

MTP_BNN

May 26, 2022

packages

```
[ ]: #empty
```

```
[ ]: !pip install pyforest
# a package which automatically installs a package as an when it is used.
# may not work sometimes in notebook.
```

```
Looking in indexes: https://pypi.org/simple, https://us-python.pkg.dev/colab-
wheels/public/simple/
Collecting pyforest
  Downloading pyforest-1.1.0.tar.gz (15 kB)
Building wheels for collected packages: pyforest
  Building wheel for pyforest (setup.py) ... done
  Created wheel for pyforest: filename=pyforest-1.1.0-py2.py3-none-any.whl
size=14607
sha256=8b55dc28443a64c18c99111832f45e7e282c60b5068ead6ddf386de7261cc385
  Stored in directory: /root/.cache/pip/wheels/61/1c/da/48e6c884142d485475d852d6
9d20a096aba5beceb338822893
Successfully built pyforest
Installing collected packages: pyforest
Successfully installed pyforest-1.1.0
```

```
[ ]: #automatic imports required packages as per usage in code
import pyforest
```

```
[ ]: #packages
!pip install tensorflow-probability
!pip install nbconvert
```

```
Looking in indexes: https://pypi.org/simple, https://us-python.pkg.dev/colab-
wheels/public/simple/
Requirement already satisfied: tensorflow-probability in
/usr/local/lib/python3.7/dist-packages (0.16.0)
Requirement already satisfied: cloudpickle>=1.3 in
/usr/local/lib/python3.7/dist-packages (from tensorflow-probability) (1.3.0)
Requirement already satisfied: gast>=0.3.2 in /usr/local/lib/python3.7/dist-
packages (from tensorflow-probability) (0.5.3)
Requirement already satisfied: absl-py in /usr/local/lib/python3.7/dist-packages
```

(from tensorflow-probability) (1.0.0)

Requirement already satisfied: decorator in /usr/local/lib/python3.7/dist-packages (from tensorflow-probability) (4.4.2)

Requirement already satisfied: dm-tree in /usr/local/lib/python3.7/dist-packages (from tensorflow-probability) (0.1.7)

Requirement already satisfied: six>=1.10.0 in /usr/local/lib/python3.7/dist-packages (from tensorflow-probability) (1.15.0)

Requirement already satisfied: numpy>=1.13.3 in /usr/local/lib/python3.7/dist-packages (from tensorflow-probability) (1.21.6)

Looking in indexes: <https://pypi.org/simple>, <https://us-python.pkg.dev/colab-wheels/public/simple/>

Requirement already satisfied: nbconvert in /usr/local/lib/python3.7/dist-packages (5.6.1)

Requirement already satisfied: entrypoints>=0.2.2 in /usr/local/lib/python3.7/dist-packages (from nbconvert) (0.4)

Requirement already satisfied: defusedxml in /usr/local/lib/python3.7/dist-packages (from nbconvert) (0.7.1)

Requirement already satisfied: testpath in /usr/local/lib/python3.7/dist-packages (from nbconvert) (0.6.0)

Requirement already satisfied: bleach in /usr/local/lib/python3.7/dist-packages (from nbconvert) (5.0.0)

Requirement already satisfied: traitlets>=4.2 in /usr/local/lib/python3.7/dist-packages (from nbconvert) (5.1.1)

Requirement already satisfied: pandocfilters>=1.4.1 in /usr/local/lib/python3.7/dist-packages (from nbconvert) (1.5.0)

Requirement already satisfied: mistune<2,>=0.8.1 in /usr/local/lib/python3.7/dist-packages (from nbconvert) (0.8.4)

Requirement already satisfied: jinja2>=2.4 in /usr/local/lib/python3.7/dist-packages (from nbconvert) (2.11.3)

Requirement already satisfied: jupyter-core in /usr/local/lib/python3.7/dist-packages (from nbconvert) (4.10.0)

Requirement already satisfied: pygments in /usr/local/lib/python3.7/dist-packages (from nbconvert) (2.6.1)

Requirement already satisfied: nbformat>=4.4 in /usr/local/lib/python3.7/dist-packages (from nbconvert) (5.4.0)

Requirement already satisfied: MarkupSafe>=0.23 in /usr/local/lib/python3.7/dist-packages (from jinja2>=2.4->nbconvert) (2.0.1)

Requirement already satisfied: jsonschema>=2.6 in /usr/local/lib/python3.7/dist-packages (from nbformat>=4.4->nbconvert) (4.3.3)

Requirement already satisfied: fastjsonschema in /usr/local/lib/python3.7/dist-packages (from nbformat>=4.4->nbconvert) (2.15.3)

Requirement already satisfied: attrs>=17.4.0 in /usr/local/lib/python3.7/dist-packages (from jsonschema>=2.6->nbformat>=4.4->nbconvert) (21.4.0)

Requirement already satisfied: importlib-resources>=1.4.0 in /usr/local/lib/python3.7/dist-packages (from jsonschema>=2.6->nbformat>=4.4->nbconvert) (5.7.1)

Requirement already satisfied: typing-extensions in /usr/local/lib/python3.7/dist-packages (from

```

jsonschema>=2.6->nbformat>=4.4->nbconvert) (4.2.0)
Requirement already satisfied: importlib-metadata in
/usr/local/lib/python3.7/dist-packages (from
jsonschema>=2.6->nbformat>=4.4->nbconvert) (4.11.3)
Requirement already satisfied: pyrsistent!=0.17.0,!0.17.1,!0.17.2,>=0.14.0 in
/usr/local/lib/python3.7/dist-packages (from
jsonschema>=2.6->nbformat>=4.4->nbconvert) (0.18.1)
Requirement already satisfied: zipp>=3.1.0 in /usr/local/lib/python3.7/dist-
packages (from importlib-
resources>=1.4.0->jsonschema>=2.6->nbformat>=4.4->nbconvert) (3.8.0)
Requirement already satisfied: webencodings in /usr/local/lib/python3.7/dist-
packages (from bleach->nbconvert) (0.5.1)
Requirement already satisfied: six>=1.9.0 in /usr/local/lib/python3.7/dist-
packages (from bleach->nbconvert) (1.15.0)

```

```
[ ]: import pandas as pd
import numpy as np
```

0.0.1 DATA

import data

```
[ ]: #using official url to load data
# this is the dataset which is used throughout the project. taken from uci_
↳ repository.
url = 'https://archive.ics.uci.edu/ml/machine-learning-databases/00601/ai4i2020.
↳ csv'
#loading the dataset into data variable
data = pd.read_csv(url)

data.head()
```

```
[ ]:
UDI Product ID Type Air temperature [K] Process temperature [K] \
0 1 M14860 M 298.1 308.6
1 2 L47181 L 298.2 308.7
2 3 L47182 L 298.1 308.5
3 4 L47183 L 298.2 308.6
4 5 L47184 L 298.2 308.7

Rotational speed [rpm] Torque [Nm] Tool wear [min] Machine failure TWF \
0 1551 42.8 0 0 0
1 1408 46.3 3 0 0
2 1498 49.4 5 0 0
3 1433 39.5 7 0 0
4 1408 40.0 9 0 0

HDF PWF OSF RNF
```

0	0	0	0	0
1	0	0	0	0
2	0	0	0	0
3	0	0	0	0
4	0	0	0	0

data description taken from UCI:

Abstract: The AI4I 2020 Predictive Maintenance Dataset is a synthetic dataset that reflects real predictive maintenance data encountered in industry.

Variable	Value
Data Set Characteristics:	Multivariate, Time-Series
Number of Instances:	10000
Area:	Computer
Attribute Characteristics:	Real
Number of Attributes:	14
Date Donated:	2020-08-30
Associated Tasks:	Classification, Regression, Causal-Discovery
Missing Values?	N/A
Number of Web Hits:	33135

** Data Set Information: **

Since real predictive maintenance datasets are generally difficult to obtain and in particular difficult to publish, we present and provide a synthetic dataset that reflects real predictive maintenance encountered in industry to the best of our knowledge.

Attribute Information:

The dataset consists of 10 000 data points stored as rows with 14 features in columns UID: unique identifier ranging from 1 to 10000 product ID: consisting of a letter L, M, or H for low (50% of all products), medium (30%) and high (20%) as product quality variants and a variant-specific serial number air temperature [K]: generated using a random walk process later normalized to a standard deviation of 2 K around 300 K process temperature [K]: generated using a random walk process normalized to a standard deviation of 1 K, added to the air temperature plus 10 K. rotational speed [rpm]: calculated from a power of 2860 W, overlaid with a normally distributed noise torque [Nm]: torque values are normally distributed around 40 Nm with a $\hat{\sigma} = 10$ Nm and no negative values. tool wear [min]: The quality variants H/M/L add 5/3/2 minutes of tool wear to the used tool in the process. and a 'machine failure' label that indicates, whether the machine has failed in this particular datapoint for any of the following failure modes are true.

The machine failure consists of five independent failure modes tool wear failure (TWF): the tool will be replaced or fail at a randomly selected tool wear time between 200 – 240 mins (120 times in our dataset). At this point in time, the tool is replaced 69 times, and fails 51 times (randomly assigned). heat dissipation failure (HDF): heat dissipation causes a process failure, if the difference between air- and process temperature is below 8.6 K and the tool's rotational speed is below 1380 rpm. This is the case for 115 data points. power failure (PWF): the product of torque and

rotational speed (in rad/s) equals the power required for the process. If this power is below 3500 W or above 9000 W, the process fails, which is the case 95 times in our dataset. overstrain failure (OSF): if the product of tool wear and torque exceeds 11,000 minNm for the L product variant (12,000 M, 13,000 H), the process fails due to overstrain. This is true for 98 datapoints. random failures (RNF): each process has a chance of 0,1 % to fail regardless of its process parameters. This is the case for only 5 datapoints, less than could be expected for 10,000 datapoints in our dataset.

If at least one of the above failure modes is true, the process fails and the 'machine failure' label is set to 1. It is therefore not transparent to the machine learning method, which of the failure modes has caused the process to fail

Relevant Papers:

Stephan Matzka, 'Explainable Artificial Intelligence for Predictive Maintenance Applications', Third International Conference on Artificial Intelligence for Industries (AI4I 2020), 2020 (in press)

```
[ ]: data.describe()
```

```
[ ]:
```

	UDI	Air temperature [K]	Process temperature [K]	\
count	10000.00000	10000.000000	10000.000000	
mean	5000.50000	300.004930	310.005560	
std	2886.89568	2.000259	1.483734	
min	1.00000	295.300000	305.700000	
25%	2500.75000	298.300000	308.800000	
50%	5000.50000	300.100000	310.100000	
75%	7500.25000	301.500000	311.100000	
max	10000.00000	304.500000	313.800000	

	Rotational speed [rpm]	Torque [Nm]	Tool wear [min]	Machine failure \
count	10000.000000	10000.000000	10000.000000	10000.000000
mean	1538.776100	39.986910	107.951000	0.033900
std	179.284096	9.968934	63.654147	0.180981
min	1168.000000	3.800000	0.000000	0.000000
25%	1423.000000	33.200000	53.000000	0.000000
50%	1503.000000	40.100000	108.000000	0.000000
75%	1612.000000	46.800000	162.000000	0.000000
max	2886.000000	76.600000	253.000000	1.000000

	TWF	HDF	PWF	OSF	RNF
count	10000.000000	10000.000000	10000.000000	10000.000000	10000.000000
mean	0.004600	0.011500	0.009500	0.009800	0.00190
std	0.067671	0.106625	0.097009	0.098514	0.04355
min	0.000000	0.000000	0.000000	0.000000	0.000000
25%	0.000000	0.000000	0.000000	0.000000	0.000000
50%	0.000000	0.000000	0.000000	0.000000	0.000000
75%	0.000000	0.000000	0.000000	0.000000	0.000000
max	1.000000	1.000000	1.000000	1.000000	1.000000

```
[ ]: #for i in data:
      #print(data[i].unique())
```

```
[ ]: # checking about different attributes in the data
data.nunique()
```

```
[ ]: UDI          10000
      Product ID  10000
      Type        3
      Air temperature [K]  93
      Process temperature [K]  82
      Rotational speed [rpm]  941
      Torque [Nm]  577
      Tool wear [min]  246
      Machine failure  2
      TWF           2
      HDF           2
      PWF           2
      OSF           2
      RNF           2
      dtype: int64
```

```
[ ]: #basic info about dataset
df = data
df.shape
df.index
df.columns
df.info()
df.count()
```

```
<class 'pandas.core.frame.DataFrame'>
RangeIndex: 10000 entries, 0 to 9999
Data columns (total 14 columns):
#   Column                                Non-Null Count  Dtype
---  -
0   UDI                                   10000 non-null  int64
1   Product ID                           10000 non-null  object
2   Type                                 10000 non-null  object
3   Air temperature [K]                  10000 non-null  float64
4   Process temperature [K]              10000 non-null  float64
5   Rotational speed [rpm]               10000 non-null  int64
6   Torque [Nm]                         10000 non-null  float64
7   Tool wear [min]                     10000 non-null  int64
8   Machine failure                      10000 non-null  int64
9   TWF                                  10000 non-null  int64
10  HDF                                  10000 non-null  int64
11  PWF                                  10000 non-null  int64
```

```

12  OSF                                10000 non-null  int64
13  RNF                                10000 non-null  int64
dtypes: float64(3), int64(9), object(2)
memory usage: 1.1+ MB

```

```

[ ]: UDI                                10000
     Product ID                        10000
     Type                              10000
     Air temperature [K]               10000
     Process temperature [K]          10000
     Rotational speed [rpm]           10000
     Torque [Nm]                      10000
     Tool wear [min]                  10000
     Machine failure                   10000
     TWF                              10000
     HDF                              10000
     PWF                              10000
     OSF                              10000
     RNF                              10000
     dtype: int64

```

```

[ ]: # not used all these but just to check the data.
     df.sum()
     df.cumsum()
     df.min()
     df.max()
     df.describe()
     df.mean()
     df.median()

```

```

/usr/local/lib/python3.7/dist-packages/pyforest/__init__.py:7: FutureWarning:
Dropping of nuisance columns in DataFrame reductions (with 'numeric_only=None')
is deprecated; in a future version this will raise TypeError.  Select only valid
columns before calling the reduction.

```

```

    install_labextension,
/usr/local/lib/python3.7/dist-packages/pyforest/__init__.py:8: FutureWarning:
Dropping of nuisance columns in DataFrame reductions (with 'numeric_only=None')
is deprecated; in a future version this will raise TypeError.  Select only valid
columns before calling the reduction.
)

```

```

[ ]: UDI                                5000.5
     Air temperature [K]                300.1
     Process temperature [K]            310.1
     Rotational speed [rpm]             1503.0
     Torque [Nm]                       40.1
     Tool wear [min]                   108.0
     Machine failure                    0.0

```

```
TWF          0.0
HDF          0.0
PWF          0.0
OSF          0.0
RNF          0.0
dtype: float64
```

preprocessing data

```
[ ]: #define X and y from df
# product id is unique for each data row and its not important
# but we have product type of 3 categories
# L, M, H are three types representing for low (50% of all products),
# medium (30%) and high (20%) as product quality variants respectively
df['Type'].unique()
```

```
[ ]: array(['M', 'L', 'H'], dtype=object)
```

```
[ ]: # converting this categorical data to numerical with class 0, 1, 2 for L,M,H
      ↳respectively
# using OrdinalEncoder from sklearn for ordinal data of product quality variant
# indicating l for low quality, m for medium quality, h for high quality
# one-hot encoding is not suitable for ordinal data
from sklearn.preprocessing import OrdinalEncoder
ordinal_encoder = OrdinalEncoder()
df['Type'] = ordinal_encoder.fit_transform(df[['Type']])
df['Type'].unique()
# this gives categories converted into integers
```

```
[ ]: array([2., 1., 0.])
```

```
[ ]: # these are original categories in data
ordinal_encoder.categories_
```

```
[ ]: [array(['H', 'L', 'M'], dtype=object)]
```

```
[ ]: # this sorts all the categories present and assigns values to them in
      ↳alphabetical order
# 0 for H
# 1 for L
# 2 for M
print(ordinal_encoder.inverse_transform([[0]]))
print(ordinal_encoder.inverse_transform([[1]]))
print(ordinal_encoder.inverse_transform([[2]]))
```

```
[['H']]
[['L']]
```



```
[['M']]
```

```
[ ]: df.describe()
```

```
[ ]:
```

	UDI	Type	Air temperature [K]	Process temperature [K]	\
count	10000.00000	10000.00000	10000.00000	10000.00000	
mean	5000.50000	1.19940	300.004930	310.005560	
std	2886.89568	0.60023	2.000259	1.483734	
min	1.00000	0.00000	295.300000	305.700000	
25%	2500.75000	1.00000	298.300000	308.800000	
50%	5000.50000	1.00000	300.100000	310.100000	
75%	7500.25000	2.00000	301.500000	311.100000	
max	10000.00000	2.00000	304.500000	313.800000	

	Rotational speed [rpm]	Torque [Nm]	Tool wear [min]	Machine failure	\
count	10000.000000	10000.000000	10000.000000	10000.000000	
mean	1538.776100	39.986910	107.951000	0.033900	
std	179.284096	9.968934	63.654147	0.180981	
min	1168.000000	3.800000	0.000000	0.000000	
25%	1423.000000	33.200000	53.000000	0.000000	
50%	1503.000000	40.100000	108.000000	0.000000	
75%	1612.000000	46.800000	162.000000	0.000000	
max	2886.000000	76.600000	253.000000	1.000000	

	TWF	HDF	PWF	OSF	RNF
count	10000.000000	10000.000000	10000.000000	10000.000000	10000.000000
mean	0.004600	0.011500	0.009500	0.009800	0.00190
std	0.067671	0.106625	0.097009	0.098514	0.04355
min	0.000000	0.000000	0.000000	0.000000	0.000000
25%	0.000000	0.000000	0.000000	0.000000	0.000000
50%	0.000000	0.000000	0.000000	0.000000	0.000000
75%	0.000000	0.000000	0.000000	0.000000	0.000000
max	1.000000	1.000000	1.000000	1.000000	1.000000

```
[ ]: df.nunique()
```

```
[ ]:
```

UDI	10000
Product ID	10000
Type	3
Air temperature [K]	93
Process temperature [K]	82
Rotational speed [rpm]	941
Torque [Nm]	577
Tool wear [min]	246
Machine failure	2
TWF	2
HDF	2

```
PWF                2
OSF                2
RNF                2
dtype: int64
```

```
[ ]: df.info()
```

```
<class 'pandas.core.frame.DataFrame'>
RangeIndex: 10000 entries, 0 to 9999
Data columns (total 14 columns):
#   Column                                Non-Null Count  Dtype
---  -
0   UDI                                    10000 non-null  int64
1   Product ID                           10000 non-null  object
2   Type                                  10000 non-null  float64
3   Air temperature [K]                  10000 non-null  float64
4   Process temperature [K]              10000 non-null  float64
5   Rotational speed [rpm]               10000 non-null  int64
6   Torque [Nm]                          10000 non-null  float64
7   Tool wear [min]                      10000 non-null  int64
8   Machine failure                      10000 non-null  int64
9   TWF                                  10000 non-null  int64
10  HDF                                  10000 non-null  int64
11  PWF                                  10000 non-null  int64
12  OSF                                  10000 non-null  int64
13  RNF                                  10000 non-null  int64
dtypes: float64(4), int64(9), object(1)
memory usage: 1.1+ MB
```

```
[ ]: # now make the final dataset to be used in NN
# remove the product id variable
# remaining attributes are of types either int64 or float64
df.drop('Product ID', axis=1, inplace=True)
df.drop('UDI', axis=1, inplace=True)
```

```
[ ]: df.info()
```

```
<class 'pandas.core.frame.DataFrame'>
RangeIndex: 10000 entries, 0 to 9999
Data columns (total 12 columns):
#   Column                                Non-Null Count  Dtype
---  -
0   Type                                  10000 non-null  float64
1   Air temperature [K]                  10000 non-null  float64
2   Process temperature [K]              10000 non-null  float64
3   Rotational speed [rpm]               10000 non-null  int64
4   Torque [Nm]                          10000 non-null  float64
```

```
5   Tool wear [min]          10000 non-null  int64
6   Machine failure         10000 non-null  int64
7   TWF                     10000 non-null  int64
8   HDF                     10000 non-null  int64
9   PWF                     10000 non-null  int64
10  OSF                     10000 non-null  int64
11  RNF                     10000 non-null  int64
dtypes: float64(4), int64(8)
memory usage: 937.6 KB
```

```
[ ]: ## add mitosheet data visualization
```

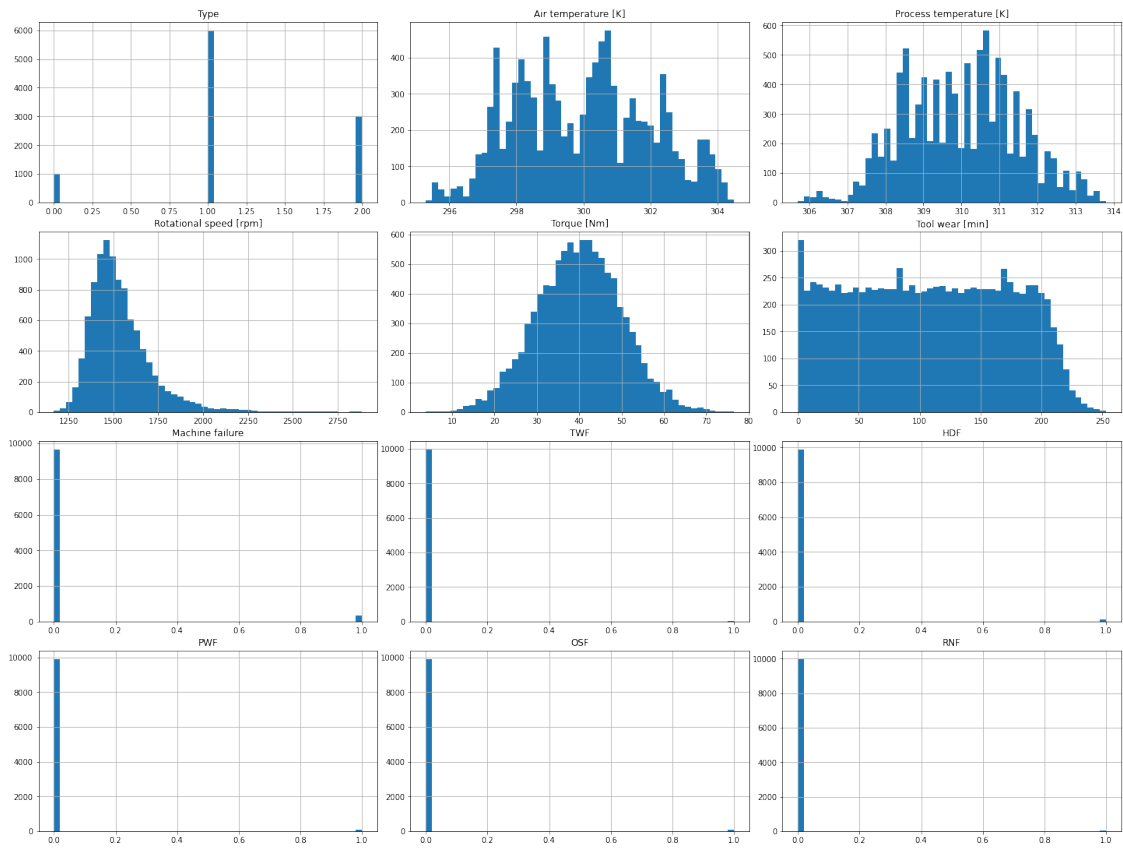
mitosheet visualization code

```
[ ]: # exploring data with various plots to know more about it
```

```
[ ]: df.hist(bins=50, figsize=(20,15))
plt.tight_layout(pad=0.4)
plt.show()
```

<IPython.core.display.Javascript object>

<IPython.core.display.Javascript object>



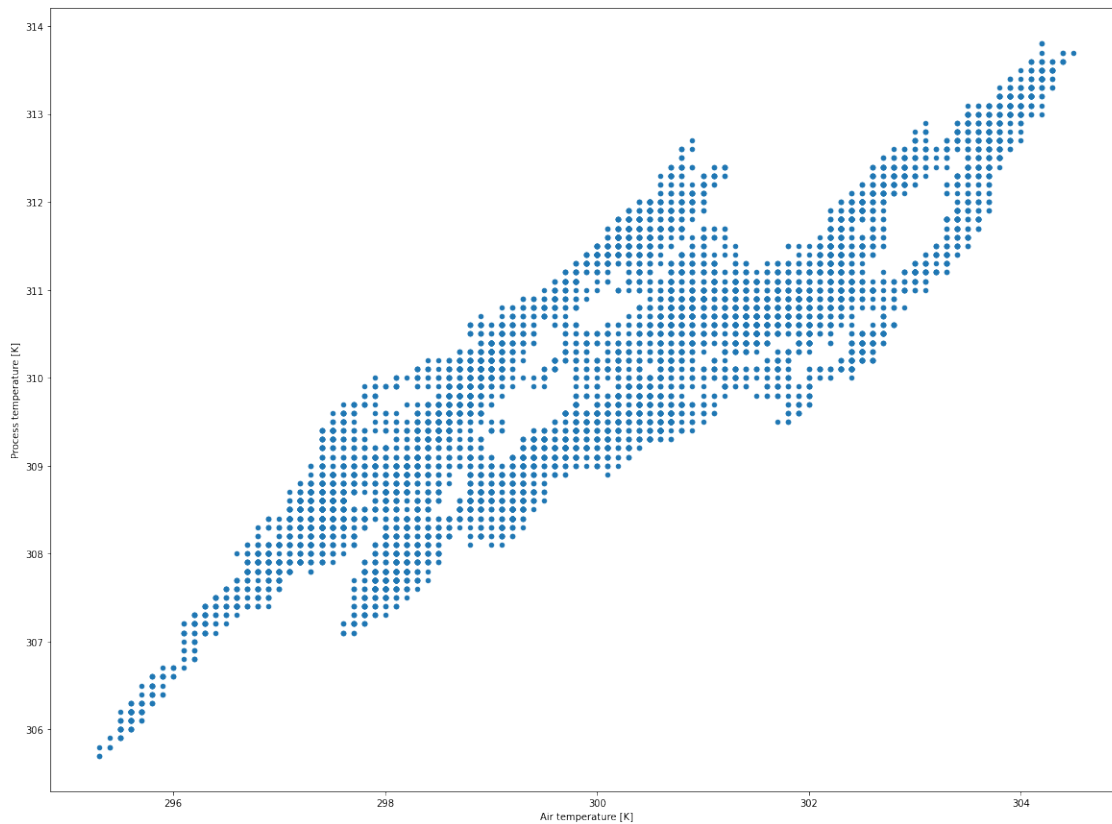
```
[ ]: df.plot.scatter(y = 'Type',x='Air temperature [K]', figsize=(20,15))
plt.show()
```

<IPython.core.display.Javascript object>



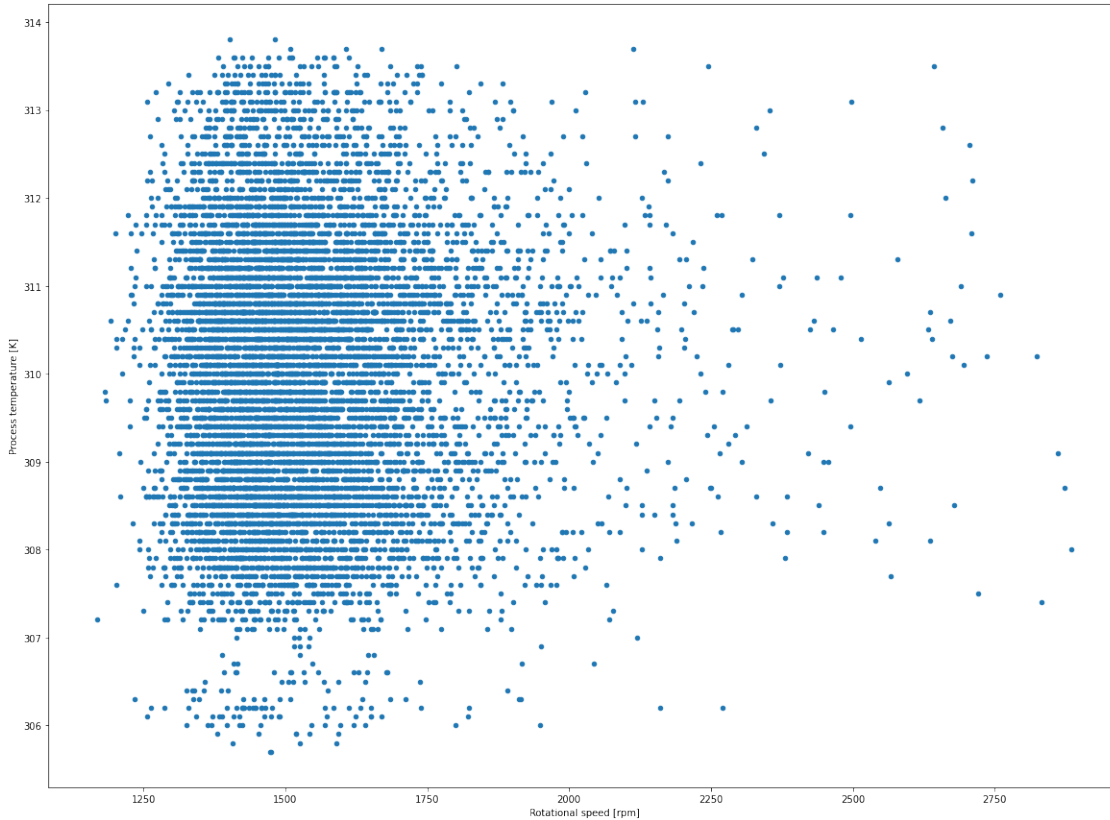
```
[ ]: df.plot.scatter(y = 'Process temperature [K]',x='Air temperature [K]',  
    ↳figsize=(20,15))  
plt.show()
```

