

A

Project Report On

**“DESIGN AND DEVELOPMENT OF AUTOMATED WRITING MACHINE”**

Submitted in partial fulfillment of the Requirements for the award of degree of

**BACHELOR OF TECHNOLOGY**

*In*

**Electrical and Electronics Engineering**

**By**

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**DEPARTMENT OF ELECTRICAL & ELECTRONICS ENGINEERING**

**ANNAMACHARYA INSTITUTE OF TECHNOLOGY AND SCIENCES :: RAJAMPET**

**(AUTONOMOUS)**

(Approved by AICTE, NEWDELHI & Affiliated to J.N.T. University, Anantapur) Accredited by NBA

and NAAC of UGC, BANGALORE.

Rajampet, Kadapa (Dist), A.P-516126.

2022-2023

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# DEPARTMENT OF ELECTRICAL & ELECTRONICS ENGINEERING

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This is to certify that the project work entitled “**DESIGN AND DEVELOPMENT OF AUTOMATED WRITING MACHINE**” is a bonafied record of work done by

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**Bachelor of Technology in the E.E.E. during the year 2022-2023.**

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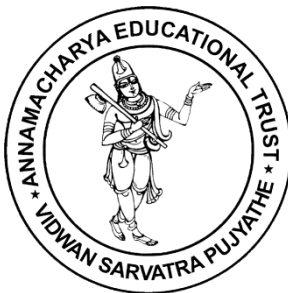
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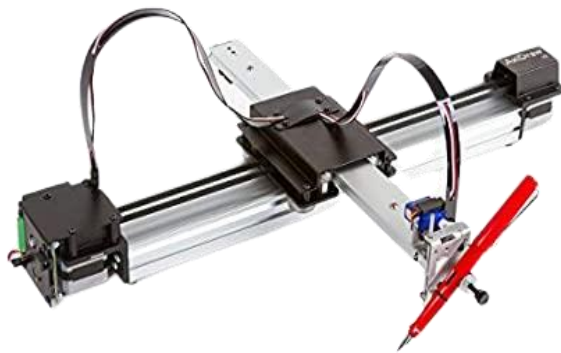
We express our gratitude and sincere thanks to all Project Review Committee members for their support and cooperation in successfully completing Project Stage.

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## **ABSTRACT**

The progressions in the new modern patterns have led to a mechanical advancement, which is prompting the improvement of Industry 4.0 with exceptionally mechanized ventures through human-machine collaboration. As the interaction gets more perplexing and lumbering, robotization turns out to be more crucial for the development and productivity of a framework. Robotized machines are more exact, adaptable, ideal decrease the likelihood of mistake altogether. Lately, various frameworks were proposed to work as a composing machine that can give yield in predefined text styles. The framework proposed in this paper manages perceiving the text in the record and afterward giving the result in the client's textual style. Utilizing this strategy also, the heaviness of the whole framework is made generally lower than the other financially accessible composing machines.



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## **LIST OF ABBREVIATIONS**

<b>CNC</b>	<b>-</b>	<b>Computer Numerical Control</b>
<b>OCR</b>	<b>-</b>	<b>Optical Character Recognition</b>
<b>UGP</b>	<b>-</b>	<b>Universal G-Code Platform</b>
<b>DRO</b>	<b>-</b>	<b>Digital Read Out</b>
<b>USB</b>	<b>-</b>	<b>Universal Serial Bus</b>
<b>AWM</b>	<b>-</b>	<b>Automated Writing Machine</b>
<b>PWM</b>	<b>-</b>	<b>Pulse Width Modulation</b>

# **CHAPTER - 1**

## INTRODUCTION

Industry 4.0, also known as Brilliant Assembling, is a manufacturing breakthrough that is taking place as the globe transitions into a new era. The Business 4.0 uprising may seem more feasible given how quickly organizations are adopting computerized innovations like modern mechanical technology, 3D printing, AI, optical person recognition, distributed computing, expanded reality, and sensors.



Fig 1 Writing Machine

Humanity is going to robots to accomplish the work and diminish human exertion. Time and labor are the two main basic constraints on completing any projects with a broad scope and efficiency in today's society, which is undergoing rapid development. So, in many of the routinely carried out tasks like welding, painting, gathering, filling holders, authoring, and so forth. Computerization is playing a crucial role in saving a lot of human labor. Considering everything, mechanization can help avoid the time and effort required to compose the keys on a console, which is laborious and necessitates a lot of skills and human activities.

To write only the built-in text styles like Roman, Calibri, Arial, Effect, Georgia, and so on, advances like automated speech to message converters are used. The paper aspires to develop a framework that is prepared for writing on a page with the aid of a pen in the client's unique handwriting or, if necessary, in any of the predefined text styles.

Hence, the concept of CNC machines—PC mathematical control machines—as an intriguing and adaptable kind of delicate computerization is introduced. It was initially developed to regulate the motion and furthermore the functioning of technological devices. A computerized machine can be used to execute ideas like CNC machines in order to write additionally the general equipment arrangement of the proposed framework.

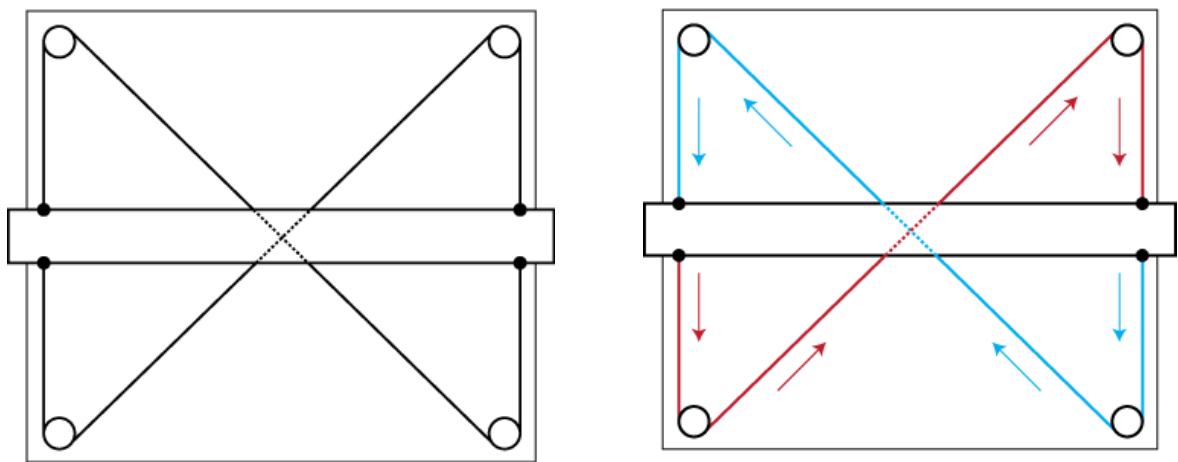
People can read the text on an image and identify the objects in it by looking at it, but PCs require a more co-ordinated comprehension strategy. Computers are used to view the images. Visual Person Acknowledgment includes locating and acknowledging messages contained in sophisticated photographs as well as totally converting these messages to an encoded format that PCs can easily decode. It has been used in a few applications, such as the recognition of license plates captured by cameras or the examination of handwritten records to create electronic copies of them.

## OBJECTIVE

The Objective of this project are:

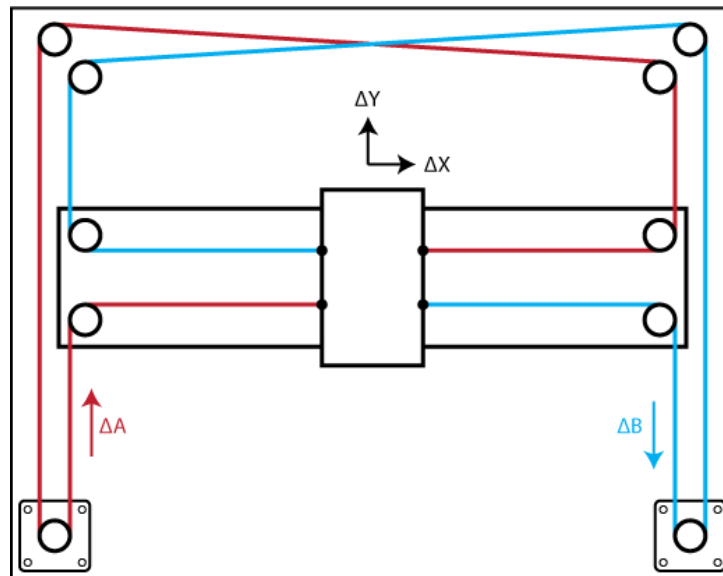
- This Automated writing and drawing device is used to save the wastage of time.
- There are a lot of automated drawing machines are there. But this is useful among all.
- By this we can make the notes in our own handwriting just by giving the input to the machine. We don't need to waste lots of time by sitting in front of the work
- This machine will be able to draw and write the assignments and other hand written notes in our own handwriting • By this we can save our time.
- This machine can be used very easily for writing we just need to give the input text and for drawing we need to give the measurement as the input..

## Principle of Operation



This is a standard drafting table. The horizontal bar is a straight-edge which can be moved up and down by the user. The criss-cross pattern of the cables stabilizes the bar and keeps it horizontal.

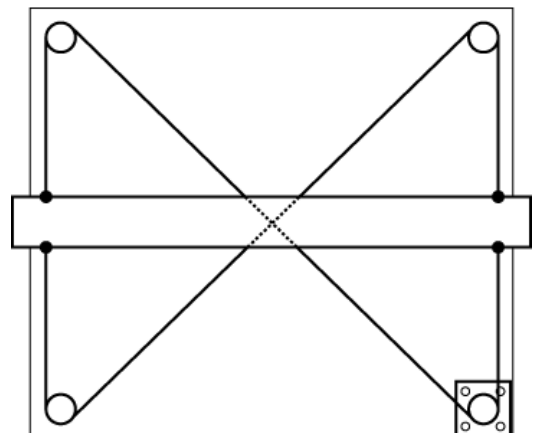
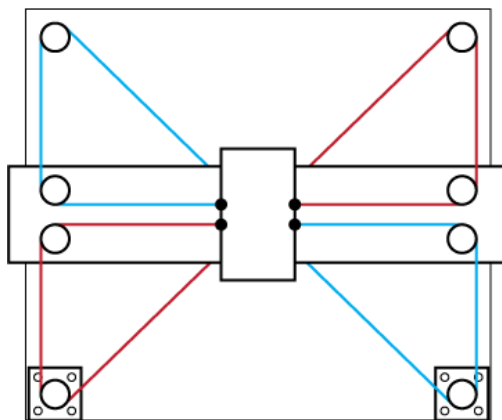
This effect can be seen by following the direction of motion of the two cables which comprise the mechanism. Note that all of the vertical arrows point in the same direction.



Equations of Motion:

$$\Delta X = \frac{1}{2} (\Delta A + \Delta B), \quad \Delta Y = \frac{1}{2} (\Delta A - \Delta B)$$

$$\Delta A = \Delta X + \Delta Y, \quad \Delta B = \Delta X - \Delta Y$$



You could imagine attaching a stepper motor to one of the pulleys. Now, the horizontal bar can be moved up and down under computer control. This might be called a single-axis CNC stage.

## Mechanism

How might we modify this mechanism to convert it into a two-axis CNC stage? The illustrated mechanism above is one solution. Rotating both motors in the same direction results in horizontal motion. Rotating both motors in opposite directions results in vertical motion.

This reference mechanism is functionally identical to the last figure in the prior section. Two additional pulleys have been added to shift the belt cross-over outside of the working envelope.

## *Goals*

### **THE GOAL OF THIS PROJECT ARE:**

- This machine-controlled writing and drawing device is employed to save lots of the wastage of your time.
- There are heaps of machine-controlled drawing machines. however, this is often helpful among all.
- By this we are able to build the notes in our own handwriting simply by giving the input to the machine. we do not have to be compelled to waste a lot of time by sitting ahead of the work
- This machine is able to draw and write the assignments and different hand written notes in our own handwriting
- By this we are able to save our time.

## *ALGORITHM*

The G-Code file created by the assistance of Inkscape

Software then the process code is employed to send the GCode file to the Arduino controller unit (via USB) then The CNC protect drive send the dominant signals to the stepper motors and servo motor.

## *BLOCK DIAGRAM*

As shown in the block diagram of the automatic writing machine (AWM) it represents the working process of AWM. The laptop or pc is connected with Arduino with help of USB cable and Arduino connected to the motor driver and act as an input. It pass the signal to the motor driver and motor driver give the signal to stepper motor. The stepper motor is place in linear position for moving the direction of X & Y. X movement left to right and Y movement forward and backward direction, servo motor is gives the movement of pen or marker up & down.

## **CHAPTER-2**



## EXISTING SYSTEM

Modern Innovations like printers and scanners only write in specified text styles that are present on the PC. It is addressed in a slate show or a power point presentation. The kids describe board shows, an interaction that has been going on for a while, as being tiresome. Power point presentations are used to further improve, as they are more engaging and simpler than chalkboard instruction.

**DRAWBACKS: -**

The main flaw in this study is that the same method of instruction makes for a monotonous learning environment for both teachers and students. This system causes interest in a student's capacity for observation to decline.

