



$$2.) \quad F_c = 40 \quad F_m = 1000 \quad F_m = 2$$



**EXPERIMENT - 6**

[U19CS012]

**ASK, FSK and PSK**

**AIM :** To study Amplitude shift keying (A.S.K.), Frequency shift keying (F.S.K.) and phase shift keying (P.S.K) modulation Technique and verify waveforms.

**APPARATUS :** MATLAB

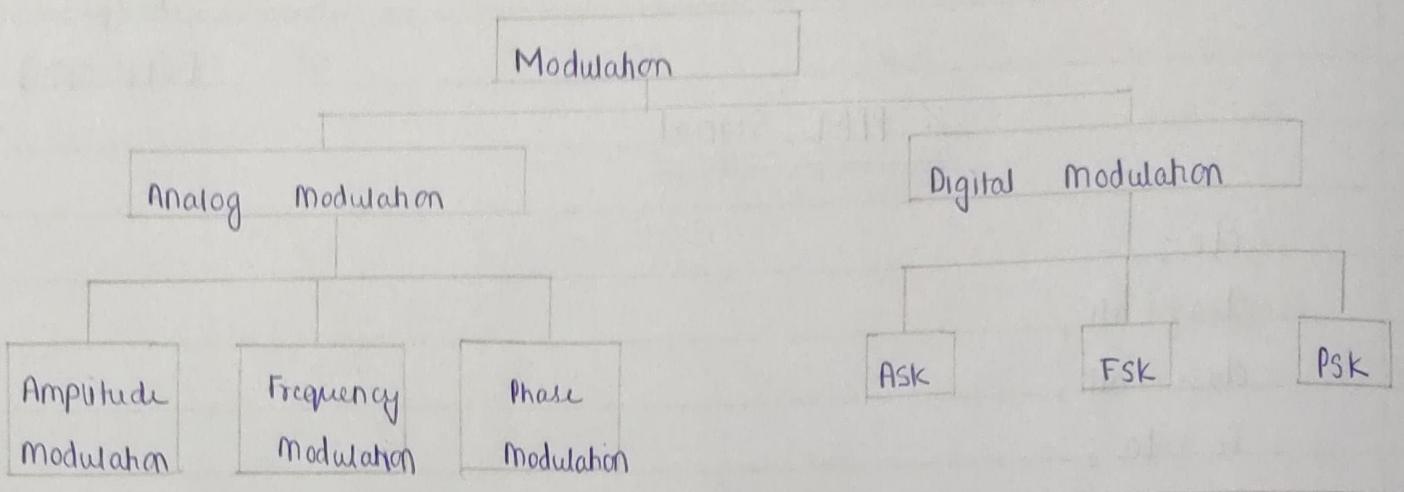
**THEORY :** 1. > Modulation : Modulation is a process, by which some characteristics of a carrier wave is varied in accordance with a modulating (message) signal.

Digital modulation : It is a special kind of modulation, where the message signal is digital in nature and the carrier wave is analog (sinusoidal) in nature.

The ASK, FSK and PSK are analogous to AM, FM and PM respectively. The difference is that in digital modulation techniques (ASK, FSK and PSK) the modulation signal is digital in nature, while in AM, FM and PM modulating signal is analog in nature.

**2. > ASK (Amplitude Shift keying)**

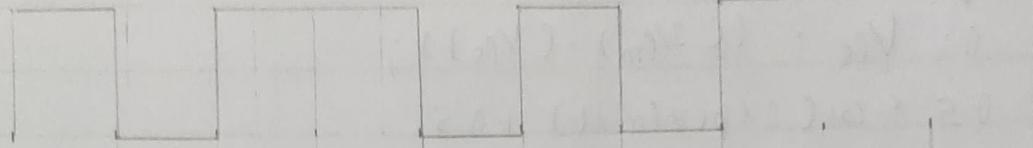
In ASK, the amplitude of the carrier wave is changed (switched) according to the digital input signal (modulating signal).



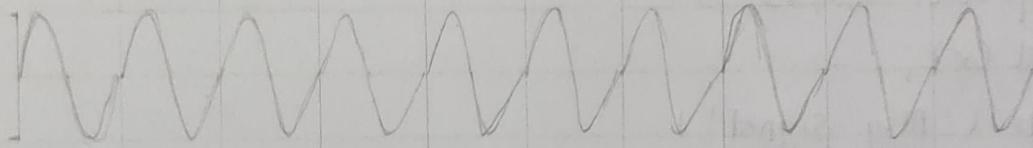
## ASK

ASK

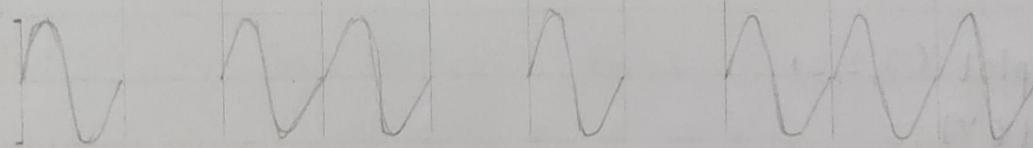
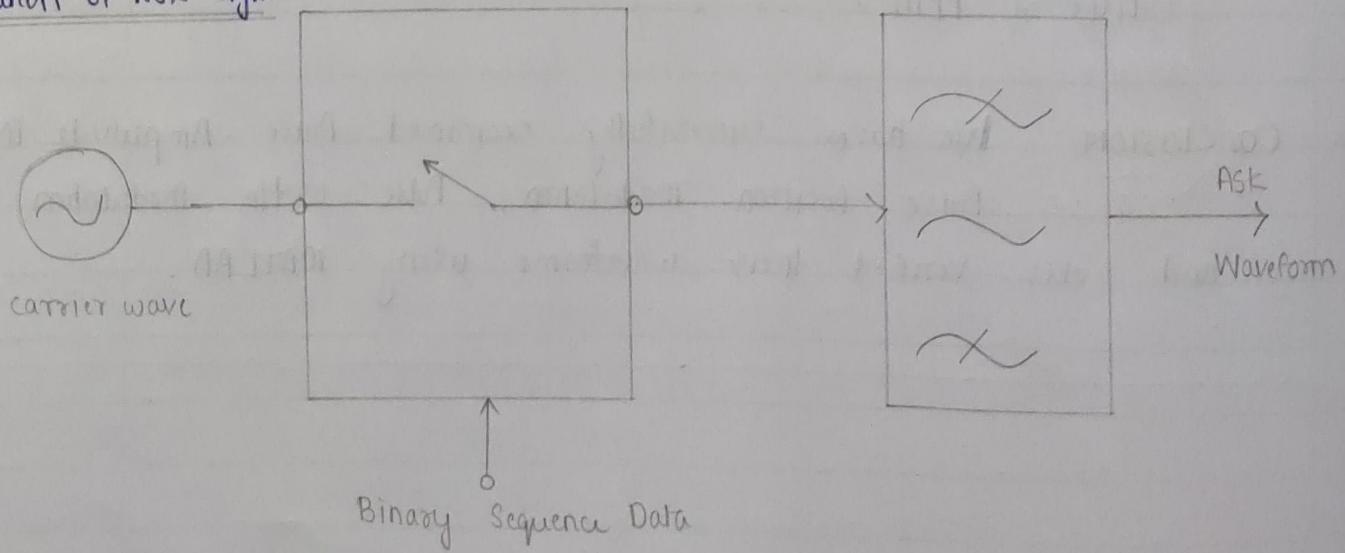
Binary Input



Carrier Signal



ASK

Generation of ASK signal :

Application of ASK : 1.) Wireless Base station

2.) Low Frequency RF Application

3.) Fastru Industrial Network Devias

3.) FSK (Frequency Shift Keying)

→ If the frequency of sinusoidal carrier wave is varied (switched) depending on the digital input signal, then it is known as the frequency shift keying.

→ Application of FSK :-

1. High Frequency Radio Transmission

4.) PSK (Phase Shift Keying)

In PSK, phase of the carrier wave (analog in nature) is switched as per the input digital signal.

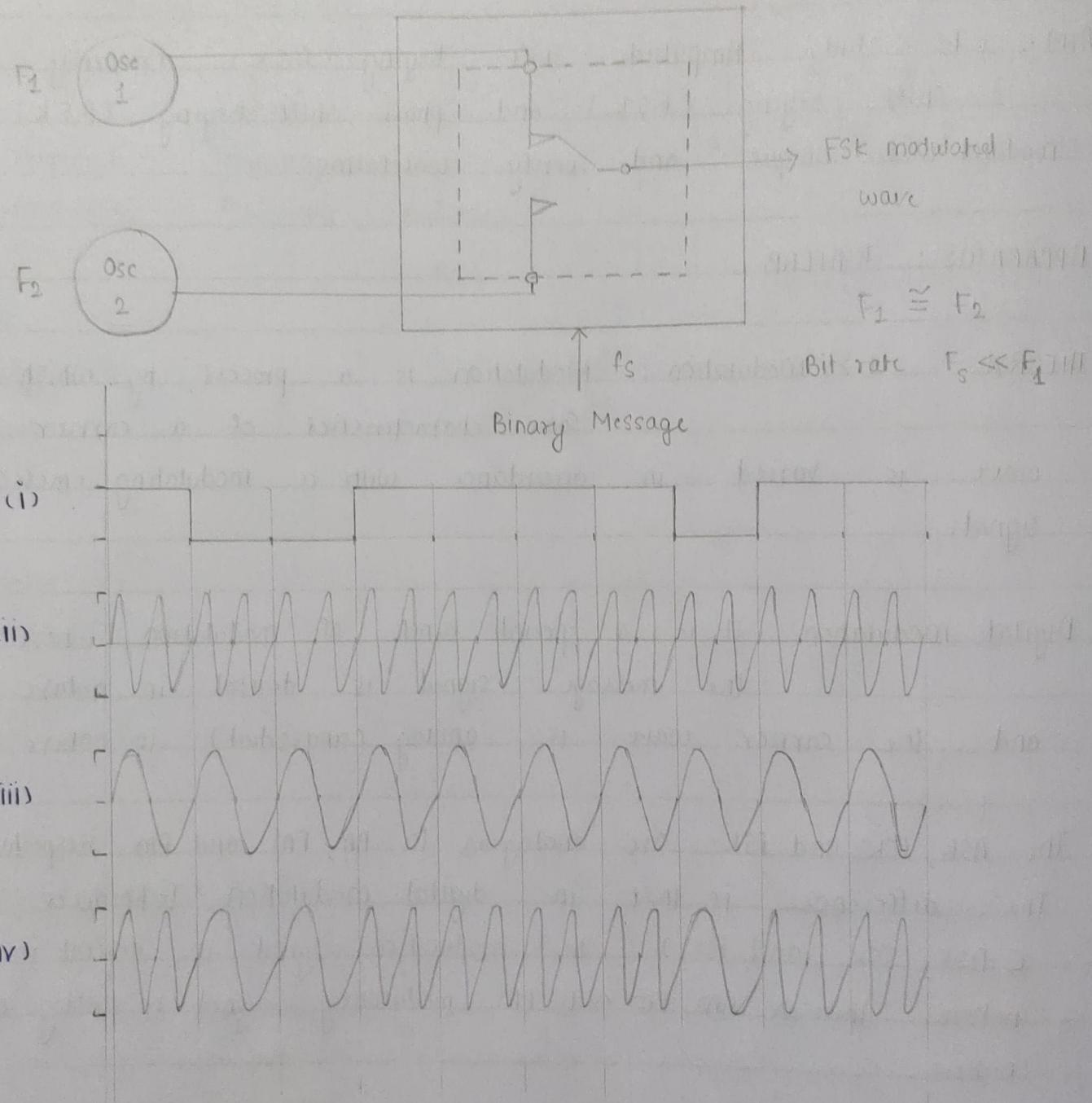
Application of PSK :

1. It is widely used for wireless LANs, RFID and Bluetooth communication.

(4)

FSK

## Generation of FSK



(i) Digital Bitstream

(ii) High frequency carrier wave

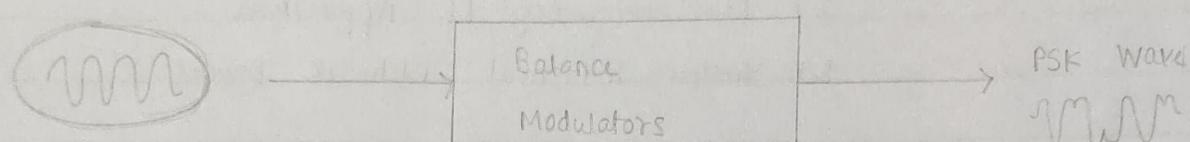
(iii) Low frequency carrier wave

(iv) FSK modulated wave

# PSK

(5)

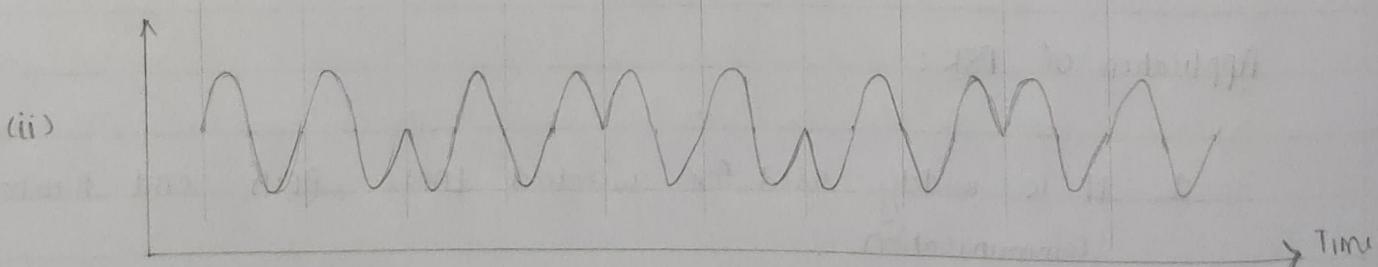
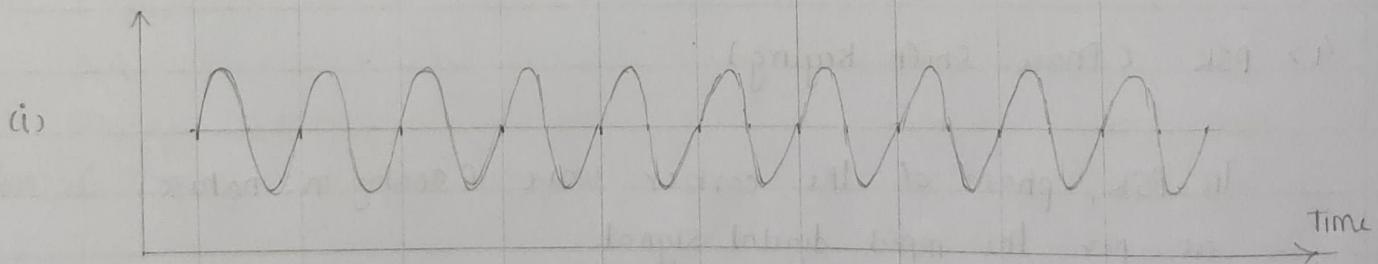
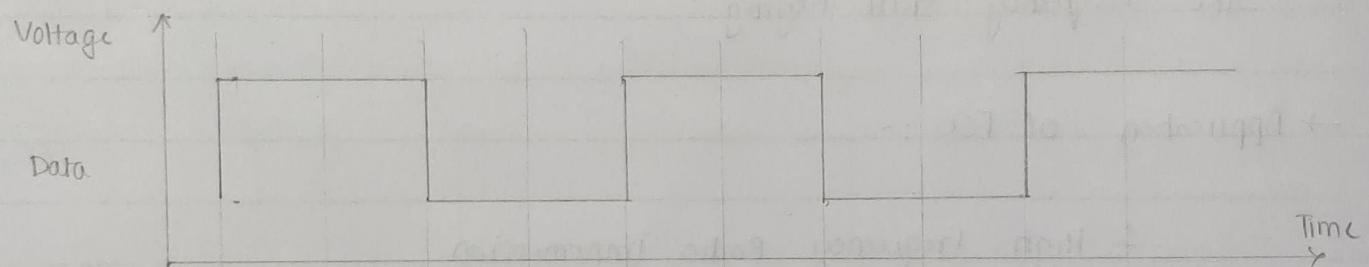
## Generation of PSK



Carrier Wave  
generator

Binary  
Sequence (Data)

PSK Wave



(i) Carrier Frequency Before Modulation

(ii) Carrier Frequency After Modulation

## &gt; MATLAB CODE :

% % ASK

```
clc; close all; clear all; % for deleting all variables from memory
fc = input('Enter the freq of Sine Wave carrier:');
fp = input('Enter the freq of Periodic Binary pulse (message):');
amp = input('Enter the amplitude (For carrier & Binary Pulse message):');

t = 0: 0.001:1; % for setting the sampling interval
c = amp. * sinc(2*pi*fc*t); % for generating carrier sine wave

subplot(3,1,1) % For Plotting Carrier wave
plot(t,c)
xlabel('Time')
ylabel('Amplitude')
title ('carrier wave')

m = amp/2 . * square(2*pi*fp*t) + (amp/2); % Square wave msg

subplot(3,1,2) % Plotting square Binary Pulse
plot(t,m)
xlabel('Time')
ylabel('Amplitude')
title ('Binary Message Pulse')

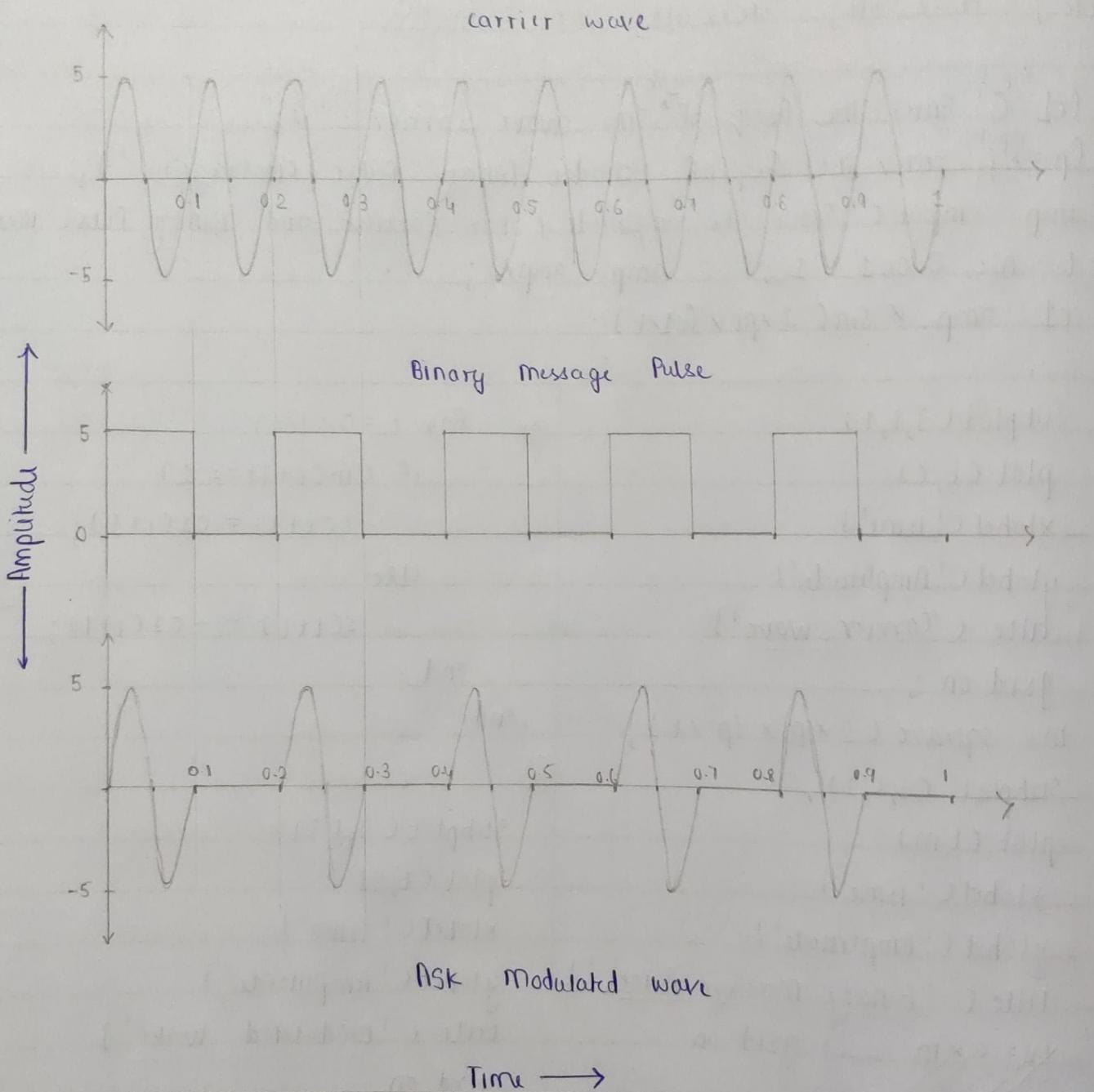
w = c*m % The Shift Keyed wave

subplot(3,1,3) % for plotting ASK wave
plot(t,w)
xlabel('Time')
ylabel('Amplitude')
title ('Amplitude Shift Keyed Signal')
```

(A) **ASK :**

(7)

3.)  $F_c = 10 \text{ Hz}$      $F_p = 5 \text{ Hz}$     Amp = 5



% % FSK

clc; close all; clear all;

fc1 = input('Enter the freq of 1st sine wave carrier: ');

fc2 = input('Enter the freq of 2nd sine wave carrier: ');

fp = input('Enter the freq of Periodic Binary pulse (message): ');

amp = amp/2;

t = 0: 0.001 : 1;

c1 = amp. \* sin ( 2\*pi\* fc1\*t );

c2 = amp. \* sin ( 2\*pi\* fc2\*t );

① subplot( 4,1,1 );

plot( t,c1 )

xlabel ('Time')

ylabel ('Amplitude')

title ('carrier 1 wave')

② subplot( 4,1,2 );

plot( t,c2 )

xlabel ('Time')

ylabel ('Amplitude')

title ('carrier 2 wave')

③ m = amp. \* square ( 2\*pi\*fp\*t ) + amp; % square wave form

subplot( 4,1,3 )

plot( t,m )

xlabel ('Time')

ylabel ('Amplitude')

title ('Binary message pulses')

④ for i=0:1000

if m(i+1) == 0

mm(i+1)= c2(i+1);

else

mm(i+1)=c1(i+1);

end

end

⑤ subplot( 4,1,4 )

plot( t,mm )

xlabel ('Time')

ylabel ('Amplitude')

title ('Modulated Wave')

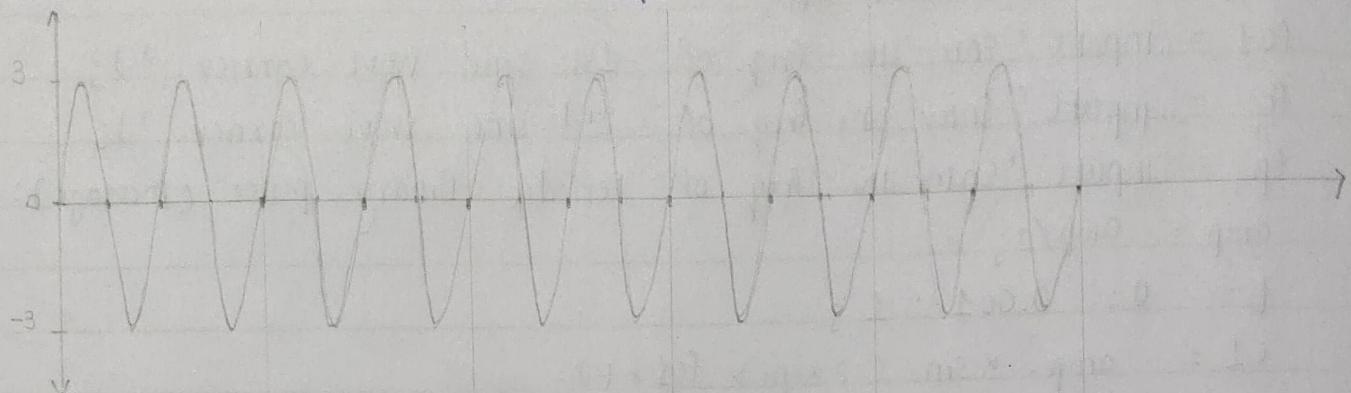
(B)

FSK :

