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Challenging Problem1

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Lines and Planes

Abstract—This documnet contains the solution to find the points on the lines that are closest to each other. Given Lines are skew

Download latex-tikz codes from

https://github.com/shivangi-975/Challenge_1/blob/master/Challenge_1.tex

1 Problem

Find the points on the skew lines that are closest to eachother in 3-Dimensions? skew line 1 passing through the point A(1,1,0) with directional vector $v_1(2,-1,1)$ and skew line 2 passing through the point B(2,1,-1) with directional vector $v_2(3,-5,2)$

$$L_1: x = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} + \lambda \begin{pmatrix} 2 \\ -1 \\ 1 \end{pmatrix}$$
 (1.0.1)

and

$$L_2: x = \begin{pmatrix} 2\\1\\-1 \end{pmatrix} + \omega \begin{pmatrix} 3\\-5\\2 \end{pmatrix}$$
 (1.0.2)

2 Solution

Let the closest points be $P(p_1, p_2, p_3)$ on skew line1 and $Q(q_1, q_2, q_3)$ on skew line2, Let p,q be two points on the lines L_1, L_2

$$p = x_1 + \lambda_1 v_1 \tag{2.0.1}$$

$$q = x_2 + \lambda_2 \mathbf{v_2} \tag{2.0.2}$$

$$pq = x_2 + \lambda_2 v_2 - x_1 - \lambda_1 v_1$$

$$pq = \begin{pmatrix} x_2 & v_2 \end{pmatrix} \begin{pmatrix} 1 \\ \lambda_2 \end{pmatrix} - \begin{pmatrix} x_1 & v_1 \end{pmatrix} \begin{pmatrix} 1 \\ \lambda_1 \end{pmatrix}$$
 (2.0.3)

points P and Q are closest points,p-q will be perpendicular to both the skew lines, Therefore,

$$\mathbf{v}_1^T(\mathbf{q} - \mathbf{p}) = 0 \tag{2.0.4}$$

$$\mathbf{v}_2^T(\mathbf{q} - \mathbf{p}) = 0 \tag{2.0.5}$$

From 2.0.4 and 2.0.5 we have: The dot product of v_1 with the line pq is

$$\mathbf{v_1}^T \begin{pmatrix} x_2 & \mathbf{v_2} \end{pmatrix} \begin{pmatrix} 1 \\ \lambda_2 \end{pmatrix} - \mathbf{v_1}^T \begin{pmatrix} x_1 & \mathbf{v_1} \end{pmatrix} \begin{pmatrix} 1 \\ \lambda_1 \end{pmatrix} = 0$$
 (2.0.6)

The dot product of v_2 with the line pq is

$$\mathbf{v_2^T} \begin{pmatrix} x_2 & \mathbf{v_2} \end{pmatrix} \begin{pmatrix} 1 \\ \lambda_2 \end{pmatrix} - \mathbf{v_2^T} \begin{pmatrix} x_1 & \mathbf{v_2} \end{pmatrix} \begin{pmatrix} 1 \\ \lambda_1 \end{pmatrix} = 0$$
 (2.0.7)

solving 2.0.6 and 2.0.7we get

$$\begin{pmatrix} \mathbf{v}_{1}^{T} x_{2} & \mathbf{v}_{1}^{T} \mathbf{v}_{2} & -\mathbf{v}_{1}^{T} x_{1} & -\mathbf{v}_{1}^{T} \mathbf{v}_{1} \\ \mathbf{v}_{2}^{T} x_{2} & \mathbf{v}_{2}^{T} \mathbf{v}_{2} & -\mathbf{v}_{2}^{T} x_{1} & -\mathbf{v}_{2}^{T} \mathbf{v}_{1} \end{pmatrix} \begin{pmatrix} 1 \\ \lambda_{1} \\ 1 \\ \lambda_{2} \end{pmatrix} = 0$$
 (2.0.8)

simplifying it further

$$\begin{pmatrix} v_1^T v_1 & -v_1^T v_2 \\ v_2^T v_1 & -v_2^T v_2 \end{pmatrix} \begin{pmatrix} \lambda_1 \\ \lambda_2 \end{pmatrix} = \begin{pmatrix} v_1^T (x_2 - x_1) \\ v_2^T (x_2 - x_1) \end{pmatrix}$$
(2.0.9)

Substituting values we have $\lambda_1 = 25/59$ and $\lambda_2 = 7/59$ and coordinates of points would be.

$$P = \begin{pmatrix} 109/59\\ 34/59\\ 23/59 \end{pmatrix} \tag{2.0.10}$$