Quasar Photo-z Research Notes

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Abstract

1 TODO

1.1 Data wrangling

- Download the DR10QSO dataset (link) to get PLATE-MJD-FIBER information. (in DES-IMCMC/data/DR10QSO)
- Download PLATE-MJD-FIBER files corresponding to quasars in DR10QSO dataset (note—these files contain red-shift, fluxes, pretty much everything spec-PLATE-MJD-FIBER files). Instructions in "optical spectra per file" section.—Script written, downloads need to happen on edison.

•

- See how the different plates sample different inputs. Sinc resample to a common basis.
- Figure out how to normalize the spectra

1.2 Implementing

• write function spectrum to flux integration:

$$f_u, f_q, f_r, f_i, f_z = g(spec) \tag{1}$$

$$= g(\mathbf{w})$$
 for spec weights/cluster \mathbf{w} (2)

where fluxes end up in nanomaggies. Verify this with a few spec-PLATE-MJD-FIBER files (which has SPECTROFLUX and SPECTROSYNFLUX)

• Implement rescaling, we have

$$f^{(rest)}(\cdot) = \ell \cdot f^{(sed)}(\cdot)$$
 s.t. $\int f^{(sed)}(d\lambda) = 1$ (3)

$$= \ell \sum w_k B_k(\cdot)$$
 s.t. $\int B_k(\cdot) = 1, \sum w_k = 1$ (4)

$$f^{(obs)}(\lambda) = \ell^{(obs)} f^{(sed)}(\lambda \cdot (1+z))$$
 red-shift rescales, but sed is invariant (5)

That is, a *luminosity-distance* value that scales the overall density, and a spectral energy density (SED) that integrates to 1.

- Implement smooth-ish LGCP prior over $B_k(\cdot)$ in pre-train optimization.
- Run the basis maximization code with these two formulations.
- Write a density estimator for the weights (or log weights) and use this in inference.

1.3 Experiments

- Basis smoothing there is no smoothing along similar frequencies. However there is clearly structure there.
 - Proper process model: try a Gaussian process with fixed covariance function maybe an OU process or a matern initially.
- Figure out an idea of the curvature at the MAP.
- Assess mixing of weights, z (and eventually basis) I think it's mixing rather slowly...
- Also, figure out what the Planck's law luminosity, temperature, radius degree of freedom issue.
- Inferences with structured prior over w's and without. Is there a difference in MSE or Δz ? A difference in Bayesian credible coverage?

1.4 Notes on SDSS data

- Spectra data access: spectra data access information
- DR10QSO, data model. Notes:
 - BOSS spectra files (latest, i believe) have spAll fields in in HDU 2 (details here)
 - The psfflux fields should carry over from the "photoObj" field types
 - the "Z" field should carry over from the "spZbest"
- Snippet of information about SPECTRO Fluxes

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SPECTROFLUX 5-element array of integrated flux in each of the 5 SDSS imaging filters (ugriz); the units are nanomaggies, which is 1 at 22.5 magnitude; convert to magnitudes with 22.5 - 2.5 * LOG_10(SPECTROFLUX);
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the u-band and z-band counts should not be used

SPECTROFLUX_IVAR: The approximate error (inverse variance) in SPECTROFLUX as measured by the sky fibers; we assign identical errors in linear flux units to all fibers on a plate.

SPECTROSYNFLUX: Same as SPECTROFLUX, but measured using the best-fit synthetic eigen-spectrum rather than the actual data points SPECTROSYNFLUX_IVAR: The approximate error (inverse variance) in SPECTROSYNFLUX as measured by the sky fibers; we assign identical errors

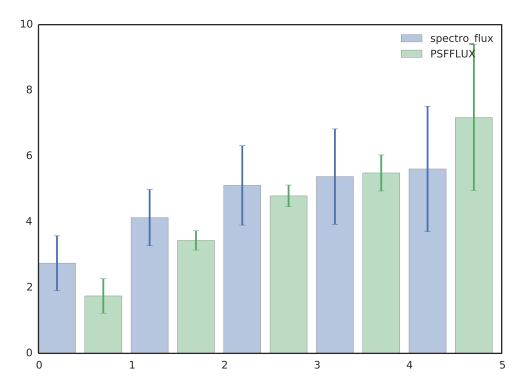
in linear flux units to all fibers on a plate.