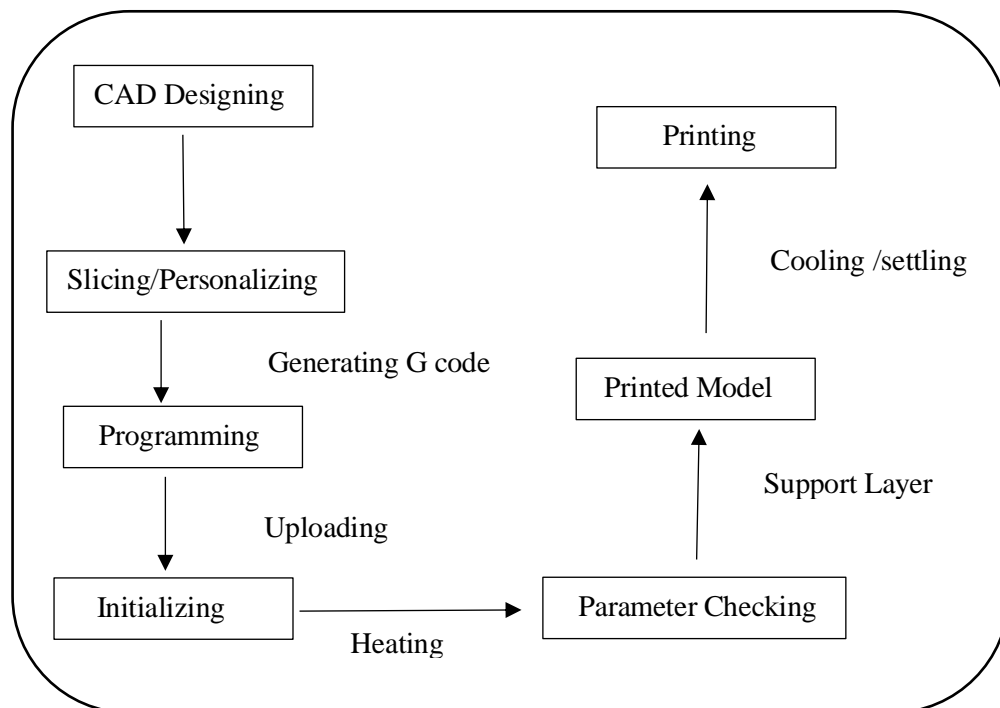


Fig 2 OCR Writing Machine

## **CHAPTER-3**

## **Literature Survey**

### **POLYGRAPH: -**

The first signature duplicating devices called polygraphs, were created by John Isaac Hawkins in the year 1803, and they resemble modern autopens in both appearance and operation. Pen and ink copies of a document were made using the Polygraph.



Fig 3.1 POLYGRAPH

### **TYPEWRITER: -**

In 1874, the first typewriter for business use was released. It was a device that employed a variety of keys to write characters.



Fig 3.2 TYPEWRITER

### **TELAUTOGRAPH -**

Elisha Gray is credited with coming up with it in 1888. It sends electrical impulses produced by the sending end's potentiometer to the receiving end. A pen attached with a servomechanism at the receiver.

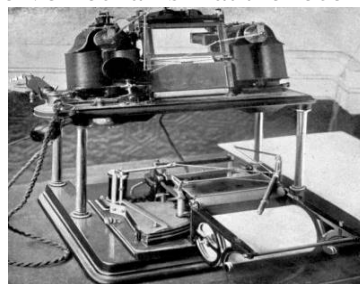


Fig 3.3 TELAUTOGRAPH

### **AUTOPEN -**

An automatic signature tool is called an autopen, commonly referred to as a signing machine or robot pen. It was created in 1980 and used as a storage device to store signed nature notes.



Fig 3.4 AUTOPEN

### **LONG PEN:-**

The long pen is an alternative to the autopen, a remote signing tool invented by Margaret at Wood TN in 2004 that enables users to sign documents from a distance using a computer, the internet, and a robotic hand.

### **AXI DRAW :-**

Dr. Lin claims that Robert Wilson presented the axi draw project in 2014. This functions as a flexible pen plotter that is compatible with a number of writing implements, including fountain pens and permanent makers.



Fig 3.5 AXI DRAW

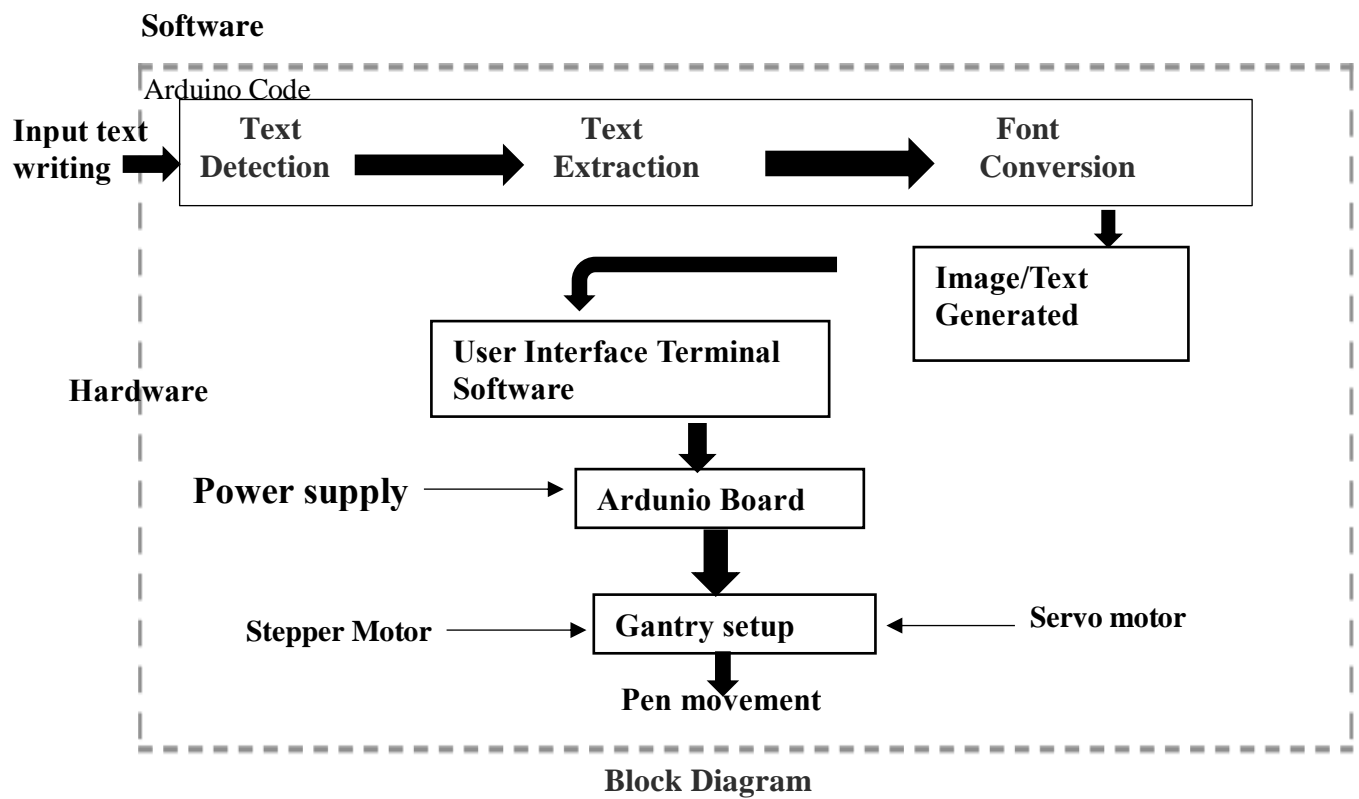
## **CHAPTER-4**

## **Proposed System**

Information is represented via an image of the studied record. The text in the checked report may be written using the client's handwriting or a specified textual style. The upcoming sections will demonstrate how this information picture is handled to achieve the best outcome. By programming the proposed framework, one can automatically form their job to make it simpler.

According to the title, this is a straightforward task using Arduino to create a composing machine at the workplace that can design any pattern and create many textual styles. This framework was implanted, and the PC Mathematical Control machine is what determines how it operates. It makes use of an Arduino development board, which is connected to similar engines, to provide the basic pen development on the paper. On the basis of the information picture that is taken care of in the framework. The Arduino board is coupled with one servo engine and two stepper engines to carry out the pen development and x-y hub gantry development independently. Z-pivot requires the pen that is attached to the structure. The servo engine aids in the pen's upward development so that the nib touches the paper only when something needs to be written and is elevated above when not needed. This z-hub pen movement combined with the x and y pivot development made possible by the stepper engines results in a two-layered sketch on the paper.

The main goal of this project is to finally see the text characters as they have been written down with the aid of a human handwriting arrangement. This is different from other innovations, like OCR to discourse acknowledgment, where the main idea is to read and pre-process the text in order to convert it to a discourse signal in the end.



## **CHAPTER-5**



## **Tools Required**

Hardware	Description
Processor	Intel Core i7 @ 2.70 GHz
Memory	8.00 GB
Hard Disk Space	256 GB
Device	HP Pavilion
2D CNC Plotter	Other hardware (Arduino UNO, Servo motor, etc)

**Table 1.** Hardware Requirements

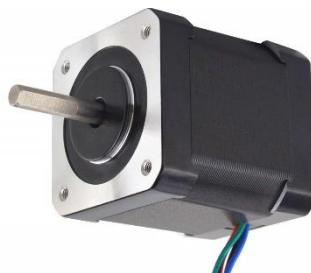
Software	Description
Operating System	Microsoft Windows 10
Inkscape	Graphics application
G-Code	Command to change geometric details, control CNC machine
Programming IDE, Arduino IDE	Python, Embedded C
Browser	Google Chrome, Microsoft Edge

**Table 2.** Software Requirements

### **Hardware:-**

#### **Stepper Motor:**

Stepper can be converted to a computerized beat for pen development using X, Y, and Z heading pivots. A stepper engine is a brushless engine that divides a full turn into several comparable advances. Its ability to convert different driving pressures into a defined rise in shaft position makes it a well-known type of engine. The shaft passes through the right place with each heartbeat. Three stepper engines with lead screws have been used. The lead screw's pivot will be the engine as a result.



**Fig 5.1** Stepper Motor

Specifications:

Step angle	1.8 degrees
Current	1.2 A/Phase
Holding Torque	4.2 Kg-Cm
Detent Torque	2.2N.Cm
Lead Wire	4
Shaft Diameter	5mm

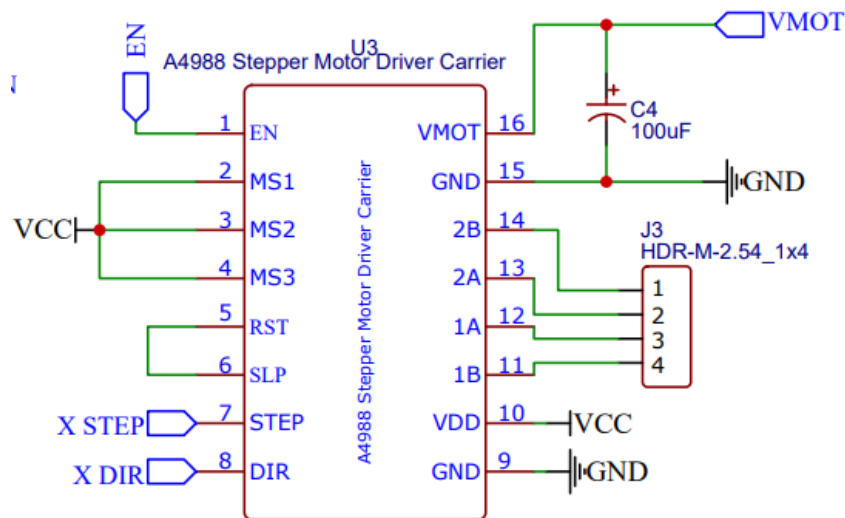


Fig 5.1.1 Pin Diagram of X-Axis Stepper Motor

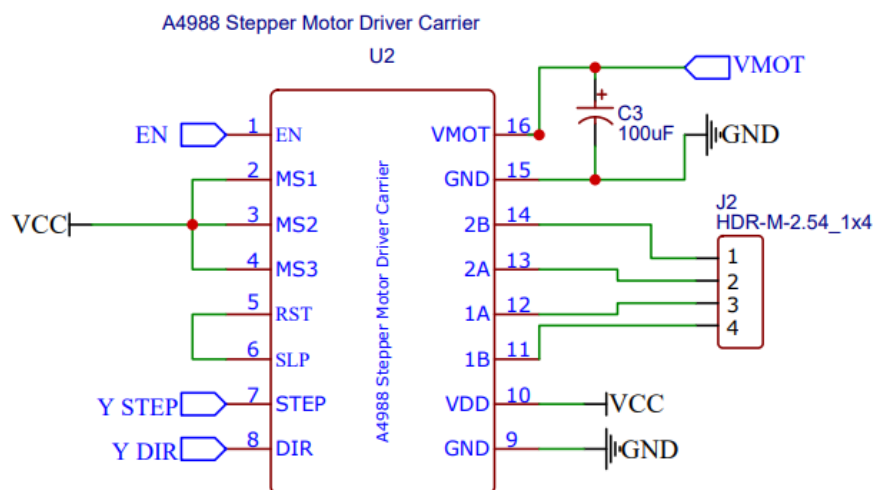


Fig 5.1.2 Pin Diagram of Y-Axis stepper Motor

**Servo Motor:**

A servo engine is special because it has the ability to receive a control signal that specifies the perfect position for the servo shift and then supply power to the DC engine until the shaft reaches that location.