<IPython.core.display.Javascript object>



```
[ ]: df.plot.scatter(y = 'Process temperature [K]',x='Rotational speed [rpm]',  
    ↳figsize=(20,15))  
plt.show()
```

<IPython.core.display.Javascript object>



```
[ ]: #confusion matrix
```

```
[ ]: import seaborn as sns
```

```
#correlation matrix
numeric_col = ['Type', 'Air temperature [K]', 'Process temperature [K]',
               'Rotational speed [rpm]', 'Torque [Nm]', 'Tool wear [min]',
               'TWF', 'HDF', 'PWF', 'OSF', 'RNF', 'Machine failure']
# Correlation Matrix formation
corr_matrix = df.loc[:,numeric_col].corr()
print(corr_matrix)
#Using heatmap to visualize the correlation matrix
fig, ax = plt.subplots(figsize=(10,10))
sns.heatmap(corr_matrix, annot=True,ax=ax)
```

	Type	Air temperature [K]	\
Type	1.000000	0.017599	
Air temperature [K]	0.017599	1.000000	
Process temperature [K]	0.013444	0.876107	
Rotational speed [rpm]	-0.002693	0.022670	
Torque [Nm]	0.004011	-0.013778	

Tool wear [min]	-0.003930	0.013853
TWF	-0.005349	0.009955
HDF	0.000108	0.137831
PWF	0.012121	0.003470
OSF	-0.021211	0.001988
RNF	-0.022147	0.017688
Machine failure	-0.005152	0.082556

	Process temperature [K]	Rotational speed [rpm]	\
Type	0.013444	-0.002693	
Air temperature [K]	0.876107	0.022670	
Process temperature [K]	1.000000	0.019277	
Rotational speed [rpm]	0.019277	1.000000	
Torque [Nm]	-0.014061	-0.875027	
Tool wear [min]	0.013488	0.000223	
TWF	0.007315	0.010389	
HDF	0.056933	-0.121241	
PWF	-0.003355	0.123018	
OSF	0.004554	-0.104575	
RNF	0.022279	-0.013088	
Machine failure	0.035946	-0.044188	

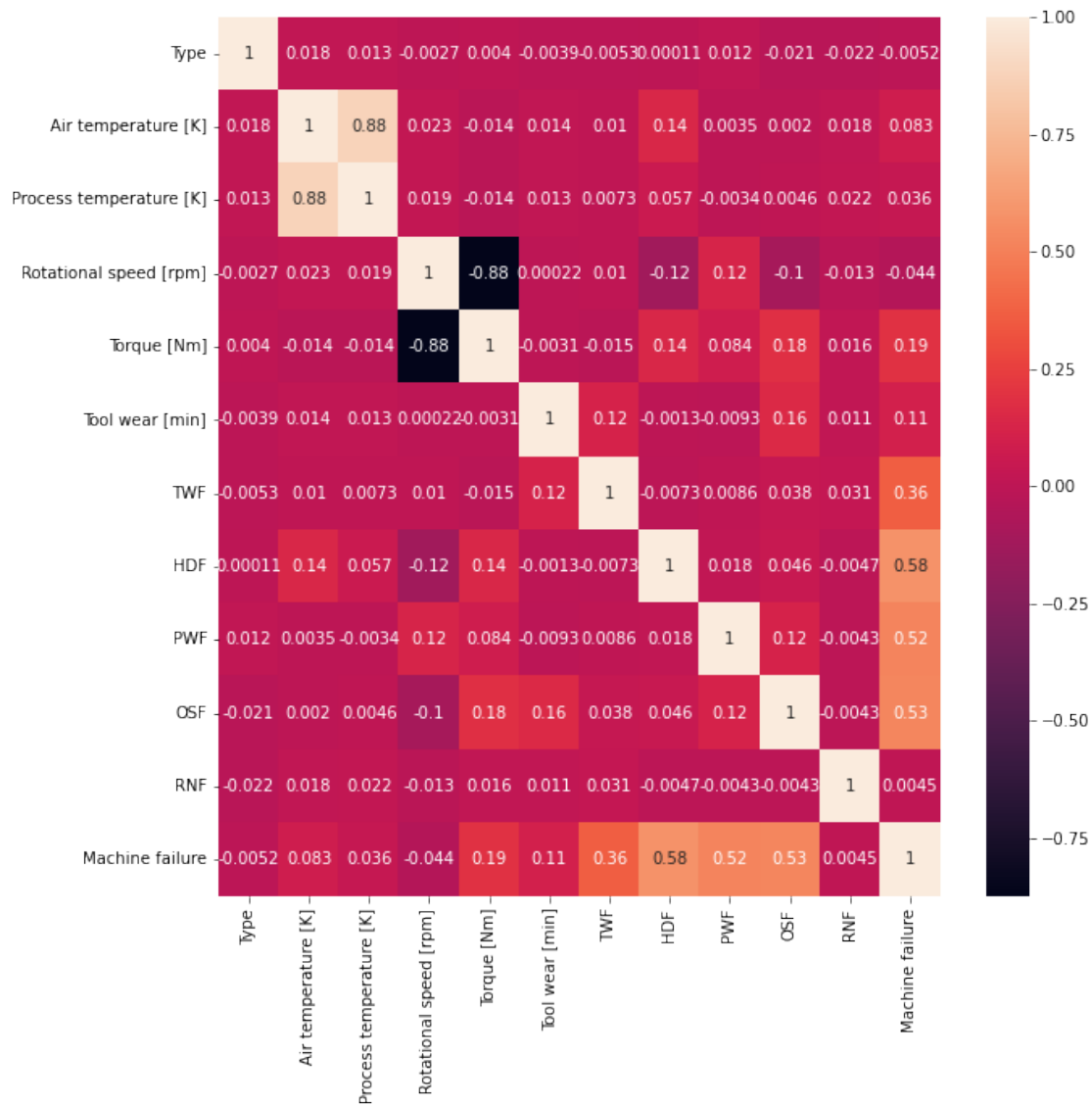
	Torque [Nm]	Tool wear [min]	TWF	HDF	\
Type	0.004011	-0.003930	-0.005349	0.000108	
Air temperature [K]	-0.013778	0.013853	0.009955	0.137831	
Process temperature [K]	-0.014061	0.013488	0.007315	0.056933	
Rotational speed [rpm]	-0.875027	0.000223	0.010389	-0.121241	
Torque [Nm]	1.000000	-0.003093	-0.014662	0.142610	
Tool wear [min]	-0.003093	1.000000	0.115792	-0.001287	
TWF	-0.014662	0.115792	1.000000	-0.007332	
HDF	0.142610	-0.001287	-0.007332	1.000000	
PWF	0.083781	-0.009334	0.008577	0.018443	
OSF	0.183465	0.155894	0.038243	0.046396	
RNF	0.016136	0.011326	0.030970	-0.004706	
Machine failure	0.191321	0.105448	0.362904	0.575800	

	PWF	OSF	RNF	Machine failure
Type	0.012121	-0.021211	-0.022147	-0.005152
Air temperature [K]	0.003470	0.001988	0.017688	0.082556
Process temperature [K]	-0.003355	0.004554	0.022279	0.035946
Rotational speed [rpm]	0.123018	-0.104575	-0.013088	-0.044188
Torque [Nm]	0.083781	0.183465	0.016136	0.191321
Tool wear [min]	-0.009334	0.155894	0.011326	0.105448
TWF	0.008577	0.038243	0.030970	0.362904
HDF	0.018443	0.046396	-0.004706	0.575800
PWF	1.000000	0.115836	-0.004273	0.522812
OSF	0.115836	1.000000	-0.004341	0.531083
RNF	-0.004273	-0.004341	1.000000	0.004516

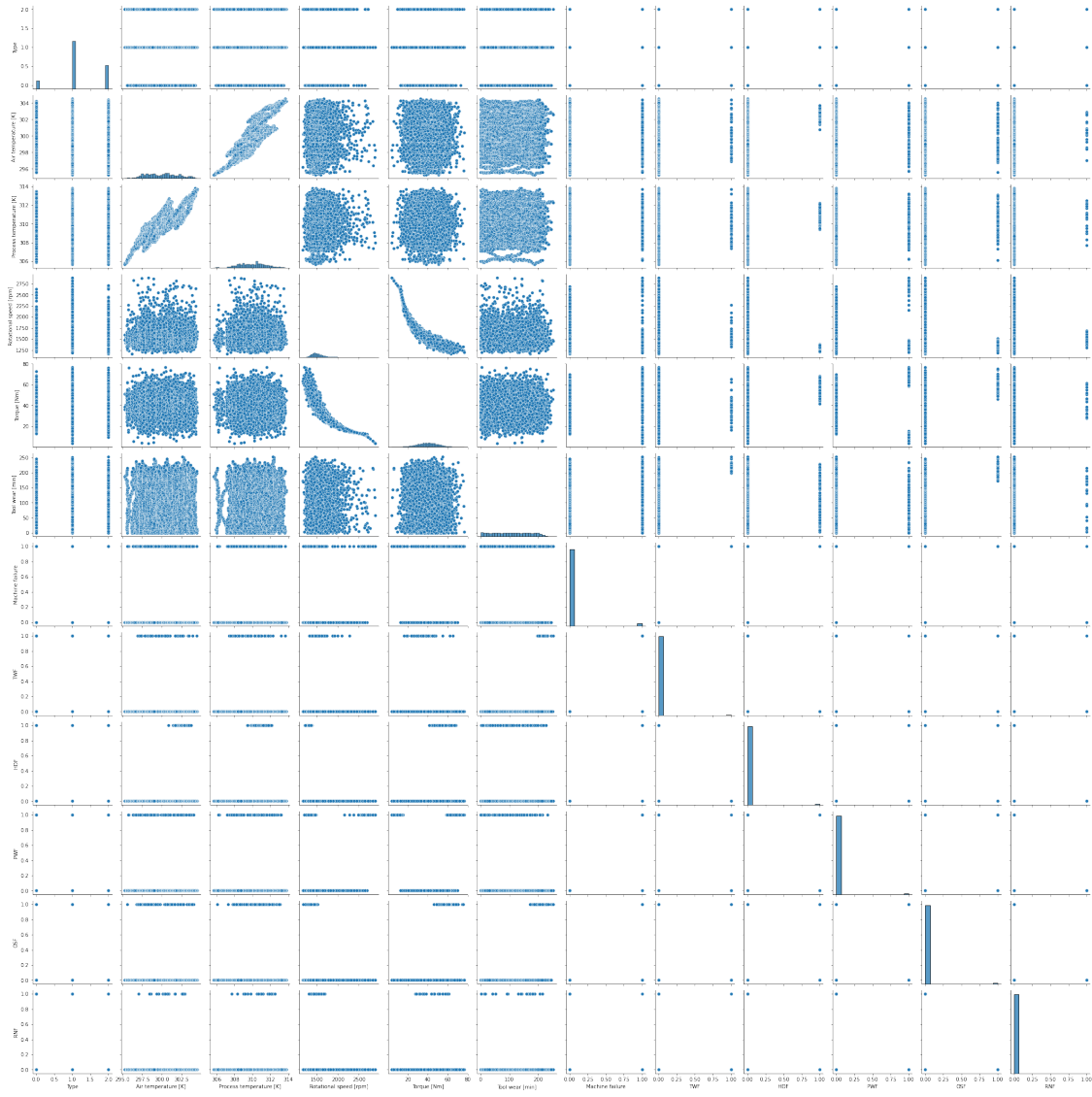
Machine failure 0.522812 0.531083 0.004516 1.000000

<IPython.core.display.Javascript object>

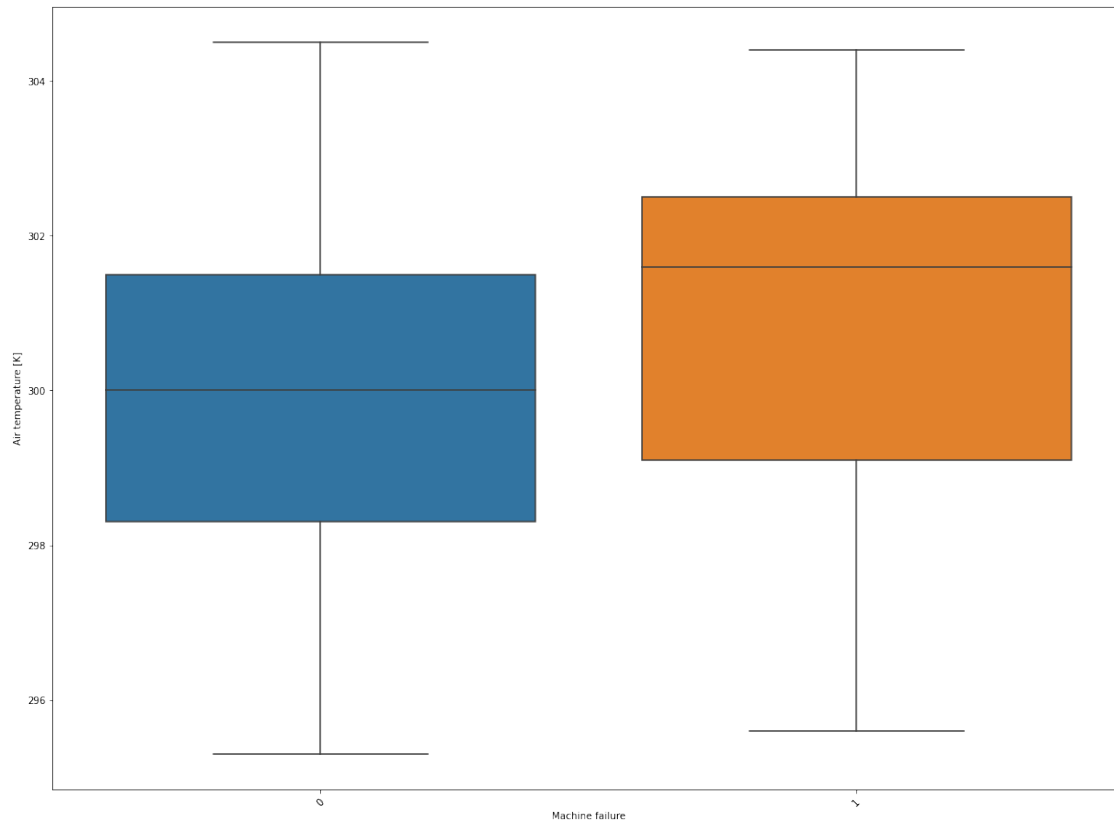
[]: <matplotlib.axes._subplots.AxesSubplot at 0x7f9e2fd5b290>



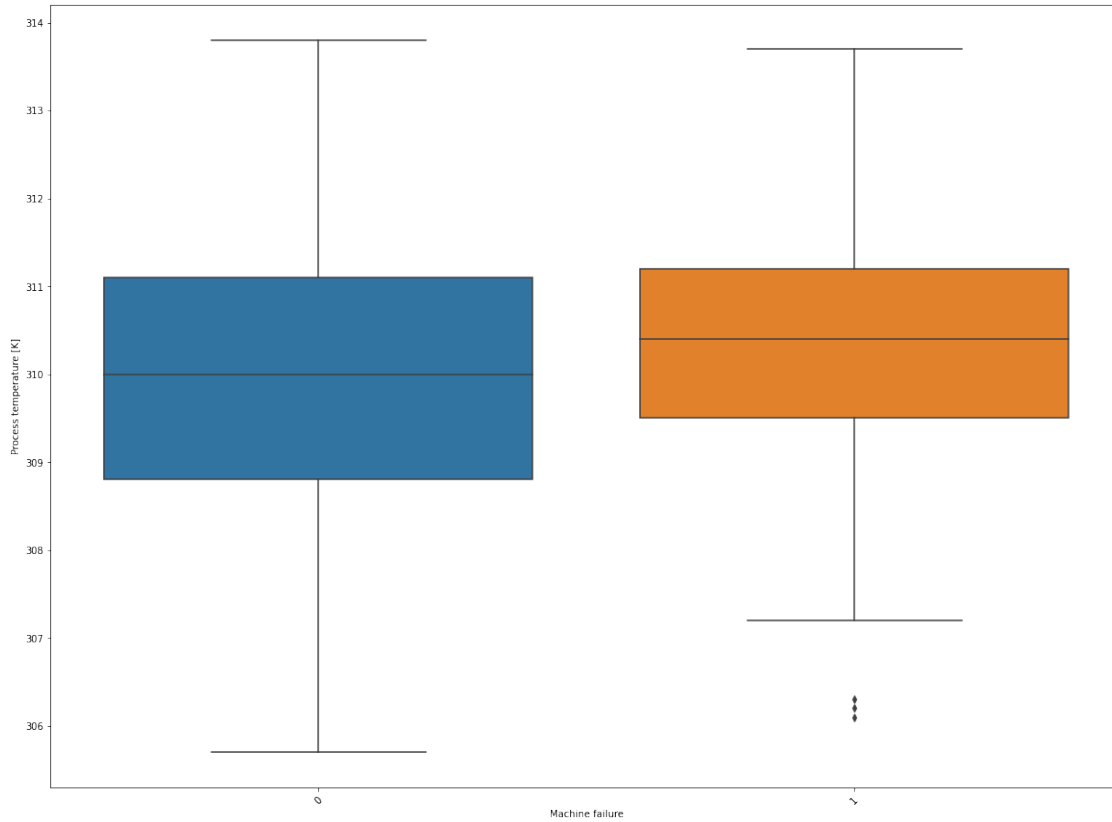
```
[ ]: import matplotlib.pyplot as plt
import seaborn as sns
sns.pairplot(df, kind="scatter")
plt.show()
```



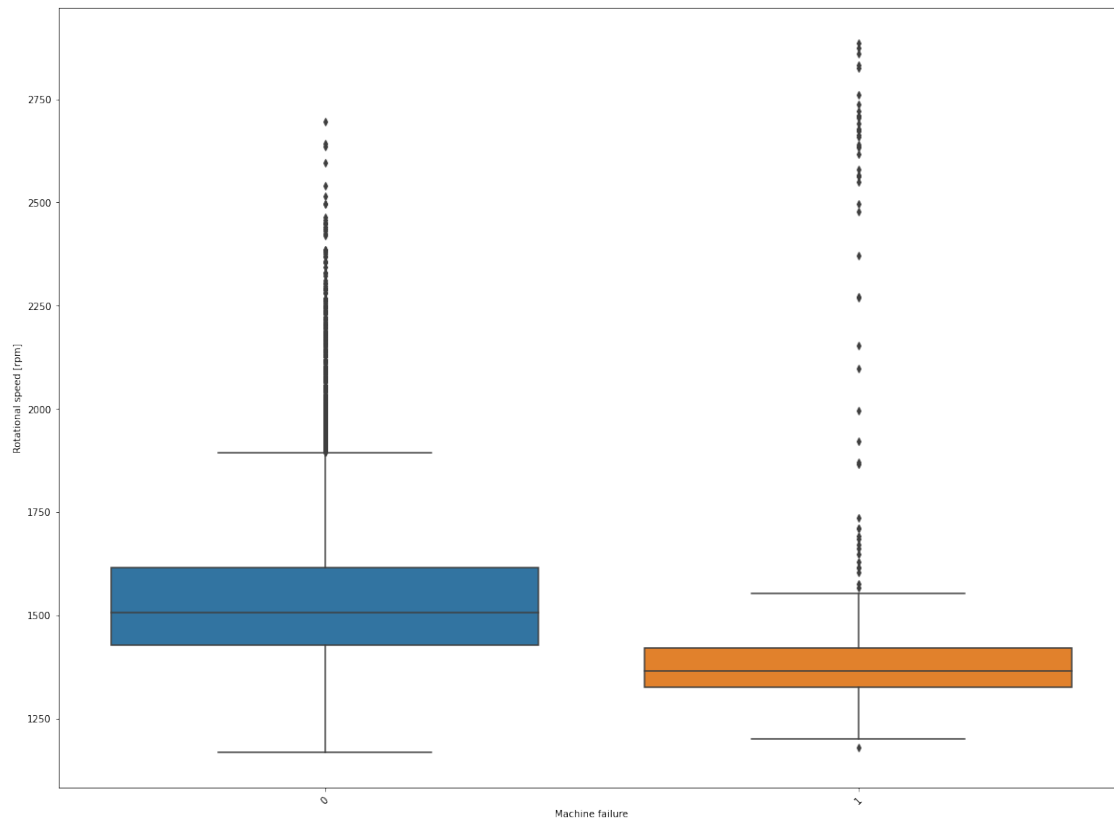
```
[ ]: plt.figure(figsize=(20,15))
plt.xticks(rotation=45)
sns.boxplot(data = df, y = 'Air temperature [K]', x = 'Machine failure');
```



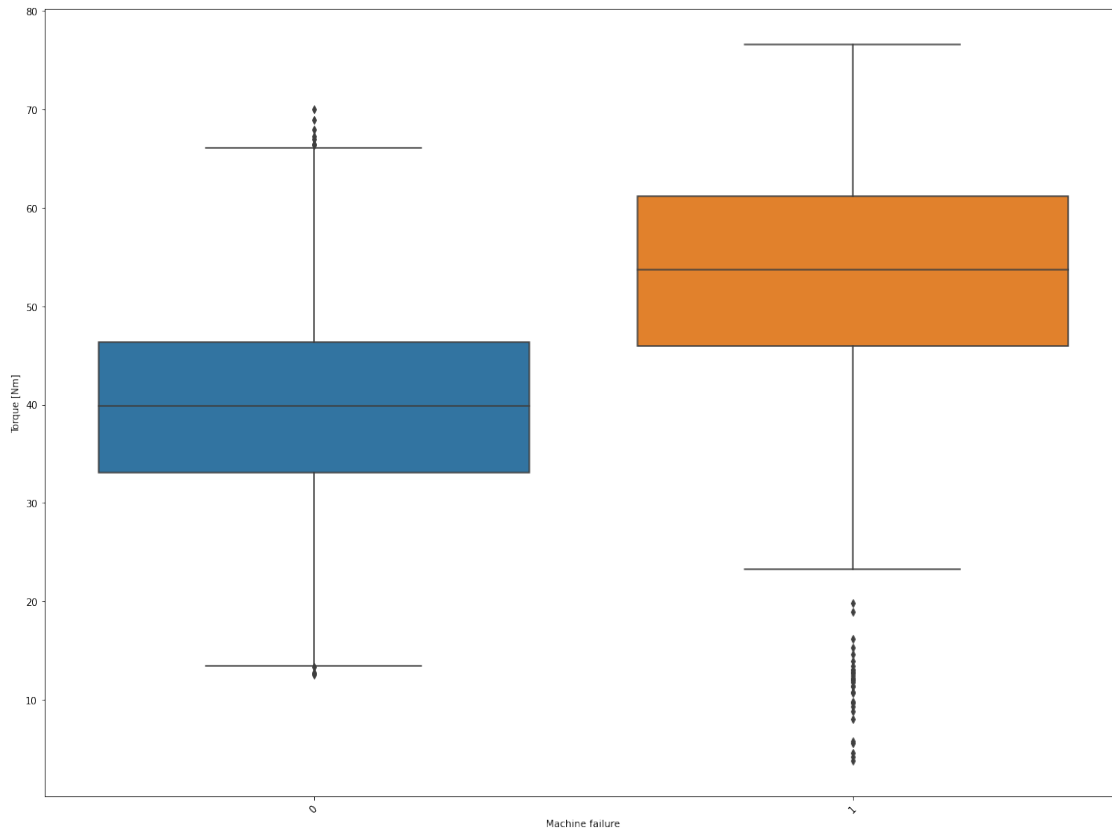
```
[ ]: plt.figure(figsize=(20,15))  
plt.xticks(rotation=45)  
sns.boxplot(data = df, y = 'Process temperature [K]', x = 'Machine failure');
```



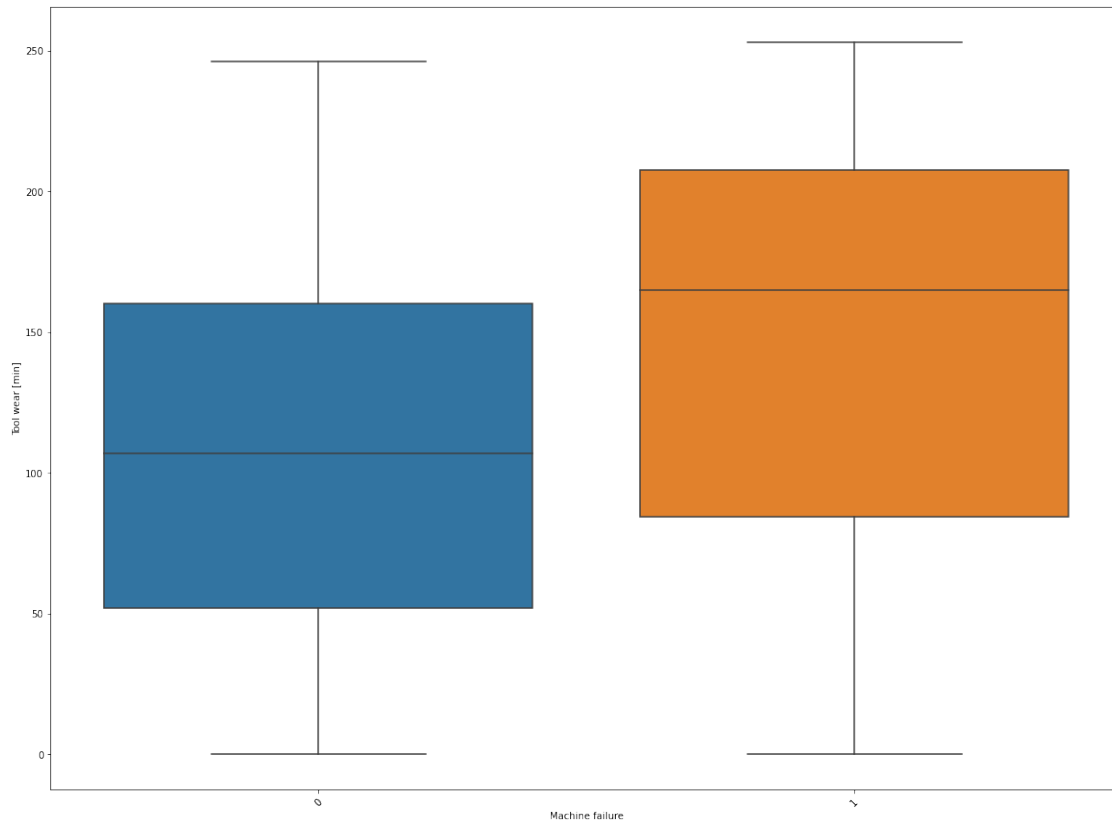
```
[ ]: plt.figure(figsize=(20,15))  
plt.xticks(rotation=45)  
sns.boxplot(data = df, y = 'Rotational speed [rpm]', x = 'Machine failure');
```



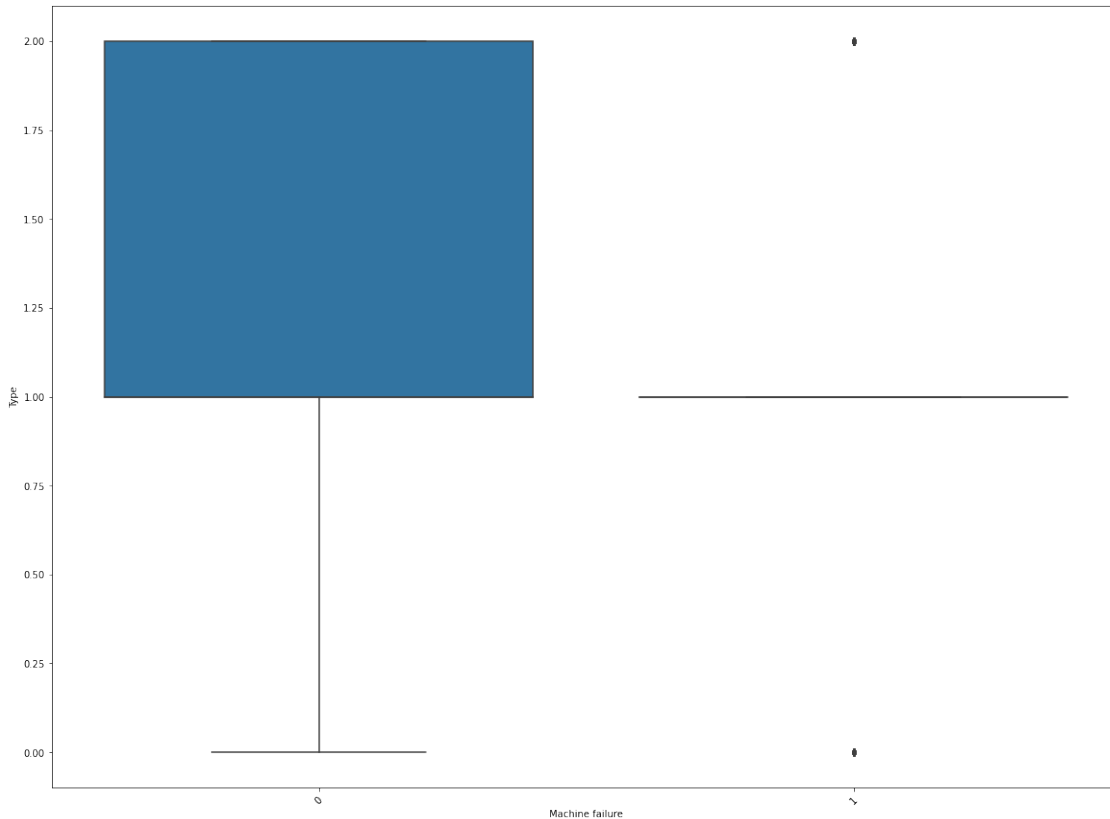
```
[ ]: plt.figure(figsize=(20,15))
plt.xticks(rotation=45)
sns.boxplot(data = df, y = 'Torque [Nm]', x = 'Machine failure');
```



```
[ ]: plt.figure(figsize=(20,15))  
plt.xticks(rotation=45)  
sns.boxplot(data = df, y = 'Tool wear [min]', x = 'Machine failure');
```



```
[ ]: plt.figure(figsize=(20,15))  
plt.xticks(rotation=45)  
sns.boxplot(data = df, y = 'Type', x = 'Machine failure');
```



