

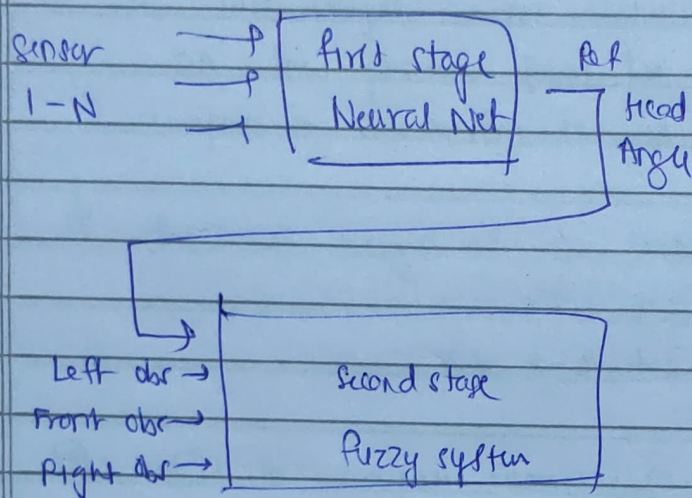
(BHAGYAKANA)

(Date: 01/12/21)

(Q5) Robot Navigation

Q5.7

Two stage Neuro-Fuzzy system



① Input from sensor

↓
Neural network

② Output by experim^{ent}

③ Neural network is trained accordingly

(MSE) mean square error

④ make adjustment in Neural Network