Fig 5.2 Servo Motor

**Specifications:**

Weight	55gm
Dimensions	39.5mm*20.5mm*40.7mm
Operating Voltage	4.8 ~ 6.6 V
Gear type	Metal Gear
Temperature range	0- 55 Deg
Servo wire length	30 Cms
Speed	3000 – 5000 rpm
Operating Speed	0.20 sec / 60 Degrees (4.8 V)

**Fig 5.2.1** Pin Diagram of Servo Motor**Arduino:**

The distinguishing feature of Arduino is that it receives commands or Information from a PC via a USB connection. It is put on a CNC guard, and using a stepper driver, it will transmit additional data from the Arduino to the guard. The Arduino UNO is a microcontroller board that includes all the necessary components to interface the microcontroller with a PC through a USB cable and a power source. With the use of a software, it directs the stepper engine's location. It is an open-source platform with user-friendly hardware and software programming.

These sophisticated and straight forward information/yield pins can connect to many boards, circuits, and microcontrollers with related components to help with programming and combining into various circuits. 5 volts are currently supplied together with a USB interface.

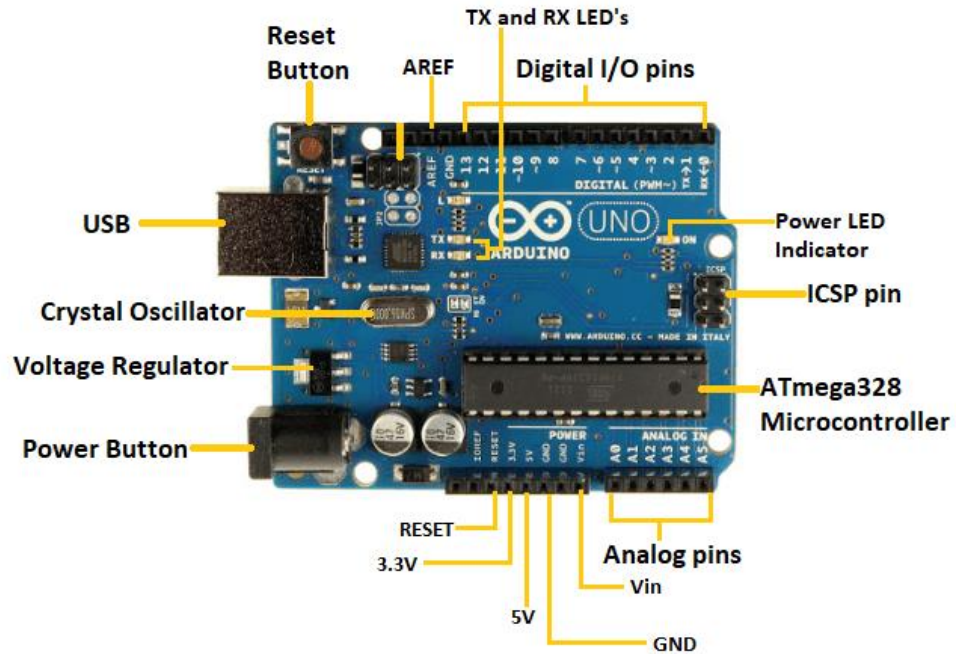


Fig 5.3 Arduino UNO

Specifications:

Micro Controller	ATmega328P
Operating Voltage	5 V
Input Voltage (Limit)	6-20V
Digital I/O Pins	14
Analog Input Pins	6
Clock Speed	16 MHz
DC Current For 3.3V Pin	50mA
DC Current Per I/O Pin	20mA

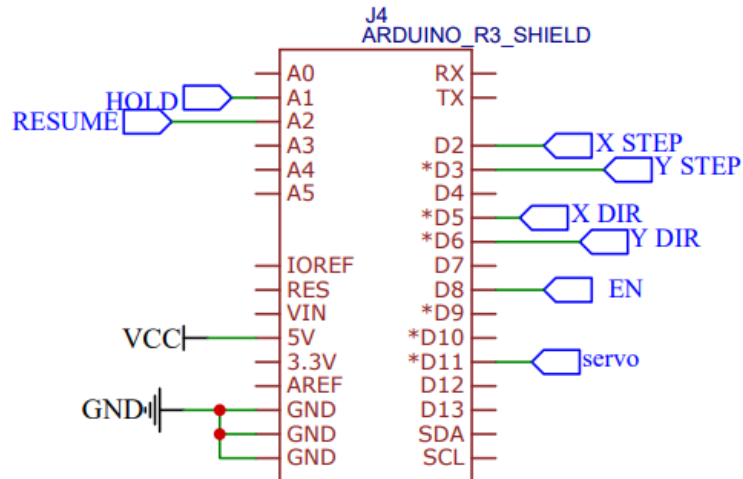


Fig 5.3.1 Pin Diagram for ARDUINO R3\_SHEILD

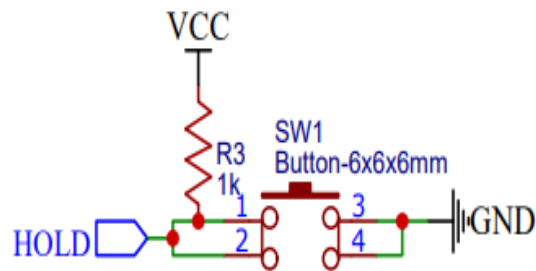


Fig 5.3.2 Pin diagram for HOLD Button

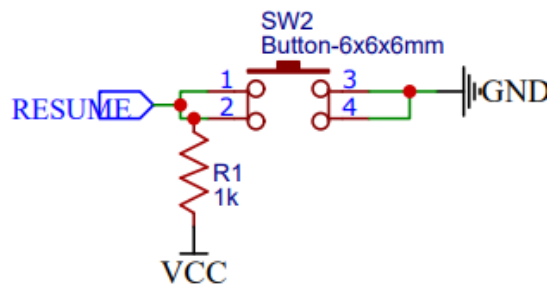


Fig 5.3.3 Pin Diagram for RESUME Button

**Linear Rods:**

Long, thin, straight metal bars known as linear rods are frequently utilized in a variety of applications that call for load-bearing or structural support.

1. Robotics: Precision linear motion in the X, Y, and Z axes is provided by linear rods in robotics applications.
2. Manufacturing: In order to support numerous components, including conveyer systems, assembly lines, and machining equipment, linear rods are employed in manufacturing processes.



**Fig 5.4** Linear Rod - 450mm

**Specifications:**

<b>Diameter</b>	<b>12mm</b>
<b>Length</b>	<b>450mm</b>
<b>Tolerance</b>	<b>-0.005mm to -0.03mm</b>



Fig 5.5 Linear Rod - 350mm

**Specifications:**

<b>Diameter</b>	<b>8mm</b>
<b>Length</b>	<b>350mm</b>
<b>Tolerance</b>	<b>-0.005mm to -0.03mm</b>

**SOFTWARE****ARDUINO IDE**

Arduino is associated with the ASCII text file physics platform supported easy-to-use hardware and software system. Arduino IDE (Integrated Development Environment) is that the software system for Arduino. It's a text editor sort of a pad of paper with totally different options. It's used for writing code, assembling the code to see if any errors square measure there and uploading the code to the Arduino.

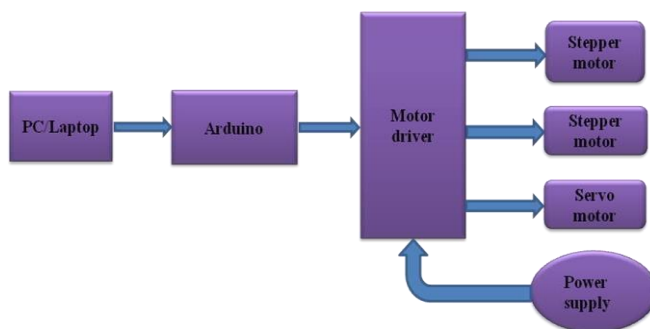


Fig 5.6 : Arduino IDE

## Inkscape 0.9.2

To create the plotted figure or text, use Inkscape. With this software, a G-code file of a chosen image or piece of text is made for this project. X, Y, and Z coordinates are part of the widely used numerical control programming language known as G-code..

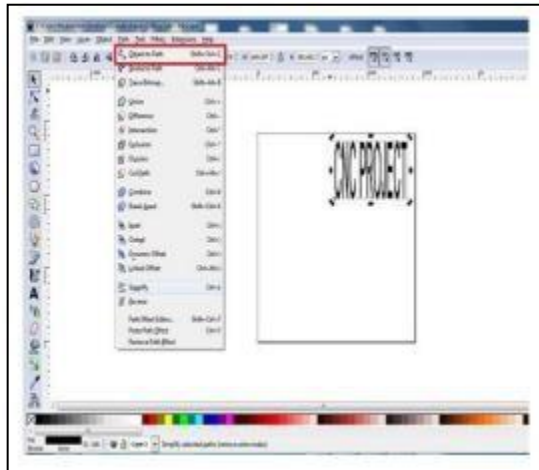


Fig 5.7 Inkscape 0.9.2

## Creating G-Code File Using Inkscape

Our project's CNC plotter will operate within a 20cm-by-20cm region. Because the plotter can only draw in the first quadrant, we choose the document attributes of the Inkscape 40cmx40cm (Width Height) document, which is four times the working area of the plotter. As a result, we first kept the axes at the motors' closest end, which is thought of as an origin to quickly change the design. The working area of the CNC plotter with the text typed in the designated area. To save the text's G-code format, select "object to path" from the drop-down window after using the cursor to pick the desired text.

The image file must have a transparent background in order to generate the G-code for it. To generate a transparent picture, drag the image into the chosen area and then choose "trace bitmap" from the drop-down menu. The "Edge detection" option is used to produce black and white images while the scans are set to 8. Using the procedures outlined previously, we added this transparent image to the designated region and then used the "object to path" command to produce the G-code file for the chosen image.



### **G – CODER: -**

"G" is presenting this. G-codes are pre-defining functions linked to Machine Axis Movement. It is a two-digit number, such as G00, G01, or G02. It is possible to place multiple G addresses in a single block. As long as these Functions do not conflict with one another. G01 and G02, which are located together in a single block, are not permitted. The path that must be taken to create a whole design is specified by the g function. positioning with

ExG00- positioning.

G01- Linear interpolation

G02- Clockwise Circular Interpolation

G03- Counter clockwise Circular Interpolation G04- Dwell

## **CHAPTER - 6**

## WORKING

First, the system must have the Arduino software installed.

Once the devices are fixed, the programming code will be uploaded to the Arduino Uno board.

The system's sensors identify the user, retrieve user input from stored documents, and then return

the result and allow the user to begin writing on paper.

The speech-independent system is less effective than the sensor. Due to pattern matching's

inability to handle accents, varied delivery speeds, pitch, volume, and intonation, speaker-

independent

speech recognition has been shown to be highly challenging.

The automatic pen also serves the purpose of enabling the user to create a new document that

doesn't already exist on the hard drive or plates.

The new document is kept on the hard drive for subsequent use.