0.0.2 BNN

```
[ ]: #importing all the required packages for building a bnn  
import numpy as np  
import tensorflow as tf  
from tensorflow import keras  
from tensorflow.keras import layers  
import tensorflow_datasets as tfds  
import tensorflow_probability as tfp
```

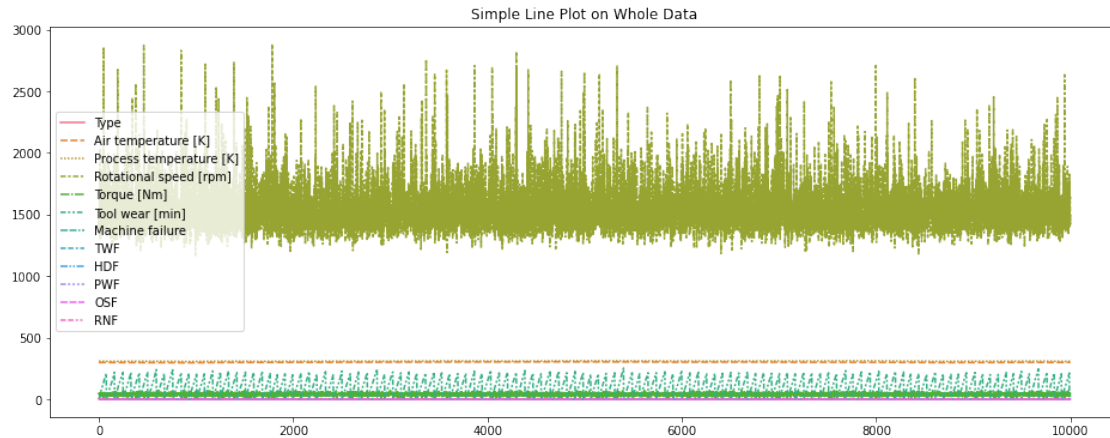
visualizing data

```
[ ]: import matplotlib.pyplot as plt
      %matplotlib inline
      import seaborn as sns

      plt.figure(figsize=(16,6))
      plt.title("Simple Line Plot on Whole Data")
      sns.lineplot(data=df)
```

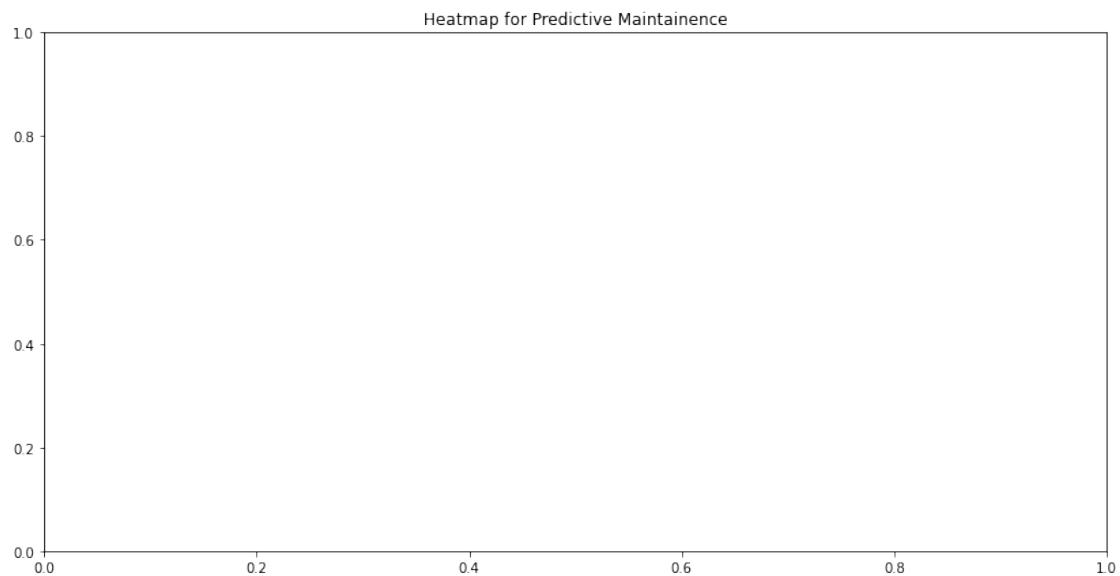


```
[ ]: <matplotlib.axes._subplots.AxesSubplot at 0x7f9e27419b90>
```



```
[ ]: #heatmaps on whole data
plt.figure(figsize=(14,7))
# Add title
plt.title("Heatmap for Predictive Maintenance")
# Heatmap
#sns.heatmap(data=df['Machine failure'], annot=True)
# Add label for horizontal axis
plt.xlabel("Axis")
```

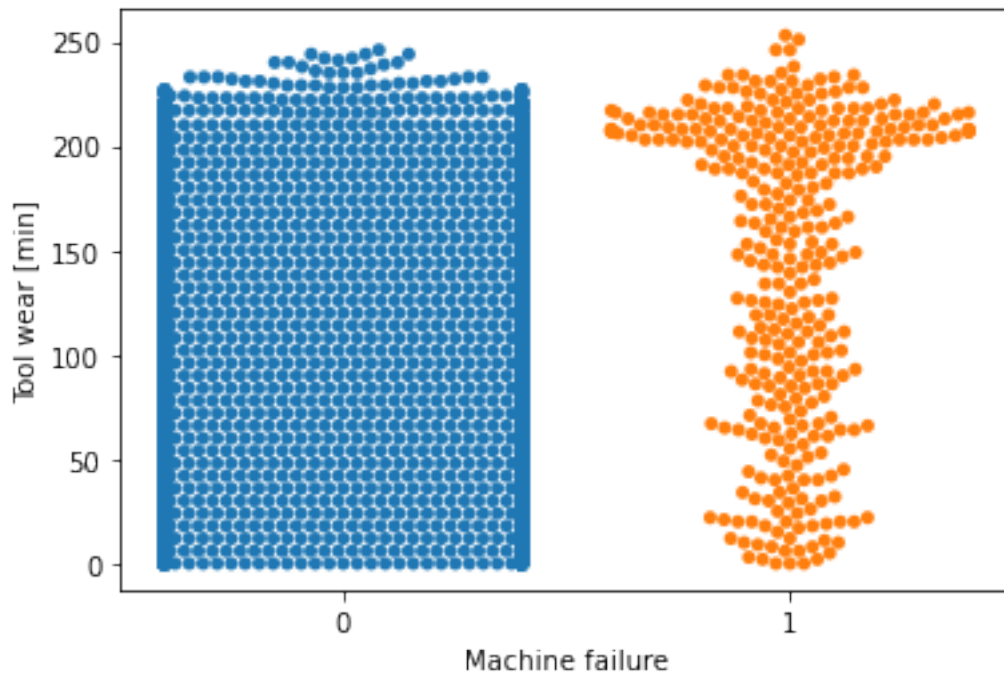
```
[ ]: Text(0.5, 1.0, 'Heatmap for Predictive Maintenance')
```



```
[ ]: sns.swarmplot(x=df['Machine failure'],y=df['Tool wear [min]'])
```

```
/usr/local/lib/python3.7/dist-packages/seaborn/categorical.py:1296: UserWarning:  
89.6% of the points cannot be placed; you may want to decrease the size of the  
markers or use stripplot.  
warnings.warn(msg, UserWarning)
```

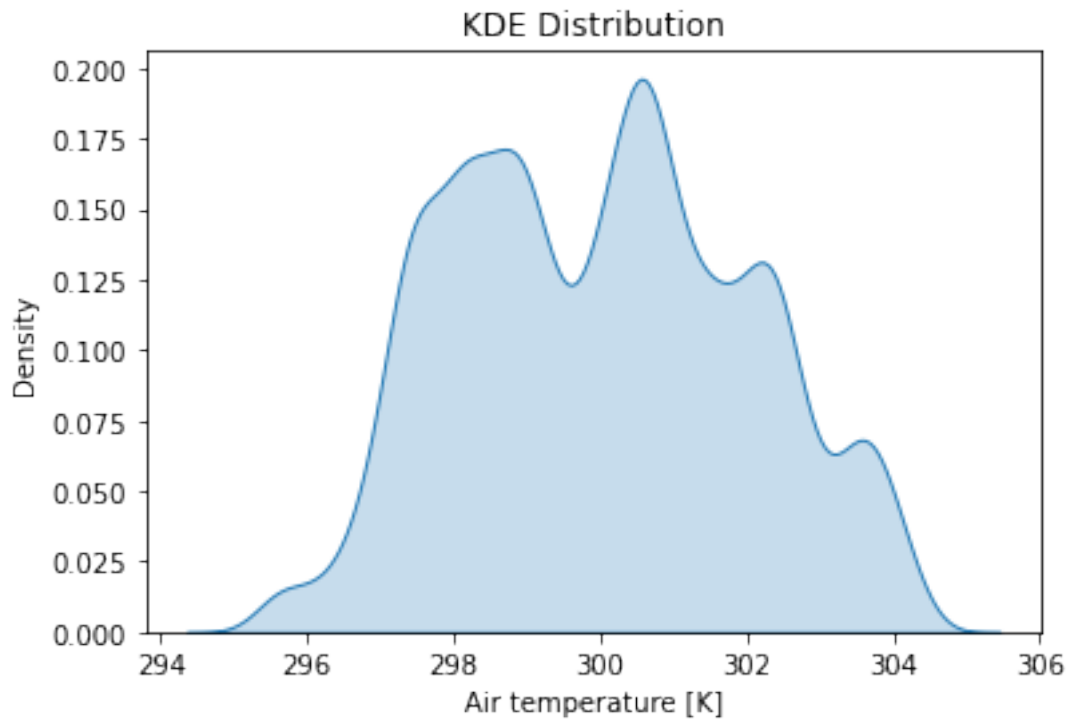
```
[ ]: <matplotlib.axes._subplots.AxesSubplot at 0x7f9dc0b369d0>
```



```
[ ]: #stripplot
```

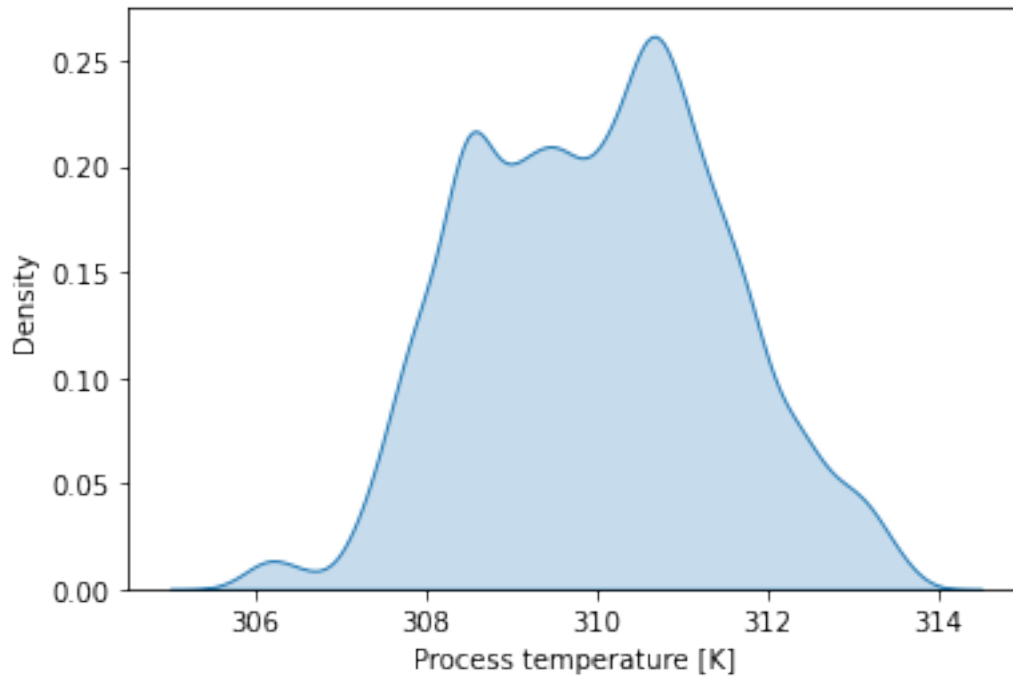
```
[ ]: #distribution  
#for i in df:  
sns.kdeplot(data=df['Air temperature [K]'], label='Air temperature [K]',  
            shade=True)  
  
plt.title('KDE Distribution')
```

```
[ ]: Text(0.5, 1.0, 'KDE Distribution')
```



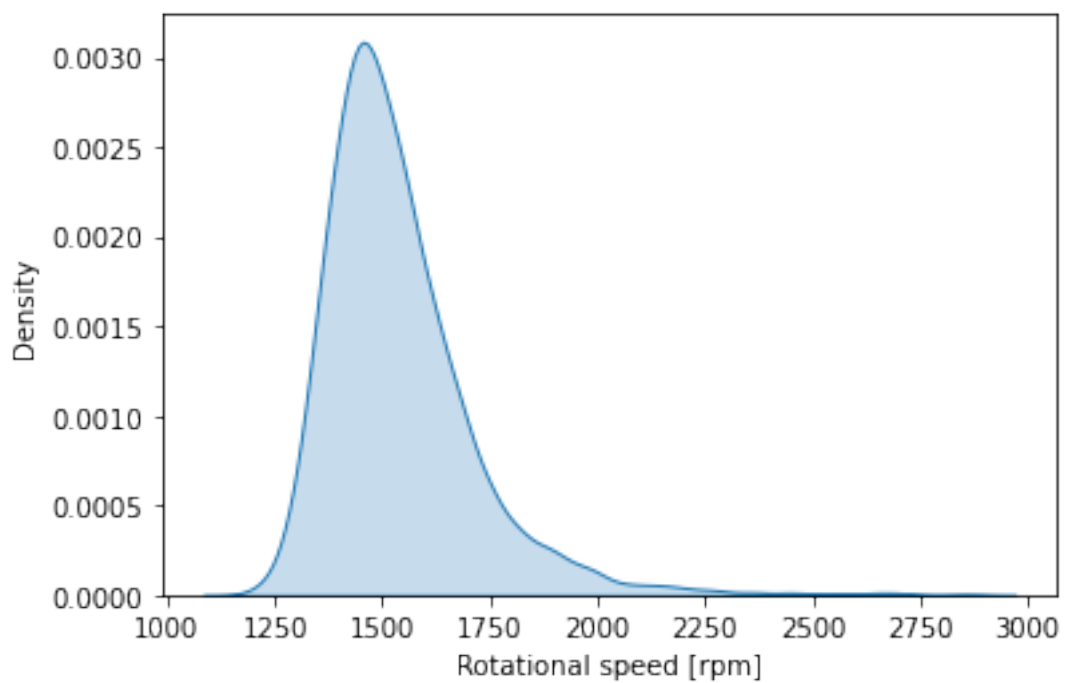
```
[ ]: sns.kdeplot(data=df['Process temperature [K]'], label='Process temperature_␣  
↪ [K]', shade=True)
```

```
[ ]: <matplotlib.axes._subplots.AxesSubplot at 0x7f9dc0a3d4d0>
```



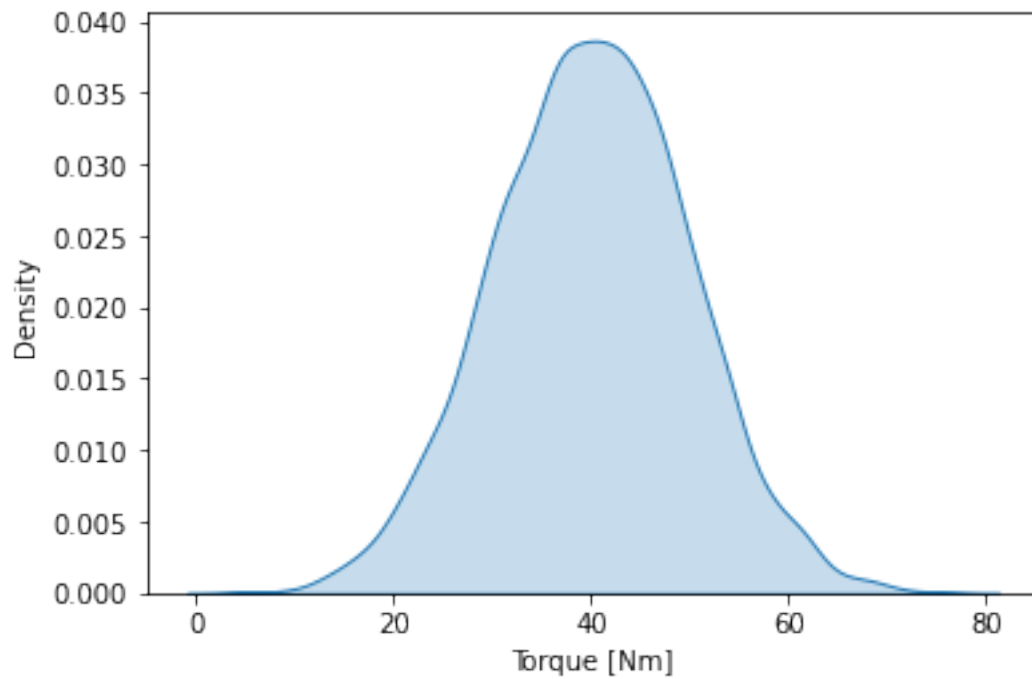
```
[ ]: sns.kdeplot(data=df['Rotational speed [rpm]'], label='Rotational speed [rpm]',  
→shade=True)
```

```
[ ]: <matplotlib.axes._subplots.AxesSubplot at 0x7f9dc0a456d0>
```



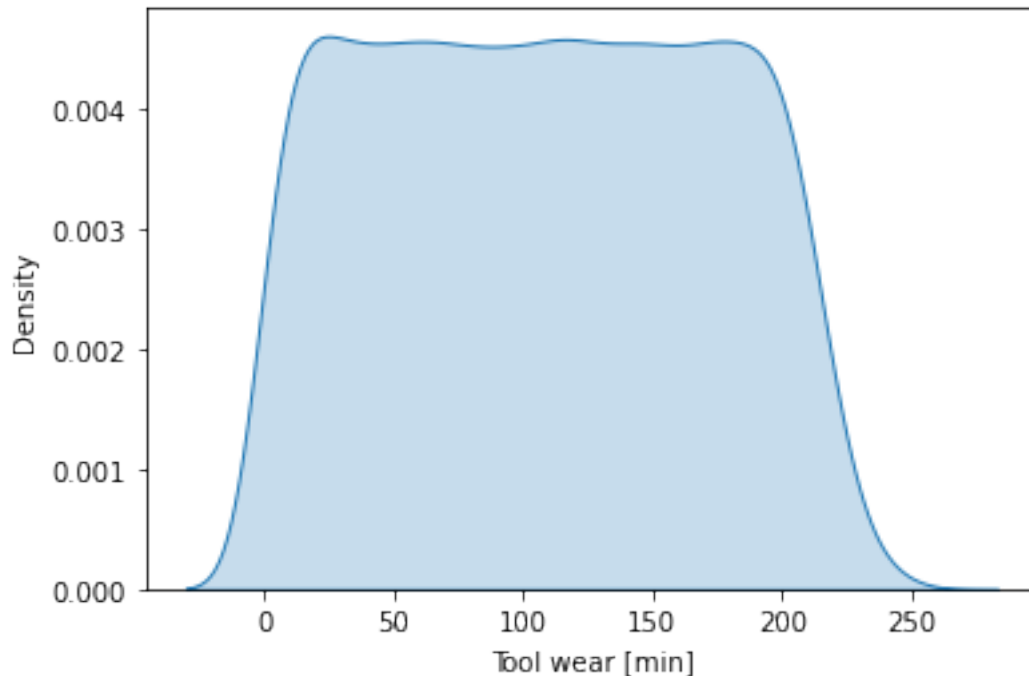
```
[ ]: sns.kdeplot(data=df['Torque [Nm]'], label='Torque [Nm]', shade=True)
```

```
[ ]: <matplotlib.axes._subplots.AxesSubplot at 0x7f9dc0996bd0>
```



```
[ ]: sns.kdeplot(data=df['Tool wear [min]'], label='Tool wear [min]', shade=True)
```

```
[ ]: <matplotlib.axes._subplots.AxesSubplot at 0x7f9dc09db1d0>
```



Create training and evaluation datasets

```
[ ]: # listing all the columns in the dataset
df.columns
```

```
[ ]: Index(['Type', 'Air temperature [K]', 'Process temperature [K]',
          'Rotational speed [rpm]', 'Torque [Nm]', 'Tool wear [min]',
          'Machine failure', 'TWF', 'HDF', 'PWF', 'OSF', 'RNF'],
          dtype='object')
```

```
[ ]: from sklearn.model_selection import train_test_split

#first moving target variable "Machine Failure" to end and then defining X and y
df = df[['Type', 'Air temperature [K]', 'Process temperature [K]',
        'Rotational speed [rpm]', 'Torque [Nm]', 'Tool wear [min]',
        'TWF', 'HDF', 'PWF', 'OSF', 'RNF', 'Machine failure']]
print(df.shape)
# excluding last variable for target variable
X = df.iloc[:, :-1]
print(X.shape)
# making last variable as target variable
y = df.iloc[:, -1]
print(y.shape)
```

```
# using 70:30 split for making training and testing datasets and using random
↳state as 42 to repeat this random split.
X_train,X_test,y_train,y_test = train_test_split(X, y,test_size=0.
↳3,random_state=42)
```

```
(10000, 12)
(10000, 11)
(10000,)
```

```
[ ]: # the shapes of X_train,X_test,y_train,y_test
print(X_train.shape)
print(X_test.shape)
print(y_train.shape)
print(y_test.shape)
```

```
(7000, 11)
(3000, 11)
(7000,)
(3000,)
```

```
[ ]: print(X_train.shape)
print(y_train.shape)
```

```
(7000, 11)
(7000,)
```

```
[ ]: y_train.head()
```

```
[ ]: 9069    0
2603     0
7738     0
1579     0
5058     0
Name: Machine failure, dtype: int64
```

```
[ ]: # correct
#done
#train dataset
train_d = pd.DataFrame(X_train)
train_d['y_train'] = y_train
print(train_d.shape)
print(train_d.shape)

#test dataset
test_d = pd.DataFrame(X_test)
test_d['y_test'] = y_test
print(test_d.shape)
```

```
print(test_d.shape)
```

```
(7000, 12)
```

```
(7000, 12)
```

```
(3000, 12)
```

```
(3000, 12)
```

```
[ ]: train_d.head()
```

```
[ ]:      Type  Air temperature [K]  Process temperature [K]  \
9069    2.0                297.2                308.2
2603    2.0                299.3                309.2
7738    2.0                300.5                312.0
1579    1.0                298.3                308.3
5058    1.0                303.9                312.9
```

```
      Rotational speed [rpm]  Torque [Nm]  Tool wear [min]  TWF  HDF  PWF  \
9069                1678        28.1          133      0    0    0
2603                1334        46.3           31      0    0    0
7738                1263        60.8          146      0    0    0
1579                1444        43.8          176      0    0    0
5058                1526        42.5          194      0    0    0
```

```
      OSF  RNF  y_train
9069     0    0        0
2603     0    0        0
7738     0    0        0
1579     0    0        0
5058     0    0        0
```

```
[ ]: test_d.head()
```

```
[ ]:      Type  Air temperature [K]  Process temperature [K]  \
6252    1.0                300.8                310.3
4684    2.0                303.6                311.8
1731    2.0                298.3                307.9
4742    1.0                303.3                311.3
4521    1.0                302.4                310.4
```

```
      Rotational speed [rpm]  Torque [Nm]  Tool wear [min]  TWF  HDF  PWF  \
6252                1538        36.1          198      0    0    0
4684                1421        44.8          101      0    0    0
1731                1485        42.0          117      0    0    0
4742                1592        33.7           14      0    0    0
4521                1865        23.9          129      0    0    0
```

```
      OSF  RNF  y_test
```


6252	0	0	0
4684	0	0	1
1731	0	0	0
4742	0	0	0
4521	0	0	0

Compile, train, and evaluate the model

```
[ ]: # from here will write in the form of functions
      # but not used
```

Create model inputs

Experiment 1: standard neural network(Non-bayesian neural network)

```
[ ]: from keras.wrappers.scikit_learn import KerasClassifier
      from sklearn.model_selection import cross_val_score
      from keras.models import Sequential # to initialize NN
      from keras.layers import Dense # to build layers
      # building a standard neural network with 3 layers
      classifier = Sequential()
      classifier.add(Dense(units = 5, input_dim = X_train.shape[1])) # changed this
      classifier.add(Dense(units = 3, activation = 'relu'))
      classifier.add(Dense(units = 1, activation = 'sigmoid'))
      classifier.compile(optimizer = 'adam', loss = 'binary_crossentropy', metrics =_
      ↪ ['accuracy'])
      history = classifier.fit(X_train, y_train, epochs=50)
      #validation_data = (np.asarray(X_test), np.asarray(y_test)), verbose=0
      test_loss, test_acc = classifier.evaluate(X_test, y_test, verbose=2)
      print('\nTest accuracy:', test_acc)
      print('\nTest loss:', test_loss)
```

Epoch 1/50

219/219 [=====] - 1s 2ms/step - loss: 11.4100 -
accuracy: 0.8780

Epoch 2/50

219/219 [=====] - 0s 2ms/step - loss: 4.2059 -
accuracy: 0.9361

Epoch 3/50

219/219 [=====] - 0s 2ms/step - loss: 3.3513 -
accuracy: 0.9380

Epoch 4/50

219/219 [=====] - 0s 2ms/step - loss: 2.4733 -
accuracy: 0.9393

Epoch 5/50

219/219 [=====] - 0s 2ms/step - loss: 1.9160 -

```

accuracy: 0.9424
Epoch 6/50
219/219 [=====] - 0s 2ms/step - loss: 1.5904 -
accuracy: 0.9444
Epoch 7/50
219/219 [=====] - 0s 2ms/step - loss: 1.2752 -
accuracy: 0.9453
Epoch 8/50
219/219 [=====] - 0s 2ms/step - loss: 1.0173 -
accuracy: 0.9484
Epoch 9/50
219/219 [=====] - 0s 2ms/step - loss: 0.7898 -
accuracy: 0.9481
Epoch 10/50
219/219 [=====] - 0s 2ms/step - loss: 0.6325 -
accuracy: 0.9481
Epoch 11/50
219/219 [=====] - 0s 2ms/step - loss: 0.5740 -
accuracy: 0.9494
Epoch 12/50
219/219 [=====] - 0s 2ms/step - loss: 0.4138 -
accuracy: 0.9541
Epoch 13/50
219/219 [=====] - 0s 2ms/step - loss: 0.3714 -
accuracy: 0.9553
Epoch 14/50
219/219 [=====] - 0s 2ms/step - loss: 0.3239 -
accuracy: 0.9574
Epoch 15/50
219/219 [=====] - 0s 2ms/step - loss: 0.3030 -
accuracy: 0.9619
Epoch 16/50
219/219 [=====] - 0s 2ms/step - loss: 0.2702 -
accuracy: 0.9606
Epoch 17/50
219/219 [=====] - 0s 2ms/step - loss: 0.2148 -
accuracy: 0.9670
Epoch 18/50
219/219 [=====] - 0s 2ms/step - loss: 0.1837 -
accuracy: 0.9691
Epoch 19/50
219/219 [=====] - 0s 2ms/step - loss: 0.1628 -
accuracy: 0.9710
Epoch 20/50
219/219 [=====] - 0s 2ms/step - loss: 0.2073 -
accuracy: 0.9651
Epoch 21/50
219/219 [=====] - 1s 5ms/step - loss: 0.1595 -

```

```

accuracy: 0.9741
Epoch 22/50
219/219 [=====] - 1s 3ms/step - loss: 0.1300 -
accuracy: 0.9761
Epoch 23/50
219/219 [=====] - 1s 6ms/step - loss: 0.1223 -
accuracy: 0.9754
Epoch 24/50
219/219 [=====] - 0s 2ms/step - loss: 0.1159 -
accuracy: 0.9793
Epoch 25/50
219/219 [=====] - 0s 2ms/step - loss: 0.0953 -
accuracy: 0.9814
Epoch 26/50
219/219 [=====] - 0s 2ms/step - loss: 0.0891 -
accuracy: 0.9810
Epoch 27/50
219/219 [=====] - 0s 2ms/step - loss: 0.0659 -
accuracy: 0.9873
Epoch 28/50
219/219 [=====] - 0s 2ms/step - loss: 0.0569 -
accuracy: 0.9880
Epoch 29/50
219/219 [=====] - 0s 2ms/step - loss: 0.0532 -
accuracy: 0.9887
Epoch 30/50
219/219 [=====] - 0s 2ms/step - loss: 0.0743 -
accuracy: 0.9844
Epoch 31/50
219/219 [=====] - 0s 2ms/step - loss: 0.0382 -
accuracy: 0.9914
Epoch 32/50
219/219 [=====] - 0s 2ms/step - loss: 0.0683 -
accuracy: 0.9894
Epoch 33/50
219/219 [=====] - 0s 2ms/step - loss: 0.0311 -
accuracy: 0.9923
Epoch 34/50
219/219 [=====] - 0s 2ms/step - loss: 0.0537 -
accuracy: 0.9879
Epoch 35/50
219/219 [=====] - 0s 2ms/step - loss: 0.0259 -
accuracy: 0.9944
Epoch 36/50
219/219 [=====] - 0s 2ms/step - loss: 0.0188 -
accuracy: 0.9964
Epoch 37/50
219/219 [=====] - 0s 2ms/step - loss: 0.0165 -

