

THEORY OF COMPUTATION

Introduction to the TOC

The purpose of TOC is to develop formal mathematical models of computation that reflect real-world computers.

TOC's areas:

- i) Complexity theory - classify problems according to their degree of difficulty
- ii) Computation theory - solvable / unsolvable
- iii) Automata theory - work with different types of computation model.

Example: Finite Automata - text processing, compiler
 context-free grammar - define programming lang., AI
 Turing machine - Abstract model of real computer

UNIT I: FINITE AUTOMATA

BASIC MATHEMATICAL NOTATION AND TECHNIQUES:

ALPHABET

An alphabet is a finite, non-empty set of symbols and Σ is used to represent alphabet.

$$\text{eg: } \Sigma = \{a, b\} \quad \{0, 1, 2, \dots\}$$

STRING:

A string is a finite sequence of symbols chosen from some alphabet

$$\Sigma = \{0, 1\} \text{ string: } 0, 1, 00, 11, 01, 10, \dots$$

$$\Sigma = \{a, b, c\}$$

$$ab, abc, bac, ..., aaaa, \dots$$

String Operations

(i) Empty String :

String with zero occurrence of symbols and represented by C (epsilon)

(ii) Length of a string

No. of positions for symbols in string (or) no. of symbols.

(iii) Power of the Alphabet

No. of occurrences of particular alphabet

$$\Sigma^0 = \emptyset$$

$$\Sigma^1 = \{0, 1\}$$

$$\Sigma^2 = \{00, 01, 10, 11\}$$

$$\Sigma^3 = \{000, 001, 010, 011, 100, 101, 110, 111\}$$

(iv) Concatenation of string

$x = ab, y = cd \text{ then } xy = abcd$

(v) Reverse (w^R)

$$w = ab, w^R = ba$$

(vi) Substring

String $w = \underline{abcd}$

$$\text{substring} = bc$$

LANGUAGE:

Set of all strings which are chosen from some Σ^* where Σ is an alphabet.

Kleene closure

$$\Sigma^* \rightarrow \Sigma^+ \cup \{\epsilon\} \geq 0$$

positive closure

$$\Sigma^+ \rightarrow \Sigma^1 \cup \Sigma^2 \cup \dots \geq 1$$

WORKING WITH SET

- * Set element / Member
- * subset [subset should not be equal to set]
- * Proper subset
- * Multiset [multiple occurrence of elements]
- * Infinite set
- * Integer \mathbb{Z}
- * Empty set \emptyset
- * Singleton set
- * Unordered pair
- * Union, intersection, complement
- * Sequence $(0, 1, 2) \neq (1, 2, 0)$
- * Finite (TUPLE)
- * Infinite
- * Power set
- * Cartesian product or cross product

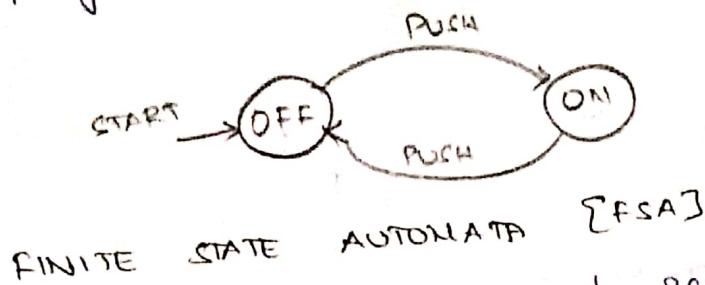
$$\begin{matrix} a & b \\ ab & ba \\ a & \\ b & \\ ab & \end{matrix} \in \mathcal{E}$$

$$\Sigma = \{0, 1\}$$

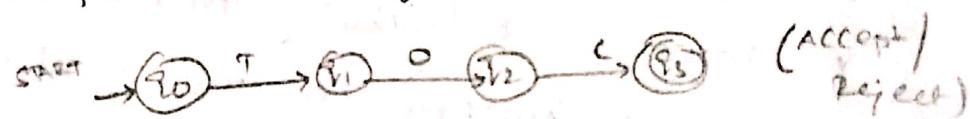
$$w \in \{0, 1\}^*$$

FINITE STATE M/C OR STATE M/C [FSM]

It is a mathematical model of computation used to design both computer programs and sequential circuits.



It is used to recognize patterns from some character sets without inputs taken from some character sets.



Finite automaton can be represented by a

5-tuple $(Q, \Sigma, \delta, q_0, F)$

* Q - finite nonempty set of states

* Σ - finite nonempty set of inputs - ifp alphabet

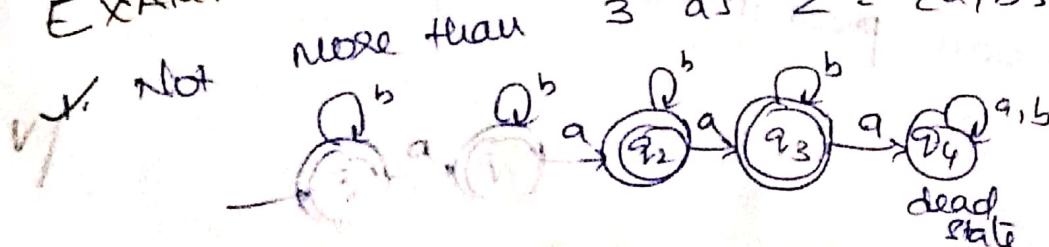
* δ - Transition function which maps $Q \times \Sigma \rightarrow Q$

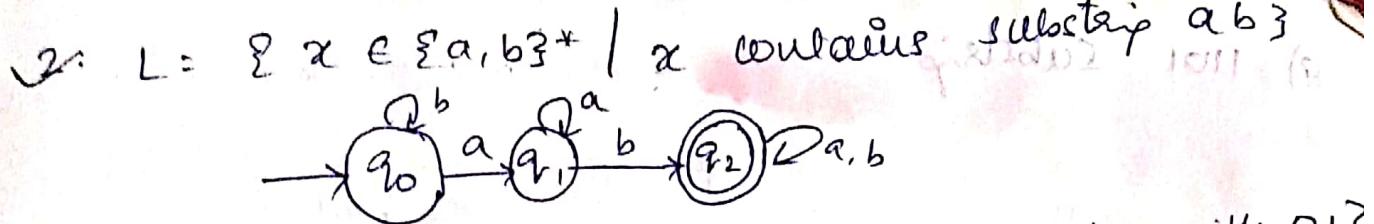
* $q_0 \in Q$ is initial state

* $F \subseteq Q$ set of final states

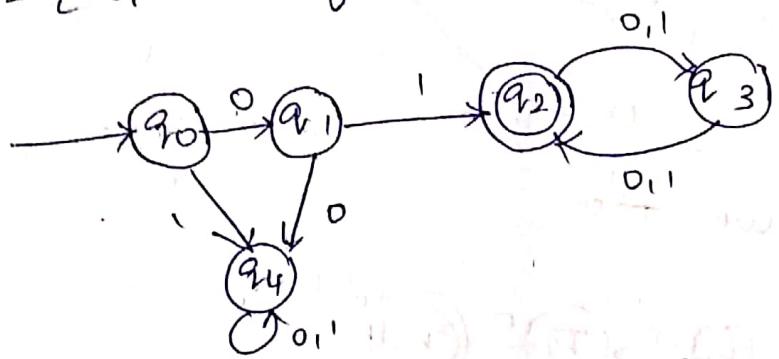
EXAMPLES OF DETERMINISTIC FINITE AUTOMATA

Not more than 3 a's. $\Sigma = \{a, b\}$

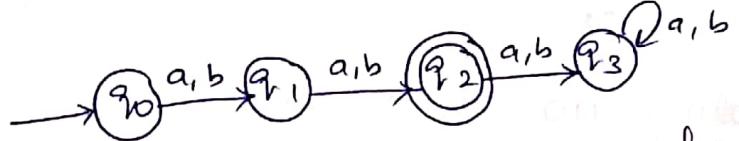




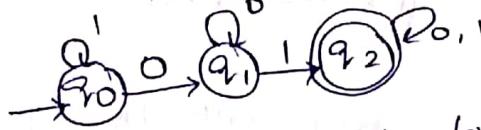
3. $L = \{w \mid w \text{ is of even length \& begins with } 01\}$



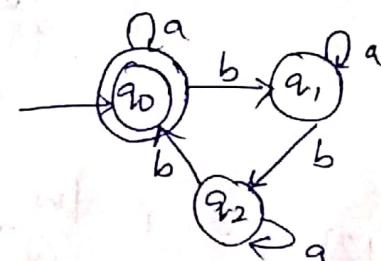
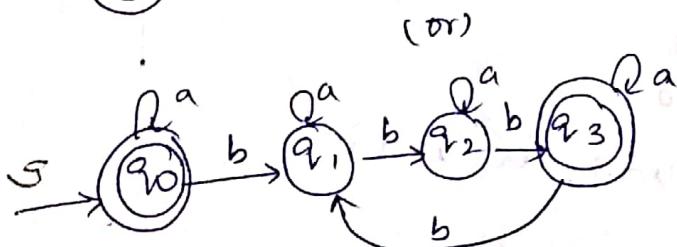
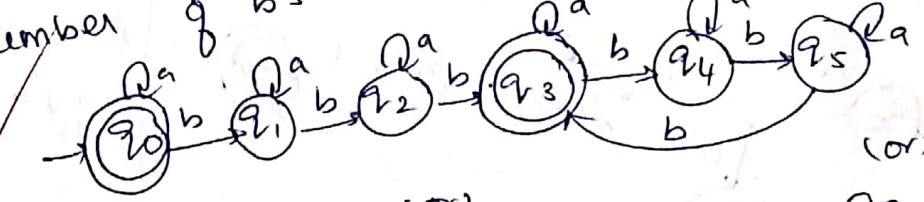
4. $\Sigma = \{a,b\}$ string length is 2



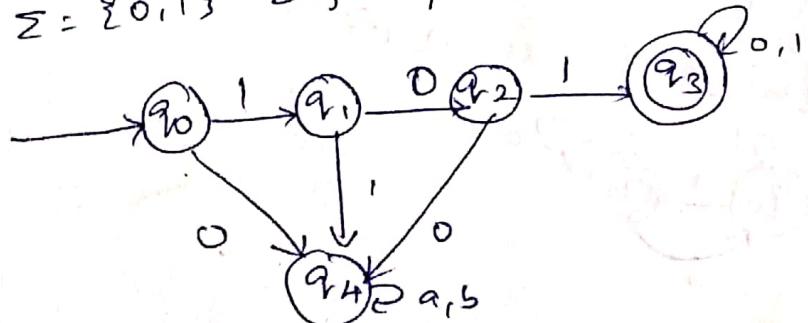
5. $\Sigma = \{0,1,3\}$ sequence 01 somewhere in the string



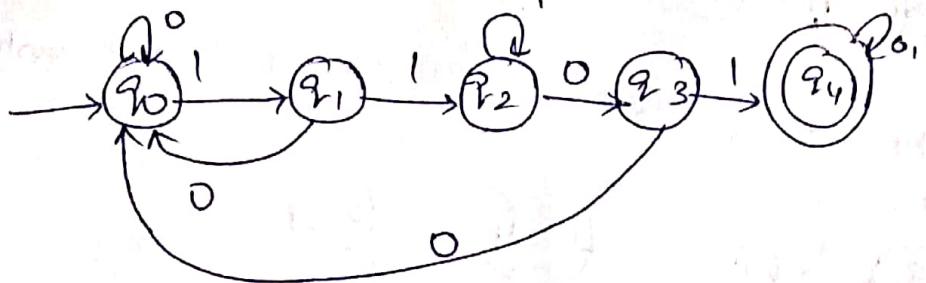
6. number of b's divisible by 3



7. $\Sigma = \{0,1,3\}$ beginning with 101



8) 1101 Substring



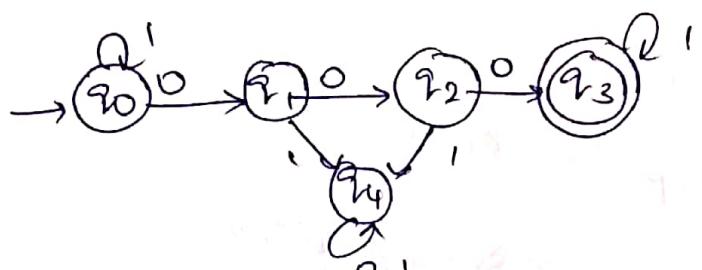
i/ 1101

14)

0011011

15)

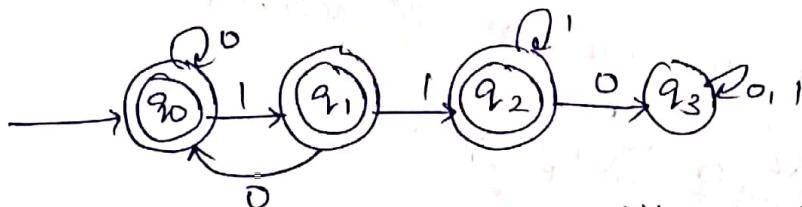
9) 3 consecutive 0's



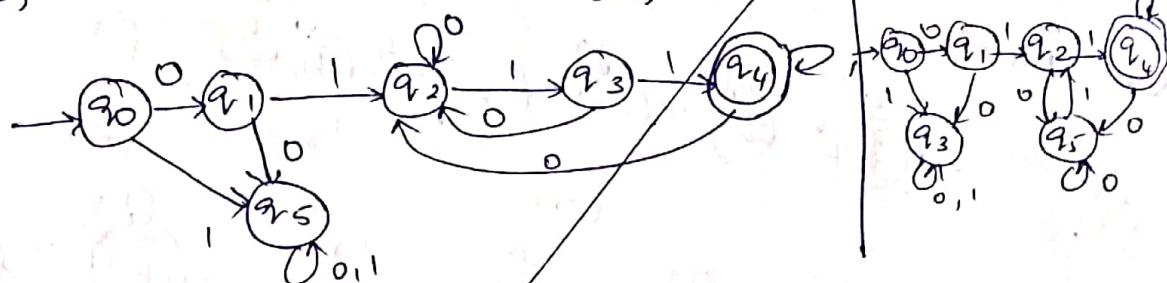
③ 0011011

16)

