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Exp.No: 01 Date: 14.03.2024

Quick Short Algorithm

AIM:

To write a program for The Quick Sort algorithm is a sorting algorithm using C++ programming Language

ALGORITHM:

Step 1: swap function: Swaps two integers.

Step 2: partition function: Places the pivot at its correct position and partitions the array around it.

Step 3 :quickSort function: Recursively sorts the array by partitioning it.

Step 4: printArray function: Prints the array elements.

Step 5: main function: Initializes an array, prints it, sorts it using Quick Sort, and prints the sorted array.

```
PROGRAM:
```

```
#include <iostream.h>
#include <conio.h>
// Function to swap two elements
void swap(int* a, int* b) {
int t = *a;
  *a = *b;
  *b = t;
}
// Partition function to place the pivot element at the correct position
int partition(intarr[], int low, int high) {
int pivot = arr[high]; // Pivot element
int i = (low - 1); // Index of the smaller element
for (int j = low; j \le high - 1; j++) {
     // If the current element is smaller than or equal to the pivot
if (arr[j] \le pivot) {
i++; // Increment the index of the smaller element
swap(&arr[i], &arr[i]);
  }
swap(\&arr[i+1], \&arr[high]);
return (i + 1);
}
```

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```
// QuickSort function
voidquickSort(intarr[], int low, int high) {
if (low < high) {
     // Partition the array around the pivot element
int pi = partition(arr, low, high);
     // Recursively sort the sub-arrays
quickSort(arr, low, pi - 1);
quickSort(arr, pi + 1, high);
  }
}
// Function to print an array
voidprintArray(intarr[], int size) {
for (int i = 0; i < size; i++) {
cout << arr[i] << " ";
  }
cout << endl;
}
void main() {
clrscr(); // Clear the screen
intarr[] = \{10, 7, 8, 9, 1, 5\};
int n = sizeof(arr) / sizeof(arr[0]);
cout<< "Unsorted array: \n";</pre>
printArray(arr, n);
quickSort(arr, 0, n - 1);
```

```
cout<< "Sorted array: \n";
printArray(arr, n);
getch(); // Wait for a key press
}</pre>
```

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OUTPUT:

```
Unsorted array:
10 7 8 9 1 5
Sorted array:
1 5 7 8 9 10
```

RESULT:

Thus the Program has been successfully completed.

Exp.No: 02 Date: 21.03.2024

DIJKSTRA'S ALGORITHM

AIM:

To implement dijkstra's algorithm using C++ programming language

ALGORITHM:

STEP 1: minDistance function: Finds the vertex with the minimum distance value that hasn't been processed yet.

STEP 2: PrintSolution function: Prints the shortest distances from the source vertex to all other vertices.

STEP 3 :dijkstra function: Implements Dijkstra's algorithm to find the shortest path from the source vertex to all other vertices in the graph.

STEP 4 :main function: Defines the graph as an adjacency matrix, calls the **dijkstra** function, and waits for a key press before terminating.

```
PROGRAM:
```

```
#include <iostream.h>
#include <conio.h>
#include inits.h>
// Number of vertices in the graph
#define V 9
// Function to find the vertex with the minimum distance value
intminDistance(intdist[], bool sptSet[]) {
int min = INT MAX, min index;
for (int v = 0; v < V; v++)
if (sptSet[v] == false &&dist[v] <= min)
min = dist[v], min_index = v;
returnmin_index;
}
// Function to print the constructed distance array
voidprintSolution(intdist[], int n) {
cout<< "Vertex \t Distance from Source\n";</pre>
for (int i = 0; i < n; i++)
cout<< i << " \t\t " << dist[i] << "\n";
}
// Function that implements Dijkstra's single source shortest path algorithm
```

