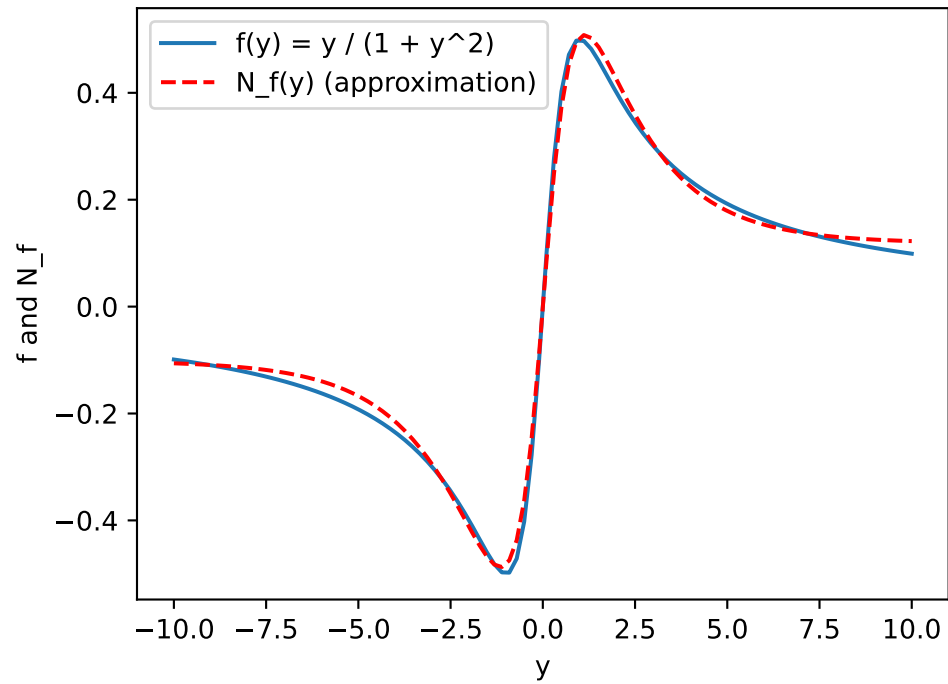


$f(y)$  and its estimate  $N_f$



$g(u)$  and its estimate  $N_g$

