

Sai Bharadhwaj Matha

Male | 10.06.1999 | Single | INDIAN | Kothmaissling 37, 93413, Cham, Germany. bharadhwaj2299@gmail.com | +49 155 108 59066 | github.com/Bharadhwajsaimatha linkedin.com/in/saibharadhwajmatha | https://bharadhwajsaimatha.github.io/portfolio/

Professional Summary

AI and Embedded Systems Engineer with 3+ years of cross-disciplinary experience in embedded systems, 3D computer vision, and intelligent robotics, including work in real-world UAV systems and advanced deep learning models. Proven track record in developing semantic occupancy prediction pipelines, SLAM-based UAV navigation, and multi-modal perception frameworks. Seeking to leverage expertise in 3D computer vision, AI for autonomous systems, and agentic frameworks to drive innovation in robotics and intelligent perception.

Education

2022 - 2025Master of Engineering in Artificial Intelligence for Smart Sensors and Actuators Cham, Germany Technische Hochschule Deggendorf. GPA: 1.4 / 5.0 Thesis: Real-world Semantic Occupancy Prediction for Advanced Air Mobility. 2016 - 2020Bachelor of Technology in Electrical Engineering Rourkela, India National Institute of Technology Rourkela. CGPA: 8.72 / 10.0 Thesis: Wireless Power Transfer and Its Application in Solar Power Harvesting. 2014 - 2016**Higher Secondary Education** Visakhapatnam, India Board of Intermediate Education Andhra Pradesh. Percentage: 98.4

Professional Experience

2024 – present	Research Assistant	
Ingolstadt, Germany	Fraunhofer IVI	
	 Designed a novel 3D semantic and panoptic scene completion data pipeline for UAVs. 	
	• Generated 50K+ sample dataset with RGB, thermal, depth, and 3D occupancy GT.	
	• Conducted ablations on Symphonize 3D and CGFormer to inform novel 3D architecture.	
2023 - 2024	Internship	
Ingolstadt, Germany	Fraunhofer IVI	
	 Built a 3D semantic point cloud pipeline using COLMAP, Metashape from images. 	
	• Cut external annotation costs by 82% via image subset optimization.	
2020 - 2022	Embedded Systems Engineer	
Mumbai, India	Full-time, Ideaforge Technology Private Limited.	
	 Headed the development of the propulsion system, ensuring reliable performance. 	
	• Engineered an FOC-based ESC for BLDC motors and a Li-ion battery pack charger.	
	 Developed embedded HW/SW for GPS-denied UAV navigation via ORB-SLAM3. 	
2019 - 2019	Internship	
Pune, India	Hachimichi Technology Private Limited.	
	• Firmware for automation and heart-rate monitoring of a toilet seat.	

Key Technical Projects

Key Technical Projects		
06.2025 – present	 PlanMyTrip - Let our agents plan your trip! Architected an agentic AI system with fine-tuned LLMs using ReAct, RAG, and dynamic tool orchestration for real-time multi-destination itinerary generation. Optimizing inference pipeline via model cascading to reduce latency and costs. 	
05.2025 – present	 MonoSpatial: Agent-Based Spatial Distance Estimation in Monocular RGB Images Developing an agentic reasoning pipeline to select and orchestrate vision models for spatial queries dynamically. Fine-tuning vision models for aerial scenes. Evaluating the Diffusion-based approach for estimating camera intrinsics. 	
04.2025 - 05.2025	 NKD Image Synthesis for Fashion Products Using LoRA-Tuned Diffusion Models Scaled dataset by 82x using text-to-image models and multi-source augmentation, achieving German prompt to fashion image synthesis dataset. Fine-tuned SDXL with LoRA, improving CLIP score by 35.7% and FID to 14.7. 	

03.2025 - 06.2025Multi-Modal 3D Object Detection in Adverse Weather Conditions

- Design and train a deep autoencoder for 2D feature extraction in adverse weather.
- Implemented early-fusion for multi-modal synthetic data generated in CARLA.

01.2025 - 02.2025

Novel Aerial View Synthesis using 3D Gaussian Splatting

- Applied 3D Gaussian Splatting to synthesize high-fidelity novel aerial views from monocular images captured using DJI Phantom 4 and DJI M3T drones.
- Leveraging Metashape to output sparse reconstruction in COLMAP format.

06.2024 - 12.2024

Semantic Occupancy Prediction for Advanced Air Mobility

Master Thesis (expected release and submission: CVPR 2026)

- A novel benchmark semantic occupancy dataset for UAS, ran ablations on SOTA SSC models, and working on a novel geometry-aware model architecture for aerial scenes.
- Developed a large-scale dataset with monocular RGB + thermal aerial imagery.
- Designed a data-generation pipeline that integrates 3D reconstruction, pose estimation, semantic fusion, mesh generation, voxelization, and voxel densification.

Skills

Pvthon — Proficient	Machine Learning and Deep Learning — Proficient
rython — Froncient	Machine Learning and Deep Learning — Proficient

Computer Vision(2D/3D) — Proficient **PyTorch** — Proficient

Generative AI — Competent **Agentic AI, MCP** — Competent

Kubernetes, Git — Competent **Docker** — Competent C++ - Competent **SQL** — Competent

Robot Operating System(ROS) — Competent **STM32, RTOS** — Competent

Data Structures — Competent **Linux** — Competent

Languages

English — Native/Bilingual German — Conversational

CEFR Level B1 *IELTS score*: 8.0/9.0

Telugu — Native/Bilingual **Hindi** — Native/Bilingual Mother Tongue National Language

Courses & Certificates

Big Data

Issued by Coursera

Quantum Computing

Elective from THD

MLOps (AWS): Deploying AI & ML Models

Issued by edX

AI Agents

Issued by Hugging Face

Leadership and Volunteering

2019 - 2020VS Hall of Residence Rourkela, India Student elected representative

2017 - 2020 Plugged_IN Rourkela, India Vice President

References

Prof. Dr. Dmitrii Dobriborsci, Professor, Technische Hochschule Deggendorf dmitrii.dobriborsci@th-deg.de

Henri Meess, M.Sc., Manager, Fraunhofer IVI henri.meess@ivi.fraunhofer.de, +49 1725169897

Interests

Cooking and blogging

• eFootball and gaming

Declaration

I affirm that all information provided is true and accurate to the best of my knowledge.

M. Sai Bhasadhwaj.