R Package FME: Tests of the Markov Chain Monte Carlo Implementation

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Abstract

This vignette tests the Markov chain Monte Carlo (MCMC) implementation of Rpackage **FME** (Soetaert and Petzoldt 2010).

It includes the delayed rejection and adaptive Metropolis algorithm (Haario, Laine, Mira, and Saksman 2006)

Keywords: Markov chain Monte Carlo, delayed rejection, adapative Metropolis, MCMC, DRAM, R.

1. Introduction

Function modMCMC from package **FME** (Soetaert and Petzoldt 2010) implements a Markov chain Monte Carlo (MCMC) algorithm using a delayed rejection and adaptive Metropolis procedure (Haario $et^{\tilde{a}}$ al. 2006).

In this vignette, the DRAM MCMC function is tested on several functions.

- Sampling from a normal distribution, using different priors
- Sampling from a log-normal distribution
- Sampling from a curvilinear ("banana") function (Laine 2008)
- A simple chemical model, fitted to a data series (Haario et al. 2006)
- A nonlinear monod function, fitted to a data series.

Other examples of **FME** functions (including modMCMC) are in the following vignettes:

- "FMEdyna", FMEs functions applied to a dynamic ordinary differential equation model
- "FMEsteady", applied to a steady-state solution of a partial differential equation

2. Function modMCMC

2.1. The Markov chain Monte Carlo method

The implemented MCMC method is designed to be applied to nonlinear models, and taking into account both the uncertainty in the model parameters and in the model output.

Consider observations y and a model f, that depend on parameters θ and independent variables x. Assuming additive, independent Gaussian errors with an unknown variance σ^2 :

$$y = f(x, \theta) + \xi$$

where

$$\xi \sim N(0, I\sigma^2)$$

For simplicity we assume that the prior distribution for θ is Gaussian:

$$\theta_i \sim N(v_i, \mu_i)$$

while for the reciprocal of the error variance $1/\sigma^2$, a Gamma distribution is used as a prior:

$$p(\sigma^{-2}) \sim \Gamma\left(\frac{n_0}{2}, \frac{n_0}{2}S_0^2\right).$$

The posterior for the parameters will be estimated as:

$$p(\theta|y,\sigma^2) \propto \exp\left(-0.5\left(\frac{SS(\theta)}{\sigma^2} + SS_{pri}(\theta)\right)\right)$$

and where σ^2 is the error variance, SS is the sum of squares function

$$SS(\theta) = \sum (y_i - f(\theta)_i)^2$$

and

$$SS_{pri}(\theta) = \sum_{i} \left(\frac{\theta_i - v_i}{\mu_i}\right)^2.$$

In the above, the sum of squares functions $(SS(\theta))$ are defined for Gaussian likelihoods. For a general likelihood function the sum-of-squares corresponds to twice the log likelihood,

$$SS(\theta) = -2\log(p(y|\theta))$$

. This is how the function value (f, see below) should be specified.

Similarly, to obtain a general non-Gaussian prior for the parameters θ (i.e. $SS_{pri}(\theta)$) minus twice the log of the prior density needs to be calculated.

If non-informative priors are used, then $SS_{pri}(\theta)=0$.

2.2. Arguments to function modMCMC

The default input to modMCMC is:

modMCMC(f, p, ..., jump=NULL, lower=-Inf, upper=+Inf, prior=NULL,
 var0 = NULL, wvar0 = NULL, n0= NULL, niter=1000, outputlength = niter,
 burninlength=0, updatecov=niter, covscale = 2.4^2/length(p),
 ntrydr=1, drscale=NULL, verbose=TRUE)

with the following arguments (see help page for more information):

- f, the sum-of-squares function to be evaluated, $SS(\theta)$
- p, the initial values of the parameters θ to be sampled
- ..., additional arguments passed to function f
- jump, the proposal distribution (this generates new parameter values)
- prior, the parameter prior, $SS_{pri}(\theta)$
- var0, wvar0, n0, the initial model variance and weight of the initial model variance, where n0=wvar0*n, n=number of observations.
- lower, upper, lower and upper bounds of the parameters
- niter, outputlength, burninlength, the total number of iterations, the numer of iterations kept in output, and the number of initial iterations removed from the output.
- updatecov, covscale, arguments for the adaptation of the proposal covariance matrix (AM-part of the algorithm).
- ntrydr, drscale, delayed rejection (DR) arguments.