```
voiddijkstra(int graph[V][V], intsrc) {
intdist[V]; // Output array. dist[i] will hold the shortest distance from src to i
boolsptSet[V]; // sptSet[i] will be true if vertex i is included in the shortest path tree
  // Initialize all distances as INFINITE and stpSet[] as false
for (int i = 0; i < V; i++)
dist[i] = INT MAX, sptSet[i] = false;
  // Distance of source vertex from itself is always 0
dist[src] = 0;
  // Find the shortest path for all vertices
for (int count = 0; count < V - 1; count++) {
     // Pick the minimum distance vertex from the set of vertices not yet processed
int u = minDistance(dist, sptSet);
     // Mark the picked vertex as processed
sptSet[u] = true;
     // Update dist value of the adjacent vertices of the picked vertex
for (int v = 0; v < V; v++)
       // Update dist[v] only if it is not in sptSet, there is an edge from u to v,
       // and total weight of path from src to v through u is smaller than current value of
dist[v]
if (!sptSet[v] \&\& graph[u][v] \&\& dist[u] != INT MAX \&\& dist[u] + graph[u][v] < dist[v])
dist[v] = dist[u] + graph[u][v];
  }
```

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```
// Print the constructed distance array
printSolution(dist, V);
}
void main() {
clrscr(); // Clear the screen
  // Example graph represented as an adjacency matrix
int graph[V][V] = {
     \{0, 4, 0, 0, 0, 0, 0, 8, 0\},\
     {4, 0, 8, 0, 0, 0, 0, 11, 0},
     \{0, 8, 0, 7, 0, 4, 0, 0, 2\},\
     \{0, 0, 7, 0, 9, 14, 0, 0, 0\},\
     \{0, 0, 0, 9, 0, 10, 0, 0, 0\},\
     \{0, 0, 4, 14, 10, 0, 2, 0, 0\},\
     \{0, 0, 0, 0, 0, 2, 0, 1, 6\},\
     \{8, 11, 0, 0, 0, 0, 1, 0, 7\},\
     \{0, 0, 2, 0, 0, 0, 6, 7, 0\}
  };
dijkstra(graph, 0); // Call Dijkstra's algorithm with source vertex 0
getch(); // Wait for a key press
}1
```

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```
Distance from Source
Vertex
        4
1
2
        12
3
        19
4
        21
5
        11
6
        8
8
        14
```

Result:

Thus the given program is executed and output Is verified successfully.

Exp.No :03 Date : 28.03.2024

Strassen Matrix Algorithm

AIM:

To implement Strassen Matrix Algorithm using C++ language

ALGORITHM:

Step 1: Add function: Adds two 2x2 matrices.

Step 2 :subtract function: Subtracts one 2x2 matrix from another.

Step 3 :strassen function: Implements Strassen's matrix multiplication algorithm for 2x2 matrices.

Step 4 :printMatrix function: Prints a 2x2 matrix.

Step 5 :main function: Initializes two 2x2 matrices, calls the **strassen** function to multiply them, and prints the result.

PROGRAM:

```
#include <iostream.h>
#include <conio.h>
#include <stdlib.h>
void add(int A[2][2], int B[2][2], int C[2][2]) {
for (int i = 0; i < 2; i++)
for (int j = 0; j < 2; j++)
       C[i][j] = A[i][j] + B[i][j];
void subtract(int A[2][2], int B[2][2], int C[2][2]) {
for (int i = 0; i < 2; i++)
for (int j = 0; j < 2; j++)
       C[i][j] = A[i][j] - B[i][j];
}
voidstrassen(int A[2][2], int B[2][2], int C[2][2]) {
int M1[2][2], M2[2][2], M3[2][2], M4[2][2], M5[2][2], M6[2][2], M7[2][2];
int temp1[2][2], temp2[2][2];
// M1 = (A11 + A22) * (B11 + B22)
add(A, A, temp1);
add(B, B, temp2);
multiply(temp1, temp2, M1);
// M2 = (A21 + A22) * B11
add(A + 1, A + 3, temp1);
multiply(temp1, B, M2);
// M3 = A11 * (B12 - B22)
subtract(B + 1, B + 3, temp2);
multiply(A, temp2, M3);
```