```

```

accuracy: 0.9959
Epoch 38/50
219/219 [=====] - 0s 2ms/step - loss: 0.0229 -
accuracy: 0.9959
Epoch 39/50
219/219 [=====] - 0s 2ms/step - loss: 0.0500 -
accuracy: 0.9910
Epoch 40/50
219/219 [=====] - 0s 2ms/step - loss: 0.0124 -
accuracy: 0.9969
Epoch 41/50
219/219 [=====] - 0s 2ms/step - loss: 0.0127 -
accuracy: 0.9969
Epoch 42/50
219/219 [=====] - 0s 2ms/step - loss: 0.0454 -
accuracy: 0.9911
Epoch 43/50
219/219 [=====] - 0s 2ms/step - loss: 0.0083 -
accuracy: 0.9979
Epoch 44/50
219/219 [=====] - 0s 2ms/step - loss: 0.0157 -
accuracy: 0.9969
Epoch 45/50
219/219 [=====] - 0s 2ms/step - loss: 0.0101 -
accuracy: 0.9977
Epoch 46/50
219/219 [=====] - 0s 2ms/step - loss: 0.0056 -
accuracy: 0.9990
Epoch 47/50
219/219 [=====] - 0s 2ms/step - loss: 0.0073 -
accuracy: 0.9983
Epoch 48/50
219/219 [=====] - 0s 2ms/step - loss: 0.0116 -
accuracy: 0.9969
Epoch 49/50
219/219 [=====] - 0s 2ms/step - loss: 0.0209 -
accuracy: 0.9964
Epoch 50/50
219/219 [=====] - 0s 2ms/step - loss: 0.0127 -
accuracy: 0.9971
94/94 - 0s - loss: 7.1267e-04 - accuracy: 0.9997 - 271ms/epoch - 3ms/step

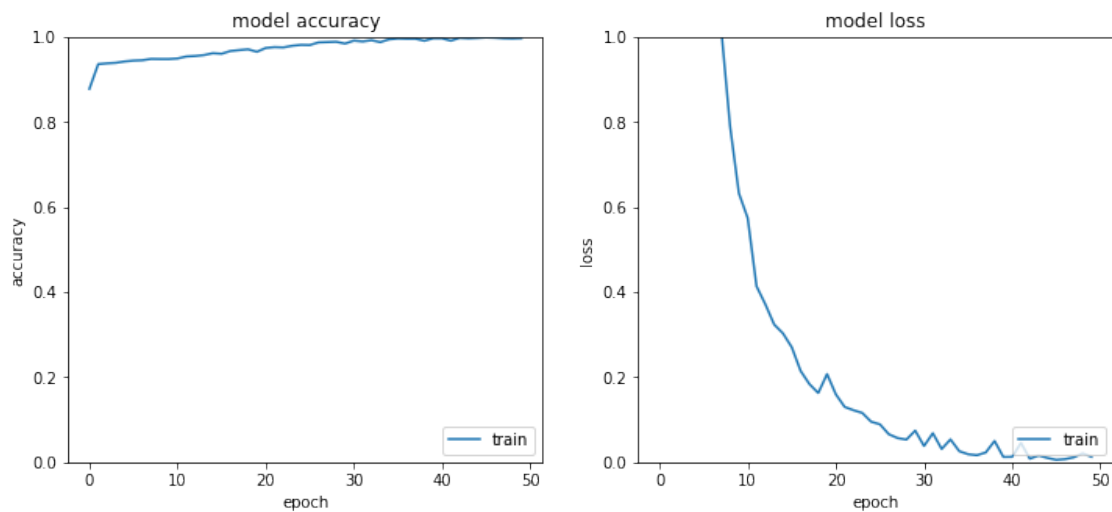
```

Test accuracy: 0.999666690826416

Test loss: 0.0007126674754545093

train accuracy: 0.9649, loss: 0.1522 after 50 epochs test accuracy: 0.9690, loss: 0.1385

```
[ ]: # plotting the performance of the model with the below parameters.
plt.figure(figsize=(12,5))
plt.subplot(1,2,1)
plt.plot(history.history['accuracy'])
#plt.plot(history.history['val_accuracy'])
plt.title('model accuracy')
plt.ylabel('accuracy')
plt.xlabel('epoch')
plt.legend(['train', 'test'], loc='lower right')
plt.ylim(0, 1)
# summarize history for loss
plt.subplot(1,2,2)
plt.plot(history.history['loss'])
#plt.plot(history.history['val_loss'])
plt.title('model loss')
plt.ylabel('loss')
plt.xlabel('epoch')
plt.legend(['train', 'test'], loc='lower right')
plt.ylim(0, 1)
plt.show()
```



```
[ ]: classifier.summary()
```

Model: "sequential"

Layer (type)	Output Shape	Param #
dense (Dense)	(None, 5)	65
dense_1 (Dense)	(None, 3)	18

dense_2 (Dense) (None, 1) 4

```
=====
Total params: 87
Trainable params: 87
Non-trainable params: 0
-----
```

```
[ ]: # checking the probabilities : not used but tried initially
probability_model = Sequential([classifier, tf.keras.layers.Softmax()])
predictions = probability_model.predict(X_test)
predictions[0]
```

```
[ ]: array([1.], dtype=float32)
```

```
[ ]: np.argmax(predictions[0])
```

```
[ ]: 0
```

```
[ ]: y_test[0]
```

```
[ ]: 0
```

```
[ ]: predictions
```

```
[ ]: array([[1.],
          [1.],
          [1.],
          ...,
          [1.],
          [1.],
          [1.]], dtype=float32)
```

```
[ ]: y_test.nunique
```

```
[ ]: <bound method IndexOpsMixin.nunique of 6252    0
4684    1
1731    0
4742    0
4521    0
..
8014    0
1074    0
3063    0
6487    0
4705    0
```

Name: Machine failure, Length: 3000, dtype: int64>

Experiment 2: Bayesian neural network (BNN)

dependencies and prerequisites

```
[ ]: from pprint import pprint
import matplotlib.pyplot as plt
import numpy as np
import seaborn as sns

import tensorflow.compat.v2 as tf
tf.enable_v2_behavior()

import tensorflow_probability as tfp

sns.reset_defaults()
sns.set_context(context='talk', font_scale=0.7)
plt.rcParams['image.cmap'] = 'viridis'

%matplotlib inline

tfd = tfp.distributions
tfb = tfp.bijectors
```

define priors and other functions

```
[ ]: # to build the bnn
```

define bnn functions and class

```
[ ]: from keras.wrappers.scikit_learn import KerasClassifier
from sklearn.model_selection import cross_val_score
from keras.models import Sequential # to initialize NN
from keras.layers import Dense # to build layers
'''
classifier = Sequential()
classifier.add(Dense(units = 8, input_dim = X_train.shape[1])) # changed this
classifier.add(Dense(units = 4, activation = 'relu'))
classifier.add(Dense(units = 1, activation = 'sigmoid'))
classifier.compile(optimizer = 'adam', loss = 'binary_crossentropy', metrics = _
↳ ['accuracy'])
classifier.fit(X_train, y_train, epochs=100)
test_loss, test_acc = classifier.evaluate(X_test, y_test, verbose=2)
print('\nTest accuracy:', test_acc)
```

```
'''
```

```
[ ]: "\nclf = Sequential()\nclf.add(Dense(units = 8, input_dim =
X_train.shape[1])) # changed this\nclf.add(Dense(units = 4, activation =
'relu'))\nclf.add(Dense(units = 1, activation =
'sigmoid'))\nclf.compile(optimizer = 'adam', loss =
'binary_crossentropy', metrics = ['accuracy'])\nclf.fit(X_train, y_train,
epochs=100)\ntest_loss, test_acc = clf.evaluate(X_test, y_test,
verbose=2)\nprint('\nTest accuracy:', test_acc)\n\n"
```

target is machine failure variable

```
[ ]: from sklearn.model_selection import train_test_split
# resetting the data to initial dataset
#first moving target variable "Machine Failure" to end and then defining X and y
df = df[['Type', 'Air temperature [K]', 'Process temperature [K]',
        'Rotational speed [rpm]', 'Torque [Nm]', 'Tool wear [min]',
        'TWF', 'HDF', 'PWF', 'OSF', 'RNF', 'Machine failure']]
print(df.shape)
# excluding last variable for target variable
X = df.iloc[:, :-1]
print(X.shape)
# making last variable as target variable
y = df.iloc[:, -1]
print(y.shape)
# using 70:30 split for making training and testing datasets and using random
→state as 42 to repeat this random split.
X_train,X_test,y_train,y_test = train_test_split(X, y,test_size=0.
→3,random_state=42)
```

```
(10000, 12)
```

```
(10000, 11)
```

```
(10000,)
```

```
[ ]: dist = tfp.distributions
dataset_size = len(X_train)
kl_divergence_function = (lambda q, p, _: dist.kl_divergence(q, p) / tf.
→cast(dataset_size, dtype=tf.float32))
# a bnn model with 3 layers which are denseflipout layers
model_tfp = tf.keras.Sequential([
    tf.keras.Input(X_train.shape[1]),
    tfp.layers.DenseFlipout(16, kernel_divergence_fn=kl_divergence_function),#,
→activation=tf.nn.relu),
    tfp.layers.DenseFlipout(6, kernel_divergence_fn=kl_divergence_function,
→activation=tf.nn.relu ),
    tfp.layers.DenseFlipout(2, kernel_divergence_fn=kl_divergence_function,
→activation=tf.nn.softmax),
```



```

])

learning_rate = 0.001 #1e-06 #
model_tfp.compile(optimizer=tf.keras.optimizers.
↳Adam(learning_rate),loss='binary_crossentropy',metrics=['accuracy'])

```

```

/usr/local/lib/python3.7/dist-
packages/tensorflow_probability/python/layers/util.py:102: UserWarning:
`layer.add_variable` is deprecated and will be removed in a future version.
Please use `layer.add_weight` method instead.
    trainable=trainable)
/usr/local/lib/python3.7/dist-
packages/tensorflow_probability/python/layers/util.py:112: UserWarning:
`layer.add_variable` is deprecated and will be removed in a future version.
Please use `layer.add_weight` method instead.
    trainable=trainable)

```

```

[ ]: model_tfp.fit(X_train, y_train, epochs=50)
test_loss, test_acc = model_tfp.evaluate(X_test, y_test)
print('\nTest accuracy:', test_acc)
print('\nTest loss:', test_loss)

```

```

Epoch 1/50
219/219 [=====] - 3s 3ms/step - loss: 1.0757 -
accuracy: 0.8729
Epoch 2/50
219/219 [=====] - 1s 3ms/step - loss: 0.7937 -
accuracy: 0.9574
Epoch 3/50
219/219 [=====] - 1s 3ms/step - loss: 0.7908 -
accuracy: 0.9594
Epoch 4/50
219/219 [=====] - 1s 3ms/step - loss: 0.7865 -
accuracy: 0.9621
Epoch 5/50
219/219 [=====] - 1s 3ms/step - loss: 0.7826 -
accuracy: 0.6240
Epoch 6/50
219/219 [=====] - 1s 2ms/step - loss: 0.7791 -
accuracy: 0.3433
Epoch 7/50
219/219 [=====] - 1s 3ms/step - loss: 0.7766 -
accuracy: 0.4560
Epoch 8/50
219/219 [=====] - 1s 3ms/step - loss: 0.7728 -
accuracy: 0.3937
Epoch 9/50
219/219 [=====] - 1s 3ms/step - loss: 0.7701 -

```

```

accuracy: 0.6831
Epoch 10/50
219/219 [=====] - 1s 3ms/step - loss: 0.7670 -
accuracy: 0.5551
Epoch 11/50
219/219 [=====] - 1s 3ms/step - loss: 0.7642 -
accuracy: 0.7180
Epoch 12/50
219/219 [=====] - 1s 3ms/step - loss: 0.7614 -
accuracy: 0.6241
Epoch 13/50
219/219 [=====] - 1s 3ms/step - loss: 0.7588 -
accuracy: 0.4771
Epoch 14/50
219/219 [=====] - 1s 3ms/step - loss: 0.7564 -
accuracy: 0.6461
Epoch 15/50
219/219 [=====] - 1s 3ms/step - loss: 0.7542 -
accuracy: 0.6146
Epoch 16/50
219/219 [=====] - 1s 3ms/step - loss: 0.7522 -
accuracy: 0.4636
Epoch 17/50
219/219 [=====] - 1s 3ms/step - loss: 0.7508 -
accuracy: 0.7271
Epoch 18/50
219/219 [=====] - 1s 4ms/step - loss: 0.7488 -
accuracy: 0.6497
Epoch 19/50
219/219 [=====] - 1s 3ms/step - loss: 0.7479 -
accuracy: 0.5296
Epoch 20/50
219/219 [=====] - 1s 3ms/step - loss: 0.7462 -
accuracy: 0.4343
Epoch 21/50
219/219 [=====] - 1s 3ms/step - loss: 0.7450 -
accuracy: 0.5571
Epoch 22/50
219/219 [=====] - 1s 3ms/step - loss: 0.7438 -
accuracy: 0.5479
Epoch 23/50
219/219 [=====] - 1s 3ms/step - loss: 0.7431 -
accuracy: 0.4851
Epoch 24/50
219/219 [=====] - 1s 3ms/step - loss: 0.7417 -
accuracy: 0.5131
Epoch 25/50
219/219 [=====] - 1s 3ms/step - loss: 0.7406 -

```

```

accuracy: 0.6360
Epoch 26/50
219/219 [=====] - 1s 3ms/step - loss: 0.7400 -
accuracy: 0.4933
Epoch 27/50
219/219 [=====] - 1s 3ms/step - loss: 0.7388 -
accuracy: 0.5763
Epoch 28/50
219/219 [=====] - 1s 3ms/step - loss: 0.7378 -
accuracy: 0.7509
Epoch 29/50
219/219 [=====] - 1s 3ms/step - loss: 0.7369 -
accuracy: 0.5059
Epoch 30/50
219/219 [=====] - 1s 3ms/step - loss: 0.7359 -
accuracy: 0.4609
Epoch 31/50
219/219 [=====] - 1s 4ms/step - loss: 0.7357 -
accuracy: 0.5491
Epoch 32/50
219/219 [=====] - 1s 3ms/step - loss: 0.7347 -
accuracy: 0.4850
Epoch 33/50
219/219 [=====] - 1s 3ms/step - loss: 0.7338 -
accuracy: 0.5180
Epoch 34/50
219/219 [=====] - 1s 3ms/step - loss: 0.7330 -
accuracy: 0.7883
Epoch 35/50
219/219 [=====] - 1s 3ms/step - loss: 0.7331 -
accuracy: 0.9646
Epoch 36/50
219/219 [=====] - 1s 3ms/step - loss: 0.7318 -
accuracy: 0.4869
Epoch 37/50
219/219 [=====] - 1s 3ms/step - loss: 0.7319 -
accuracy: 0.2961
Epoch 38/50
219/219 [=====] - 1s 3ms/step - loss: 0.7311 -
accuracy: 0.4657
Epoch 39/50
219/219 [=====] - 1s 3ms/step - loss: 0.7300 -
accuracy: 0.7320
Epoch 40/50
219/219 [=====] - 1s 3ms/step - loss: 0.7294 -
accuracy: 0.6094
Epoch 41/50
219/219 [=====] - 1s 3ms/step - loss: 0.7288 -

```

```

accuracy: 0.3671
Epoch 42/50
219/219 [=====] - 1s 3ms/step - loss: 0.7281 -
accuracy: 0.0351
Epoch 43/50
219/219 [=====] - 1s 3ms/step - loss: 0.7289 -
accuracy: 0.2726
Epoch 44/50
219/219 [=====] - 1s 3ms/step - loss: 0.7288 -
accuracy: 0.5110
Epoch 45/50
219/219 [=====] - 1s 3ms/step - loss: 0.7276 -
accuracy: 0.7980
Epoch 46/50
219/219 [=====] - 1s 3ms/step - loss: 0.7263 -
accuracy: 0.6626
Epoch 47/50
219/219 [=====] - 1s 3ms/step - loss: 0.7257 -
accuracy: 0.7466
Epoch 48/50
219/219 [=====] - 1s 3ms/step - loss: 0.7252 -
accuracy: 0.7820
Epoch 49/50
219/219 [=====] - 1s 3ms/step - loss: 0.7283 -
accuracy: 0.5833
Epoch 50/50
219/219 [=====] - 1s 3ms/step - loss: 0.7265 -
accuracy: 0.5116
94/94 [=====] - 1s 2ms/step - loss: 0.7267 - accuracy:
0.9687

```

Test accuracy: 0.968666672706604

Test loss: 0.7267147898674011

Test accuracy: 0.968666672706604 after 50 epochs and test loss: 0.450

```

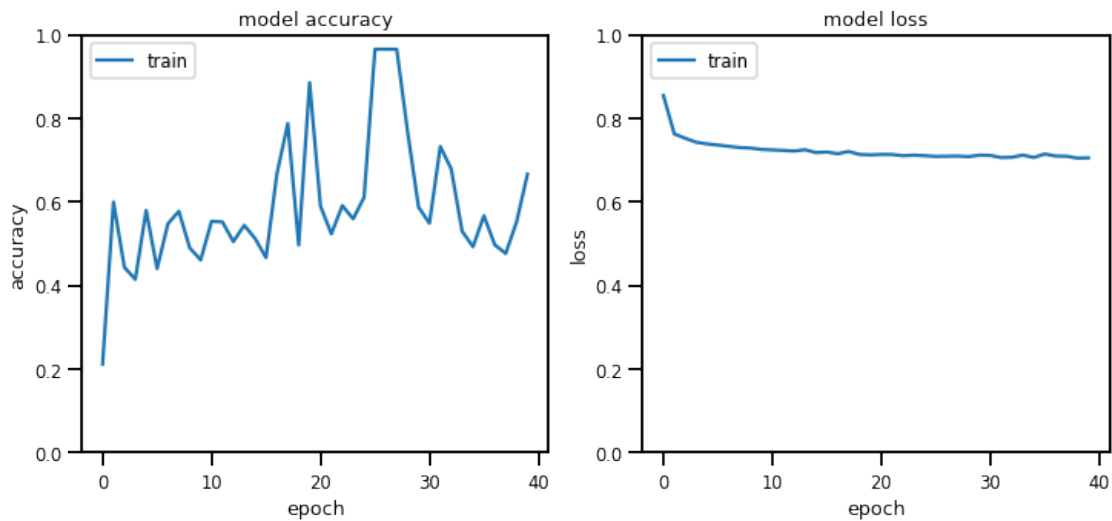
[ ]: # doing all the same steps of building model, fitting it to the data and
      ↳evaluating it and plotting parameters for all the models built in the
      ↳notebook.
plt.figure(figsize=(12,5))
plt.subplot(1,2,1)
plt.plot(history.history['accuracy'])
#plt.plot(history.history['val_accuracy'])
plt.title('model accuracy')
plt.ylabel('accuracy')
plt.xlabel('epoch')
plt.legend(['train', 'test'], loc='upper left')

```

```

plt.ylim(0, 1)
# summarize history for loss
plt.subplot(1,2,2)
plt.plot(history.history['loss'])
#plt.plot(history.history['val_loss'])
plt.title('model loss')
plt.ylabel('loss')
plt.xlabel('epoch')
plt.legend(['train', 'test'], loc='upper left')
plt.ylim(0, 1)
plt.show()

```



```

[ ]: history = model_tfp.fit(np.asarray(X_train), np.asarray(y_train), epochs=50) #,
    ↪ validation_split=0.3, shuffle=True)

```

```

Epoch 1/50
219/219 [=====] - 2s 4ms/step - loss: 2.4019 -
accuracy: 0.4121
Epoch 2/50
219/219 [=====] - 1s 4ms/step - loss: 2.3805 -
accuracy: 0.4133
Epoch 3/50
219/219 [=====] - 1s 4ms/step - loss: 2.3272 -
accuracy: 0.4190
Epoch 4/50
219/219 [=====] - 1s 4ms/step - loss: 2.2809 -
accuracy: 0.4153
Epoch 5/50
219/219 [=====] - 1s 4ms/step - loss: 2.3229 -
accuracy: 0.4161

```

Epoch 6/50
219/219 [=====] - 1s 4ms/step - loss: 2.2498 -
accuracy: 0.4149

Epoch 7/50
219/219 [=====] - 1s 4ms/step - loss: 2.3149 -
accuracy: 0.4020

Epoch 8/50
219/219 [=====] - 1s 4ms/step - loss: 2.2349 -
accuracy: 0.4023

Epoch 9/50
219/219 [=====] - 1s 4ms/step - loss: 2.2456 -
accuracy: 0.4134

Epoch 10/50
219/219 [=====] - 1s 3ms/step - loss: 2.2393 -
accuracy: 0.4119

Epoch 11/50
219/219 [=====] - 1s 4ms/step - loss: 2.2473 -
accuracy: 0.4147

Epoch 12/50
219/219 [=====] - 1s 4ms/step - loss: 2.1595 -
accuracy: 0.4086

Epoch 13/50
219/219 [=====] - 1s 4ms/step - loss: 2.2436 -
accuracy: 0.4179

Epoch 14/50
219/219 [=====] - 1s 3ms/step - loss: 2.1476 -
accuracy: 0.4146

Epoch 15/50
219/219 [=====] - 1s 3ms/step - loss: 2.1008 -
accuracy: 0.4121

Epoch 16/50
219/219 [=====] - 1s 3ms/step - loss: 2.0665 -
accuracy: 0.4091

Epoch 17/50
219/219 [=====] - 1s 3ms/step - loss: 2.1306 -
accuracy: 0.4167

Epoch 18/50
219/219 [=====] - 1s 3ms/step - loss: 2.0765 -
accuracy: 0.4129

Epoch 19/50
219/219 [=====] - 1s 3ms/step - loss: 2.0142 -
accuracy: 0.4100

Epoch 20/50
219/219 [=====] - 1s 3ms/step - loss: 2.0783 -
accuracy: 0.4184

Epoch 21/50
219/219 [=====] - 1s 4ms/step - loss: 1.9924 -
accuracy: 0.4064

Epoch 22/50
219/219 [=====] - 1s 3ms/step - loss: 1.9901 -
accuracy: 0.3927
Epoch 23/50
219/219 [=====] - 1s 3ms/step - loss: 1.9788 -
accuracy: 0.4024
Epoch 24/50
219/219 [=====] - 1s 3ms/step - loss: 1.9679 -
accuracy: 0.3907
Epoch 25/50
219/219 [=====] - 1s 3ms/step - loss: 1.9494 -
accuracy: 0.4001
Epoch 26/50
219/219 [=====] - 1s 3ms/step - loss: 1.9504 -
accuracy: 0.4001
Epoch 27/50
219/219 [=====] - 1s 3ms/step - loss: 1.9217 -
accuracy: 0.3857
Epoch 28/50
219/219 [=====] - 1s 4ms/step - loss: 1.8832 -
accuracy: 0.3871
Epoch 29/50
219/219 [=====] - 1s 4ms/step - loss: 1.8649 -
accuracy: 0.4027
Epoch 30/50
219/219 [=====] - 1s 3ms/step - loss: 1.8490 -
accuracy: 0.4084
Epoch 31/50
219/219 [=====] - 1s 3ms/step - loss: 1.8713 -
accuracy: 0.3946
Epoch 32/50
219/219 [=====] - 1s 3ms/step - loss: 1.7888 -
accuracy: 0.3956
Epoch 33/50
219/219 [=====] - 1s 3ms/step - loss: 1.8289 -
accuracy: 0.3956
Epoch 34/50
219/219 [=====] - 1s 3ms/step - loss: 1.8077 -
accuracy: 0.3866
Epoch 35/50
219/219 [=====] - 1s 3ms/step - loss: 1.7749 -
accuracy: 0.3863
Epoch 36/50
219/219 [=====] - 1s 4ms/step - loss: 1.7281 -
accuracy: 0.3827
Epoch 37/50
219/219 [=====] - 1s 4ms/step - loss: 1.7523 -
accuracy: 0.3787

```

Epoch 38/50
219/219 [=====] - 1s 4ms/step - loss: 1.7316 -
accuracy: 0.3806
Epoch 39/50
219/219 [=====] - 1s 4ms/step - loss: 1.7281 -
accuracy: 0.3827
Epoch 40/50
219/219 [=====] - 1s 4ms/step - loss: 1.7213 -
accuracy: 0.3723
Epoch 41/50
219/219 [=====] - 1s 4ms/step - loss: 1.7255 -
accuracy: 0.3633
Epoch 42/50
219/219 [=====] - 1s 4ms/step - loss: 1.7048 -
accuracy: 0.3676
Epoch 43/50
219/219 [=====] - 1s 4ms/step - loss: 1.6736 -
accuracy: 0.3780
Epoch 44/50
219/219 [=====] - 1s 4ms/step - loss: 1.6481 -
accuracy: 0.3739
Epoch 45/50
219/219 [=====] - 1s 4ms/step - loss: 1.7093 -
accuracy: 0.3699
Epoch 46/50
219/219 [=====] - 1s 4ms/step - loss: 1.6310 -
accuracy: 0.3713
Epoch 47/50
219/219 [=====] - 1s 4ms/step - loss: 1.5744 -
accuracy: 0.3533
Epoch 48/50
219/219 [=====] - 1s 4ms/step - loss: 1.6090 -
accuracy: 0.3610
Epoch 49/50
219/219 [=====] - 1s 3ms/step - loss: 1.5879 -
accuracy: 0.3554
Epoch 50/50
219/219 [=====] - 1s 4ms/step - loss: 1.5770 -
accuracy: 0.3616

```

```

[ ]: # doing all the same steps of building model, fitting it to the data and
      ↳evaluating it and plotting parameters for all the models built in the
      ↳notebook.
plt.figure(figsize=(12,5))
plt.subplot(1,2,1)
plt.plot(history.history['accuracy'])
#plt.plot(history.history['val_accuracy'])

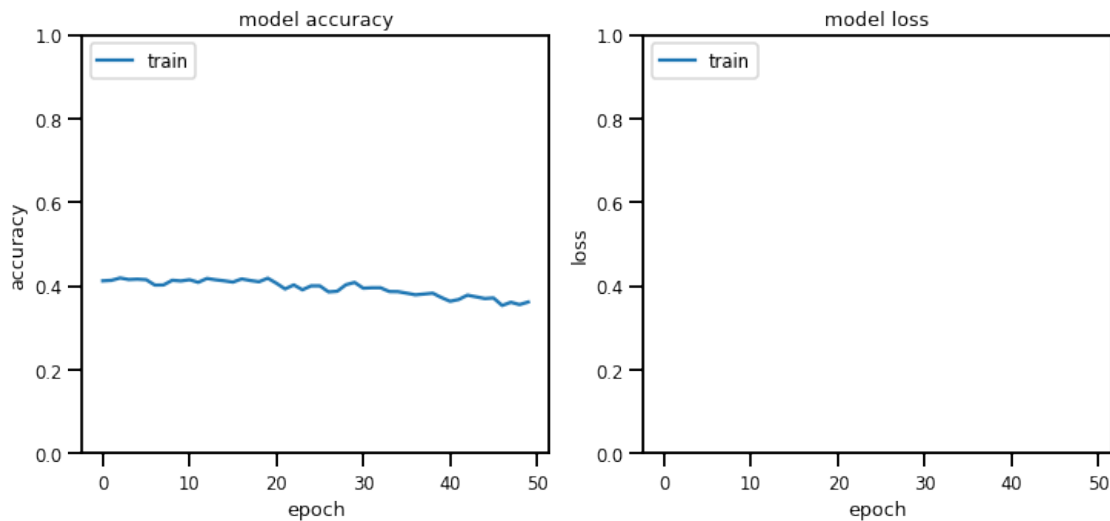
```



```

plt.title('model accuracy')
plt.ylabel('accuracy')
plt.xlabel('epoch')
plt.legend(['train', 'test'], loc='upper left')
plt.ylim(0, 1)
# summarize history for loss
plt.subplot(1,2,2)
plt.plot(history.history['loss'])
#plt.plot(history.history['val_loss'])
plt.title('model loss')
plt.ylabel('loss')
plt.xlabel('epoch')
plt.legend(['train', 'test'], loc='upper left')
plt.ylim(0, 1)
plt.show()

```



```
[ ]: model_tfp.summary()
```

Model: "sequential_2"

Layer (type)	Output Shape	Param #
dense_flipout (DenseFlipout)	(None, 16)	368
dense_flipout_1 (DenseFlipo ut)	(None, 6)	198
dense_flipout_2 (DenseFlipo ut)	(None, 2)	26

```
=====
Total params: 592
Trainable params: 592
Non-trainable params: 0
-----
```

doing all the same steps of building model, fitting it to the data and evaluating it and plotting parameters for all the models built in the notebook.

define tensorboard variables for we plots

Train BNN with a small training subset.

Train BNN with the whole training set. building different versions of bnn with different parameters.

Steps done in implementing all kind of bnns * Building a model * Fitting the model on the data * Evaluating the model * Plotting different parameters of the model for comparison * saving the model as a file * saving the model architecture as a image All these models with different versions in it as described below.