3. Sampling from a normal distribution

In the first example, function modMCMC is used to sample from a normal distribution, with mean = 10 and standard deviation = 1. We use this simple example mainly for testing the algorithm, and to show various ways of defining parameter priors.

In this example, the error variance of the model is 0 (the default).

We write a function, Nfun that takes as input the parameter value and that returns 2 times the log of the normal likelihood.

```
> mu <- 10
> std <- 1
> Nfun <- function(p)
+     -2*log(dnorm(p, mean = mu, sd = std))</pre>
```

The proposal covariance is assumed to be 5.

3.1. Noninformative prior

q075 10.736005

In the first run, a noninformative prior parameter distribution is used. 2000 iterations are produced; the initial parameter value is taken as 9.5.

```
> MCMC <- modMCMC (f = Nfun, p = 9.5, niter = 2000, jump = 5)

number of accepted runs: 514 out of 2000 (25.7%)

It is more efficient to update the proposal distribution, e.g. every 10 iterations:

> MCMC <- modMCMC (f = Nfun, p = 9.5, niter = 2000, jump = 5, updatecov = 10)

number of accepted runs: 1346 out of 2000 (67.3%)

> summary(MCMC)

p1

mean 10.016093
sd    1.035950
min    6.612467
max    12.922701
q025    9.350826
q050    9.995501
```

3.2. Noninformative prior, lower bound imposed

In the second run, the sampled parameters are restricted to be > 9 (lower=9):

3.3. A normally distributed prior

q075 9.5205309

Finally, it is assumed that the prior for the model parameter is itself a normal distribution, with mean 8 and standard devation 1: $pri(\theta) \sim N(8, 1)$.

The posterior for this problem is a normal distribution with mean = 9, standard deviation of 0.707.

```
> pri <- function(p) -2*log(dnorm(p, 8, 1))
> MCMC3 <- modMCMC (f = Nfun, p = 9.5, niter = 2000, jump = 5,
+ updatecov = 10, prior = pri)

number of accepted runs: 1401 out of 2000 (70.05%)

> summary(MCMC3)

p1
mean 9.0298375
sd 0.7131151
min 6.4069930
max 11.5160459
q025 8.5254041
q050 9.0217954
```

The number of accepted runs is increased by toggling on delayed rejection; at most 2 delayed rejections steps are tried (ntrydr=2):

```
> summary(MCMC4 <- modMCMC(f = Nfun, p = 1, niter = 2000, jump = 5,
+ updatecov = 10, prior = pri, ntrydr = 2))</pre>
```

> MCMC4\$count

```
dr_steps Alfasteps num_accepted num_covupdate 647 1941 1911 181
```

Finally, we plot a histogram of the three MCMC runs, and end by plotting the trace of the last run (figure 1).

```
> par(mfrow = c(2,2))
> hist(MCMC$pars, xlab="x", freq = FALSE, main = "unconstrained", xlim = c(6, 14))
> hist(MCMC2$pars, xlab="x", freq = FALSE, main = "x>9", xlim = c(6, 14))
> hist(MCMC3$pars, xlab="x", freq = FALSE, main = "pri(x)~N(8,1)", xlim = c(6, 14))
> plot(MCMC3, mfrow = NULL, main = "AM")
> mtext(outer = TRUE, line = -1.5, "N(10,1)", cex = 1.25)
```

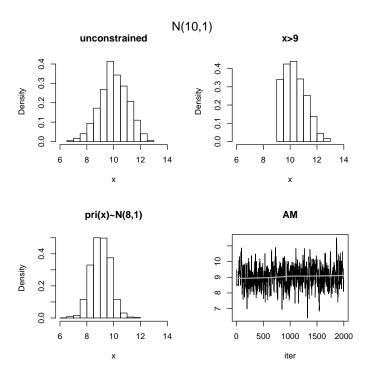


Figure 1: Simulated draws of a normal distribution (N(10,1)) with different prior parameter distributions - see text for R-code

4. Sampling from a lognormal distribution

In the second example, function modMCMC is used to sample from a 3-variate log-normal distribution, with mean = 1,2,3, and standard deviation = 0.1.

