



# Sai Bharadhwaj Matha

Male | 10.06.1999 | Single | INDIAN | Kothmaissling 37, 93413, Cham, Germany.

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## Professional Summary

AI and Embedded Systems Engineer with 3+ years of cross-disciplinary experience in embedded systems, 3D computer vision, and intelligent robotics, including work in real-world UAV systems and advanced deep learning models. Proven track record in developing semantic occupancy prediction pipelines, SLAM-based UAV navigation, and multi-modal perception frameworks. Seeking to leverage expertise in 3D computer vision, AI for autonomous systems, and agentic frameworks to drive innovation in robotics and intelligent perception.

## Education

2022 – 2025 Cham, Germany	<b>Master of Engineering in Artificial Intelligence for Smart Sensors and Actuators</b> <i>Technische Hochschule Deggendorf.</i> GPA: 1.4 / 5.0 Thesis: Real-world Semantic Occupancy Prediction for Advanced Air Mobility.
2016 – 2020 Rourkela, India	<b>Bachelor of Technology in Electrical Engineering</b> <i>National Institute of Technology Rourkela.</i> CGPA: 8.72 / 10.0 Thesis: Wireless Power Transfer and Its Application in Solar Power Harvesting.
2014 – 2016 Visakhapatnam, India	<b>Higher Secondary Education</b> <i>Board of Intermediate Education Andhra Pradesh.</i> Percentage: 98.4

## Professional Experience

2024 – present Ingolstadt, Germany	<b>Research Assistant</b> <i>Fraunhofer IVI</i> <ul style="list-style-type: none"><li>Designed a novel 3D semantic and panoptic scene completion data pipeline for UAVs.</li><li>Generated 50K+ sample dataset with RGB, thermal, depth, and 3D occupancy GT.</li><li>Conducted ablations on Symphonize 3D and CGFormer to inform novel 3D architecture.</li></ul>
2023 – 2024 Ingolstadt, Germany	<b>Internship</b> <i>Fraunhofer IVI</i> <ul style="list-style-type: none"><li>Built a 3D semantic point cloud pipeline using COLMAP, Metashape from images.</li><li>Cut external annotation costs by 82% via image subset optimization.</li></ul>
2020 – 2022 Mumbai, India	<b>Embedded Systems Engineer</b> <i>Full-time, Ideaforge Technology Private Limited.</i> <ul style="list-style-type: none"><li>Headed the development of the propulsion system, ensuring reliable performance.</li><li>Engineered an FOC-based ESC for BLDC motors and a Li-ion battery pack charger.</li><li>Developed embedded HW/SW for GPS-denied UAV navigation via ORB-SLAM3.</li></ul>
2019 – 2019 Pune, India	<b>Internship</b> <i>Hachimichi Technology Private Limited.</i> <ul style="list-style-type: none"><li>Firmware for automation and heart-rate monitoring of a toilet seat.</li></ul>

## Key Technical Projects

06.2025 – present	<b>PlanMyTrip - Let our agents plan your trip!</b> <ul style="list-style-type: none"><li>Architected an agentic AI system with fine-tuned LLMs using ReAct, RAG, and dynamic tool orchestration for real-time multi-destination itinerary generation.</li><li>Optimizing inference pipeline via model cascading to reduce latency and costs.</li></ul>
05.2025 – present	<b>MonoSpatial: Agent-Based Spatial Distance Estimation in Monocular RGB Images</b> <ul style="list-style-type: none"><li>Developing an agentic reasoning pipeline to select and orchestrate vision models for spatial queries dynamically. Fine-tuning vision models for aerial scenes.</li><li>Evaluating the Diffusion-based approach for estimating camera intrinsics.</li></ul>
03.2025 – 06.2025	<b>Multi-Modal 3D Object Detection in Adverse Weather Conditions</b> <ul style="list-style-type: none"><li>Design and train a deep autoencoder for 2D feature extraction in adverse weather.</li><li>Implemented early-fusion for multi-modal synthetic data generated in CARLA.</li></ul>

- 01.2025 – 02.2025      **Novel Aerial View Synthesis using 3D Gaussian Splatting**
- Applied 3D Gaussian Splatting to synthesize high-fidelity novel aerial views from monocular images.
  - Leveraging Metashape to output sparse reconstruction in COLMAP format.
- 06.2024 – 12.2024      **Semantic Occupancy Prediction for Advanced Air Mobility**  
*Master Thesis (expected release and submission: CVPR 2026)*
- A novel benchmark semantic occupancy dataset for UAS, ran ablations on SOTA SSC models, and working on a novel geometry-aware model architecture for aerial scenes.
  - Developed a large-scale dataset with monocular RGB + thermal aerial imagery.
  - Designed a data-generation pipeline that integrates 3D reconstruction, pose estimation, semantic fusion, mesh generation, voxelization, and voxel densification.

## Skills

<b>Python</b> — Proficient	<b>Machine Learning and Deep Learning</b> — Proficient
<b>Computer Vision(2D/3D)</b> — Proficient	<b>PyTorch</b> — Proficient
<b>Generative AI</b> — Competent	<b>Agentic AI, MCP</b> — Competent
<b>Kubernetes, Git</b> — Competent	<b>Docker</b> — Competent
<b>C++</b> — Competent	<b>SQL</b> — Competent
<b>Robot Operating System(ROS)</b> — Competent	<b>STM32, RTOS</b> — Competent
<b>Linux</b> — Competent	<b>Data Structures</b> — Competent

## Languages

<b>English</b> — Native/Bilingual <i>IELTS score: 8.0/9.0</i>	<b>German</b> — Conversational CEFR Level B1
<b>Telugu</b> — Native/Bilingual <i>Mother Tongue</i>	<b>Hindi</b> — Native/Bilingual <i>National Language</i>

## Courses & Certificates

<b>Big Data</b> <i>Issued by Coursera</i>	<b>Quantum Computing</b> <i>Elective from THD</i>
<b>MLOps (AWS): Deploying AI &amp; ML Models</b> <i>Issued by edX</i>	<b>AI Agents</b> <i>Issued by Hugging Face</i>

## Leadership and Volunteering

2019 – 2020 Rourkela, India	<b>VS Hall of Residence</b> <i>Student elected representative</i>
2017 – 2020 Rourkela, India	<b>Plugged_IN</b> <i>Vice President</i>

## References

**Prof. Dr. Dmitrii Dobriborsci**, *Professor*, Technische Hochschule Deggendorf  
dmitrii.dobriborsci@th-deg.de

**Henri Meess**, *M.Sc., Manager*, Fraunhofer IVI  
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## Interests

- Cooking and blogging
- eFootball and gaming

## Declaration

I affirm that all information provided is true and accurate to the best of my knowledge.

*M. Sai Bhavadhuaj*

Kothmaissling, 13.07.2025