```
// M4 = A22 * (B21 - B11)
subtract(B + 2, B, temp2);
multiply(A + 3, temp2, M4);
  // M5 = (A11 + A12) * B22
add(A, A + 1, temp1);
multiply(temp1, B + 3, M5);
  // M6 = (A21 - A11) * (B11 + B12)
subtract(A + 2, A, temp1);
add(B, B + 1, temp2);
multiply(temp1, temp2, M6);
  // M7 = (A12 - A22) * (B21 + B22)
subtract(A + 1, A + 3, temp1);
add(B + 2, B + 3, temp2);
multiply(temp1, temp2, M7);
  // C11 = M1 + M4 - M5 + M7
add(M1, M4, temp1);
subtract(temp1, M5, temp2);
add(temp2, M7, C);
  // C12 = M3 + M5
add(M3, M5, C + 1);
```

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```
// C21 = M2 + M4
add(M2, M4, C + 2);
  // C22 = M1 - M2 + M3 + M6
subtract(M1, M2, temp1);
add(temp1, M3, temp2);
add(temp2, M6, C + 3);
}
voidprintMatrix(int matrix[2][2]) {
for (int i = 0; i < 2; i++) {
for (int j = 0; j < 2; j++)
cout << matrix[i][j] << " ";
cout << endl;
  }
void main() {
clrscr(); // Clear the screen
int A[2][2] = \{ \{1, 2\}, \{3, 4\} \};
int B[2][2] = \{ \{5, 6\}, \{7, 8\} \};
int C[2][2]; // Result matrix
strassen(A, B, C);
cout<< "Resultant matrix: \n";</pre>
printMatrix(C);
getch(); // Wait for a key press
}
```

Resultant matrix:
19 22
43 50

Result:

Thus the given program is executed and output Is verified successfully.

Exp.No :04 Date : 04.04.2024

SHORTST PATHS USING FLOYD'S ALGOITHM

AIM:

To write a c++ program to find shortest path using floyd's algorithm.

ALGORITHM:

- 1.intillalize the solution matrix same as the input graph matrix as a first step.
- 2. Then update the solution matrix by considering all vertices as an intermediate vertex.
- 3. The idea is to pick all vertices one by one and updates all shortest paths which include the picked vertex as an intermediate vertex in the shortest path.
- 4. When we pick vertex number k as an intermediate vertex, we already have considered vertices $\{0, 1, 2, ... k-1\}$ as intermediate vertices.
- 5. For every pair (i, j) of the source and destination vertices respectively, there are two possible cases.
- 6.K is not an intermediate vertex in shortest path from **i** to **j**. We keep the value of **dist[i][j]** as it is.
- 7.k is an intermediate vertex in shortest path from i to j. We update the value of dist[i][j] as dist[i][k] + dist[k][j], if dist[i][j] > dist[i][k] + dist[k][j].

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```
Program:
```

```
#include <iostream.h>
#include <conio.h>
voidfloyds(int b[][7])
{
int i, j, k;
  for (k = 0; k < 7; k++)
     for (i = 0; i < 7; i++)
        for (j = 0; j < 7; j++)
if ((b[i][k] * b[k][j] != 0) && (i != j))
             if ((b[i][k] + b[k][j] < b[i][j]) \parallel (b[i][j] == 0))
                b[i][j] = b[i][k] + b[k][j];
             }
  for (i = 0; i < 7; i++)
cout<<"\nMinimum Cost With Respect to Node:"<<iendl;</pre>
     for (j = 0; j < 7; j++)
```