We write a function that has as input the parameter values (a 3-valued vector) and that returns 2 times the lognormal likelihood.

```
> mu <- 1:4
> std <- 1
> NL <- function(p) {
+    -2*sum(log(dlnorm(p, mean = mu, sd = std)))
+ }</pre>
```

The proposal covariance is assumed to be the identity matrix with a variance of 5. The simulated chain is of length 10000 (niter), but only 1000 are kept in the output (outputlength).

```
> MCMCl <- modMCMC (f = NL, p = rep(1, 4), niter = 10000,
+ outputlength = 1000, jump = 5)
number of accepted runs: 3233 out of 10000 (32.33%)
```

Convergence is tested by plotting the trace; in the first run convergence is not good (figure 2)

```
> plot(MCMCl)
```

The number of accepted runs is increased by updating the jump covariance matrix every 100 runs and toggling on delayed rejection.

```
> MCMCl <- modMCMC (f = NL, p = rep(1, 4), niter = 5000,
+ outputlength = 1000, jump = 5, updatecov = 100, ntrydr = 2)
number of accepted runs: 3159 out of 5000 (63.18%)
Convergence of the chain is checked (figure 3).
> plot(MCMCl)
```

The histograms show the posterior densities (figure 4).

```
> hist(MCMCl)
```

```
> MCMCl$pars <- log(MCMCl$pars)</pre>
```

> summary(MCMCl)

```
р1
                       p2
                                   рЗ
                           2.81932387 3.7833606
      1.1166649
                1.8734114
mean
sd
      1.0707153 0.9300218
                           0.90709157 0.9977708
min -2.3555294 -1.0483020 -0.02578414 0.0000000
      3.8925707 4.3570795 4.84303871 6.1432261
max
q025
     0.4108427
                1.2458315
                           2.19616661 3.0845191
                           2.81504045 3.7758082
q050
     1.0627417
                1.9193596
q075 1.7641849 2.4800461 3.51383466 4.5308615
```

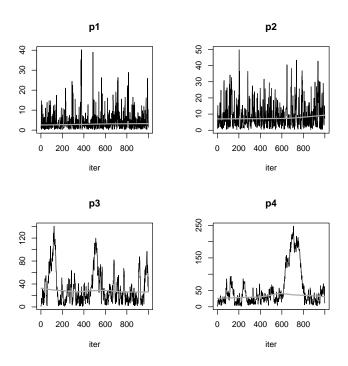


Figure 2: The trace of the log normal distribution -Metropolis algorithm - see text for R-code

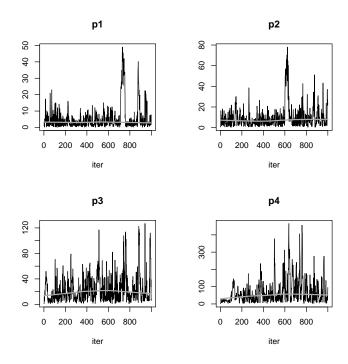


Figure 3: The trace of the log normal distribution - adaptive Metropolis - see text for R-code

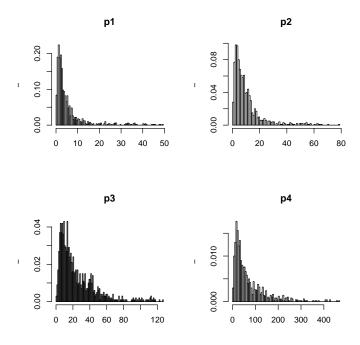


Figure 4: The histograms of the log normal distributed samples - see text for $\mathsf{R}\text{-}\mathsf{code}$

5. The banana

5.1. The model

This example is from Laine (2008).

