Robotics Mini Project

ROLL NO.: 512

AIM: Create a Robot which will move only on yellow-path in given image.

CODE:

```
import ch.aplu.robotsim.*;
public class MiniProject {
  MiniProject(){
    LegoRobot r = new LegoRobot();
    Gear g = new Gear();
    LightSensor Is = new LightSensor(SensorPort.S3);
    r.addPart(g);
    r.addPart(ls);
    g.forward();
    g.setSpeed(100);
    while(true){
      int v =ls.getValue();
      if(v >= 1000)
             g.forward();
      if(v < 1000)
             g.left();
      if(v < 100)
            g.stop();
  }
}
```

```
static {
    RobotContext.setStartPosition(430,230);
    RobotContext.useBackground("sprites/yellowpath.gif");
}
public static void main (String args[]){
    new MiniProject();
}
```

OUTPUT:

