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18EC0133T · Sensors & Transducers

Unit - 1

Sensors & Transducers

used → in industries

Sensors: Converts physical qty. to some other electrical qty.

Transducers : One form of energy to another

SYLLABUS

1. Introduction to sensors/transducers, principles
2. Classification based on different criteria
3. Characteristics of measurement systems
4. Static characteristics (accuracy, precision, resolution, sensitivity) MCQ
X area,
10M
5. Dynamic characteristics
6. Electrical parameters
7. Electrical & Mechanical characterization
8. Thermal, Optical characteristics
9. Sensors and its classification

10. Selection of transducers
 11. Intro. to mechanical sensors
 12. Resistive potentiometers
 13. Strain Gauge
 14. RTB
 15. Thermistor
- } Theory portion

Definition

1. Transducer

A device that converts energy from one form to another form

2. Sensor

It is a type of transducer which converts a physical parameter to an electrical output. Eg: Microphone

3. Physical Quantity

Temperature, pressure, force, motion, displacement, humidity etc.

4. Electrical Quality

Change in Resistance, Inductance,
Capacitance

STATIC CHARACTERISTICS

A set of criteria which do not vary with time

↳ Accuracy

↳ precision

↳ Resolution

↳ Sensitivity

(i) Accuracy

The accuracy of an instrument is a measure how closely measured value of the instrument is to the true value.

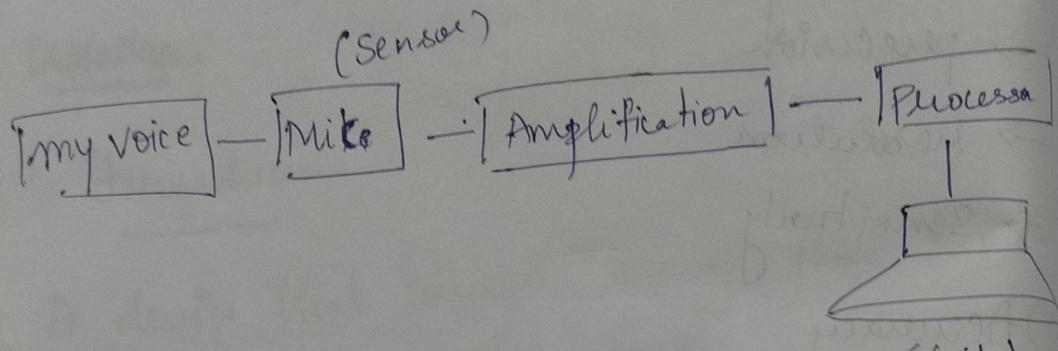
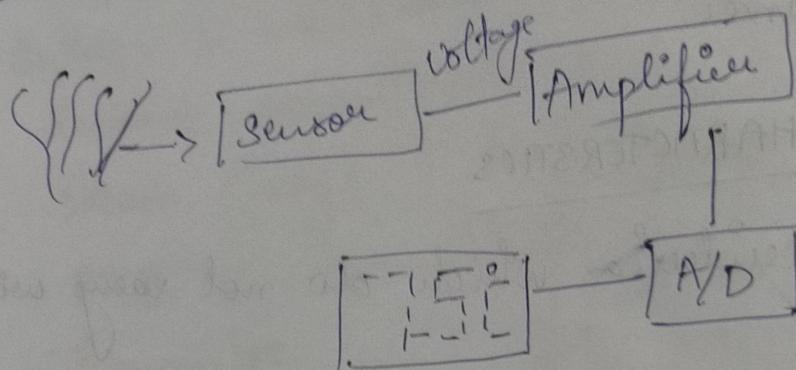
(ii) Precision

It is defined as capability of an instrument to show the same reading when used each time.

[Reproducibility of an instrument]

↓
Repeatability.

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I STATIC CHARACTERISTICS

- A set of criteria which does not vary with time is called static characteristics
- * Accuracy
 - * Precision
 - * Resolution
 - * Sensitivity

Accuracy

The accuracy of an instrument is a measure of how close the measured value of the instrument is to the true value.

Percentage of accuracy = $\frac{\text{True value} + \text{Measured value}}{\text{True value}} \times 100$

Precision

Precision is defined as capability of an instrument to show the same reading everytime. (Reproducibility of the instrument)

Sensitivity

It is defined as the ratio of change in output towards the change in input at a steady state condition

$Q \rightarrow \text{quantity}$

$$\text{Sensitivity (K)} = \frac{\Delta Q_o}{\Delta Q_i}$$

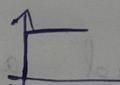
Resolution

It is the smallest change in the measured quantity that will produce a detectable change in instrument reading.

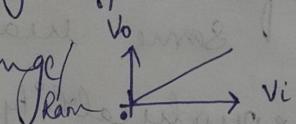
II. Dynamic characteristics

A set of criteria which varies with time is called dynamic characteristics.

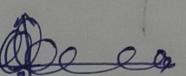
* Step change



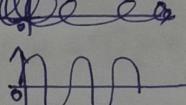
* Linear change



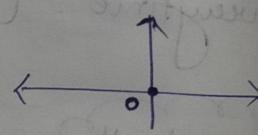
* Impulse change



* Sinusoidal change



* Speed of response



* Fidelity

* Lag

* Dynamic Errors

(i) Speed of response

It gives the information about how fast the system reacts to the changes in input.

(ii) Fidelity (without error how a system will output)

It is defined as the degree to which an instrument indicates the changes in the measured variable without dynamic error.

(iii) Lag : delay in the response of the system

(iv) Dynamic error : difference b/w true value of the variable to be measured changing with time and the value indicated by the measurement system assuming zero error.

Classification of Sensors

Based on

i) Transduction principle

- using physical / chemical effect

ii) Primary input quantity

→ pressure

→ temperature

→ humidity ... etc

iii) Material & Technology

↓
Sensors

Image Sensor

Motion detector
→ IR, Ultrasonic

Biosensor
electrical

Acceleration
MEMS

→ CMOS

IV) Application

industrial type

non-industrial type

V) property

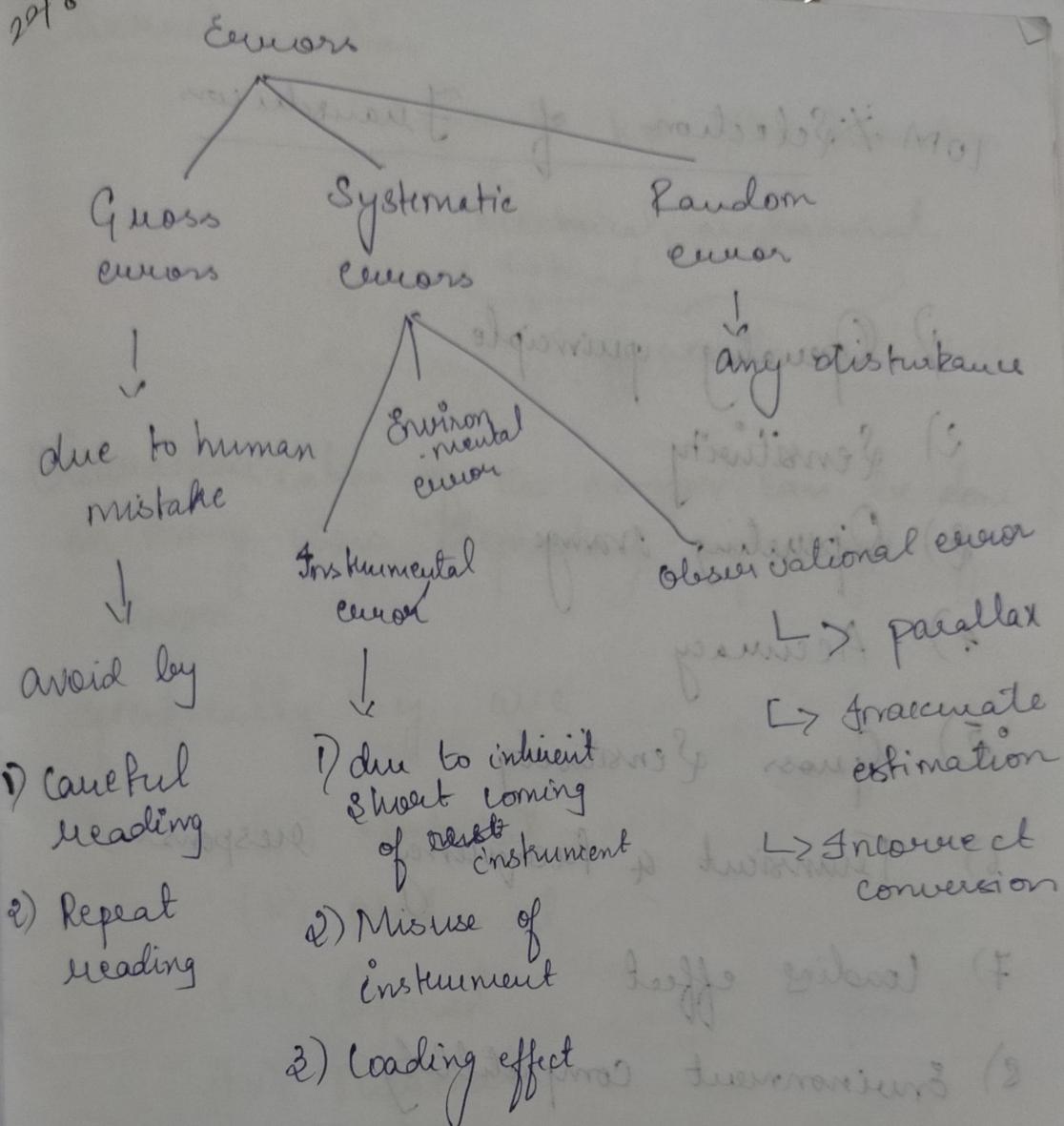
automobile

Consumer products

aircraft

Medic products

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Types of error appeared in Sensors & Transducers

- Gross error
- Systematic error
- Random error

IGM & Selection of Transducers

1) Operating principle

2) Sensitivity

3) Operating range

4) Accuracy

5) Gross sensitivity at output

6) Transient & frequency response

7) Loading effect

8) Environment compatibility

9) Usage and Readiness

10) Electrical aspects

11) Stability & mean reliability

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Characterization

↳ (how to test the transducer)
electrical, mechanical,
optical
diff. aspects

Characterization of the sensor can be done
in many ways depending upon type of
sensors.

Specifically they are

(i) electrical

(ii) Mechanical

(iii) Optical

(iv) Thermal

(v) Chemical

(vi) Biological and so on

Electrical Characterization

(i) Impedance, Voltage, Current

(ii) Breakdown voltage & fields

(iii) Leakage current

(iv) noise

(v) cross talk

Impedance: Coupling circuit



ratio of voltage & current

O/P imp

Yp cmp

⑩

should

will be high for
Voltage sensitive sensor

O/P imp

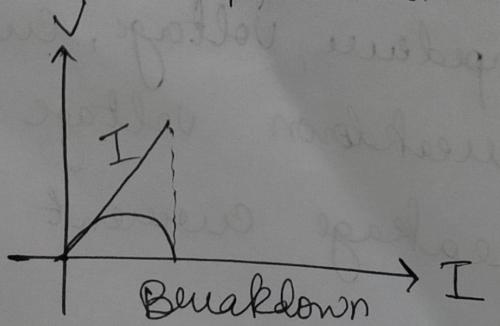
Yp cmp

should

will be low for current
sensitive sensor

check up health

- sudden, avalanche
- extensive, intrinsic



Breakdown,
voltage &
field

Mechanical & thermal characteristics

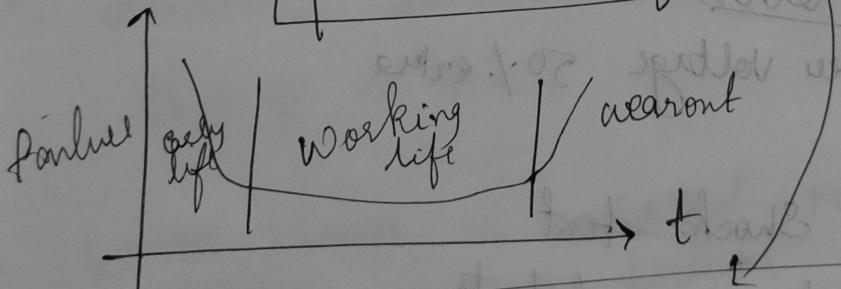
- Reliability & integrity

by means of testing

failure analysis

- (1) catastrophic early life failure (due to many manufacturing faults)
- (2) short term drift (within very short term, it may get fail)
- (3) long term drift (due to ageing / used for long term failure)

Probability of failure : $f(x)$



Probability of reliability : $R(x) = 1 - f(x)$

$$= \int f(t) dt$$

Explain characterization of
transistors

core (12M)

i) High temperature burn in

→ H.T over a stipulated period
 (25°C)

2) High temperature storage leak

leaked at a high temperature
 (25°C)

→ contamination

→ Metallization problem

3) Electrical Overstress

Over voltage 50% extra

4) Thermal Shock test

packaging defects

$65^{\circ} - 125^{\circ}\text{C}$

10 seconds → repeated

3) mechanical shock test

dropping 3 to 10m and sees

to show the effects of impacts

mechanical characterisation of the visit

Optical characterisation

absorption co-efficient

refractive index \times

reflectivity is of interest

MCP

waveform behaviour

1. Change in output of sensor with change in input \rightarrow sensitivity

2. dynamic describes the performance with change in time

3. Which error is related to human error \rightarrow gross error

4. Fidelity is static characteristics - False

5. Sudden change in voltage/current
- breakdown

6. Large value upto 50% in excess are applied over different intervals of time is called electrical oversress

7. Reliability f_n is as suggested

Y Reliability f_n is given by $\underline{1 - f(n)}$

Sensors and Transducers

Mechanical Sensors

Input quantity - Mechanical parameter

Motion

Displacement

Speed

Velocity

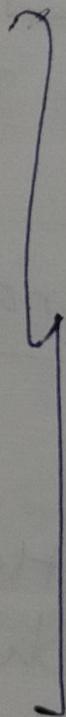
pressure flow & Flow
acceleration

Torque

electromechanical

(or)

mechanoelectrical



→ Sensor

↓
Output

electrical

magnetic

optical

thermal etc

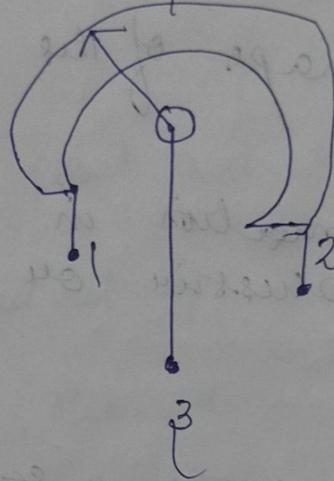


→ processing or display

Resistive potentiometers

1) Linear potentiometer

2) Variable potentiometer



$$\Delta V = \frac{V}{n}$$

$$\Delta V_m = V_p \left[\frac{1}{n-1} - \frac{1}{n} \right]$$

$$\Delta V - \Delta V_m = \frac{V}{n} - V_p \left[\frac{1}{n-1} - \frac{1}{n} \right]$$

Strain Gauge (X) (class test)

$$\text{Gauge factor } (\alpha) = \left\{ \frac{\Delta R/R}{\Delta L/L} \right\} \rightarrow \text{strain}$$

When an external force is applied on an object (tension, pressure, tension, weight) due to which there is a deformation (change in in the shape of the object)

This deformation in the shape is both compressive or tensile is called strain

A strain gauge is a sensor whose resistance varying with applied force by measuring the change in resistance of an object. The amount of produced stress can be calculated.

Type of strain gauge

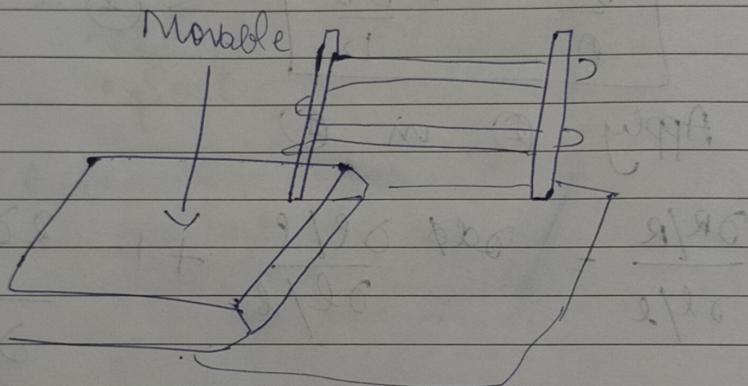
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1) Wire strain type -

Unbonded resistance
Wire strain gauge
bonded resistance
Wire strain gauge

2) Semiconductor gauge type

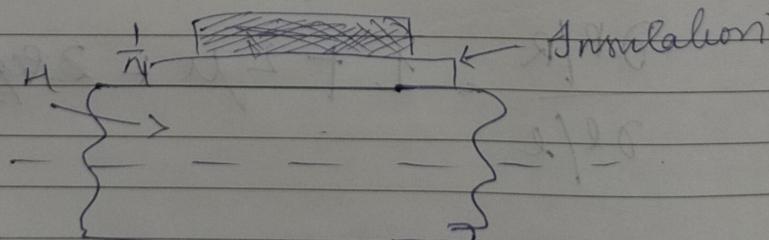
Unbonded strain gauge



Bonded type

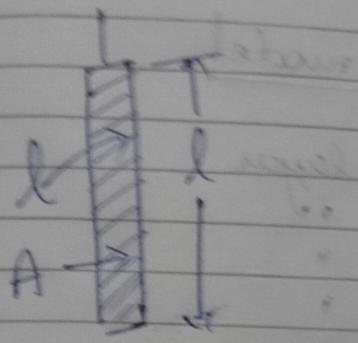
$$\text{Strain} = \frac{\epsilon_m}{H}$$

$$h + H$$



depending upon the implementation, the resistance gauge can be classified as

- (i) Unbraided metal wire
- (ii) Braided metal wire
- (iii) Bonded nickel foil
- (iv) Thin metal film by vacuum
- v) " " by sputter



$$R = \frac{\rho l}{A}$$

ρ - resistivity
A - Area of
cross section
of wire

Strain Gauge

for Calculation of gauge factor

$$\log R = \log \rho + \log l - \log A$$

$$\frac{\partial R}{R} = \frac{\partial \rho}{\rho} + \frac{\partial l}{l} - \frac{\partial A}{A}$$

divide $\partial l/l$ completely

$$\frac{\partial R/R}{\partial l/l} = \frac{\partial \rho/\rho}{\partial l/l} + 1 - \frac{\partial A/A}{\partial l/l}$$

$$A = \pi D^2 \quad \frac{\partial A}{\partial l} = \frac{\pi 2 D}{D} 2 D$$

$$\frac{\partial A}{4} = \pi (2D) \Delta D$$

$$\therefore A$$

$$\frac{\partial A}{A} = \frac{\pi K (2D) \Delta D}{E D^2}$$

$$\left[\frac{\partial A}{A} = 2 \frac{\partial D}{D} \right] \rightarrow ②$$

Apply ② in ①

$$\frac{\partial R/R}{\partial l/l} = \text{def } \frac{\partial e/e}{\partial l/l} + 1 - \frac{2 \partial D}{D} \frac{\partial l}{l}$$

$$\text{Let poisson ratio } \mu = -\frac{\partial D}{D} \frac{\partial l}{l}$$

$$\frac{\partial R/R}{\partial l/l} = 1 + 2\mu + 2 \frac{\partial e/e}{\partial l/l}$$

RTD (Resistance Temperature Detector)

? The value of resistance changes with change in temperature

$$R_T = R_0 (1 + \alpha T)$$

↳ Temperature
Co-efficient of resistance

→ the temperature co-efficient

PTC - Temp ↑ R ↑

NTC - Temp ↑ R ↓

↓

-ve temperature co-efficient

Mostly platinum

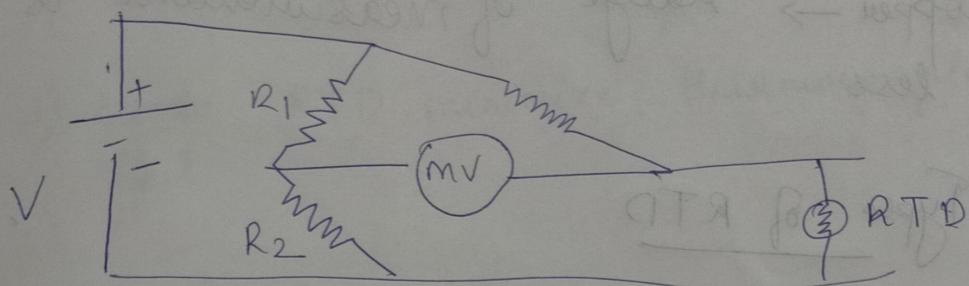
Others are copper, nichel

Eg

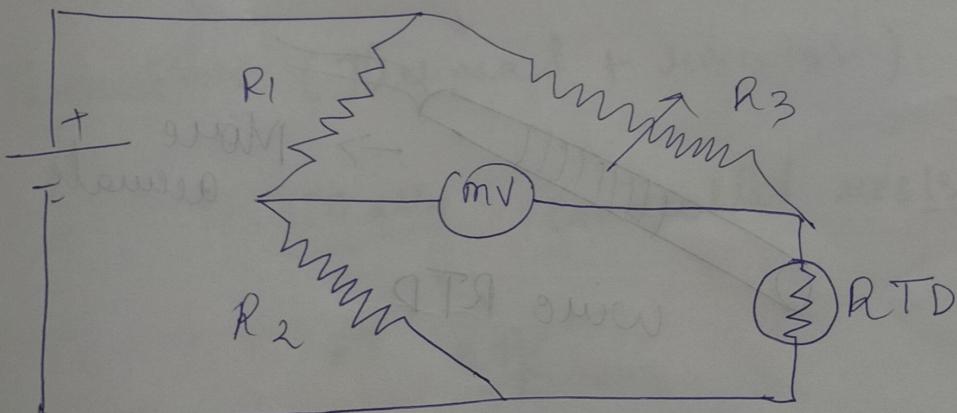
Used in Industries to monitor temperature of steam flowing in a pipeline

* RTD inserted in pipeline

* PT100 $\Rightarrow 0^\circ\text{C} \rightarrow 100\Omega$
 $1^\circ\text{C} \rightarrow 200\Omega$



cheap, simple, but lower accuracy.



Materials used in RTD:

platinum \rightarrow most common type RTD
 \rightarrow excellent corrosion resistance
 \rightarrow a longterm stability

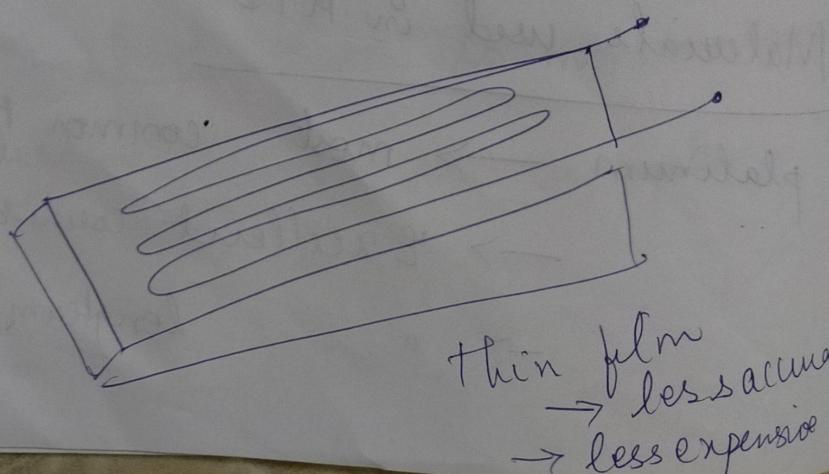
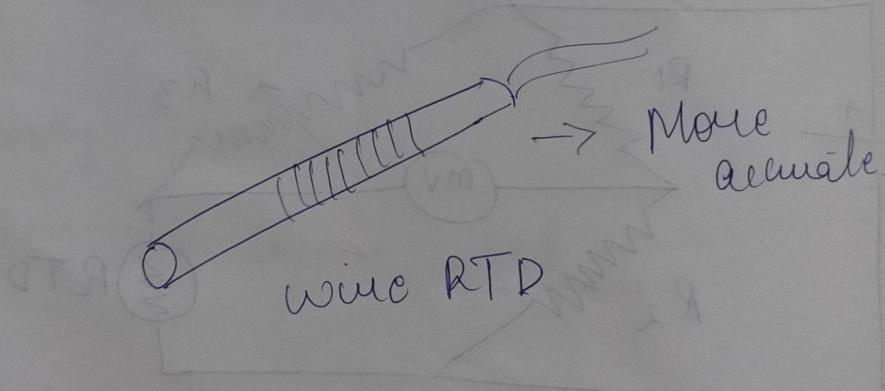
Nickel → less expensive
→ good corrosion resistance
→ less accuracy

Copper → range of measurement is less

Types of RTD

1) Wire type RTD

2) Film type RTD



Advantages of RTD for app

- 1) Good sensitivity
- 2) Linearity over wide operating range
- 3) Copper RTD minimize thermocouple effect

Disadvantage

- 1) Bulky in size & fragile
- 2) Self heating problem

Thermistor (Thermal + resistor)

THERM ally

controlled resistor

PTC: $T \uparrow R \uparrow$

NTC: $T \uparrow R \downarrow$

diff. types of thermistors shape

1) Disc Type

2) Bead "

cored type

different type of

1) DISC Type



→ ~~shelves~~ generate power dissipation
capacitor

2) Bead Type - very small size (0.15 mm diameter)

mostly used in industry

3) Rod Type - high power
slightly weak in handling
withstanding protection capacity

applications

1) digital thermometers

2) automotive applications

3) Household appliances

4) circuit protection

Thermistor

low cost

more accuracy

Thermistors are more accurate, cheaper and faster response than RTD.

Only element of Thermistor is narrow operating temperature range, which is wider for RTD

Advantages

1) compact, ie inexpensive

2) good stability

3) sensitivity

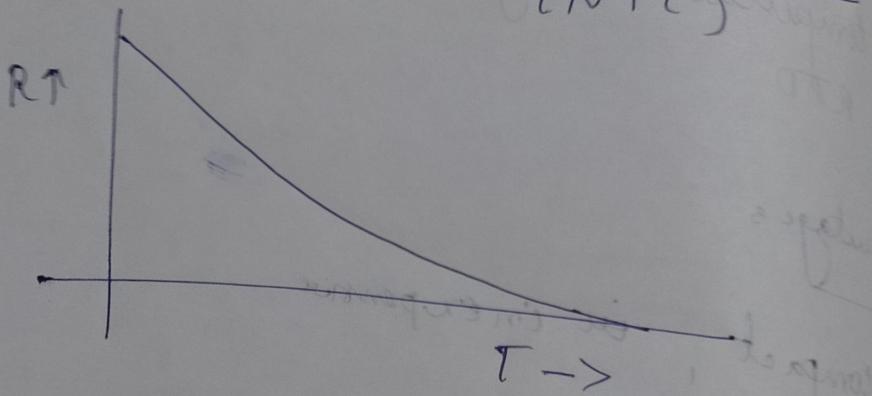
4) Faster response

does not get affected due to electric and magnetic fields

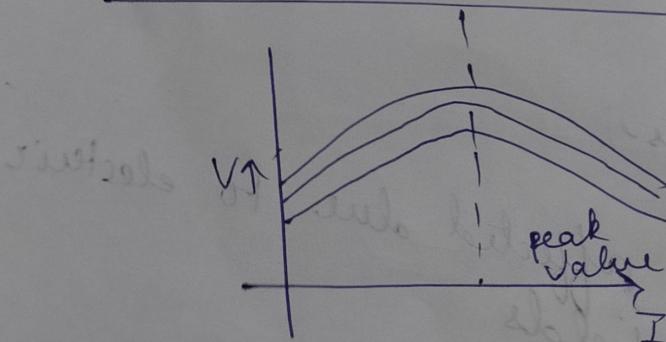
Characteristics of Thermistor

- 1) Resistance - Temperature characteristic
- 2) Voltage - Current
- 3) Current - Time

I Resistance - temperature characteristic (NTC)



II Voltage current characteristic



$I \uparrow$ $V \uparrow$ after peak $V \downarrow I \uparrow$

Reason: Initially I is small, it's not produce a change in temp. So voltage drop \uparrow

After peak value, $I \uparrow$, R_L , $V \downarrow$,

current-time charac