A banana-shaped function is created by distorting a two-dimensional Gaussian distribution, with mean = 0 and a covariance matrix τ with unity variances and covariance of 0.9:

$$\tau = \left[\begin{array}{cc} 1 & 0.9 \\ 0.9 & 1 \end{array} \right].$$

The distortion is along the second-axis only and given by:

$$y_1 = x_1$$

$$y_2 = x_2 - (x_1^2 + 1).$$

5.2. R-implementation

First the banana function is defined.

```
> Banana <- function (x1, x2) {
+   return(x2 - (x1^2+1))
+ }</pre>
```

We need a function that estimates the probability of a multinormally distributed vector

```
> pmultinorm <- function(vec, mean, Cov) {
+    diff <- vec - mean
+    ex <- -0.5*t(diff) %*% solve(Cov) %*% diff
+    rdet <- sqrt(det(Cov))
+    power <- -length(diff)*0.5
+    return((2.*pi)^power / rdet * exp(ex))
+ }</pre>
```

The target function returns -2 *log (probability) of the value

```
> BananaSS <- function (p)
+ {
+    P <- c(p[1], Banana(p[1], p[2]))
+    Cov <- matrix(nr = 2, data = c(1, 0.9, 0.9, 1))
+    -2*sum(log(pmultinorm(P, mean = 0, Cov = Cov)))
+ }</pre>
```

The initial proposal covariance (jump) is the identity matrix with a variance of 5. The simulated chain is of length 2000 (niter). The modMCMC function prints the % of accepted runs. More information is in item count of its return element.

5.3. Metropolis Hastings algorithm

The First Markov chain is generated with the simple Metropolis Hastings (MH) algorithm

```
> MCMC <- modMCMC(f = BananaSS, p = c(0, 0.5), jump = diag(nrow = 2, x = 5),
+ niter = 2000)
```

number of accepted runs: 207 out of 2000 (10.35%)

> MCMC\$count

5.4. Adaptive Metropolis algorithm

Next we use the adaptive Metropolis (AM) algorithm and update the proposal every 100 runs (updatecov)

```
> MCMC2 \leftarrow modMCMC(f = BananaSS, p = c(0, 0.5), jump = diag(nrow = 2, x = 5),
+ updatecov = 100, niter = 2000)
```

number of accepted runs: 402 out of 2000 (20.1%)

> MCMC2\$count

5.5. Delayed Rejection algorithm

Then the Metropolis algorithm with delayed rejection (DR) is applied; upon rejection one next parameter cadidate is tried (ntrydr). (note ntrydr=1 means no delayed rejection steps).

```
> MCMC3 <- modMCMC(f = BananaSS, p = c(0, 0.5), jump = diag(nrow = 2, x = 5),
+ ntrydr = 2, niter = 2000)
```

number of accepted runs: 1083 out of 2000 (54.15%)

> MCMC3\$count

dr_steps denotes the number of delayed rejection steps; Alfasteps is the number of times the algorithm has entered the acceptance function for delayed rejection.

5.6. Delayed Rejection Adaptive Metropolis algorithm

Finally the adaptive Metropolis with delayed rejection (DRAM) is used. (Here we also estimate the elapsed CPU time, in seconds - print(system.time()) does this)

We plot the generated chains for both parameters and for the four runs in one plot (figure 5). Calling plot with mfrow=NULL prevents the plotting function to overrule these settings.

```
> par(mfrow = c(4, 2))
> par(mar = c(2, 2, 4, 2))
> plot(MCMC, mfrow = NULL, main = "MH")
> plot(MCMC2, mfrow = NULL, main = "AM")
> plot(MCMC3, mfrow = NULL, main = "DR")
> plot(MCMC4, mfrow = NULL, main = "DRAM")
> mtext(outer = TRUE, side = 3, line = -2, at = c(0.05, 0.95),
+ c("y1", "y2"), cex = 1.25)
> par(mar = c(5.1, 4.1, 4.1, 2.1))
```

