

**Operations Research (Paper III)**  
**MSc. (Computer Science) Semester III 2022-23**

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**Practical 1**

**Aim:** Use graphical method to solve the following LPP:

$$\text{Max } Z = 3x + 5y$$

w.r.t.

$$x + 2y \leq 2000,$$

$$x + y \leq 1500,$$

$$y \leq 600, x, y \geq$$

0

## Source Code:

```
require(lpSolv)

e) C <- c(3, 5)

A <- matrix(c(1, 2,
              1, 1,
              0, 1), nrow = 3, byrow =

T) B <- c(2000, 1500, 600)

constraint_direction <- c("<=", "<=",

"<=")

plot.new()
plot.window(xlim = c(0, 2000), ylim = c(0,
2000)) axis(1) axis(2)
title(main = "LPP using graphical method", xlab = "X-axis",
ylab = "Yaxis") box()

segments(x0 = 2000, y0 = 0, x1 = 0, y1 = 1000, col =
"green") segments(x0 = 1500, y0 = 0, x1 = 0, y1 = 1500,
col = "red") segments(x0 = 0, y0 = 0, x1 = 600, y1 = 0,
col = "blue") z <- lp(direction = "max",
      objective.in = C,
const.mat = A,      const.dir =
constraint_direction,
const.rhs = B,      all.int = T
) print(z$status)

best_sol <- z$solution names(best_sol) <-
c("x1", "x2") print(paste("Total cost: ",
z$objval, sep = ""))
```

## Output:

```

> # Use graphical method to solve the following LPP:
> # Max z = 3x + 5y
> # w.r.t
> # x + 2y ≤ 2000,
> # x + y ≤ 1500,
> # y ≤ 600,
> # x, y ≥ 0
>
> require(lpSolve)
>
> C ← c(3, 5)
>
> A ← matrix(c(1, 2,
+             1, 1,
+             0, 1), nrow = 3, byrow = T)
>
> B ← c(2000, 1500, 600)
>
> constraint_direction ← c("≤", "≤", "≤")
>
> plot.new()
> plot.window(xlim = c(0, 2000), ylim = c(0, 2000))
> axis(1)
> axis(2)
> title(main = "LPP using graphical method", xlab = "X-axis", ylab = "Y-axis")
> box()
>
> segments(x0 = 2000, y0 = 0, x1 = 0, y1 = 1000, col = "green")
> segments(x0 = 1500, y0 = 0, x1 = 0, y1 = 1500, col = "red")
> segments(x0 = 0, y0 = 0, x1 = 600, y1 = 0, col = "blue")
>
> z ← lp(direction = "max",
+        objective.in = C,
+        const.mat = A,
+        const.dir = constraint_direction,
+        const.rhs = B,
+        all.int = T
+        )
>
> print(z$status)
[1] 0
>
> best_sol ← z$solution
> names(best_sol) ← c("x1", "x2")

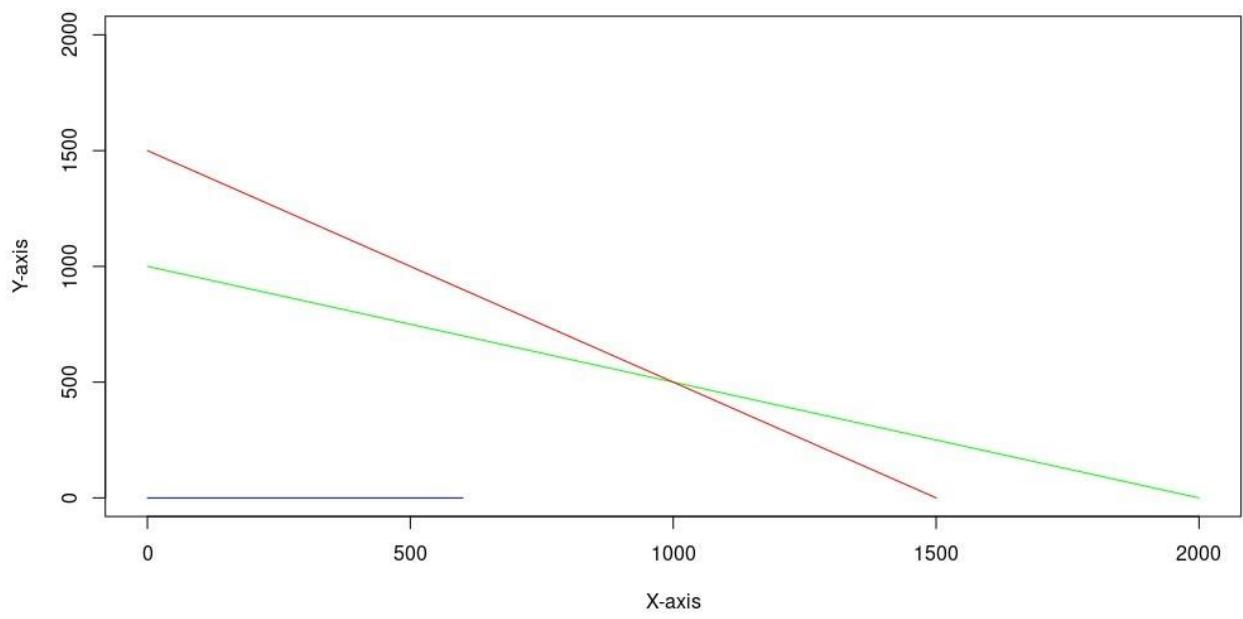
```

```

> best_sol ← z$solution
> names(best_sol) ← c("x1", "x2")
> print(paste("Total cost: ", z$objval, sep = ""))
[1] "Total cost: 5500"
>

