Code:

```
#include <Servo.h>

Servo myservo;
int pos;

String readvoice;
const int RELAY_PIN = A5;   //define relay pin
const int BUZZER_PIN = A4;  //define buzzer and LED pin
void setup() {
Serial.begin(9600);
pinMode(RELAY_PIN, OUTPUT);   //set relay pin as output
pinMode(BUZZER_PIN, OUTPUT);  //set buzzer and LED as output
myservo.attach(10);

}

void loop() {
digitalWrite(RELAY_PIN, HIGH);   //initially set relay as HIGH
while (Serial.available())       //while Bluetooth is connected
{
delay(3);
char c = Serial.read();         //read input from HC-05
readvoice += c;                //append the words
}

if(readvoice.length() > 0)     //works if any word is read by HC-05 other than
null
{
Serial.println(readvoice);

if(readvoice == "lift")      //checks if command is lift

{
  for (pos = 0; pos <= 90; pos += 1)   //rotate the servo from 0 to 90 degrees
  {
    myservo.write(pos);
    delay(50);
  }

}

if(readvoice == "down")               //checks if command is down
{
  for (pos = 90; pos >= 0; pos -= 1)   //rotate the servo from 90 to 0 degrees
  {
    myservo.write(pos);
```

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    delay(50);
}

}


if(readvoice == "water")              //checks if command is down
{
digitalWrite(RELAY_PIN, LOW);         //dc motor pump runs for 5 seconds
delay(5000);
digitalWrite(RELAY_PIN, HIGH);
}


if(readvoice == "help")            //checks if command is help
{
digitalWrite(BUZZER_PIN, HIGH);       //led and buzzer turns on
}
if(readvoice == "stop")            //checks if command is stop
{
digitalWrite(BUZZER_PIN, LOW);        //led and buzzer turns off
}

}
readvoice="";                        //read voice declared as string
}
```