SPECTROSKYFLUX: 5-element array of the sky flux in each of the 5 SDSS imaging filters

• SDSS Spectra are on Edison:

/project/projectdirs/cosmo/data/sdss/dr10/boss/spectro/redux/v5_5_12/spectra
And it looks like DR10Q is there too,

- .../cosmo/data/sdss/dr10/boss/qso/DR10Q/
- Note on different FLUX measurements available in the specALl files (attachd to the individual spectra)



Above is a comparison of the SPECTROSYNFLUX (+ IVAR) and the PSFFLUX (+ IVAR) with two standard errors. There is a discrepancy - which should I take as true? How are PSFFLUX measured?

2 Related work

Below is a list of astronomy references on photo-z with a brief summary of methodology/contribution.

- Benitez (2000) presents a thorough summary of Bayesian methods for photometric red-shift estimation from spectral templates (as opposed to the so called empirical method of learning a function from colors to z value, e.g. with a neural network). They set up the framework where we are given data $D = \{C, m_0\}$, the colors C (ratio of each band's magnitude to some reference band's magnitude) and the magnitude information of the reference band m_0 . The goal is then to infer the distribution p(z|D) using some prior information in the form of a spectral template library. Some interesting notes
 - The prior probability $p(z|m_0)$ should be a function of the magnitude of observations (fainter = farther a priori). They also note that this should be defined in terms of $p(z|\hat{m}_0)$, where \hat{m}_0 is the true value of that magnitude, and we observe some noisy version that needs to be integrated over.
 - They then discuss galaxy templates, T, which are essentially types of galaxies (characterized by spectral density). The fully Bayesian photo-z distribution averages over these templates

$$p(z|C, m_0) = \sum_{T} p(z, T|C, m_0)$$
(6)

$$\propto \sum_{T} p(z, T|m_0) p(C|z, T) \tag{7}$$

$$p(z,T|m_0) = p(T|m_0)p(z|T,m_0)$$
(8)

The idea is to then extend T to parameterize the types of spectra expected - basically the weights involved

$$p(z|C, m_0) = \int dS p(z, S|C, m_0)$$

$$\tag{9}$$

$$\propto \int dS p(z, S|m_0) p(C|z, S) \tag{10}$$

where S are like pca weights or other parameters of spectra. They discuss how to do this with the template idea, but not so much on the parameterization of spectra. This is the key piece of information I'm missing, and would be the novel contribution of the paper.

 They employ the template method as their likelihood. The likelihood, if I understand it correctly, looks like this

$$p(C|z,T) \propto \frac{1}{\sqrt{F_{TT}(z)}} \exp\left(-\frac{1}{2} \sum_{\alpha} \frac{(f_{\alpha} - a f_{T_{\alpha}})^2}{\sigma_{f_{\alpha}}^2}\right)$$
 (11)

where f_0, \ldots, f_{n_C} are the observed fluxes, $f_T\alpha(z)$ is the flux of the template T (I think), and a is a magnitude nuisance parameter. They then discuss different algebraic representations of this likelihood. Importantly, I think their relationship between spectral template T and likelihood p(fluxes|z,T) is sort of empirical, based on how well individual template fluxes match the observed fluxes. I think what I need is the function to go from spectral template and red shift to fluxes.

$$(f_{T,u}, f_{T,g}, \dots, f_{T,z}) = h(z,T)$$
 (12)

How is p(C|z,S) defined - this is the important part of the likelihood

or better yet, a parameterization

$$f(s,z)_{u},\dots,f(s,z)_{z} = h(z,s)$$
 (13)

where s are like PCA coefficients or other model parameters of the spectra.

 Equation 22 gives the form of the prior they use for the probability of galaxy type given magnitude of reference flux

$$p(T|m_0) = f_t \exp\left(-k_t(m_0 - 20)\right) \tag{14}$$

 Equation 23 gives the prior probability distribution over red shift given galaxy type and reference flux magnitude

$$p(z|T, m_0) (15)$$

• Budavari et al. (2001) and companion paper Richards et al. (2001) goes into specific detail for SED model based photometric redshifts for quasars. They compare a bunch of methods. In particular, Budavari et al. (2001) describes an algorithm for reconstruction a quasar spectrum template from photometric observations and spectroscopic redshifts. It seems sorta like a dynamic K-means/EM algorithm (they add spectral types as needed), and does a decent job reconstructing bumps where the emission lines are.