The 2-D plots show the banana shape:

```
> par(mfrow = c(2, 2))
> x1 <- c(-3, 3)
> y1 <- c(-1, 8)
> plot(MCMC$pars, main = "MH", xlim = xl, ylim = yl)
> plot(MCMC2$pars, main = "AM", xlim = xl, ylim = yl)
> plot(MCMC3$pars, main = "DR", xlim = xl, ylim = yl)
> plot(MCMC4$pars, main = "DRAM", xlim = xl, ylim = yl)
```

Finally, we test convergence to the original distribution. This can best be done by estimating means and covariances of the transformed parameter values.

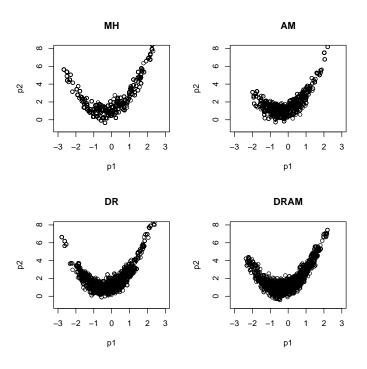


Figure 5: The bananas - see text for R-code

[2,] 0.8456841 0.9819903

6. A simple chemical model

This is an example from (Haario *et~al.* 2006). We fit two parameters that describe the dynamics in the following reversible chemical reaction:

$$A \rightleftharpoons k_2 k_1 B$$
.

Here k_1 is the forward, k_2 the backward rate coefficient.

The ODE system is written as:

$$\frac{dA}{dt} = -k_1 \cdot A + k_2 \cdot B$$
$$\frac{dB}{dt} = +k_1 \cdot A - k_2 \cdot B,$$

with initial values $A_0 = 1$, $B_0 = 0$.

The analytical solution for this system of differential equations is given in (Haario et~al. 2006).

6.1. Implementation in R

First a function is defined that takes as input the parameters (k) and that returns the values of the concentrations A and B, at selected output times.

```
> Reaction <- function (k, times)
+ {
+    fac <- k[1]/(k[1]+k[2])
+    A <- fac + (1-fac)*exp(-(k[1]+k[2])*times)
+    return(data.frame(t=times,A=A))
+ }</pre>
```

All the concentrations were measured at the time the equilibrium was already reached. The data are the following:

```
> Data
           <- data.frame(
     times = c(2,
                       4,
                               6,
                                       8,
           = c(0.661, 0.668, 0.663, 0.682, 0.650))
     Α
> Data
 times
            Α
      2 0.661
2
      4 0.668
3
      6 0.663
4
      8 0.682
     10 0.650
```

We impose parameter priors to prevent the model parameters from drifting to infinite values. The prior is taken to be a broad Gaussian distribution with mean (2,4) and standard deviation = 200 for both.

k2 0.9959 1.0000

The prior function returns the sum of squares function (weighted sum of squared residuals of the parameter values with the expected value).

```
> Prior <- function(p)
+ return( sum(((p - c(2, 4))/200)^2 ))</pre>
```

First the model is fitted to the data; we restrict the parameter values to be in the interval [0,1].

```
[0,1].
> residual <- function(k) return(Data$A - Reaction(k,Data$times)$A)</pre>
> Fit <- modFit(p = c(k1 = 0.5, k2 = 0.5), f = residual,
                  lower = c(0, 0), upper = c(1, 1))
> (sF <- summary(Fit))</pre>
Parameters:
   Estimate Std. Error t value Pr(>|t|)
                0.3944
                                  0.0850 .
k1
     1.0000
                          2.536
k2
     0.5123
                 0.1928
                          2.657
                                  0.0765 .
Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
Residual standard error: 0.01707 on 3 degrees of freedom
Parameter correlation:
       k1
              k2
k1 1.0000 0.9959
```

Here the observations have additive independent Gaussian errors with unknown variance σ^2 . As explained above, the error variance is treated as a 'nuisance' parameter, and a prior distribution should be specified as a Gamma-type distribution for its inverse.