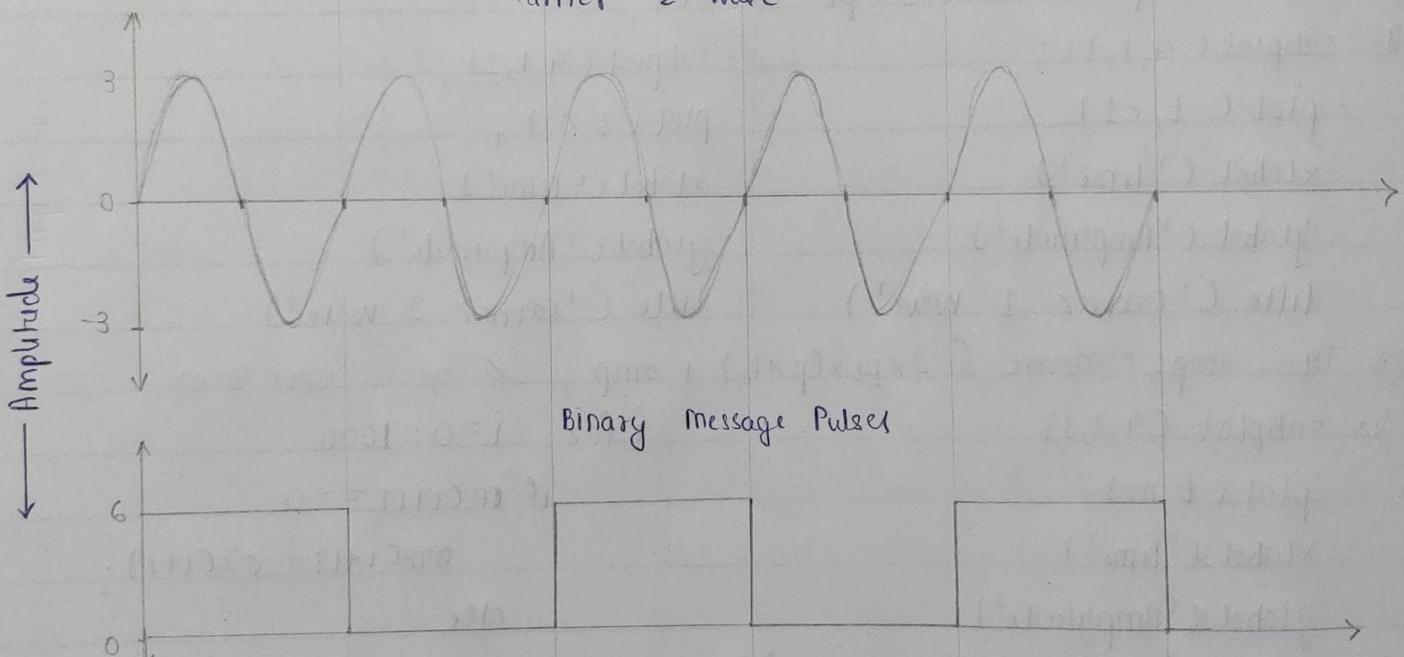
$$2. \gamma \quad F_{C1} = 30 \quad F_{C2} = 10 \quad F_p = 5 \quad \text{amp} = 6$$

(9)

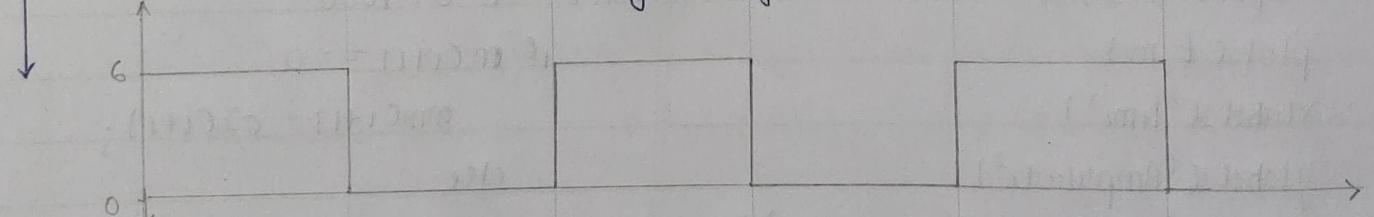
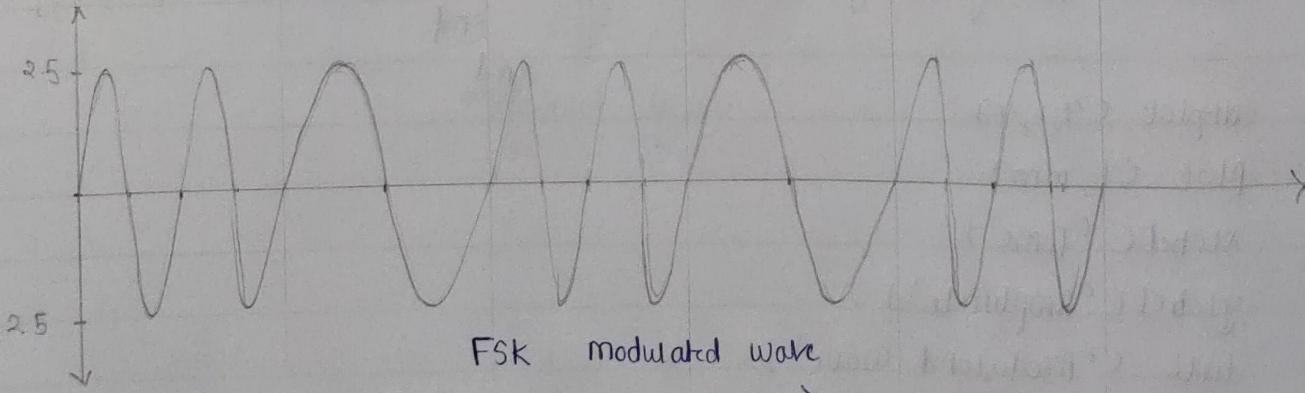
Carrier 1 wave



Carrier 2 wave



Binary message Pulse

FSK modulated wave  
Time

% % PSK

clc; close all; clear all;

fc = <sup>input</sup>('Enter the freq. of <sup>1st</sup> Sine wave carrier:');fp = <sup>input</sup>('Enter the freq. of Periodic Binary Pulse (message):');

amp = input('Enter the amplitude ( For Carrier and Binary Pulse Message);

t = 0 : 0.001 : 1; amp = amp/2;

c1 = amp \* sin(2\*pi\*fc\*t);

(1) subplot(3,1,1)

plot(t,c1)

xlabel('Time')

ylabel('Amplitude')

title('Carrier wave')

grid on;

m = square(2\*pi\*fp\*t);

(2) subplot(3,1,2),

plot(t,m)

xlabel('Time')

ylabel('Amplitude')

title('Binary Message Pulse')

w = c1\*m grid on

subplot(3,1,3)

(3) for i=0:1000

if cm(i+1) == 1

sc(i+1) = c1(i+1);

else

sc(i+1) = -c1(i+1);

end

end

(4)

subplot(3,1,3)

plot(t,s)

xlabel('Time')

ylabel('Amplitude')

title('modulated wave')

grid on

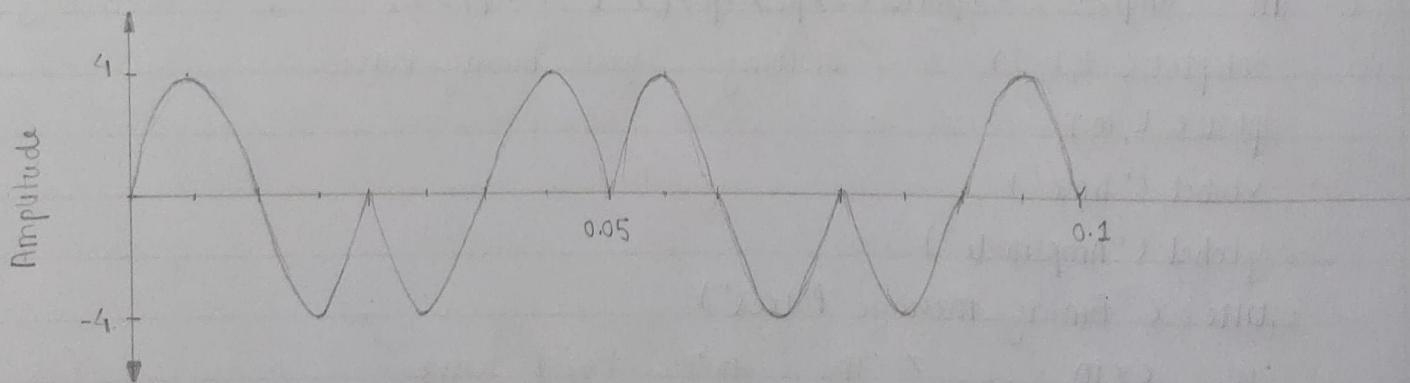
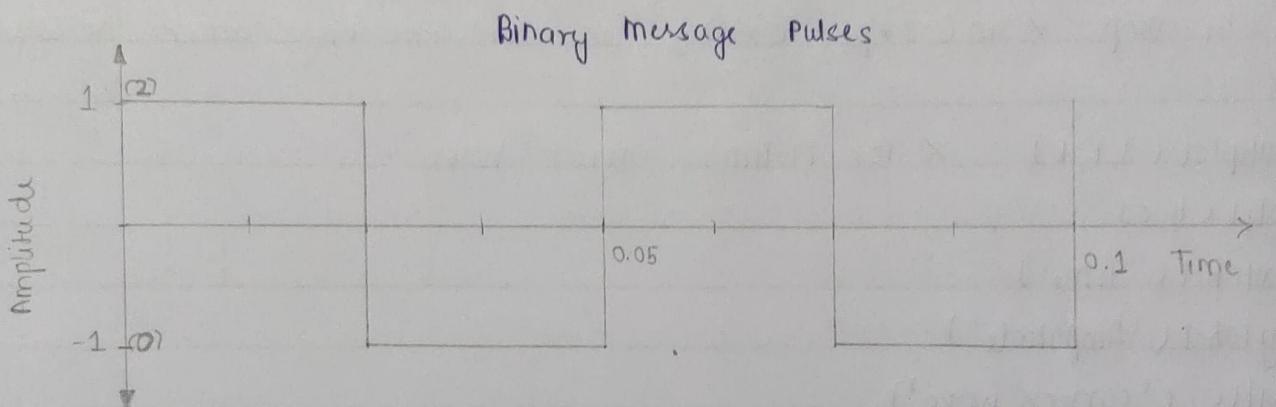
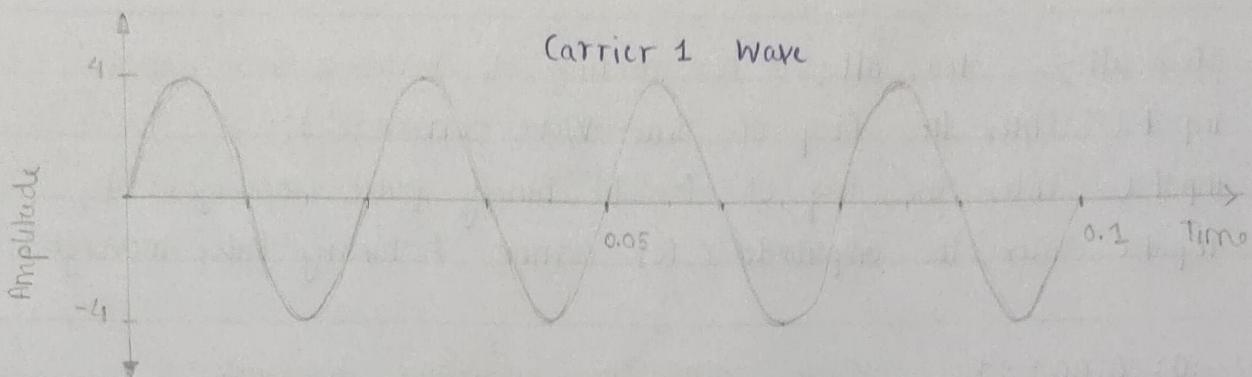
# Waveforms using MATLAB

(A) (C)

(11)

PSK :

1.)  $F_{c1} = 40\text{Hz}$     $F_p = 20\text{Hz}$    Amp = 8V



Modulated Wave

[U19CS012]

### CONCLUSION :

- 1) We have successfully studied ASK, PSK and FSK modulation technique and verified their waveforms using MATLAB. We also observed the schematic diagrams for ASK, FSK & PSK.

## EXPERIMENT 7 :

[U19ACSO12]

## EFFECT OF AWGN ON AM AND FM

AWGN : Additive white Gaussian noise

AIM: To study the transmission of Amplitude modulated (AM) and Frequency modulated (FM) signal under the Additive Gaussian Noise channel.

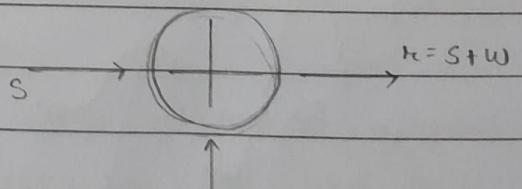
APPARATUS: MATLAB

THEORY: 1. > Additive White Gaussian Noise (AWGN)

A Basic Noise model used to mimic the effect of many random processes that occur in nature. Channel produces Additive white Gaussian Noise. (AWGN)

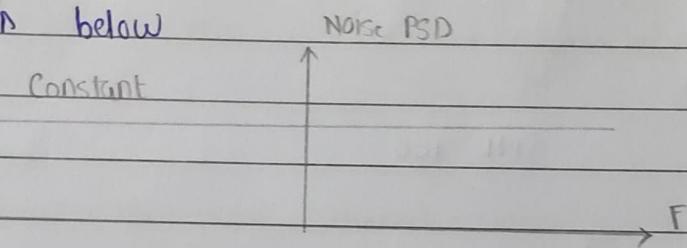
① Additive: The received signal equals the transmit signal plus some noise, where the noise is statistically independent of the signal.

$$r(t) = s(t) + w(t)$$



② White: It refers that the noise has the same power distribution at every frequency OR it has uniform power across the frequency band for the information system.

- It is an analogy to the color white which has uniform emissions at all frequencies in the visible spectrum. If we focussed a beam of light for each color on the visible spectrum onto a single spot, that combination would result in a beam of white light.
- As a consequence, the Power spectral density (PSD) of white noise is constant for all frequencies ranging from  $-\infty$  to  $+\infty$  as shown below



③ Gaussian - Gaussian distribution, or a normal distribution, has an average of zero in the time domain, and is represented as a bell shaped curve.

- The probability distribution of the noise samples is Gaussian with a zero mean.
- The values close to zero have a higher chance of occurrence while the values far away from zero are less likely to appear.
- In reality, the ideal flat spectrum from  $-\infty$  to  $+\infty$  is true for frequencies of interest in wireless communication (few kHz - hundred GHz) but not for higher frequencies.

## 2.7 Signal to Noise Ratio

- The SNR or S/N is a measure used in science and engineering that compares the level of a desired signal to the level of background noise.
- It is defined as the ratio of signal power to the noise power, often expressed in decibels. A ratio higher than 1:1 (greater than 0 dB) indicates more signal than noise.
- SNR, bandwidth and channel capacity of a communication channel are connected by the Shannon-Hartley theorem.

$$\text{SNR}_{\text{dB}} = 10 \log_{10} \left( \frac{P_{\text{signal}}}{P_{\text{noise}}} \right)$$

### Shannon-Hartley Theorem

It states that the channel capacity (bits per second) or information rate of data that can be communicated at low error data using an average received signal power through communication channel subject to additive white Gaussian noise (AWGN) of power.

$$C = B \log_2 \left( 1 + \frac{S}{N} \right), \quad B = \text{Bandwidth of channel in Hz}$$

- It is related to signal to noise (SNR) or carrier to noise (CNR) [linear power ratio]

- 5 dB - 10 dB  $\Rightarrow$  It is below the minimum level to establish a connection due to the noise level being nearly indistinguishable from the desired signal (useful information)
- 25 dB - 40 dB = deemed to be good.
- 41 dB or higher = considered to be excellent

### 3.) Mathematics of AM

- Let modulating signal be  $e_m = E_m \sin(\omega_m t)$

carrier signal be  $e_c = E_c \sin(\omega_c t)$

$$\begin{aligned} \therefore E_{Am} &= E_c + e_m \\ &= E_c + E_m \sin(\omega_m t) \end{aligned}$$

The instantaneous value of the amplitude modulated wave can be given as

$$\begin{aligned} e_{Am} &= E_{Am} \sin(\theta) \\ &= E_{Am} \sin(\omega_c t) \end{aligned}$$

$$e_{Am} = (E_c + E_m \sin(\omega_m t)) \sin(\omega_c t)$$

This is an equation of AM wave.

### 4.) Mathematics of FM

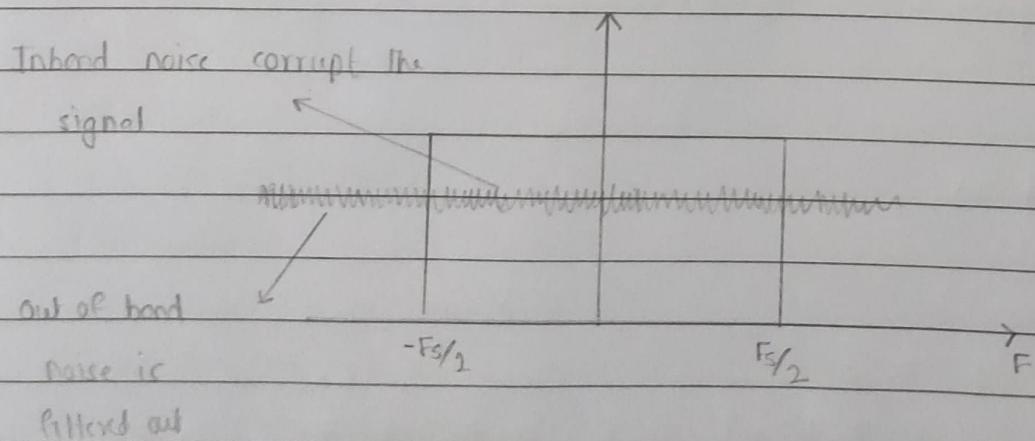
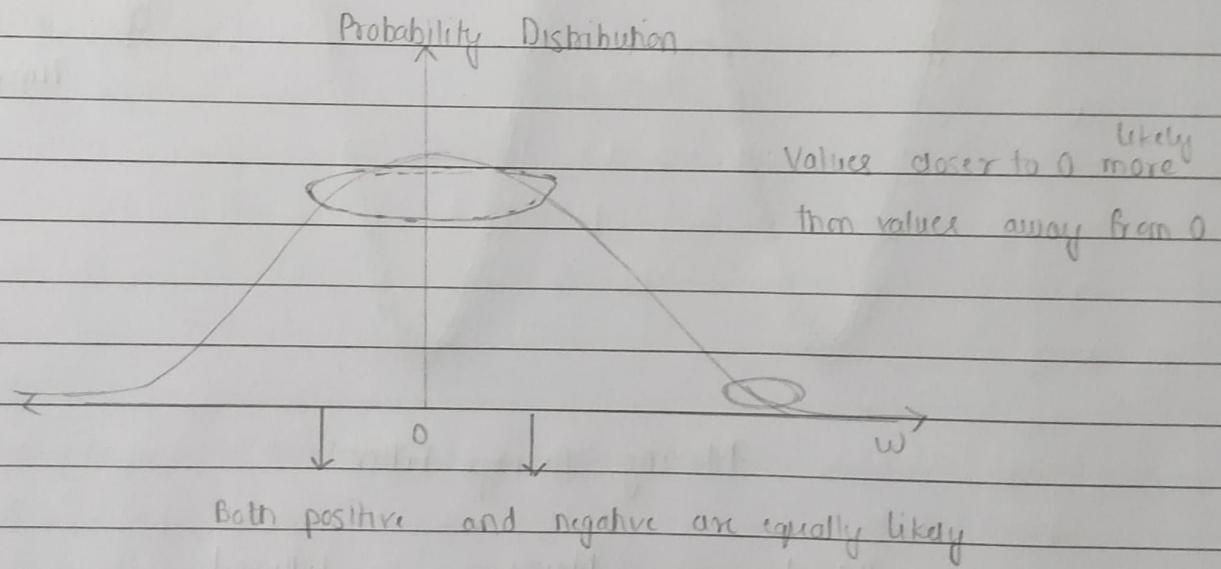
$$s(t) = E_s \sin(\omega_c t + m_f \sin(\omega_m t))$$

This is the expression for FM wave,  $m_f$  = modulation index

$$m_F = \frac{\text{Frequency deviation}}{\text{Modulating Frequency}} = \frac{\Delta f}{f_m}$$

- Frequency deviation  $\Delta f$  represents the maximum departure of the instantaneous frequency  $F_i(t)$  of the FM wave from the carrier frequency  $F_c$ .

$\Rightarrow$  Gaussian



## &gt; MATLAB CODE :

AWGN in different function

```
clc;
clear all;
t = 0 : 0.1 : 10;
x = sawtooth(t);
y = awgn(x, 10, 'measured');
plot(t, [x, y]);
legend('original signal', 'signal with AWGN');
```

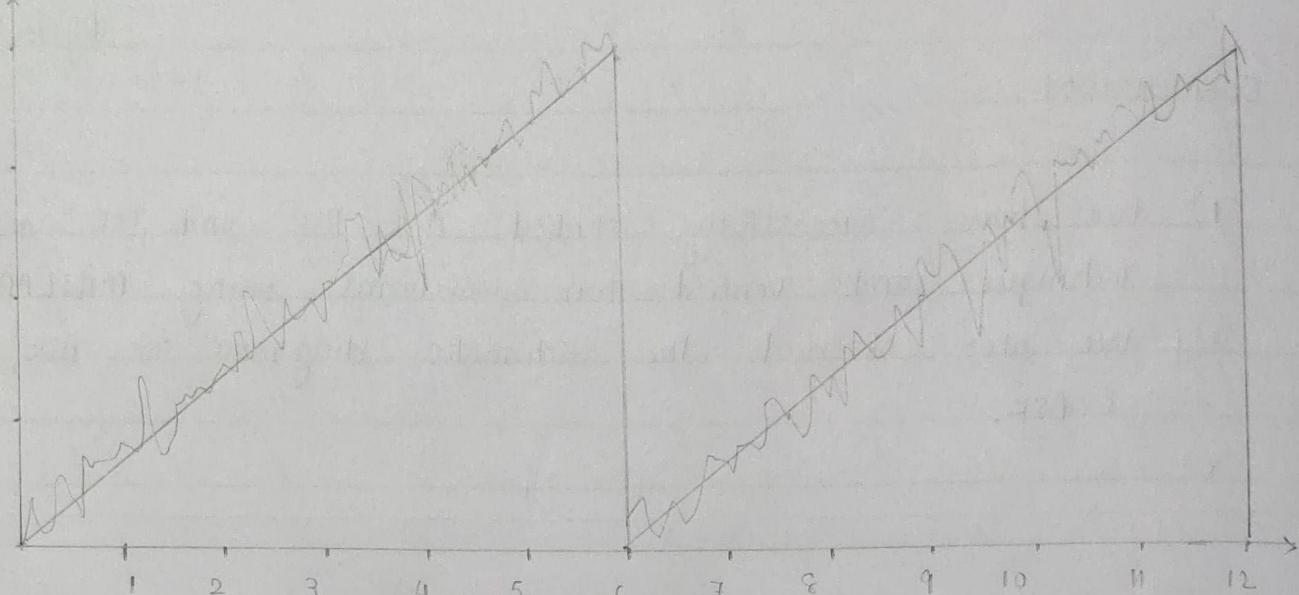
```
clc;
clear all;
t = (0 : 0.1 : 10);
x = sin(t);
y = awgn(x, 10, 'measured');
plot(t, [x, y]);
legend('original signal', 'signal with AWGN');
```

```
clc;
clear all;
t = (0 : 0.1 : 10);
x = cos(t);
y = awgn(x, 10, 'measured');
plot(t, [x, y]);
legend('original signal', 'signal with AWGN');
```

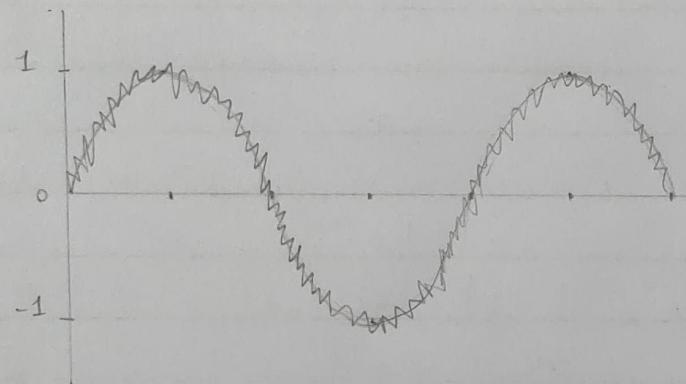
④

## AWGN Effect on Different functions

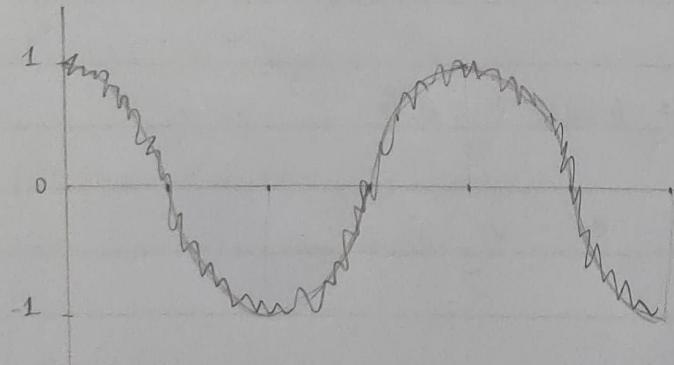
1) Sawtooth



2) Sine



3) cosine



AWGN in AM

dc;

clear all;

t = 0 : 0.001 : 1;

Vm = 5;