The algorithm is: start with a collection of initial spectral templates (I believe these are rest frame.) $\psi_1(\lambda), \dots \psi_K(\lambda)$

- 1. Categorize all photometric observations in the training set into one of these K categories. Which is the most likely template to describe each observation?
- 2. Repair the estimated SEDs of each object (does this mean just de-redshift them?)
- 3. Replace each reference templates $\psi_k(\lambda)$ with the mean of each of the repaired templates of that class (discovered in step 1). This is like computing the new mean in k-means.
- 4. Check to see if you need to add a new template or remove an existing template based on some statistical criterion.

A difference to point out - my work proposes to do all of these steps within a rigorous probabilistic framework. We can even incorporate a nonparametric model to add/remove templates (or bases). Also, my model is more of a factor analysis approach as opposed to clustering. I'm not sure what difference this makes.

Some takeaways from this paper:

- High level intuition:

For a given redshift, the photometric observation gives constraints on the possible underlying SED, since we expect to get back the measured photometric values by redshifting the SED and convolving it with the filter response function. This constraint obviously depends on the photometric system and, also, the redshift of the object as the rest-frame spectrum is sampled at different wavelengths.

- They land on four classes of quasars (Fig 7), each of which has a slightly different distribution of red shift (figure 6)

Again, this paper doesn't really clarify to me an important aspect - how exactly is the χ^2 objective defined? How do you go from templates, T to fluxes? One improvement that I can make would be learning a prior over spectral model weights w (similarly, template indicators T), and use this prior to hone in on combinations of w that are likely, while leaving the correlation between w and z alone a priori. Similarly, incorporating prior information about magnitudes might disambiguate really low red shifts with higher red shifts.

- Bovy et al. (2012) extreme deconvolution method
- Suzuki (2006) (QUASAR SPECTRUM CLASSIFICATION WITH PRINCIPAL COMPO-NENT ANALYSIS (PCA): EMISSION LINES IN THE Lyα FOREST)
- Brescia et al. (2013) use a multi-layer perceptron (four layers) regression setting on a combination of SDSS (from the DR7QSO dataset, I believe), UKIDSS, and WISE photometric datasets, comparing photo-z performance on the following intersections:

```
1. SDSS: 1.1 \times 105;

2. SDSS \cap GALEX: 4.5 \times 104;

3. SDSS \cap UKIDSS: 3.1 \times 104;

4. SDSS \cap GALEX \cap UKIDSS: 1.5 \times 104;

5. SDSS \cap GALEX \cap UKIDSS cap WISE: 1.4 \times 104.
```

The largest dataset combined 43 features (mostly band fluxes and magnitudes). The authors mostly discuss the multi-layer model and their training technique, which is L-BFGS and various rounds of cross validation. The authors note their model's inability to generalize to regions of the space for which they don't have data (particularly large magnitudes or out of range z values).

The authors outline a bunch of statistics to compare between methods, including the bias, sample stdev, median of absolute value of two quantities

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- \Delta z = (z_{spec} - z_{phot}) (residuals)

- \Delta z_{norm} = (z_{spec} - z_{phot})/(1 + z_{spec}) (normalized residuals)
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And a bunch of percentages of outliers and such based on those statistics. One is "catastrophic outliers", defined as individual samples where $|z_{norm}| > 2\sigma(z_{norm})|$ - outside of two sample standard deviations.

- Kind and Brunner (2014) perform photo-z on a galaxy sample in a two step process
 - use a self-organizing map as an unsupervised preprocessing step to put data on a low (2) dimensional manifold, typically from galaxy meta information like fluxes and profile information. In a sense, galaxies are clustered into little grid cells on this low-dimensional manifold, which are continuous.

- Spectroscopic z measurements are then somehow assigned to each grid cell for use in the prediction task. Prediction seems to be take galaxy features, map it to the cell, and use some sort of average or statistic of that cell's photo-z measurement. This seems like a k-nn kinda thing? I'm not sure.

They really emphasize the fact that their SOM is unsupervised, and I'm not sure why it's a selling point. They deliberately cut off their representation learning step from the actual signal they wish to predict, though it does show the representation is capturing relevant structure.

Though similar in spirit, the self-organizing map doesn't elicit much of a generative or physical interpretation, and really serves as more of a manifold learning. I would not expect generalization outside of the range of z values and flux magnitudes to predict accurately with this method.