The residual error of the fit (sF\$modfVariance) is used as initial model variance (argument var0), the scaled covariance matrix of the fit (sF\$cov.scaled) is used as the proposal distribution (to generate new parameter values). As the covariance matrix is nearly singular this is not a very good approximation.

The MCMC is initiated with the best-fit parameters (Fit\$par); the parameters are restricted to be positive numbers (lower).

```
> mse <- sF$modVariance
> Cov <- sF$cov.scaled * 2.4^2/2
> print(system.time(
+ MCMC <- modMCMC(f = residual, p = Fit$par, jump = Cov, lower = c(0, 0),
+ var0 = mse, wvar0 = 1, prior = Prior, niter = 2000)
+ ))
number of accepted runs: 1841 out of 2000 (92.05%)
user system elapsed
1.260 0.000 1.259</pre>
```

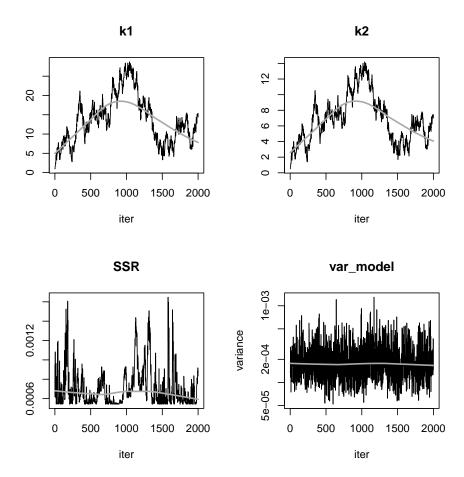


Figure 6: Metropolis-Hastings MCMC of the chemical model - see text for R-code

The initial MCMC method, using the Metropolis-Hastings, has very high acceptance rate, indicating that it has not at all converged; this is confirmed by plotting the chain (figure 6)

```
> plot(MCMC, Full = TRUE)
```

Better convergence is achieved by the adaptive Metropolis, updating the proposal every 100 runs (figure 7)

```
> MCMC2 < - modMCMC(f = residual, p = Fit$par, jump = Cov, updatecov = 100, 
+ lower = <math>c(0, 0), var0 = mse, wvar0 = 1, prior = Prior, niter = 2000)
```

number of accepted runs: 790 out of 2000 (39.5%)

```
> plot(MCMC2, Full = TRUE)
```

The correlation between the two parameters is clear (figure 8):

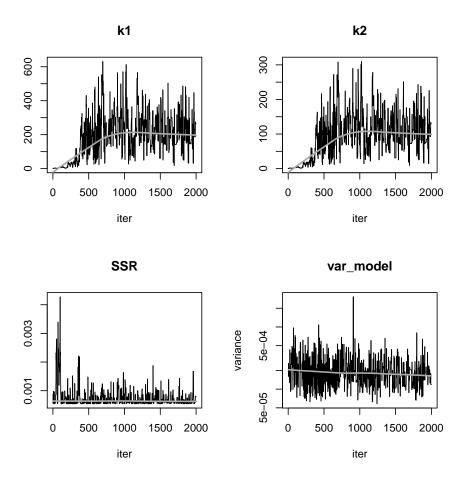


Figure 7: Adaptive Metropolis MCMC of the chemical model - see text for $\mathsf{R}\text{-}\mathsf{code}$

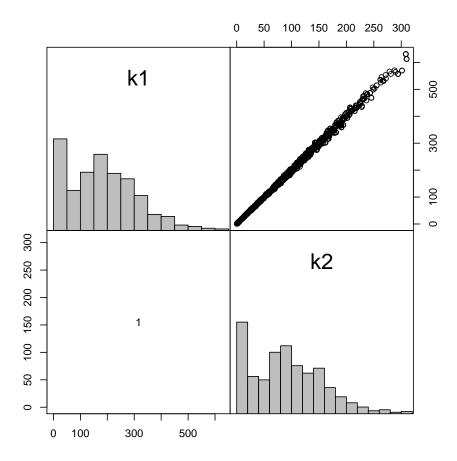


Figure 8: Pairs plot of the Adaptive Metropolis MCMC of the chemical model - see text for $\mathsf{R}\text{-}\mathsf{code}$