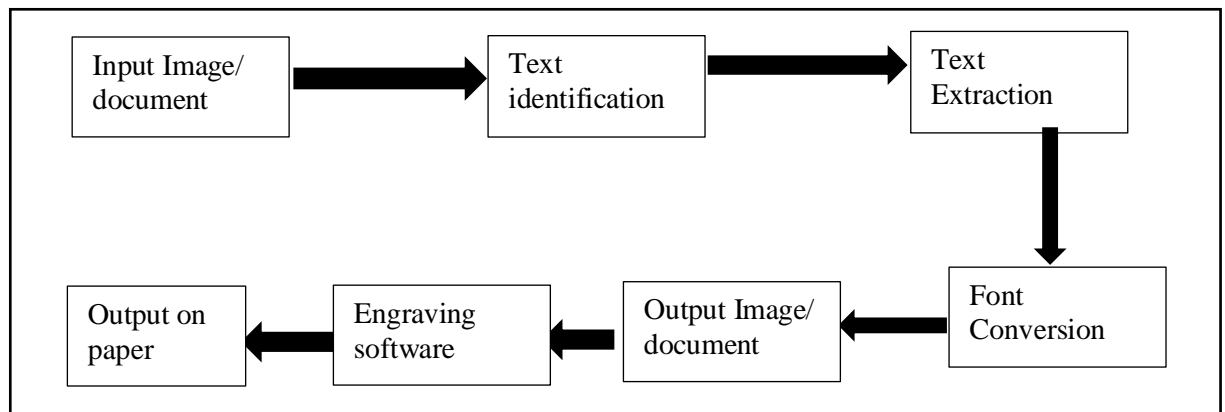
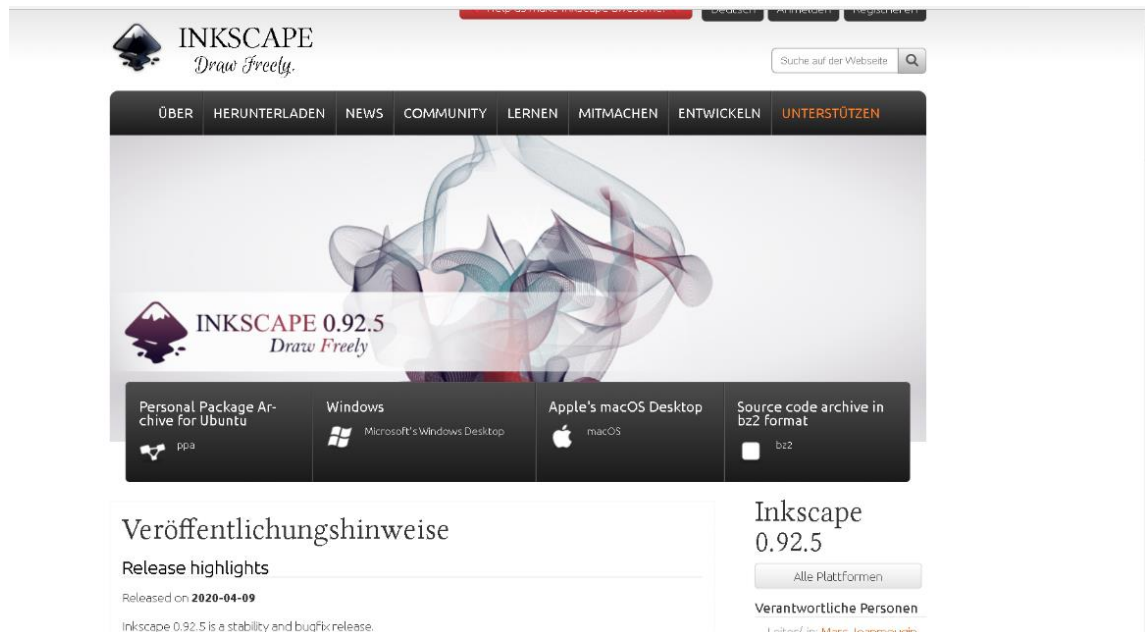
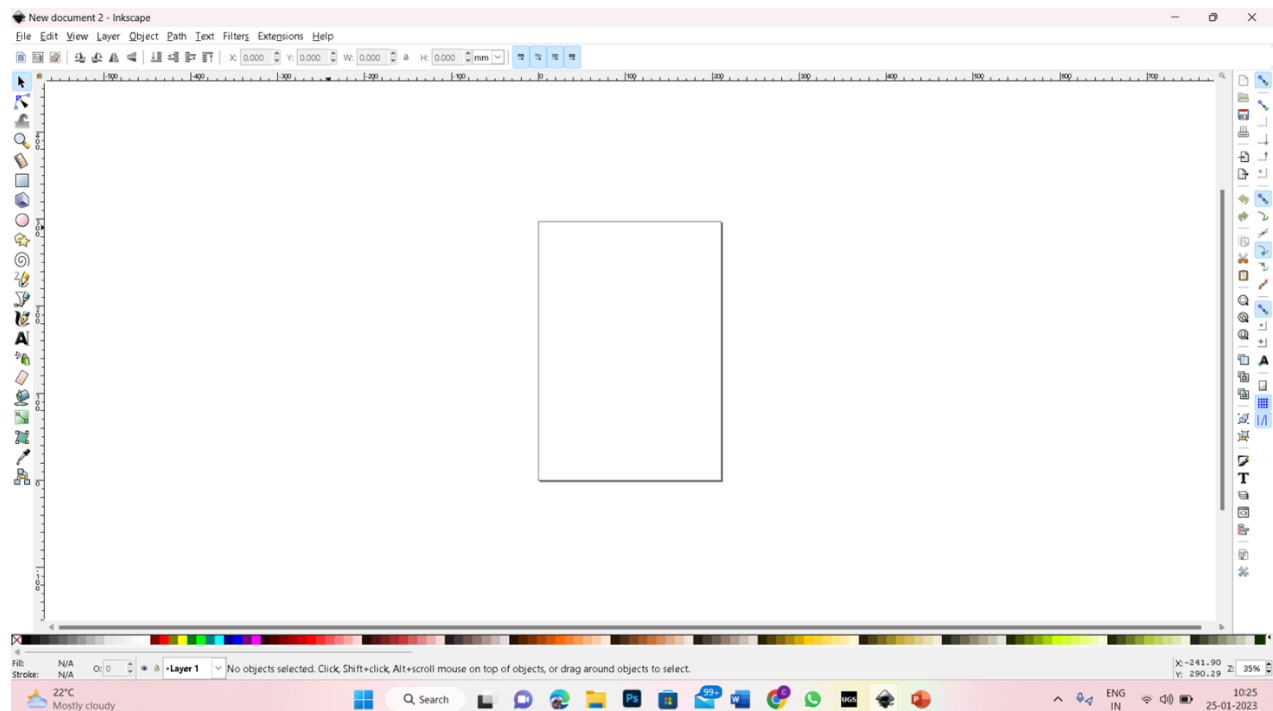


Fig 6.1 The flowchart of the overall process in an automated writing machine

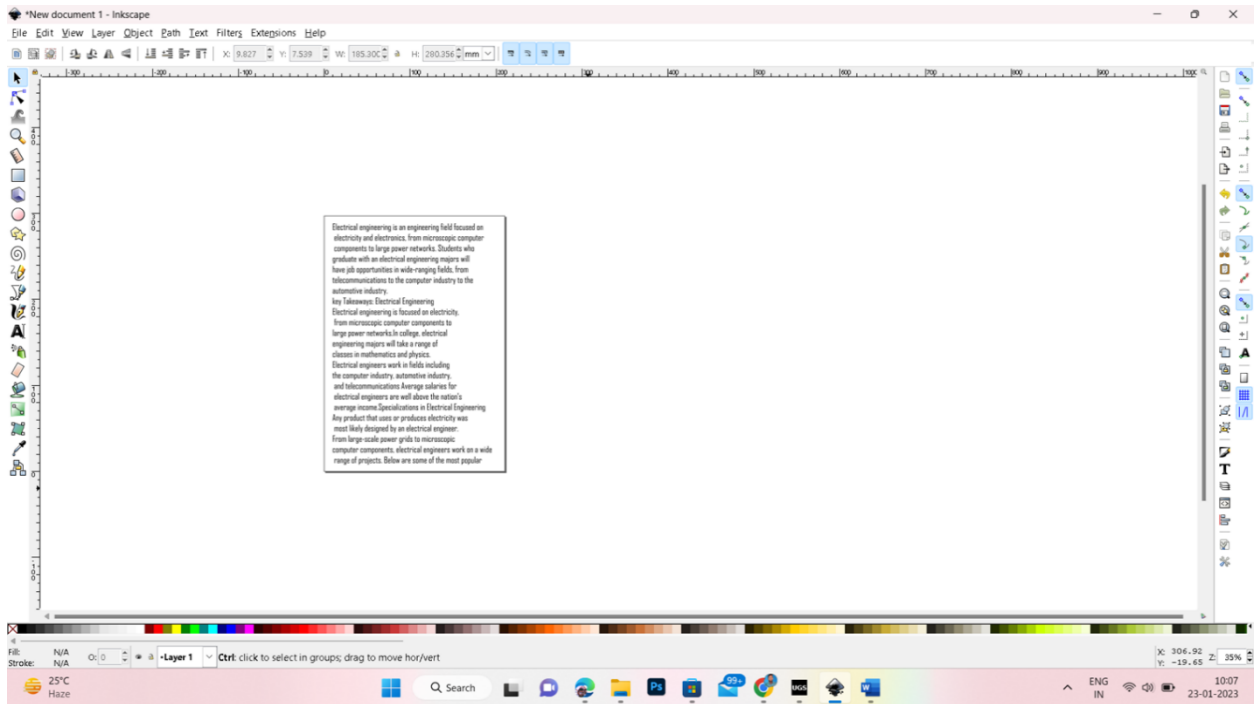
## Step 1: Install Inkscape software 0.9.2



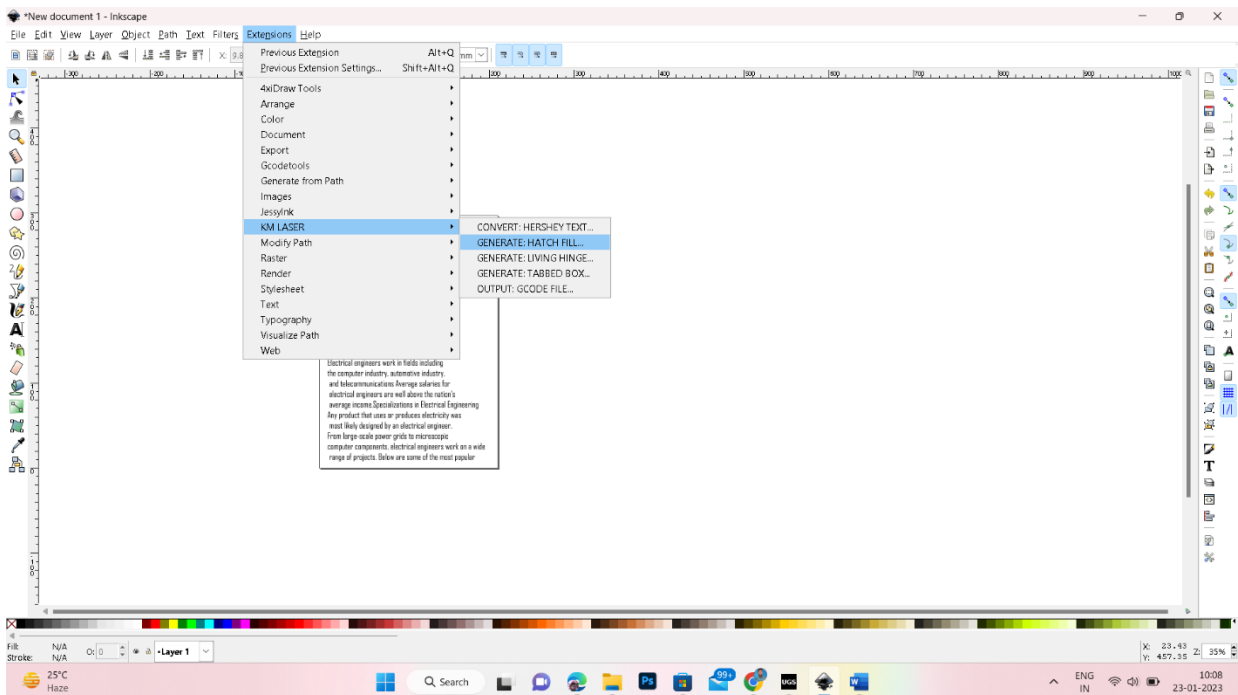
## Step 2: Open the Inkscape application



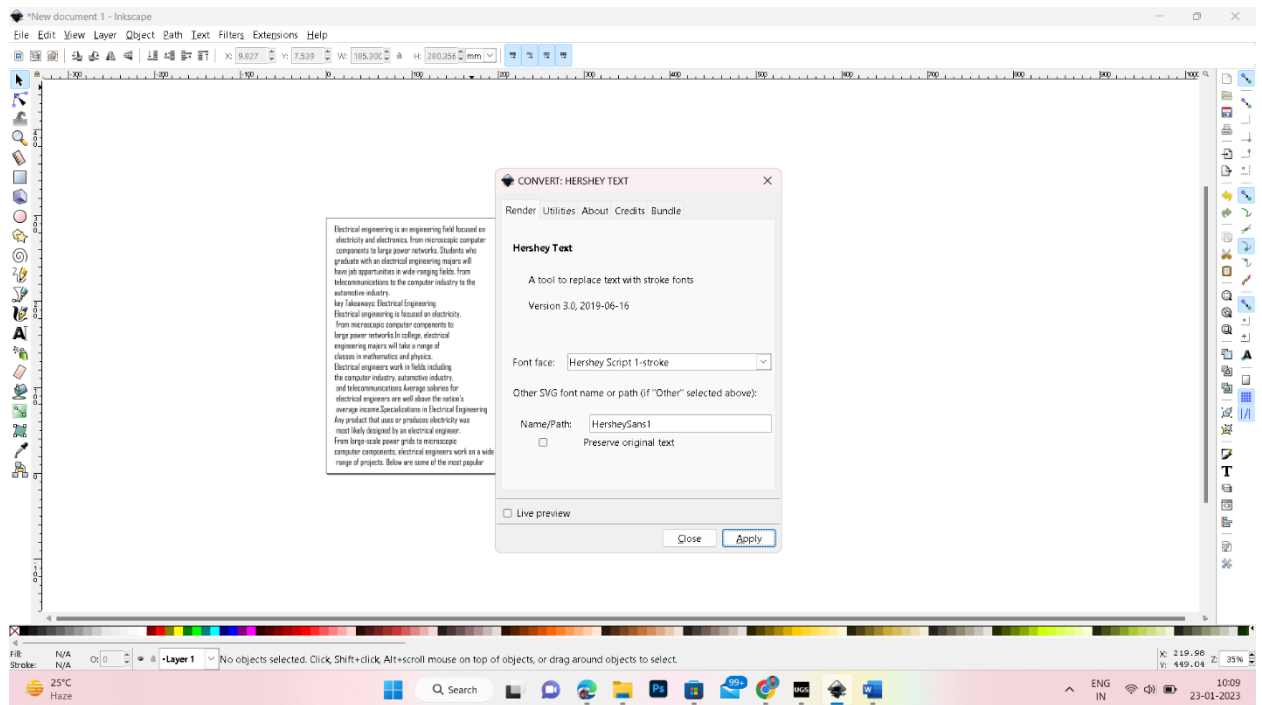
### Step 3: After that we can take text option and text