```

### LPP using graphical method



**Aim:** Use simplex method to solve the following LPP:

## Practical 2

$$\text{Max } Z = 3x + 2y$$

w.r.t.

$$x + y \leq 4,$$

$$x - y \leq 2,$$

$$x, y \geq 0$$

**Source Code:**

```
from scipy.optimize import linprog

obj = [-3, -2] lhs_ineq =
[[1, 1], [1, -1]] In[1]:
rhs_ineq = [4, 2] bound = [(0,
float("inf")), (0, float("inf"))]

z = linprog(c = obj, A_ub = lhs_ineq, b_ub = rhs_ineq,
bounds = bound, method = "revised simplex") In[2]:

z

print(z.fun)
In[3]:
print(z.success)
print(z.x)
```

## Output:

```
In [1]: 1 from scipy.optimize import linprog
2
3 obj = [-3, -2]
4 lhs_ineq = [[1, 1],
5             [1, -1]]
6
7 rhs_ineq = [4,
8             2]
9
10 bound = [(0, float("inf")),
11           (0, float("inf"))]

In [2]: 1 z = linprog(c = obj, A_ub = lhs_ineq, b_ub = rhs_ineq,
2             bounds = bound, method = "revised simplex")
3
4 z

Out[2]: con: array([], dtype=float64)
fun: -11.0
message: 'Optimization terminated successfully.'
nit: 2
slack: array([0., 0.])
status: 0
success: True
x: array([3., 1.])

In [3]: 1 print(z.fun)
2 print(z.success)
3 print(z.x)

-11.0
True
[3. 1.]
```

## Practical 3

$$\text{Min } Z = x_1 - 3x_2 + 2x_3$$

w.r.t

$$3x_1 - x_2 + 3x_3 \leq 7,$$

$$-2x_1 + 4x_2 \leq 12, -4x_1$$

$$+ 3x_2 + 8x_3 \leq 10, x_1,$$

$$x_2, x_3 \geq 0$$

## Source Code:

**Aim:** Use simplex method to solve the following LPP:

```
from scipy.optimize import linprog
```

```
obj = [1, -3, 2]
```

```
lhs_ineq = [[3, -1, 3],  
            [-2, 4, 0],  
            [-4, 3, 8]]
```

In [1]:

```
rhs_ineq = [7,  
            12,  
            10]
```

```
bound = [(0, float("inf")),  
         (0, float("inf")),  
         (0, float("inf"))]
```

```
z = linprog(c = obj, A_ub = lhs_ineq, b_ub =  
rhs_ineq, In [2]:      bounds = bound, method = "revised  
simplex") z
```

## Output:

```
In [1]: 1 from scipy.optimize import linprog
2
3 obj = [1, -3, 2]
4
5 lhs_ineq = [[3, -1, 3],
6             [-2, 4, 0],
7             [-4, 3, 8]]
8
9 rhs_ineq = [7,
10            12,
11            10]
12
13 bound = [(0, float("inf")),
14          (0, float("inf")),
15          (0, float("inf"))]

In [2]: 1 z = linprog(c = obj, A_ub = lhs_ineq, b_ub = rhs_ineq,
2             bounds = bound, method = "revised simplex")
3
4 z

Out[2]: con: array([], dtype=float64)
fun: -11.0
message: 'Optimization terminated successfully.'
nit: 2
slack: array([ 0.,  0., 11.])
status: 0
success: True
x: array([4., 5., 0.])
```