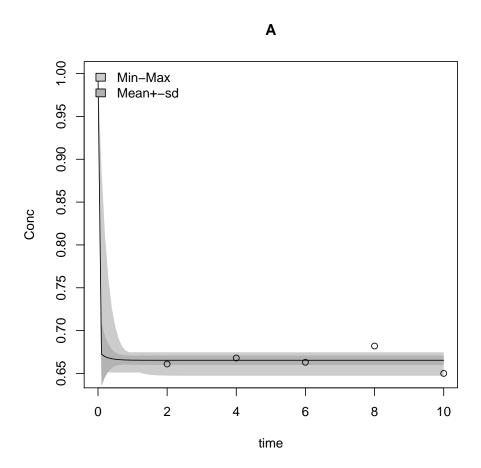


Figure 9: Output ranges induced by parameter uncertainty of the chemical model - see text for $\mathsf{R}\text{-}\mathsf{code}$

> pairs(MCMC2)

Finally, we estimate and plot the effects of the estimated parameters on the model output (figure 9)

- > sR <- sensRange(f=Reaction,times=seq(0,10,0.1),parInput=MCMC2\$pars)
- > plot(summary(sR), xlab = "time", ylab = "Conc")
- > points(Data)

7. Fitting a nonlinear model

The following model:

$$y = \theta_1 \cdot \frac{x}{x + \theta_2} + \epsilon$$
$$\epsilon \sim N(0, I\sigma^2)$$

is fitted to two data sets ¹.

7.1. Implementation in R

First we input the observations:

```
> Obs <- data.frame(x=c( 28, 55, 83, 110, 138, 225, 375), # mg COD/1 
+ y=c(0.053,0.06,0.112,0.105,0.099,0.122,0.125)) # 1/hour 
> Obs2<- data.frame(x=c( 20, 55, 83, 110, 138, 240, 325), # mg COD/1 
+ y=c(0.05,0.07,0.09,0.10,0.11,0.122,0.125)) # 1/hour 
>
```

The Monod model returns a data.frame, with elements x and y:

```
> Model <- function(p,x) return(data.frame(x = x, y = p[1]*x/(x+p[2])))
```

In function Residuals, the model residuals and sum of squares are estimated. In this function, modCost is called twice; first with data set "Obs", after which the cost function is updated with data set "Obs2".

```
> Residuals <- function(p) {
+    cost <- modCost(model = Model(p, Obs$x), obs = Obs, x = "x")
+    modCost(model = Model(p, Obs2$x), obs = Obs2, cost = cost, x = "x")
+ }</pre>
```

This function is input to modFit which fits the model to the observations.

We plot the observations and best-fit line (figure 10)

```
> plot(Obs, xlab = "mg COD/1", ylab = "1/hour", pch = 16, cex = 1.5)
> points(Obs2, pch = 18, cex = 1.5, col = "red")
> lines(Model(p = P$par, x = 0:375))
```

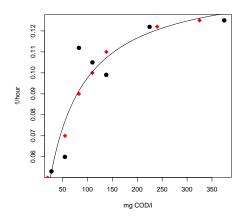


Figure 10: The two sets of Monod observations with best-fit line - see text for R-code

Starting from the best fit, we run several MCMC analyses.

The -scaled- parameter covariances returned from the summary function are used as estimate of the proposal covariances (jump). Scaling is as in (Gelman, Varlin, Stern, and Rubin 2004).

```
> Covar <- summary(P)$cov.scaled * 2.4^2/2</pre>
```

7.2. Equal model variance

In the first run, we assume that both data sets have equal model variance σ^2 .

For the initial model variance (var0) we use the residual mean squares P\$ms, returned by the modFit function. We give low weight to the prior (wvar0=0.1)

The adoptive Metropolis MCMC is run for 1000 steps; the best-fit parameter set (P\$par) is used to initiate the chain (p). A lower bound (0) is imposed on the parameters (lower).