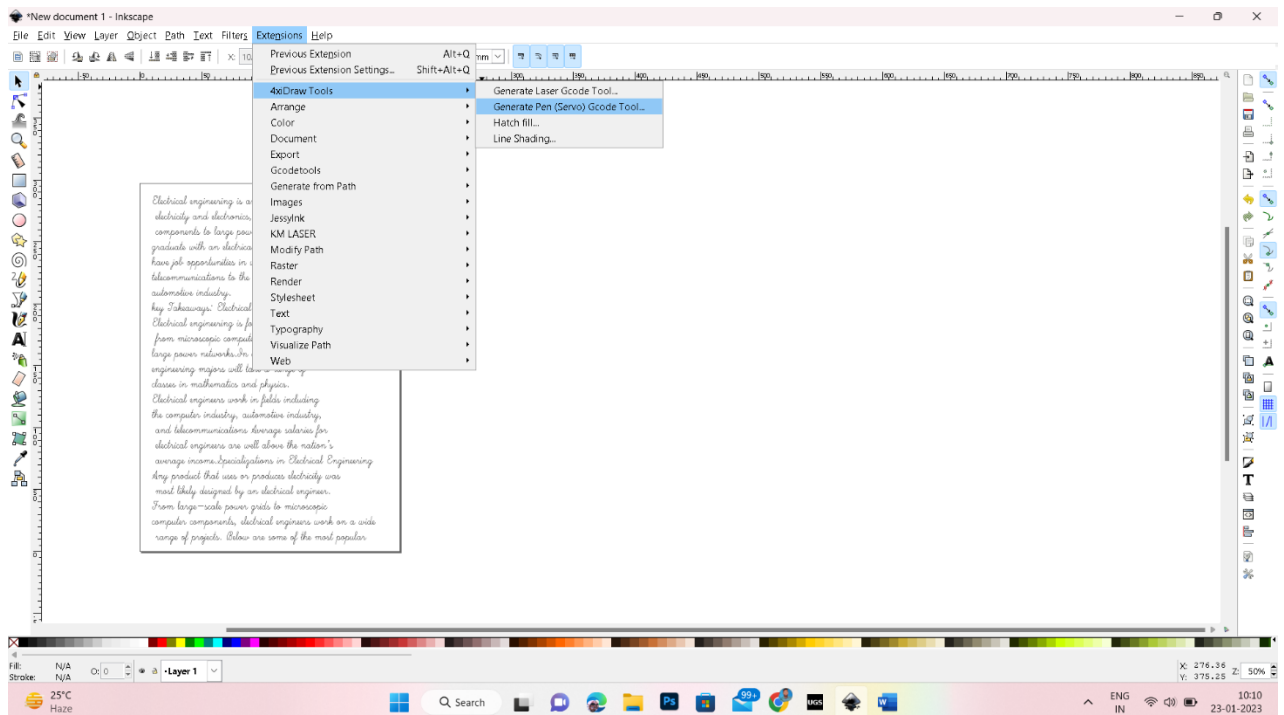
### Step 4: We will go to the extension file and we can select “KM laser” in that file. In KM laser we can select “convert Hershey text” (for converting text into different fonts)



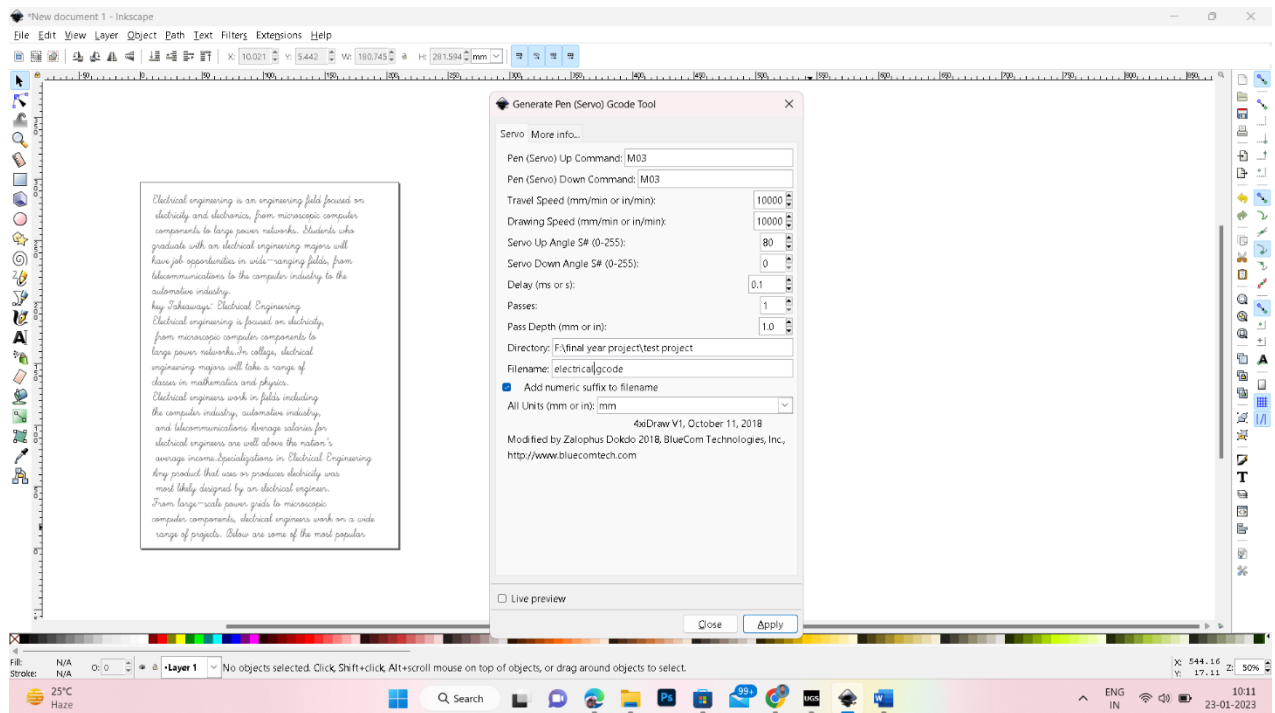
**Step 5:** After that font has been applied then it is converted in a selected font.



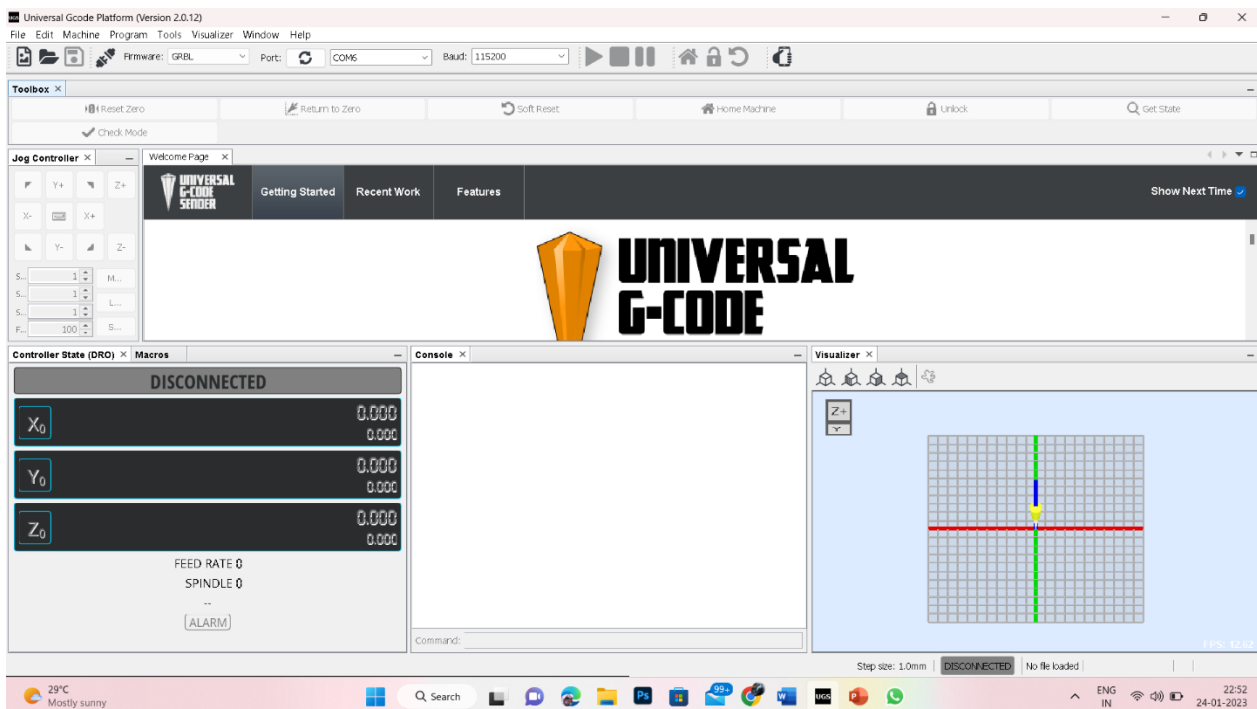
**Step 6:** We will go to the extension file to select “4xdraw tools” again and select “generate pen GCODE tool”.



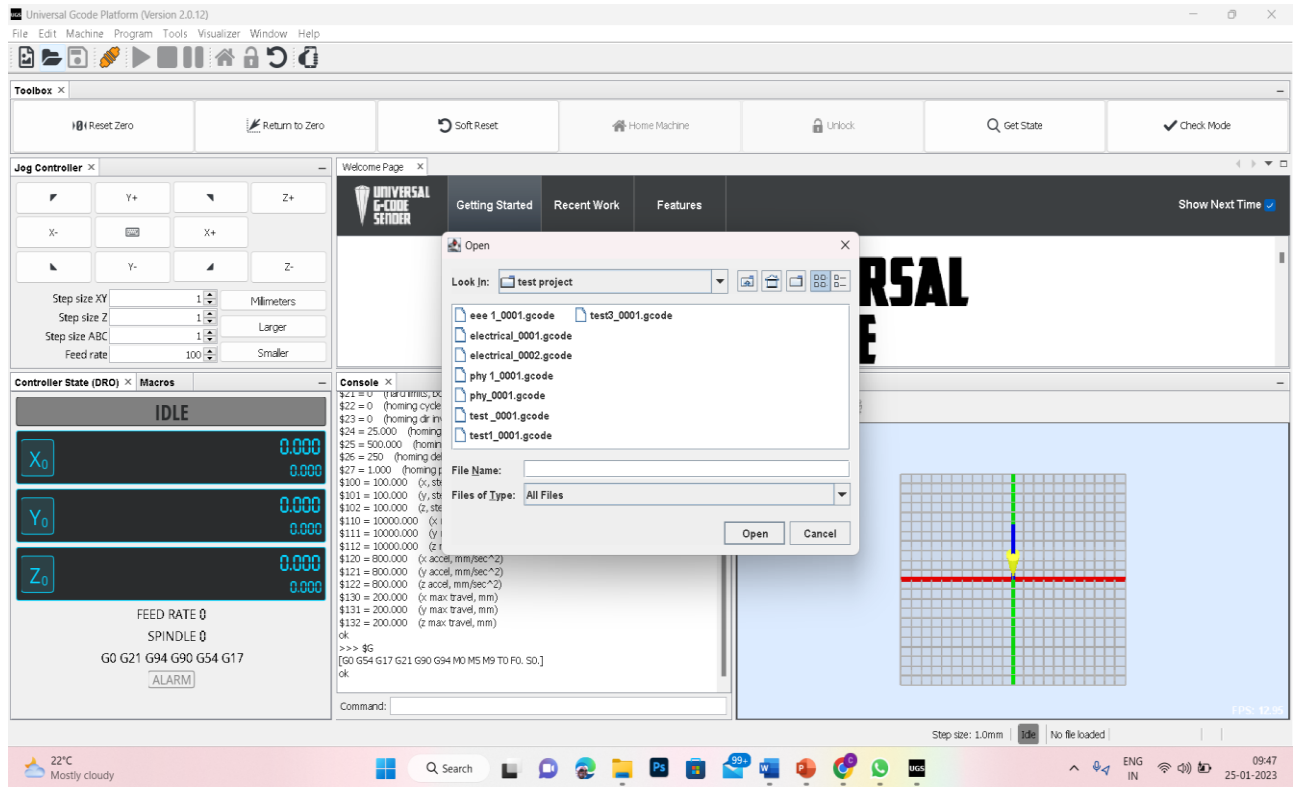
**Step 7:** We can select pen movement (up and down) travelling speed, servo angles and delay time. In dictionary we can select file location after we can give file name and click on the “apply” option.



**Step 8:** Next open UGP (universal G-Code platform) version 2.0.12. we can connect Arduino connection whether it is Connect or not.



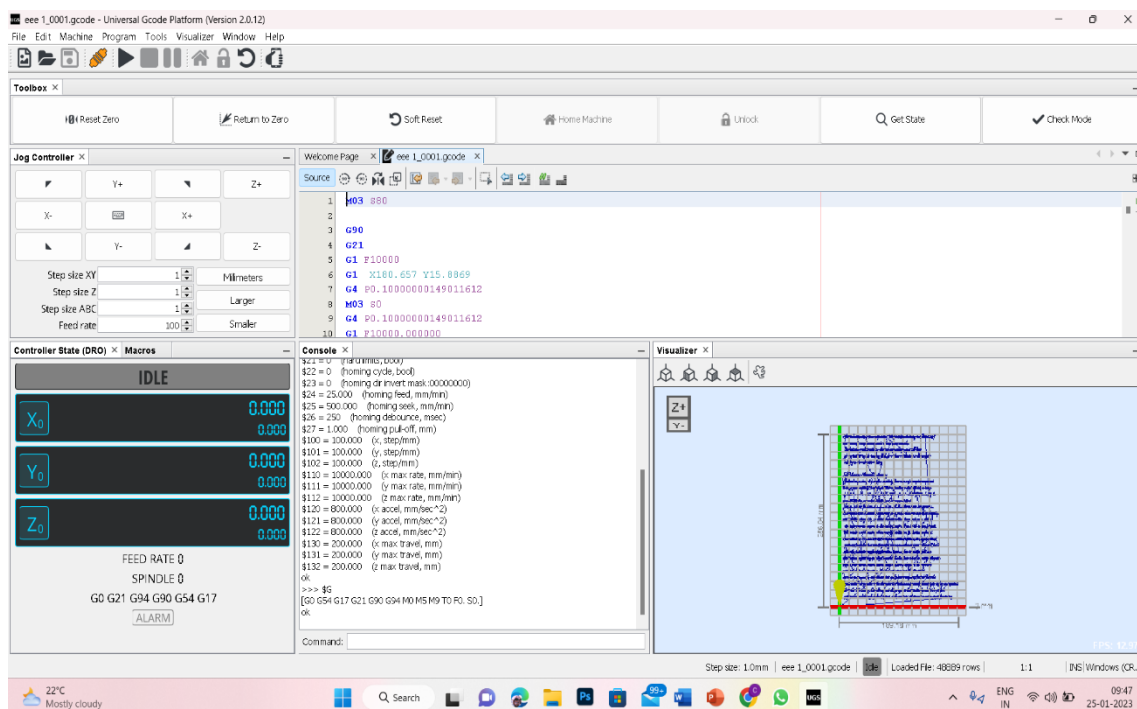
**Step 9:** Click on the connect or disconnect option. It is connected open file we can select file already which is saved in the inkscape after that we can select the file and open it. The automatically the source will display.