- Budavári (2009) (Unified photo-z paper)
- Berk et al. (2001) Describes a composite spectra for quasars using 2200 sample spectra form the SDSS sample in 2001. This paper goes into details about the characteristic emission lines and how they combined (de-redshifted, re-binned, took the median, etc), and what it says about the physical makeup of the object. Major quote

The steps required to generate a composite quasar spectrum involve selecting the input spectra, determining accurate redshifts, rebinning the spectra to the rest frame, scaling or normalizing the spectra, and stacking the spectra into the final composite. Each of these steps can have many variations, and their effect on the resulting spectrum can be significant

Takeaway: details about the particular meaning behind emission lines or inductive biases about smoothness or good models for quasar spectra can probably be mined from this paper.

• Walcher et al. (2011) provides an extensive review of spectral energy density (SED) models for stars and galaxies, and various models and methods that can be used for measuring specific properties. They describe various types of eigendecomposition of galaxy spectra (SVD, trimmed SVD, robust SVD), and various other models of spectra. They also go into detail about the emission/absorption lines.

One example they go into detail is photometric red shifts.

Traditionally, photometric redshift estimation is broadly split into two areas: empirical methods and the template- fitting approach. Empirical methods use a subsample of the photometric survey with spectroscopically-measured red- shifts as a training set for the redshift estimators. This sub- sample describes the redshift distribution in magnitude and colour space empirically and is used then to calibrate this relation. Template methods use libraries of either observed spectra of galaxies exterior to the survey or model SEDs (as described in Sect. 2). As these are full spectra, the templates can be shifted to any redshift and then convolved with the transmission curves of the filters used in the photometric survey to create the template set for the redshift estimators.

- Ball et al. (2008a) Is cited in the review Walcher et al. (2011) as a quasar photo-z method using artificial neural networks.
- Myers et al. (2009)
- Ball et al. (2008b)

2.1 Related work takeaways

This work extends previous work by

• Being fully Bayesian - the stochastic process prior allows for integrating out the templates as well - instead of computing p(z|f,T) we marginalize this and compute

$$p(z|f) = \int_{T} p(T)p(z|f,T)$$
(16)

• We also make our model directly a function of PIXELS - instead of fitting a flux vector, f_{ugriz} Ambit we integrate it out (which includes integrating out location, magnitude, etc).

$$p(z|x_n, \mathbf{X}) = \int_{T, f} p(T)p(f|x_n, T)p(z|f, T)$$
(17)

$$p(z|x_n, \mathbf{X}) = \int_{\mathcal{W}.\mathcal{B}} p(w|x_n, B)p(B|X, x_n)p(z|w, B, x_n)$$
(18)

In doing this - do we get more realistic uncertainty? We seem to be underestimating uncertainty quite a bit.

• Our model is not a clustering/single type model. It is a (nonnegative) latent factor model, so we parameterize more of a continuum of types. Our positive basis also elicits an interpretable basis.

3 Stochastic process model of spectra

Our approach is to directly model the probability distribution over the full spectrum of a quasar given a small number of photometric observations (bands). We view the spectrum of a quasar as a (scaled) probability distribution itself, and thus model it as a random measure. Specifically, we specify a model for the *rest frame* spectrum of a quasar, and explain observations by warping the input measurements by the appropriate red-shift values.

We further assume that each quasar is at some specific red-shift with respect to Earth, z_n , (typically in the range 0 to 8). Denoting the rest-frame spectrum of a quasar n as a function, $f_n^{(rest)}: \mathcal{W} \to \mathbb{R}_+$, the affect of red-shift on our observations is summarized by the relationship

$$f_n^{(obs)}(\lambda) = f_n^{(rest)}(\lambda \cdot (1+z_n)) \tag{19}$$

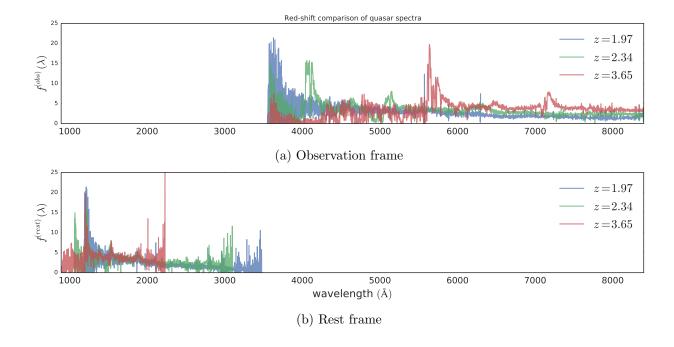


Figure 1: High fidelity spectroscopy of multiple quasars at different red-shifts, z. The top graphic depicts the spectrograph in the observation frame, which can be intuitively thought of as "stretched" by a factor (1+z). The lower figure depicts the "de-redshifted" version of the same quasar spectra. This effectively squashes observations, and reconstructs the quasar spectra as it would be seen in the quasar's rest frame. The salient feature of this operation is the alignment of the emission and absorption lines (albeit at different scales). This alignment will provide the information about z that we can infer from SDSS photometric projections of the very same spectra.

