

**18CSE390T**  
**Computer Vision**

Fourier-Based Alignment

# Fourier-Based Alignment

Fourier-based alignment relies on the fact that the Fourier transform of a shifted signal has the same magnitude as the original signal but a linearly varying phase

$$\mathcal{F}\{I_1(x+u)\} = \mathcal{F}\{I_1(x)\} e^{-ju\omega} = I_1(\omega) e^{-ju\omega},$$

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- where  $\omega$  is the vector-valued angular frequency of the Fourier transform and we use calligraphic notation  $I_1(\omega) = \mathcal{F} \{I_1(x)\}$  to denote the Fourier transform of a signal
- Another useful property of Fourier transforms is that convolution in the spatial domain corresponds to multiplication in the Fourier domain

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Fourier transform of the cross-correlation function ECC can be written as

$$\mathcal{F}\{E_{CC}(\mathbf{u})\} = \mathcal{F}\left\{\sum_i I_0(\mathbf{x}_i)I_1(\mathbf{x}_i + \mathbf{u})\right\} = \mathcal{F}\{I_0(\mathbf{u})\bar{*}I_1(\mathbf{u})\} = \mathcal{I}_0(\boldsymbol{\omega})\mathcal{I}_1^*(\boldsymbol{\omega}),$$

where

$$f(\mathbf{u})\bar{*}g(\mathbf{u}) = \sum_i f(\mathbf{x}_i)g(\mathbf{x}_i + \mathbf{u})$$

is the correlation function, i.e., the convolution of one signal with the reverse of the other, and  $\mathcal{I}_1^*(\boldsymbol{\omega})$  is the complex conjugate of  $\mathcal{I}_1(\boldsymbol{\omega})$

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- While Fourier-based convolution is often used to accelerate the computation of image correlations, it can also be used to accelerate the sum of squared differences function (and its variants)
- Its Fourier transform can be written as

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$$\begin{aligned}\mathcal{F}\{E_{\text{SSD}}(\mathbf{u})\} &= \mathcal{F}\left\{\sum_i |I_1(\mathbf{x}_i + \mathbf{u}) - I_0(\mathbf{x}_i)|^2\right\} \\ &= \delta(\omega) \sum_i |I_0^2(\mathbf{x}_i) + I_1^2(\mathbf{x}_i)| - 2I_0(\omega)I_1^*(\omega).\end{aligned}$$

SSD function can be computed by taking twice the correlation function and subtracting it from the sum of the energies in the two images.