Vc = 10;

fm = 2;

fc = 25;

m = Vm \* sin(2 \* pi \* fm \* t);

c = Vc \* sin(2 \* pi \* fc \* t);

amp = Vc + Vm \* sin(2 \* pi \* fm \* t);

am = amp. \* sin(2 \* pi \* fe \* t);

y = awgn(am, 10, 'measured');

(1)

subplot(4,1,1);  
plot(t,m);  
xlabel('Time');  
ylabel('amplitude')

(2)

subplot(4,1,2);  
plot(t,c);  
xlabel('Time');  
ylabel('amplitude');

(3)

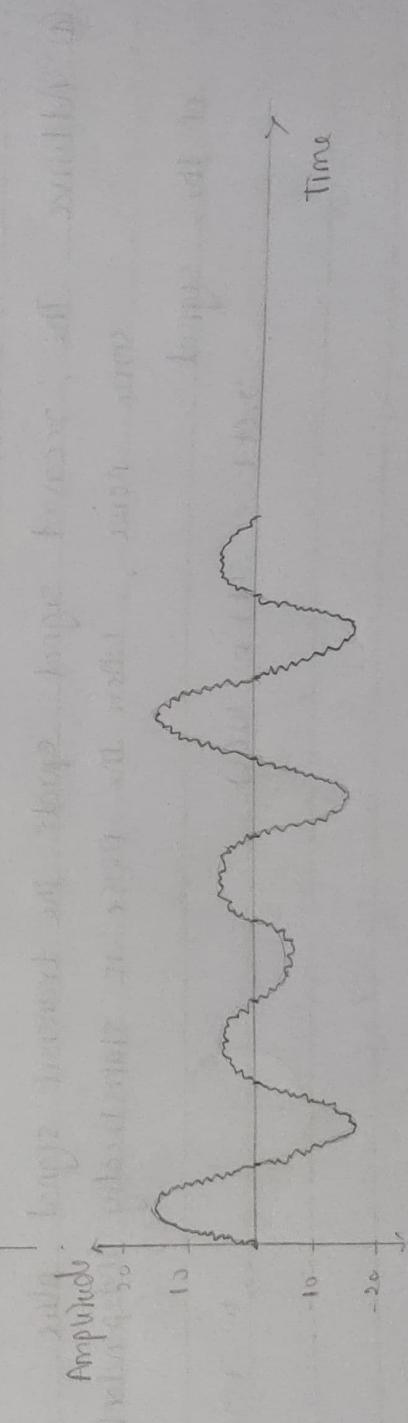
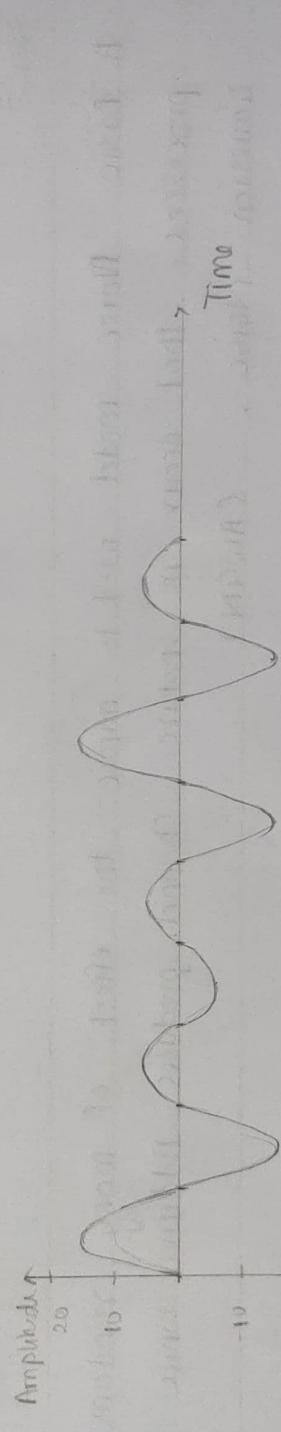
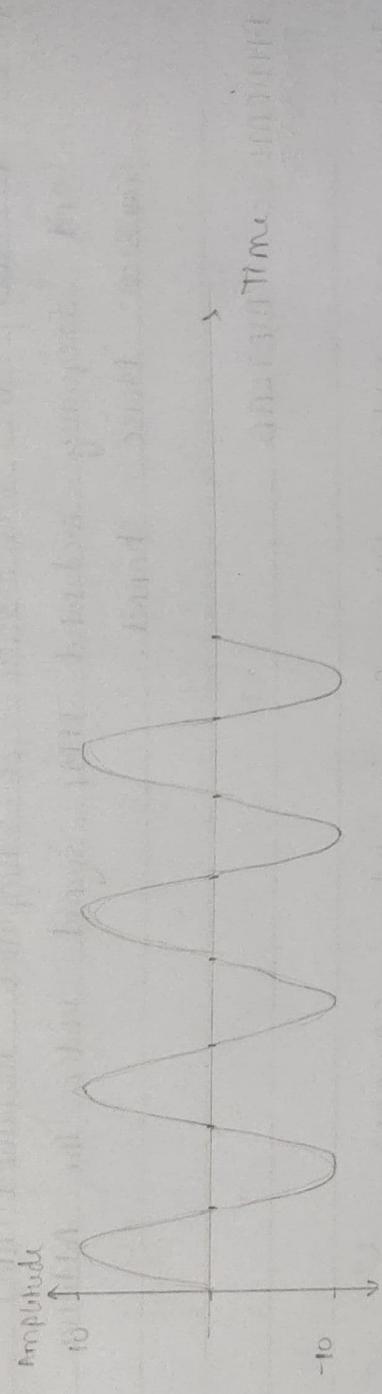
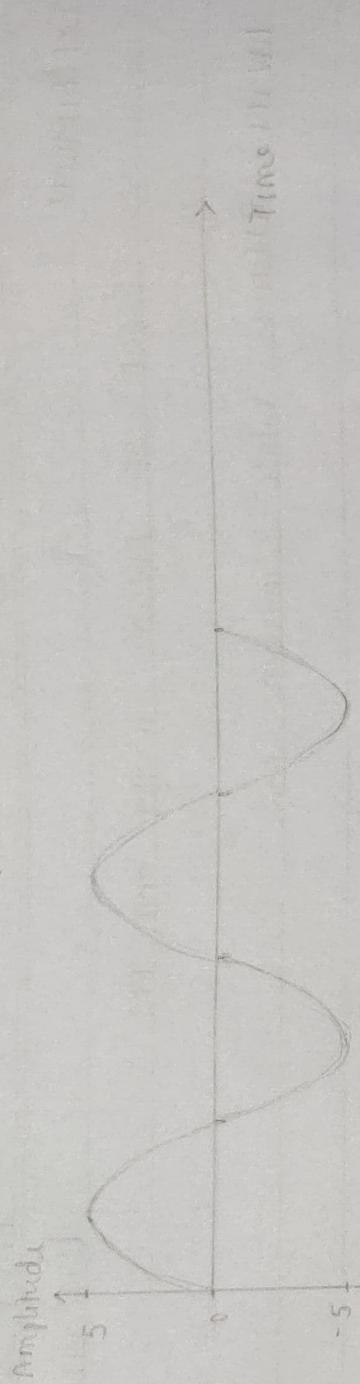
subplot(4,1,3);  
plot(t, am);  
xlabel('Time');  
ylabel('amplitude');

(4)

subplot(4,4,4);  
plot(t,y);  
xlabel('Time');  
ylabel('amplitude');  
title('amplitude modulated signal with AWGN');

## Am signal under AWGN

⑨



## AWGN in different SNR

```
clc; clear all;
```

```
t = 0: 0.001: 1;
```

```
Vm = 5; fm = 2;
```

```
Vc = 10; fc = 25;
```

```
m = Vm * sin( 2*pi*(m*t) );
```

```
c = Vc * sin( 2*pi*(fc*t) );
```

```
amp = Vc + Vm * sin( 2*pi*(fm*t) );
```

```
am = amp. * sin( 2*pi*(fc*t) );
```

```
y1 = awgn(c, 10, 'measured');
```

```
y2 = awgn(c, 100, 'measured');
```

```
y3 = awgn(c, 1000, 'measured');
```

①

```
subplot(4,1,1);
```

```
plot(t, am)
```

```
xlabel('time')
```

```
ylabel('amplitude')
```

```
title('amplitude modulated signal');
```

②

```
subplot(4,1,2);
```

```
plot(t, y1);
```

```
xlabel('time')
```

```
ylabel('amplitude')
```

```
title('AM signal with AWGN [SNR 10]');
```

③

```
subplot(4,1,3);
```

```
plot(t, y2);
```

```
xlabel('time')
```

```
ylabel('amplitude')
```

```
title('AM signal with AWGN [SNR 100]');
```

④

```
subplot(4,1,4);
```

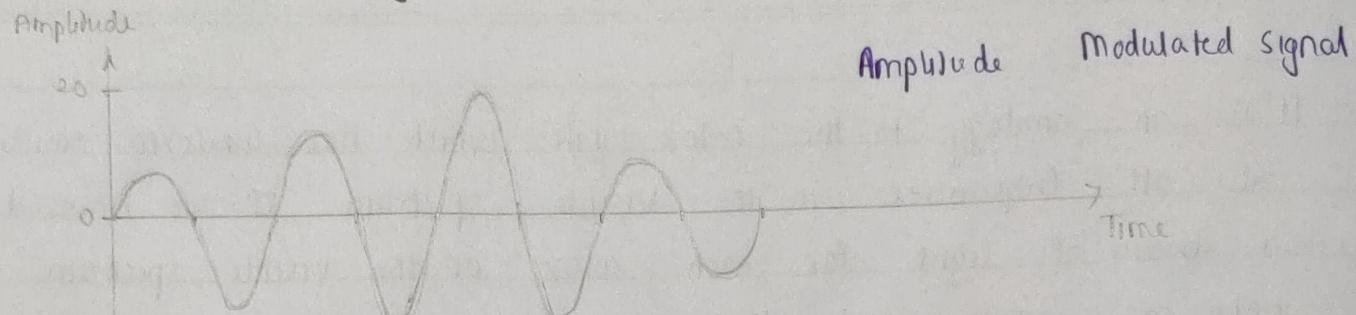
```
plot(t, y3);
```

```
xlabel('time')
```

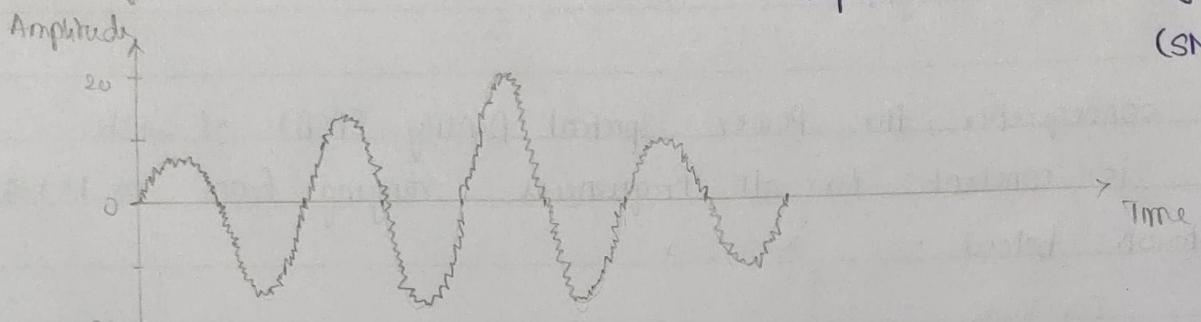
```
ylabel('amplitude')
```

```
title('AM signal with AWGN  
[SNR 1000]');
```

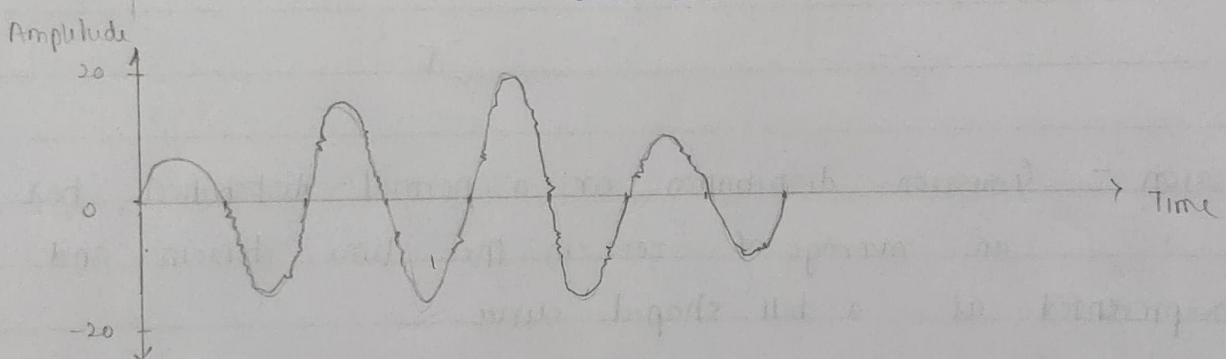
## AM Signal with different SNR values



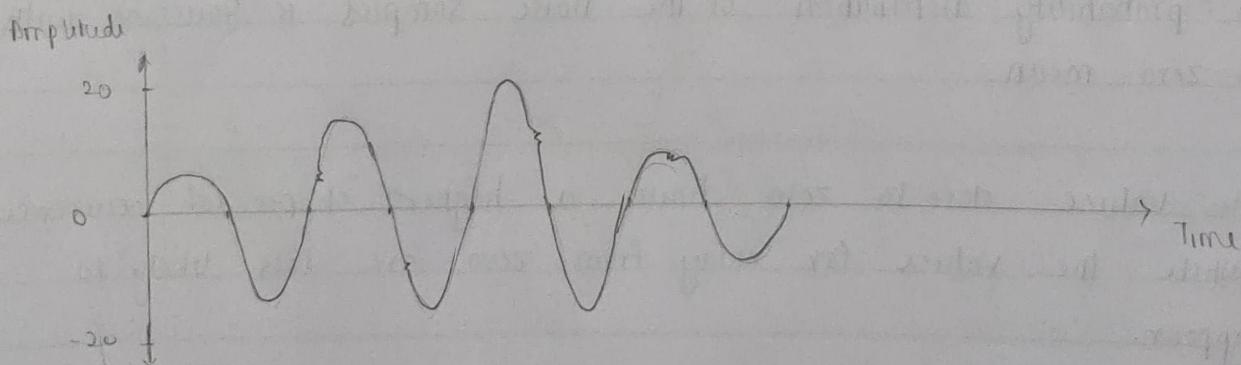
Amplitude Modulated Signal with AWGN  
(SNR = 10)



SNR = 100



SNR = 1000



## AWGN in FM

```

clc;
clear all;
t = 0 : 0.001 : 1;
Vm = 5;
Vc = 5;
fm = 2;
fc = 25;
fd = 5;
msg = Vm * sin(2 * pi * fm * t);
c = Vc * sin(2 * pi * fc * t);
y = Vc * sin(2 * pi * fc * t + fd * cos(2 * pi * fm * t));
z = awgn(y, 5, 'measured');

```

①

```

subplot(4,1,1);
plot(t, msg);
xlabel('time');
ylabel('Amplitude');
title('message signal');

```

②

```

subplot(4,1,2);
plot(t, c);
xlabel('time');
ylabel('amplitude');
title('carrier signal');

```

③

```

subplot(4,1,3);
plot(t, y);
xlabel('time');
ylabel('Amplitude');
title('Frequency modulated signal');

```

④

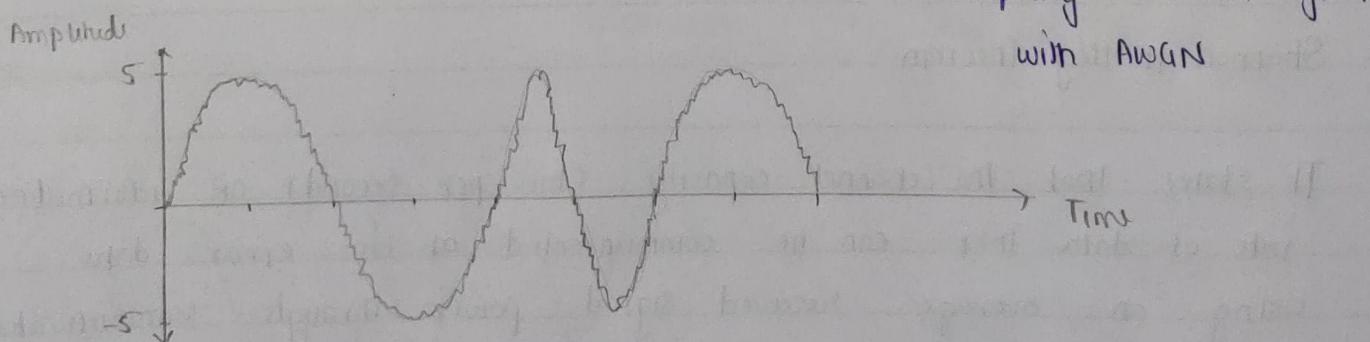
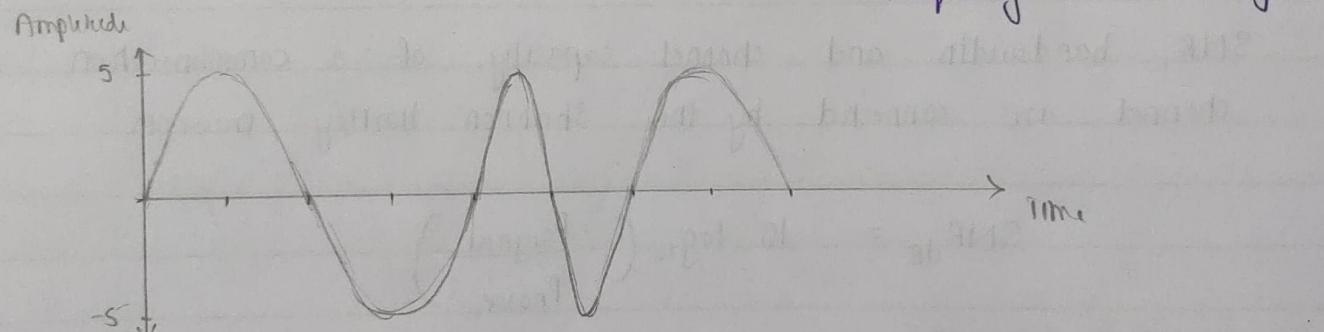
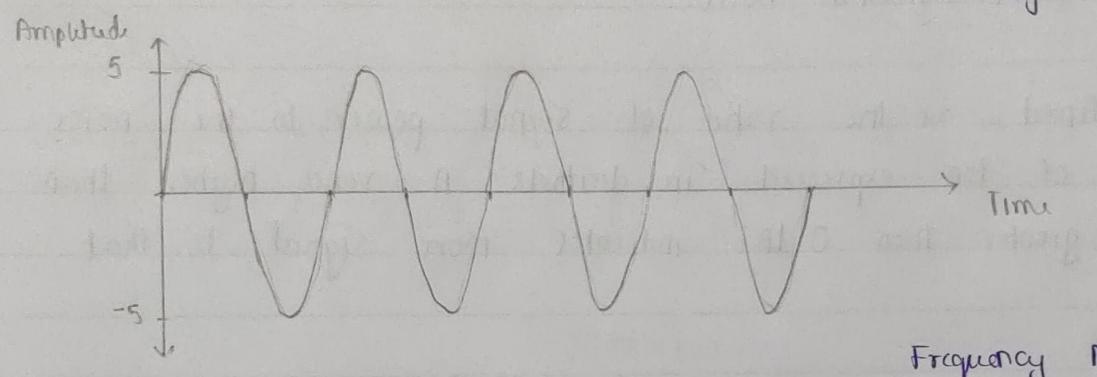
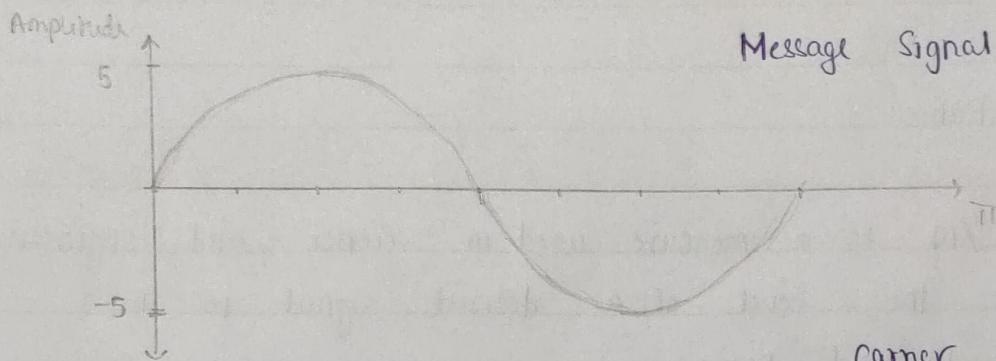
```

subplot(4,1,4);
plot(t, z);
xlabel('time');
ylabel('amplitude');
title('Frequency modulated signal with
      AWGN');

```

# FM Signal under AWGN

(13)



FM in Different SNR

dc; clear all;

t = 0 : 0.001 : 1;

vm = 10; fm = 2;

vc = 5; fc = 28;

fd = 10

m = vm \* sin(2\*pi\*fm\*t);

c = vc \* sin(2\*pi\*fc\*t);

amp = vc + vm \* sin(2\*pi\*fm\*t);

y = vc \* sin(2\*pi\*fc\*t) + fd \* cos(2\*pi\*fm\*t);

y1 = awgn(y, 1, 'measured');

y2 = awgn(y, 10, 'measured');

y3 = awgn(y, 100, 'measured');

① subplot(4,1,1);

plot(t, y);

xlabel('time')

ylabel('amplitude')

title('Frequency modulated signal')

② subplot(4,1,2);

plot(t, y1);

xlabel('time');

ylabel('amplitude');

title('SNR 10');

③ subplot(4,1,3);

plot(t, y2);

xlabel('time');

ylabel('amplitude');

title('AWGN [SNR 10] FM');

④ subplot(4,1,4);

plot(t, y3);

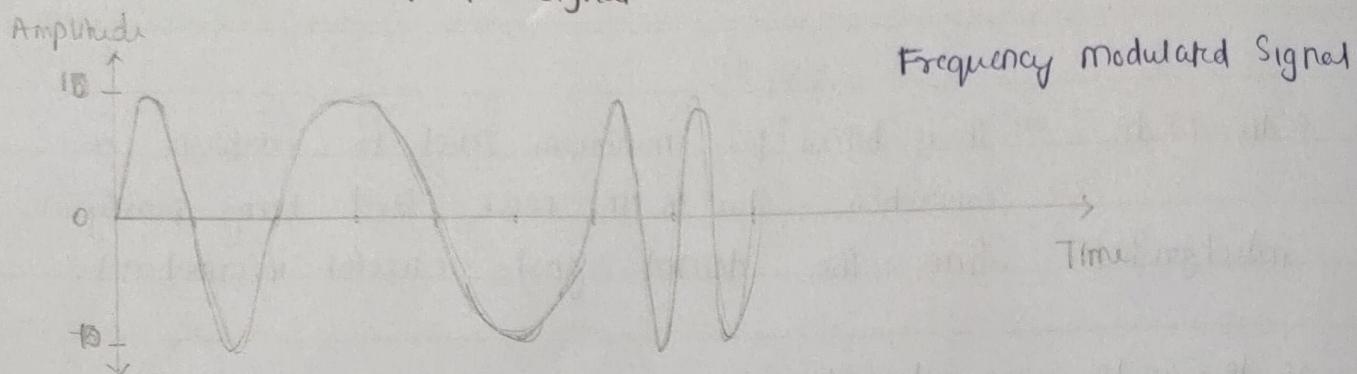
xlabel('time');

ylabel('amplitude');

title('AWGN [SNR 100] FM');

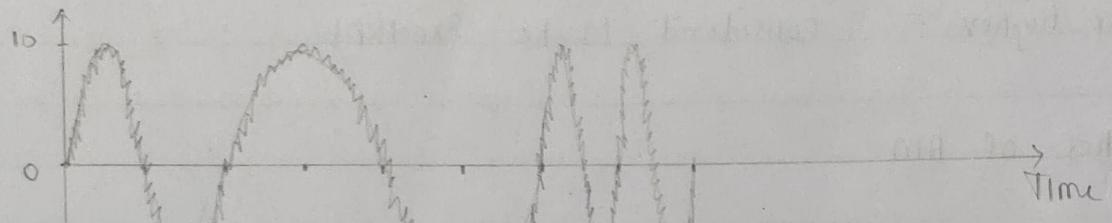
# FM signal with different SNR

(15)