EXP VBNN:

```
[ ]: dist = tfp.distributions
dataset_size = len(X_train)
#defining kl_divergence function
kl_divergence_function = (lambda q, p, _: dist.kl_divergence(q, p) / tf.
    ↳ cast(dataset_size, dtype=tf.float32))
#defining model
model_tfp_v1 = tf.keras.Sequential([
    tf.keras.Input(X_train.shape[1]),
    tfp.layers.DenseFlipout(14, kernel_divergence_fn=kl_divergence_function,↳
    ↳ activation=tf.nn.relu),
    tfp.layers.DenseFlipout(6, kernel_divergence_fn=kl_divergence_function,↳
    ↳ activation=tf.nn.relu ),
    tfp.layers.DenseFlipout(2, kernel_divergence_fn=kl_divergence_function,↳
    ↳ activation=tf.nn.softmax),
])
# compiling the model
learning_rate = 0.005 #1e-06 #
model_tfp_v1.compile(optimizer=tf.keras.optimizers.
    ↳ Adam(learning_rate),loss='binary_crossentropy',metrics=['accuracy'])
```

```
/usr/local/lib/python3.7/dist-
packages/tensorflow_probability/python/layers/util.py:102: UserWarning:
`layer.add_variable` is deprecated and will be removed in a future version.
Please use `layer.add_weight` method instead.
```

```

    trainable=trainable)
/usr/local/lib/python3.7/dist-
packages/tensorflow_probability/python/layers/util.py:112: UserWarning:
`layer.add_variable` is deprecated and will be removed in a future version.
Please use `layer.add_weight` method instead.
    trainable=trainable)

```

```
[ ]: from keras.utils.vis_utils import plot_model
```

```
[ ]: #fitting the model on the training data
history = model_tfp_v1.fit(X_train, y_train,
    ↳epochs=40)#,batch_size=1,validation_data = (np.asarray(X_test), np.
    ↳asarray(y_test)),verbose=0)
#evaluating the model on the test dataset
test_loss, test_acc = model_tfp_v1.evaluate(X_test, y_test)
print('\nTest accuracy:', test_acc)
print('\nTest loss:', test_loss)
# TRY REMOVING THE VALIDATION PART FROM THE FIT
# validation_data = (np.asarray(X_test), np.asarray(y_test))
#history = normal_bnn_model.fit(np.asarray(X_train), np.
    ↳asarray(y_train),epochs=50,validation_split=0.2, shuffle=True)
# to see history:
# list all data in history
print(history.history.keys())
# summarize history for accuracy

#normal_bnn_model.save('model_tfp_v1.h5')
#normal_bnn_model.save('saved_model/model_tfp_v1')
plt.figure(figsize=(12,5))
plt.subplot(1,2,1)
plt.plot(history.history['accuracy'])
#plt.plot(history.history['val_accuracy'])
plt.title('model accuracy')
plt.ylabel('accuracy')
plt.xlabel('epoch')
plt.legend(['train', 'test'], loc='upper left')
plt.ylim(0, 1)
# summarize history for loss
plt.subplot(1,2,2)
plt.plot(history.history['loss'])
#plt.plot(history.history['val_loss'])
plt.title('model loss')
plt.ylabel('loss')
plt.xlabel('epoch')
plt.legend(['train', 'test'], loc='upper left')
plt.ylim(0, 1)
plt.show()

```

```
plot_model(model_tfp_v1, to_file='model_plot.png', show_shapes=True,  
↳ show_layer_names=True)
```

```
Epoch 1/40  
219/219 [=====] - 3s 3ms/step - loss: 0.8091 -  
accuracy: 0.5089  
Epoch 2/40  
219/219 [=====] - 1s 3ms/step - loss: 0.7567 -  
accuracy: 0.3874  
Epoch 3/40  
219/219 [=====] - 1s 3ms/step - loss: 0.7431 -  
accuracy: 0.3524  
Epoch 4/40  
219/219 [=====] - 1s 3ms/step - loss: 0.7349 -  
accuracy: 0.4621  
Epoch 5/40  
219/219 [=====] - 1s 3ms/step - loss: 0.7321 -  
accuracy: 0.4561  
Epoch 6/40  
219/219 [=====] - 1s 3ms/step - loss: 0.7277 -  
accuracy: 0.4784  
Epoch 7/40  
219/219 [=====] - 1s 3ms/step - loss: 0.7261 -  
accuracy: 0.5200  
Epoch 8/40  
219/219 [=====] - 1s 3ms/step - loss: 0.7302 -  
accuracy: 0.5444  
Epoch 9/40  
219/219 [=====] - 1s 3ms/step - loss: 0.7234 -  
accuracy: 0.5099  
Epoch 10/40  
219/219 [=====] - 1s 3ms/step - loss: 0.7206 -  
accuracy: 0.5121  
Epoch 11/40  
219/219 [=====] - 1s 3ms/step - loss: 0.7223 -  
accuracy: 0.4017  
Epoch 12/40  
219/219 [=====] - 1s 3ms/step - loss: 0.7191 -  
accuracy: 0.5080  
Epoch 13/40  
219/219 [=====] - 1s 3ms/step - loss: 0.7171 -  
accuracy: 0.5443  
Epoch 14/40  
219/219 [=====] - 1s 3ms/step - loss: 0.7160 -  
accuracy: 0.5454  
Epoch 15/40  
219/219 [=====] - 1s 3ms/step - loss: 0.7154 -
```

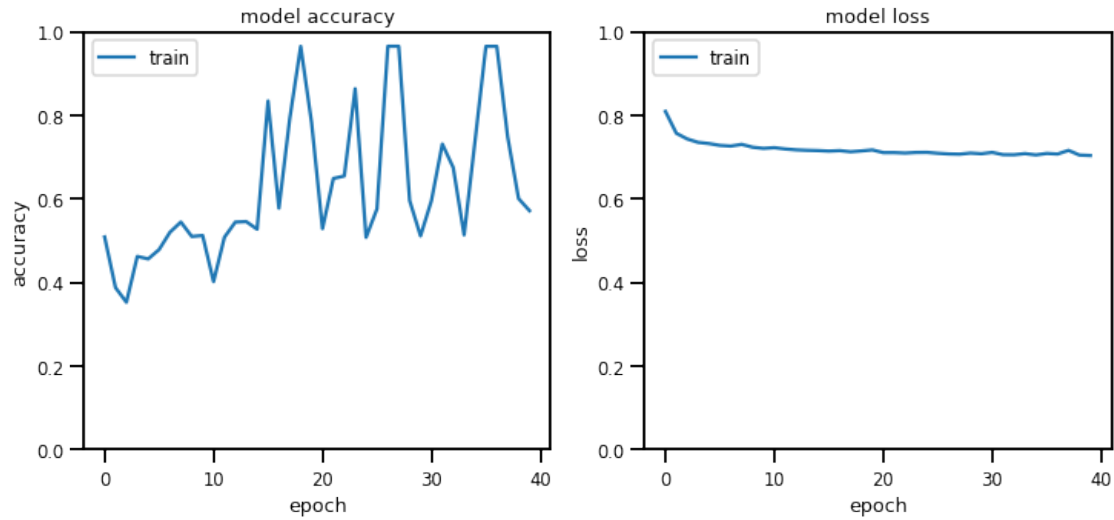
accuracy: 0.5271
Epoch 16/40
219/219 [=====] - 1s 3ms/step - loss: 0.7141 -
accuracy: 0.8340
Epoch 17/40
219/219 [=====] - 1s 3ms/step - loss: 0.7152 -
accuracy: 0.5776
Epoch 18/40
219/219 [=====] - 1s 3ms/step - loss: 0.7125 -
accuracy: 0.7929
Epoch 19/40
219/219 [=====] - 1s 3ms/step - loss: 0.7146 -
accuracy: 0.9647
Epoch 20/40
219/219 [=====] - 1s 4ms/step - loss: 0.7169 -
accuracy: 0.7817
Epoch 21/40
219/219 [=====] - 1s 3ms/step - loss: 0.7104 -
accuracy: 0.5286
Epoch 22/40
219/219 [=====] - 1s 3ms/step - loss: 0.7105 -
accuracy: 0.6486
Epoch 23/40
219/219 [=====] - 1s 3ms/step - loss: 0.7094 -
accuracy: 0.6546
Epoch 24/40
219/219 [=====] - 1s 3ms/step - loss: 0.7108 -
accuracy: 0.8633
Epoch 25/40
219/219 [=====] - 1s 5ms/step - loss: 0.7110 -
accuracy: 0.5076
Epoch 26/40
219/219 [=====] - 1s 6ms/step - loss: 0.7089 -
accuracy: 0.5757
Epoch 27/40
219/219 [=====] - 2s 7ms/step - loss: 0.7073 -
accuracy: 0.9649
Epoch 28/40
219/219 [=====] - 1s 3ms/step - loss: 0.7067 -
accuracy: 0.9649
Epoch 29/40
219/219 [=====] - 1s 4ms/step - loss: 0.7094 -
accuracy: 0.5957
Epoch 30/40
219/219 [=====] - 1s 4ms/step - loss: 0.7078 -
accuracy: 0.5111
Epoch 31/40
219/219 [=====] - 1s 4ms/step - loss: 0.7109 -

```
accuracy: 0.5956
Epoch 32/40
219/219 [=====] - 1s 3ms/step - loss: 0.7056 -
accuracy: 0.7310
Epoch 33/40
219/219 [=====] - 1s 3ms/step - loss: 0.7053 -
accuracy: 0.6747
Epoch 34/40
219/219 [=====] - 1s 3ms/step - loss: 0.7081 -
accuracy: 0.5136
Epoch 35/40
219/219 [=====] - 1s 3ms/step - loss: 0.7049 -
accuracy: 0.7377
Epoch 36/40
219/219 [=====] - 1s 3ms/step - loss: 0.7085 -
accuracy: 0.9646
Epoch 37/40
219/219 [=====] - 1s 3ms/step - loss: 0.7071 -
accuracy: 0.9647
Epoch 38/40
219/219 [=====] - 1s 3ms/step - loss: 0.7158 -
accuracy: 0.7479
Epoch 39/40
219/219 [=====] - 1s 3ms/step - loss: 0.7046 -
accuracy: 0.6004
Epoch 40/40
219/219 [=====] - 1s 3ms/step - loss: 0.7035 -
accuracy: 0.5716
94/94 [=====] - 1s 2ms/step - loss: 0.7034 - accuracy:
0.9690
```

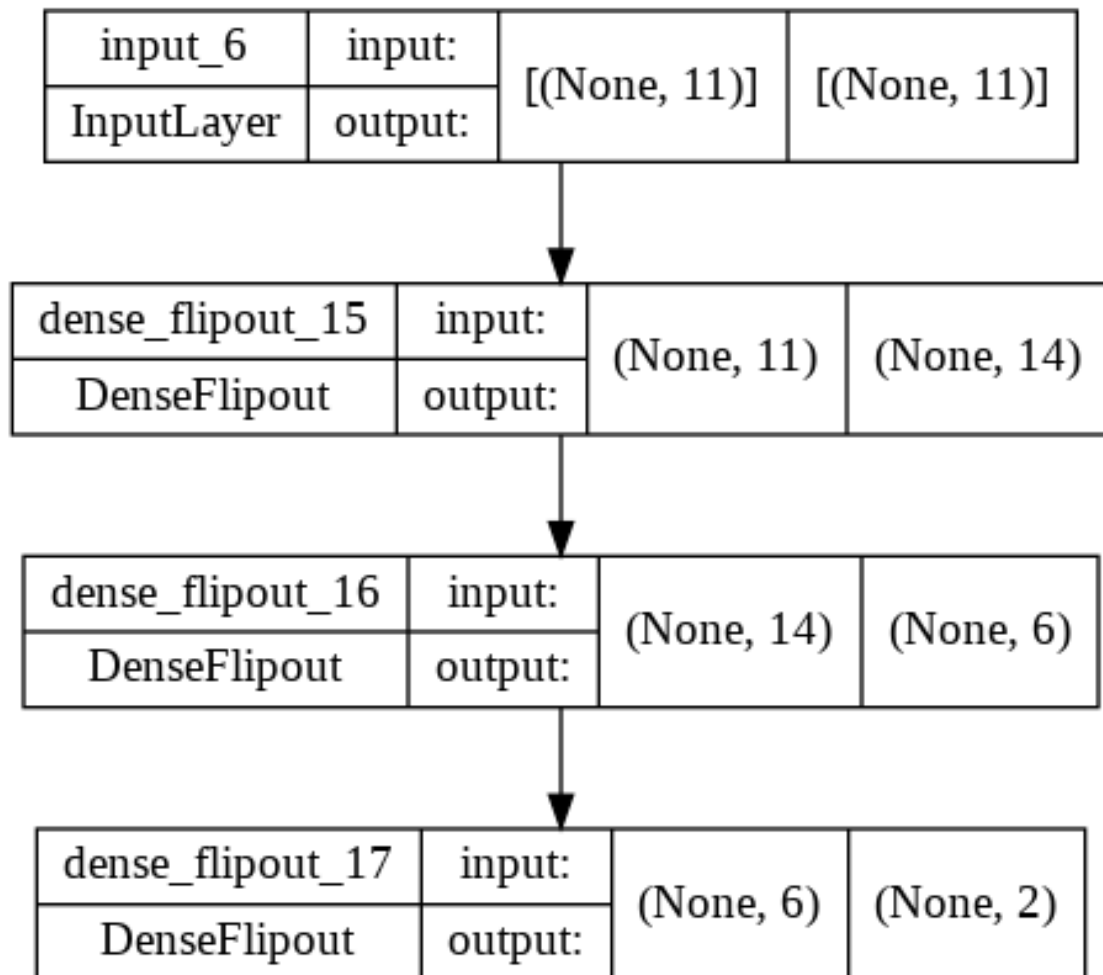
Test accuracy: 0.968999981880188

Test loss: 0.7033995985984802

dict_keys(['loss', 'accuracy'])



[]:



```
[ ]: #prints model summary
model_tfp_v1.summary()
```

Model: "sequential_7"

Layer (type)	Output Shape	Param #
dense_flipout_15 (DenseFlip out)	(None, 14)	322
dense_flipout_16 (DenseFlip out)	(None, 6)	174
dense_flipout_17 (DenseFlip out)	(None, 2)	26

=====
 Total params: 522
 Trainable params: 522
 Non-trainable params: 0
 =====

```
[ ]: !pip install pickle5
```

Collecting pickle5
 Downloading
 pickle5-0.0.12-cp37-cp37m-manylinux_2_5_x86_64.manylinux1_x86_64.whl (256 kB)
 | 256 kB 5.2 MB/s
 Installing collected packages: pickle5
 Successfully installed pickle5-0.0.12

```
[ ]: import pickle
# used to save model as a pkl file and can be loaded anywhere ans used directly
↳with required packages.
filename = 'model_tfp1v1.pkl'
tf.saved_model.SaveOptions(
    namespace_whitelist=None, save_debug_info=False, function_aliases=None,
    experimental_io_device=None, experimental_variable_policy=None,
    experimental_custom_gradients=True
)
pickle.dump(model_tfp_v1, open(filename, 'wb'))
```

INFO:tensorflow:Assets written to:
 ram://8d4e6946-7a50-422b-b9af-069382b34d78/assets

```
[ ]: !mkdir -p saved_model
```



```
[ ]: #saving tensorflow model of version v1 to drive. download this and place it in
#streamlit local folder and load it using tensorflow load model
model_tfp_v1.save('saved_model/model_tfp_v1')
```

INFO:tensorflow:Assets written to: saved_model/model_tfp_v1/assets

```
[ ]: #saving model into hdf5 format and load the same file using same loadmodel_
↪function
model_tfp_v1.save('model_tfp_v1.h5')
```

```
[ ]: # use this to load the model into local
new_model = tf.keras.models.load_model('saved_model/model_tfp_v1')

# Check its architecture
new_model.summary()
```

Model: "sequential_7"

Layer (type)	Output Shape	Param #
dense_flipout_15 (DenseFlip out)	(None, 14)	322
dense_flipout_16 (DenseFlip out)	(None, 6)	174
dense_flipout_17 (DenseFlip out)	(None, 2)	26

=====
 Total params: 522
 Trainable params: 522
 Non-trainable params: 0
 =====

```
[ ]: !pip3 install ann_visualizer
!pip install graphviz
```

Looking in indexes: <https://pypi.org/simple>, <https://us-python.pkg.dev/colab-wheels/public/simple/>

Collecting ann_visualizer

Downloading ann_visualizer-2.5.tar.gz (4.7 kB)

Building wheels for collected packages: ann-visualizer

Building wheel for ann-visualizer (setup.py) ... done

Created wheel for ann-visualizer: filename=ann_visualizer-2.5-py3-none-any.whl size=4168 sha256=29c69b3f6d77a59efcf04d9e258a2946bf6d3b8c8b3fff153ba417c31a5da620

Stored in directory: /root/.cache/pip/wheels/1b/fc/58/2ab1c3b30350105929308bec
ddda4fb59b1358e54f985e1f4a
Successfully built ann-visualizer
Installing collected packages: ann-visualizer
Successfully installed ann-visualizer-2.5
Looking in indexes: <https://pypi.org/simple>, <https://us-python.pkg.dev/colab-wheels/public/simple/>
Requirement already satisfied: graphviz in /usr/local/lib/python3.7/dist-packages (0.10.1)

```
[ ]: from ann_visualizer.visualize import ann_viz;
```

```
#ann_viz(new_model, title="My first neural network")
```

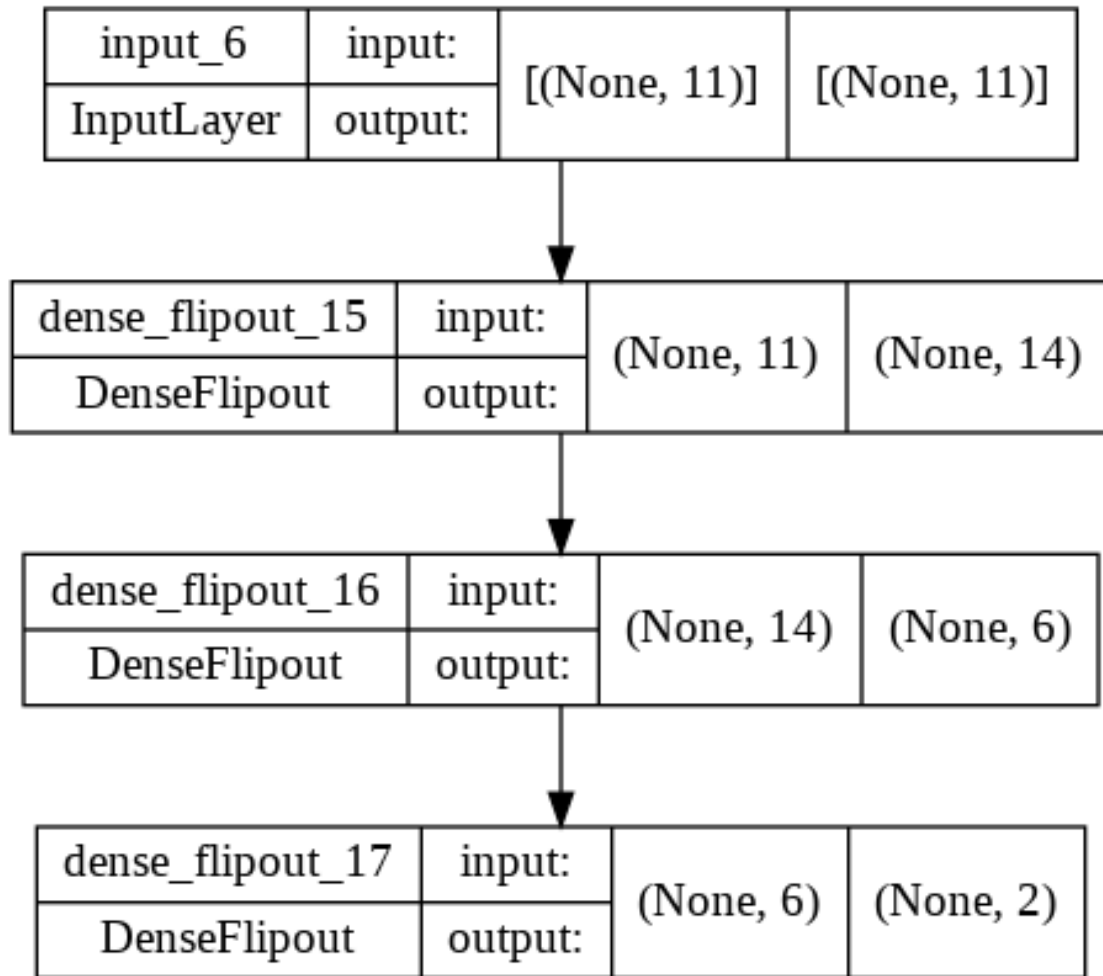
```
[ ]: from keras.utils.vis_utils import plot_model
```

```
#trying to save model architecture as an image.
```

```
# tried with different one but its not supporting the tfp layers, so just only  
↪ this one.
```

```
plot_model(new_model, to_file='model_plot1.png', show_shapes=True,  
↪ show_layer_names=True)
```

```
[ ]:
```



v2

```
[ ]: dist = tfp.distributions
dataset_size = len(X_train)
kl_divergence_function = (lambda q, p, _: dist.kl_divergence(q, p) / tf.
    ↳ cast(dataset_size, dtype=tf.float32))

model_tfp_v2 = tf.keras.Sequential([
    tf.keras.Input(X_train.shape[1]),
    tfp.layers.DenseFlipout(14, kernel_divergence_fn=kl_divergence_function, ↳
    ↳ activation=tf.nn.relu),
    tfp.layers.DenseFlipout(6, kernel_divergence_fn=kl_divergence_function, ↳
    ↳ activation=tf.nn.relu ),
    tfp.layers.DenseFlipout(2, kernel_divergence_fn=kl_divergence_function, ↳
    ↳ activation=tf.nn.softmax),
])
```

```

learning_rate = 0.005 #1e-06#
model_tfp_v2.compile(optimizer=tf.keras.optimizers.
    ↳Adam(learning_rate),loss='binary_crossentropy',metrics=['accuracy'])

history = model_tfp_v2.fit(X_train, y_train,↳
    ↳epochs=80)#,batch_size=1,validation_data = (np.asarray(X_test), np.
    ↳asarray(y_test)),verbose=0)
test_loss, test_acc = model_tfp_v2.evaluate(X_test, y_test)
print('\nTest accuracy:', test_acc)
print('\nTest loss:', test_loss)

# TRY REMOVING THE VALIDATION PART FROM THE FIT
# validation_data = (np.asarray(X_test), np.asarray(y_test))
#history = normal_bnn_model.fit(np.asarray(X_train), np.
    ↳asarray(y_train),epochs=50,validation_split=0.2, shuffle=True)
# to see history:
# list all data in history
print(history.history.keys())
# summarize history for accuracy

model_tfp_v2.save('model_tfp_v2.h5')
model_tfp_v2.save('saved_model/model_tfp_v2')
plt.figure(figsize=(12,5))
plt.subplot(1,2,1)
plt.plot(history.history['accuracy'])
#plt.plot(history.history['val_accuracy'])
plt.title('model accuracy')
plt.ylabel('accuracy')
plt.xlabel('epoch')
plt.legend(['train', 'test'], loc='upper left')
plt.ylim(0, 1)
# summarize history for loss
plt.subplot(1,2,2)
plt.plot(history.history['loss'])
#plt.plot(history.history['val_loss'])
plt.title('model loss')
plt.ylabel('loss')
plt.xlabel('epoch')
plt.legend(['train', 'test'], loc='upper left')
plt.ylim(0, 1)
plt.show()
plot_model(model_tfp_v2, to_file='model_plot.png', show_shapes=True,↳
    ↳show_layer_names=True)

model_tfp_v2.summary()

```

```

/usr/local/lib/python3.7/dist-
packages/tensorflow_probability/python/layers/util.py:102: UserWarning:
`layer.add_variable` is deprecated and will be removed in a future version.
Please use `layer.add_weight` method instead.
    trainable=trainable)
/usr/local/lib/python3.7/dist-
packages/tensorflow_probability/python/layers/util.py:112: UserWarning:
`layer.add_variable` is deprecated and will be removed in a future version.
Please use `layer.add_weight` method instead.
    trainable=trainable)

Epoch 1/80
219/219 [=====] - 3s 3ms/step - loss: 0.9311 -
accuracy: 0.0879
Epoch 2/80
219/219 [=====] - 1s 3ms/step - loss: 0.7601 -
accuracy: 0.4794
Epoch 3/80
219/219 [=====] - 1s 3ms/step - loss: 0.7468 -
accuracy: 0.6104
Epoch 4/80
219/219 [=====] - 1s 3ms/step - loss: 0.7393 -
accuracy: 0.5711
Epoch 5/80
219/219 [=====] - 1s 3ms/step - loss: 0.7363 -
accuracy: 0.5110
Epoch 6/80
219/219 [=====] - 1s 3ms/step - loss: 0.7319 -
accuracy: 0.4351
Epoch 7/80
219/219 [=====] - 1s 4ms/step - loss: 0.7288 -
accuracy: 0.4657
Epoch 8/80
219/219 [=====] - 1s 3ms/step - loss: 0.7265 -
accuracy: 0.4647
Epoch 9/80
219/219 [=====] - 1s 3ms/step - loss: 0.7240 -
accuracy: 0.4300
Epoch 10/80
219/219 [=====] - 1s 3ms/step - loss: 0.7233 -
accuracy: 0.4793
Epoch 11/80
219/219 [=====] - 1s 3ms/step - loss: 0.7216 -
accuracy: 0.5134
Epoch 12/80
219/219 [=====] - 1s 3ms/step - loss: 0.7197 -
accuracy: 0.5316
Epoch 13/80

```

219/219 [=====] - 1s 3ms/step - loss: 0.7195 -
accuracy: 0.4676
Epoch 14/80
219/219 [=====] - 1s 3ms/step - loss: 0.7183 -
accuracy: 0.4764
Epoch 15/80
219/219 [=====] - 1s 3ms/step - loss: 0.7168 -
accuracy: 0.5439
Epoch 16/80
219/219 [=====] - 1s 3ms/step - loss: 0.7161 -
accuracy: 0.5971
Epoch 17/80
219/219 [=====] - 1s 3ms/step - loss: 0.7153 -
accuracy: 0.6049
Epoch 18/80
219/219 [=====] - 1s 4ms/step - loss: 0.7161 -
accuracy: 0.5280
Epoch 19/80
219/219 [=====] - 1s 3ms/step - loss: 0.7133 -
accuracy: 0.9649
Epoch 20/80
219/219 [=====] - 1s 3ms/step - loss: 0.7173 -
accuracy: 0.5521
Epoch 21/80
219/219 [=====] - 1s 3ms/step - loss: 0.7121 -
accuracy: 0.5409
Epoch 22/80
219/219 [=====] - 1s 3ms/step - loss: 0.7114 -
accuracy: 0.5807
Epoch 23/80
219/219 [=====] - 1s 4ms/step - loss: 0.7106 -
accuracy: 0.7837
Epoch 24/80
219/219 [=====] - 1s 3ms/step - loss: 0.7119 -
accuracy: 0.5833
Epoch 25/80
219/219 [=====] - 1s 3ms/step - loss: 0.7136 -
accuracy: 0.5080
Epoch 26/80
219/219 [=====] - 1s 3ms/step - loss: 0.7088 -
accuracy: 0.7309
Epoch 27/80
219/219 [=====] - 1s 3ms/step - loss: 0.7085 -
accuracy: 0.6814
Epoch 28/80
219/219 [=====] - 1s 3ms/step - loss: 0.7087 -
accuracy: 0.6179
Epoch 29/80

219/219 [=====] - 1s 3ms/step - loss: 0.7085 -
 accuracy: 0.5709
 Epoch 30/80
 219/219 [=====] - 1s 3ms/step - loss: 0.7086 -
 accuracy: 0.7956
 Epoch 31/80
 219/219 [=====] - 1s 3ms/step - loss: 0.7085 -
 accuracy: 0.5579
 Epoch 32/80
 219/219 [=====] - 1s 3ms/step - loss: 0.7059 -
 accuracy: 0.8029
 Epoch 33/80
 219/219 [=====] - 1s 3ms/step - loss: 0.7133 -
 accuracy: 0.9640
 Epoch 34/80
 219/219 [=====] - 1s 3ms/step - loss: 0.7118 -
 accuracy: 0.6674
 Epoch 35/80
 219/219 [=====] - 1s 3ms/step - loss: 0.7170 -
 accuracy: 0.6384
 Epoch 36/80
 219/219 [=====] - 1s 3ms/step - loss: 0.7078 -
 accuracy: 0.4956
 Epoch 37/80
 219/219 [=====] - 1s 6ms/step - loss: 0.7045 -
 accuracy: 0.5657
 Epoch 38/80
 219/219 [=====] - 1s 6ms/step - loss: 0.7065 -
 accuracy: 0.9337
 Epoch 39/80
 219/219 [=====] - 1s 6ms/step - loss: 0.7051 -
 accuracy: 0.4970
 Epoch 40/80
 219/219 [=====] - 1s 7ms/step - loss: 0.7038 -
 accuracy: 0.8129
 Epoch 41/80
 219/219 [=====] - 1s 6ms/step - loss: 0.7066 -
 accuracy: 0.5614
 Epoch 42/80
 219/219 [=====] - 1s 6ms/step - loss: 0.7037 -
 accuracy: 0.8314
 Epoch 43/80
 219/219 [=====] - 2s 8ms/step - loss: 0.7034 -
 accuracy: 0.9649
 Epoch 44/80
 219/219 [=====] - 2s 9ms/step - loss: 0.7031 -
 accuracy: 0.9649
 Epoch 45/80

219/219 [=====] - 2s 8ms/step - loss: 0.7038 -
 accuracy: 0.9649
 Epoch 46/80
 219/219 [=====] - 2s 7ms/step - loss: 0.7035 -
 accuracy: 0.9649
 Epoch 47/80
 219/219 [=====] - 2s 8ms/step - loss: 0.7033 -
 accuracy: 0.6684
 Epoch 48/80
 219/219 [=====] - 2s 7ms/step - loss: 0.7120 -
 accuracy: 0.5044
 Epoch 49/80
 219/219 [=====] - 2s 9ms/step - loss: 0.7031 -
 accuracy: 0.7150
 Epoch 50/80
 219/219 [=====] - 2s 9ms/step - loss: 0.7074 -
 accuracy: 0.8543
 Epoch 51/80
 219/219 [=====] - 2s 9ms/step - loss: 0.7046 -
 accuracy: 0.4874
 Epoch 52/80
 219/219 [=====] - 2s 9ms/step - loss: 0.7028 -
 accuracy: 0.7771
 Epoch 53/80
 219/219 [=====] - 2s 9ms/step - loss: 0.7022 -
 accuracy: 0.6733
 Epoch 54/80
 219/219 [=====] - 2s 8ms/step - loss: 0.7017 -
 accuracy: 0.7454
 Epoch 55/80
 219/219 [=====] - 2s 9ms/step - loss: 0.7015 -
 accuracy: 0.9649
 Epoch 56/80
 219/219 [=====] - 2s 8ms/step - loss: 0.7023 -
 accuracy: 0.9647
 Epoch 57/80
 219/219 [=====] - 2s 8ms/step - loss: 0.7040 -
 accuracy: 0.6410
 Epoch 58/80
 219/219 [=====] - 2s 7ms/step - loss: 0.7011 -
 accuracy: 0.7229
 Epoch 59/80
 219/219 [=====] - 2s 8ms/step - loss: 0.7009 -
 accuracy: 0.9649
 Epoch 60/80
 219/219 [=====] - 2s 10ms/step - loss: 0.7027 -
 accuracy: 0.9646
 Epoch 61/80