There has to be a scaling factor here (otherwise I think energy is not conserved), but I believe I can brush the details under the rug by referring to these as spectral energy densities and say they integrate to 1.

As the spectrum of a source characterizes much of the information of interest, we take special care creating a structured prior over $f_n(\cdot)$ using available observations of rich spectra. Furthermore, due to the fact that the red-shift value effectively scales the input of this function, we cannot rely on a fixed grid of $\lambda_1, \ldots, \lambda_P$ values, but must define a stochastic process to coherently define a probabilistic model. The rest of this section outlines a model for these spectra and subsequent photometric observations.

3.1 Additive stochastic process prior

To model the full spectral observations, we define a library of K latent positive stochastic processes, and assume that the true rest frame spectrum is a positive linear combination of these K processes. Spectral observations, $x_n(\lambda_i)$, are measured with Gaussian noise (which can be negative) centered around a realization of the true spectra process. The noise of the spectral intensity measured at each wavelength is measured and assumed to be known. The full generative model for this prior is

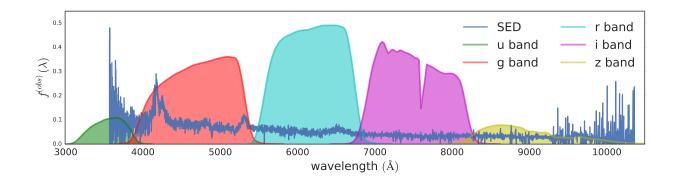


Figure 2: Example of a (scaled) quasar spectrum with SDSS ugriz band filters, $S_{\beta}(\lambda)$, overlaid. Computing red-shift given the full spectrum is often straightforward and often quite precise, however full spectra are more difficult to obtain. Photometry data, while far easier to obtain, only measures band specific flux, a weighted average of the unobserved spectrum of the object.

simply

$$B_k(\cdot) \sim F_B \text{ with } B_k : \mathcal{W} \to \mathbb{R}_+ \text{ and } \int_{\mathcal{W}} B_k(d\lambda) = 1$$
 (20)

$$f_n(\cdot) = \sum_{k=1} w_{n,k} B_k(\cdot) \tag{21}$$

$$z_n \sim F_z$$
 (22)

$$x_n(\lambda_i) \sim \mathcal{N}\left(f_n(\lambda_i \cdot (1+z_n)), \sigma_{n,\lambda_i}^2\right)$$
 (23)

where F_B defines the probability distribution over the stochastic processes that compose our basis, B_1, \ldots, B_K , and thus encode assumptions about the overall shape and smoothness of the rest frame spectrum. The red-shift parameter z_n is drawn from a prior with probability distribution F_z . The observation noise for spectrum n measured at observation wavelength λ_i is given by σ_{n,λ_i}^2 , and is known.

We note that this is a similar set up to (cite NMF, LDA, other positive density model stuff here), and is an example of a hierarchical mixture model to define a density.

3.2 Generative model of photometric observations

Photometric observations are far less information rich than the full spectrum - fine details are averaged away over large swaths of wavelength values. However, the band-specific fluxes captured in photometric images do convey information about the object depicted (cite photo z papers). The photometric count observations can be modeled as a function of the object's unobserved full spectral density in a generative way. For quasar n, the generative process of a photometric observation of a quasar is

• Rest-frame quasar spectra is sampled from the structured prior determined by the unsupervised procedure.

$$f_n(\cdot) \sim F$$
 (24)

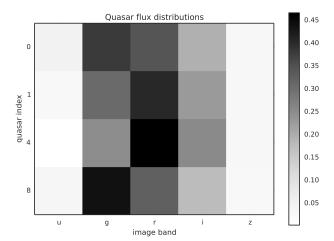


Figure 3: Flux distributions in the SDSS ugriz bands (columns) computed from high fidelity spectroscopy of four quasars (rows). The value in each square is computed by integrating the filter band from 2 against the full spectrum of the source. The "photo-z" goal is to somehow infer the red-shift of a quasar from these five values spatially distributed in an image.

or, in the positive basis representation

$$w_{n,k} \sim p_k(w) \text{ for } k = 1, \dots, K$$
(25)

$$f_n(\cdot) = \sum_{k=1}^K w_{n,k} B_k(\cdot) \tag{26}$$

This defines the amount of energy $W/m^2/\lambda$ emitted by the quasar. Figure out how this relates to the spectral radiance defined by Planck's law. Figure out how the emission angle portion of Planck's law will relate to this..

• Red shift is sampled from an appropriate prior (to be determined)

$$z_n \sim F_z$$
 (27)

• The number of photons captured in band β is a function of the band sensitivity function $S_{\beta}(\cdot)$, the distance to the object, and the number of photons emitted across the spectrum, given by the photon-energy relationship

$$E(\lambda) = \frac{hc}{\lambda} \text{ J / photon} \tag{28}$$

How does this look to us? Does it make sense to just stretch out the $f_n(\cdot)$ and then apply $E(\lambda)$, or is there something else that happens that makes this order of operations invalid?

The expected number of photons measured in band β with lens size A m² and exposure duration Δ seconds is

$$\mu_n = \underbrace{b_n}_{m^2} \underbrace{\frac{A\Delta}{4\pi d_n^2}}_{s} \int_{\Lambda} \underbrace{f_n(\lambda \cdot (1+z_n))}_{10^{-20} \underbrace{\frac{J}{s \cdot m^2 \cdot \Lambda}}} \underbrace{E(\lambda)^{-1}}_{\frac{photon}{J}} S_{\beta_n}(\lambda) d\lambda \tag{29}$$

where the term $\frac{A\Delta}{4\pi d_n^2}$ captures the notion that only a small fraction of the shell of radius d_n is being measured. The b_s term indicates the surface area of emission. Both d_n and b_n are not measurable, and treated as nuisance variables. The rest frame spectrum has been shifted to observation frame using the unknown red-shift value z_n .

• As the spatial appearance of a quasar is modeled as a point source, pixel observations are finally determined by the point spread function, which scatter's light across the lens. This function, which is assumed known and denoted as $p_n(\cdot)$, models atmospheric effects and other causes of spatial spread of a source's light. Given the object's expected photon flux, b_{n,β_n} (photons / second), the number of photons observed in pixel n in image n is distributed

Defining notation, for image $n \in \{1, ..., N\}$, denote the image band as $\beta_n \in \{u, g, r, i, z\}$, and denote pixel $m \in \{1, ..., M_n\}$ as $x_{n,m}$.

$$x_{n,m} \sim \text{Pois}(\mu_n p_n(m))$$
 (30)

This defines our likelihood, and our inferential goal is now to compute the posterior distribution over w_n and z_n given the band fluxes.

3.3 Inference

For each image, we sum over all pixels in the spatial extent of the quasar (due to the point spread function). Due to additive properties of Poissons, this value is distributed

$$\sum_{m}^{M_n} x_{n,m} \sim \text{Pois}\left(b_{n,\beta_n} \sum_{m}^{M_n} p_n(m)\right)$$
(31)

$$\sim \operatorname{Pois}\left(b_{n,\beta_n}\right)$$
 (32)

Current inference scheme is

• Map estimation of \hat{B} and \hat{W} a large range of canonical values λ_0

$$\hat{B}, \hat{W} = \arg\max_{B,W} \sum_{n=1}^{N} \sum_{p=1}^{P} p(x_n(\lambda_i)|W_n, B, \sigma_n^2)$$
(33)

• Full Bayesian inference of z_n, w_n for test n. We generate posterior samples from the posterior distribution

$$p(w_n, z_n | B, b_{n,ugriz}) \propto \prod_{\beta \in \{ugriz\}} p(b_{n,\beta} | w_n, z_n, B) p(w_n, z_n)$$
(34)

$$\propto \prod_{\beta \in \{ugriz\}} p_{pois} \left(b_{n,\beta}; \int_{\mathcal{W}} S_{\beta}(\lambda) w_n^{\mathsf{T}} B(1+z_n) \right) d\lambda \right) p(w_n, z_n)$$
 (35)

where the input warping of $w_n^{\mathsf{T}}B$ is done by linear interpolation. This doesn't feel right.

This is also currently done by univariate slice sampling. This is super slow, and I'm not sure how well it's converging.

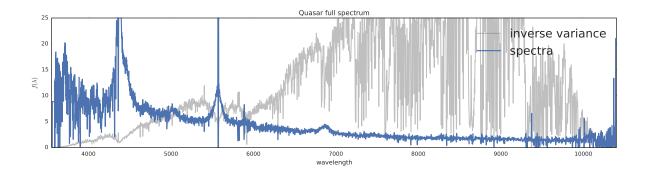


Figure 4: Example of measured quasar spectrum (blue), x_{n,λ_p} , and inverse variance of the measurement (grey), $\sigma_{n,\lambda_p}^{-2}$.

3.4 Data

We use a database of full spectral measurements and precisely measured red-shifts to predict quasars for which we only have photometry data (where do these specifically come from?).

We observe noisy measurements of the full spectra, y_n , (quasar n of N) recorded on a wavelength grid $\Lambda = (\lambda_1, \ldots, \lambda_P)$. The values of y_n have been perturbed by Gaussian noise σ_n (and thus, can be negative), however we know that the spectral distribution of light must be positive, so we assume there is some latent spectrum f_n that specifies y_n . Precisely, this relationship can be written

$$y_n \equiv (y_{n,\lambda_1}, \dots, y_{n,\lambda_P}) \text{ for } n = 1, \dots, N$$
 (36)

$$\sigma_n^2 \equiv (\sigma_{n,\lambda_1}^2, \dots, \sigma_{n,\lambda_P}^2) \tag{37}$$

$$y_{n,\lambda_1} \sim \mathcal{N}(f_n(\lambda_1), \operatorname{diag}(\sigma_n))$$
 (38)

We approach this task as a density estimation problem, where we find a physically interpretable low-dimensional specification of a quasar's spectral density.

4 Experiments

We run several experiments to show the utility of this model. We divide the N=568 available spectra and their precisely measured z values into a training set, $N_{train}=400$, and a testing set, $N_{test}=168$. We then take the testing set, and project the full spectra down on to the SDSS bands by numerically integrating the test spectra against the known filter sensitivities. These serve as "test fluxes" from which we predict red-shift and validate our model.

Our experimental framework proceeds as follows

- Fit a model over the training set, \hat{B}, \hat{W}
- \bullet For each quasar n in the test set
 - Compute band fluxes, $b_{n,\beta}$ for the SDSS ugriz bands.
 - Compute posterior samples of $z_n, w_n | b_{n,\beta}, B$

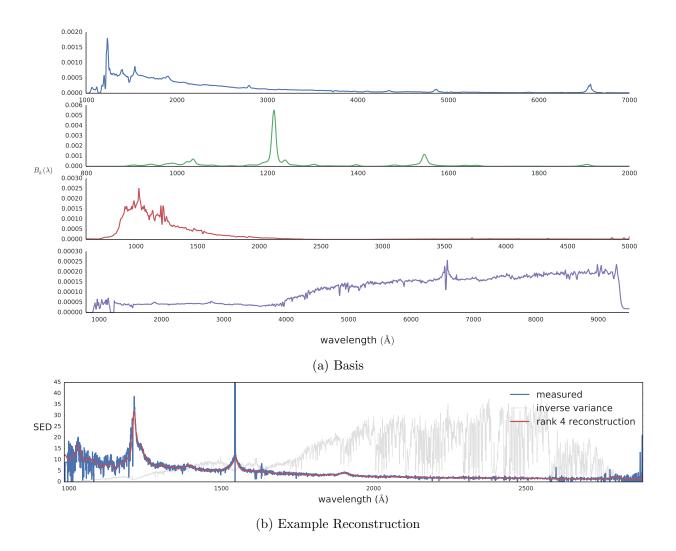


Figure 5: The upper plot depicts the non-negative basis decomposition of 400 rest frame quasar spectra (de-redshifted) from a maximum a posteriori fit to the model. The lower plot shows an example reconstruction of one quasar in red.

- Predict with the expectation of the posterior marginal distribution:

$$z_n = E\left(z_n | b_{n,\beta}, B\right) \tag{39}$$

4.1 Non-negative basis decomposition

Figure 5a graphically depicts the non-negative basis decomposition, B_1, \ldots, B_k , from 400 quasar spectra, and Figure 5b depicts the model's reconstruction for one quasar.

4.2 Photo-z measurements

Figure 6 depicts a sampling of marginal posterior distributions of z_n conditioned only on band fluxes and the learned basis B.

Figure 8 depicts the reconstruction of the full spectra from the five band fluxes $b_{n,\beta}$.

Figure 9 depicts the "photo-z" prediction against the spectroscopic measurement of red-shift for the held out test stars.