```
cout << b[i][j] << " \setminus t";
     }
  }
int main()
{
int b[7][7];
cout<<"ENTER VALUES OF ADJACENCY MATRIX\n\n";
  for (int i = 0; i < 7; i++) {
cout \le "enter values for " \le (i+1) \le "row" \le endl;
     for (int j = 0; j < 7; j++)
     {
cin>>b[i][j];
     } }
floyds(b);
getch();
return(0);
}
```

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```
enter values for 2 row
enter values for 3 row
enter values for 4 row
enter values for 5 row
enter values for 6 row
enter values for 7 row
Minimum Cost With Respect to Node:0
               -96
       -76
                       -68
                                       -140
                                               -87
Minimum Cost With Respect to Node:1
               -97
-73
       6
                       -69
                                        -141
                                               -88
Minimum Cost With Respect to Node:2
-53
       -57
               4945
                       -49
                                        -121
                                               -68
Minimum Cost With Respect to Node:3
-50
       -54
               -74
                       3292
                                       -118
                                               -65
Minimum Cost With Respect to Node:4
       -81
               -101
                      -73
                                520
                                       -145
                                               -92
Minimum Cost With Respect to Node:5
                                        1300
                                               -14
               -23
                       5
Minimum Cost With Respect to Node:6
               -9
                       19
                                       -53
                                                        ENTER VALUES OF ADJACENC
                                               8115
                               15
Y MATRIX
enter values for 1 row
```

Result:

Thus the given Program is executed and output is verified successfully.

Exp.No: 05 Date: 18.04.2024

TRAVELLING SALESPERSON PROBLEM

AIM:

To write C++ program Find the Optimal solution for travelling salesperson problem using approximation algorithm.

ALGORITHM:

STEP-1: Travelling salesman problem takes a graph G {V, E} as an input and declare another graph as the output (say G') which will record the path the salesman is going to take from one node to another.

STEP-2: The algorithm begins by sorting all the edges in the input graph G from the least distance to the largest distance.

STEP-3:The first edge selected is the edge with least distance, and one of the two vertices (say A and B) being the origin node (say A).

STEP-4: Then among the adjacent edges of the node other than the origin node (B), find the least cost edge and add it onto the output graph.

STEP-5:Continue the process with further nodes making sure there are no cycles in the output graph and the path reaches back to the origin node A.

STEP-6:However, if the origin is mentioned in the given problem, then the solution must always start from that node only. Let us look at some example problems to understand this better.

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PROGRAM:

```
#include<iostream>
using namespace std;
intary[10][10],completed[10],n,cost=0;
voidtakeInput()
{
inti,j;
cout<<"Enter the number of villages: ";</pre>
cin>>n;
cout<<"\nEnter the Cost Matrix\n";</pre>
for(i=0;i <n;i++)
{
cout<<"\nEnter Elements of Row: "<<i+1<<"\n";
for( j=0;j <n;j++)
cin>>ary[i][j];
completed[i]=0;
}
cout<<"\n\nThe cost list is:";</pre>
for( i=0;i <n;i++)
{
cout << "\n";
for(j=0;j < n;j++)
cout << "\t" << ary[i][j];
}
int least(int c)
```

```
{
inti,nc=999;
int min=999,kmin;
for(i=0;i <n;i++)
{
if((ary[c][i]!=0)&&(completed[i]==0))
if(ary[c][i]+ary[i][c] < min)
{
min=ary[i][0]+ary[c][i];
kmin=ary[c][i];
nc=i;
}
if(min!=999)
cost+=kmin;
return nc;
}
voidmincost(int city)
{
inti,ncity;
completed[city]=1;
cout<<city+1<<"--->";
ncity=least(city);
if(ncity==999)
{
ncity=0;
cout<<ncity+1;</pre>
```

```
return;
}
mincost(ncity);
}
int main()
{
takeInput();
cout<<"\n\nThe Path is:\n";
mincost(0); //passing 0 because starting vertex
cout<<"\n\nMinimum cost is "<<cost;
return 0;
}</pre>
```

Result:

Thus the given program is executed and output is verified successfully.