## Practical 4

$$\text{Max } Z = x + 2y$$

w.r.t.

$$2x + y \leq 20,$$

$$-4x + 5y \leq 10,$$

$$-x + 2y \geq -2, -x$$

$$+ 5y = 15, x, y \geq$$

$$0$$

## Source code:



**Aim:** Use simplex method to solve the following LPP:

```
from scipy.optimize import linprog
```

```
obj = [-1, -2]
```

```
lhs_ineq = [[2, 1],  
            [-4, 5],  
            [1, -2]]
```

```
rhs_ineq = [20,
```

In [1]:

```
        10,  
        2]
```

```
lhs_eq = [[-1, 5]]
```

```
rhs_eq = [15]
```

```
bound = [(0, float("inf")),  
         (0, float("inf"))]
```

```
z = linprog(c = obj, A_ub = lhs_ineq, b_ub =  
rhs_ineq,
```

```
        A_eq = lhs_eq, b_eq = rhs_eq,
```

In [2]:

```
        bounds = bound, method = "revised simplex")
```

```
z
```

## Output:

```
In [1]: 1 from scipy.optimize import linprog
2
3 obj = [-1, -2]
4
5 lhs_ineq = [[2, 1],
6             [-4, 5],
7             [1, -2]]
8
9 rhs_ineq = [20,
10            10,
11            2]
12
13 lhs_eq = [[-1, 5]]
14 rhs_eq = [15]
15
16 bound = [(0, float("inf")),
17           (0, float("inf"))]

In [2]: 1 z = linprog(c = obj, A_ub = lhs_ineq, b_ub = rhs_ineq,
2             A_eq = lhs_eq, b_eq = rhs_eq,
3             bounds = bound, method = "revised simplex")
4
5 z

Out[2]: con: array([0.])
fun: -16.818181818181817
message: 'Optimization terminated successfully.'
nit: 3
slack: array([ 0.          , 18.18181818,  3.36363636])
status: 0
success: True
x: array([7.72727273, 4.54545455])
```

**Aim:**

## Practical 5

Use Big M method to solve the following LPP:

$$\text{Min } Z = 4x_1 + x_2$$

w.r.t.

$$3x_1 + 4x_2 \geq 12,$$

$$x_1 + 5x_2 \geq 15,$$

$$x_1, x_2 \geq 0$$

**Source code:**

```
from scipy.optimize import linprog
```

```
obj = [4, 1]
```

```
lhs_ineq = [[-3, -4],  
            [-1, -5]]
```

In [1]:

```
rhs_ineq = [-20,  
            -15]
```

```
bound = [(0, float("inf")),  
         (0, float("inf"))]
```

```
opt = linprog(c=obj,A_ub=lhs_ineq,b_ub=rhs_ineq,  
bounds=bound,method="interior-point") In [2]:
```

## Output:

opt

```
In [1]: 1 from scipy.optimize import linprog
2
3 obj = [4, 1]
4 lhs_ineq = [[-3, -4],
5             [-1, -5]]
6
7 rhs_ineq = [-20,
8             -15]
9
10 bound = [(0, float("inf")),
11           (0, float("inf"))]

In [2]: 1 opt =linprog(c=obj,A_ub=lhs_ineq,b_ub=rhs_ineq,
2                  bounds=bound,method="interior-point")
3
4 opt

Out[2]:      con: array([], dtype=float64)
      fun: 5.0000000002364455
      message: 'Optimization terminated successfully.'
      nit: 5
      slack: array([1.64270375e-10, 1.00000000e+01])
      status: 0
      success: True
      x: array([6.01160437e-11, 5.00000000e+00])
```

## Practical 6

Use any method to solve the following resource allocation problem:

Max  $Z = 20x_1 + 12x_2 + 50x_3 + 25x_4$  .....(profit)  
w.r.t.  $x_1 + x_2 + x_3 + x_4 \leq 50$   
.....(manpower)  $3x_1 + 2x_2 + x_3 \leq 100$   
.....(material A)  $x_2 + 2x_3 \leq 90$ ,  
.....(material B)  $x_1, x_2, x_3 \geq 0$