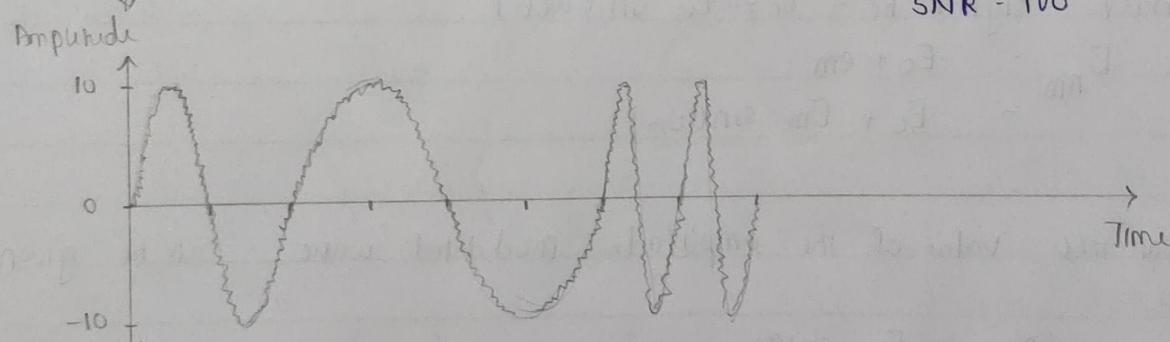


Amplitude

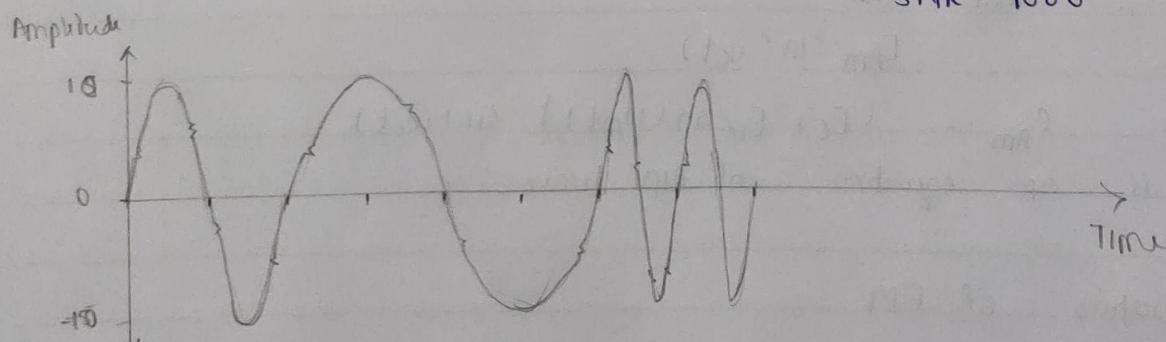
$\text{SNR} = 10$



$\text{SNR} = 100$



$\text{SNR} = 1000$



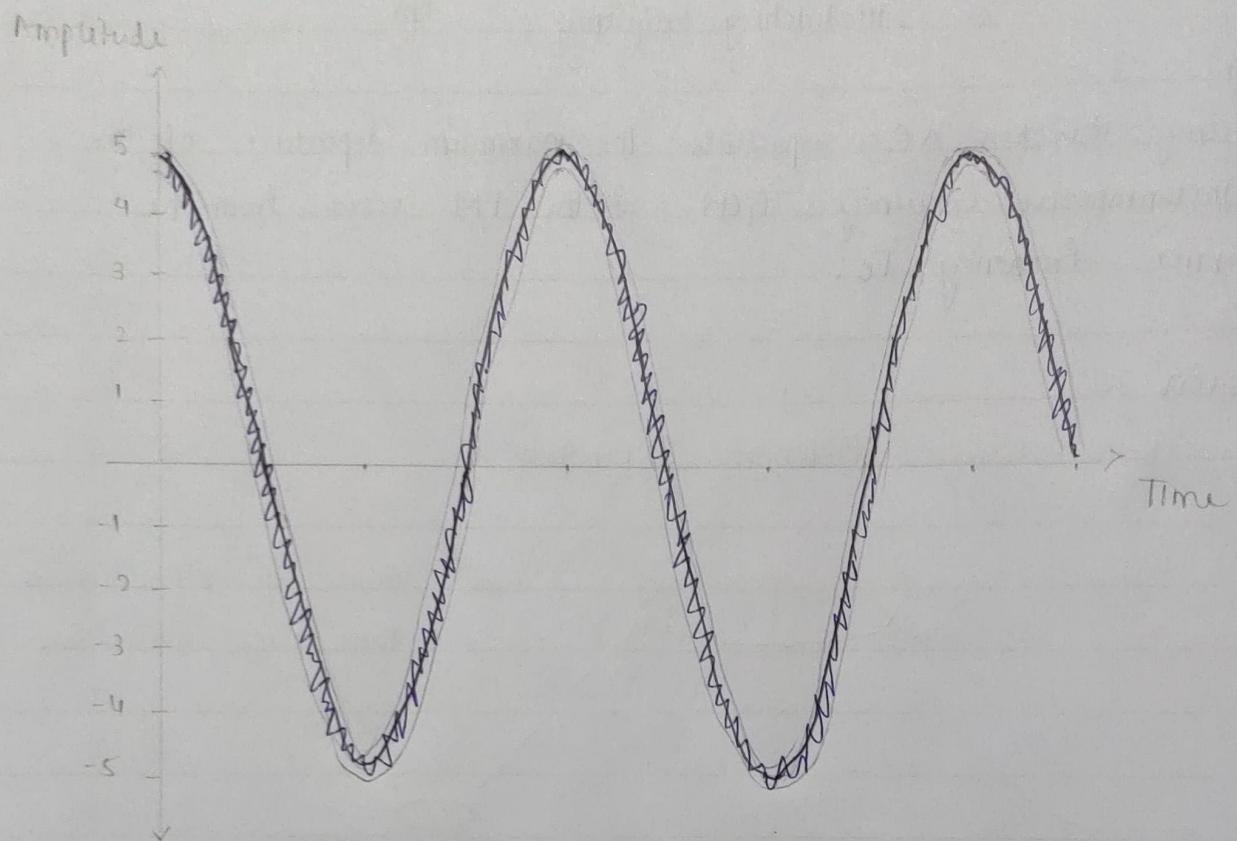
[U19CS012]

## Moving Average Filter

```
clear all; clc;  
close all;  
fs = 500000;  
fm = 10000;  
t = 1:200;  
x = 5 * (sin(2*pi*(fm/fs)*t));  
z = awgn(x, 5);  
plot(x, 'g', 'LineWidth', 1.5);  
hold on;  
plot(z); hold on;  
for i = 1:194;  
    y(i) = (z(i) + z(i+1) + z(i+2) + z(i+3) + z(i+4) + z(i+5))/6;  
end  
plot(y, 'r', 'LineWidth', 1.5);  
legend('Actual', 'Noisy', 'Filtered');  
title('moving Average Filter', 'FontSize', 12);  
xlabel('--> time in 2us');  
ylabel('--> volts');
```

> CONCLUSION: We have successfully studied the effect of AWGN on transmission of Amplitude modulation (AM) and Frequency Modulation (FM).

Use of moving average filter to retrieve the signal by averaging the noise fluctuation



Moving Average Filter

— = Actual   — = Noisy   - = Filtered

## EXPERIMENT - 8

[UI9CS012]

## SINGLE SIDE BAND (SSB-SC) MODULATION

## SCHEME

AIM: Write and simulate a program for single side-band (SSB) modulation scheme. Draw the message/carrier waveforms and resultant modulated signal in time domain and frequency domain. Show input/output using matlab code in virtual mode.

APPARATUS: MATLAB

## THEORY:

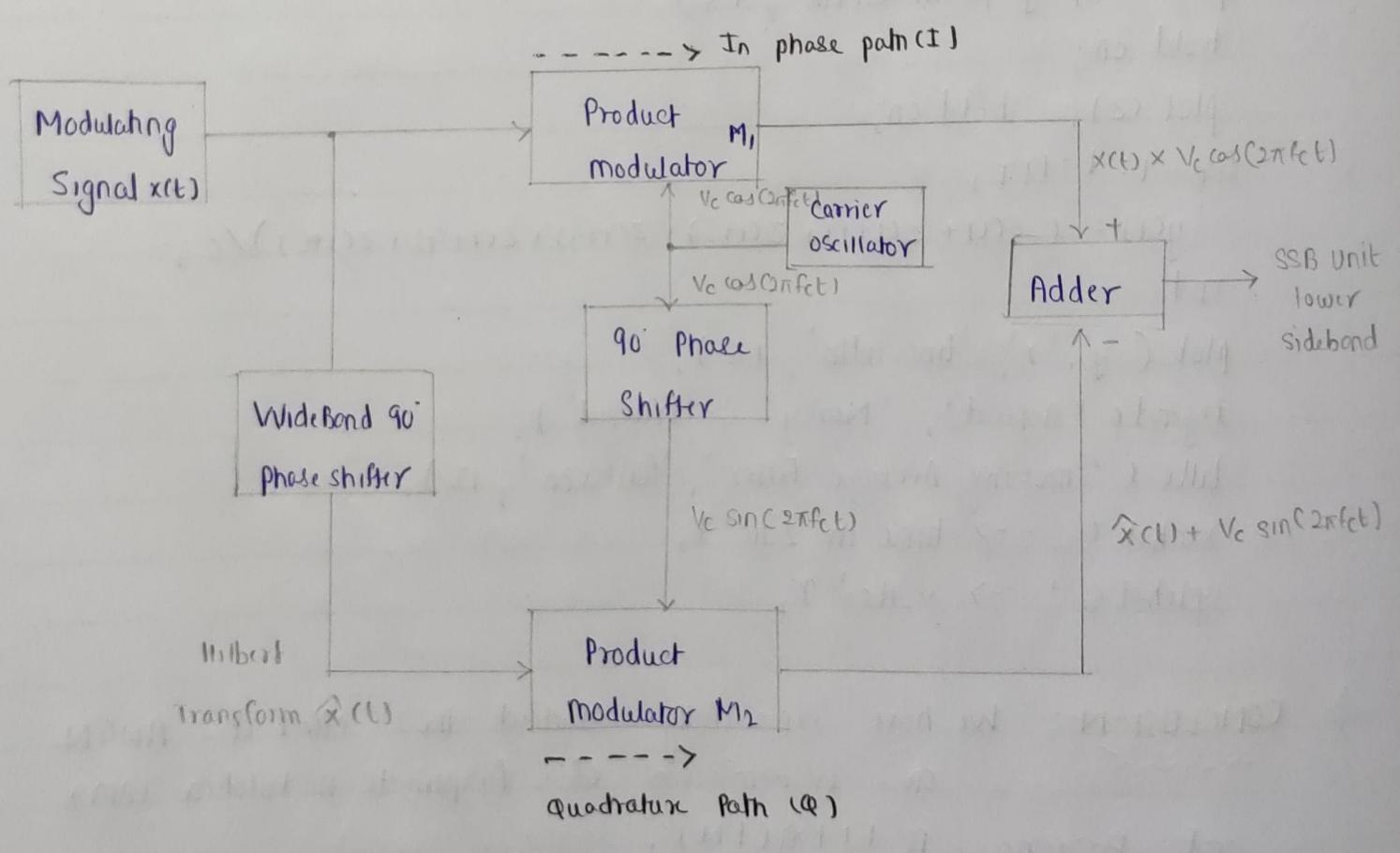
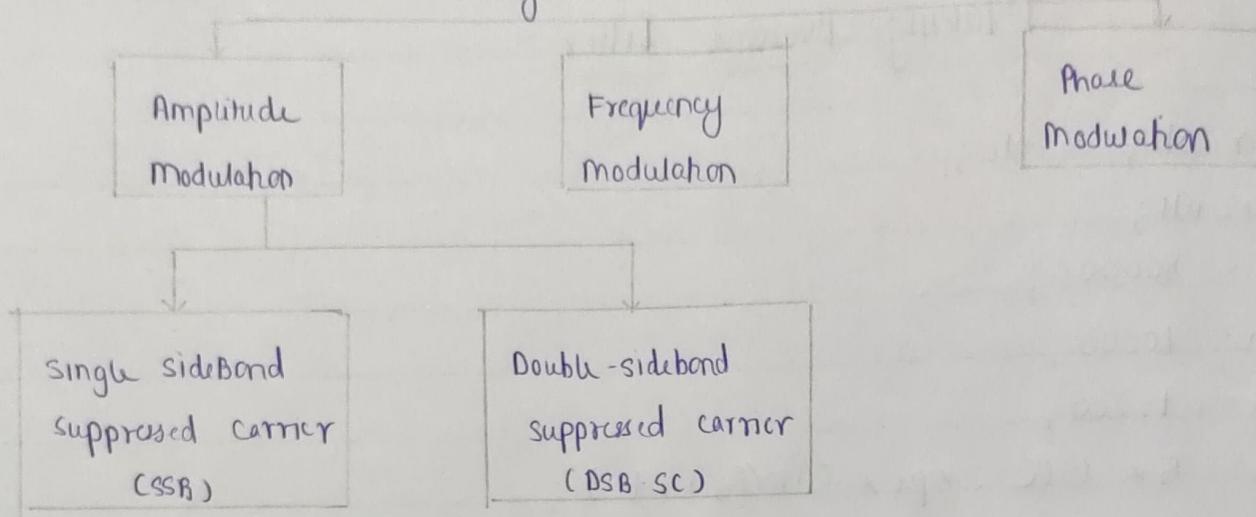
1.) Modulation: Modulation is a process by which some characteristics of a carrier wave is varied in accordance with a modulating (message) signal.

2) Analog Modulation: It is a kind of modulation, where the message signal and the carrier wave both are analog in nature.

## 3.) Single Side Band (SSB-SC) modulation :

- SSB-SC is a type of Amplitude Modulation
- In conventional A.M, we have two side band and the one carrier wave (no information is contained by the carrier)
- In SSB-SC modulation, only one side band is transmitted because

## Analog modulation methods



Generation of SSB-SC : By Hilbert Transform method

both USB (upper side band) and LSB (lower side band) having the same information.

- Therefore, the transmission bandwidth is reduced to half and also required less power compare to other method of A.M.

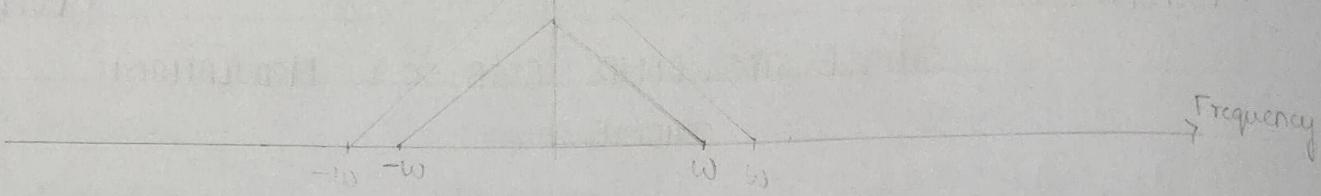
4.) There are two methods of generation of SSB-SC :

- ① Frequency discrimination method
- ② Hilbert transform method or Phase discrimination method

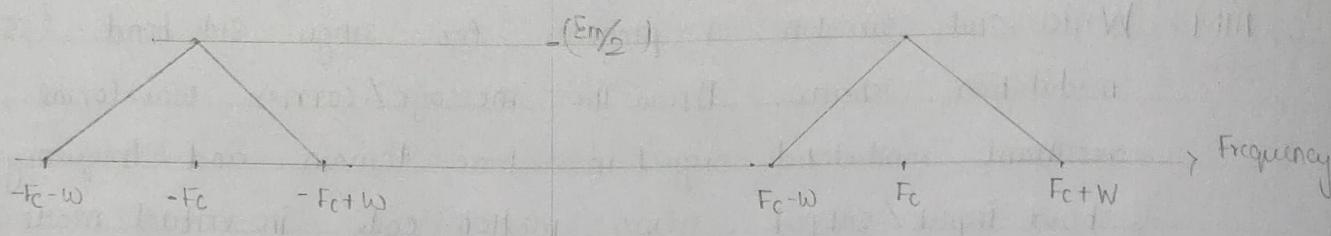
5.) Applications :

- In point-to-point communications
- Radar Communication
- Where the power saving and low bandwidth requirements are important-
- In many voice applications.

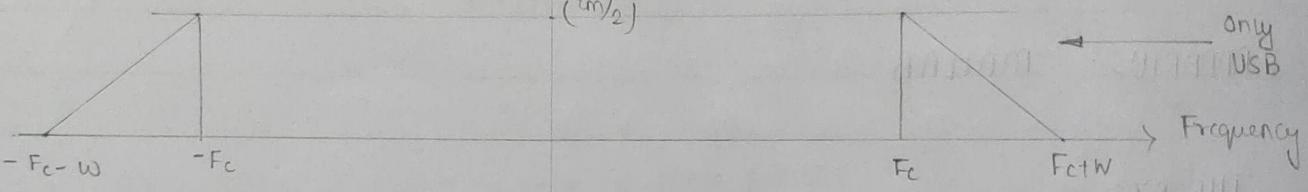
(a)



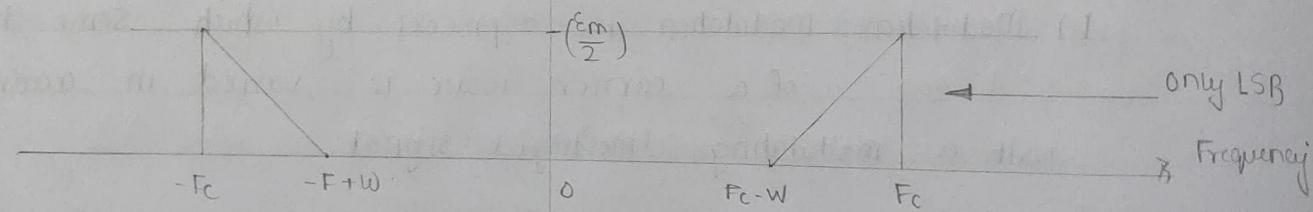
(b)



(c)



(d)



- (a) Spectrum of Message Signal
- (b) Spectrum of DSB-SC wave
- (c) Spectrum of DSB-SC with only USB Transmission
- (d) Spectrum of DSB-SC with only LSB Transmission

## MATLAB Code :

```
clc;
```

```
clear all;
```

```
close all;
```

```
am = 1 ;
```

% amplitude of modulating signal

```
ac = 1 ;
```

% amplitude of carrier signal

```
fm = 500 ;
```

% modulating signal frequency

```
fc = 5000 ;
```

% carrier frequency

```
fs = 100000 ;
```

% sampling frequency

```
ts = 1/fs ;
```

% sampling interval

```
N = 10000 ;
```

% no. of samples

```
t = (-N/2 : 1 : (N/2 - 1)) * ts ;
```

% time interval

```
m = am * cos(2 * pi * fm * t) ;
```

% modulating signal

```
mh = am * sin(2 * pi * fm * t) ;
```

% hilbert transformation of message signal

```
c = ac * cos(2 * pi * fc * t) ;
```

% carrier signal

```
ch = ac * sin(2 * pi * fc * t) ;
```

% hilbert transform of carrier signal

```
st = m * c - mh * ch ;
```

% SSB-SC signal

% time domain of all signals

```
subplot (3,2,1)
```

```
plot (t, m, 'red', 'LineWidth', 1.5);
```

```
axis [0 0.005 -2.5 2.5];
```

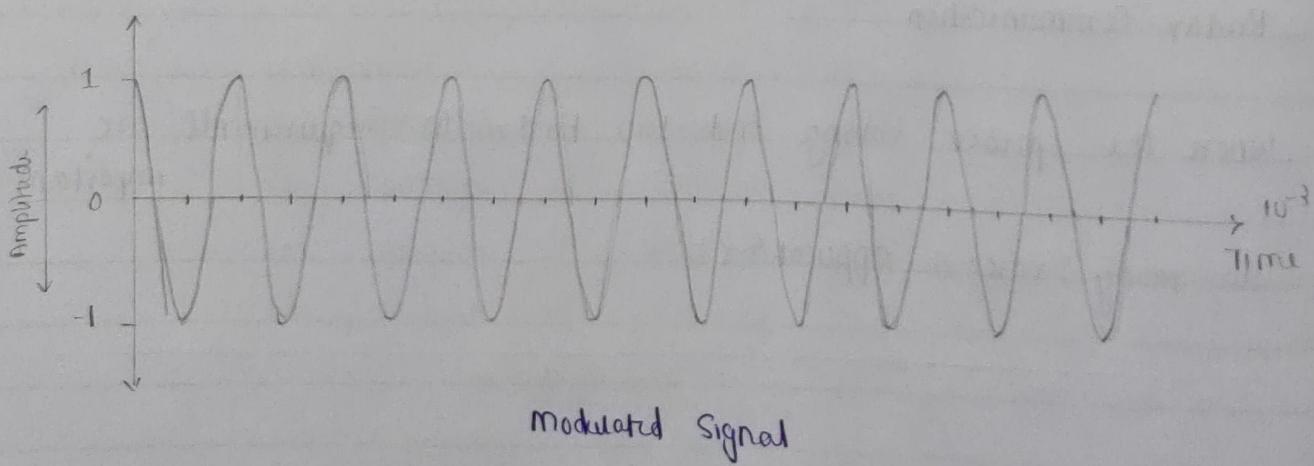
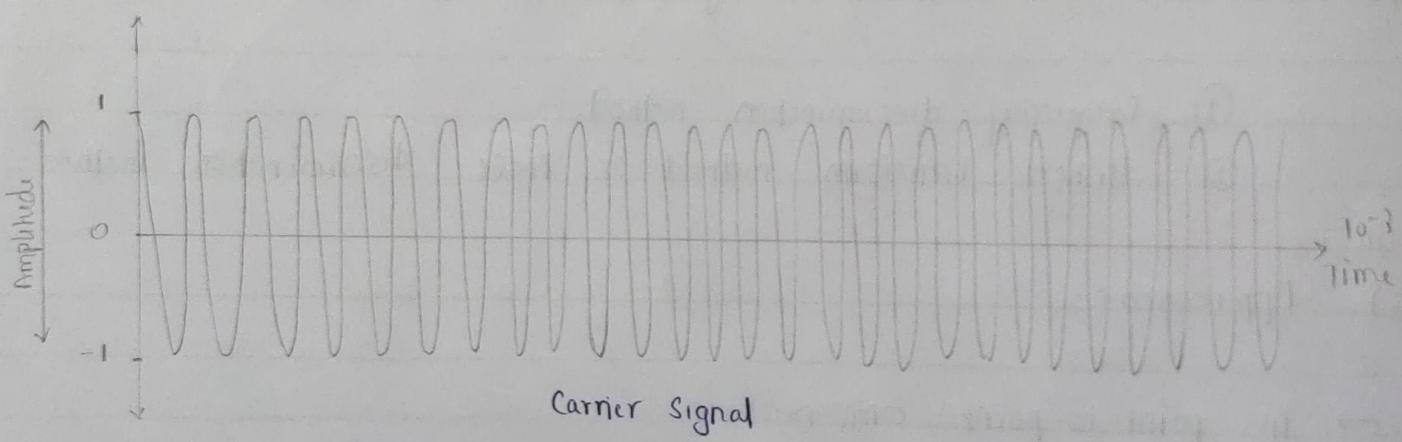
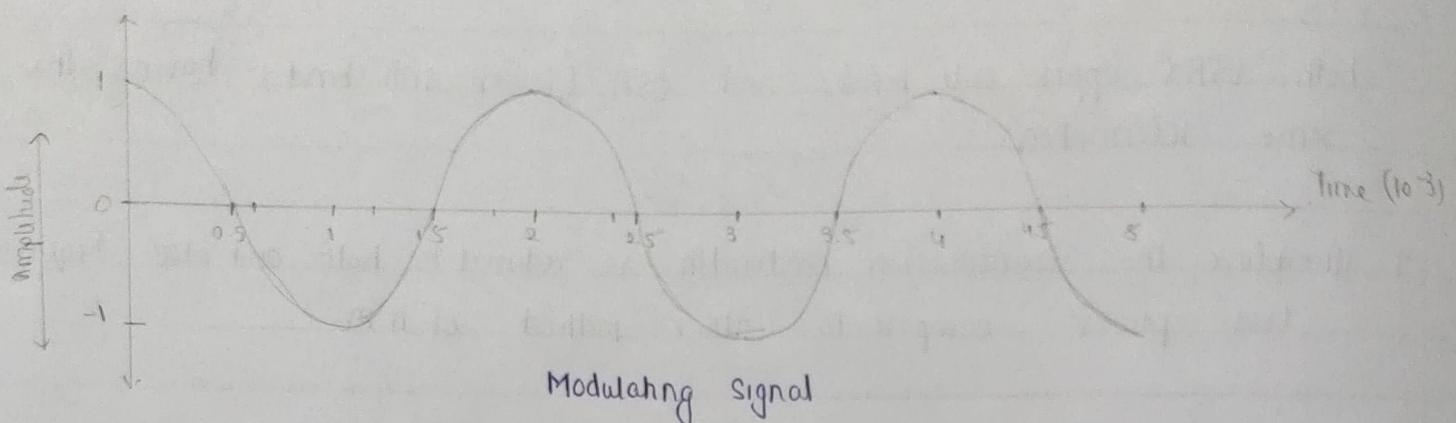
```
xlabel ('Time');
```

```
ylabel ('Amplitude');
```

```
title ('modulating signal');
```

```
grid on;
```

©



subplot(3,2,3)

```
plot(t, c, 'black', 'LineWidth', 1.5);  
axis([0 0.005 -2.5 2.5]);  
xlabel('time');  
ylabel('amplitude');  
title('carrier signal');  
grid on;
```

subplot(3,2,5)

```
plot(t, st, 'blue', 'LineWidth', 1.5);  
axis([0 0.005 -2.5 2.5]);  
xlabel('time');  
ylabel('amplitude');  
title('modulated signal');  
grid on;
```

% spectrum of all signals

$$f = (-N/2 : 1 : (N/2 - 1)) \times fs/N;$$

$$M = abs((2/N) * fftshift(fft(m)));$$

$$C = abs((2/N) * fftshift(fft(c)));$$

$$SF = abs((2/N) * fftshift(fft(st)));$$

subplot(3,2,2);

```
plot(f, M/max(M), 'red', 'LineWidth', 1.5);
```

```
axis([-2*fc 2*fc -0.1 1.1]);
```

```
xlabel('frequency');
```

```
ylabel('amplitude');
```

```
title('modulating signal');
```

```
grid on;
```

subplot(3,2,4);

```
plot(f, C/max(c), 'black', 'LineWidth', 1.5);
```

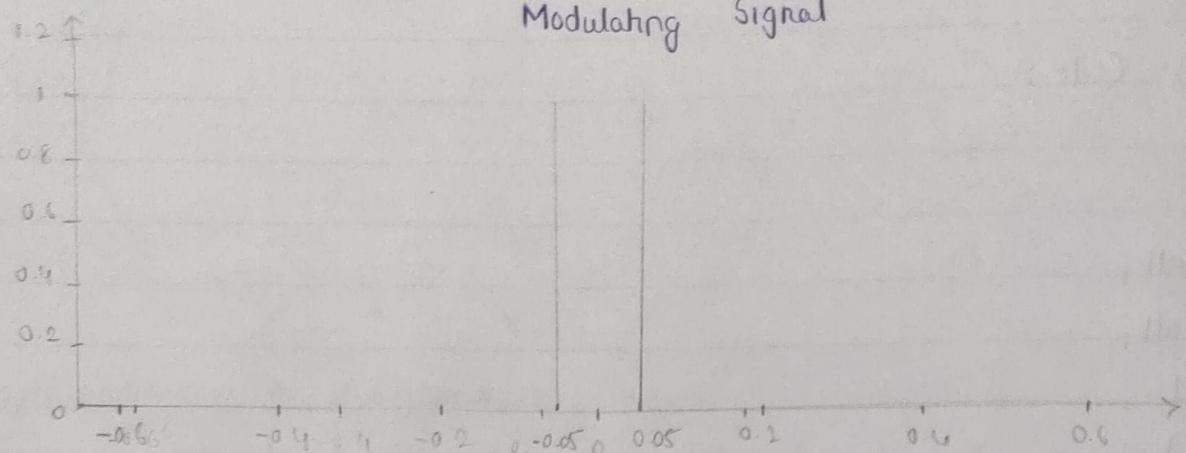
```
axis([-2*fc 2*fc -0.1 1.1]);
```

```
xlabel('frequency');
```

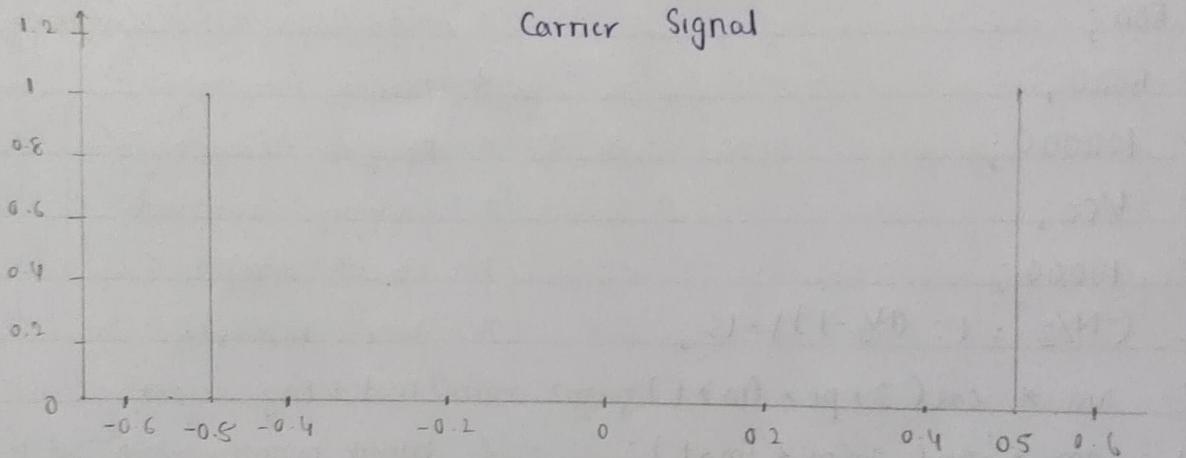
```
ylabel('carrier amplitude');
```

```
title('carrier signal'); grid on;
```

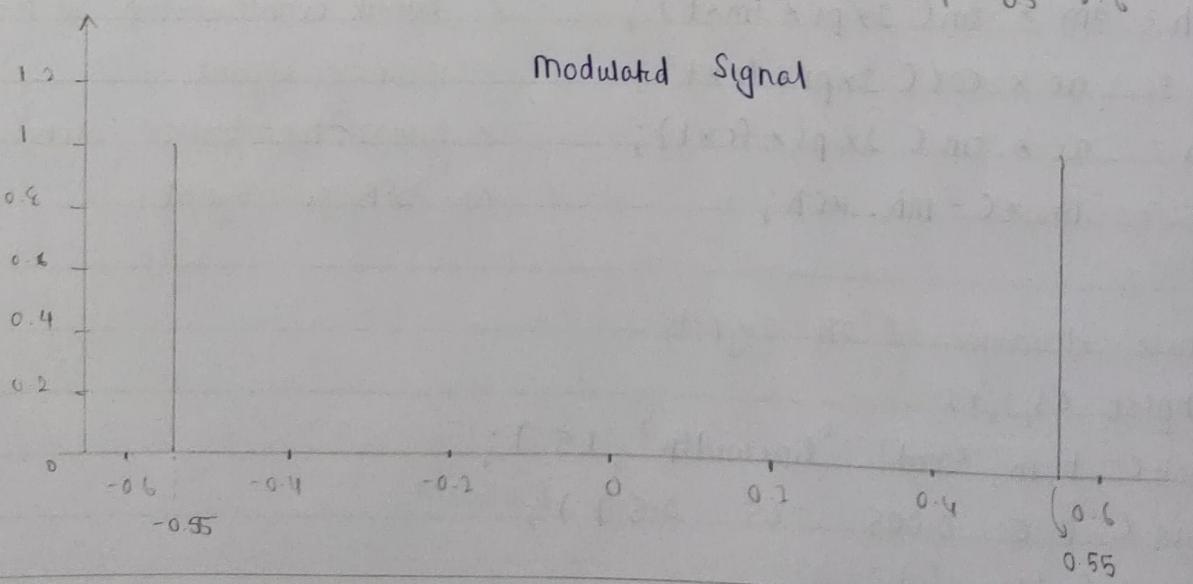
Modulating Signal



Carrier Signal



Modulated Signal



[U19CS012]

```
subplot (3,2,6);
```

```
plot ( f, SF/max(SF) , 'blue' , 'linewidth' , 1.5 );
```

```
axis [ -2*fc 2*fc -0.1 1.1 ] ;
```

```
xlabel ( 'frequency' );
```

```
ylabel ( 'amplitude' );
```

```
title ( 'modulating signal' );
```

```
grid on;
```

CONCLUSION : We successfully observed single side Band (SSB-SC) Modulation scheme and as we come to know that here low Bandwidth is required for transmission. Hence, we also save power.

x-

## EXPERIMENT 9

[U19CS012]

QAM MODULATION AND  
DE MODULATION

AIM: Study of 16 QAM Modulation and Demodulation technique with constellation diagram and waveforms.

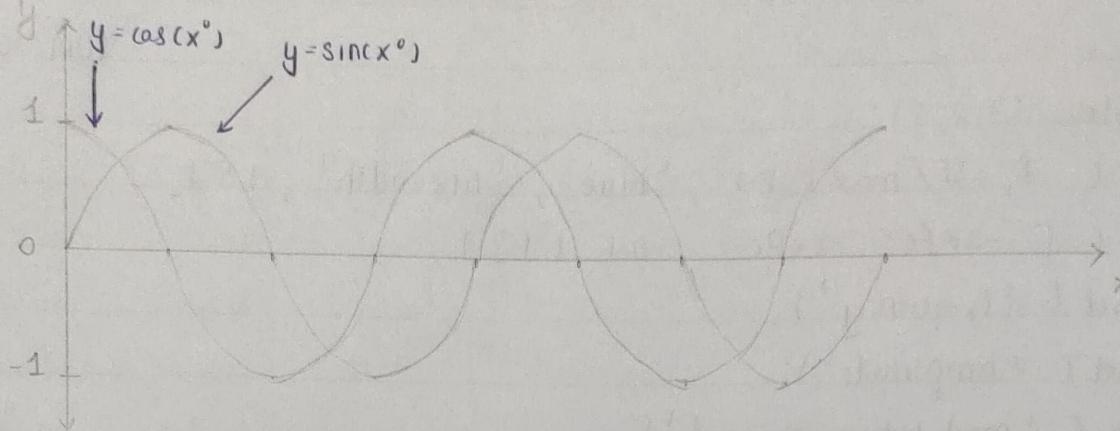
APPARATUS: MATLAB

THEORY: ① QAM: Quadrature Amplitude Modulation or QAM is a form of modulation which is widely used for modulating data signals onto a carrier used for radio communications.

- QAM is a signal in which two carriers shifted in phase by 90° are modulated & the resultant output consists of both amplitude and phase variations.
- hence it may also be considered as a mixture of amplitude and phase modulation. QAM is both an analog and digital modulation technique.
- ② Main parameters to be considered while designing any communication system
  - Transmission Power
  - Transmission Bandwidth
- Although the SSB-SC systems are most power and bandwidth efficient but still their performance lags in the noisy environment.

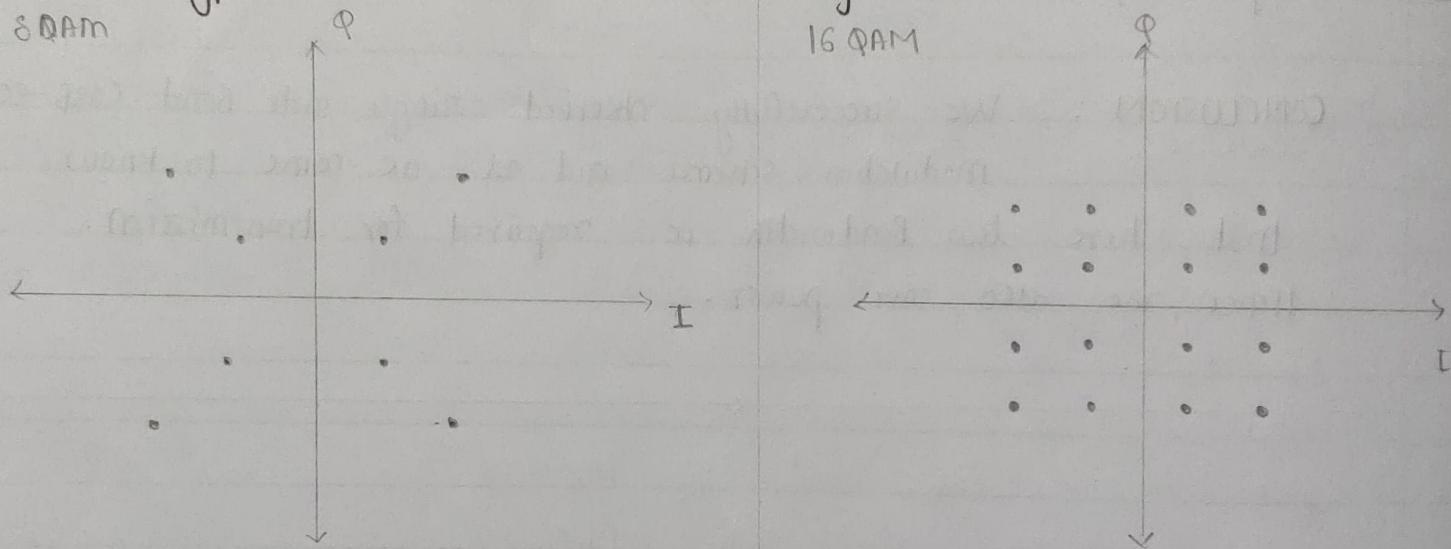
Quadrature = Sine wave + Cosine wave

(2)



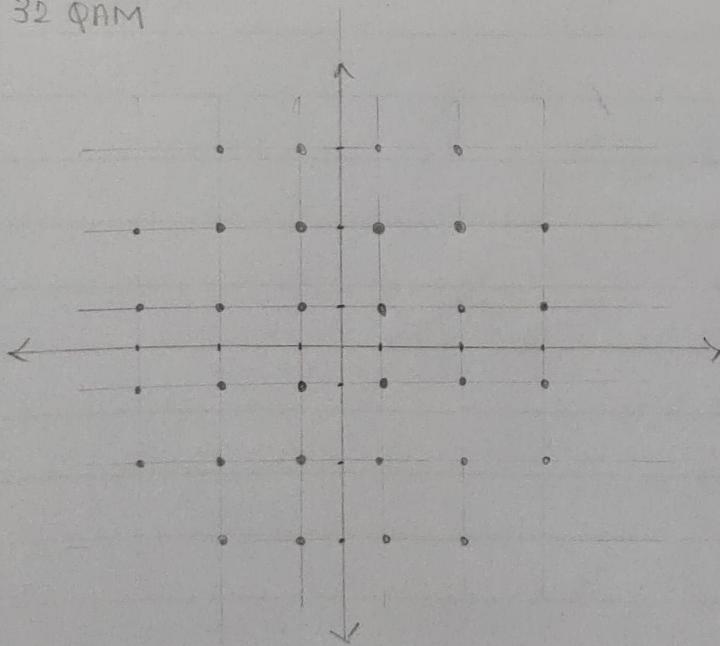
Types of QAM - constellation Diagram  $\rightarrow$

8 QAM

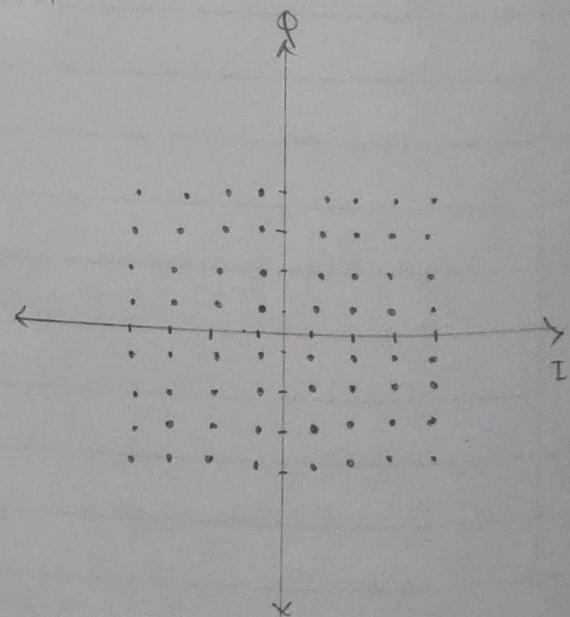


16 QAM

32 QAM



64 QAM



### 3. Why QAM?

- The main aim is to save bandwidth: Two modulated signal occupies the same transmission channel.
- A motivation for the use of QAM comes from the fact that a straight amplitude modulated signal occupies twice the bandwidth of the modulating signal.
- This is very wasteful of the available frequency spectrum
- QAM places two independent double sideband suppressed carrier signals in the same spectrum.

### 4.1 Types of QAM

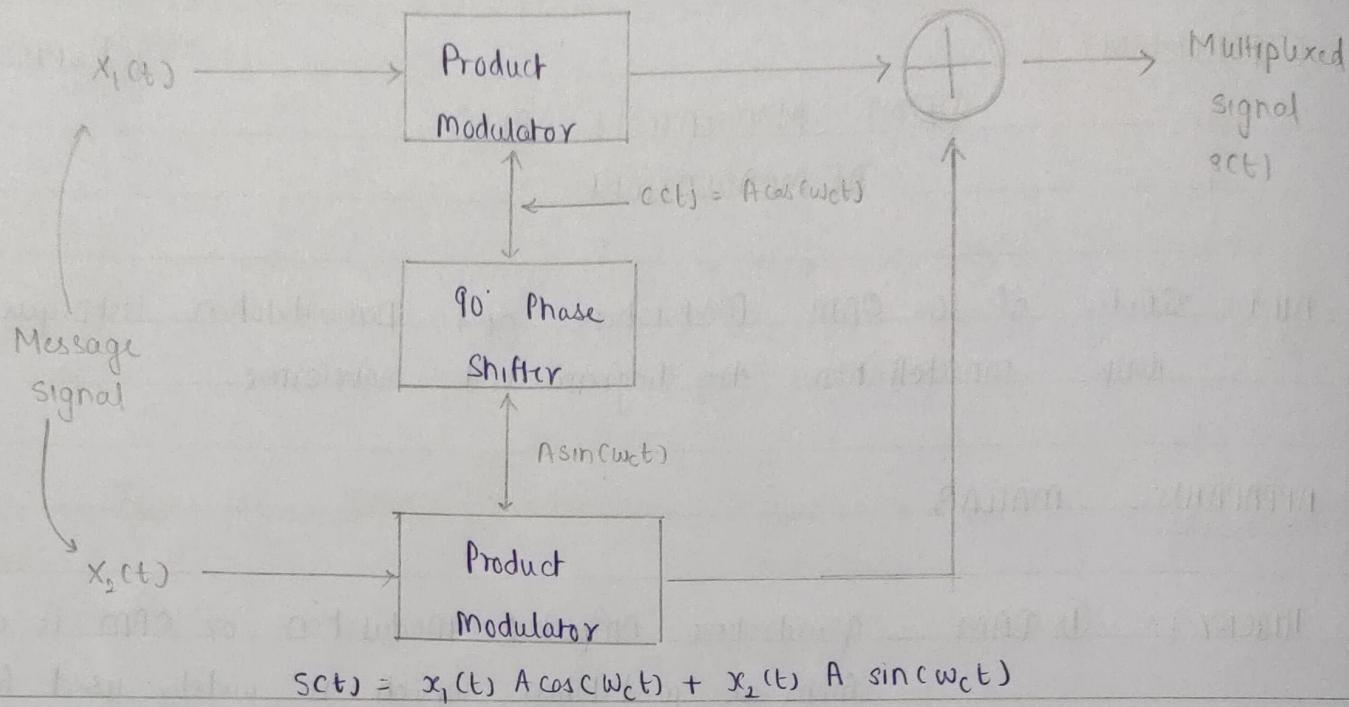
- A variety of forms of QAM are available which include:
  - 16 QAM
  - 64 QAM
  - 256 QAM
  - 32 QAM
  - 128 QAM

### 5.1 QAM Modulation

- QAM theory states that both Amplitude and phase changes within a QAM signal.
- The basic way in which a QAM signal can be generated is to generate two signals that are 90° out of phase with each other and then sum them.

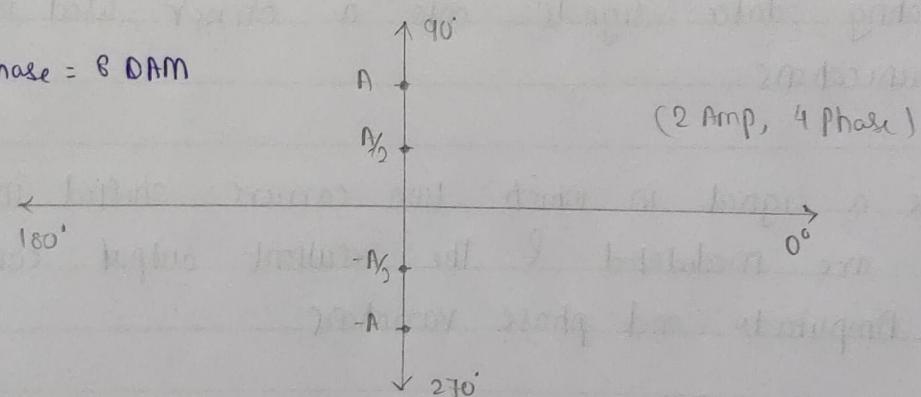
## QAM Modulation

(4)

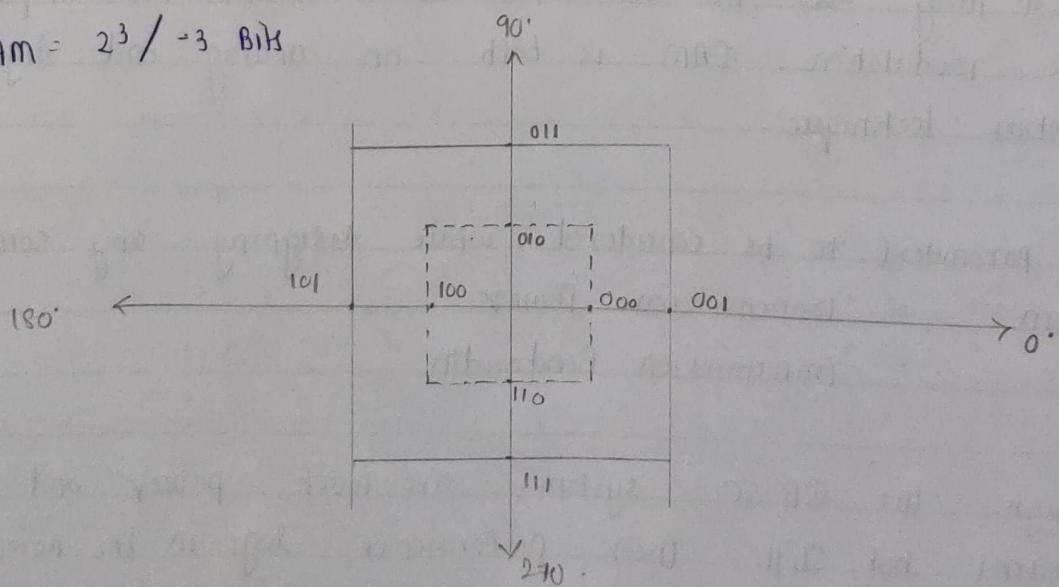


$$s(t) = x_1(t) A \cos(\omega_c t) + x_2(t) A \sin(\omega_c t)$$

$2 \text{ Amp} \times 4 \text{ phase} = 8 \text{ QAM}$



$8 \text{ QAM} = 2^3 / -3 \text{ Bits}$



- The I and Q signals can be represented by the equation below:

$$I = A \cos(\phi)$$

$$Q = A \sin(\phi)$$

- These signals will not overlap with each other because they are orthogonal.

"2f<sub>m</sub>"

- It is possible to transmit two DSB-SC signal within bandwidth of  $f_m$ .
- It provides bandwidth efficiency.
- Gives better performance than SSB and also improves data rate.

#### 6.) QAM Demodulation

- The QAM demodulator is very much the reverse of the QAM modulator.

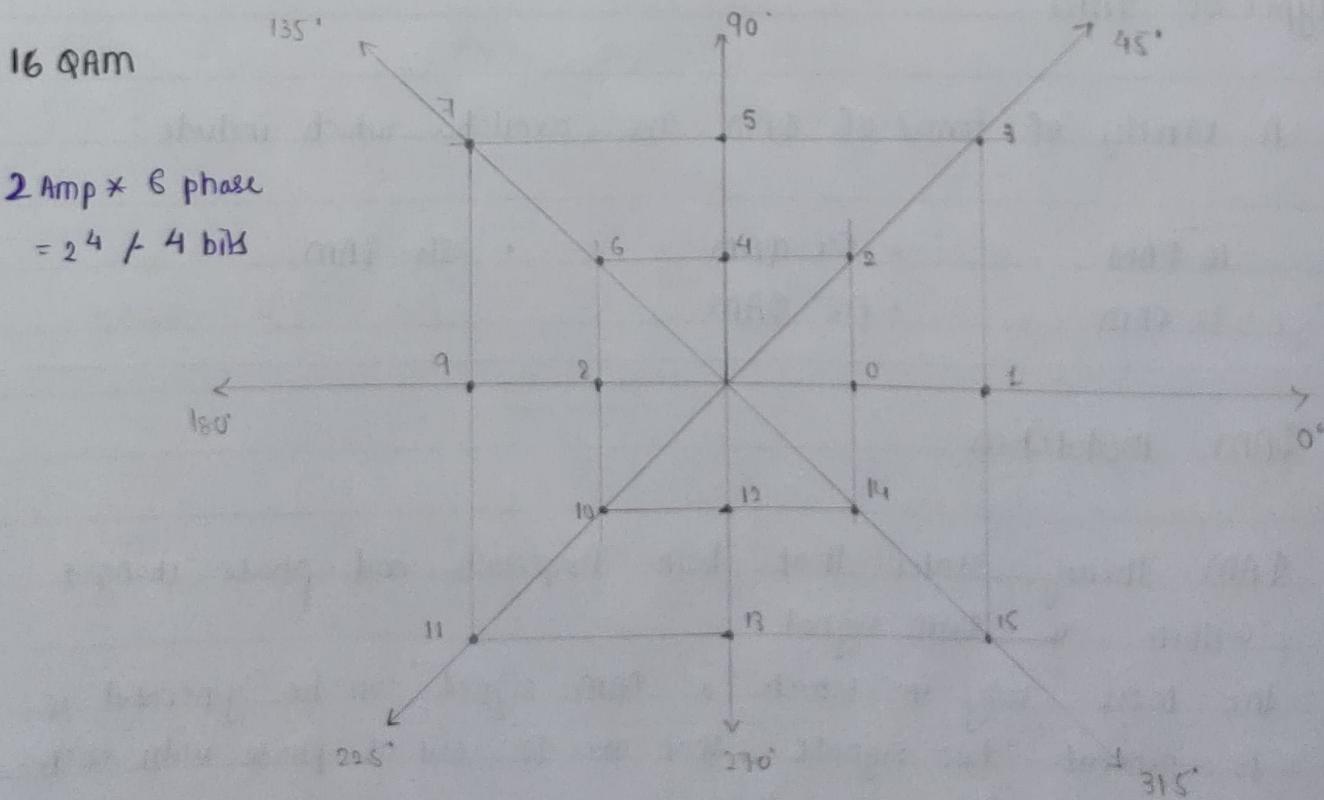
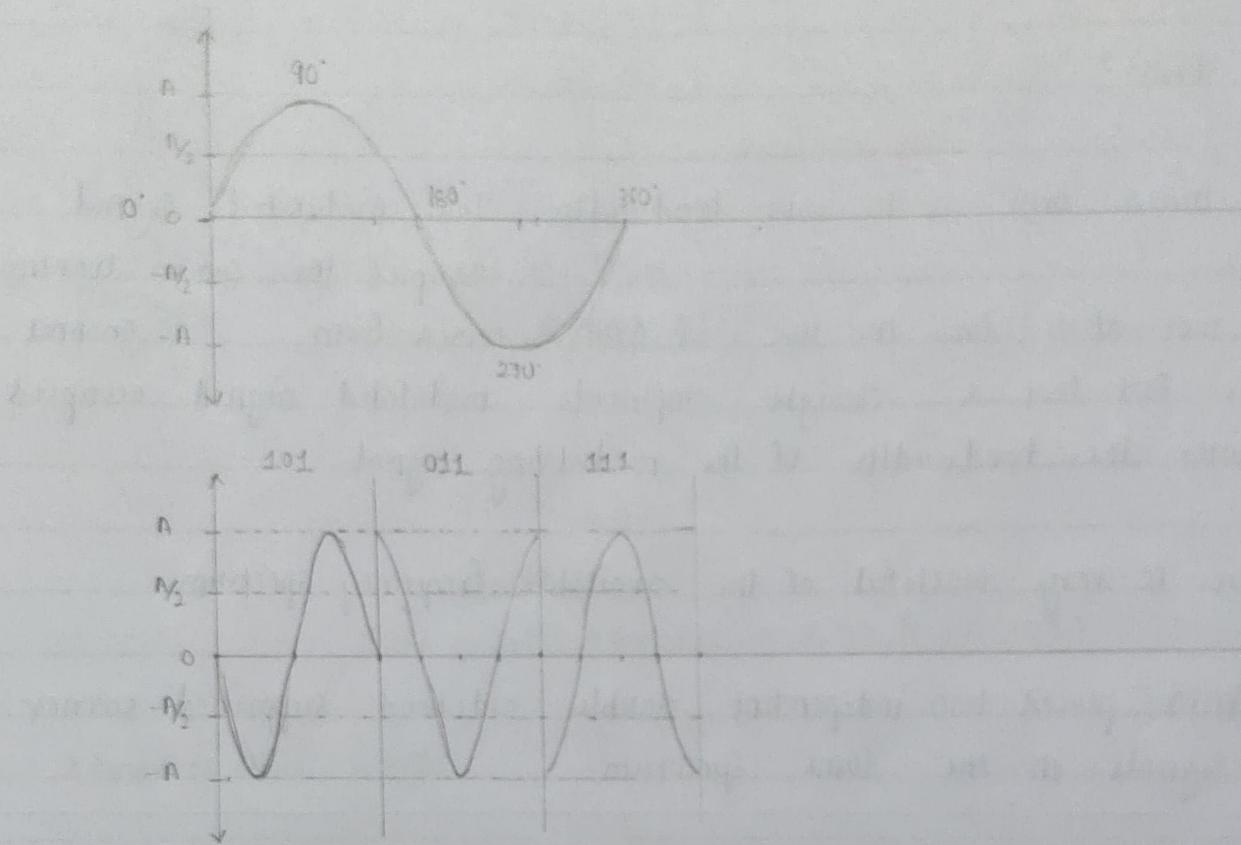
- The signals enter the system, they are split and each side is applied to a mixer.

#### 7.) Bit error Rate (Received Bits)

- While higher order modulation rates are able to offer much faster data rates and higher levels of spectral efficiency for the radio communication system, this comes at a price.
- The higher order modulation schemes are considerably less robust to noise and interference.

(6)

## Phasor Diagram



- Many radio communications systems now use dynamic adaptive modulation techniques. They sense the channel conditions and adapt the modulation scheme to obtain the highest data rate for the given conditions.
- M-QAM technique provides better bit error rate performance than M-PSK modulation techniques.

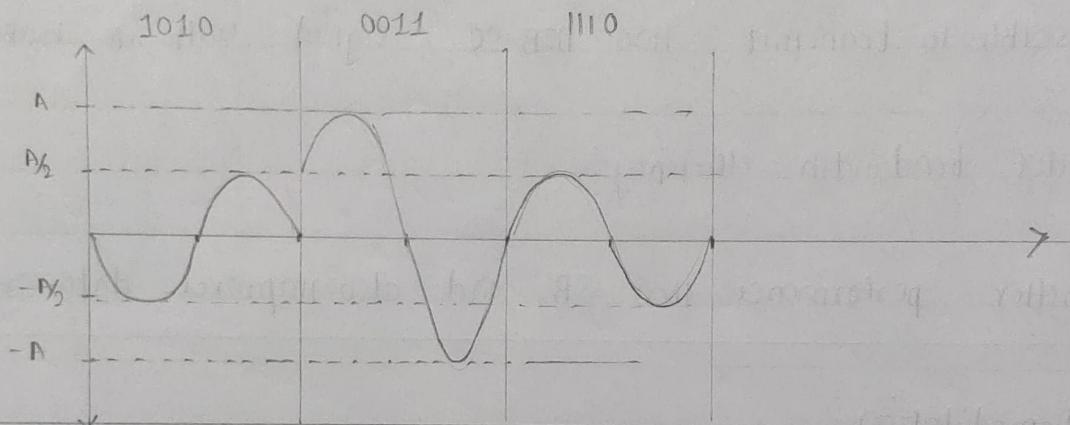
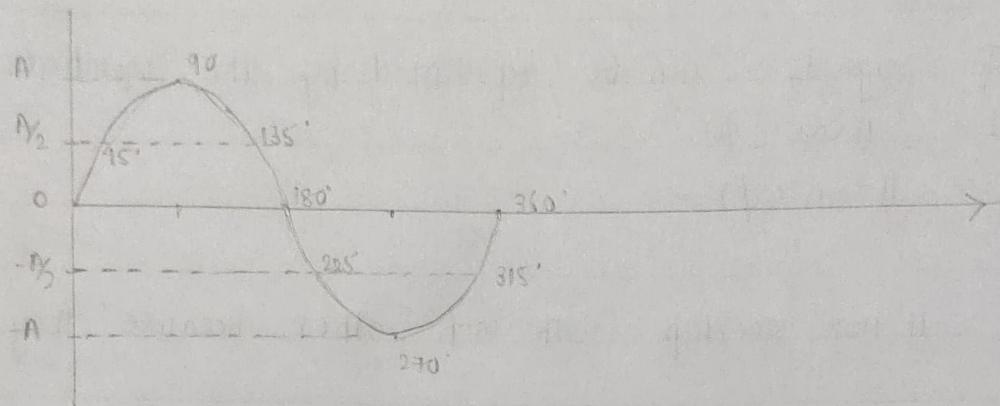
#### 8. > Advantages

- The advantage of using QAM is that it is a higher order form of modulation. As a result, it is able to carry more bits of information per symbol.
- By selecting a higher order format of QAM, the data rate of a link can be increased.
- Bit rate is increased without increasing the bandwidth.

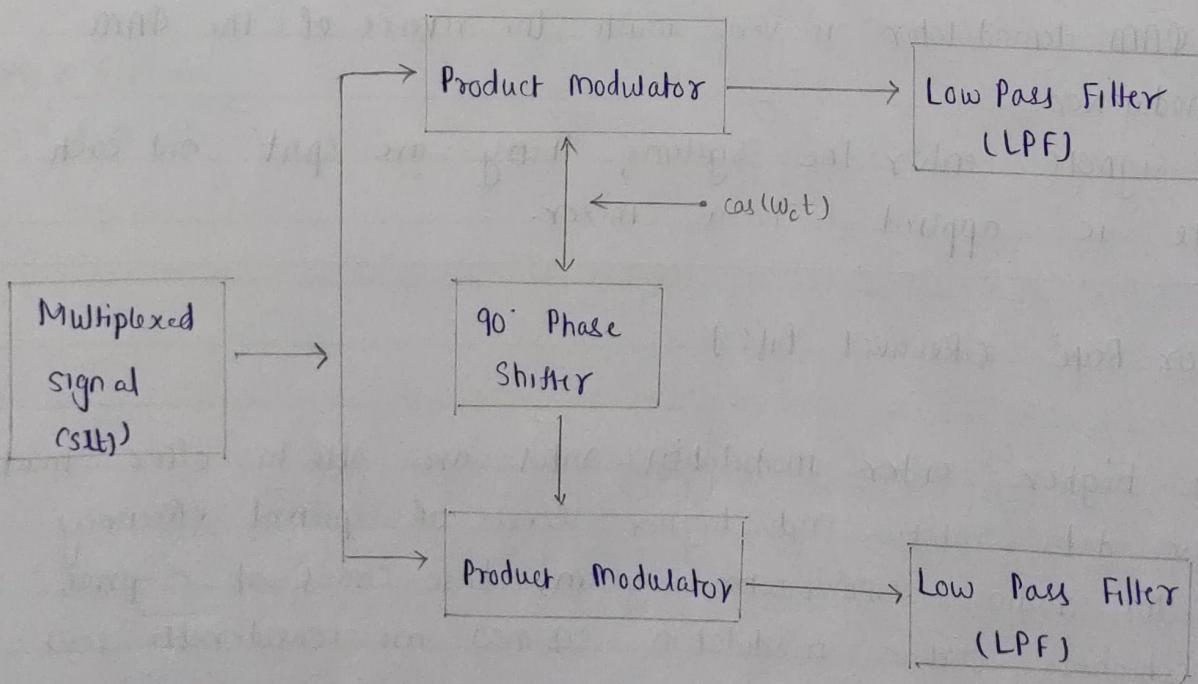
#### 9. > Applications

- Quadrature multiplexing is used in color television to multiplex the so-called chrominance signals which carry the information about colors.
- QAM scheme is used on telephone lines for data transmission.
- Ultra high capacity microwave Backhaul systems also use 1024-QAM.

## Phasor Diagram



## QAM Demodulation



## &gt; MATLAB Code:

clc;

clear all;

close all;

M = 16;

x = (0 : M-1);

y = gammod(x, M);

scatterplot(y);

% z = qam demod(y, M, pi/4);

% scatterplot(z);

ber\_1 = [];

for EbN0dB = 0 : 20;

$$((3 * \log_2(M) * \epsilon_{\text{BER}}) / 2 * (M-1))$$

EbN0 = 10^(EbN0dB/10);

ber = (1 / log2(M)) \* (2 \* (1 - sqrt(1/M)) \* erfc(sqrt(epsilon)^0.5));

ber\_1 = [ber\_1 ber];

end

EbN0dB = 0 : 20;

figure

semilogy(EbN0dB, ber\_1(1, :), 'r-');

xlabel('Eb/N0(dB)');

ylabel('BER');

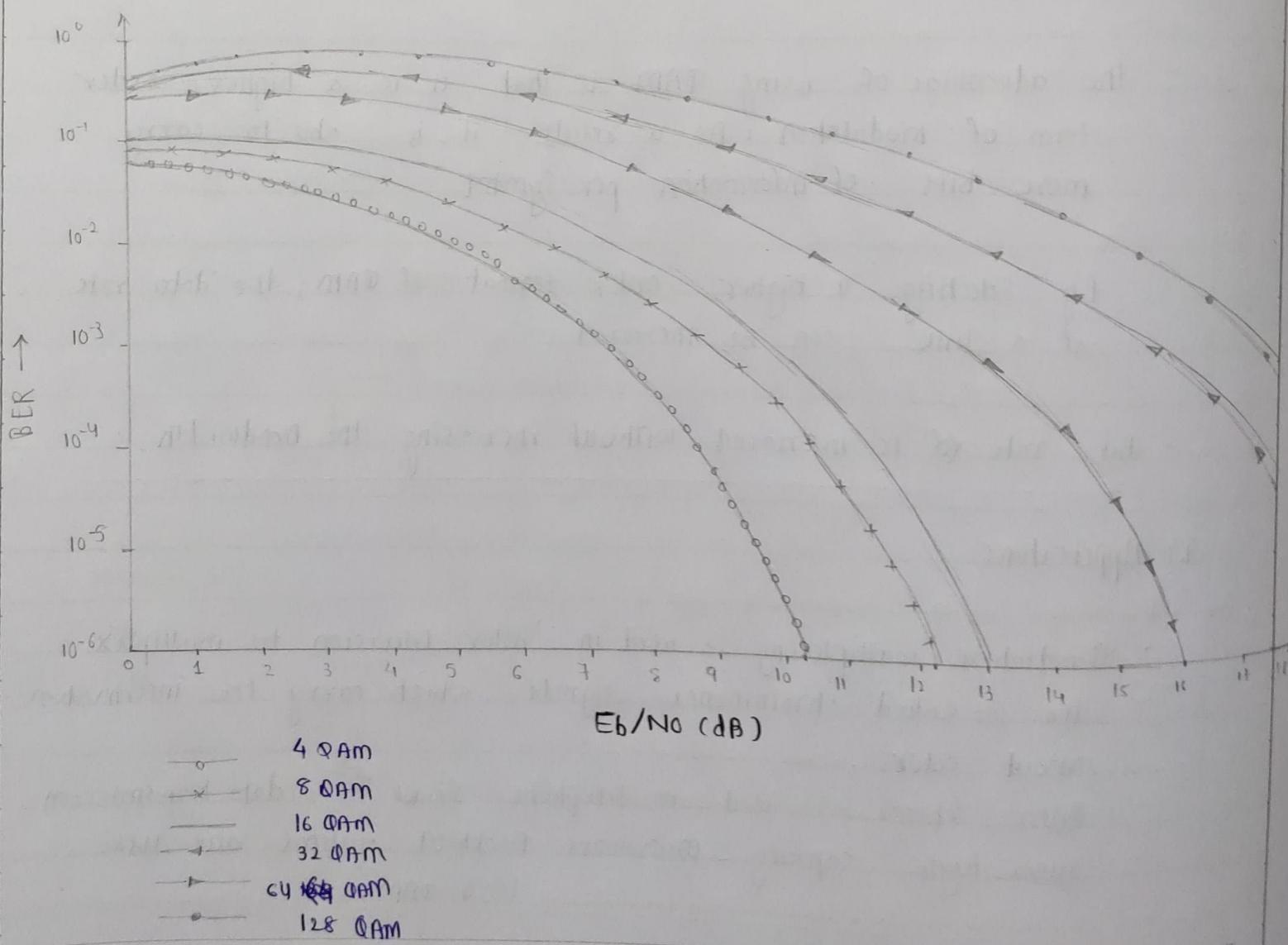
title('BER of 16-QAM');

axis([0 16 10^-6 10^0]);

grid on;

| Modulation | Bit Per Symbol | Symbol Rate            |
|------------|----------------|------------------------|
| BPSK       | 1              | 1 Bit Rate             |
| QPSK       | 2              | $\frac{1}{2}$ Bit Rate |
| 8PSK       | 3              | $\frac{1}{3}$ Bit Rate |
| 16 PSK     | 4              | $\frac{1}{4}$ bit Rate |
| 32 PSK     | 5              | $\frac{1}{5}$ bit Rate |
| 64 PSK     | 6              | $\frac{1}{6}$ bit Rate |

"BER Values" using MATLAB



[UI9CS012]

1. BER comparison of various M-QAM

dc; clear; close all;

$$M = [4 8 16 64 128 256]$$

for  $i = 1 : \text{length}(M)$

ber\_m1 = [];

for  $E_{bNodB} = 0 : 20$

$$E_{bNOD} = 10^{(E_{bNodB}/10)};$$

$$\text{ber} = (1 / \log_2(M(i))) * (2 * (1 - \sqrt{1/m(i)})) * \\ \text{erfc}(\sqrt{(3 * \log_2(M(i)) * E_{bNOD}) / (2 * (m(i) - 1))})$$

ber\_th1 = [ber\_m1 ber];

end

ber\_th = [ber\_th1 ber\_th];

end

$E_{bNodB} = 0 : 20;$

semilogy( $E_{bNodB}$ , ber\_th(1, :), 'ro-'); hold on

semilogy( $E_{bNodB}$ , ber\_th(2, :), 'gt-'); hold on

semilogy( $E_{bNodB}$ , ber\_th(3, :), 'y.-'); hold on

semilogy( $E_{bNodB}$ , ber\_th(4, :), 'k>-'); hold on

semilogy( $E_{bNodB}$ , ber\_th(5, :), 'c<-'); hold on

semilogy( $E_{bNodB}$ , ber\_th(6, :), 'mx-'); hold on

xlabel('Eb/N0(dB)'), ylabel('BER'), axis([0 20 10^-4 10^0]);

CONCLUSION: We successfully examined the 16-Quadrature Amplitude Modulation (16-QAM) and Demodulation scheme.

We also evaluated 16 BER values for different QAM using MATLAB.

## EXPERIMENT 10

[U19CS012]

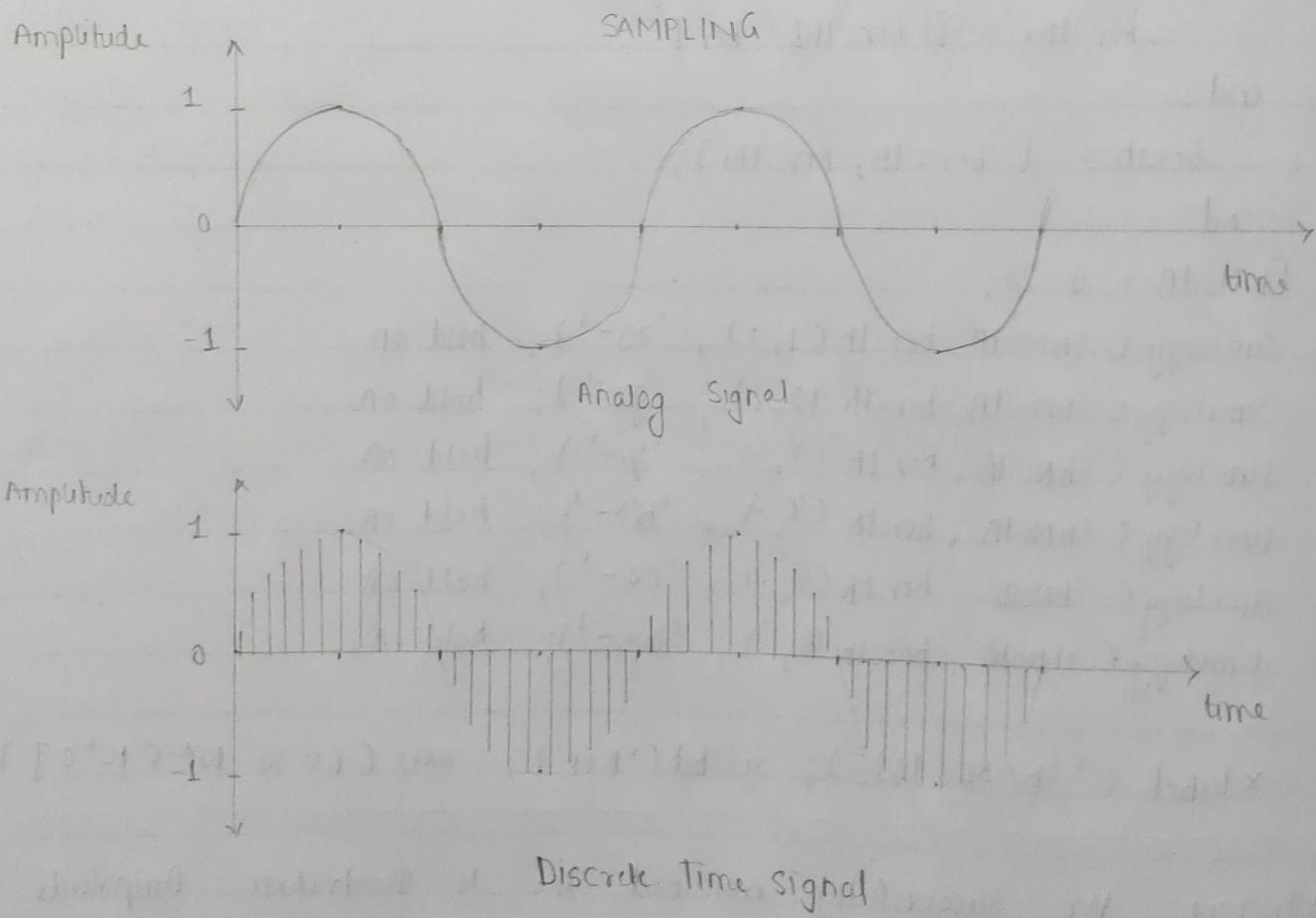
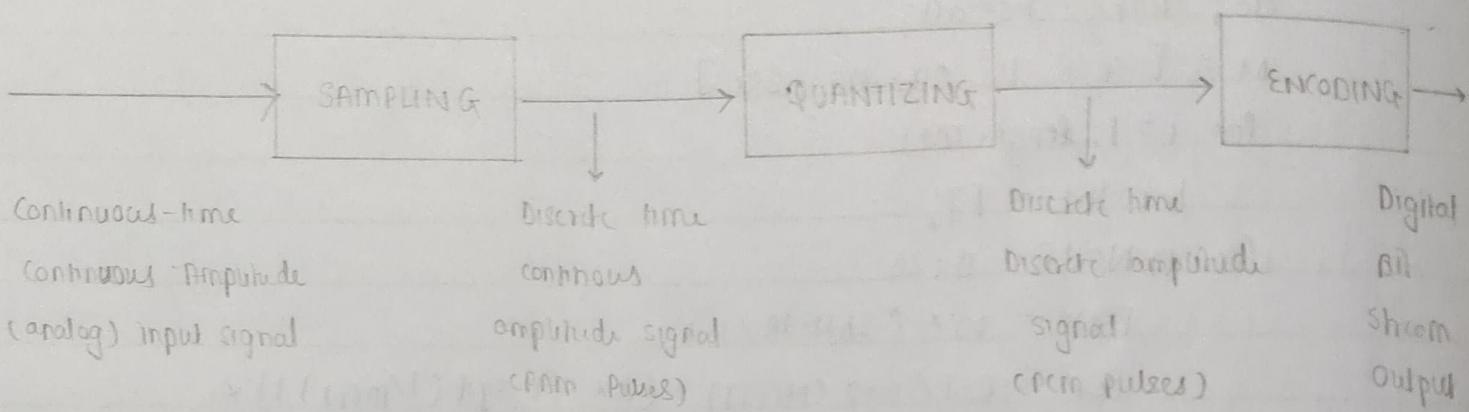
PULSE CODE MODULATION AND  
DEMODULATION

AIM: To demonstrate the pulse code modulation (PCM) and demodulation technique. To show the sampled, quantized / encoded and decoded time domain signal for different bit-codes.

SOFTWARE: MATLAB

THEORY: 1. > Pulse Code Modulation (PCM)

- PCM is a technique, which is used to convert an analog signal into digital signal.
- PCM is a preferred method of communication within public switched telephone network (PSTN).
- A PCM stream is determined by two following steps:
  - a) Sampling Rate: which the number of times per second that samples are taken.
  - b) Bit depth: which determines the number of possible digital values that can be used to represent each sample.
- Hence, the output of PCM resembles a binary sequence.



## 2.) Reasons for Digital Transmission

- Less susceptible to interference cause by noise due to discrete level.
- Easy to detect errors due to discrete levels
- Easy to encrypt (Higher Security)
- Simpler to store digital data

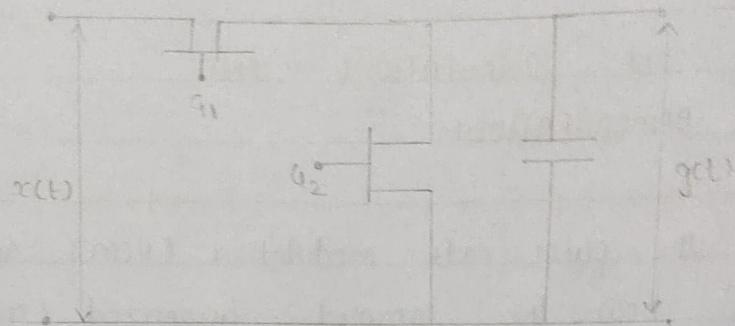
## 3.) Sampling

- Sampler extract samples of a continuous signal.
- Sampler produces samples that are equivalent to the instantaneous value of the continuous signal at the specified various points.
- The sampling process generates Flat-top Pulse Amplitude modulated (PAM) signal.