Exp.No: 06 Date: 25.04.2024

KNAPSACK PROBLEM USING GREEDY METHOD

Aim:

To write a C++ program to solve the knapsack problem using greedy method **Algorithm**:

- 1. Sort the array in decreasing order using the value/weight ratio
- 2.Start taking the element having the maximum value/weight ratio
- 3.If the weight of the current item is less than the current knapsack capacity, add the whole item, or else add the portion of the item to the knapsack
- 4.Stop adding the elements when the capacity of the knapsack becomes 0
- 5. Choose the item that has the maximum value from the remaining items
- 6.Choose the lightest item from the remaining items which uses up capacity as slowly as possible
- 7. Put items into the bag until the next item on the list cannot fit
- 8. Try to fill any remaining capacity with the next item on the list that can fit

Program:

```
#include <stdio.h>
#include<iostream.h>
// A utility function that returns
// maximum of two integers
int max(int a, int b) { return (a > b) ? a : b; }
// Returns the maximum value that
// can be put in a knapsack of capacity W
intknapSack(int W, intwt[], intval[], int n)
{
  // Base Case
  if (n == 0 || W == 0)
       return 0;
  // If weight of the nth item is more
  // than Knapsack capacity W, then
  // this item cannot be included
  // in the optimal solution
if (wt[n-1] > W)
       returnknapSack(W, wt, val, n - 1);
  // Return the maximum of two cases:
  // (1) nth item included
```

```
// (2) not included
   else
         return max(
         val[n - 1]
                  + \operatorname{knapSack}(W - \operatorname{wt}[n - 1], \operatorname{wt}, \operatorname{val}, n - 1),
         knapSack(W, wt, val, n - 1));
}
// Driver code
int main()
{
int profit[] = { 60, 100, 120 };
int weight[] = { 10, 20, 30 };
   int W = 50;
int n = sizeof(profit) / sizeof(profit[0]);
cout<<knapSack(W, weight, profit, n);</pre>
  return 0;
}
```



Result:

Thus given program travelling salesperson problem is executed successfully and output is verified

Exp.No: 07 Date :02.05.2024

Shortest path to other vertices using Dijkstra's Algorithm

AIM:

To implement shortest path to other vertices using Dijkstras algorithm by using C++ Language

ALGORITHM:

Step 1: minDistance function: Finds the vertex with the minimum distance value not yet included in the shortest path tree.

Step 2: printSolution function: Prints the distances of all vertices from the source vertex.

Step 3: dijkstra function: Initializes distances and shortest path tree set, then iteratively selects the vertex with the minimum distance to update adjacent vertices' distances.

Step 4: main function: Sets up the graph as an adjacency matrix.

Step 5: main function (continued): Calls 'Dijkstra' to compute and print the shortest paths from the source vertex.

PROGRAM:

```
#include <iostream.h>
#include <conio.h>
#include inits.h>
// Number of vertices in the graph
#define V 9
// Function to find the vertex with the minimum distance value
intminDistance(intdist[], bool sptSet[]) {
int min = INT MAX, min index;
for (int v = 0; v < V; v++)
if(!sptSet[v] \&\&dist[v] \le min)
min = dist[v], min_index = v;
returnmin_index;
}
// Function to print the constructed distance array
voidprintSolution(intdist[]) {
cout<< "Vertex \t Distance from Source\n";</pre>
for (int i = 0; i < V; i++)
cout << i << " \setminus t \setminus t " << dist[i] << " \setminus n";
}
// Function that implements Dijkstra's single source shortest path algorithm
```

```
voiddijkstra(int graph[V][V], intsrc) {
intdist[V]; // Output array. dist[i] will hold the shortest distance from src to i
boolsptSet[V]; // sptSet[i] will be true if vertex i is included in the shortest path tree
  // Initialize all distances as INFINITE and sptSet[] as false
for (int i = 0; i < V; i++)
dist[i] = INT MAX, sptSet[i] = false;
  // Distance of source vertex from itself is always 0
dist[src] = 0;
  // Find the shortest path for all vertices
for (int count = 0; count < V - 1; count++) {
     // Pick the minimum distance vertex from the set of vertices not yet processed
int u = minDistance(dist, sptSet);
     // Mark the picked vertex as processed
sptSet[u] = true;
     // Update dist value of the adjacent vertices of the picked vertex
for (int v = 0; v < V; v++)
if (!sptSet[v] \&\& graph[u][v] \&\& dist[u] != INT\_MAX \&\& dist[u] + graph[u][v] < dist[v]) \\
dist[v] = dist[u] + graph[u][v];
  }
  // Print the constructed distance array
printSolution(dist);
```

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```
}
void main() {
clrscr(); // Clear the screen
  // Example graph represented as an adjacency matrix
int graph[V][V] = \{
     \{0, 4, 0, 0, 0, 0, 0, 8, 0\},\
      {4, 0, 8, 0, 0, 0, 0, 11, 0},
     \{0, 8, 0, 7, 0, 4, 0, 0, 2\},\
     \{0, 0, 7, 0, 9, 14, 0, 0, 0\},\
     \{0, 0, 0, 9, 0, 10, 0, 0, 0\},\
     \{0, 0, 4, 14, 10, 0, 2, 0, 0\},\
     \{0, 0, 0, 0, 0, 2, 0, 1, 6\},\
     \{8, 11, 0, 0, 0, 0, 1, 0, 7\},\
     \{0, 0, 2, 0, 0, 0, 6, 7, 0\}
  };
dijkstra(graph, 0); // Call Dijkstra's algorithm with source vertex 0
getch(); // Wait for a key press
}
```

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Vertex	Distance from Source
0	0
1	4
2	12
3	19
4	21
5	11
6	9
7	8
8	14

Result:

Thus the program is executed and the output is verified successfully.

Exp.No: 08 Date: 9.05.2024

MINIMUM COST SPANNING TREE USING KRUSKALS

ALGORITHM

AIM:

To find the minimum cost spanning tree of a given undirected graph using kruskal's algorithm.

ALGORITHM:

STEP-1:.A \leftarrow Ø.

STEP-2: for each vertex v V[G].

STEP-3:do MAKE-SET(v).

STEP-4:sort the edges of E into nondecreasing order by weight w.

STEP-5:For each edge (u, v) E, taken in nondecreasing order by weight.

STEP-6:do if FIND-SET(u) \neq FIND-SET(v).

STEP-7:then $A \leftarrow A \{(u, v)\}.$

STEP-8:UNION(u, v).

STEP-9:return A.

STEP-10:display the mincost as Minimum cost.

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PROGRAM:

```
#include<stdio.h>
#include<conio.h>
#include<stdlib.h>
inti,j,k,a,b,u,v,n,ne=1;
intmin,mincost=0,cost[9][9],parent[9];
int find(int);
intuni(int,int);
void main()
{
clrscr();
printf("\n\tImplementation of Kruskal's algorithm\n\n");
printf("\nEnter the no. of vertices\n");
scanf("%d",&n);
printf("\nEnter the cost adjacency matrix\n");
for(i=1;i<=n;i++)
for(j=1;j \le n;j++)
{
scanf("%d",&cost[i][j]);
if(cost[i][j]==0)
cost[i][j]=999;
}
printf("\nThe edges of Minimum Cost Spanning Tree are\n\n");
while(ne<n)
{
```

```
for(i=1,min=999;i<=n;i++)
for(j=1;j<=n;j++)
if(cost[i][j]<min)
{
min=cost[i][j];
a=u=i;
b=v=j;
u=find(u);
v=find(v);
if(uni(u,v))
printf("\n%d edge (%d,%d) =%d\n",ne++,a,b,min);
mincost +=min;
}
cost[a][b]=cost[b][a]=999;
printf("\n\tMinimum cost = %d\n",mincost);
getch();
}
int find(int i)
{
while(parent[i])
```

```
i=parent[i];
return i;
}
intuni(inti,int j)
{
  if(i!=j)
  {
  parent[j]=i;
  return 1;
}
```

```
Implementation of Kruskal's algorithm

Enter the no. of vertices
2

Enter the cost adjacency matrix
100 200
200 300

The edges of Minimum Cost Spanning Tree are

1 edge (1,2) =200

Minimum cost = 200
```

RESULT:

Thus the program is executed and the output is verified successfully.

Exp.No:09 Date:16.05.2024

Implementation of the N Queens problem

Aim:

Implementation of the N Queens problem using C++ programming language.

ALGORITHM:

Step 1: printSolution function: Prints the current chessboard configuration, where 1s represent queens' positions and 0s represent empty squares.

Step 2 :isSafe function: Checks if it's safe to place a queen at a given position, ensuring no other queens threaten it horizontally, vertically, or diagonally.

Step 3: solveNQUtil function: Recursively solves the N Queens problem by trying to place queens column by column, ensuring each placement is safe.

Step 4: solveNQ function: Initializes the chessboard and invokes solveNQUtil to find a solution. If found, prints it; otherwise, indicates no solution exists.

Step 5 :main function: Initializes the chessboard with empty squares, calls solveNQ to find the solution, and manages the program flow.

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```
Program:
```

```
#include <iostream.h>
#include <conio.h>
#define N 8
voidprintSolution(int board[N][N]) {
for (int i = 0; i < N; i++) {
for (int j = 0; j < N; j++)
cout << board[i][j] << " ";
cout << endl;
  }
boolisSafe(int board[N][N], int row, int col) {
int i, j;
  // Check this row on the left side
for (i = 0; i < col; i++)
if (board[row][i])
return false;
  // Check upper diagonal on left side
for (i = row, j = col; i \ge 0 \&\& j \ge 0; i--, j--)
if (board[i][j])
return false;
```

```
// Check lower diagonal on left side
for (i = row, j = col; j \ge 0 \&\& i < N; i++, j--)
if (board[i][j])
return false;
return true;
}
boolsolveNQUtil(int board[N][N], int col) {
  // If all queens are placed, return true
if (col >= N)
return true;
  // Consider this column and try placing this queen in all rows one by one
for (int i = 0; i < N; i++) {
     // Check if the queen can be placed on board[i][col]
if (isSafe(board, i, col)) {
       // Place this queen in board[i][col]
board[i][col] = 1;
       // Recur to place rest of the queens
if (solveNQUtil(board, col + 1))
return true;
       // If placing queen in board[i][col] doesn't lead to a solution, then remove the queen
from board[i][col]
board[i][col] = 0; // BACKTRACK
```

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```
}
  // If the queen cannot be placed in any row in this column, return false
return false;
}
boolsolveNQ() {
int board[N][N] = { \{0, 0, 0, 0, 0, 0, 0, 0, 0, 0\},\
                  \{0, 0, 0, 0, 0, 0, 0, 0, 0\},\
                  \{0, 0, 0, 0, 0, 0, 0, 0, 0\},\
                  \{0, 0, 0, 0, 0, 0, 0, 0, 0\},\
                  \{0, 0, 0, 0, 0, 0, 0, 0, 0\},\
                  \{0, 0, 0, 0, 0, 0, 0, 0, 0\},\
                  \{0, 0, 0, 0, 0, 0, 0, 0, 0\},\
                  \{0, 0, 0, 0, 0, 0, 0, 0, 0\}\};
if (solveNQUtil(board, 0) == false) {
cout<< "Solution does not exist";</pre>
return false;
  }
printSolution(board);
return true;
}
void main() {
```

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```
clrscr(); // Clear the screen
solveNQ();
getch(); // Wait for a key press
}
```

RESULT:

Thus the program is executed and the output is verified successfully