**Aim:**

**Source code:**

```
from scipy.optimize import linprog

obj = [-20, -12, -40, -25]

lhs_ineq = [[1, 1, 1, 1],
            [3, 2, 1, 0],
            [0, 1, 2, 3]]

rhs_ineq = [50,
            100,
            90]

opt = linprog(c = obj, A_ub = lhs_ineq, b_ub =
rhs_ineq, In [2]: method="revised simplex") opt
```

## Output:

```
In [1]: 1 from scipy.optimize import linprog
2
3 obj = [-20, -12, -40, -25]
4
5 lhs_ineq = [[1, 1, 1, 1],
6             [3, 2, 1, 0],
7             [0, 1, 2, 3]]
8
9 rhs_ineq = [50,
10            100,
11            90]
```

```
In [2]: 1 opt = linprog(c = obj, A_ub = lhs_ineq, b_ub = rhs_ineq, method="revised simplex")
2
3 opt
```

```
Out[2]:      con: array([], dtype=float64)
         fun: -1900.0
         message: 'Optimization terminated successfully.'
         nit: 2
         slack: array([ 0., 40.,  0.])
         status: 0
         success: True
         x: array([ 5.,  0., 45.,  0.] )
```

**Aim:**

## Practical 7

Use simplex method to solve the following LPP:

$$\text{Max } Z = 200x + 300y$$

w.r.t.

$$2x + 3y \geq 1200,$$

$$x + y \leq 400, 2x$$

$$+ 1.5y \geq 900, x,$$

$$y \geq 0$$

**Source code:**

```
from scipy.optimize import linprog

obj = [-200, 300]

lhs_ineq = [[-2, -3],
            [1, 1],
            [-2, -3/2]] rhs_ineq = [-
1200, 400, -900]

bnd=[(0, float("inf")),
      (0, float("inf"))]

opt = linprog(c = obj, A_ub = lhs_ineq, b_ub = rhs_ineq,
bounds = bnd, In [2]:
            method = "revised simplex")

opt
```

## Output:

```
In [1]: 1 from scipy.optimize import linprog
2
3 obj = [-200, 300]
4
5 lhs_ineq = [[-2, -3],
6             [1, 1],
7             [-2, -3/2]]
8
9 rhs_ineq = [-1200, 400, -900]
10
11 bnd=[(0, float("inf")),
12       (0, float("inf"))]
```

```
In [2]: 1 opt = linprog(c = obj, A_ub = lhs_ineq, b_ub = rhs_ineq,
2               bounds = bnd,
3               method = "revised simplex")
4
5 opt
```

```
Out[2]: con: array([], dtype=float64)
fun: 120000.0
message: 'The problem appears infeasible, as the phase one auxiliary problem terminated successfully with a residual of
3.0e+02, greater than the tolerance 1e-12 required for the solution to be considered feasible. Consider increasing the tol
erance to be greater than 3.0e+02. If this tolerance is unacceptably large, the problem is likely infeasible.'
nit: 1
slack: array([ 0.,  0., -300.])
status: 2
success: False
x: array([ 0., 400.])
```



**Aim:****Practical 8**

Use dual simplex method to solve the following LPP:

$$\text{Max } Z = 40x_1 + 50x_2$$

w.r.t.

$$2x_1 + 3x_2 \leq 3,$$

$$8x_1 + 4x_2 \leq 5,$$

$$x_1, x_2 \geq 0$$

**Source code:**

```
require(lpSolve)
f.obj <- c(40, 50)
f.con <- matrix(c(2, 3,
                  8, 4), nrow = 2, byrow = T)
f.dir <- c("<=", "<=")
f.rhs <- c(3, 5)

lp("max", f.obj, f.con, f.dir, f.rhs)$solution
lp("max", f.obj, f.con, f.dir, f.rhs, compute.sens =
T)$sens.coef.from lp("max", f.obj, f.con, f.dir, f.rhs,
compute.sens = T)$sens.coef.to lp("max", f.obj, f.con, f.dir,
f.rhs, compute.sens = T)$duals lp("max", f.obj, f.con, f.dir,
f.rhs, compute.sens = T)$duals.to
```

## Output:

```
> # Maximize the following:
> # z = 40x1 + 50x2
> # w.r.t
> # 2x1 + 3x2 ≤ 3
> # 8x1 + 4x2 ≤ 5
> # x1, x2 ≥ 0
>
> require(lpSolve)
Loading required package: lpSolve
> f.obj ← c(40, 50)
> f.con ← matrix(c(2, 3,
+                 8, 4), nrow = 2, byrow = T)
> f.dir ← c("≤", "≤")
> f.rhs ← c(3, 5)
>
> lp("max", f.obj, f.con, f.dir, f.rhs)$solution
[1] 0.1875 0.8750
> lp("max", f.obj, f.con, f.dir, f.rhs, compute.sens = T)$sens.coef.from
[1] 33.33333 20.00000
> lp("max", f.obj, f.con, f.dir, f.rhs, compute.sens = T)$sens.coef.to
[1] 100 60
```

```
> lp("max", f.obj, f.con, f.dir, f.rhs, compute.sens = T)$duals
[1] 15.00 1.25 0.00 0.00
> lp("max", f.obj, f.con, f.dir, f.rhs, compute.sens = T)$duals.to
[1] 3.75e+00 1.20e+01 1.00e+30 1.00e+30
>
```

## Practical 9

Solve following transportation problem in which each cell represents unit costs:

	Customers				Supply
	1	2	3	4	
Suppliers	10	2	20	11	15
	12	7	9	20	25
	4	14	16	18	10
Demand	5	15	15	15	

### Source code:

```
library(lpSolve)
```

## Aim:

```
cost <- matrix(c(10, 2, 20, 11,
                12, 7, 9, 20,
                4, 14, 16, 18), nrow = 3, byrow = T)

colnames(cost) <- c("Customer 1", "Customer 2", "Customer 3",
"Customer
4")
rownames(cost) <- c("Supplier 1", "Supplier 2", "Supplier 3")

row.signs <- rep("<=", 3)
row.rhs <- c(15, 25, 10)

col.signs <- rep("<=", 4)
col.rhs <- c(5, 15, 15, 15)

total.cost <- lp.transport(cost, "min", row.signs, row.rhs,
col.signs, col.rhs) total.cost$solution print(total.cost)
```

```
> ##SOLVE FOLLOWING TRANSPORTATION PROBLEM IN WHICH CELL ENTRIES REPRESENT UNIT COSTS USING R PROGRAMMIN
G.
>
> #
> #SUPPLIER 1    10      2      20      11      15
> #SUPPLIER 2    12      7      9      20      25
> #SUPPLIER 3     4     14     16     18     10
> #DEMAND        5     15     15     15
>
> library(lpSolve)
> cost <- matrix(c(10, 2, 20, 11,
+                 12, 7, 9, 20,
+                 4, 14, 16, 18), nrow = 3, byrow = T)
>
> colnames(cost) <- c("Customer 1", "Customer 2", "Customer 3", "Customer 4")
> rownames(cost) <- c("Supplier 1", "Supplier 2", "Supplier 3")
>
> row.signs <- rep("<=", 3)
> row.rhs <- c(15, 25, 10)
>
> col.signs <- rep("<=", 4)
> col.rhs <- c(5, 15, 15, 15)
```

```
> total.cost <- lp.transport(cost, "min", row.signs, row.rhs, col.signs, col.rhs)
> total.cost$solution
      [,1] [,2] [,3] [,4]
[1,]    0    5    0   10
[2,]    0   10   15    0
[3,]    5    0    0    5
> print(total.cost)
Success: the objective function is 435
```

**Output:**

## Practical 10

Solve following assignment problem represented in this matrix:

		Jobs		
		1	2	3
Workers	1	15	10	9
	2	9	15	10
	3	10	12	8

**Source Code:**

```
library(lpSolve)

cost <- matrix(c(15, 10,
9,          9, 15,
10,
          10, 12, 8), nrow = 3, byrow = T)

cost
answer <- lp.assign(cost)
answer$solution
```

**Output:**

## Aim:

```
> #SOLVE FOLLOWING ASSIGNMENT PROBLEM REPRESENTED IN FOLLOWING MATRIX USING R PROGRAMMING
> # Assignment Problem
> #      JOB1    JOB2    JOB3
> #W1     15     10     9
> #W2     9      15     10
> #W3     10     12     8
>
> library(lpSolve)
>
> cost <- matrix(c(15, 10, 9,
+                  9, 15, 10,
+                  10, 12, 8), nrow = 3, byrow = T)
>
> cost
      [,1] [,2] [,3]
[1,]   15   10   9
[2,]    9   15  10
[3,]   10   12   8
> answer <- lp.assign(cost)
```

```
> answer ← lp.assign(cost)
> answer$solution
      [,1] [,2] [,3]
[1,]    0    1    0
[2,]    1    0    0
[3,]    0    0    1
> |
```