**Step 10:** In control state (DRO). We can set x-axis, y-axis and z-axis are zero. After we can run it. Before starting the pen movement in console we have to give commands for pen up and down

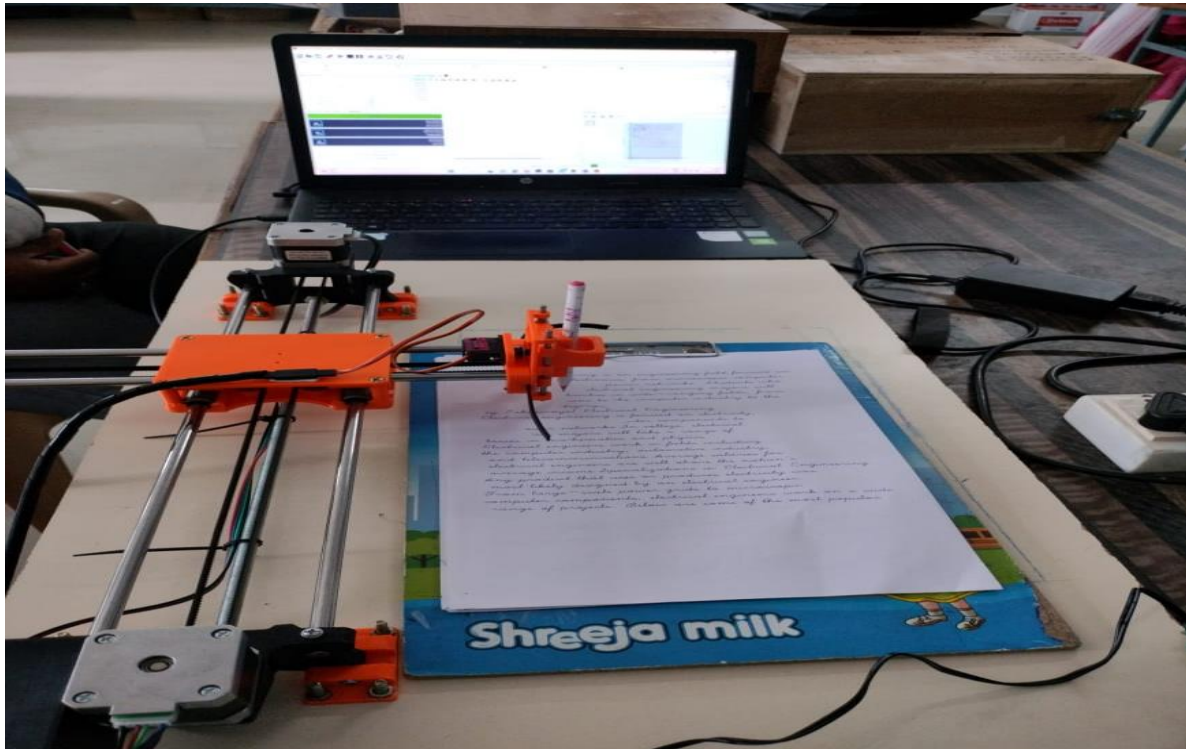
**Pen up=M03 S80**

**Pen down=M05 S10**





**Step 11:** After that it shows the pen movement how much speed it goes on x, y, and z-axis.



## **CHAPTER-7**

**CODE**

M03 S80

G90

G21

G1 F10000

G1 X31.929 Y223.3807

G4

P0.10000000149011612

M03 S0

G4

P0.10000000149011612

G1 F15000.000000

G1 X31.7068 Y223.161

G1 X31.9481 Y222.9007

G1 X32.1703 Y223.1007

G1 X31.929 Y223.3807

G4

P0.10000000149011612

M03 S80

G4

P0.10000000149011612

G1 F10000

G1 X27.5659 Y222.2606

G4

P0.10000000149011612

M03 S0

G4

P0.10000000149011612

G1 F15000.000000

G1 X28.2841 Y222.0186

G1 X28.8874 Y222.0377

G1 X29.3636 Y222.3806

G1 X29.5478 Y222.9807

G1 X29.5287 Y223.4791

G1 X29.243 Y223.803

G1 X28.7667 Y223.9236

G1 X28.4048 Y223.803

G1 X28.0047 Y223.6823

G1 X28.2841 Y225.4032

G1 X28.5254 Y225.6

G1 X29.7256 Y225.581

G4

P0.10000000149011612

M03 S80

G4

P0.10000000149011612

G1 F10000

G1 X27.0332 Y230.0353

G4

P0.10000000149011612

M03 S0

G4

P0.10000000149011612

G1 F15000.000000

G1 X26.7157 Y230.3556

G1 X26.9316 Y230.5957

G1 X27.2364 Y230.275

G1 X27.0522 Y229.8349

G1 X26.7538 Y229.3739

G4

P0.10000000149011612

M03 S80

G4

P0.10000000149011612

G1 F10000

G1 X25.452 Y232.7775

G4

P0.10000000149011612

M03 S0

G4

P0.10000000149011612

G1 F15000.000000

G1 X25.0774 Y232.9553

G1 X24.7535 Y232.8982

G1 X24.436 Y232.6569

G1 X24.3147 Y232.3584

G1 X24.436 Y231.9774

G1 X24.7345 Y231.6155

G1 X24.9948 Y231.2535

G1 X25.1536 Y230.8979

G1 X25.1345 Y230.5753

G1 X24.8932 Y230.275

G1 X24.5567 Y230.0753

G1 X24.2747 Y229.9953

G1 X23.9147 Y230.1556

G4

P0.10000000149011612

M03 S80

G4

P0.10000000149011612

G1 F10000

G1 X22.0141 Y232.4727

G4

P0.10000000149011612

M03 S0

G4

P0.10000000149011612

G1 F15000.000000

G1 X22.3742 Y232.7775  
 G1 X22.5742 Y232.9172  
 G1 X22.3742 Y231.8377  
 G1 X22.2142 Y230.8535  
 G1 X22.1938 Y230.3753  
 G1 X22.1938 Y230.1753  
 G1 X22.3742 Y230.8154  
 G1 X22.6542 Y231.4377  
 G1 X22.8942 Y232.0727  
 G1 X23.1914 Y232.5743  
 G1 X23.3565 Y232.7775  
 G1 X23.5724 Y232.8728  
 G1 X23.8328 Y232.8537  
 G4  
 P0.10000000149011612  
 M03 S80  
 G4  
 P0.10000000149011612  
 G1 F10000  
 G1 X21.4325 Y232.714  
 G4  
 P0.10000000149011612  
 M03 S0  
 G4  
 P0.10000000149011612  
 G1 F15000.000000  
 G1 X20.734 Y232.7585  
 G1 X20.2317 Y232.5362  
 G1 X19.8716 Y231.8949  
 G1 X19.7316 Y231.0757  
 G1 X19.7316 Y230.435  
 G1 X19.7916 Y230.1156  
 G1 X20.172 Y230.4953  
 G1 X20.7149 Y231.2535  
 G1 X21.0515 Y231.8187  
 G1 X21.3118 Y232.3584  
 G1 X21.4325 Y232.6378  
 G1 X21.1531 Y231.3932  
 G1 X21.0134 Y230.7773  
 G1 X20.9689 Y230.435  
 G1 X20.9308 Y230.0953  
 G1 X21.3309 Y230.3556  
 G1 X22.0294 Y231.1964  
 G1 X22.3342 Y231.6155  
 G4  
 P0.10000000149011612  
 M03 S80  
 G4  
 P0.10000000149011612  
 G1 F10000

G1 X17.8901 Y231.3742  
 G4  
 P0.10000000149011612  
 M03 S0  
 G4  
 P0.10000000149011612  
 G1 F15000.000000  
 G1 X18.3305 Y231.6536  
 G1 X18.8734 Y232.1933  
 G1 X19.0703 Y232.4727  
 G1 X19.1274 Y232.7775  
 G1 X19.0131 Y232.8982  
 G1 X18.7528 Y232.9172  
 G1 X18.3305 Y232.6378  
 G1 X18.0098 Y232.1743  
 G1 X17.8301 Y231.4948  
 G1 X17.7501 Y230.9551  
 G1 X17.8501 Y230.5156  
 G1 X18.0701 Y230.1956  
 G1 X18.2702 Y229.9953  
 G1 X18.9496 Y230.6947  
 G1 X19.3878 Y231.1964  
 G1 X19.6926 Y231.6345  
 G4  
 P0.10000000149011612  
 M03 S80  
 G4  
 P0.10000000149011612  
 G1 F10000  
 G1 X15.7467 Y232.5362  
 G4  
 P0.10000000149011612  
 M03 S0  
 G4  
 P0.10000000149011612  
 G1 F15000.000000  
 G1 X15.807 Y232.5553  
 G1 X16.1067 Y232.7775  
 G1 X16.3068 Y232.9172  
 G1 X16.1067 Y231.7933  
 G1 X15.9867 Y230.7773  
 G1 X16.0467 Y230.1556  
 G1 X16.5468 Y230.6947  
 G1 X16.9684 Y231.3551  
 G1 X17.2669 Y231.9139  
 G1 X17.6669 Y232.8156  
 G1 X17.4637 Y231.8758  
 G1 X17.2859 Y230.5353  
 G1 X17.1272 Y229.6552  
 G1 X16.9494 Y229.2533

G1 X16.7081 Y229.0374  
 G1 X16.3468 Y228.9167  
 G1 X15.6864 Y228.9739  
 G4  
 P0.10000000149011612  
 M03 S80  
 G4  
 P0.10000000149011612  
 G1 F10000  
 G1 X16.8478 Y225.3397  
 G4  
 P0.10000000149011612  
 M03 S0  
 G4  
 P0.10000000149011612  
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 G1 X17.8892 Y225.6635  
 G1 X18.2638 Y225.4794  
 G1 X18.3654 Y225.0031  
 G1 X18.1876 Y224.438  
 G1 X17.705 Y223.8601  
 G1 X17.1272 Y223.321  
 G1 X16.5671 Y222.8607  
 G1 X17.1081 Y222.8607  
 G1 X18.0479 Y222.9007  
 G1 X18.3083 Y222.881  
 G1 X18.448 Y222.9007  
 G1 X18.7274 Y223.0804  
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 M03 S80  
 G4  
 P0.10000000149011612  
 G1 F10000  
 G1 X21.5658 Y225.7016  
 G4  
 P0.10000000149011612  
 M03 S0  
 G4  
 P0.10000000149011612  
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 G1 X20.4482 Y224.819  
 G1 X20.2641 Y224.2221  
 G1 X20.3276 Y223.5426  
 G1 X20.5879 Y223.0004  
 G1 X21.1658 Y222.8607  
 G1 X21.8897 Y223.1407  
 G1 X22.3659 Y223.7204

G1 X22.5691 Y224.4634  
 G1 X22.5056 Y225.1809  
 G1 X22.2072 Y225.6  
 G1 X21.8643 Y225.7016  
 G1 X21.5658 Y225.7016  
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 G4  
 P0.10000000149011612  
 G1 F10000  
 G1 X24.3471 Y225.3397  
 G4  
 P0.10000000149011612  
 M03 S0  
 G4  
 P0.10000000149011612  
 G1 F15000.000000  
 G1 X24.8488 Y225.581  
 G1 X25.3885 Y225.6635  
 G1 X25.7632 Y225.4794  
 G1 X25.8648 Y225.0031  
 G1 X25.687 Y224.438  
 G1 X25.2044 Y223.8601  
 G1 X24.6265 Y223.321  
 G1 X24.0665 Y222.8607  
 G1 X24.6075 Y222.8607  
 G1 X25.5473 Y222.9007  
 G1 X25.8076 Y222.881  
 G1 X25.9473 Y222.9007  
 G1 X26.2267 Y223.0804  
 G4  
 P0.10000000149011612  
 M03 S80  
 G4  
 P0.10000000149011612  
 G1 F10000  
 G1 X32.4751 Y232.714  
 G4  
 P0.10000000149011612  
 M03 S0  
 G4  
 P0.10000000149011612  
 G1 F15000.000000  
 G1 X31.7766 Y232.7585  
 G1 X31.2743 Y232.5362  
 G1 X30.9143 Y231.8949  
 G1 X30.7743 Y231.0757  
 G1 X30.7743 Y230.435  
 G1 X30.8343 Y230.1156