219/219 [=====] - 2s 7ms/step - loss: 0.7023 -
 accuracy: 0.8296
 Epoch 62/80
 219/219 [=====] - 1s 7ms/step - loss: 0.7007 -
 accuracy: 0.5303
 Epoch 63/80
 219/219 [=====] - 2s 8ms/step - loss: 0.7005 -
 accuracy: 0.9649
 Epoch 64/80
 219/219 [=====] - 2s 8ms/step - loss: 0.7004 -
 accuracy: 0.9649
 Epoch 65/80
 219/219 [=====] - 2s 9ms/step - loss: 0.7012 -
 accuracy: 0.9647
 Epoch 66/80
 219/219 [=====] - 2s 9ms/step - loss: 0.7061 -
 accuracy: 0.8104
 Epoch 67/80
 219/219 [=====] - 2s 8ms/step - loss: 0.7000 -
 accuracy: 0.5383
 Epoch 68/80
 219/219 [=====] - 2s 7ms/step - loss: 0.7058 -
 accuracy: 0.9643
 Epoch 69/80
 219/219 [=====] - 2s 8ms/step - loss: 0.7086 -
 accuracy: 0.7787
 Epoch 70/80
 219/219 [=====] - 2s 9ms/step - loss: 0.7035 -
 accuracy: 0.5463
 Epoch 71/80
 219/219 [=====] - 3s 12ms/step - loss: 0.7093 -
 accuracy: 0.9641
 Epoch 72/80
 219/219 [=====] - 2s 8ms/step - loss: 0.7133 -
 accuracy: 0.5841
 Epoch 73/80
 219/219 [=====] - 2s 8ms/step - loss: 0.7184 -
 accuracy: 0.5600
 Epoch 74/80
 219/219 [=====] - 2s 9ms/step - loss: 0.7076 -
 accuracy: 0.5120
 Epoch 75/80
 219/219 [=====] - 2s 8ms/step - loss: 0.7009 -
 accuracy: 0.4879
 Epoch 76/80
 219/219 [=====] - 2s 7ms/step - loss: 0.7028 -
 accuracy: 0.9087
 Epoch 77/80

```

219/219 [=====] - 2s 8ms/step - loss: 0.7053 -
accuracy: 0.8533
Epoch 78/80
219/219 [=====] - 2s 8ms/step - loss: 0.7107 -
accuracy: 0.5307
Epoch 79/80
219/219 [=====] - 1s 7ms/step - loss: 0.7047 -
accuracy: 0.6173
Epoch 80/80
219/219 [=====] - 1s 4ms/step - loss: 0.7026 -
accuracy: 0.7944
94/94 [=====] - 1s 2ms/step - loss: 0.7438 - accuracy:
0.9667

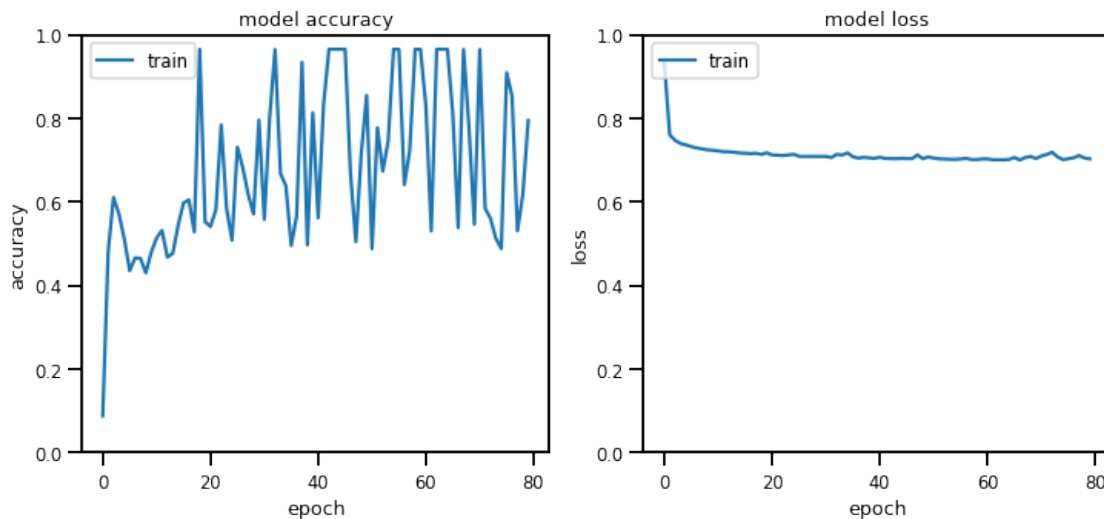
```

Test accuracy: 0.9666666388511658

Test loss: 0.7437806129455566

dict_keys(['loss', 'accuracy'])

INFO:tensorflow:Assets written to: saved_model/model_tfp_v2/assets



Model: "sequential_8"

Layer (type)	Output Shape	Param #
dense_flipout_18 (DenseFlip out)	(None, 14)	322
dense_flipout_19 (DenseFlip out)	(None, 6)	174

dense_flipout_20 (DenseFlip out) (None, 2)

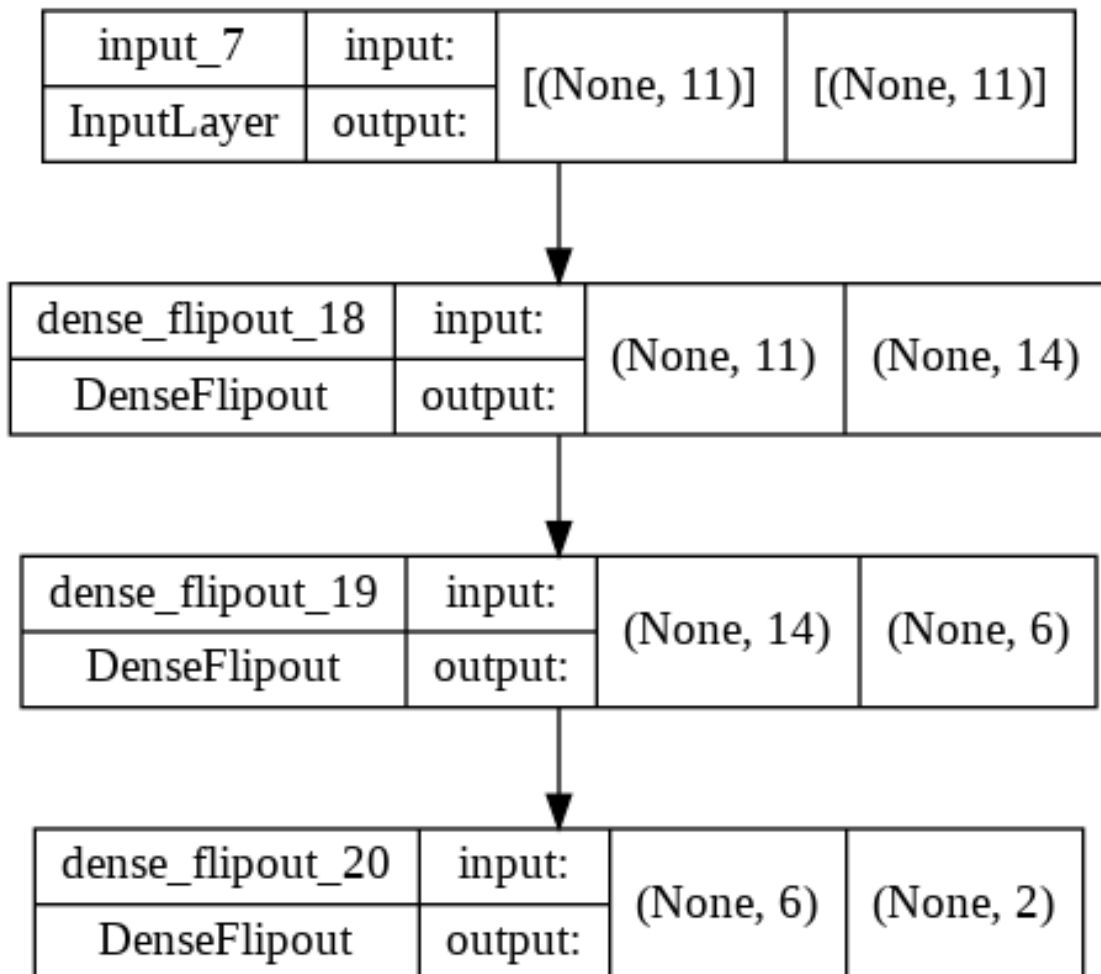
26

```
=====
Total params: 522
Trainable params: 522
Non-trainable params: 0
-----
```

```
[ ]: #ann_viz(model_tfp_v2, title="My Second neural network")
```

```
[ ]: from keras.utils.vis_utils import plot_model
plot_model(model_tfp_v2, to_file='model_plot.png', show_shapes=True,
↳ show_layer_names=True)
```

[]:



visualize BNN

```
[ ]: !pip3 install keras
      !pip3 install ann_visualizer
      !pip install graphviz
```

Looking in indexes: <https://pypi.org/simple>, <https://us-python.pkg.dev/colab-wheels/public/simple/>

Requirement already satisfied: keras in /usr/local/lib/python3.7/dist-packages (2.8.0)

Looking in indexes: <https://pypi.org/simple>, <https://us-python.pkg.dev/colab-wheels/public/simple/>

Requirement already satisfied: ann_visualizer in /usr/local/lib/python3.7/dist-packages (2.5)

Looking in indexes: <https://pypi.org/simple>, <https://us-python.pkg.dev/colab-wheels/public/simple/>

Requirement already satisfied: graphviz in /usr/local/lib/python3.7/dist-packages (0.10.1)

Experiment 3: probabilistic Bayesian neural network: not needed

0.0.3 DIFFERENT BNN'S

1. NORMAL BNN
2. BNN WITH DIFFERENT DROPOUTS
3. BNN WITH DIFFERENT EARLY STOPS
4. BNN WITH DIFFERENT REGULARIZERS
5. SIR mentioned to work on transformers also
6. MIXING OF THE ABOVE VARIANTS AND COMPARING WITH THE NORMAL ANN

PLOT THE UNCERTAINTIES FOR ALL THESE MODELS

1. NORMAL BNN

```
[ ]: dist = tfp.distributions
      dataset_size = len(X_train)
      kl_divergence_function = (lambda q, p, _: dist.kl_divergence(q, p) / tf.
        ↳ cast(dataset_size, dtype=tf.float32))

      normal_bnn_model = tf.keras.Sequential([
        tf.keras.Input(X_train.shape[1]),
        tfp.layers.DenseFlipout(16, kernel_divergence_fn=kl_divergence_function,
        ↳ #activation=tf.nn.relu),
        tfp.layers.DenseFlipout(6,
        ↳ kernel_divergence_fn=kl_divergence_function, activation=tf.nn.relu),
        tfp.layers.DenseFlipout(2, kernel_divergence_fn=kl_divergence_function,
        ↳ activation=tf.nn.softmax),
      ])
```

```
learning_rate = 1e-06#0.001
normal_bnn_model.compile(optimizer=tf.keras.optimizers.
    ↳Adam(learning_rate),loss='binary_crossentropy',metrics=['accuracy'])
```

```
/usr/local/lib/python3.7/dist-
packages/tensorflow_probability/python/layers/util.py:102: UserWarning:
`layer.add_variable` is deprecated and will be removed in a future version.
Please use `layer.add_weight` method instead.
    trainable=trainable)
/usr/local/lib/python3.7/dist-
packages/tensorflow_probability/python/layers/util.py:112: UserWarning:
`layer.add_variable` is deprecated and will be removed in a future version.
Please use `layer.add_weight` method instead.
    trainable=trainable)
```

```
[ ]: # TRY REMOVING THE VALIDATION PART FROM THE FIT
# validation_data = (np.asarray(X_test), np.asarray(y_test))
#history = normal_bnn_model.fit(np.asarray(X_train), np.
    ↳asarray(y_train),epochs=50,validation_split=0.2, shuffle=True)
# to see history:
history = normal_bnn_model.fit(np.asarray(X_train), np.
    ↳asarray(y_train),epochs=25, batch_size=1,validation_data = (np.
    ↳asarray(X_test), np.asarray(y_test)),verbose=0)
# list all data in history
print(history.history.keys())
# summarize history for accuracy
test_loss, test_acc = normal_bnn_model.evaluate(X_test, y_test)
print('\nTest accuracy:', test_acc)
print('\nTest loss:', test_loss)

normal_bnn_model.save('normal_bnn_model.h5')
normal_bnn_model.save('saved_model/normal_bnn_model')
```

```
dict_keys(['loss', 'accuracy', 'val_loss', 'val_accuracy'])
94/94 [=====] - 1s 4ms/step - loss: 0.8616 - accuracy:
0.8623
```

Test accuracy: 0.862333357334137

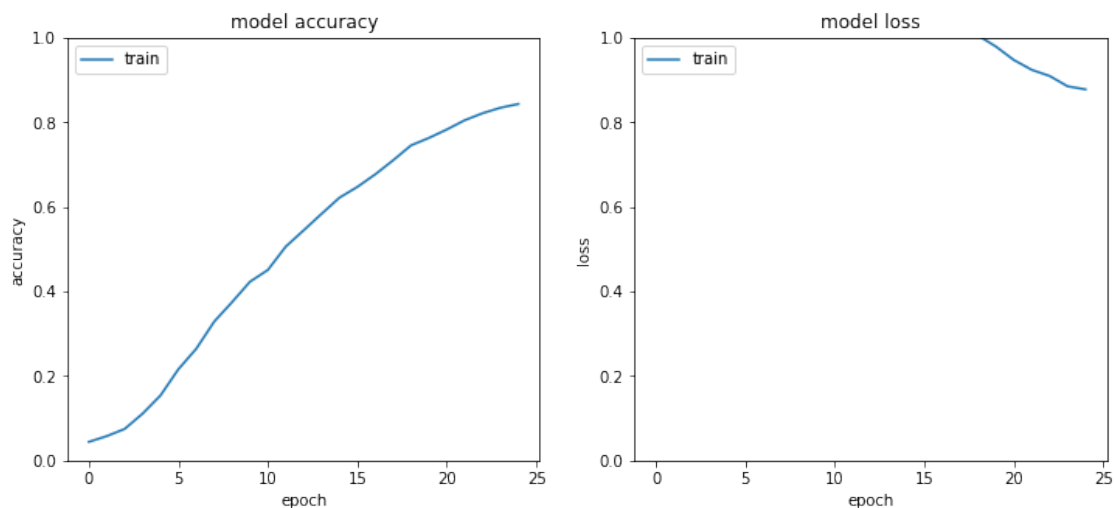
Test loss: 0.8615836501121521

INFO:tensorflow:Assets written to: saved_model/normal_bnn_model/assets

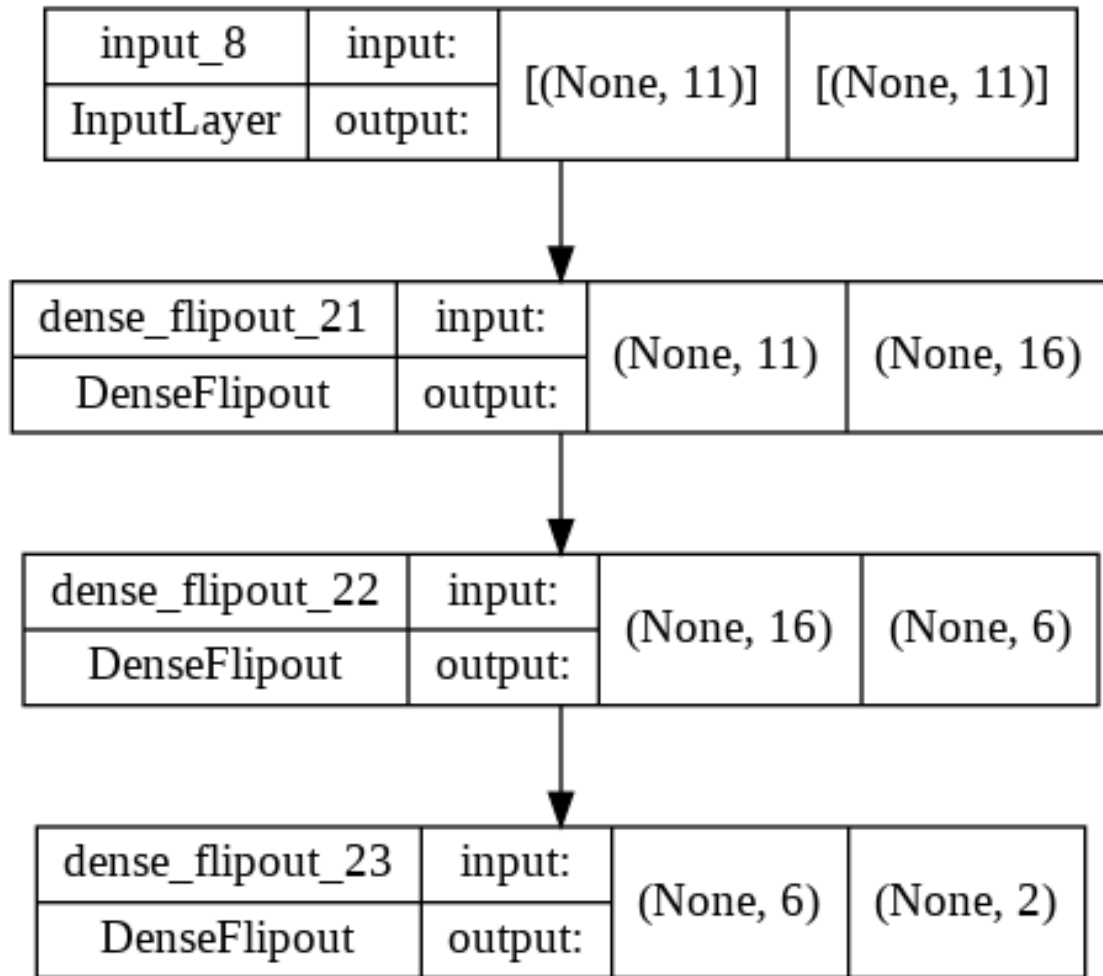
```
[ ]: print(normal_bnn_model.predict([[2,299.1,309.5,1600,47.8,80,0,0,0,0]]))

[[0.54033256 0.45966744]]
```

```
[ ]: plt.figure(figsize=(12,5))
plt.subplot(1,2,1)
plt.plot(history.history['accuracy'])
#plt.plot(history.history['val_accuracy'])
plt.title('model accuracy')
plt.ylabel('accuracy')
plt.xlabel('epoch')
plt.legend(['train', 'test'], loc='upper left')
plt.ylim(0, 1)
# summarize history for loss
plt.subplot(1,2,2)
plt.plot(history.history['loss'])
#plt.plot(history.history['val_loss'])
plt.title('model loss')
plt.ylabel('loss')
plt.xlabel('epoch')
plt.legend(['train', 'test'], loc='upper left')
plt.ylim(0, 1)
plt.show()
plot_model(normal_bnn_model, to_file='model_plot.png', show_shapes=True,
→show_layer_names=True)
```



```
[ ]:
```



New Section

NORMAL BNN2

```
[ ]: dist = tfp.distributions
dataset_size = len(X_train)
kl_divergence_function = (lambda q, p, _: dist.kl_divergence(q, p) / tf.
    ↳ cast(dataset_size, dtype=tf.float32))

normal_bnn2_model = tf.keras.Sequential([
    tf.keras.Input(X_train.shape[1]),
    #Dense(units = 22, activation = 'relu'),
    tfp.layers.DenseFlipout(22,
    ↳ kernel_divergence_fn=kl_divergence_function), #activation=tf.nn.relu),
    tfp.layers.DenseFlipout(12,
    ↳ kernel_divergence_fn=kl_divergence_function), #activation=tf.nn.relu),
```

```

    tfp.layers.DenseFlipout(4, kernel_divergence_fn=kl_divergence_function,
↪activation=tf.nn.relu),
    tfp.layers.DenseFlipout(2, kernel_divergence_fn=kl_divergence_function,
↪activation=tf.nn.softmax),
])

learning_rate = 1e-06 #0.00065
normal_bnn2_model.compile(optimizer=tf.keras.optimizers.
↪Adam(learning_rate), loss='binary_crossentropy', metrics=['accuracy'])

```

```

/usr/local/lib/python3.7/dist-
packages/tensorflow_probability/python/layers/util.py:102: UserWarning:
`layer.add_variable` is deprecated and will be removed in a future version.
Please use `layer.add_weight` method instead.
    trainable=trainable)
/usr/local/lib/python3.7/dist-
packages/tensorflow_probability/python/layers/util.py:112: UserWarning:
`layer.add_variable` is deprecated and will be removed in a future version.
Please use `layer.add_weight` method instead.
    trainable=trainable)

```

```

[ ]: # TRY REMOVING THE VALIDATION PART FROM THE FIT
# validation_data = (np.asarray(X_test), np.asarray(y_test))
# history = normal_bnn2_model.fit(np.asarray(X_train), np.
↪asarray(y_train), epochs=100, validation_split=0.3, shuffle=True)
# to see history:
history = normal_bnn2_model.fit(np.asarray(X_train), np.
↪asarray(y_train), epochs=15, batch_size=1, validation_data = (np.
↪asarray(X_test), np.asarray(y_test)), verbose=0)
# list all data in history
print(history.history.keys())
# summarize history for accuracy
test_loss, test_acc = normal_bnn2_model.evaluate(X_test, y_test)
print('\nTest accuracy:', test_acc)
print('\nTest loss:', test_loss)

```

```

dict_keys(['loss', 'accuracy', 'val_loss', 'val_accuracy'])
94/94 [=====] - 1s 3ms/step - loss: 0.9225 - accuracy:
0.9180

```

Test accuracy: 0.9179999828338623

Test loss: 0.9225282669067383

```

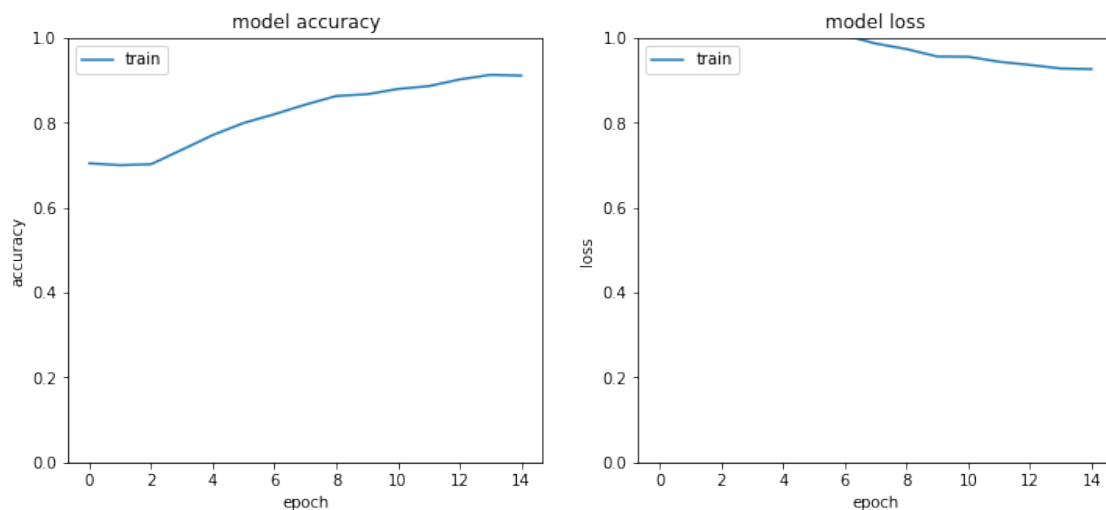
[ ]: print(normal_bnn2_model.predict([[1.0,299.1,309.5,1800.0,47.8,200.0,1.0,1.0,0.
↪0,0.0,30.0]]))

```

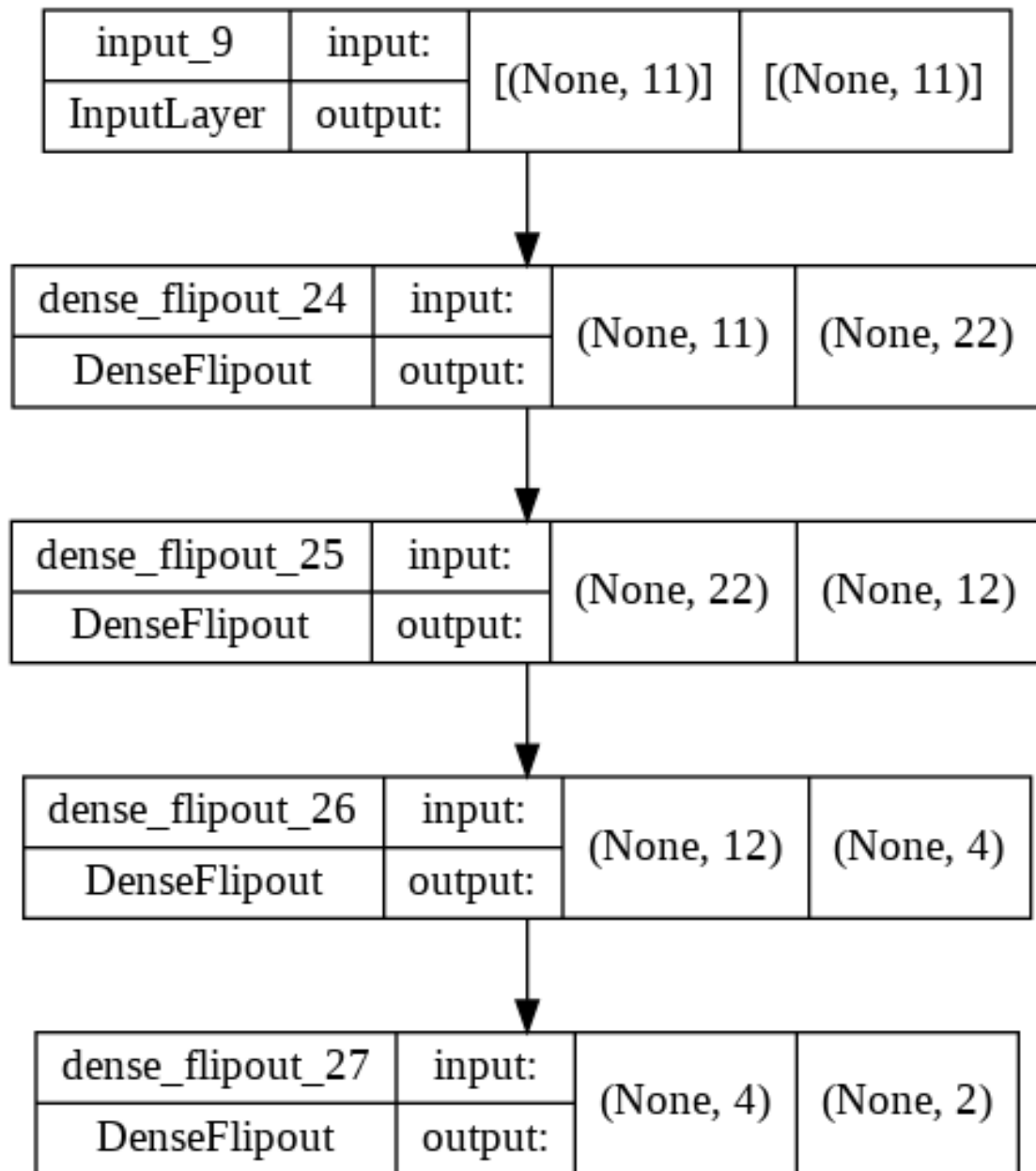


```
[[0.50020003 0.49979994]]
```

```
[ ]: plt.figure(figsize=(12,5))
plt.subplot(1,2,1)
plt.plot(history.history['accuracy'])
#plt.plot(history.history['val_accuracy'])
plt.title('model accuracy')
plt.ylabel('accuracy')
plt.xlabel('epoch')
plt.legend(['train', 'test'], loc='upper left')
plt.ylim(0, 1)
# summarize history for loss
plt.subplot(1,2,2)
plt.plot(history.history['loss'])
#plt.plot(history.history['val_loss'])
plt.title('model loss')
plt.ylabel('loss')
plt.xlabel('epoch')
plt.legend(['train', 'test'], loc='upper left')
plt.ylim(0, 1)
plt.show()
plot_model(normal_bnn2_model, to_file='model_plot.png', show_shapes=True,
→show_layer_names=True)
```



```
[ ]:
```



```
[ ]: normal_bnn2_model.save('normal_bnn2_model.h5')
normal_bnn2_model.save('saved_model/normal_bnn2_model')
```