10) Not containing 110



11) Begins with 01 & ends with 11
length: 4



length: 3

12) $L = \{w | w \text{ ends in a } 1^3\}$



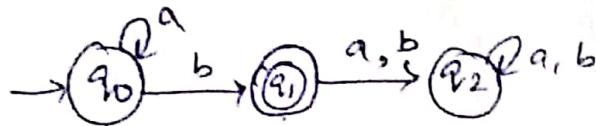
12) $L = \{w | w \text{ ends in a } 0^3\}$



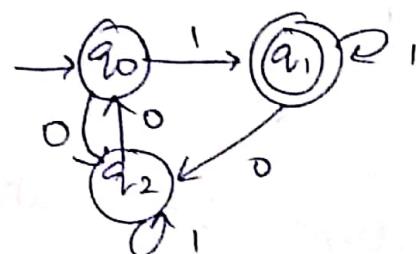
17)

18)

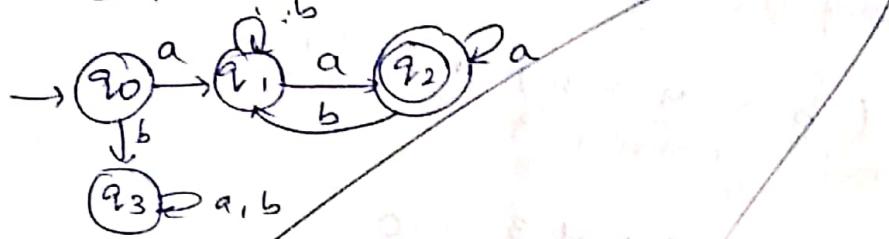
14) $L = \{a^n b : n \geq 0\}$



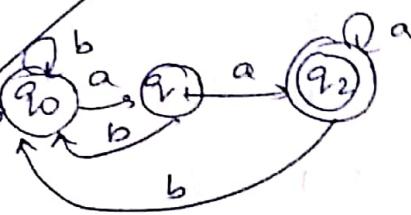
✓ 15) $L = \{w | w \text{ contains at least one } 1 \text{ and an even number of } 0's \text{ followed by the last } 1\}$



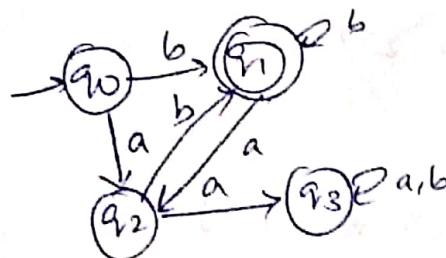
16) $L = \{a^i b a^j : i \in \{0, 1\}^*\}$



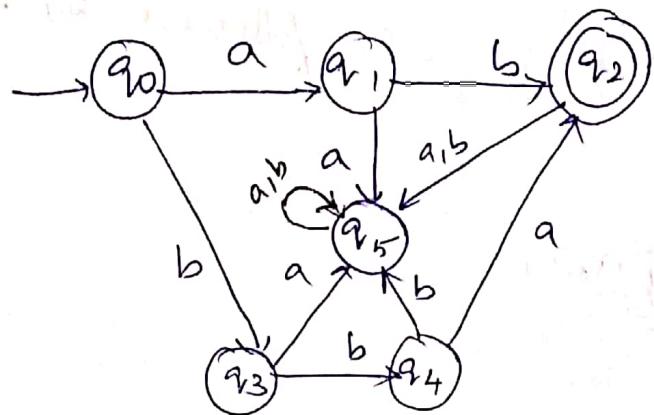
17) $L = \{w | w \in \{a, b\}^* \text{ ends with } aa^3\}$



✓ 18) Ends with b and doesn't contain aa



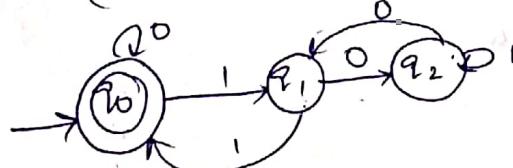
19) strip contains either ab (or) bba



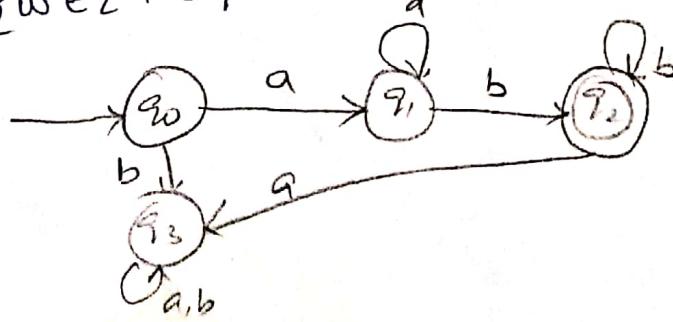
20) $\Sigma = \{0, 1\}^3$ set of all strips when interpreted as binary integer is multiple of 3

$$\begin{array}{l}
 \text{Base start state: } i/p \\
 \text{mod value: } i/p \\
 \text{mod } 3 \rightarrow \text{number} \\
 \text{end state: } i/p
 \end{array}$$

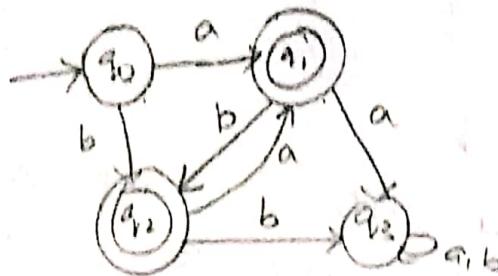
$$\begin{aligned}
 & (2 * 0 + 0) \bmod 3 = 0 \\
 & (2 * 0 + 1) \bmod 3 = 1 \\
 & (2 * 1 + 0) \bmod 3 = 2 \\
 & (2 * 1 + 1) \bmod 3 = 0 \\
 & (2 * 2 + 0) \bmod 3 = 1 \\
 & (2 * 2 + 1) \bmod 3 = 2
 \end{aligned}$$



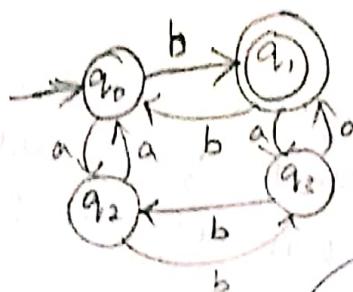
21) $L = \{w \in \{a, b\}^* \mid w = a^n b^m, n, m > 0\}$



22) $L = \{w \mid w \in \{a, b\}^*, w \text{ has neither aa nor bb as substring}\}$



23) $L = \{w \mid w \in \{a, b\}^*, \text{ odd number of } b's \text{ & even no. of } a's\}$



LANGUAGE

Let $M = (\Sigma, Q, S, T, F)$ be a finite automaton. The language $L(M)$ accepted by M is defined to be the set of all strings that are accepted by M .

$L(M) = \{w \mid w \text{ is a string over } \Sigma \text{ and } M \text{ accepts } w\}$

LANGUAGE IS REGULAR

A language L is called regular if and only if there exists some deterministic finite acceptor M such that $L = L(M)$

NOTATIONS:

1. Language
2. Transition diagram
3. Transition table

FUNCTION OF DFA (ETE)

BASIS:

$$\hat{\delta}(q, \epsilon) = q$$

If we are in a state q and read no input then we are still in the same state q .

INDUCTION:

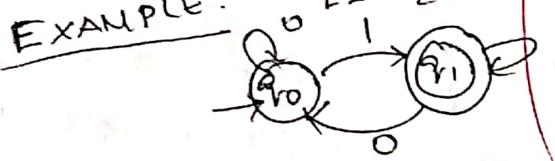
w is the strip of the form $w = x a$, where a is the last symbol of w and x is a strip consisting of all but not the last symbol.

ex: $w = 1101$; $x = 110$, $a = 1$

$$\hat{\delta}(q, w) = \hat{\delta}(\hat{\delta}(q, x), a)$$

To compute $\hat{\delta}(q, w)$, first compute $\hat{\delta}(q, x)$. Suppose $\hat{\delta}(q, x) = p$, then $\hat{\delta}(q, w) = \delta(p, a)$

EXAMPLE:



$$w = 001$$

$$\hat{\delta}(q_0, \epsilon) = q_0$$

$$\hat{\delta}(q_0, 0) = \delta(\hat{\delta}(q_0, \epsilon), 0) = \delta(q_0, 0) = q_0$$

$$\hat{\delta}(q_0, 0) = \delta(\hat{\delta}(q_0, 0), 0) = \delta(q_0, 0) = q_0$$

$$\hat{\delta}(q_0, 00) = \delta(\hat{\delta}(q_0, 0), 0) = \delta(q_0, 0) = q_0$$

$$\hat{\delta}(q_0, 001) = \delta(\hat{\delta}(q_0, 00), 1) = \delta(q_0, 1) = q_1$$

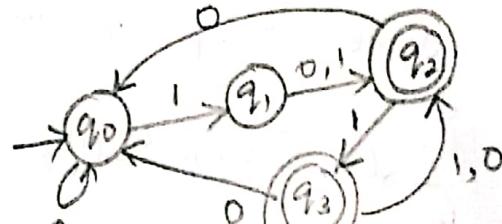
δ	0	1
$\rightarrow q_0$	q_0	q_1
$\rightarrow q_1$	q_0	q_1

NON - DETERMINISTIC FINITE AUTOMATA (NFA)

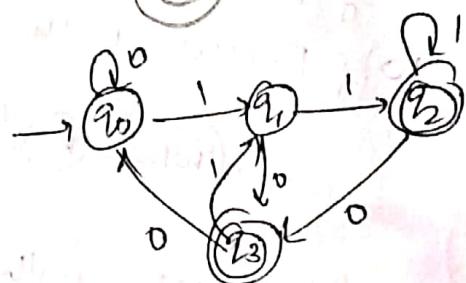
\rightarrow models of search-and-backtrack algorithm & simplicity
in tuple notation $(Q, \Sigma, \delta, q_0, F)$

$$\delta = \Sigma \times Q \rightarrow 2^Q$$

1. Second last symbol is 1, $\Sigma = \{0, 1\}$



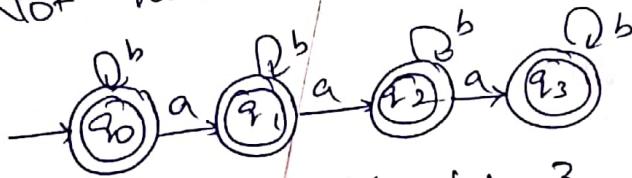
2. Ends with a



3. $(a|b)^* ab$



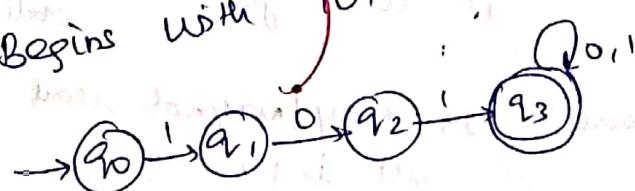
4. Not more than 3 a's



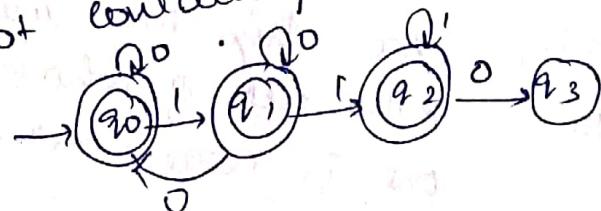
5. No. of b's divisible by 3



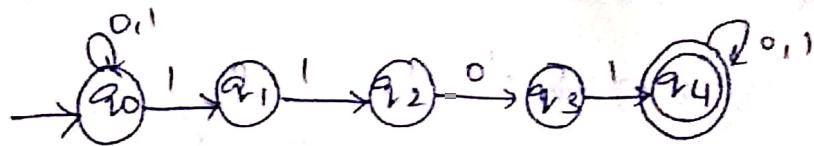
6. Begins with 101



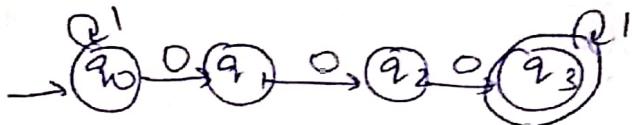
7. Not containing 110



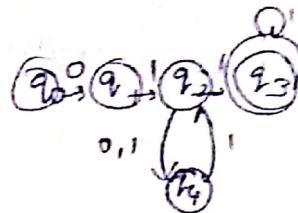
8) substring 1101



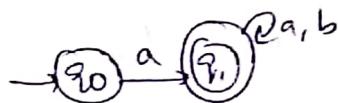
9) starts Exactly 3 consecutive 0's



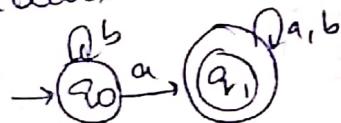
10) begins with 01 ends with 11



11) starts with a



12) contains a



DFA

1. $\delta: Q \times \Sigma \rightarrow Q$

2. Reading one input, moves to only one state

3. All states has to read all ips

A. For an accepted strip, there is only one path

NFA

$\delta: Q \times \Sigma \rightarrow 2^Q$

On reading one input, it can go to zero or more states

It may/may not read all inputs

Acc strip has many paths out of which only one is correct path.

EXTENDED TRANSITION FUNCTION FOR NFA (ETF)

BASIS:

$$\hat{\delta}(q, \epsilon) = \{q\}$$

Being in state Readip no input, the system remains in the same state

INDUCTION:

Suppose $w = \alpha a$, where a is the final input and x is rest of input.

$$\hat{\delta}(q, x) = \{p_1, p_2, \dots, p_k\}$$

$$\text{Let } \bigcup_{i=1}^k \delta(p_i, a) = \{q_1, q_2, \dots, q_m\}$$

$$\text{Then } \hat{\delta}(q, w) = \{q_1, q_2, \dots, q_m\}$$

$\hat{\delta}(q, w)$ is computed by first computing $\hat{\delta}(q, a)$ in those states that is labelled a . Then $\hat{\delta}(q, x)$ and by then following any transition from any of those states to that is labelled a .



	0	1
q0	{q0}	{q0, q1}
q1	{q2}	{q2}
q2	Ø	Ø

$$\hat{\delta}(q_0, \epsilon) = \{q_0\}$$

$$\hat{\delta}(q_0, 0) = \hat{\delta}(\hat{\delta}(q_0, \epsilon), 0) = \hat{\delta}(\{q_0\}, 0) = \{q_0\}$$

$$\hat{\delta}(q_0, 01) = \hat{\delta}(\hat{\delta}(q_0, 0), 1) = \hat{\delta}(\{q_0\}, 1) = \{q_0, q_1\}$$

$$\hat{\delta}(q_0, 010) = \hat{\delta}(\hat{\delta}(q_0, 01), 0) = \hat{\delta}(\{q_0, q_1\}, 0) = \{q_0\} \cup \{q_2\} = \{q_0, q_2\}$$

$$\hat{\delta}(q_0, 010) = \hat{\delta}(\hat{\delta}(q_0, 0), 10) = \hat{\delta}(\{q_0\}, 10) = \{q_0, q_1, q_2\}$$

LANGUAGE

$$L(A) = \{w \mid \hat{\delta}(q_0, w) \cap F \neq \emptyset\}$$

METHODS OF NFA & DFA

METHODS OF CONVERSION

- * SUBSET construction
- * LAZY construction

11

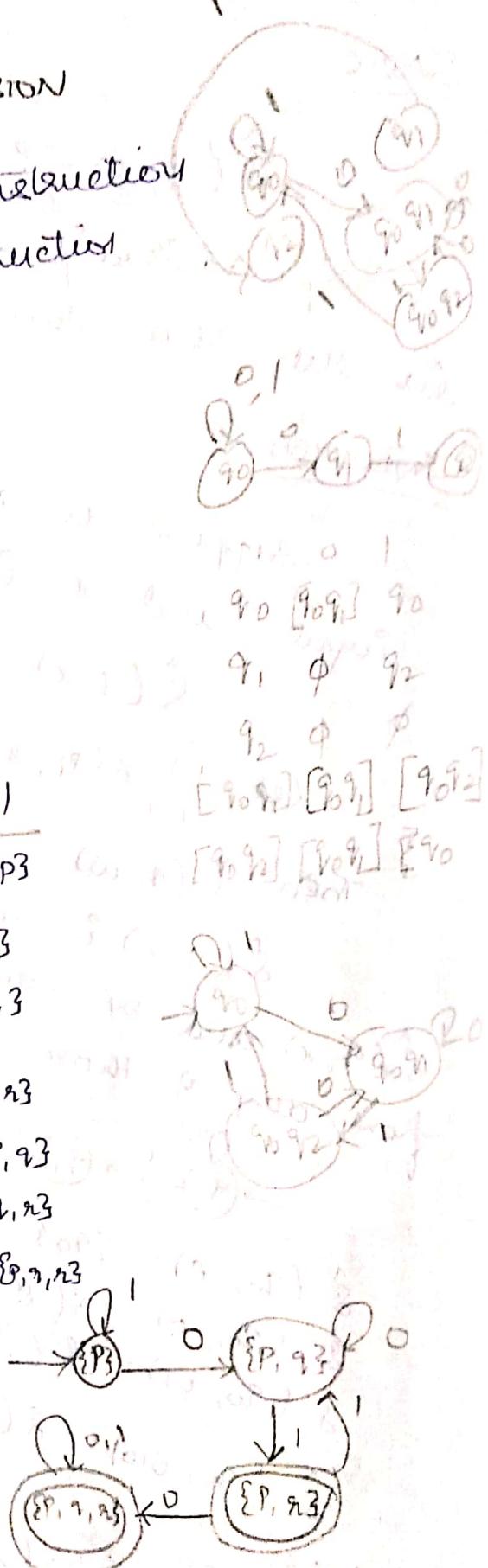
δ	0	1
$\rightarrow P$	$\{\bar{P}, q_3\}$	$\{\bar{P}\}$
q	\emptyset	$\{\bar{q}\}$
$\times \bar{q}$	$\{\bar{P}, q_3\}$	$\{\bar{q}\}$

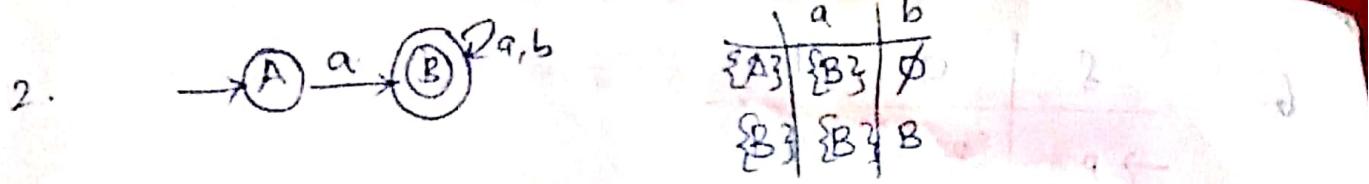
LAZY CONSTRUCTION

$\rightarrow \delta$	0	1
P:	$\{\bar{P}, q_3\}$	$\{\bar{P}\}$
q:	\emptyset	$\{\bar{q}\}$
$\times \bar{q}$	$\{\bar{P}, q_3\}$	$\{\bar{q}\}$
$\times \bar{P}$	$\{\bar{P}, q_3\}$	$\{\bar{q}_1, q_3\}$
$\times q_1$	$\{\bar{P}, q_3\}$	$\{\bar{q}_1, q_3\}$
$\times q_2$	$\{\bar{P}, q_3\}$	$\{\bar{q}_2, q_3\}$
$\times q_3$	$\{\bar{P}, q_3\}$	$\{\bar{q}_1, q_3\}$
$\times \bar{q}_1$	$\{\bar{P}, q_1, q_3\}$	$\{\bar{q}_1, q_3\}$
$\times \bar{q}_2$	$\{\bar{P}, q_1, q_3\}$	$\{\bar{q}_1, q_2, q_3\}$
$\times \bar{q}_3$	$\{\bar{P}, q_1, q_3\}$	$\{\bar{q}_1, q_2, q_3\}$

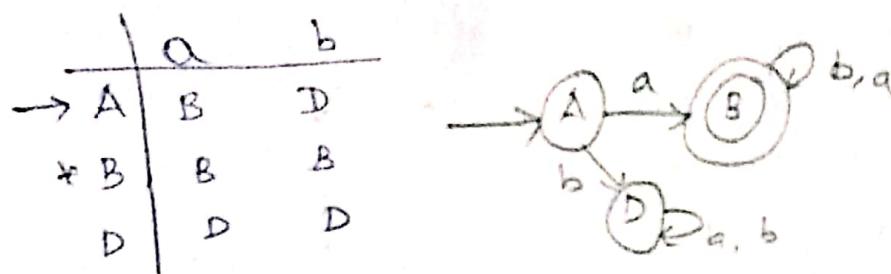
SUBSET CONSTRUCTION

δ	0	1
$\rightarrow \{\bar{P}\}$	$\{\bar{P}, q_3\}$	$\{\bar{P}\}$
$\times \{\bar{P}\}$	$\{\bar{P}, q_3\}$	$\{\bar{P}, q_3\}$
$\times \{\bar{P}, q_3\}$	$\{\bar{P}, q_3\}$	$\{\bar{P}, q_3\}$

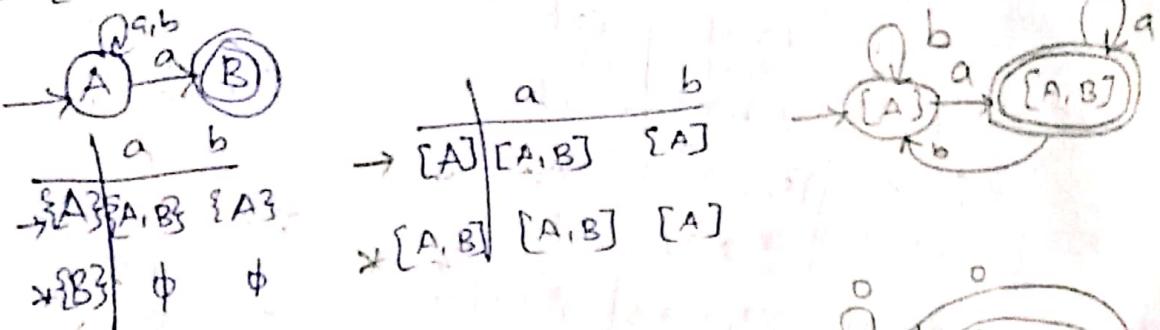




a	b
{A}	{B}
{B}	{B}
	B



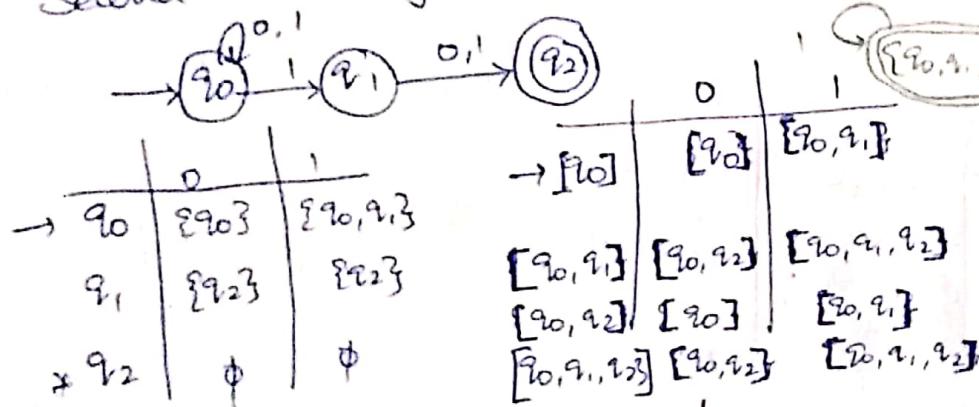
3. $L = \{ \text{ends with an } a \}$ $Z = \{ a, b \}$



a	b
{A}	{A, B}
{B}	∅

[A]	[A, B]	[A]
[A, B]	[A, B]	[A]

4. Second last symbol is 1

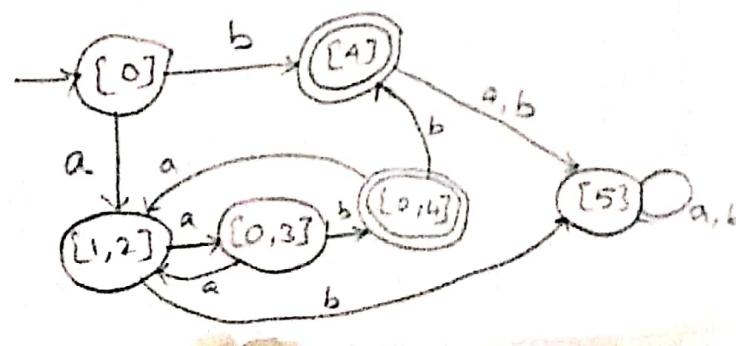


0	1
[q ₀]	[q ₀] [q ₀ , q ₁]
[q ₀ , q ₁]	[q ₀ , q ₂] [q ₁ , q ₂]
[q ₀ , q ₂]	[q ₀] [q ₂]
[q ₀ , q ₁ , q ₂]	[q ₀ , q ₁ , q ₂] [q ₁ , q ₂]

5.

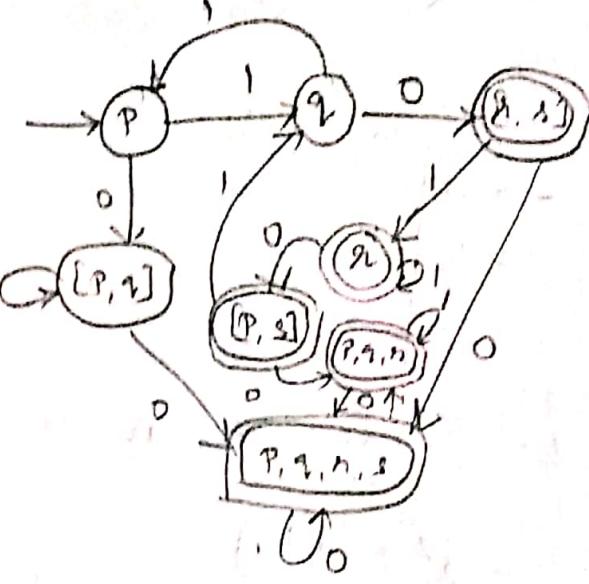
s	a	b
0	{1, 2, 3}	{4, 5}
1	{0, 3}	∅
2	{2, 3}	∅
3	∅	{0, 3}
4	∅	∅

s	a	b
[0]	[1, 2]	[4]
* [4]	r [5] D	[5] r D
[1, 2]	[0, 3]	[5] D
[0, 3]	[1, 2]	[0, 4]
* [0, 4]	[1, 2]	[4]
[5]	[5]	[5]



6.

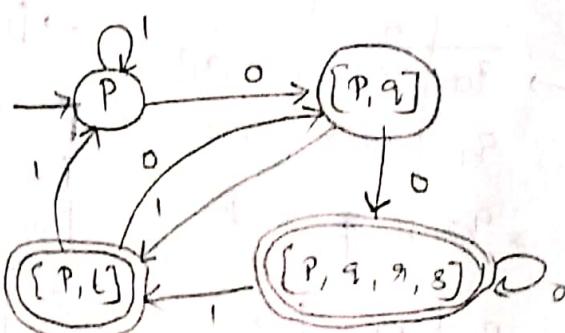
δ	0	1
$\rightarrow P$	$\{P, q\}$	$\{q\}$
q	$\{q, r\}$	$\{P, r\}$
$\times r$	$\{P, r\}$	$\{r\}$
$\times s$	$\{q, r\}$	\emptyset



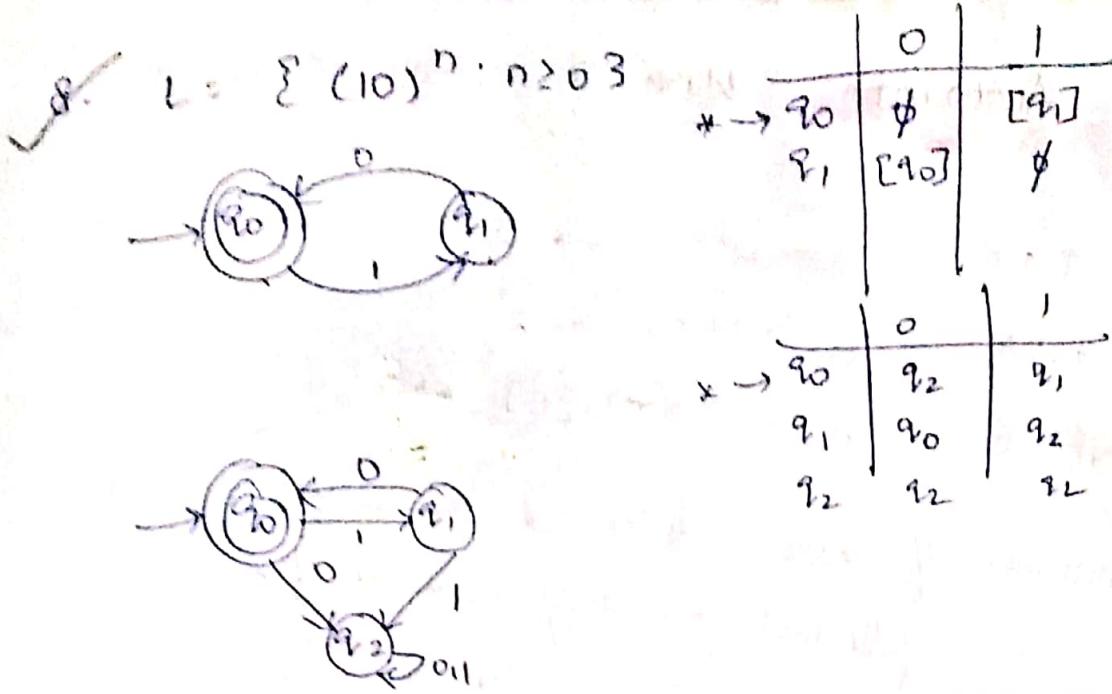
δ	0	1
$\rightarrow P$	$[P, q]$	$[q]$
q	$[q, r]$	$[P]$
$\times r$	$[P, r]$	$[r]$
$\times \{P, q\}$	$[P, q, r, s]$	$[P, q]$
$\times \{q, r\}$	$[P, q, r, s]$	$[q]$
$\times \{P, r\}$	$[P, q, r, s]$	$[q, r]$
$\times \{q, s\}$	$[P, q, r, s]$	$[q, r, s]$
$\times \{P, q, r, s\}$	$[P, q, r, s]$	$[P, q, r]$

7/

δ	0	1
$\rightarrow P$	$\{P, q\}$	$\{P\}$
q	$\{q, r\}$	$\{q\}$
r	$\{P, r\}$	$\{r\}$
$\times s$	\emptyset	\emptyset
$\times t$	\emptyset	\emptyset



δ	0	1
$\rightarrow P$	$[P, q]$	$[P]$
$\times \{P, q\}$	$[P, q, r, s]$	$[P, t]$
$\times \{P, t\}$	$[P, q]$	$[P]$
$\times \{P, q, r, s\}$	$[P, q, r, s]$	$[P, t]$



CONVERTING NFA TO DFA - Theorem [JUNE 2016]

If $D = (Q_D, \Sigma, \delta_D, \{q_0\}, F_D)$ is the DFA constructed from NFA $N = (Q_N, \Sigma, \delta_N, q_0, F_N)$ by subset construction, then $L(D) = L(N)$

BASIS

$$|\omega| = 0 \quad \omega = \epsilon \\ \hat{\delta}_D(\{q_0\}, \epsilon) = \hat{\delta}_N(q_0, \epsilon) = q_0$$

INDUCTION.

Let $\omega = x a$ where a is the final symbol of ω .
Let $\omega = x a$ where a is the final symbol of ω .

$$\omega \text{ by inductive hypothesis.} \\ \hat{\delta}_D(\{q_0\}, x) = \hat{\delta}_N(q_0, x)$$

Let both these sets of N -states reach $\{p_1, p_2, \dots, p_k\}$

$$\text{By inductive part of definition, NFA tells us} \\ \hat{\delta}_N(q_0, \omega) = \bigcup_{i=1}^k \delta_N(p_i, a)$$

The subset construction on the other hand tells us that

$$\hat{\delta}_D(\{q_0\}, \omega) = \bigcup_{i=1}^k \delta_D(p_i, a)$$

$$\text{we know, } \hat{\delta}_D(\{q_0\}, x) = \{p_1, p_2, \dots, p_k\}$$

$$\hat{\delta}_D(\{q_0\}, \omega) = \hat{\delta}_D(\hat{\delta}_D(\{q_0\}, x), a)$$

$$= \hat{\delta}_D(\{p_1, p_2, \dots, p_k\}, a)$$

$$= \bigcup_{i=1}^k \delta_N(p_i, a) = \hat{\delta}_N(q_0, \omega)$$

Hence $L(D) = L(N)$

FINITE AUTOMATA WITH EPSILON TRANSITION

DFA $\delta \Rightarrow Q \times \Sigma \rightarrow Q$

NFA $\delta \Rightarrow Q \times \Sigma \rightarrow 2^Q$

NFA- ϵ $\delta \Rightarrow Q \times \Sigma \cup \{\epsilon\} \rightarrow 2^Q$

1. Any number of zeros followed by any number of one's followed by any number of two's



[JUN 2014]

[DEC 2015]

[JUNE 2016]

012

01

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210*

0

$$\epsilon\text{-closure } (\{q_0\}) = \{q_0, q_1, q_2\}$$

$$\epsilon\text{-closure } (\{q_1\}) = \{q_1, q_2\}$$

$$\epsilon\text{-closure } (\{q_2\}) = \{q_2\}$$

$$\epsilon\text{-closure } (\delta(q_0, 0)) = \epsilon\text{-closure } (\delta(\{q_0, q_1, q_2\}, 0))$$

$$= \epsilon\text{-closure } (\{q_0\}) = \{q_0, q_1, q_2\}$$

$$\epsilon\text{-closure } (\delta(q_0, 1)) = \epsilon\text{-closure } (\delta(\{q_0, q_1, q_2\}, 1))$$

$$= \epsilon\text{-closure } (\{q_1\}) = \{q_1, q_2\}$$

$$\epsilon\text{-closure } (\delta(\{q_0, q_1, q_2\}, 2))$$

$$\epsilon\text{-closure } (\delta(q_0, 2)) = \epsilon\text{-closure } (\delta(\{q_2\}, 2)) = \{q_2\}$$

$$= \epsilon\text{-closure } (\{q_2\}) = \emptyset$$

$$\epsilon\text{-closure } (\delta(q_1, 0)) = \sim(\delta(\{q_1, q_2\}, 0)) = \sim(\emptyset) = \emptyset$$

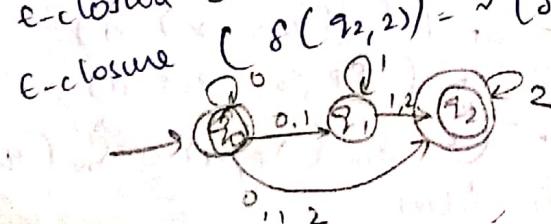
$$\epsilon\text{-closure } (\delta(q_1, 1)) = \sim(\delta(\{q_1, q_2\}, 1)) = \sim(\{q_1\}) = \{q_1, q_2\}$$

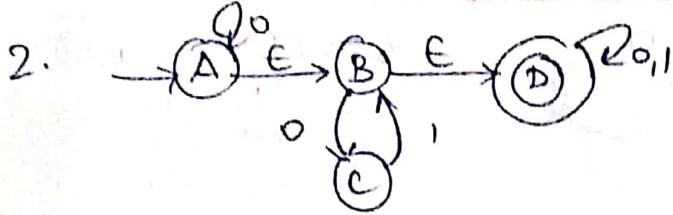
$$\epsilon\text{-closure } (\delta(q_1, 2)) = \sim(\delta(\{q_1, q_2\}, 2)) = \sim(\{q_2\}) = \{q_2\}$$

$$\epsilon\text{-closure } (\delta(q_2, 0)) = \sim(\delta(\{q_2\}, 0)) = \sim(\emptyset) = \emptyset$$

$$\epsilon\text{-closure } (\delta(q_2, 1)) = \sim(\delta(\{q_2\}, 1)) = \emptyset$$

$$\epsilon\text{-closure } (\delta(q_2, 2)) = \sim(\delta(\{q_2\}, 2)) = \sim(\{q_2\}) = \{q_2\}$$





ϵ -closure(A) = {A, B, D} ϵ -closure(B) = {B, D} ϵ -closure(C) = {C} ϵ -closure(D) = {D}

$$\epsilon\text{-closure}(\delta(A, 0)) = \sim(\delta(\{A, B, D\}, 0)) = \sim(A, C, D) = \{A, B, C, D\}$$

$$\epsilon\text{-closure}(\delta(A, 1)) = \sim(\delta(\{A, B, D\}, 1)) = \sim(D) = \{D\}$$

$$\epsilon\text{-closure}(\delta(B, 0)) = \sim(\delta(\{B, D\}, 0)) = \sim(D) = \{D\}$$

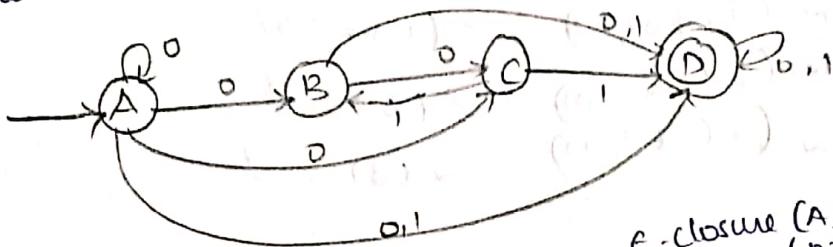
$$\epsilon\text{-closure}(\delta(B, 1)) = \sim(\delta(\{B, D\}, 1)) = \sim(D) = \{D\}$$

$$\epsilon\text{-closure}(\delta(C, 0)) = \sim(\delta(\{C\}, 0)) = \sim(\phi) = \emptyset$$

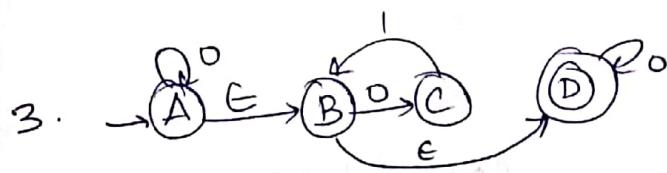
$$\epsilon\text{-closure}(\delta(C, 1)) = \sim(\delta(\{C\}, 1)) = \sim(B) = \{B, D\}$$

$$\epsilon\text{-closure}(\delta(D, 0)) = \sim(\delta(\{D\}, 0)) = \sim(D) = \{D\}$$

$$\epsilon\text{-closure}(\delta(D, 1)) = \sim(\delta(\{D\}, 1)) = \sim(D) = \{D\}$$



ϵ -closure(A) = {A, B, D} ϵ -closure(B) = {B, D} ϵ -closure(C) = {C} ϵ -closure(D) = {D}



$$\sim(\delta(A, 0)) = \sim(\delta(\{A, B, D\}, 0)) = \sim(A, C, D) = \{A, B, C, D\}$$

$$\sim(\delta(A, 1)) = \sim(\delta(\{A, B, D\}, 1)) = \sim(\phi) = \emptyset$$

$$\sim(\delta(B, 0)) = \sim(\delta(\{B, D\}, 0)) = \sim(C, D) = \{C, D\}$$

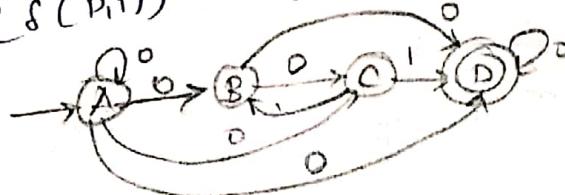
$$\sim(\delta(B, 1)) = \sim(\delta(\{B, D\}, 1)) = \sim(\phi) = \emptyset$$

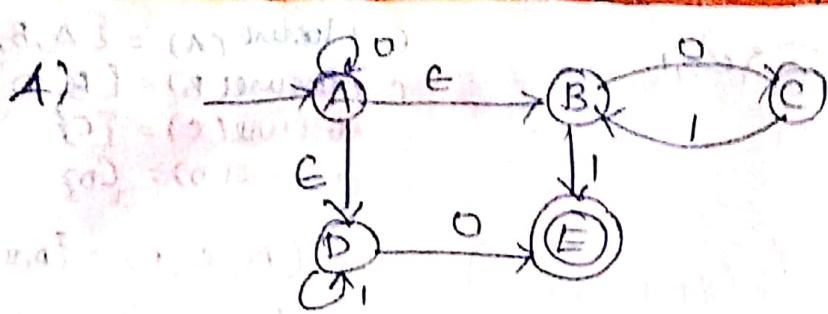
$$\sim(\delta(C, 0)) = \sim(\delta(\{C\}, 0)) = \sim(D) = \emptyset$$

$$\sim(\delta(C, 1)) = \sim(\delta(\{C\}, 1)) = \sim(B) = \{B, D\}$$

$$\sim(\delta(D, 0)) = \sim(\delta(\{D\}, 0)) = \sim(D) = \{D\}$$

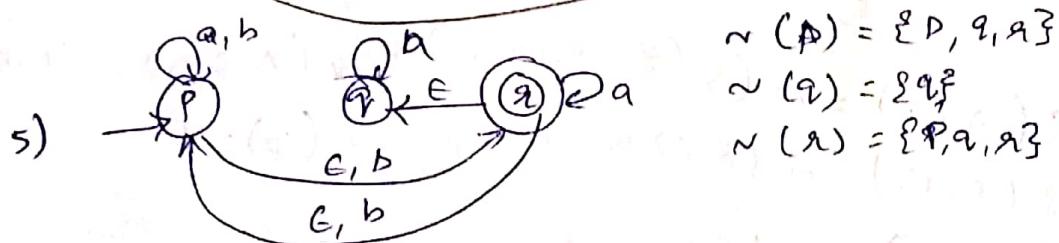
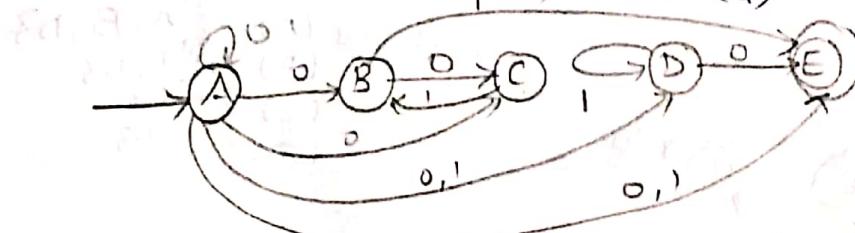
$$\sim(\delta(D, 1)) = \sim(\delta(\{D\}, 1)) = \sim(\phi) = \emptyset$$



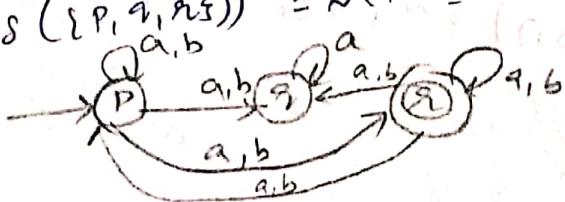


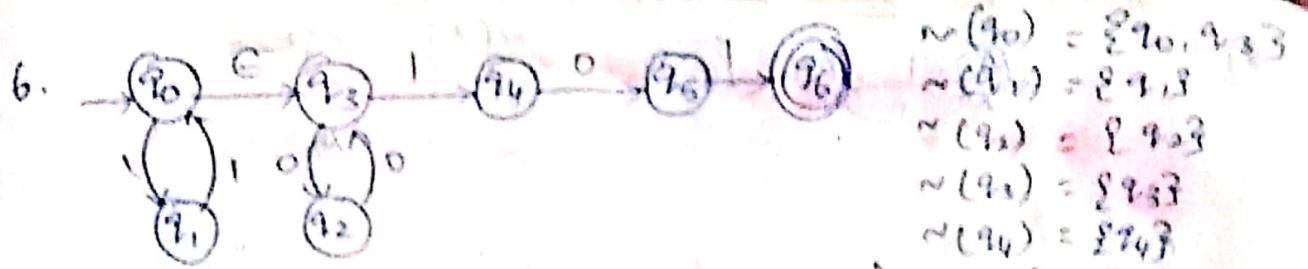
$\text{e-closure}(A) = \{A, B, D\}$
 $\sim (B) = \{B\}$
 $\sim (C) = \{C\}$
 $\sim (D) = \{D\}$
 $\sim (E) = \{E\}$

- $\sim \delta(A, 0) = \sim (\delta(\{A, B, D\}, 0)) = \sim (A, C, E) = \{A, B, C, D, E\}$
- $\sim \delta(A, 1) = \sim (\delta(\{A, B, D\}, 1)) = \sim (B) = \{B\}$
- $\sim \delta(B, 0) = \sim (\delta(\{B\}, 0)) = \sim (C) = \{C\}$
- $\sim \delta(B, 1) = \sim (\delta(\{B\}, 1)) = \sim (E) = \{E\}$
- $\sim \delta(C, 0) = \sim (\delta(\{C\}, 0)) = \sim (\phi) = \emptyset$
- $\sim \delta(C, 1) = \sim (\delta(\{C\}, 1)) = \sim (B) = \{B\}$
- $\sim \delta(D, 0) = \sim (\delta(\{D\}, 0)) = \sim (E) = \{E\}$
- $\sim \delta(D, 1) = \sim (\delta(\{D\}, 1)) = \sim (D) = \{D\}$
- $\sim \delta(E, 0) = \sim (\delta(\{E\}, 0)) = \sim (\phi) = \emptyset$
- $\sim \delta(E, 1) = \sim (\delta(\{E\}, 1)) = \sim (d) = \emptyset$



- $\sim (P) = \{P, Q, R\}$
- $\sim (Q) = \{Q\}$
- $\sim (R) = \{P, Q, R\}$
- $\sim \delta(P, a) = \sim (\delta(\{P, Q, R\}, a)) = \sim (P, Q, R) = \{P, Q, R\}$
- $\sim \delta(P, b) = \sim (\delta(\{P, Q, R\}, b)) = \sim (P) = \{P, Q, R\}$
- $\sim \delta(Q, a) = \sim (\delta(\{Q\}, a)) = \sim (Q) = \{Q\}$
- $\sim \delta(Q, b) = \sim (\delta(\{Q\}, b)) = \sim (\phi) = \emptyset$
- $\sim \delta(R, a) = \sim (\delta(\{P, Q, R\}, a)) = \sim (R) = \{P, Q, R\}$
- $\sim \delta(R, b) = \sim (\delta(\{P, Q, R\}, b)) = \sim (P) = \{P, Q, R\}$
- $\sim \delta(S, a) = \sim (\delta(\{P, Q, R\}, a)) = \sim (S) = \{P, Q, R\}$
- $\sim \delta(S, b) = \sim (\delta(\{P, Q, R\}, b)) = \sim (S) = \{P, Q, R\}$





$$\sim(\delta(q_0, 0)) = \sim(\delta(\delta(q_0, q_3, 0))) \text{ and } q_0 \sim q_6 = \{\delta\}$$

$$\sim(\delta(q_0, 1)) = \sim(\delta(\delta(q_0, q_3, 1))) = \sim(q_1) \cdot \delta q_3$$

$$\sim(\delta(q_1, 0)) = \sim(\delta(q_1, 0)) = \sim(\emptyset)$$

$$\sim(\delta(q_1, 1)) = \sim(\delta(q_1, 1)) = \sim(q_0) = \{\delta\}$$

$$\sim(\delta(q_2, 0)) = \sim(\delta(q_2, 0)) = \sim(q_3) = \{\delta\}$$

$$\sim(\delta(q_2, 1)) = \sim(\delta(q_2, 1)) = \sim(\emptyset) = \emptyset$$

$$\sim(\delta(q_3, 0)) = \sim(\delta(q_3, 0)) = \sim(q_4) = \{\delta\}$$

$$\sim(\delta(q_3, 1)) = \sim(\delta(q_3, 1)) = \sim(q_4) = \{\delta\}$$

$$\sim(\delta(q_4, 0)) = \sim(\delta(q_4, 0)) = \sim(q_5) = \{\delta\}$$

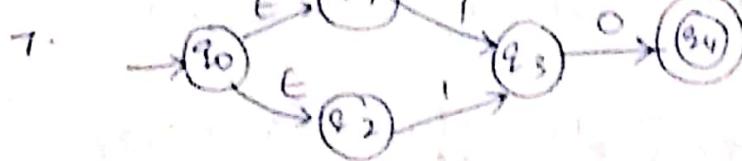
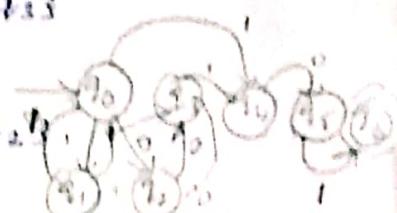
$$\sim(\delta(q_4, 1)) = \sim(\delta(q_4, 1)) = \sim(\emptyset) = \emptyset$$

$$\sim(\delta(q_5, 0)) = \sim(\delta(q_5, 0)) = \sim(q_6) = \{\delta\}$$

$$\sim(\delta(q_5, 1)) = \sim(\delta(q_5, 1)) = \sim(q_6) = \{\delta\}$$

$$\sim(\delta(q_6, 0)) = \sim(\delta(q_6, 0)) = \sim(\emptyset) = \emptyset$$

$$\sim(\delta(q_6, 1)) = \sim(\delta(q_6, 1)) = \sim(\emptyset) = \emptyset$$



$$\begin{aligned} \sim(q_0) &= \{\delta\}, q_1, q_2 \\ \sim(q_2) &= \{\delta\} \\ \sim(q_3) &= \{\delta\} \\ \sim(q_4) &= \{\delta\} \end{aligned}$$

$$\sim(\delta(q_0, 0)) = \sim(\delta(\delta(q_0, q_1, q_2, 0))) = \sim(\emptyset) = \emptyset$$

$$\sim(\delta(q_0, 1)) = \sim(\delta(\delta(q_0, q_1, q_2, 1))) = \sim(q_3) = \{\delta\}$$

$$\sim(\delta(q_1, 0)) = \sim(\delta(q_1, 0)) = \sim(\emptyset) = \emptyset$$

$$\sim(\delta(q_1, 1)) = \sim(\delta(q_1, 1)) = \sim(q_3) = \{\delta\}$$

$$\sim(\delta(q_2, 0)) = \sim(\delta(q_2, 0)) = \sim(\emptyset) = \emptyset$$

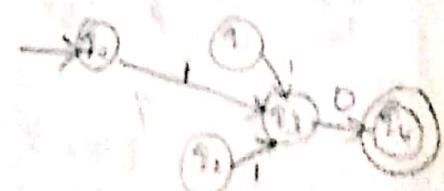
$$\sim(\delta(q_2, 1)) = \sim(\delta(q_2, 1)) = \sim(q_3) = \{\delta\}$$

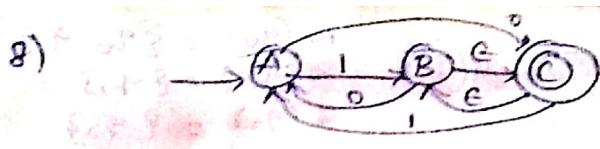
$$\sim(\delta(q_3, 0)) = \sim(\delta(q_3, 0)) = \sim(q_4) = \{\delta\}$$

$$\sim(\delta(q_3, 1)) = \sim(\delta(q_3, 1)) = \sim(\emptyset) = \emptyset$$

$$\sim(\delta(q_4, 0)) = \sim(\delta(q_4, 0)) = \sim(\emptyset) = \emptyset$$

$$\sim(\delta(q_4, 1)) = \sim(\delta(q_4, 1)) = \sim(\emptyset) = \emptyset$$





$$\sim(A) = \{A\}$$

$$\sim(B) = \{B, C\}$$

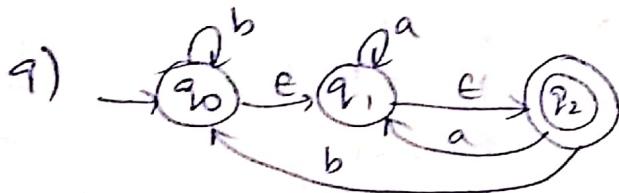
$$\sim(C) = \{C, B\}$$

A language

iff L

BASIS

$$\begin{aligned}\sim(\delta(A, 0)) &= \sim(\delta(\{A\}, 0)) = \sim(C) = \{C, B\} \\ \sim(\delta(A, 1)) &= \sim(\delta(\{A\}, 1)) = \sim(B) = \{B, C\} \\ \sim(\delta(B, 0)) &= \sim(\delta(\{B, C\}, 0)) = \sim(A) = \{A\} \\ \sim(\delta(B, 1)) &= \sim(\delta(\{B, C\}, 1)) = \sim(C) = \{C, B\} \\ \sim(\delta(C, 0)) &= \sim(\delta(\{C\}, 0)) = \sim(A) = \{A\} \\ \sim(\delta(C, 1)) &= \sim(\delta(\{C\}, 1)) = \sim(A) = \{A\}\end{aligned}$$



$$\sim(q_0) = \{q_0, q_1, q_2\}$$

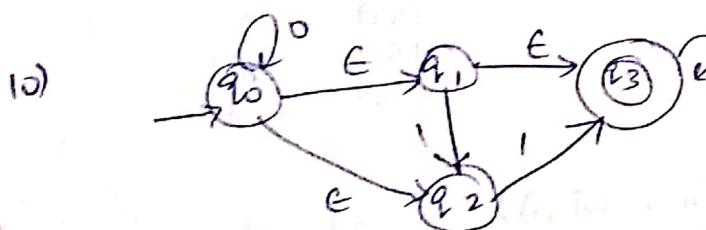
$$\sim(q_1) = \{q_1, q_2\}$$

$$\sim(q_2) = \{q_2\}$$

We know the
we
of

$$\begin{aligned}\sim(\delta(q_0, a)) &= \sim(\delta(\{q_0, q_1, q_2\}, a)) = \sim(q_1) = \{q_1, q_2\} \\ \sim(\delta(q_0, b)) &= \sim(\delta(\{q_0, q_1, q_2\}, b)) = \sim(q_0) = \{q_0, q_1, q_2\} \\ \sim(\delta(q_1, 0)) &= \sim(\delta(\{q_1, q_2\}, 0)) = \sim(q_1) = \{q_1, q_2\} \\ \sim(\delta(q_1, b)) &= \sim(\delta(\{q_1, q_2\}, b)) = \sim(q_0) = \{q_0, q_1, q_2\} \\ \sim(\delta(q_2, a)) &= \sim(\delta(\{q_2\}, a)) = \sim(q_2) = \{q_2\} \\ \sim(\delta(q_2, b)) &= \sim(\delta(\{q_2\}, b)) = \sim(q_1) = \{q_1, q_2\} \\ \sim(\delta(q_2, 0)) &= \sim(\delta(\{q_2\}, 0)) = \sim(q_0) = \{q_0, q_1, q_2\}\end{aligned}$$

IN



$$\begin{aligned}\sim(q_0) &= \{q_0, q_1, q_2, q_3\} \\ \sim(q_1) &= \{q_1, q_3\} \\ \sim(q_2) &= \{q_2\} \\ \sim(q_3) &= \{q_3\}\end{aligned}$$

$$\begin{aligned}q_{0,0} &= \{q_0, q_1, q_2, q_3\} & q_{2,0} &= \emptyset \\ q_{0,1} &= \{q_2, q_3\} & q_{2,1} &= \{q_3\} \\ q_{0,2} &= \emptyset(q_3) & q_{2,2} &= \emptyset\end{aligned}$$

$$\begin{aligned}q_{1,0} &= \emptyset \\ q_{1,1} &= \{q_2, q_3\} \\ q_{1,2} &= \emptyset(q_3)\end{aligned}$$

$$\begin{aligned}q_{3,0} &= \emptyset \\ q_{3,1} &= \emptyset \\ q_{3,2} &= \{q_3\}\end{aligned}$$

	a	b	
q_0	q_1	q_0	q_0
q_1	q_0	q_2	q_2
q_2	q_3	q_1	q_1
q_3	q_3	q_0	q_0
q_4	q_3	q_5	q_4
q_5	q_6	q_4	q_4
q_6	q_5	q_6	q_5
q_7	q_6	q_7	q_6
q_8	q_7	q_8	q_7

A language L is accepted by some E -NFA
 iff L is accepted by DFA

[DEC]

[JUNE]

BASIS:

If $|w|=0$ then $w = \epsilon$

Let $D = \{Q_D, \Sigma, \delta_D, q_0, F_D\}$

$E = \{Q_E, \Sigma, \delta_E, q_0, F_E\}$

We know that $\hat{\delta}_E(q_0, \epsilon) = \epsilon\text{-closure}(q_0)$
 we also know that $\tau_D = \epsilon\text{-closure}(q_0)$

for a DFA, $\hat{\delta}_D(p, \epsilon) = p$ for any state p

$\hat{\delta}_D(q_D, \epsilon) = \epsilon\text{-closure}(q_0)$

thus, $\hat{\delta}_E(q_0, \epsilon) = \hat{\delta}_D(q_0, \epsilon)$

INDUCTION:

Suppose $w = xa$

if w and assume that where a is the final symbol statement holds for x that is

$\hat{\delta}_E(q_0, x) = \hat{\delta}_D(q_0, x)$
 states be $\{p_1, p_2, p_3, \dots, p_k\}$

Let both these

By the definition of $\hat{\delta}$ for NFA-E, we

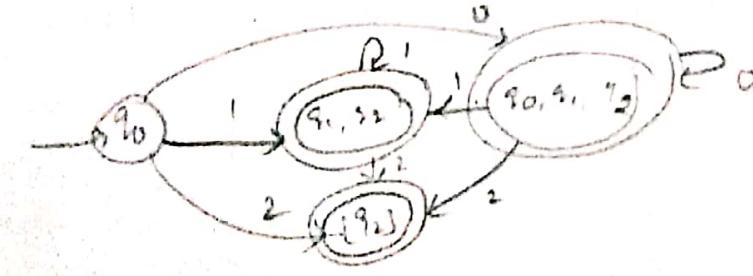
compute $\hat{\delta}_E(q_0, w)$

1. Let $\{q_1, q_2, \dots, q_m\}$ be $\bigcup_{i=1}^k \delta_E(p_i, a)$

then $\hat{\delta}_E(q_0, w) = \bigcup_{j=1}^m \epsilon\text{-closure}(q_j)$

$\hat{\delta}_D(q_0, w) = \delta_D(\{p_1, p_2, \dots, p_k\}, a) = \hat{\delta}_E(q_0, w)$

Thus $\hat{\delta}_D(q_0, w) = \hat{\delta}_E(q_0, w)$

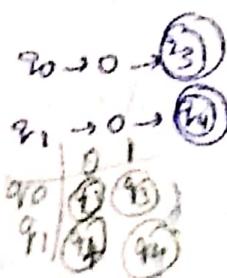
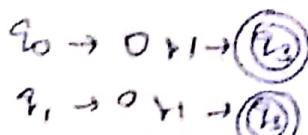
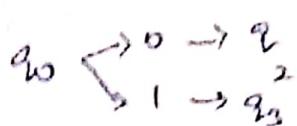


NFA-E
 $\epsilon\text{-closure}(\hat{\delta}(q_0, \epsilon)) = \{q_0, q_1, q_2\}$

DFA

$(q_0, \epsilon) = [q_0, q_1, q_2]$

also of $\hat{\delta}_D(q_0, \epsilon) = \{q_0, q_1, q_2\}$

CASE 1:CASE 2:CASE 3:CASE 4:

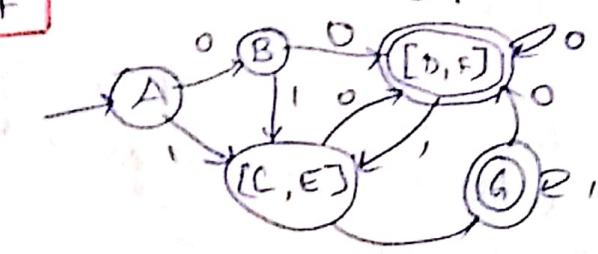
$q_0 \xrightarrow{0} q_2$
 $q_1 \xrightarrow{0} q_4$

$q_2 = q_4$
 $\text{seen } q_0 = q_1$

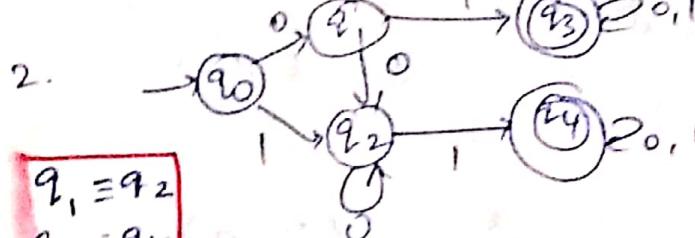
B	Y				
C	X	X			
D	Y	Y	Y		
E	X	X	✓	X	
F	Y	X	Y	✓	X
G	Y	Y	X	X	X

q_1					
q_2	X				
q_3	Y		✓		
q_4	Y	X	X		
q_0		q_1	q_2	q_3	q_4

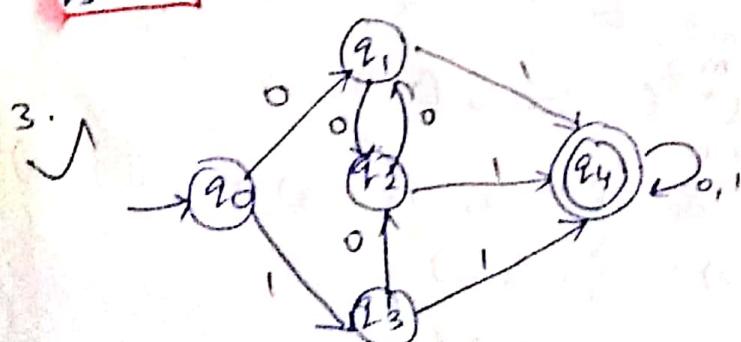
$q_1 = q_2$
 $q_2 = q_4$



$q_0 \xrightarrow{0} q_1$
 $q_0 \xrightarrow{0} q_2$
 $q_0 \xrightarrow{0} q_3$
 $q_2 \xrightarrow{0} q_1$



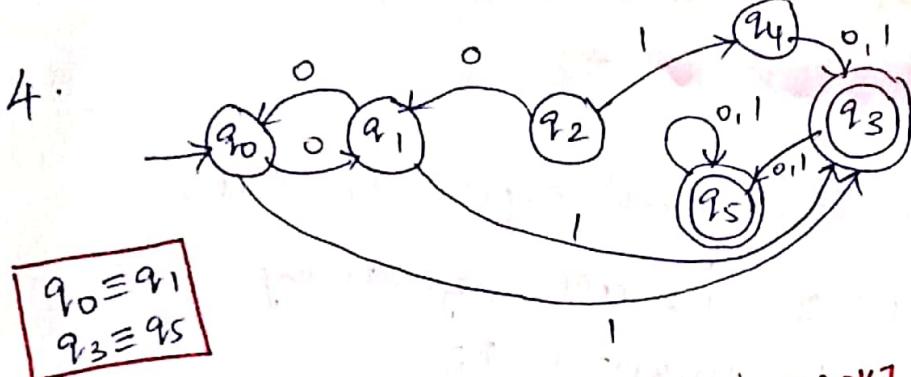
$q_1 = q_2$
 $q_2 = q_4$



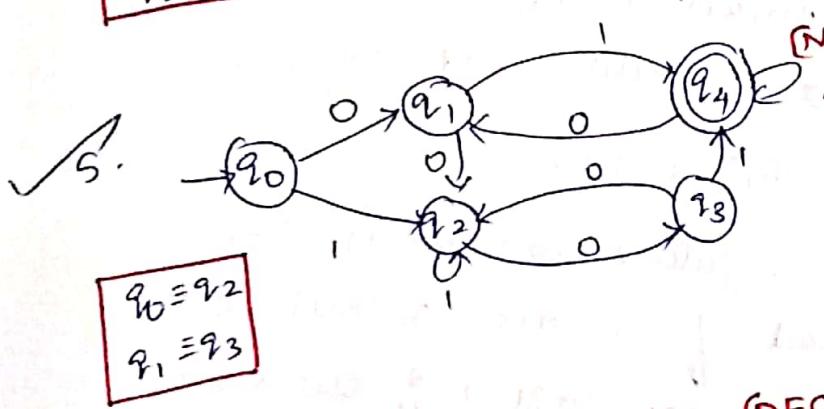
$q_1 = q_2 = q_3$

q_1				
q_2	X	L		
q_3	Y	L	L	
q_4	Y	Y	Y	Y
q_0	q_1	q_2	q_3	q_4

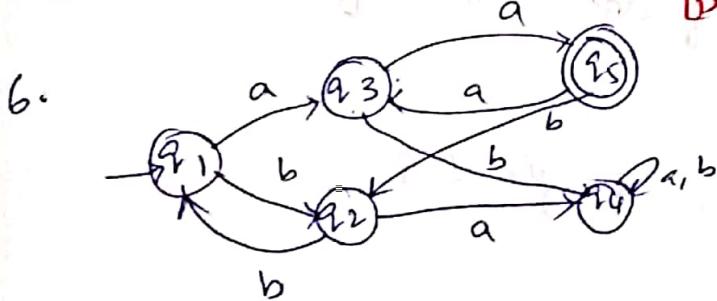
✓ (1)



q_1	✓				
q_2	x	y			
q_3	x	x	x		
q_4	x	x	x	x	x
q_5	x	x	x	✓	x



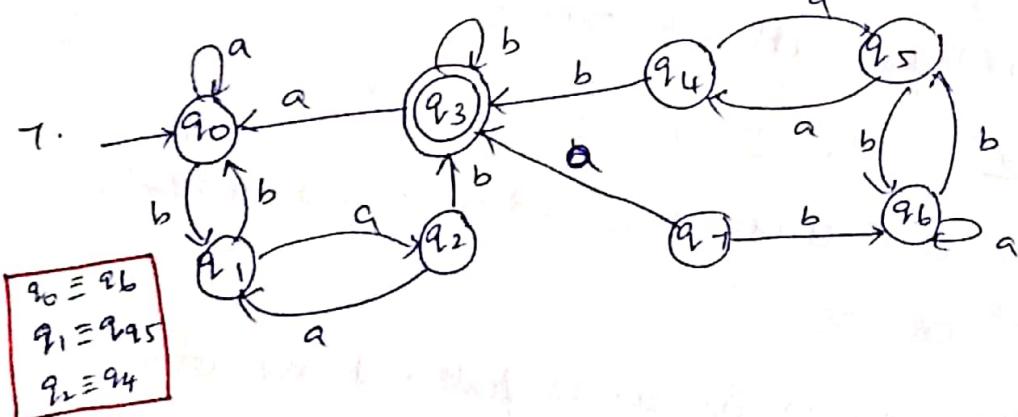
q_1	x				
q_2	✓	x			
q_3	x	✓	x		
q_4	x	x	y	x	
q_5	q ₀	q ₁	q ₂	q ₃	q ₄



[DEC 2015]

cannot be minimized

2



q_1	x					
q_2	x	x				
q_3	x	y	y			
q_4	y	x	v	x		
q_5	x	v	x	x	y	
q_6	v	x	x	x	x	y
q_7	x	x	x	x	x	x

REGULAR EXPRESSIONS & LANGUAGES

Equivalent to NFA-E. Algebraic description

3 main expressions: Union, concatenation, closure (kleene)

Informal: Languages that can be accepted by finite automata are the same as regular languages which can be represented by formulas of RE.

FORMAL

Let Σ be the given alphabet, then
if ϕ, ϵ and $a \in \Sigma$ are all regular expressions,

then are called primitive RE

if α_1 and α_2 are regular expression, so
are $\alpha_1 + \alpha_2, \alpha_1 \cdot \alpha_2, \alpha_1^*$ and (α_1)

iii) A string is a regular expression iff
it can be derived from the primitive RE
by the finite no. of application of the rules.

in iii)

1) $L = \{w | w \text{ contains a single } 1\}$

$$0^* 1 0^*$$

2) $L = \{w | w \text{ has atleast one } 1\}$

$$\Sigma^* 1 \Sigma^* \text{ or } (0+1)^* 1 (0+1)^*$$

$$0^*, +, 0^*$$

~~0101-string~~

3) $L = \{w | w \text{ contains the string } 001 \text{ as a substip}\}$

$$\Sigma^* 001 \Sigma^*$$

A) $L = \{w | \text{every } 0 \text{ in } w \text{ is followed by atleast}$

$$10110101 \quad \text{one } 1 \}$$

$$101 \quad (01)^* (1)^* \quad \text{or} \quad 1^* (01^*)^*$$

5) $L = \{w | w \text{ is a string of even length}$

$$(\Sigma \Sigma)^*$$

6) $L = \{w | \text{the length of } w \text{ is a multiple of } 3\}$

$$(\Sigma \Sigma \Sigma)^*$$

7) $L = \{ \epsilon, 0, 1, 01 \}$

11) At least 2 consecutive 0's
 $(0+1)^* 00(0+1)^*$

$(E+0)(E+1)$ or $E+0+1+01$

12) All strings of 0's & 1's
 $(0+1)^*$

8) $L = \{ 01, 10 \}$

13) Any no. of 0's followed by
 1's, 2's $0^*, 1^*, 2^*$

$(01+10)$

14) min one occurrence
 $0^1+2^1 \quad (0^1)^* 00^* 11^* 22^*$
 same symbol}

9) $L = \{ w | w \text{ starts and ends with the same symbol} \}$

$0\sum^* 0 + 1\sum^* 1 + 0+1$

10) $L = \{ x \in \{0, 1\}^* \mid x \text{ ends with } 1 \text{ and doesn't contain the substrip } 001 \}$

$(1+01)^*$

THOMSON'S CONSTRUCTION

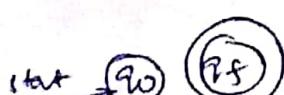
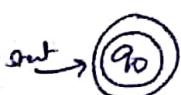
RE TO NFA-E

Let R be a regular expression then,
 there exists an NFA-E transition that accept $L(R)$

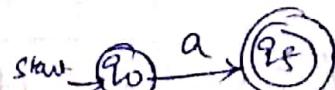
PROOF:

We show by induction on the no. of operators
 in the regular expression R then there is a NFA
 with E transition having one final state and
 no transitions out of this final state
 such that $L(N) = L(R)$

BASIC: (zero operator)
 The expression R must be $\epsilon, \#$ or a for some
 $a \in \Sigma$.



(a) $r = \epsilon$



(b) $r = \emptyset$

(c) $r = a$

INDUCTION (≥ 1 operation)

CASE 1: $\lambda = q_1 + q_2$

$$M_1 = (Q_1, \Sigma_1, \delta_1, q_1, \{f_1\})$$

$$M_2 = (Q_2, \Sigma_2, \delta_2, q_2, \{f_2\})$$

$$L(M_2) = L(q_2)$$

$$L(M_1) = L(q_1) \text{ and}$$

q_1 and q_2 are disjoint.

We may assume Q_1 and Q_2 are disjoint.
Let q_0 be a new initial state and f_0 a new final state.

construct
 $M = (Q_1 \cup Q_2 \cup \{q_0, f_0\}, \Sigma \cup \Sigma_2, \delta, q_0, \{f_0\})$

We define δ by

$$(i) \quad \delta(q_0, \epsilon) = \{q_1, q_2\}$$

(ii) $\delta(q, a) = \delta_1(q, a)$ for $q \in Q_1 - \{f_1\}$ and $a \in \Sigma \cup \{\epsilon\}$

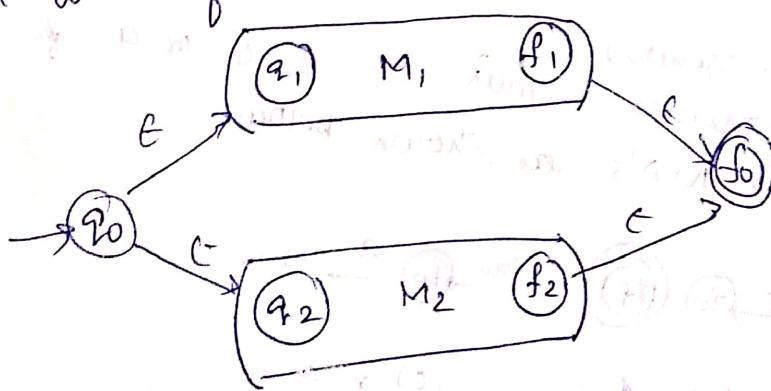
$$(iii) \quad \delta(q, a) = \delta_2(q, a) \text{ for } q \in Q_2 - \{f_2\} \text{ and } a \in \Sigma_2 \cup \{\epsilon\}$$

$$(iv) \quad \delta(f_1, \epsilon) = \delta_1(f_1, \epsilon) = \{f_0\}$$

There is a path labelled x in M from q_1 to f_1 iff

there is a path labelled x in M_1 from q_1 to f_1

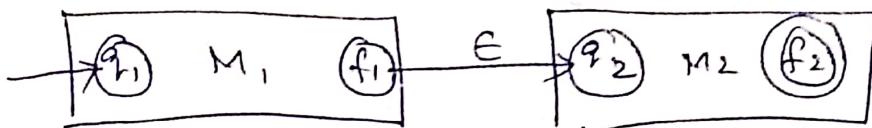
path in M_2 from q_2 to f_2 hence $L(M) = L(M_1) \cup L(M_2)$



CASE - 2 $\alpha = \alpha_1, \alpha_2$. Let M_1 and M_2 be as in Case 1
and construct $M = (\Omega, \cup Q_2, \Sigma, \cup \Sigma_2, \delta, \{\alpha_1\}, \{\alpha_2\})$

where δ is given by

- (i) $\delta(q, a) = \delta_1(q, a)$ for q in $Q_1 - \{f_1\}$ and a in $\Sigma_1, \cup \{\epsilon\}$
- (ii) $\delta(f_1, \epsilon) = \{\alpha_2\}$
- (iii) $\delta(q, a) = \delta_2(q, a)$ for q in Q_2 and a in $\Sigma_2, \cup \{\epsilon\}$



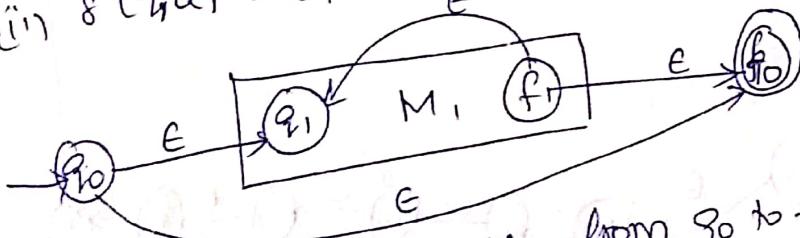
Every path in M from q_1 to f_2 is a path labeled by some strip x from q_1 to f_1 , followed by the edge from f_1 to q_2 labeled ϵ , followed by a path labeled by some strip y from q_2 to f_2 . Thus $L(M) = \{xy \mid x \text{ is in } L(M_1)$
and $y \text{ is in } L(M_2)\}$ and $L(M) = L(M_1)L(M_2)$ are derived.

CASE - 3 $\alpha = \alpha_1^*$
Let $M_1 = (\Omega_1, \Sigma_1, \delta_1, q_1, \{f_1\})$ and $L(M_1) = \alpha_1$,

construct $M = (\Omega, \cup \{q_0, f_0\}, \Sigma, \delta, q_0, \{f_0\})$

where δ is defined by

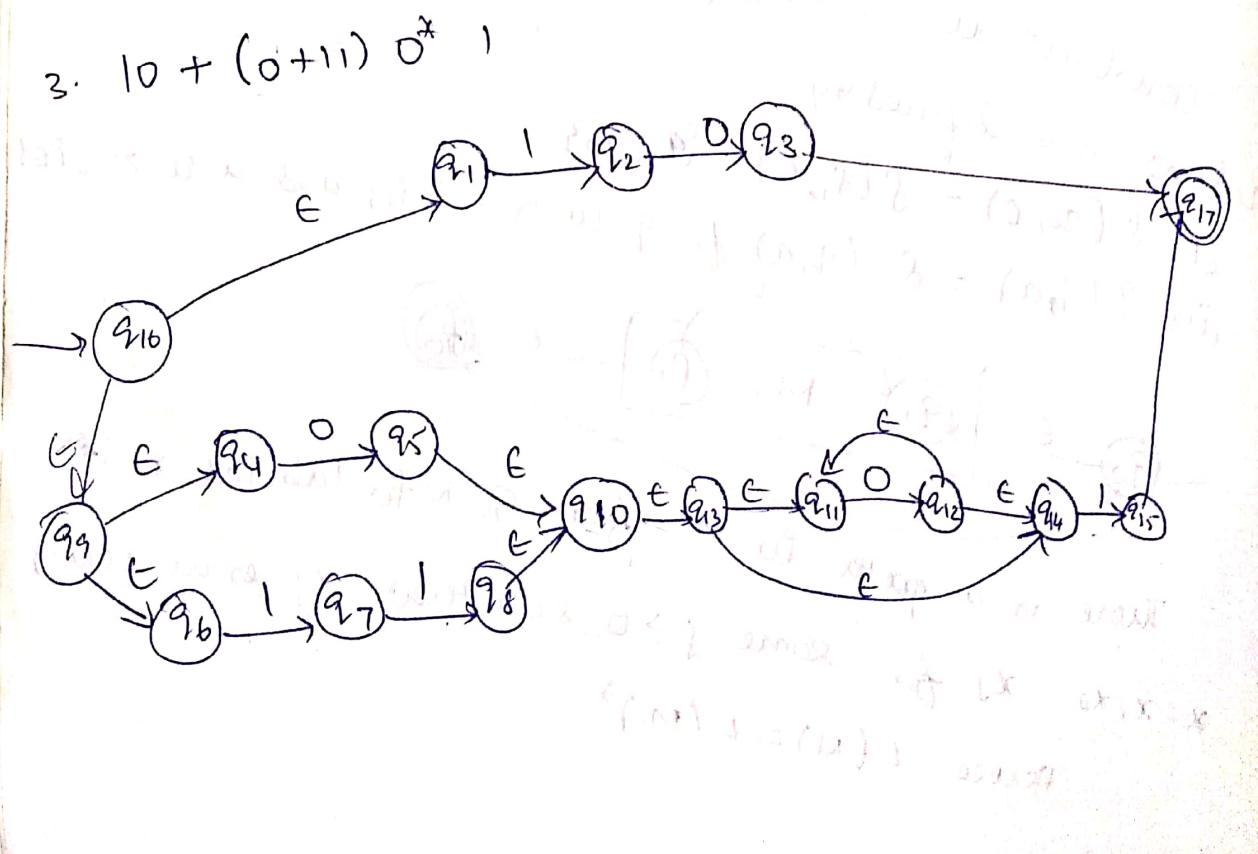
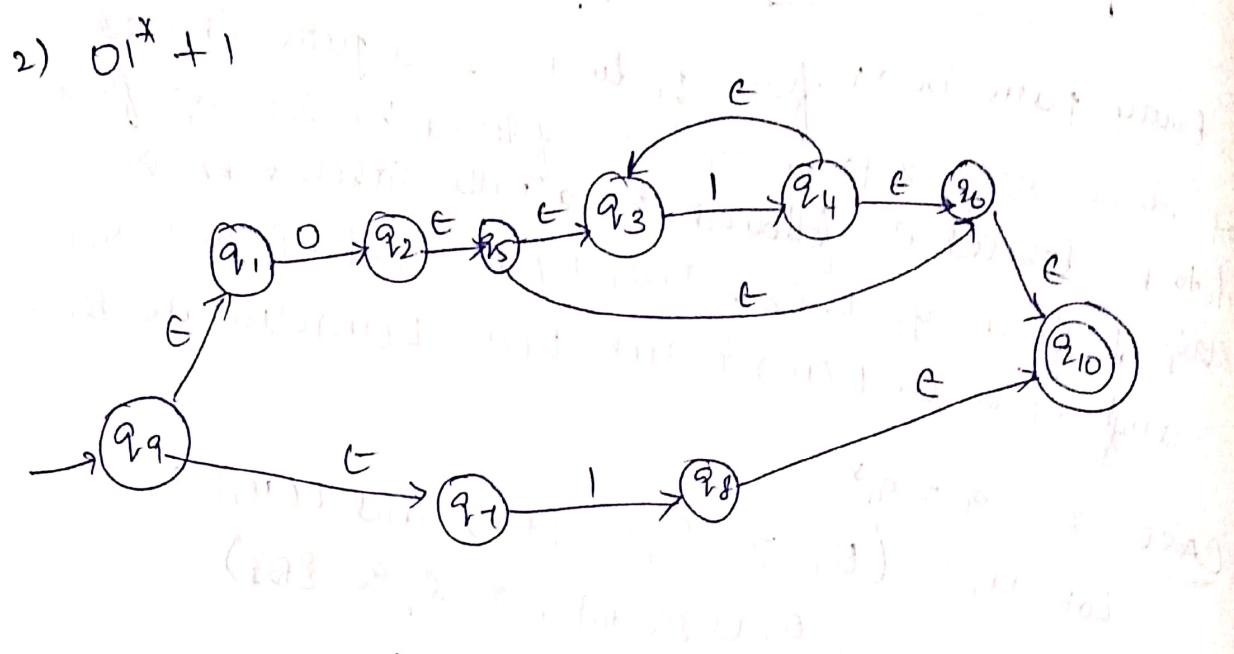
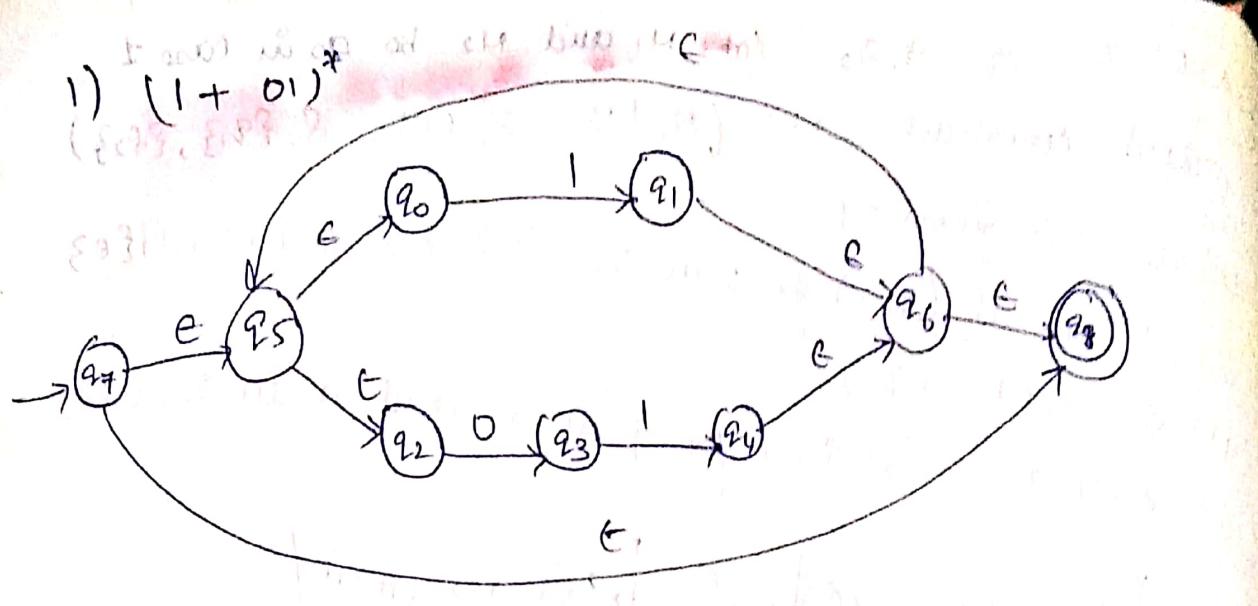
- (i) $\delta(q_0, \epsilon) = \delta(f_0, \epsilon) = \{q_1, f_0\}$
- (ii) $\delta(q, a) = \delta_1(q, a)$ for q in $Q_1 - \{f_1\}$ and a in $\Sigma_1, \cup \{\epsilon\}$