G1 X31.2146 Y230.4953  
 G1 X31.7576 Y231.2535  
 G1 X32.0941 Y231.8187  
 G1 X32.3545 Y232.3584  
 G1 X32.4751 Y232.6378  
 G1 X32.1957 Y231.3932  
 G1 X32.056 Y230.7773  
 G1 X32.0116 Y230.435  
 G1 X31.9735 Y230.0953  
 G1 X32.3735 Y230.3556  
 G1 X33.072 Y231.1964  
 G1 X33.3768 Y231.6155  
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 M03 S80  
 G4  
 P0.10000000149011612  
 G1 F10000  
 G1 X33.3568 Y232.4981  
 G4  
 P0.10000000149011612  
 M03 S0  
 G4  
 P0.10000000149011612  
 G1 F15000.000000  
 G1 X33.7369 Y232.8156  
 G1 X33.9166 Y232.9363  
 G1 X33.8169 Y232.4537  
 G1 X33.6969 Y231.6155  
 G1 X33.5768 Y231.0376  
 G1 X33.4968 Y230.4953  
 G1 X33.4568 Y230.1556  
 G1 X33.4772 Y230.0553  
 G1 X33.4568 Y230.475  
 G1 X33.8772 Y231.0567  
 G1 X34.196 Y231.6726  
 G1 X34.5579 Y232.1933  
 G1 X34.9389 Y232.6378  
 G1 X35.1358 Y232.8728  
 G1 X35.2374 Y232.8728  
 G1 X35.2945 Y232.4537  
 G1 X35.1358 Y231.6726  
 G1 X34.9961 Y231.0757  
 G1 X34.8754 Y230.6153  
 G1 X34.7738 Y230.0353  
 G1 X35.1358 Y230.3353  
 G1 X35.6565 Y230.8725  
 G1 X35.9359 Y231.2726  
 G1 X36.2153 Y231.6345  
 G4

P0.10000000149011612  
 M03 S80  
 G4  
 P0.10000000149011612  
 G1 F10000  
 G1 X39.2379 Y234.7968  
 G4  
 P0.10000000149011612  
 M03 S0  
 G4  
 P0.10000000149011612  
 G1 F15000.000000  
 G1 X38.7553 Y234.7968  
 G1 X38.3171 Y234.5365  
 G1 X38.0568 Y234.0983  
 G1 X37.9171 Y233.4951  
 G1 X37.8155 Y232.7585  
 G1 X37.7583 Y232.3584  
 G1 X37.4535 Y231.7742  
 G1 X37.0344 Y231.0376  
 G1 X36.635 Y230.475  
 G1 X36.2153 Y230.0953  
 G1 X36.1353 Y230.8344  
 G1 X36.2353 Y231.7171  
 G1 X36.4756 Y232.2759  
 G1 X36.6756 Y232.5553  
 G1 X36.9773 Y232.714  
 G1 X37.2948 Y232.7966  
 G1 X37.6123 Y232.7585  
 G1 X37.7583 Y232.5934  
 G1 X37.6758 Y231.8568  
 G1 X37.5932 Y230.9741  
 G1 X37.4154 Y230.0553  
 G1 X37.8726 Y230.4153  
 G1 X38.4124 Y231.0757  
 G1 X38.8378 Y231.6345  
 G4  
 P0.10000000149011612  
 M03 S80  
 G4  
 P0.10000000149011612  
 G1 F10000  
 G1 X40.9994 Y232.4537  
 G4  
 P0.10000000149011612  
 M03 S0  
 G4  
 P0.10000000149011612  
 G1 F15000.000000  
 G1 X41.3194 Y232.7585

G1 X41.4794 Y232.8347  
 G1 X41.1991 Y231.1583  
 G1 X41.0787 Y230.5753  
 G1 X41.0787 Y230.0953  
 G1 X41.5588 Y230.5156  
 G1 X41.9366 Y230.936  
 G1 X42.4764 Y231.6345  
 G4  
 P0.10000000149011612  
 M03 S80  
 G4  
 P0.10000000149011612  
 G1 F10000  
 G1 X44.1147 Y232.7775  
 G4  
 P0.10000000149011612  
 M03 S0  
 G4  
 P0.10000000149011612  
 G1 F15000.000000  
 G1 X43.74 Y232.9553  
 G1 X43.4162 Y232.8982  
 G1 X43.0987 Y232.6569  
 G1 X42.9774 Y232.3584  
 G1 X43.0987 Y231.9774  
 G1 X43.3971 Y231.6155  
 G1 X43.6575 Y231.2535  
 G1 X43.8162 Y230.8979  
 G1 X43.7972 Y230.5753  
 G1 X43.5559 Y230.275  
 G1 X43.2193 Y230.0753  
 G1 X42.9374 Y229.9953  
 G1 X42.5773 Y230.1556  
 G4  
 P0.10000000149011612  
 M03 S80  
 G4  
 P0.10000000149011612  
 G1 F10000  
 G1 X41.6388 Y234.0539  
 G4  
 P0.10000000149011612  
 M03 S0  
 G4  
 P0.10000000149011612  
 G1 F15000.000000  
 G1 X41.6388 Y233.7173  
 G1 X41.5791 Y233.6538  
 G4  
 P0.10000000149011612

M03 S80  
 G4  
 P0.10000000149011612  
 G1 F10000  
 G1 X46.8969 Y231.3742  
 G4  
 P0.10000000149011612  
 M03 S0  
 G4  
 P0.10000000149011612  
 G1 F15000.000000  
 G1 X47.3373 Y231.6536  
 G1 X47.8802 Y232.1933  
 G1 X48.0771 Y232.4727  
 G1 X48.1342 Y232.7775  
 G1 X48.0199 Y232.8982  
 G1 X47.7596 Y232.9172  
 G1 X47.3373 Y232.6378  
 G1 X47.0166 Y232.1743  
 G1 X46.8369 Y231.4948  
 G1 X46.7569 Y230.9551  
 G1 X46.8569 Y230.5156  
 G1 X47.0769 Y230.1956  
 G1 X47.277 Y229.9953  
 G1 X47.9564 Y230.6947  
 G1 X48.3946 Y231.1964  
 G1 X48.6994 Y231.6345  
 G4  
 P0.10000000149011612  
 M03 S80  
 G4  
 P0.10000000149011612  
 G1 F10000  
 G1 X49.0988 Y232.5172  
 G4  
 P0.10000000149011612  
 M03 S0  
 G4  
 P0.10000000149011612  
 G1 F15000.000000  
 G1 X49.4169 Y232.7775  
 G1 X49.6773 Y232.9172  
 G1 X50.598 Y230.0553  
 G1 X50.9155 Y230.235  
 G1 X51.1187 Y230.475  
 G4  
 P0.10000000149011612  
 M03 S80  
 G4  
 P0.10000000149011612



G1 F10000  
 G1 X51.4362 Y231.0757  
 G4  
 P0.10000000149011612  
 M03 S0  
 G4  
 P0.10000000149011612  
 G1 F15000.000000  
 G1 X51.4962 Y231.1138  
 G1 X51.6763 Y231.7361  
 G1 X52.0966 Y232.314  
 G1 X52.4776 Y232.714  
 G1 X52.6935 Y232.8728  
 G1 X52.7951 Y232.314  
 G1 X52.7761 Y231.7361  
 G1 X52.6364 Y231.1138  
 G1 X52.4395 Y230.5753  
 G1 X52.1982 Y230.235  
 G1 X51.8763 Y230.1156  
 G1 X51.6166 Y230.1556  
 G1 X51.4562 Y230.275  
 G1 X51.2959 Y230.5353  
 G4  
 P0.10000000149011612  
 M03 S80  
 G4  
 P0.10000000149011612  
 G1 F10000  
 G1 X51.1562 Y232.5362  
 G4  
 P0.10000000149011612  
 M03 S0  
 G4  
 P0.10000000149011612  
 G1 F15000.000000  
 G1 X51.6559 Y232.8982  
 G1 X51.1365 Y229.4952  
 G1 X50.9765 Y228.9929  
 G1 X50.3758 Y228.5738  
 G1 X51.4962 Y229.1771  
 G4  
 P0.10000000149011612  
 M03 S80  
 G4  
 P0.10000000149011612  
 G1 F10000  
 G1 X48.8988 Y230.1156  
 G4  
 P0.10000000149011612  
 M03 S0

G4  
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 G1 X50.979 Y232.7775  
 G1 X51.2965 Y232.8347  
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 M03 S0  
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 G1 X54.4207 Y232.8982  
 G1 X54.1604 Y232.9172  
 G1 X53.7381 Y232.6378  
 G1 X53.4174 Y232.1743  
 G1 X53.2377 Y231.4948  
 G1 X53.1577 Y230.9551  
 G1 X53.2577 Y230.5156  
 G1 X53.4777 Y230.1956  
 G1 X53.6778 Y229.9953  
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 G1 X54.7954 Y231.1964  
 G1 X55.1002 Y231.6345  
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 P0.10000000149011612  
 M03 S0  
 G4



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 Y231.6345  
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 Y232.4537  
 G1 X114.3355  
 Y231.6155  
 G1 X114.2155

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Y230.4953	Y232.7585
G1 X114.0955	G1 X119.5146
Y230.1556	Y232.8347
G1 X114.1158	G1 X119.2342
Y230.0553	Y231.1583
G1 X114.0955 Y230.475	G1 X119.1139
G1 X114.5158	Y230.5753
Y231.0567	G1 X119.1139
G1 X114.8346	Y230.0953
Y231.6726	G1 X119.5939
G1 X115.1966	Y230.5156
Y232.1933	G1 X119.9718 Y230.936
G1 X115.5776	G1 X120.5115
Y232.6378	Y231.6345
G1 X115.7744	G4
Y232.8728	P0.10000000149011612
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G1 X115.9332	G4
Y232.4537	P0.10000000149011612
G1 X115.7744	G1 F10000
Y231.6726	G1 X120.4725
G1 X115.6347	Y232.4981
Y231.0757	G4
G1 X115.5141	P0.10000000149011612
Y230.6153	M03 S0
G1 X115.4125	G4
Y230.0353	P0.10000000149011612
G1 X115.7744	G1 F15000.000000
Y230.3353	G1 X120.8525
G1 X116.2951	Y232.8156
Y230.8725	G1 X121.0322
G1 X116.5745	Y232.9363
Y231.2726	G1 X120.9325
G1 X116.8539	Y232.4537
Y231.6345	G1 X120.8125
G4	Y231.6155
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M03 S80	Y231.0376
G4	G1 X120.6125
P0.10000000149011612	Y230.4953
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G1 X119.0345	Y230.1556
Y232.4537	G1 X120.5928
G4	Y230.0553
P0.10000000149011612	G1 X120.5725 Y230.475
M03 S0	G1 X120.9929
G4	Y231.0567
P0.10000000149011612	G1 X121.3116

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G1 X121.6736	Y230.1753
Y232.1933	G1 X125.7712
G1 X122.0546	Y230.8154
Y232.6378	G1 X126.0513
G1 X122.2514	Y231.4377
Y232.8728	G1 X126.2913
G1 X122.353 Y232.8728	Y232.0727
G1 X122.4102	G1 X126.5885
Y232.4537	Y232.5743
G1 X122.2514	G1 X126.7536
Y231.6726	Y232.7775
G1 X122.1117	G1 X126.9695
Y231.0757	Y232.8728
G1 X121.9911	G1 X127.2298
Y230.6153	Y232.8537
G1 X121.8895	G4
Y230.0353	P0.10000000149011612
G1 X122.2514	M03 S80
Y230.3353	G4
G1 X122.7721	P0.10000000149011612
Y230.8725	G1 F10000
G1 X123.0515	G1 X128.4528
Y231.2726	Y232.4981
G1 X123.3309	G4
Y231.6345	P0.10000000149011612
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P0.10000000149011612	G4
M03 S80	P0.10000000149011612
G4	G1 F15000.000000
P0.10000000149011612	G1 X128.4732
G1 F10000	Y232.4981
G1 X125.4112	G1 X128.7335
Y232.4727	Y232.7775
G4	G1 X129.0132
P0.10000000149011612	Y232.9172
M03 S0	G1 X129.0732
G4	Y230.7582
P0.10000000149011612	G1 X129.1336
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Y232.7775	Y230.5753
G1 X125.9712	G1 X129.7508
Y232.9172	Y231.1583
G1 X125.7712	G1 X130.0365
Y231.8377	Y231.8377
G1 X125.6112	G1 X130.1508
Y230.8535	Y232.2124
G1 X125.5909	G1 X130.2334
Y230.3753	Y232.9172

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M03 S80  
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P0.10000000149011612  
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G1 X130.6534  
Y231.3742  
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G4  
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G1 X131.6367  
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Y232.8982  
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Y232.9172  
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Y232.6378  
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Y230.1956  
G1 X131.0335  
Y229.9953  
G1 X131.7129  
Y230.6947  
G1 X132.1511  
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G1 X132.4559  
Y231.6345  
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G4

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G4  
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Y230.0353  
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Y230.8725  
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G1 X135.3134

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M03 S0  
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Y230.4153  
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Y231.5774  
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G1 X137.8343  
Y231.6345

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Y232.9172  
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Y232.6378  
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Y230.1956  
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Y230.6947  
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Y231.1964  
G1 X139.6377  
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G4  
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 G1 X144.6364  
 Y234.3587  
 G1 X144.3964