INFO:tensorflow:Assets written to: saved_model/normal_bnn2_model/assets

2. BNN WITH DIFFERENT DROPOUT VALUES MC Dropout write description here!

```
[ ]: dist = tfp.distributions
dataset_size = len(X_train)
kl_divergence_function = (lambda q, p, _: dist.kl_divergence(q, p) / tf.
    ↳cast(dataset_size, dtype=tf.float32))

model_dropout_v1 = tf.keras.Sequential([
    tf.keras.Input(X_train.shape[1]),
    tfp.layers.DenseFlipout(14, kernel_divergence_fn=kl_divergence_function,↳
    ↳activation=tf.nn.relu),
    tf.keras.layers.Dropout(0.2),
    tfp.layers.DenseFlipout(6, kernel_divergence_fn=kl_divergence_function,↳
    ↳activation=tf.nn.relu ),
    tfp.layers.DenseFlipout(2, kernel_divergence_fn=kl_divergence_function,↳
    ↳activation=tf.nn.softmax),
])

learning_rate = 1e-06 #0.005
model_dropout_v1.compile(optimizer=tf.keras.optimizers.
    ↳Adam(learning_rate),loss='binary_crossentropy',metrics=['accuracy'])
```

```
/usr/local/lib/python3.7/dist-
packages/tensorflow_probability/python/layers/util.py:102: UserWarning:
`layer.add_variable` is deprecated and will be removed in a future version.
Please use `layer.add_weight` method instead.
    trainable=trainable)
/usr/local/lib/python3.7/dist-
packages/tensorflow_probability/python/layers/util.py:112: UserWarning:
`layer.add_variable` is deprecated and will be removed in a future version.
Please use `layer.add_weight` method instead.
    trainable=trainable)
```

```
[ ]: dist = tfp.distributions
dataset_size = len(X_train)
kl_divergence_function = (lambda q, p, _: dist.kl_divergence(q, p) / tf.
    ↳cast(dataset_size, dtype=tf.float32))

model_dropout_v2 = tf.keras.Sequential([
    tf.keras.Input(X_train.shape[1]),
    tfp.layers.DenseFlipout(14, kernel_divergence_fn=kl_divergence_function,↳
    ↳activation=tf.nn.relu),
    tf.keras.layers.Dropout(0.35),
    tfp.layers.DenseFlipout(6, kernel_divergence_fn=kl_divergence_function,↳
    ↳activation=tf.nn.relu ),
    tfp.layers.DenseFlipout(2, kernel_divergence_fn=kl_divergence_function,↳
    ↳activation=tf.nn.softmax),
])
```

```
learning_rate = 1e-06 #0.005
model_dropout_v2.compile(optimizer=tf.keras.optimizers.
    ↪Adam(learning_rate),loss='binary_crossentropy',metrics=['accuracy'])
```

```
/usr/local/lib/python3.7/dist-
packages/tensorflow_probability/python/layers/util.py:102: UserWarning:
`layer.add_variable` is deprecated and will be removed in a future version.
Please use `layer.add_weight` method instead.
    trainable=trainable)
/usr/local/lib/python3.7/dist-
packages/tensorflow_probability/python/layers/util.py:112: UserWarning:
`layer.add_variable` is deprecated and will be removed in a future version.
Please use `layer.add_weight` method instead.
    trainable=trainable)
```

```
[ ]: dist = tfp.distributions
dataset_size = len(X_train)
kl_divergence_function = (lambda q, p, _: dist.kl_divergence(q, p) / tf.
    ↪cast(dataset_size, dtype=tf.float32))

model_dropout_v3 = tf.keras.Sequential([
    tf.keras.Input(X_train.shape[1]),
    tfp.layers.DenseFlipout(14, kernel_divergence_fn=kl_divergence_function,
    ↪activation=tf.nn.relu),
    tf.keras.layers.Dropout(0.5),
    tfp.layers.DenseFlipout(6, kernel_divergence_fn=kl_divergence_function,
    ↪activation=tf.nn.relu ),
    tfp.layers.DenseFlipout(2, kernel_divergence_fn=kl_divergence_function,
    ↪activation=tf.nn.softmax),
])

learning_rate = 1e-06 #0.005
model_dropout_v3.compile(optimizer=tf.keras.optimizers.
    ↪Adam(learning_rate),loss='binary_crossentropy',metrics=['accuracy'])
```

```
/usr/local/lib/python3.7/dist-
packages/tensorflow_probability/python/layers/util.py:102: UserWarning:
`layer.add_variable` is deprecated and will be removed in a future version.
Please use `layer.add_weight` method instead.
    trainable=trainable)
/usr/local/lib/python3.7/dist-
packages/tensorflow_probability/python/layers/util.py:112: UserWarning:
`layer.add_variable` is deprecated and will be removed in a future version.
Please use `layer.add_weight` method instead.
    trainable=trainable)
```

```

[ ]: from sklearn.metrics import classification_report

models = [normal_bnn_model, normal_bnn2_model, model_dropout_v1,
          ↪ model_dropout_v2, model_dropout_v3]

models_acc = []
models_loss = []
i = 1
for p_model in models:
    #history = p_model.fit(X_train, y_train,
    ↪ epochs=40)#, batch_size=1, validation_data = (np.asarray(X_test), np.
    ↪ asarray(y_test)), verbose=0)
    history = p_model.fit(np.asarray(X_train), np.asarray(y_train), epochs=40,
    ↪ batch_size=1, validation_data = (np.asarray(X_test), np.
    ↪ asarray(y_test)), verbose=0)
    #history = normal_bnn_model.fit(np.asarray(X_train), np.
    ↪ asarray(y_train), epochs=100, batch_size=1, validation_data = (np.
    ↪ asarray(X_test), np.asarray(y_test)), verbose=0)
    test_loss, test_acc = p_model.evaluate(X_test, y_test)
    y_pred = p_model.predict(X_test)
    print('\nTest accuracy:', test_acc)
    print('\nTest loss:', test_loss)
    models_acc.append(test_acc)
    models_loss.append(test_loss)
    #history = normal_bnn_model.fit(np.asarray(X_train), np.
    ↪ asarray(y_train), epochs=100, batch_size=1, verbose=0)
    # to see history:
    # list all data in history
    print(history.history.keys())
    p_model.save('%s.h5' % ('p_model'+' '+str(i)))
    p_model.save('saved_model/%s' % ('p_model'+' '+str(i)))
    i = i+1
    # summarize history for accuracy
    plt.figure(figsize=(12,5))
    plt.subplot(1,2,1)
    plt.plot(history.history['accuracy'])
    #plt.plot(history.history['val_accuracy'])
    plt.title('model accuracy')
    plt.ylabel('accuracy')
    plt.xlabel('epoch')
    plt.legend(['train', 'test'], loc='upper left')
    plt.ylim(0, 1)
    # summarize history for loss
    plt.subplot(1,2,2)
    plt.plot(history.history['loss'])
    #plt.plot(history.history['val_loss'])
    plt.title('model loss')

```

```

plt.ylabel('loss')
plt.xlabel('epoch')
plt.legend(['train', 'test'], loc='upper left')
plt.ylim(0, 1)
plt.show()
plot_model(p_model, to_file='model_plotss.png', show_shapes=True,
→show_layer_names=True)
'''index = 0
for i in y_pred:
    if i<0.5:
        y_pred[index] = 0
    else:
        y_pred[index] = 1

print(classification_report(y_test, y_pred))'''

```

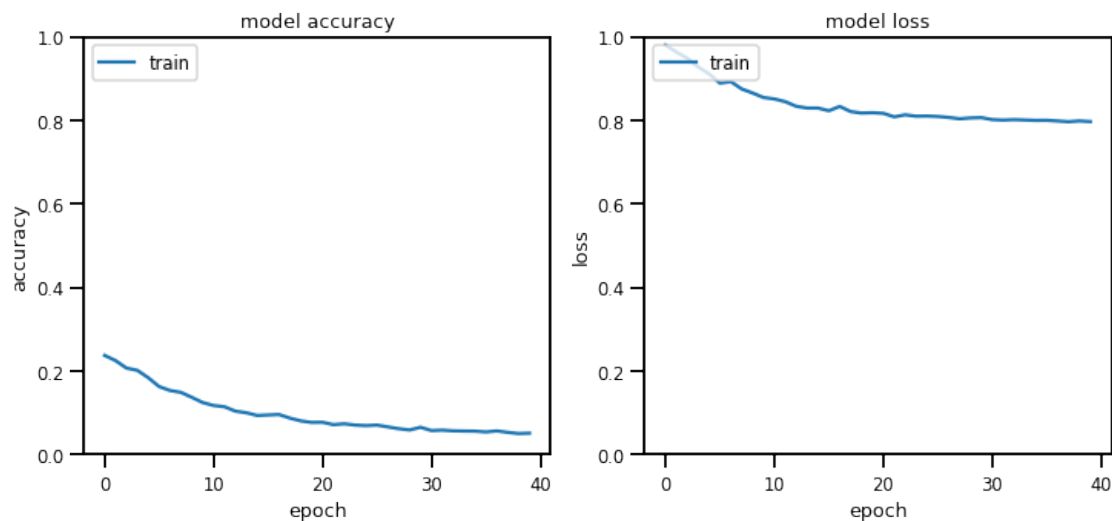
94/94 [=====] - 0s 2ms/step - loss: 0.7981 - accuracy: 0.0460

Test accuracy: 0.04600000008940697

Test loss: 0.7980939149856567

dict_keys(['loss', 'accuracy', 'val_loss', 'val_accuracy'])

INFO:tensorflow:Assets written to: saved_model/p_model 1/assets



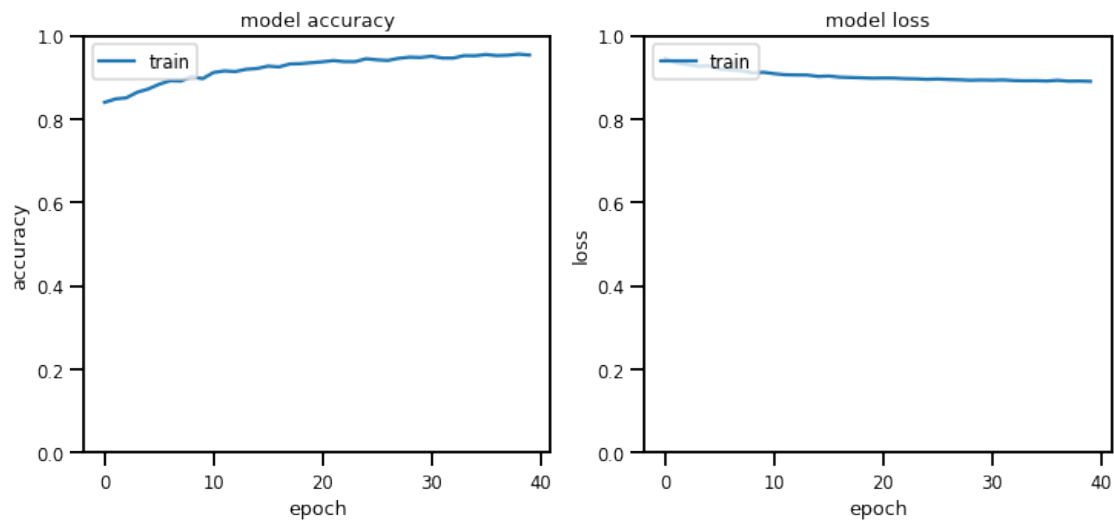
94/94 [=====] - 0s 3ms/step - loss: 0.8895 - accuracy: 0.9600

Test accuracy: 0.9599999785423279

Test loss: 0.8895038366317749

dict_keys(['loss', 'accuracy', 'val_loss', 'val_accuracy'])

INFO:tensorflow:Assets written to: saved_model/p_model 2/assets



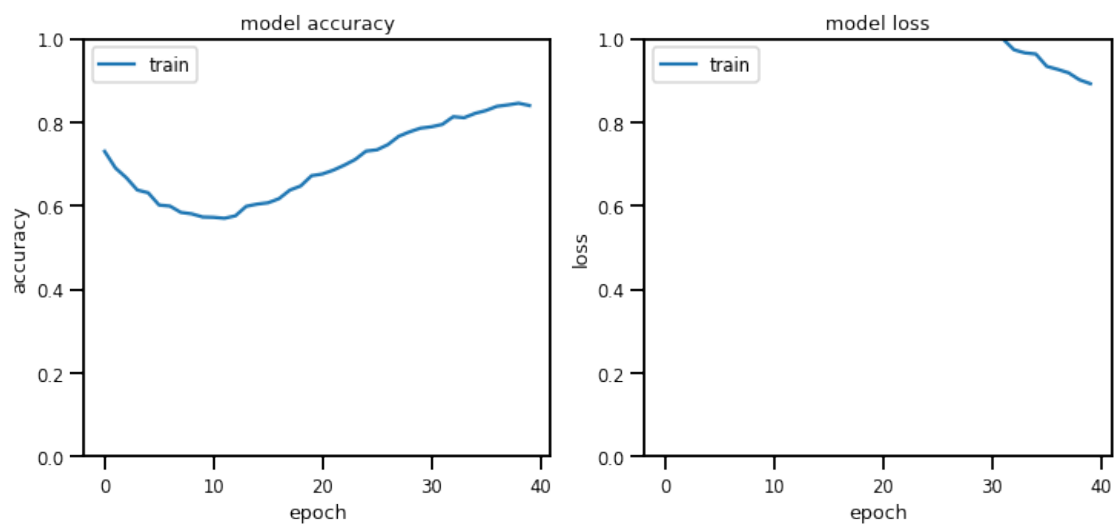
94/94 [=====] - 1s 2ms/step - loss: 0.7902 - accuracy: 0.9357

Test accuracy: 0.9356666803359985

Test loss: 0.7901726961135864

dict_keys(['loss', 'accuracy', 'val_loss', 'val_accuracy'])

INFO:tensorflow:Assets written to: saved_model/p_model 3/assets



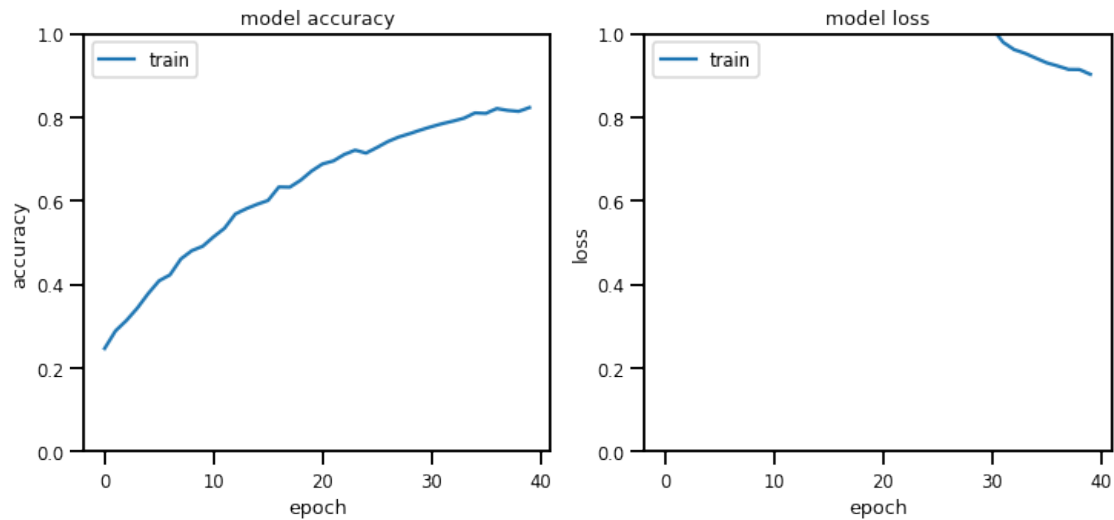
94/94 [=====] - 1s 3ms/step - loss: 0.7885 - accuracy: 0.9517

Test accuracy: 0.951666531562805

Test loss: 0.7884607911109924

dict_keys(['loss', 'accuracy', 'val_loss', 'val_accuracy'])

INFO:tensorflow:Assets written to: saved_model/p_model 4/assets



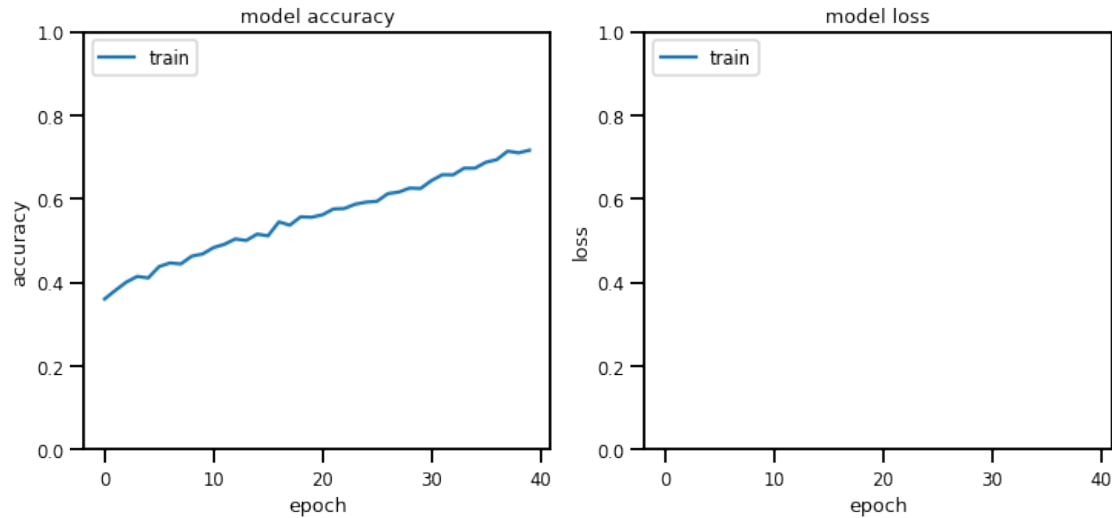
94/94 [=====] - 1s 2ms/step - loss: 0.8642 - accuracy: 0.8343

Test accuracy: 0.8343333601951599

Test loss: 0.8642163276672363

dict_keys(['loss', 'accuracy', 'val_loss', 'val_accuracy'])

INFO:tensorflow:Assets written to: saved_model/p_model 5/assets



```
[ ]: print(models_acc)
      print(models_loss)
```

```
[0.04600000008940697, 0.9599999785423279, 0.9356666803359985,
0.9516666531562805, 0.8343333601951599]
[0.7980939149856567, 0.8895038366317749, 0.7901726961135864, 0.7884607911109924,
0.8642163276672363]
```

3. BNN WITH DIFFERENT EARLY STOPS

```
[ ]: callback = tf.keras.callbacks.EarlyStopping(monitor='loss', patience=3)

#callbacks=[callback]
dist = tfp.distributions
dataset_size = len(X_train)
kl_divergence_function = (lambda q, p, _: dist.kl_divergence(q, p) / tf.
    ↳ cast(dataset_size, dtype=tf.float32))

model_callback_v1 = tf.keras.Sequential([
    tf.keras.Input(X_train.shape[1]),
    tfp.layers.DenseFlipout(14, kernel_divergence_fn=kl_divergence_function,
    ↳ activation=tf.nn.relu),
    #tf.keras.layers.Dropout(0.5)
    tfp.layers.DenseFlipout(6, kernel_divergence_fn=kl_divergence_function,
    ↳ activation=tf.nn.relu),
    tfp.layers.DenseFlipout(2, kernel_divergence_fn=kl_divergence_function,
    ↳ activation=tf.nn.softmax),
])
```

```

learning_rate = 0.005 #1e-06 #
model_callback_v1.compile(optimizer=tf.keras.optimizers.
    ↳Adam(learning_rate),loss='binary_crossentropy',metrics=['accuracy'])
history = model_callback_v1.fit(np.asarray(X_train), np.
    ↳asarray(y_train),epochs=50, batch_size=1,↳
    ↳callbacks=[callback],validation_data = (np.asarray(X_test), np.
    ↳asarray(y_test)),verbose=0)
len(history.history['loss'])

#model_tfp_v2.fit(X_train, y_train, epochs=80)
test_loss, test_acc = model_callback_v1.evaluate(X_test, y_test)
print('\nTest accuracy:', test_acc)
print('\nTest loss:', test_loss)

model_callback_v1.summary()

```

```

/usr/local/lib/python3.7/dist-
packages/tensorflow_probability/python/layers/util.py:102: UserWarning:
`layer.add_variable` is deprecated and will be removed in a future version.
Please use `layer.add_weight` method instead.
    trainable=trainable)

```

```

/usr/local/lib/python3.7/dist-
packages/tensorflow_probability/python/layers/util.py:112: UserWarning:
`layer.add_variable` is deprecated and will be removed in a future version.
Please use `layer.add_weight` method instead.
    trainable=trainable)

```

```

94/94 [=====] - 1s 2ms/step - loss: 1.0252 - accuracy:
0.9477

```

Test accuracy: 0.9476666450500488

Test loss: 1.0251801013946533

Model: "sequential_9"

Layer (type)	Output Shape	Param #
dense_flipout_21 (DenseFlip out)	(None, 14)	322
dense_flipout_22 (DenseFlip out)	(None, 6)	174
dense_flipout_23 (DenseFlip out)	(None, 2)	26

Total params: 522

Trainable params: 522
Non-trainable params: 0

```
[ ]: callback = tf.keras.callbacks.EarlyStopping(monitor='loss', patience=4)

#callbacks=[callback]
dist = tfp.distributions
dataset_size = len(X_train)
kl_divergence_function = (lambda q, p, _: dist.kl_divergence(q, p) / tf.
    ↳cast(dataset_size, dtype=tf.float32))

model_callback_v2 = tf.keras.Sequential([
    tf.keras.Input(X_train.shape[1]),
    tfp.layers.DenseFlipout(14, kernel_divergence_fn=kl_divergence_function,
    ↳activation=tf.nn.relu),
    #tf.keras.layers.Dropout(0.5)
    tfp.layers.DenseFlipout(6, kernel_divergence_fn=kl_divergence_function,
    ↳activation=tf.nn.relu ),
    tfp.layers.DenseFlipout(2, kernel_divergence_fn=kl_divergence_function,
    ↳activation=tf.nn.softmax),
])

learning_rate = 0.005 #1e-06 #
model_callback_v2.compile(optimizer=tf.keras.optimizers.
    ↳Adam(learning_rate),loss='binary_crossentropy',metrics=['accuracy'])
history = model_callback_v2.fit(np.asarray(X_train), np.
    ↳asarray(y_train),epochs=10, batch_size=1,
    ↳callbacks=[callback],validation_data = (np.asarray(X_test), np.
    ↳asarray(y_test)),verbose=0)
len(history.history['loss'])

test_loss, test_acc = model_callback_v2.evaluate(X_test, y_test)
print('\nTest accuracy:', test_acc)
print('\nTest loss:', test_loss)
model_callback_v2.summary()
```

```
/usr/local/lib/python3.7/dist-
packages/tensorflow_probability/python/layers/util.py:102: UserWarning:
`layer.add_variable` is deprecated and will be removed in a future version.
Please use `layer.add_weight` method instead.
    trainable=trainable)
/usr/local/lib/python3.7/dist-
packages/tensorflow_probability/python/layers/util.py:112: UserWarning:
`layer.add_variable` is deprecated and will be removed in a future version.
Please use `layer.add_weight` method instead.
    trainable=trainable)
```

94/94 [=====] - 1s 3ms/step - loss: 0.7097 - accuracy: 0.9680

Test accuracy: 0.9679999947547913

Test loss: 0.7096814513206482

Model: "sequential_10"

Layer (type)	Output Shape	Param #
dense_flipout_24 (DenseFlipout)	(None, 14)	322
dense_flipout_25 (DenseFlipout)	(None, 6)	174
dense_flipout_26 (DenseFlipout)	(None, 2)	26

=====
Total params: 522
Trainable params: 522
Non-trainable params: 0
=====

```
[ ]: callback = tf.keras.callbacks.EarlyStopping(monitor='loss', patience=2)

#callbacks=[callback]
dist = tfp.distributions
dataset_size = len(X_train)
kl_divergence_function = (lambda q, p, _: dist.kl_divergence(q, p) / tf.
    ↳ cast(dataset_size, dtype=tf.float32))

model_callback_v3 = tf.keras.Sequential([
    tf.keras.Input(X_train.shape[1]),
    tfp.layers.DenseFlipout(14, kernel_divergence_fn=kl_divergence_function,
    ↳ activation=tf.nn.relu),
    #tf.keras.layers.Dropout(0.5)
    tfp.layers.DenseFlipout(6, kernel_divergence_fn=kl_divergence_function,
    ↳ activation=tf.nn.relu),
    tfp.layers.DenseFlipout(2, kernel_divergence_fn=kl_divergence_function,
    ↳ activation=tf.nn.softmax),
])

learning_rate = 0.005 #1e-06 #
model_callback_v3.compile(optimizer=tf.keras.optimizers.
    ↳ Adam(learning_rate), loss='binary_crossentropy', metrics=['accuracy'])
```

```

history = model_callback_v3.fit(np.asarray(X_train), np.
    ↳asarray(y_train), epochs=10, batch_size=1,
    ↳callbacks=[callback], validation_data = (np.asarray(X_test), np.
    ↳asarray(y_test)), verbose=0)
len(history.history['loss'])

test_loss, test_acc = model_callback_v3.evaluate(X_test, y_test)
print('\nTest accuracy:', test_acc)
print('\nTest loss:', test_loss)
model_callback_v3.summary()

```

```

/usr/local/lib/python3.7/dist-
packages/tensorflow_probability/python/layers/util.py:102: UserWarning:
`layer.add_variable` is deprecated and will be removed in a future version.
Please use `layer.add_weight` method instead.
    trainable=trainable)

```

```

/usr/local/lib/python3.7/dist-
packages/tensorflow_probability/python/layers/util.py:112: UserWarning:
`layer.add_variable` is deprecated and will be removed in a future version.
Please use `layer.add_weight` method instead.
    trainable=trainable)

```

```

94/94 [=====] - 1s 3ms/step - loss: 0.8335 - accuracy:
0.9577

```

Test accuracy: 0.9576666951179504

Test loss: 0.8335036039352417

Model: "sequential_12"

Layer (type)	Output Shape	Param #
dense_flipout_30 (DenseFlip out)	(None, 14)	322
dense_flipout_31 (DenseFlip out)	(None, 6)	174
dense_flipout_32 (DenseFlip out)	(None, 2)	26

=====
 Total params: 522
 Trainable params: 522
 Non-trainable params: 0

```

[ ]: from sklearn.metrics import classification_report

models = [normal_bnn_model, normal_bnn2_model, model_callback_v1,
          ↪ model_callback_v2, model_callback_v3]

models_acc = []
models_loss = []
i = 6
for p_model in models:
    #history = p_model.fit(X_train, y_train,
    ↪ epochs=40)#, batch_size=1, validation_data = (np.asarray(X_test), np.
    ↪ asarray(y_test)), verbose=0)

    history = p_model.fit(np.asarray(X_train), np.asarray(y_train), epochs=50,
    ↪ batch_size=1, validation_data = (np.asarray(X_test), np.
    ↪ asarray(y_test)), verbose=0)

    #history = normal_bnn_model.fit(np.asarray(X_train), np.
    ↪ asarray(y_train), epochs=100, batch_size=1, validation_data = (np.
    ↪ asarray(X_test), np.asarray(y_test)), verbose=0)

    test_loss, test_acc = p_model.evaluate(X_test, y_test)
    y_pred = p_model.predict(X_test)
    print('\nTest accuracy:', test_acc)
    print('\nTest loss:', test_loss)
    models_acc.append(test_acc)
    models_loss.append(test_loss)

    #history = normal_bnn_model.fit(np.asarray(X_train), np.
    ↪ asarray(y_train), epochs=100, batch_size=1, verbose=0)

    # to see history:
    # list all data in history
    print(history.history.keys())
    p_model.save('%s.h5' % ('callp_model' + ' ' + str(i)))
    p_model.save('saved_model/%s' % ('callp_model' + ' ' + str(i)))
    i = i+1

    # summarize history for accuracy
    plt.figure(figsize=(12,5))
    plt.subplot(1,2,1)
    plt.plot(history.history['accuracy'])
    #plt.plot(history.history['val_accuracy'])
    plt.title('model accuracy')
    plt.ylabel('accuracy')
    plt.xlabel('epoch')
    plt.legend(['train', 'test'], loc='upper left')
    plt.ylim(0, 1)

    # summarize history for loss
    plt.subplot(1,2,2)
    plt.plot(history.history['loss'])
    #plt.plot(history.history['val_loss'])
    plt.title('model loss')

```

```

plt.ylabel('loss')
plt.xlabel('epoch')
plt.legend(['train', 'test'], loc='upper left')
plt.ylim(0, 1)
plt.show()
plot_model(p_model, to_file='model_plotsss.png', show_shapes=True,
→show_layer_names=True)
'''index = 0
for i in y_pred:
    if i<0.5:
        y_pred[index] = 0
    else:
        y_pred[index] = 1

print(classification_report(y_test, y_pred))'''

```

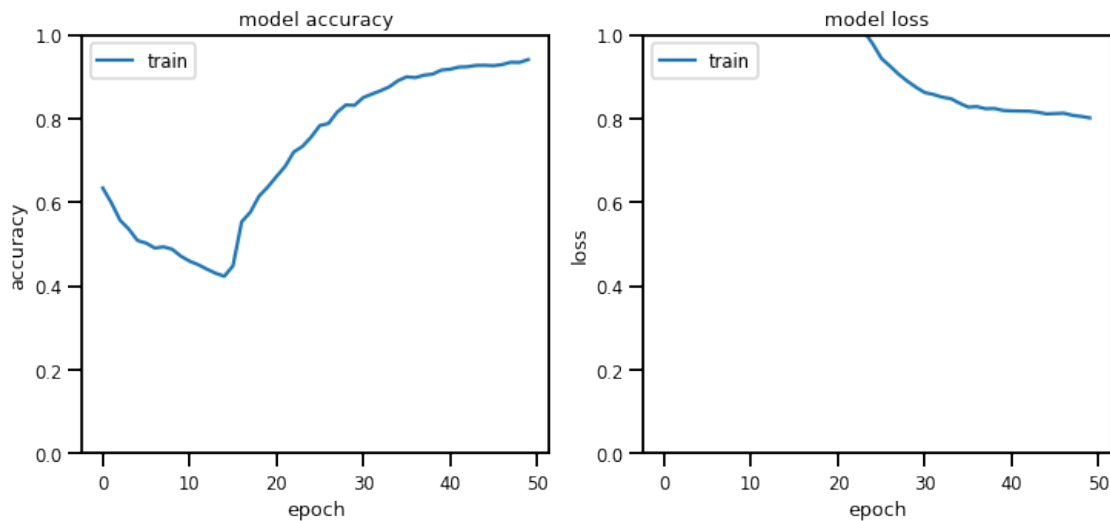
94/94 [=====] - 1s 3ms/step - loss: 0.8025 - accuracy: 0.9410

Test accuracy: 0.9409999847412109

Test loss: 0.8024592399597168

dict_keys(['loss', 'accuracy', 'val_loss', 'val_accuracy'])