The plotted results demonstrate (near-) convergence of the chain, and the sampled error variance (Model)(figure 11).

```
> plot(MCMC, Full = TRUE)
```

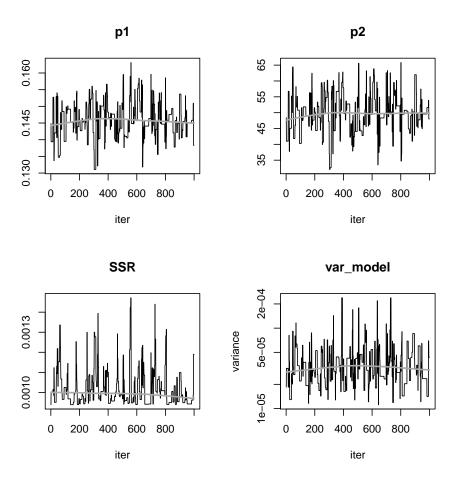


Figure 11: The mcmc, same error variance - see text for ${\sf R\text{-}code}$

7.3. Dataset-specific model variance

In the second run, a different error variance for the two data sets is used.

This is simply done by using, for the initial model variance the variables mean squares, before they are weighted (P\$var_ms_unweighted).

```
> varprior <- P$var_ms_unweighted
> print(system.time(
+ MCMC2 <- modMCMC(f = Residuals, p = P$par, jump = Covar, niter = 1000,
+ var0 = varprior, wvar0 = 0.1, lower = c(0, 0))
+ ))

number of accepted runs: 249 out of 1000 (24.9%)
    user system elapsed
10.901    0.000    10.899</pre>
```

We plot only the residual sum of squares and the error variances; which=NULL does that (figure 12).

```
> plot(MCMC2, Full = TRUE, which = NULL)
```

The summaries for both Markov chains show only small differences.

> summary(MCMC)

```
meanp1p2var_modelsd0.0052372736.1057973.108551e-05min0.13108207732.0761431.114977e-05max0.16314919065.8348792.384232e-04q0250.14254777545.9745122.284145e-05q0500.14549765249.5819153.146526e-05q0750.14894587052.7378814.389924e-05
```

> summary(MCMC2)

```
p1 p2 sig.var_y sig.var_y.1
mean 0.144824252 49.044737 3.191614e-05 1.650702e-04
sd 0.005591581 6.541036 2.039365e-05 1.170012e-04
min 0.128591428 31.890671 7.070847e-06 4.363985e-05
max 0.168157781 83.173529 1.426655e-04 2.287789e-03
q025 0.141339254 45.258553 1.830466e-05 9.773926e-05
q050 0.144280117 49.083896 2.591655e-05 1.363419e-04
q075 0.148297529 53.197281 3.731158e-05 1.987369e-04
```

¹A similar example is also discussed in vignette ("FMEother"). Here the emphasis is on the MCMC method

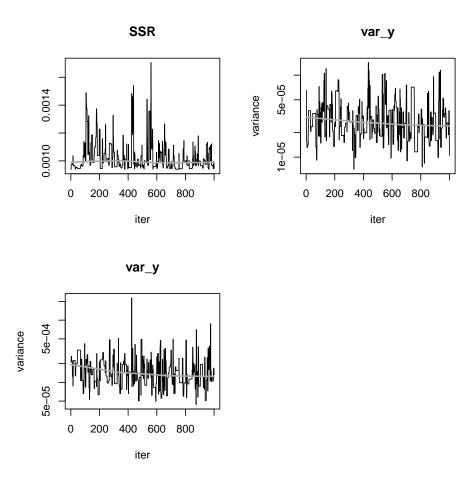


Figure 12: The mcmc chain, separate error variance per data set - see text for $\mathsf{R}\text{-}\mathsf{code}$

If var0 has the same number of elements as the number of data points, then distinct error variances for each data point will be estimated.

8. Finally

This vignette is made with Sweave (Leisch 2002).

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