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G1 X144.0964	Y231.0186
Y231.1964	G1 X150.4994
G1 X144.0164	Y230.5753
Y230.6153	G1 X150.3591
G1 X143.976 Y230.2953	Y230.0353
G1 X144.0564	G1 X150.8194
Y230.0353	Y230.4153
G1 X144.4567	G1 X151.3979
Y230.0953	Y231.0567
G1 X145.0987	G1 X151.817 Y231.6345
Y230.5353	G4
G1 X145.4162	P0.10000000149011612
Y231.2345	M03 S80
G1 X145.5559	G4
Y231.8568	P0.10000000149011612
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G1 X145.5369	G1 X154.4024
Y232.8347	Y231.3742
G1 X144.9971	G4
Y232.2949	P0.10000000149011612
G1 X144.4364	M03 S0
Y231.4948	G4
G1 X144.0364 Y230.635	P0.10000000149011612
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M03 S80	Y231.6536
G4	G1 X155.3857
P0.10000000149011612	Y232.1933
G1 F10000	G1 X155.5826
G1 X150.8798	Y232.4727
Y233.2157	G1 X155.6397
G4	Y232.7775
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M03 S0	Y232.8982
G4	G1 X155.2651
P0.10000000149011612	Y232.9172
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G1 X150.8594	Y232.6378
Y232.8347	G1 X154.5221
G1 X150.3997	Y232.1743
Y232.7966	G1 X154.3424
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Y232.8537	G1 X154.2624
G1 X151.7027	Y230.9551
Y232.8728	G1 X154.3624
G1 X150.8594	Y230.5156
Y232.8537	G1 X154.5824
G1 X150.7394	Y230.1956
Y231.7552	G1 X154.7825

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 Y230.6947  
 G1 X155.9001  
 Y231.1964  
 G1 X156.2049  
 Y231.6345  
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 M03 S0  
 G4  
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 Y231.1964  
 G1 X162.2501  
 Y231.6345  
 G4



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 M03 S0  
 G4  
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 Y230.4953  
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 M03 S80  
 G4  
 P0.10000000149011612  
 G1 F10000

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 M03 S0  
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 G4  
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 G1 X162.5876  
 Y238.7357  
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 M03 S0  
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 G1 F15000.000000  
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 Y239.0151  
 G1 X163.5709

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G1 X163.7677	Y237.6568
Y239.8343	G1 X164.4491
G1 X163.8249	Y237.4968
Y240.1391	G1 X164.8288
G1 X163.7106	Y237.9769
Y240.2597	G1 X165.1266
G1 X163.4502	Y238.5579
Y240.2788	G1 X165.3679
G1 X163.0279	Y239.1993
Y239.9994	G1 X165.4886
G1 X162.7073	Y239.4596
Y239.5358	G1 X165.7489
G1 X162.5276	Y240.2788
Y238.8564	G1 X165.5902 Y240.12
G1 X162.4476	G1 X165.6473
Y238.3166	Y237.9769
G1 X162.5476	G1 X165.6918
Y237.8772	Y237.5368
G1 X162.7676	G1 X166.0474
Y237.5571	Y237.9369
G1 X162.9676	G1 X166.3712
Y237.3568	Y238.5389
G1 X163.6471	G1 X166.6316
Y238.0563	Y239.1548
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Y238.5579	Y239.6374
G1 X164.39 Y238.9961	G1 X166.8284
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M03 S80	Y240.2788
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G1 X163.7893	G4
Y239.8787	P0.10000000149011612
G4	G1 F10000
P0.10000000149011612	G1 X164.6323
M03 S0	Y245.9703
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Y240.1581	P0.10000000149011612
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G1 X164.4291	Y246.2497
Y240.2153	G1 X165.6156
G1 X164.3891	Y246.7895
Y238.3801	G1 X165.8124

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 Y247.5134  
 G1 X165.0726 Y247.234  
 G1 X164.752 Y246.7704  
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 G1 X40.0189 Y239.1358  
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 G1 X38.7807 Y237.4568  
 G1 X38.7007 Y238.196  
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 M03 S0

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 G1 F10000  
 G1 X0 Y0

## **CHAPTER - 8**

**Table I. Cost of Components**

<b>S.no</b>	<b>Cost estimation of project</b>		
	<b>Name of material</b>	<b>Number of unit</b>	<b>Cost (Approx.)</b>
1	NEMA 17 Stepper motor	2	700
2	Arduino Uno		400
3	CNC shield board		200
4	A4988 motor driver	2	300
5	Mg995s metal gear servo motor		250
6	12V Adapter		100
7	8mmx300mm Threaded rod	2	400
8	8mmx300mm smooth rod	4	400
9	Bearing 8mm dia	4	160
10	Linear coupling bearing	2	300
11	Miscellaneous		350
	<b>Total</b>		<b>3560</b>

### **Advantages**

1. CNC machines can be utilized constantly, 24 hours a day, with the exception of infrequent maintenance shutdowns.
2. Designs are modified for CNC machines so that hundreds or even thousands of copies can be manufactured of them. Each manufactured item will be very identical to the others.
3. Unlike manual machines, processing machines, and other devices that require professional architects, CNC machines can be managed by those who are less talented or qualified.
4. The CNC machines may be updated by making the product that powers them better.
5. "Virtual programming" enables instruction on how to operate CNC equipment. The administrator can control the CNC machine using this gadget, which resembles a computer game, on the PC's display.
6. Modern strategy the architect can replicate the design of their ideas through programming. It is imperative that a model or models be created. Time and money are put aside in this.
7. One person can manage several CNC machines due to the fact that customized CNC machines can often be passed on to operate without assistance from anybody else. Only the cutting instruments occasionally need to be replaced.

### **Disadvantages**

As a result of the machine's sluggish performance and excessive heat output, the intensity sink warms up quickly. After the image record has been plotted, a little error might still be present due to the fact that one side of the Y-hub is locked to the moving system while the other end is free to move. Since the Z-hub isn't extremely rigid, it causes a slight vibration.

### **Applications**

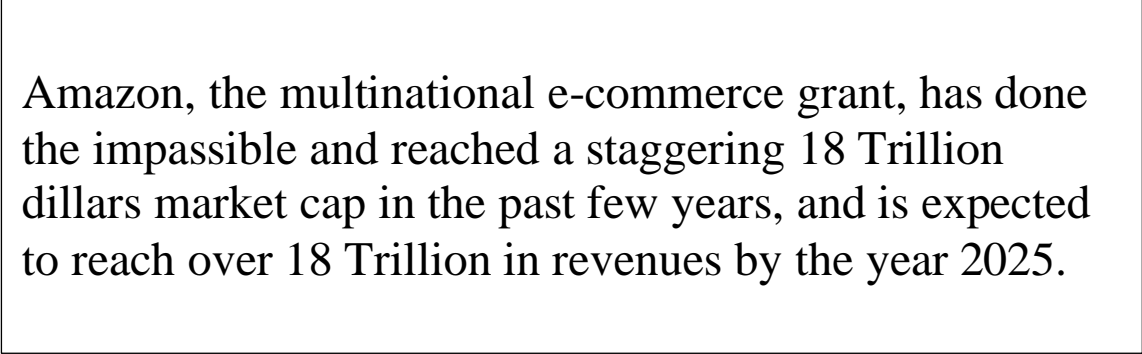
1. Brijesh Sondarva's Little CNC/3D Printer, for starters
2. Jonahmarrs' Small CNC Froth Shaper
3. Me zain's Small Arduino CNC
4. CD/DVD Bipolar Engine Driver by Samiran without Microcontroller
5. CNC Plasma Cutting byivanirons | CNC Step Pad Project | CNC Programming
6. Brijesh Sondarya's L293D driver board for CNC

## **CHAPTER -9**



**Result:-**

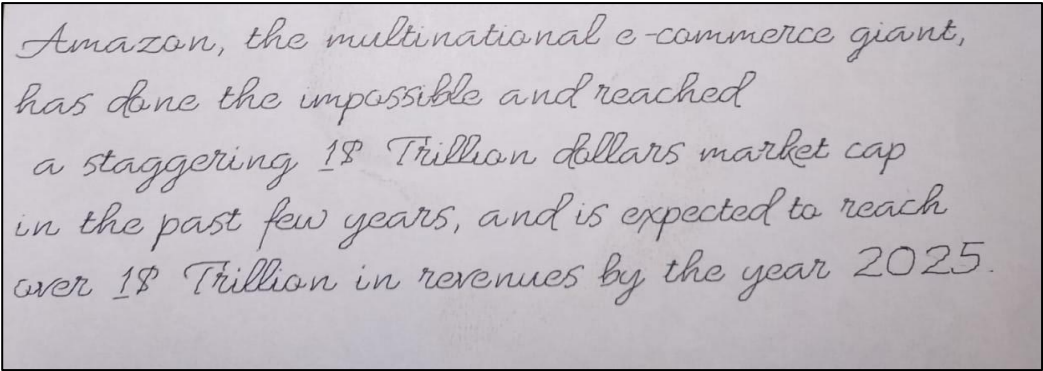
This research suggests a different type of computerized composition device that incorporates optical person recognition. The text will be extracted from the information image using the source code, and it will then be converted to one of the predefined text styles stored on the computer or to the client's handwriting. The removed text totally switched over to the client's text style in the info image, which is a bit of a checked record in the predefined text style "Arial."



Amazon, the multinational e-commerce grant, has done the impassible and reached a staggering 18 Trillion dillars market cap in the past few years, and is expected to reach over 18 Trillion in revenues by the year 2025.

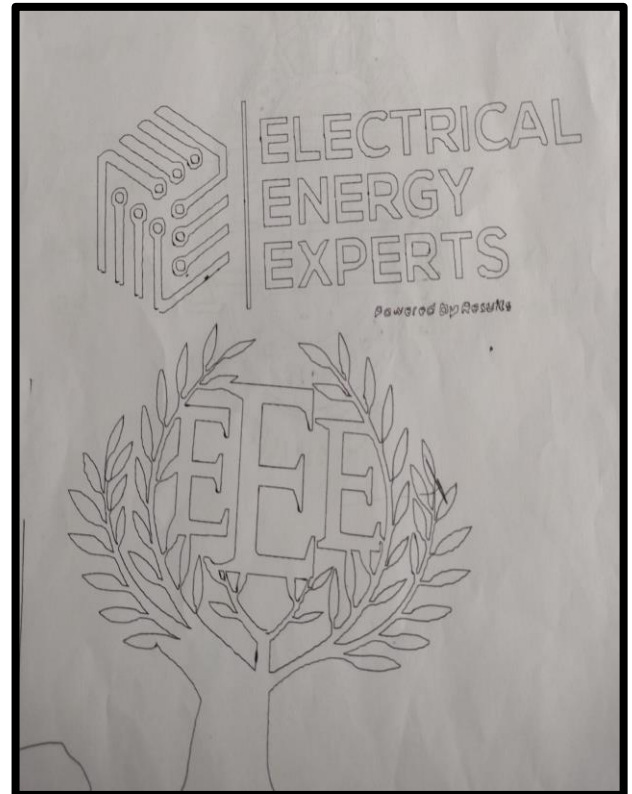
Fig 8.1 Input

A web application is used to help with the textual style change. In this case, the client's sequential information is transferred, and this textual style is worked to.



Amazon, the multinational e-commerce giant, has done the impossible and reached a staggering 18 Trillion dollars market cap in the past few years, and is expected to reach over 18 Trillion in revenues by the year 2025.

Fig 8.2 Output

**Input in predefined Image****Output Image**

The cost of creation is where this framework's primary advantage lies. In order to do an analysis, two comparably priced frameworks are taken into consideration.

#### Comparison of the proposed system with others

Parameters	Existing Method	Proposed Method
Cost (Rupees)	8090	6003
Converter	OCR	CNC
Font Converter	Possible	Possible
Weight(KGS)	1	0.88
Speed (WPM)	5-10	5-15
Origin	INDIA	INDIA

It's also important to keep in mind the accuracy of the optical person. Depending on whatever textual style is used, CNC of text in preset textual styles is generally above 95% more accurate than human penmanship. Depending on how sloppy or perfect the person's penmanship is, the CNC's accuracy in the event of human penmanship recognition will vary. The machine's composing speed, which is 13 wpm, is nearly identical to that of the average human (words each moment). One of the project's limitations is that, due to the laser fetching programming used, the final product could only be inscribed in block letters. Maybe, this problem could be solved by using other programming.

**Conclusion:-**

Humans are increasingly using robots to complete tasks in order to save time, resources, and produce goods that are effective. The fundamental issue with currently available technology, such as speech-to-text converters, printers, and scanners, is that they can only write in computer-predefined typefaces. The suggested system functions as an automatic writing device that may produce text in any specified font or according to the user's handwriting. Software and hardware integration produces a mechanical system that, with minimal human interference, creates an automated writing machine that is user-friendly and economical while also requiring less manual labour and time. In conclusion, the automatic writing machine will be able to help with the problems we face every day and so raise our quality of life.

**FUTURE SCOPE**

The suggested framework can be used as a benchmark for the majority of upcoming improvements. One such improvement might be to compose more quickly than is now possible. Also, the inclusion of voice-to-message modules in the general framework proposal will benefit people with a range of abilities. Creating a constant framework, where the client can submit the message to be created remotely and the device must be prepared to record it on paper, could be another modification.. By incorporating the use of the web and cloud administrations into the cycle, this can be achieved. A relative who's phone battery may have died and the phone may have turned off might be informed using this unique application. The optical person recognition of the suggested framework isn't currently as accurate for outdated penmanship as it is for established penmanship styles. Consequently, by achieving superior text recognition, the system may be made to read professional advice, which can then be completely translated into the client's language using a language interpretation model.

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