INFO:tensorflow:Assets written to: saved_model/callp_model 6/assets



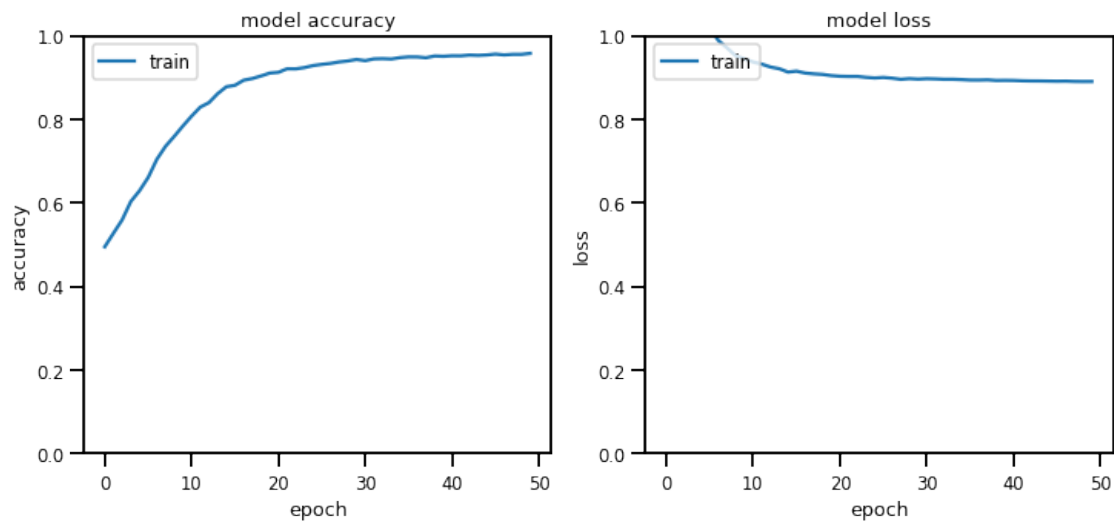
94/94 [=====] - 1s 3ms/step - loss: 0.8896 - accuracy: 0.9630

Test accuracy: 0.9629999995231628

Test loss: 0.8896040320396423

dict_keys(['loss', 'accuracy', 'val_loss', 'val_accuracy'])

INFO:tensorflow:Assets written to: saved_model/callp_model 7/assets



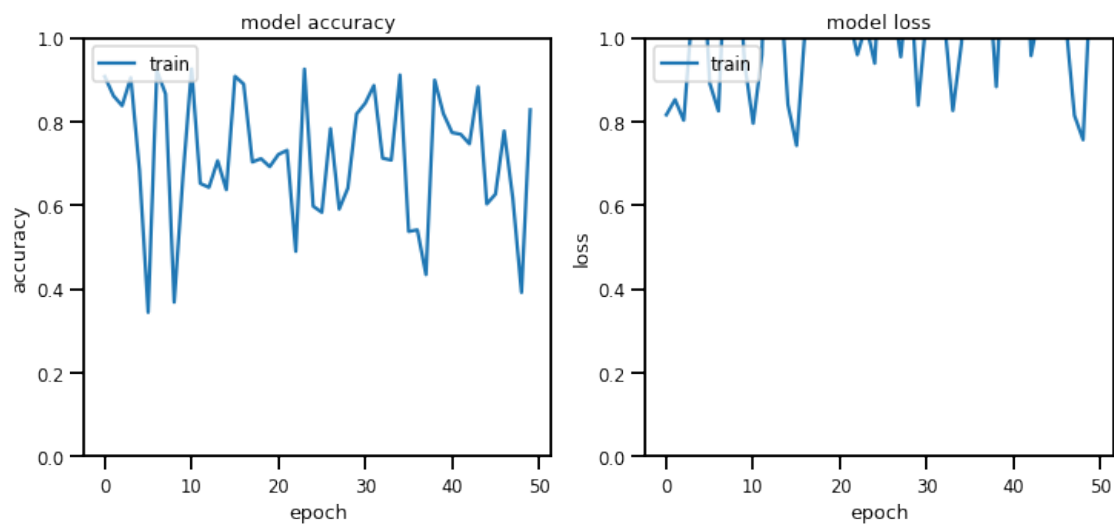
94/94 [=====] - 0s 3ms/step - loss: 1.3953 - accuracy: 0.9347

Test accuracy: 0.9346666932106018

Test loss: 1.3952935934066772

dict_keys(['loss', 'accuracy', 'val_loss', 'val_accuracy'])

INFO:tensorflow:Assets written to: saved_model/callp_model 8/assets



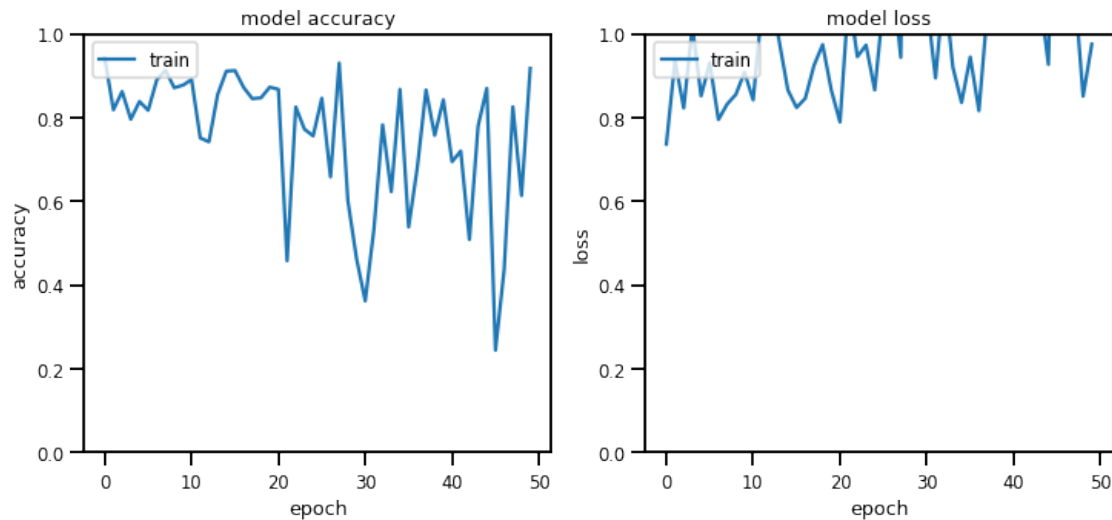
94/94 [=====] - 0s 4ms/step - loss: 1.0007 - accuracy: 0.9483

Test accuracy: 0.948333230018616

Test loss: 1.0007153749465942

dict_keys(['loss', 'accuracy', 'val_loss', 'val_accuracy'])

INFO:tensorflow:Assets written to: saved_model/callp_model 9/assets



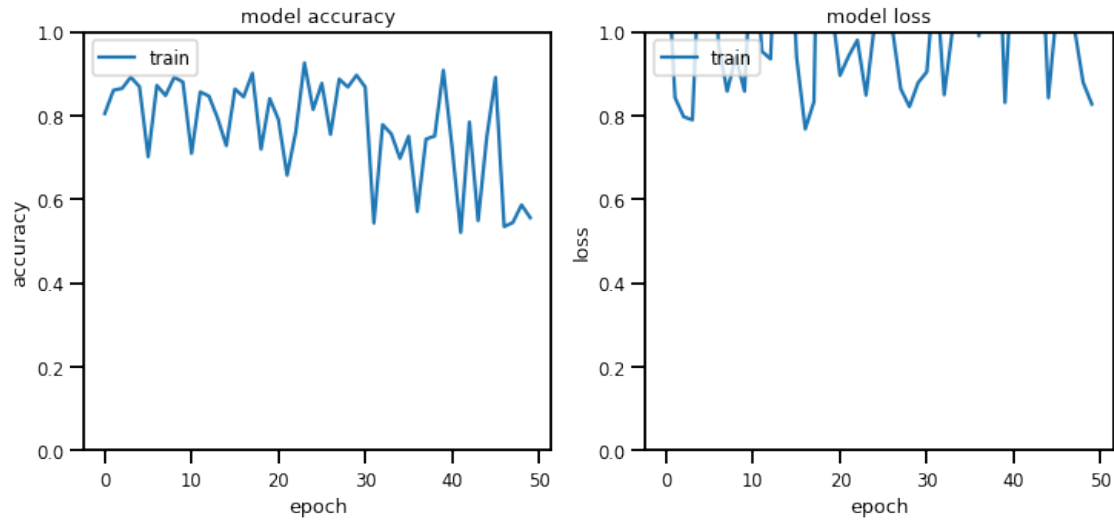
94/94 [=====] - 0s 3ms/step - loss: 0.7728 - accuracy: 0.9640

Test accuracy: 0.9639999866485596

Test loss: 0.7727773189544678

dict_keys(['loss', 'accuracy', 'val_loss', 'val_accuracy'])

INFO:tensorflow:Assets written to: saved_model/callp_model 10/assets



```
[ ]: #BNN WITH DIFFERENT REGULARIZERS TRANSFORMERS
      # MIXING OF THE ABOVE VARIANTS AND COMPARING WITH THE NORMAL ANN
```

w and b site streamlit for gui

```
[ ]:
```

0.0.4 WEEKLY OUTPUT PDFS

convert notebook to pdf for weekly progrss submission

```
[ ]:
```

```
[ ]: %cd /content/drive/MyDrive/Colab Notebooks/MTP
```

```
!pwd
```

```
!ls
```

```
/content/drive/MyDrive/Colab Notebooks/MTP
/content/drive/MyDrive/Colab Notebooks/MTP
3rd_sem1.pdf          dec.pdf
3rd_sem.pdf           material
4th_sem_FINAL_may.pdf models.zip
4th_sem_MARCH.pdf     model_tfp1v1.pkl
4th_sem_mid_FINAL_all.pdf model_tfp_v1.h5
4th_sem_mid_FINAL_all.pdf MTP_BNN.ipynb
4th_sem_mid_FINAL.pdf MTP_BNN.pdf
4th_sem_mid.pdf       MTP_Data_Visualization.ipynb
4th_sem_mid_plots.pdf 'p-2 mid'
```

4th_sem_mid_plots_sir.pdf	READ.md
4th_sem.pdf	README.md
'Copy of 4th_sem_mid.pdf'	saved_model
'Copy of 4th_sem_mid_plots.pdf'	w1.pdf
'Copy of 4th_sem_mid_plots_sir.pdf'	w2.pdf
datasets	'web app'

```
[ ]: !sudo apt-get install texlive-xetex texlive-fonts-recommended
      ↳texlive-generic-recommended
```

```
[ ]: !jupyter nbconvert --to pdf --output "4th_sem_FINAL_Present" MTP_BNN.ipynb
```

```
[ ]:
```

```
[ ]:
```

```
[ ]: # should have saved plots as files for download
```

```
[ ]: from google.colab import files
      !zip -r /content/models.zip /content/saved_model
      files.download("/content/models.zip")
      !zip -r /content/contenth5.zip /content/*.h5
      files.download("/content/contenth5.zip")
      !zip -r /content/contentpng.zip /content/*.png
      files.download("/content/contentpng.zip")
```

```

adding: content/saved_model/ (stored 0%)
adding: content/saved_model/callp_model 6/ (stored 0%)
adding: content/saved_model/callp_model 6/variables/ (stored 0%)
adding: content/saved_model/callp_model
6/variables/variables.data-00000-of-00001 (deflated 48%)
adding: content/saved_model/callp_model 6/variables/variables.index (deflated
68%)
adding: content/saved_model/callp_model 6/saved_model.pb (deflated 92%)
adding: content/saved_model/callp_model 6/assets/ (stored 0%)
adding: content/saved_model/callp_model 6/keras_metadata.pb (deflated 94%)
adding: content/saved_model/model_tfp_v2/ (stored 0%)
adding: content/saved_model/model_tfp_v2/variables/ (stored 0%)
adding:
content/saved_model/model_tfp_v2/variables/variables.data-00000-of-00001
(deflated 54%)
adding: content/saved_model/model_tfp_v2/variables/variables.index (deflated
68%)
adding: content/saved_model/model_tfp_v2/saved_model.pb (deflated 92%)
adding: content/saved_model/model_tfp_v2/assets/ (stored 0%)
adding: content/saved_model/model_tfp_v2/keras_metadata.pb (deflated 94%)
adding: content/saved_model/callp_model 9/ (stored 0%)

```

```

    adding: content/saved_model/callp_model 9/variables/ (stored 0%)
    adding: content/saved_model/callp_model
9/variables/variables.data-00000-of-00001 (deflated 57%)
    adding: content/saved_model/callp_model 9/variables/variables.index (deflated
68%)
    adding: content/saved_model/callp_model 9/saved_model.pb (deflated 92%)
    adding: content/saved_model/callp_model 9/assets/ (stored 0%)
    adding: content/saved_model/callp_model 9/keras_metadata.pb (deflated 94%)
    adding: content/saved_model/callp_model 10/ (stored 0%)
    adding: content/saved_model/callp_model 10/variables/ (stored 0%)
    adding: content/saved_model/callp_model
10/variables/variables.data-00000-of-00001 (deflated 56%)
    adding: content/saved_model/callp_model 10/variables/variables.index (deflated
68%)
    adding: content/saved_model/callp_model 10/saved_model.pb (deflated 92%)
    adding: content/saved_model/callp_model 10/assets/ (stored 0%)
    adding: content/saved_model/callp_model 10/keras_metadata.pb (deflated 94%)
    adding: content/saved_model/model_tfp_v1/ (stored 0%)
    adding: content/saved_model/model_tfp_v1/variables/ (stored 0%)
    adding:
content/saved_model/model_tfp_v1/variables/variables.data-00000-of-00001
(deflated 53%)
    adding: content/saved_model/model_tfp_v1/variables/variables.index (deflated
68%)
    adding: content/saved_model/model_tfp_v1/saved_model.pb (deflated 92%)
    adding: content/saved_model/model_tfp_v1/assets/ (stored 0%)
    adding: content/saved_model/model_tfp_v1/keras_metadata.pb (deflated 94%)
    adding: content/saved_model/callp_model 7/ (stored 0%)
    adding: content/saved_model/callp_model 7/variables/ (stored 0%)
    adding: content/saved_model/callp_model
7/variables/variables.data-00000-of-00001 (deflated 41%)
    adding: content/saved_model/callp_model 7/variables/variables.index (deflated
70%)
    adding: content/saved_model/callp_model 7/saved_model.pb (deflated 92%)
    adding: content/saved_model/callp_model 7/assets/ (stored 0%)
    adding: content/saved_model/callp_model 7/keras_metadata.pb (deflated 95%)
    adding: content/saved_model/callp_model 8/ (stored 0%)
    adding: content/saved_model/callp_model 8/variables/ (stored 0%)
    adding: content/saved_model/callp_model
8/variables/variables.data-00000-of-00001 (deflated 56%)
    adding: content/saved_model/callp_model 8/variables/variables.index (deflated
68%)
    adding: content/saved_model/callp_model 8/saved_model.pb (deflated 92%)
    adding: content/saved_model/callp_model 8/assets/ (stored 0%)
    adding: content/saved_model/callp_model 8/keras_metadata.pb (deflated 94%)
<IPython.core.display.Javascript object>

```

<IPython.core.display.Javascript object>

```
adding: content/callp_model 10.h5 (deflated 86%)
adding: content/callp_model 6.h5 (deflated 84%)
adding: content/callp_model 7.h5 (deflated 82%)
adding: content/callp_model 8.h5 (deflated 86%)
adding: content/callp_model 9.h5 (deflated 87%)
adding: content/model_tfp_v1.h5 (deflated 86%)
adding: content/model_tfp_v2.h5 (deflated 86%)
```

<IPython.core.display.Javascript object>

<IPython.core.display.Javascript object>

```
adding: content/model_plot1.png (deflated 13%)
adding: content/model_plot.png (deflated 15%)
adding: content/model_plotsss.png (deflated 13%)
```

<IPython.core.display.Javascript object>

<IPython.core.display.Javascript object>

comparison of models.

```
[ ]: from bokeh.plotting import figure, output_file, show
```

```
[ ]: # normal vs dropout
    '''import numpy as np
    import matplotlib.pyplot as plt

    train_loss = [0.4377, 0.7227, 0.7029, 0.7039, 0.7060]
    train_accuracy = [0.9687, 0.9693, 0.9690, 0.0313, 0.9687]
    test_accuracy = [0.968666672706604, 0.9693333506584167, 0.968999981880188, 0.
        ↳ 03133333474397659, 0.968666672706604]
    test_loss = [0.43769827485084534, 0.7226769924163818, 0.7028810977935791, 0.
        ↳ 703898012638092, 0.7059929370880127]
    labels = ['normal_bnn1', 'normal_bnn1', 'dropout_1', 'dropout_2', 'dropout_3' ]

    plot_df = pd.DataFrame({"train_loss":train_loss,"train_accuracy":
        ↳ train_accuracy,"test_accuracy":test_accuracy,"test_loss":test_loss})

    #plot_df['train_loss'] = train_loss
    #plot_df['train_accuracy'] = train_accuracy
    #plot_df['test_accuracy'] = test_accuracy
    #plot_df['test_loss'] = test_loss
```

```

plot_df.plot_bokeh(kind='bar',x = train_accuracy,title = "ta")
plt.bar([train_loss,train_accuracy,test_loss,test_accuracy],labels)

plt.xlabel("models")
plt.ylabel("parameters")
plt.title("normal bnn models vs dropout bnn models")
plt.show()'''

```

```

[ ]: 'import numpy as np\nimport matplotlib.pyplot as plt\n\ntrain_loss = [0.4377,
0.7227, 0.7029, 0.7039, 0.7060]\ntrain_accuracy = [0.9687, 0.9693, 0.9690 ,
0.0313, 0.9687]\ntest_accuracy = [0.968666672706604,0.9693333506584167
,0.968999981880188 ,0.03133333474397659 ,0.968666672706604]\ntest_loss =
[0.43769827485084534, 0.7226769924163818,0.7028810977935791, 0.703898012638092,
0.7059929370880127]\nlabels = [\n'normal_bnn1'\n,\n'normal_bnn1'\n,\n'dropout_1'\n,
\ndropout_2'\n,\n'dropout_3'\n]\n\nplot_df = pd.DataFrame({"train_loss":train_lo
s,"train_accuracy":train_accuracy,"test_accuracy":test_accuracy,"test_loss":test
_loss})\n\n#plot_df[\n'train_loss\n'] = train_loss\n#plot_df[\n'train_accuracy\n'] =
train_accuracy\n#plot_df[\n'test_accuracy\n'] =
test_accuracy\n#plot_df[\n'test_loss\n'] =
test_loss\n\nplot_df.plot_bokeh(kind=\n'bar\n',x = train_accuracy,title = "ta")\nnp
lt.bar([train_loss,train_accuracy,test_loss,test_accuracy],labels)\n\nplt.xlabel
("models")\nplt.ylabel("parameters")\nplt.title("normal bnn models vs dropout
bnn models")\nplt.show()'

```

Normal BNN -1: 3 - layers, epochs = 25, learning rate = 1e-06, Accuracy: 0.86233
Normal BNN -2: 4 - layers, epochs = 15, learning rate = 1e-06, Accuracy: 0.91799
Normal BNN -1: 3 - layers, epochs = 40, learning rate = 1e-06, Accuracy: 0.96866
Normal BNN -2: 4 - layers, epochs = 40, learning rate = 1e-06, Accuracy: 0.95999
Normal BNN -1: 3 - layers, epochs = 50, learning rate = 1e-06, Accuracy: 0.94099
Normal BNN -2: 4 - layers, epochs = 50, learning rate = 1e-06, Accuracy: 0.96299
Model_tfp_v1: 3 - layers, epochs = 40, learning rate = 0.002, Accuracy: 0.96899
Model_tfp_v2: 3 - layers, epochs = 80, learning rate = 0.005, Accuracy: 0.96666

```

[31]: import numpy as np
import pandas as pd
import matplotlib.pyplot as plt

epoch_list = [25,15,40,40,50,50,40,80]
accuracy = [0.86233,0.91799,0.96866,0.95999,0.94099,0.96299,0.96899,0.96666]
#for i in [0,len(accuracy)-1]:
#    accuracy[i] = (accuracy[i]*100)
learning_rates = []

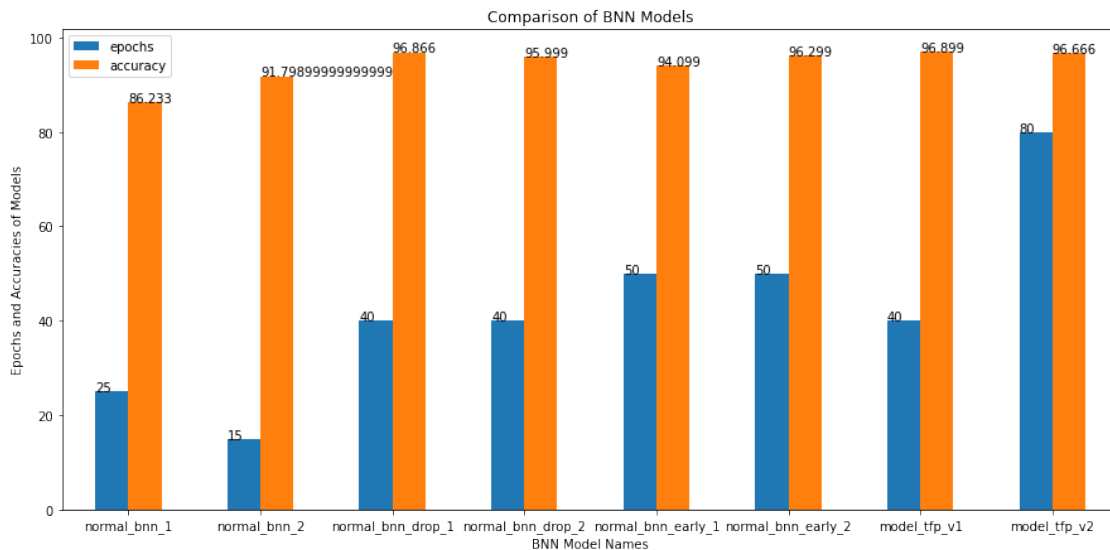
```

```

labels = [
    'normal_bnn_1', 'normal_bnn_2', 'normal_bnn_drop_1', 'normal_bnn_drop_2', 'normal_bnn_early_1'
]
plt.figure(figsize = (15, 5))
df = pd.DataFrame({'epochs': epoch_list, 'accuracy': accuracy}, index = labels)
df['accuracy'] = df['accuracy'] * 100
ax = df.plot.bar(rot=0, figsize=(15,7), title="Comparison of BNN Models")
ax.set_xlabel("BNN Model Names")
ax.set_ylabel("Epochs and Accuracies of Models")

for p in ax.patches:
    ax.annotate(str(p.get_height()), (p.get_x() * 1, p.get_height() * 1))
plt.figure(figsize = (15, 5))
plt.bar(labels, accuracy)
plt.title("Comparison of BNN Models")
plt.xlabel("BNN Model Names")
plt.ylabel("Accuracies of Models")

```



Monte Carlo - Dropout: learning rate = 1e-06, epochs=40

Dropout 1 : dropout value = 0.2, Accuracy: 0.93566

Dropout 2 : dropout value = 0.35, Accuracy: 0.95166

Dropout 3 : dropout value = 0.5, Accuracy: 0.83433

Normal BNN -1: 3 - layers, epochs = 40, learning rate = 1e-06, Accuracy: 0.96866

Normal BNN -2: 4 - layers, epochs = 40, learning rate = 1e-06, Accuracy: 0.95999

```

[30]: import numpy as np
import matplotlib.pyplot as plt

```

```

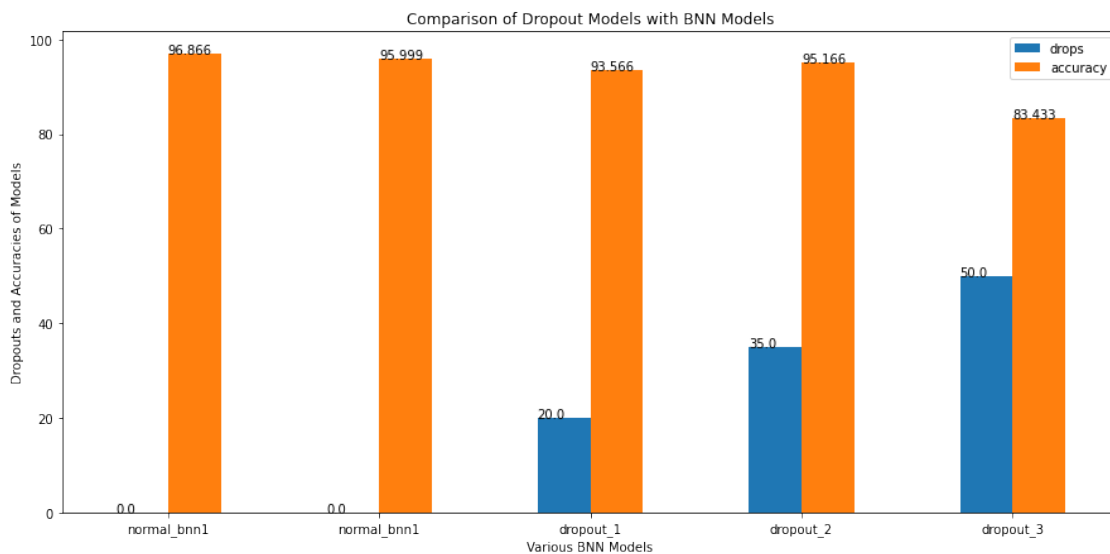
#train_loss = [0.4377, 0.7227, 0.7029, 0.7039, 0.7060]
#train_accuracy = [0.93, 0.9, 0.9690 , 0.0313, 0.9687]
test_accuracy = [0.96866,0.95999 ,0.93566 ,0.95166 ,0.83433]
dropout_rates = [0,0,0.2,0.35,0.5]

#test_loss = [0.43769827485084534, 0.7226769924163818,0.7028810977935791, 0.
↳703898012638092, 0.7059929370880127]
labels = ['normal_bnn1','normal_bnn1', 'dropout_1', 'dropout_2', 'dropout_3' ]

df = pd.DataFrame({'drops':dropout_rates,'accuracy':test_accuracy},index = _
↳labels)
df['accuracy'] = df['accuracy'] * 100
df['drops'] = df['drops'] * 100
ax = df.plot.bar(rot=0,figsize=(15,7),title="Comparison of Dropout Models with_
↳BNN Models")
ax.set_xlabel("Various BNN Models")
ax.set_ylabel("Dropouts and Accuracies of Models")

for p in ax.patches:
    ax.annotate(str(p.get_height()), (p.get_x() * 1, p.get_height() * 1))
#for container in ax.containers:
#    ax.bar_label(container)

```



Early Stopping: learning rate = 0.005, epochs=50

Early Stop 1: patience = 3, Accuracy: 0.93466

Early Stop 2: patience = 4, Accuracy: 0.94833

Early Stop 3: patience = 2, Accuracy: 0.96399

Normal BNN -1: 3 - layers, epochs = 50, learning rate = 1e-06, Accuracy: 0.94099

Normal BNN -2: 4 - layers, epochs = 50, learning rate = 1e-06, Accuracy: 0.96299

```
[32]: test_accuracy = [0.94099,0.96299 ,0.93466 ,0.94833 ,0.96399]
patience = [0,0,3,4,2]

#test_loss = [0.43769827485084534, 0.7226769924163818,0.7028810977935791, 0.
↳703898012638092, 0.7059929370880127]
labels = ['normal_bnn1','normal_bnn1', 'early_1', 'early_2', 'early_3' ]

df = pd.DataFrame({'patience':patience,'accuracy':test_accuracy},index = labels)
df['accuracy'] = df['accuracy'] * 100
df['drops'] = df['drops'] * 100
ax = df.plot.bar(rot=0,figsize=(15,7),title="Comparison of Early Stop Models_
↳with BNN Models")
ax.set_xlabel("Various BNN Models")
ax.set_ylabel("Patience and Accuracies of Models")

for p in ax.patches:
    ax.annotate(str(p.get_height()), (p.get_x() * 1, p.get_height() * 1))
```

```
↳
↳-----
KeyError                                Traceback (most recent call_
↳last)

  /usr/local/lib/python3.7/dist-packages/pandas/core/indexes/base.py in
↳get_loc(self, key, method, tolerance)
    3360         try:
-> 3361             return self._engine.get_loc(casted_key)
    3362         except KeyError as err:

  /usr/local/lib/python3.7/dist-packages/pandas/_libs/index.pyx in pandas.
↳_libs.index.IndexEngine.get_loc()

  /usr/local/lib/python3.7/dist-packages/pandas/_libs/index.pyx in pandas.
↳_libs.index.IndexEngine.get_loc()

  pandas/_libs/hashtable_class_helper.pxi in pandas._libs.hashtable.
↳PyObjectHashTable.get_item()
```

```

pandas/_libs/hashtable_class_helper.pxi in pandas._libs.hashtable.
↳ PyObjectHashTable.get_item()

```

```

KeyError: 'drops'

```

The above exception was the direct cause of the following exception:

```

KeyError                                Traceback (most recent call↳
↳ last)

```

```

<ipython-input-32-ab47efc3cfa9> in <module>()
      7 df = pd.DataFrame({'patience':patience,'accuracy':
↳ test_accuracy},index = labels)
      8 df['accuracy'] = df['accuracy'] * 100
----> 9 df['drops'] = df['drops'] * 100
     10 ax = df.plot.bar(rot=0,figsize=(15,7),title="Comparison of Early↳
↳ Stop Models with BNN Models")
     11 ax.set_xlabel("Various BNN Models")

```

```

/usr/local/lib/python3.7/dist-packages/pandas/core/frame.py in↳
↳ __getitem__(self, key)
    3456         if self.columns.nlevels > 1:
    3457             return self._getitem_multilevel(key)
-> 3458         indexer = self.columns.get_loc(key)
    3459         if is_integer(indexer):
    3460             indexer = [indexer]

```

```

/usr/local/lib/python3.7/dist-packages/pandas/core/indexes/base.py in↳
↳ get_loc(self, key, method, tolerance)
    3361         return self._engine.get_loc(casted_key)
    3362         except KeyError as err:
-> 3363             raise KeyError(key) from err
    3364
    3365         if is_scalar(key) and isna(key) and not self.hasnans:

```

```

KeyError: 'drops'

```

combined

[]: