

Sai Bharadhwaj Matha

Male | 10.06.1999 | Single | INDIAN | Kothmaissling 37, 93413, Cham, Germany.

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[linkedin.com/in/saibharadhwajmatha](https://www.linkedin.com/in/saibharadhwajmatha) | <https://bharadhwajsaimatha.github.io/portfolio/>

<https://loose0ends.wordpress.com/>

About

An ingenious engineer with two years of experience in embedded systems and power electronics for UAS and one year as a research assistant in 3D computer vision and deep learning. I completed my M.Eng in Artificial Intelligence, with my thesis on Semantic Occupancy Prediction for UAS. I am passionate about advancing my career in AI, computer vision, and intelligent robotics, striving to contribute to cutting-edge innovations.

Education

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| 2022 – 2025 Cham, Germany | Master of Engineering in Artificial Intelligence for Smart Sensors and Actuators <i>Technische Hochschule Deggendorf.</i> GPA: 1.4 Thesis: Real-world Semantic Occupancy Prediction for Advanced Air Mobility. |
| 2016 – 2020 Rourkela, India | Bachelor of Technology in Electrical Engineering <i>National Institute of Technology Rourkela.</i> CGPA : 8.72/10.0 |
| 2014 – 2016 Visakhapatnam, India | Higher Secondary Education <i>Board of Intermediate Education Andhra Pradesh.</i> Percentage: 98.4 |

Professional Experience

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| 2024 – present Ingolstadt, Germany | Research Assistant <i>Fraunhofer IVI</i> <ul style="list-style-type: none">Working on research focused on semantic occupancy prediction for UAS.Expertise in computer vision, deep learning, and UAS avionics. |
| 2023 – 2024 Ingolstadt, Germany | Internship <i>Fraunhofer IVI</i> <ul style="list-style-type: none">Developed a pipeline for 3D semantic point cloud generation. |
| 2020 – 2022 Mumbai, India | Embedded Systems Engineer <i>Full-time, Ideaforge Technology Private Limited.</i> <ul style="list-style-type: none">Led the development of the propulsion system, ensuring reliable performance.Developed an FOC-based ESC for BLDC motors.Developed Li-ion and Li-Po battery pack charging system. |
| 2019 – 2019 Pune, India | Internship <i>Hachimichi Technology Private Limited.</i> <ul style="list-style-type: none">Firmware for automation and heart-rate monitoring of a toilet seat. |

Projects

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|-------------------|---|
| 05.2025 – present | MonoSpatial: Agent-Based Spatial Distance Estimation in Monocular RGB Images <ul style="list-style-type: none">Developed an agentic reasoning pipeline to select and orchestrate vision models for spatial queries dynamically. Fine-tuning for aerial scenes.Evaluating the Diffusion-based approach for estimating camera intrinsics. |
| 03.2025 – 06.2025 | Multi-Modal 3D Object Detection in Adverse Weather Conditions <ul style="list-style-type: none">Design and train a deep autoencoder for 2D feature extraction in adverse weather.Implemented early-fusion for multi-modal synthetic data generated in CARLA. |
| 01.2025 – 02.2025 | Novel Aerial View Synthesis using 3D Gaussian Splatting <ul style="list-style-type: none">Used 3D Gaussian Splatting to create realistic novel views from aerial drone images.Leveraging Metashape to output sparse reconstruction in COLMAP format. |

06.2024 – 12.2024

Semantic Occupancy Prediction for Advanced Air Mobility

Master Thesis (expected release and submission: CVPR 2026)

- A novel benchmark semantic occupancy dataset for UAS, trained SOTA models, and working on a novel model architecture for aerial scenarios.
- Developed a large-scale dataset with monocular RGB + thermal aerial imagery.
- Designed a data-generation pipeline that integrates 3D reconstruction, pose estimation, semantic fusion, mesh generation, voxelization, and voxel densification.

2023 – 2023

6-DOF Autonomous Robot with Haptic Obstacle Sensing

- Autonomous 6-DOF robot with haptic feedback for obstacle detection.
- ROS-Gazebo simulation in Docker for modular deployment.

Skills

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| Python — Proficient | Machine Learning and Deep Learning — Proficient |
| Computer Vision — Proficient | PyTorch — Proficient |
| Generative AI — Competent | Agentic AI — Competent |
| Kubernetes, Git — Competent | Docker — Competent |
| C++ — Competent | SQL — Competent |
| Robot Operating System(ROS) — Competent | STM32, RTOS — Competent |
| Linux — Competent | Data Structures — Competent |

Languages

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| Telugu — Native/Bilingual <i>Mother Tongue</i> | Hindi — Native/Bilingual <i>National Language</i> |
| English — Native/Bilingual <i>IELTS score: 8.0/9.0</i> | German — Conversational |

Courses & Certificates

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| Big Data <i>Issued by Coursera</i> | Quantum Computing <i>Elective from THD</i> |
| MLOps (AWS): Deploying AI & ML Models <i>Issued by edX</i> | AI Agents <i>Issued by Hugging Face</i> |

Organisations

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| 2019 – 2020 Rourkela, India | VS Hall of Residence <i>Student elected representative</i> |
| 2017 – 2020 Rourkela, India | Plugged_IN <i>Vice President</i> |

Interests

- Cooking and blogging
- eFootball and gaming

References

Prof. Dr. Dmitrii Dobriborsci, *Professor*, Technische Hochschule Deggendorf
dmitrii.dobriborsci@th-deg.de

Henri Meess, *M.Sc., Manager*, Fraunhofer IVI
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Declaration

I affirm that all information provided is true and accurate to the best of my knowledge.

M. Sai Bhaskarhuja.

Kothmaissling, 03.06.2025