## 4.) Quantization

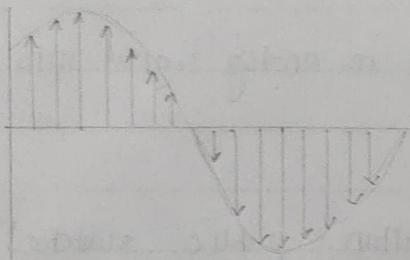
- Quantization is done by dividing the range of possible values of the analog samples into some different levels and assigning the center value of each level to any sample in the quantization interval.
- Quantization approximates the analog signal values with the nearest quantization values.

## Flat-top PAM



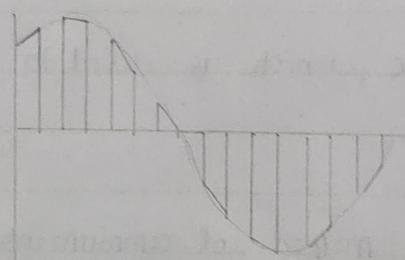
### Instantaneous Sampling

It is not practical method  
Sample rate = infinity



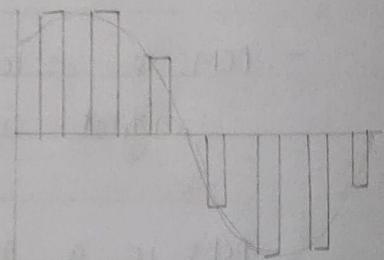
### Natural Sampling

This method is used practically  
Sample rate satisfied Nyquist



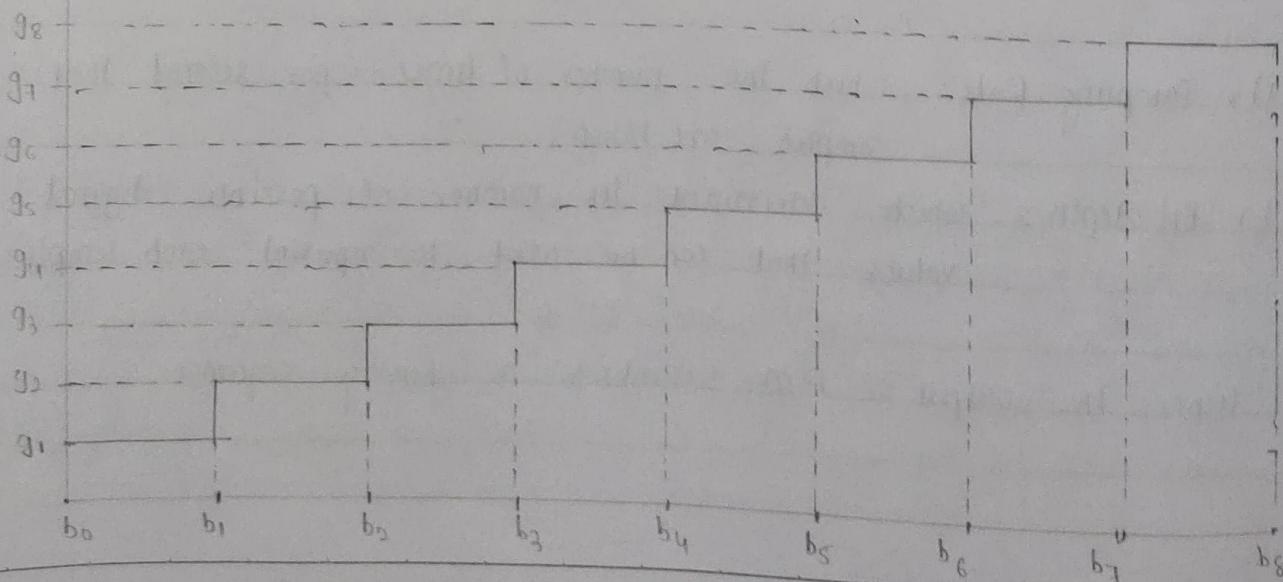
### Flat-top Sampling

This is also used practically  
Sample rate satisfied Nyquist



### Uniformly Quantized Signal

A/D output =  $n$  bits per sample (quantization level  $M = 2^n$ )



5.) Pulse Code Modulation (PCM) is a method of converting an Analog signal into a digital signal. (A/D conversion)

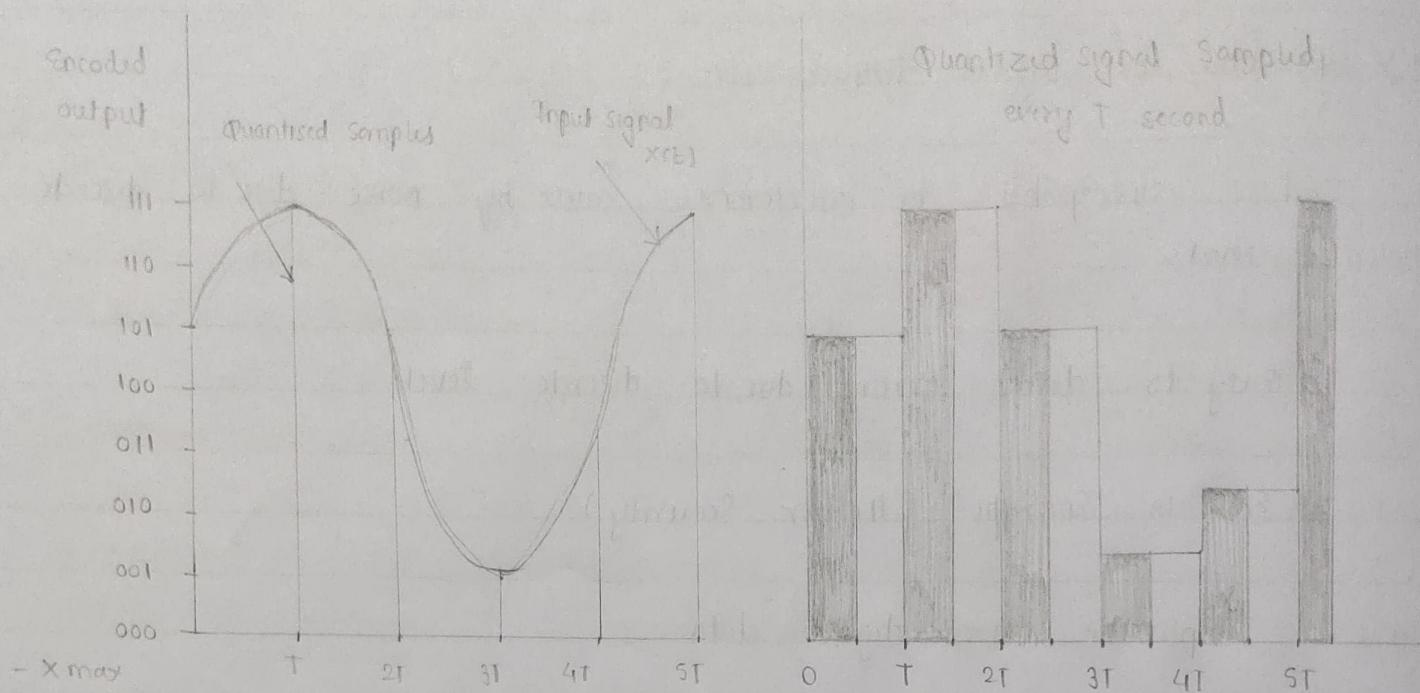
- PCM produces a series of number or digits instead of pulse train.
- Each one of these digits, in binary code, represents the approximate amplitude of the signal sample at that instant.

#### 6.) Concluding Remark for PCM

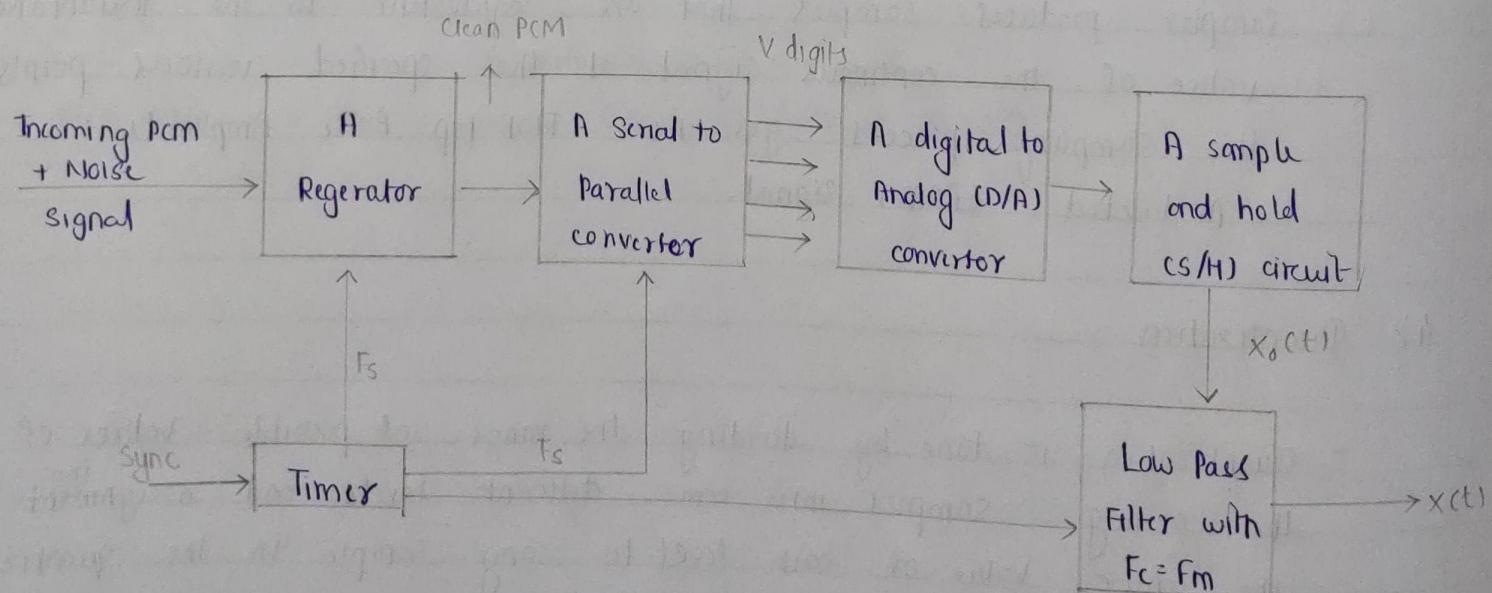
- In PCM Transmitter, the signal  $x(t)$  is first passed through the low pass filter of cut-off frequency  $F_m$  Hz.
- This low pass filter blocks all the Frequency components above  $F_m$  Hz. This means that now the signal  $x(t)$  is band-limited to  $F_m$  Hz.
- The Sample and Hold circuit then samples this signal at the rate of  $F_s$ .
- Sampling Frequency  $F_s$  is selected sufficiently above Nyquist rate to avoid Aliasing.
- The Output from sample and hold circuit is denoted by  $x(nT_s)$

## Transmitter

Figure: ↓ Quantization of a sampled Analog signal



## PCM Receiver



- This signal  $x(nT)$  is discrete in time and continuous in Amplitude
- A  $q$ -level quantizer compares input  $x(nT)$  with its fixed digital levels.
- Quantized signal is then encoded in PCM output using encoder.

### 7.) PCM Standards

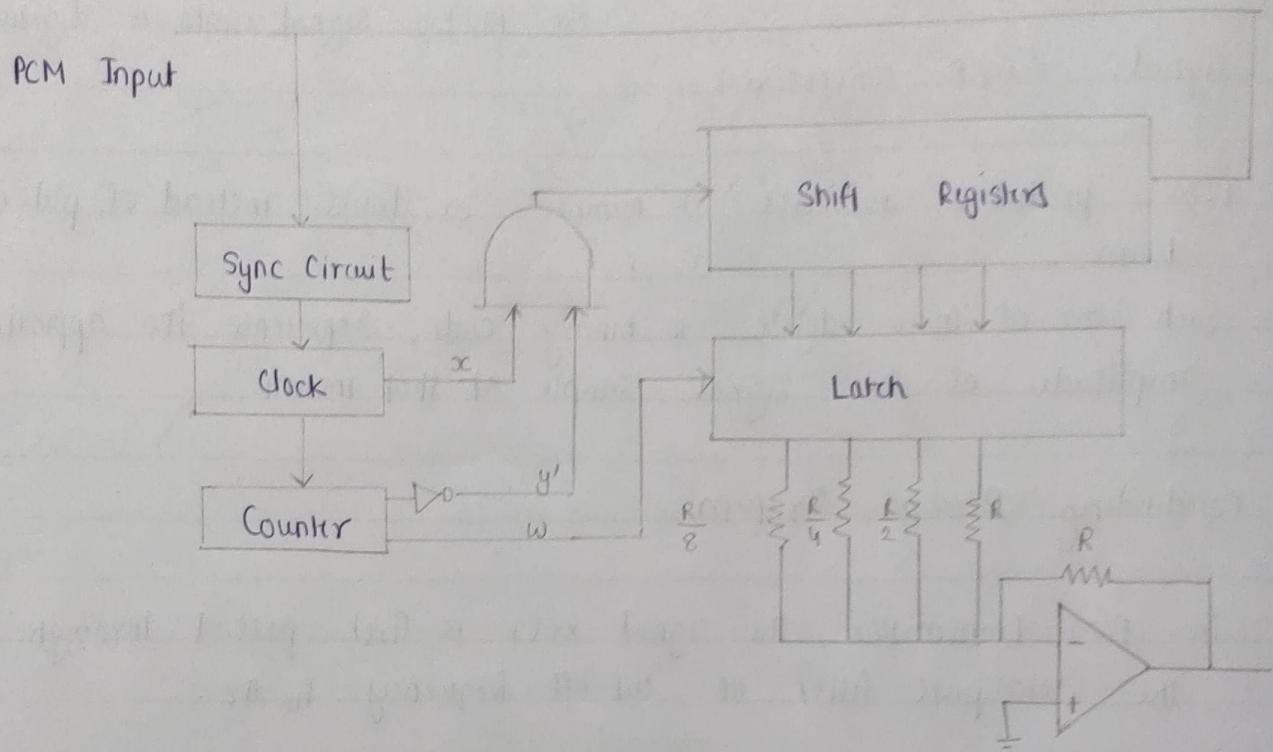
- There are two standards of PCM
  - ① The European standard
  - ② The American standard
- They differ slightly in the detail of their working but the principles are the same.
- European PCM = 30 channels
- North American PCM = 24 channels
- Japanese PCM = 24 channels

In India, we follow the European PCM of 30 channels system working.

### 8.) Applications

- In Compact Discs
- Digital Telephony
- Digital Audio Applications

## PCM Demodulator



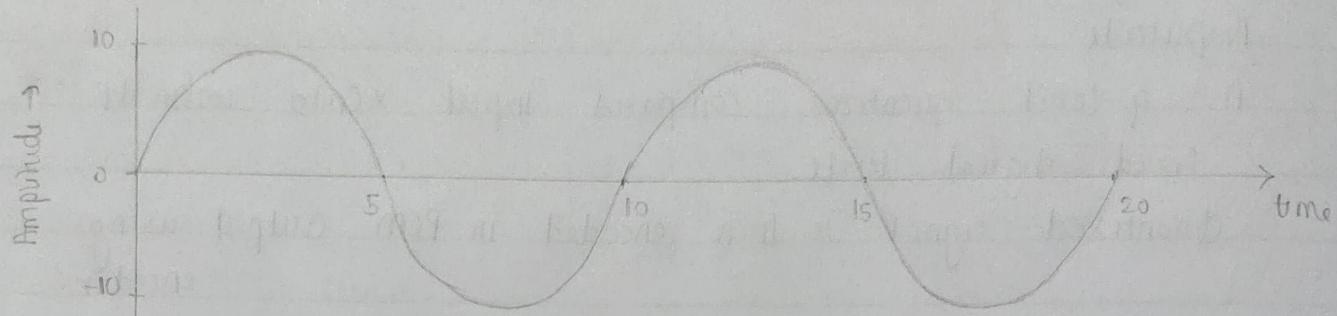
## MATLAB CODE : ① Sampling

```
n = input('Enter n value for n-bit PCM system: ');
n1 = input('Enter number of samples in a period: ');
L = 2^n;

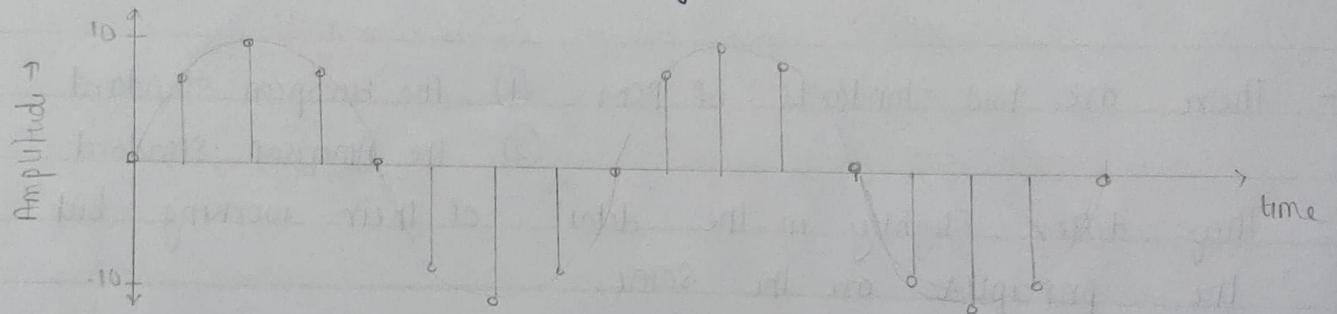
% // Signal generation
x = 0:1/100:4*pi;
y = 8 * sinc(x);
subplot(2,2,1);
plot(x,y); grid on;

% SAMPLING OPERATION
x = 0:2*pi/n1:4*pi;
s = 8 * sinc(x);
subplot(3,1,1);
plot(s);
title('Analog Signal');
ylabel('Amplitude ->');
xlabel('Time ->');

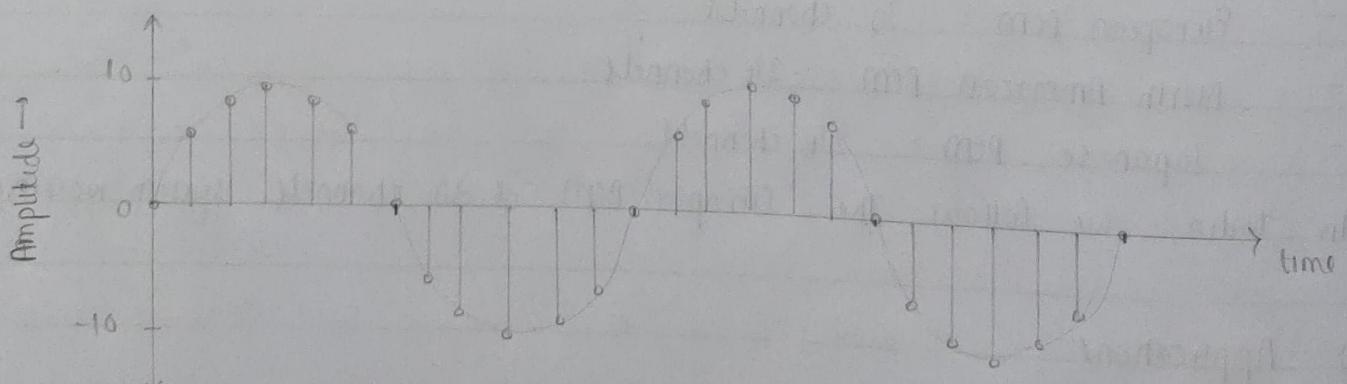
subplot(3,1,2);
stem(s);
grid on;
title('Sampled Signal');
ylabel('Amplitude ->');
xlabel('Time ->');
```

Outputs from MATLAB

Analog Signal ↑



Sampled Signal (↑)



Quantized Signal

## ② Quantization Process

$$V_{\max} = 8$$

$$V_{\min} = -V_{\max}; \quad \% \text{ level are between } V_{\min} \text{ & } V_{\max} \text{ with diff del}$$

$$\text{del} = (V_{\max} - V_{\min}) / L;$$

$$\text{part} = V_{\min} : \text{del} : V_{\max};$$

$$\text{code} = V_{\min} - (\text{del}/2) : \text{del} : V_{\max} + (\text{del}/2);$$

[ind, q] = quantiz ( s, part, code );  $\quad \% \text{ quantization Process}$

$$l_1 = \text{length}(ind);$$

$$l_2 = \text{length}(q);$$

for i=1: l1  $\quad \% \text{ to make index as binary decimal so started from}$

if (ind(i) ~= 0)

$$\text{ind}(i) = \text{ind}(i) - 1;$$

end

i = i + 1;

end

for i=1: l2  $\quad \% \text{ to make quantize value in between l1l}$

if ( q(i) == Vmin - (del/2) )

$$q(i) = Vmin + (del/2);$$

end

subplot(3,1,3);

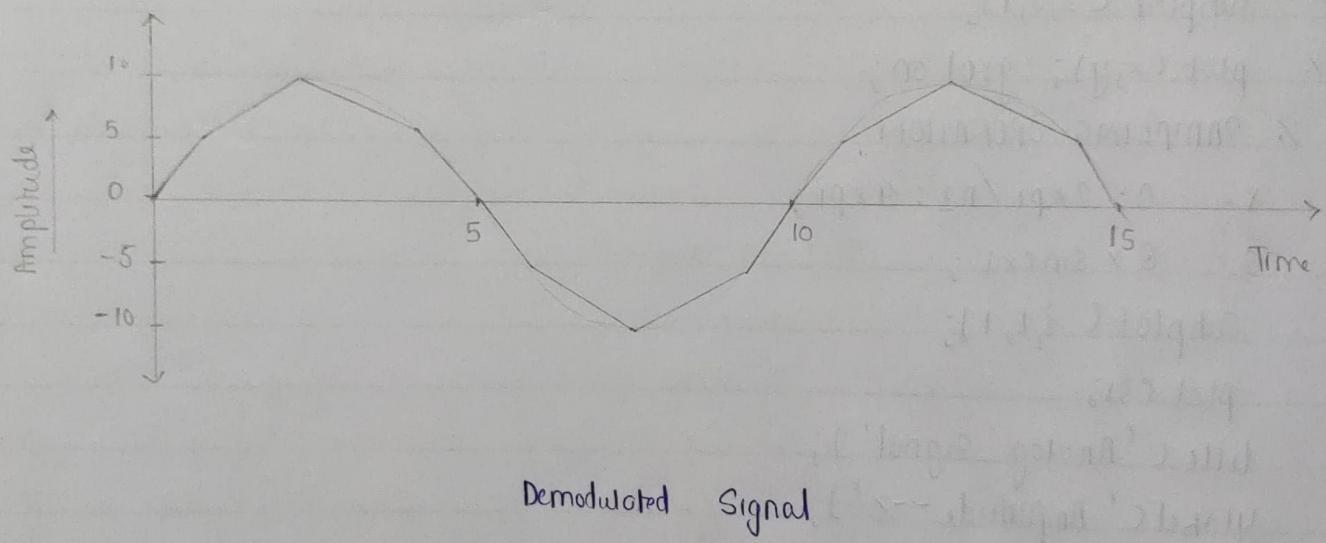
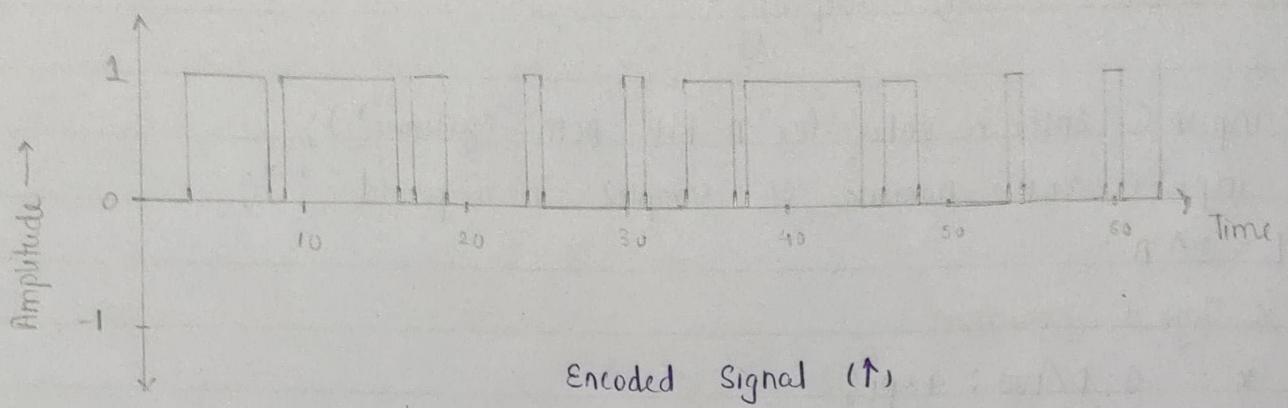
$\quad \% \text{ Display quantize values}$

stem(q); grid on;

title('Quantized Signal');

ylabel('Amplitude ->');

xlabel('Time ->');



### ③ Encoding

#### 1. Encoding Process

figure

```
code = dec2bin(ind, 'left-msb'); % convert decimal to binary
```

```
k=1;
```

```
for i=1: l1
```

```
    for j=1:n
```

```
        coded(k) = code(i,j); % convert code matrix to coded row
```

```
        j=j+1;
```

```
        k=k+1;
```

```
    end
```

```
    i=i+1;
```

```
end
```

```
subplot(2,1,1); grid on;
```

```
stairs(coded);
```

```
axis([0 100 -2 3]); % Display the encoded signal
```

```
title('Encoded Signal');
```

```
ylabel('Amplitude -->');
```

```
xlabel('Time -->');
```

[U19CS012]

## (4) Demodulation of PCM signal

```
quant = reshape ( coded, n, length(coded)/n );
index = bi2de ( quant', 'left-msb' ); % get back index in decimal
q = del * index + Vmin + ( dd/2 ); % get back quantized values
subplot ( 2, 1, 2 );
plot ( q );
title ( 'Demodulated Signal' ); % Plot Demodulated Signal
ylabel ( 'Amplitude ->' );
xlabel ( 'Time ->' );
```

- > CONCLUSION: (1) We successfully demonstrated the Pulse Code Modulation (PCM) and demodulation technique.
- (2) We observed block diagrams for receiver and transmitter of PCM signals. In later stage we also observed demodulation circuit which consist of Shift Registers, Latch and opamp.
- (3) In the last phase, we executed MATLAB code and observed sampling, quantization, Encoding and Demodulation wave and drawn them.

