(BHAGRA RANA (VIACSOIL) (25) Robot Navigation 95.7 Two stuge Neuro-Fuzzy stystem Sensor first stage Neural Net Head Inpu Run sursay Argy neural nework output by experim Left dor -> Second stage Front obe Auzzy system 1) Newral network is Pight ou bained accordingly (MSE) mean square 1 make adjustment in Neura Netugle vision