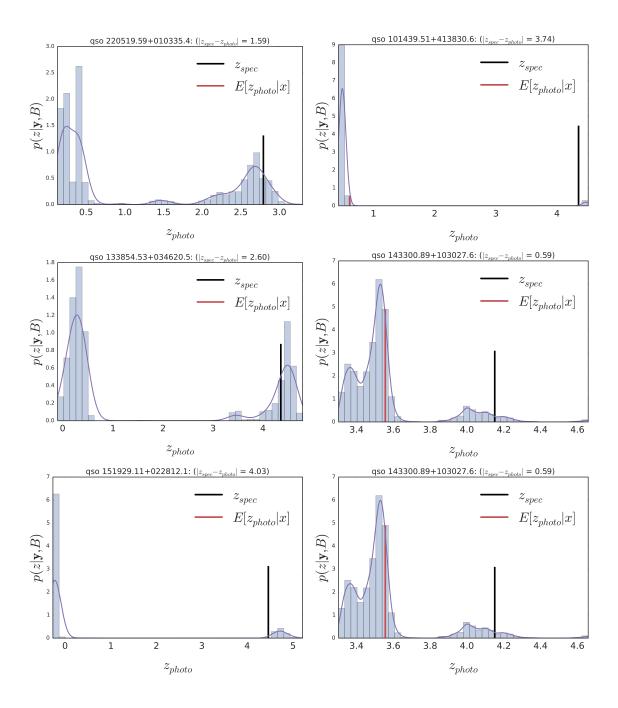


Figure 6: Histogram of red-shift posterior samples given only the SDSS band projection of the full spectrum. These histograms were computed with 5,000 MCMC samples (after 5,000 burn-in) using slice sampling. The full spectrum measured red-shift is the vertical black line, and the posterior expectation of the red-shift is the vertical red line.

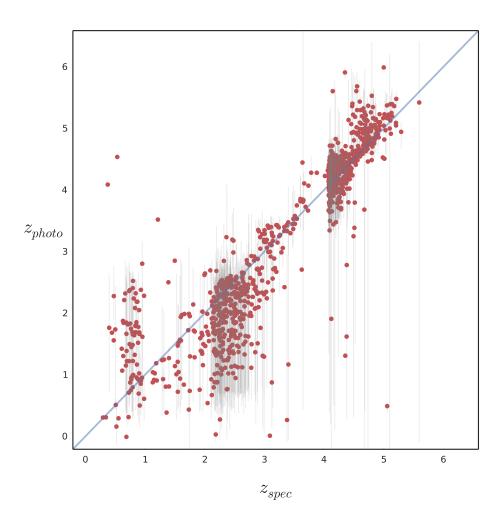


Figure 7: Red-shift predictions for 167 held out test Quasars and posterior dispersion. What the hell is going on with that weird under estimation cluster???

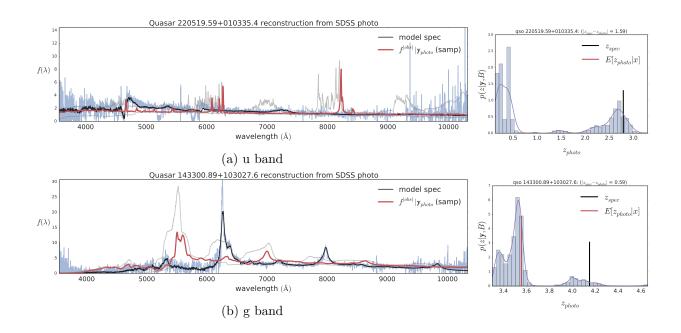


Figure 8: Monte Carlo reconstruction of the full spectrum from the five band test fluxes. The green line is the posterior median (at wavelength) and the grey lines are the 1st and 99th percentile samples. On the right are the respective red-shift posterior distributions. There seems to be some bias to the right (over prediction) in the upper cluster

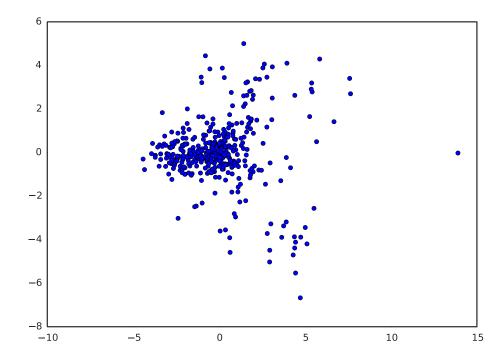


Figure 9: PCA projection of $\log w_n$ to two dimensions. Examine the z values, appearances, and total flux of the big cluster versus the outliers

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