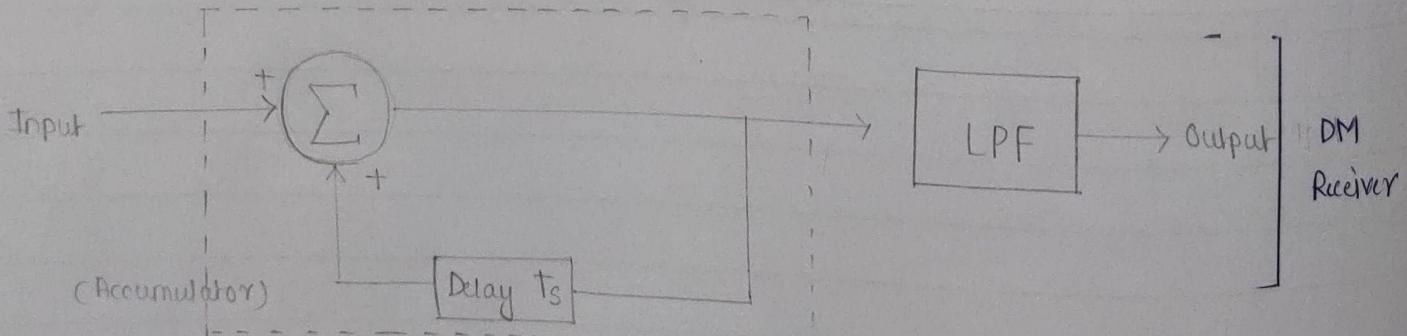
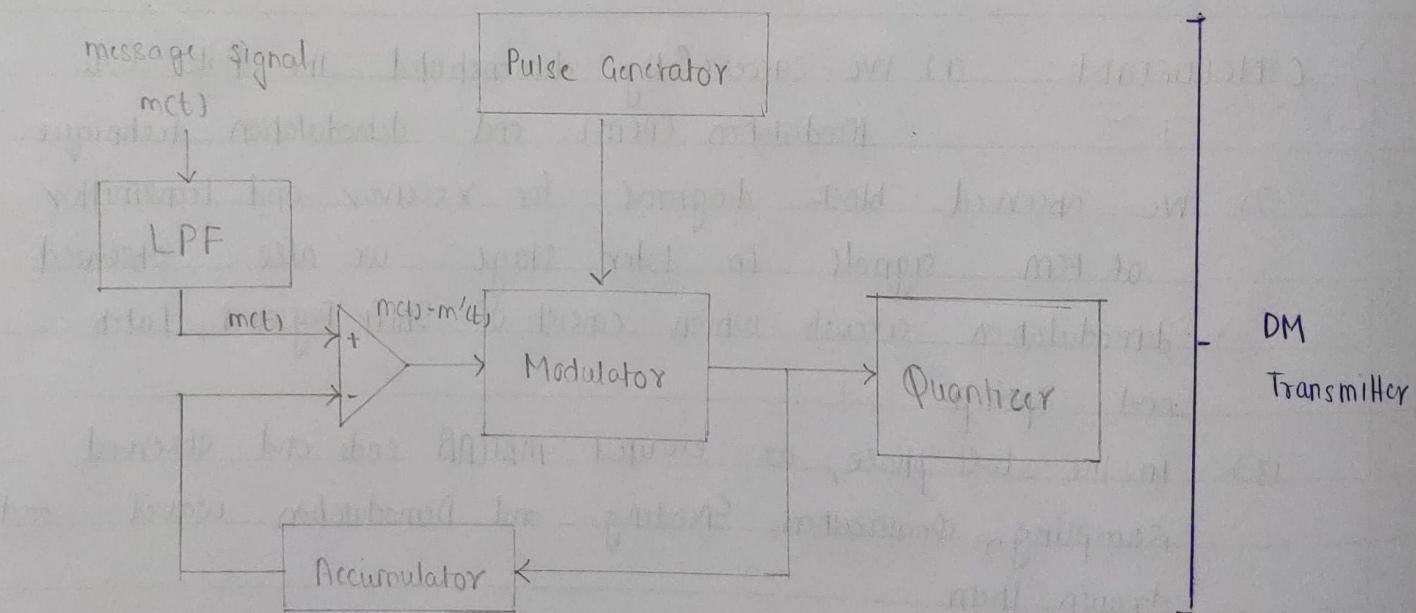
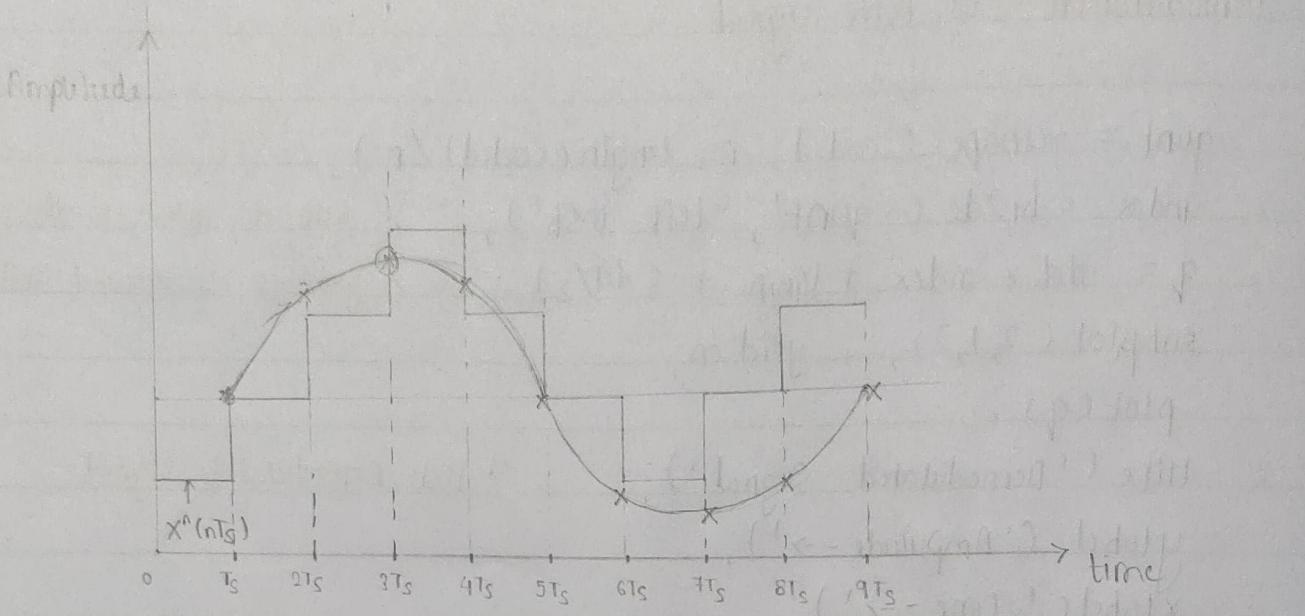
x

## EXPERIMENT - 11

[U19CS012]

## DELTA MODULATION

- AIM: To demonstrate the delta modulation (DM) and demodulation technique.
- SOFTWARE: MATLAB
- THEORY: ① Delta Modulation
- It is a technique used to convert analog-to-digital and digital-to-analog signal.
  - In this modulation signal is sent in differential form, the data is encrypted/transmitted in 1 bit.
  - The analog signal is approximated with series of segments and each segment is compared to original analog to determine the change in relative Amplitude.
  - Hence, only changes in information is sent and if no change occurs it remains on the same state.
  - This is the simplified form of Differential Pulse Code Modulation and also called as 1 bit (2 level) version of DPCM.
  - It provides a staircase approximation of over-sampled base-band signal. Here, the difference between the present sample and



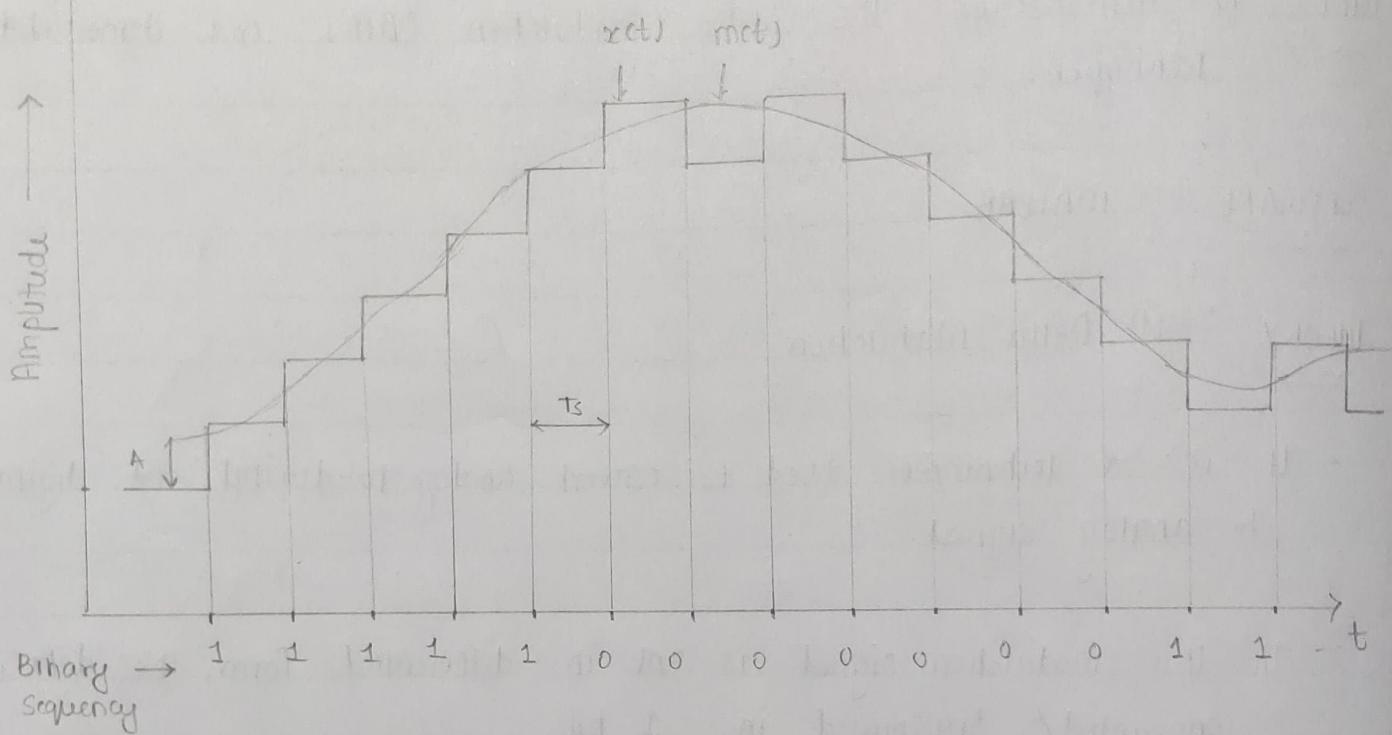
previous approximate sample is quantized into two levels i.e  $\Delta$  (delta).

- This is used for voice transmission.

## 2.7 Operating Principle

- The operating principle of DPCM is such that, a comparison between present and previously sampled value is performed, the difference of which decides the increment or decrement in the transmitted values.
- When the two sample values are compared, either we get difference having a positive polarity or negative polarity.
- If the difference polarity is positive, then the step of the signal denoted by  $\Delta$  is increased by 1. As against in case when difference polarity is negative then step of the signal is decreased i.e. reduction in  $\Delta$ .
- When  $+\Delta$  is noticed i.e. increase in step size, then 1 is transmitted. However, in case of  $-\Delta$  i.e. decrease in step size, 0 is transmitted.

## Waveform Representation of Delta modulated Signal



### 3) Advantages of Delta Modulation

- Due to transmission of 1 bit per sample, it permits low channel bandwidth as well as signaling rate.
- ADC is not required. Thus permits easy generation and detection.

### 4) Disadvantages of Delta Modulation

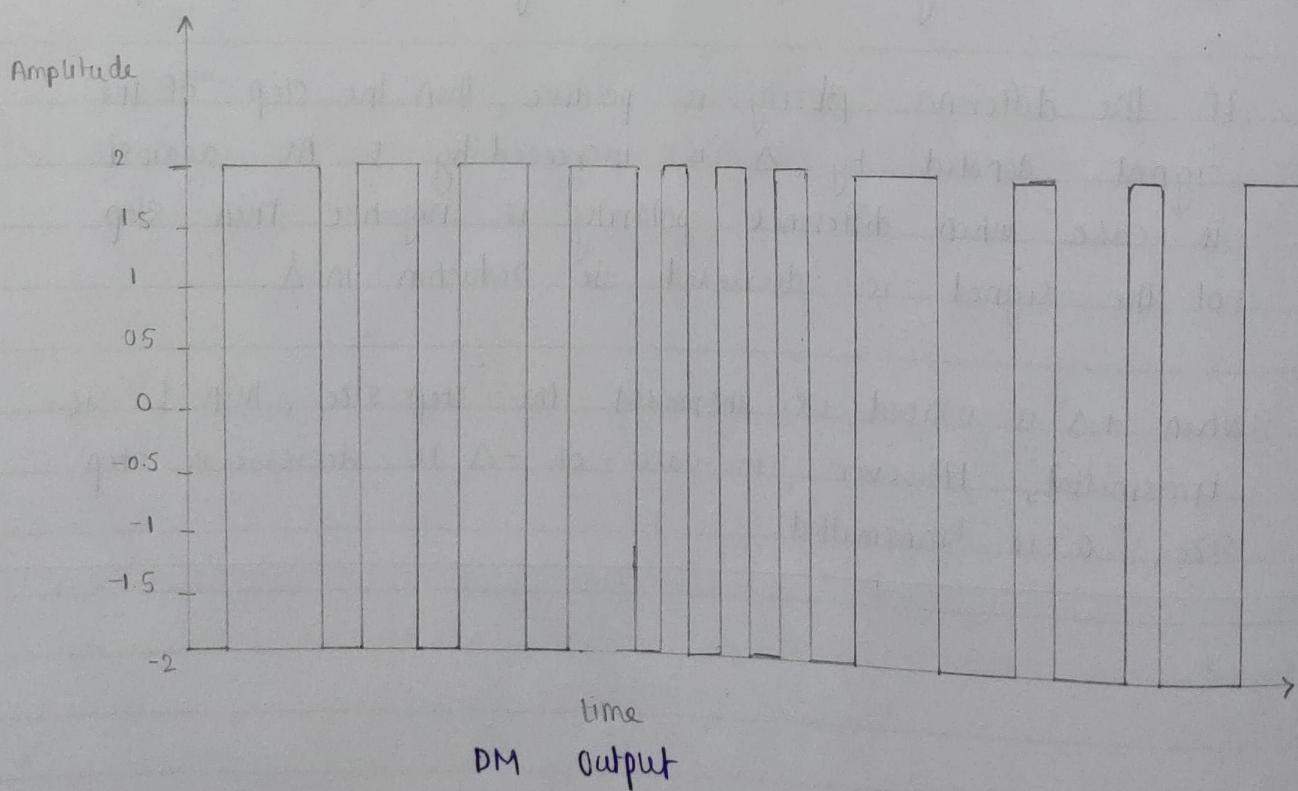
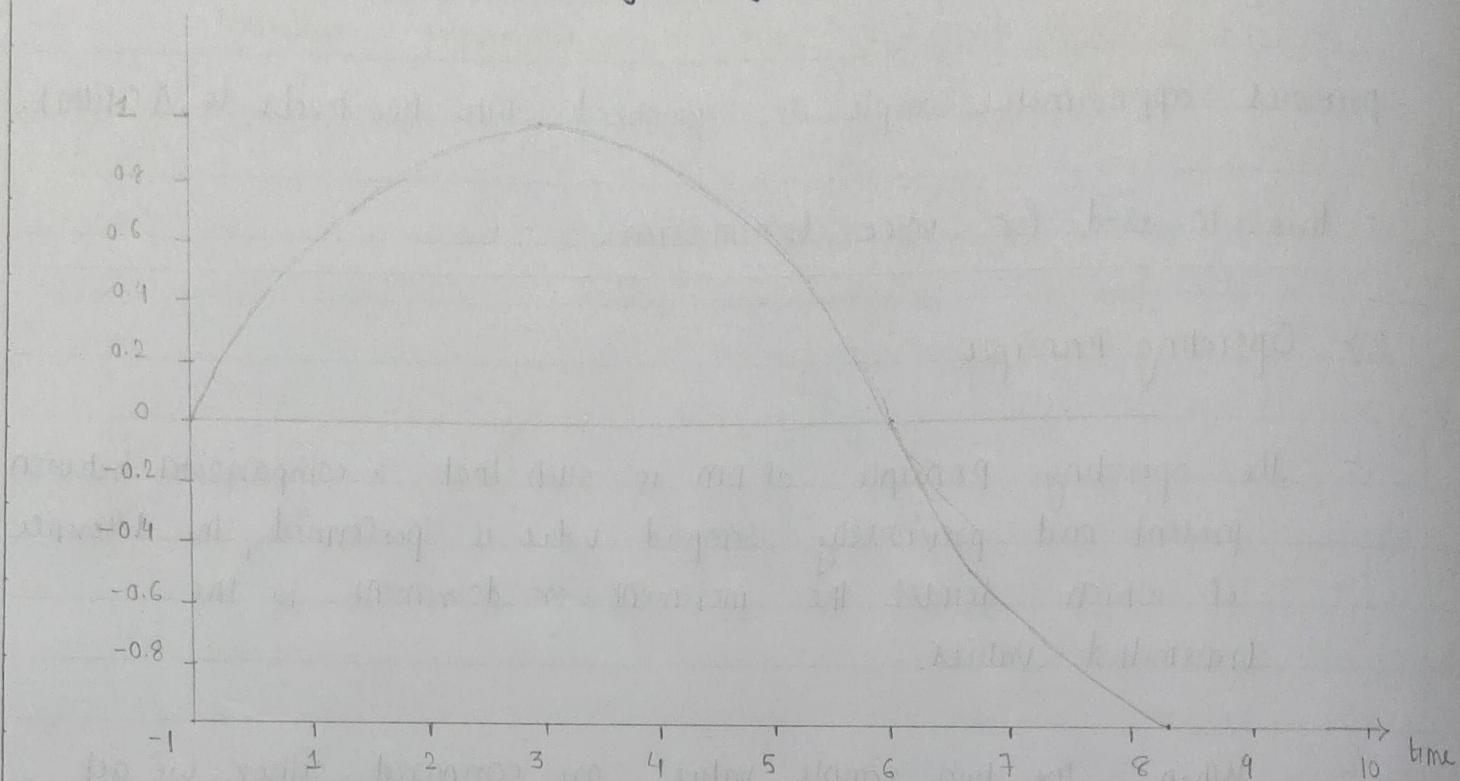
- Delta modulation leads to drawbacks such as slope overload distortion (when  $\Delta$  is small) and granular noise (when  $\Delta$  is large).

### 5) Application of Delta Modulation

- It is widely used in radio communication devices and digital voice storage and voice transmission.

(6)

original signal



## 6) MATLAB CODE :

% % Delta Modulation (DM)

predictor = [0 1];

partition = [-1:1:9];

step = 0.2

partition = [0]

codebook = [-1 \* step step];

% DM Quantizer

t = [0: pi/20 : 2\*pi];

x = 1.1 \* sinc(2\*pi\*x 0.1\*t); % Analog Signal

% Quantize x(t) using DPCM

encoded\_x = dpcmenco (x, codebook, partition, predictor);

% Try to recover x from modulated signal

decoded\_x = dpcmdeco ( encoded\_x, codebook, predictor);

% Plots

figure

plot(t, x);

xlabel('time');

title('original signal');

figure

stairs (t, 10.\*codebook (encoded\_x +1). 'g');

xlabel('time');

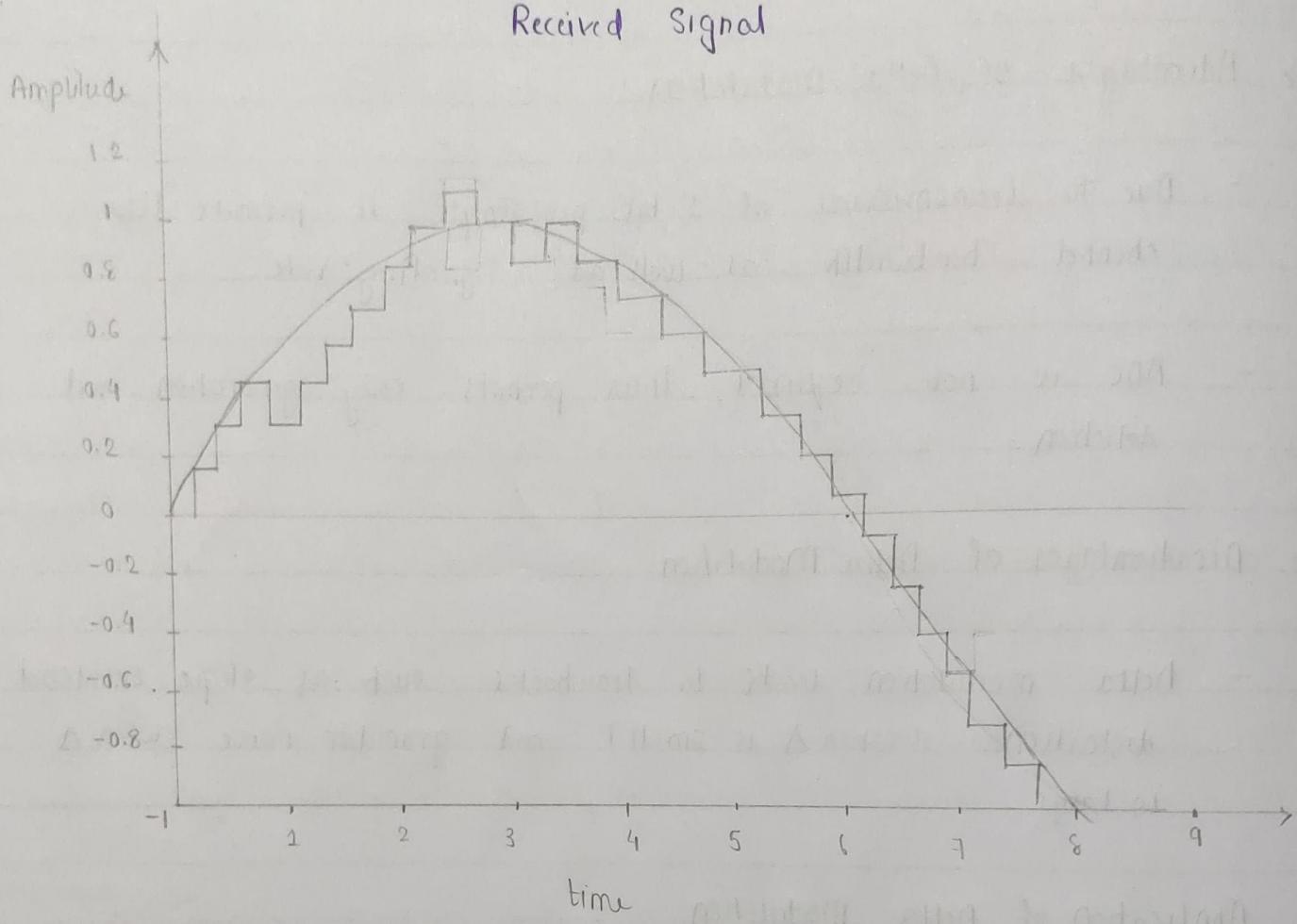
title('dm output');

figure

plot(t, x)

hold;

## Received Signal



[U19CS012]

stairs( t, decoded\_x );

grid;

xlabel ('time');

title ('received signal');

CONCLUSION: We have successfully understood and demonstrated the delta modulation (DM) and demodulation technique. and also verified it with sampled, quantized / encoded and decoded time domain signal using MATLAB in virtual LAB mode.

X

END OF DCOM JOURNAL

SUBMITTED BY:

BHAGYA

VINOD

RANI

[U19CS012]

[A-Div]

[D-12]

C. S. E, SVNIT (2<sup>nd</sup> yr)