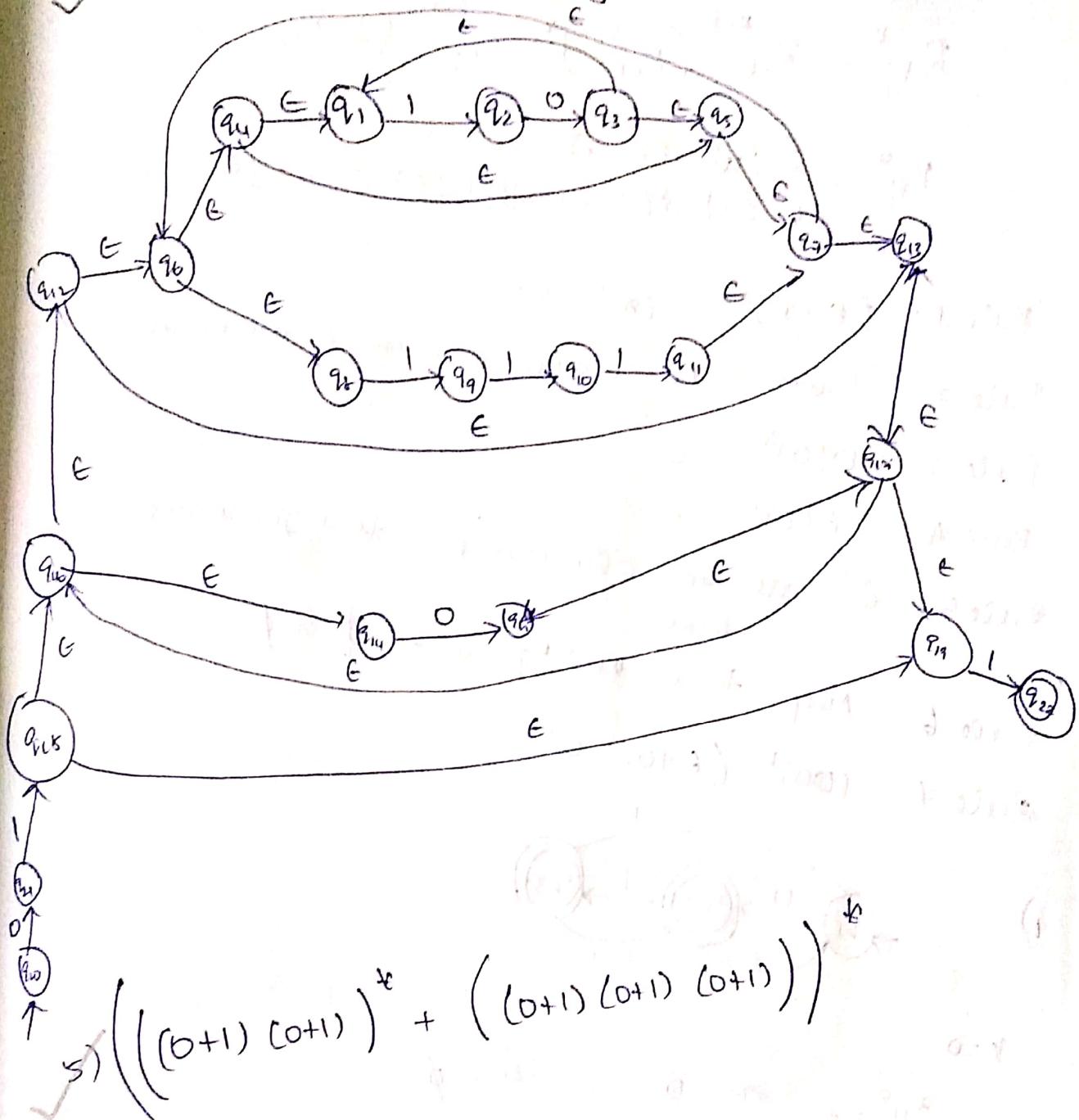
There is a path in M from q_0 to f_0 labeled x iff

$x = x_1 x_2 \dots x_j$ for some $j \geq 0$ such that x_j is in $L(M_1)$

Hence $L(M) = L(M_1)^*$



4. $01 \left[(110)^* + 111 \right]^* + 0]^*$



5) $\left((0+1)(0+1) \right)^* + \left((0+1)(0+1)(0+1) \right)$

6) $(11+0)^* (00+1)^*$

REGULAR EXPRESSION

$$R_{ij}^k = R_{ik}^{k-1} (R_{kk})^* R_{kj}^{k-1} \cup R_{ij}^{k-1}$$

$$R_{ij}^0 = \begin{cases} \{\alpha\} \cdot \delta(q_i, a) = q_j & \text{if } i \neq j \\ \{\alpha\} \cdot \delta(q_i, a) = q_j \cup \emptyset & \text{if } i = j \end{cases}$$

Rule 1: $(\epsilon + r)^* = (r)^* = r^*$

Rule 2: $w_0 + 0 = w_0, \quad 0w + 0 = 0w \quad \text{iff } r_{ij} \text{ are equal}$

Rule 3: $0(0)^* = 0^*$

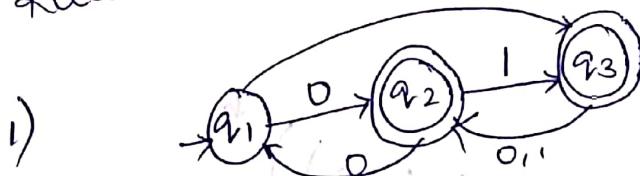
Rule 4: $\epsilon(\epsilon)^* = \epsilon^*$

Rule 5: ϵ^* can be eliminated when given with
any term multiplied by ϕ is ϕ

Rule 6: Any

$$(00)^* (\epsilon + 0) = 0^*$$

Rule 7: $(00)^* \quad |$



$k=0$

$$q_{11}^0 = \epsilon$$

$$q_{21}^0 = 0$$

$$q_{31}^0 = \emptyset$$

$$q_{12}^0 = 0$$

$$q_{22}^0 = \epsilon$$

$$q_{32}^0 = 0 + 1$$

$$q_{13}^0 = 1$$

$$q_{23}^0 = 1$$

$$q_{33}^0 = \epsilon$$

$\underline{k=1}$

$$q_{11}^1 = q_{11}^0 (q_{11}^0)^* \cancel{q_{11}^0} + \cancel{R_{11}^0}$$

$$= \epsilon(\epsilon)^* \epsilon \quad (\text{Rule 4}) = \epsilon(\epsilon)^*$$

$$= \epsilon^*$$

$$g_{12}^1 = \cancel{g_{11}^0} (\cancel{g_{11}^0})^* \cancel{g_{12}^0} + \cancel{g_{12}^0}$$

$$= \epsilon (\epsilon)^* 0$$

$$= \epsilon^* 0$$

$$= 0$$

$$g_{13}^1 = \cancel{g_{11}^0} (\cancel{g_{11}^0})^* \cancel{g_{13}^0} + \cancel{g_{13}^0}$$

$$= \epsilon (\epsilon)^* 1$$

$$= 1$$

$$g_{21}^{1\#} = \cancel{g_1^0} (\cancel{g_{11}^0})^* \cancel{g_{11}^0} + \cancel{g_{11}^0} \cancel{g_1^0} = 0 (\epsilon)^* \epsilon$$

$$= 0 (\epsilon)^* \epsilon$$

$$= 0$$

$$g_{22}^1 = \cancel{g_{21}^0} (\cancel{g_{11}^0})^* \cancel{g_{12}^0} + \cancel{g_{22}^0}$$

$$= \cancel{g_{21}^0} (\cancel{g_{11}^0})^* (\cancel{g_{12}^0}) + \cancel{g_{22}^0} = \cancel{g_{21}^0} (\cancel{g_{11}^0})^* (\cancel{g_{12}^0}) + \cancel{g_{22}^0} = 0 \cdot 0^* 1 = 0^* 1$$

$$= 0 (\epsilon)^* 0 + \epsilon$$

$$= 00 + \epsilon$$

$$g_{23}^1 = \cancel{g_{21}^0} (\cancel{g_{11}^0})^* \cancel{g_{13}^0} + \cancel{g_{23}^0} = 0 (\epsilon)^* 1 + 1 = 01 + 1$$

$$g_{31}^1 = \cancel{g_{31}^0} (\cancel{g_{11}^0})^* \cancel{g_{11}^0} + \cancel{g_{31}^0} = \phi (\epsilon)^* \epsilon = \phi$$

$$g_{32}^1 = \cancel{g_{31}^0} (\cancel{g_{11}^0})^* \cancel{g_{12}^0} + \cancel{g_{32}^0} = \phi (\cdot \epsilon)^* 0 + (0+1) = 0+1$$

$$g_{33}^1 = \cancel{g_{31}^0} (\cancel{g_{11}^0})^* \cancel{g_{13}^0} + \cancel{g_{33}^0} = \phi (\epsilon)^* 1 + \epsilon = \epsilon$$

$k=2$

$$g_{11}^2 = \cancel{g_{12}^1} (\cancel{g_{22}^1})^* \cancel{g_{21}^1} + \cancel{g_{12}^1} \cancel{g_{21}^1} = 0 (00+\epsilon)^* 0 = (00)^*$$

$$g_{12}^2 = \cancel{g_{12}^1} (\cancel{g_{22}^1})^* \cancel{g_{22}^1} + \cancel{g_{12}^1} \cancel{g_{22}^1} = 0 (00+\epsilon)^* (00+\epsilon) = 0 (00)^*$$

$$g_{13}^2 = \cancel{g_{12}^1} (\cancel{g_{22}^1})^* \cancel{g_{23}^1} + \cancel{g_{13}^1} \cancel{g_{23}^1} = 0 (00+\epsilon)^* (01+1) + 1 = 0 (00+\epsilon)^* (0+1) + 1 = 0^* 1$$

$$g_{21}^2 = \cancel{g_{22}^1} (\cancel{g_{22}^1})^* \cancel{g_{21}^1} + \cancel{g_{21}^1} \cancel{g_{22}^1} = (00+\epsilon) (00+\epsilon)^* 0 = (00)^* 0$$

$$g_{22}^2 = \cancel{g_{22}^1} (\cancel{g_{22}^1})^* \cancel{g_{22}^1} + \cancel{g_{22}^1} \cancel{g_{22}^1} = (00+\epsilon) (00+\epsilon)^* = (00)^*$$

$$g_{23}^2 = \cancel{g_{22}^1} (\cancel{g_{22}^1})^* \cancel{g_{23}^1} + \cancel{g_{23}^1} \cancel{g_{23}^1} = (00+\epsilon) (00+\epsilon)^* (01+1) = 0^* 1$$

$$g_{31}^2 = \cancel{g_{32}^1} (\cancel{g_{22}^1})^* \cancel{g_{21}^1} + \cancel{g_{31}^1} \cancel{g_{21}^1} = (0+1) (00+\epsilon)^* 0 + \phi = (0+1) (00)^* 0$$

$$g_{32}^2 = \cancel{g_{32}^1} (\cancel{g_{22}^1})^* \cancel{g_{22}^1} + \cancel{g_{32}^1} \cancel{g_{22}^1} = (0+1) (00+\epsilon)^* (0+1) = (0+1) (00)^*$$

$$g_{33}^2 = \cancel{g_{32}^1} (\cancel{g_{22}^1})^* \cancel{g_{23}^1} + \cancel{g_{33}^1} \cancel{g_{23}^1} = (0+1) (00+\epsilon)^* (01+1) + \epsilon = (0+1) 0^* 1.$$

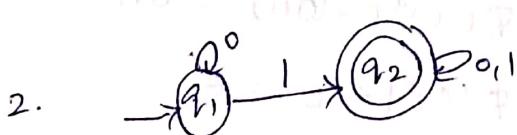
$$r_{12}^3 + r_{13}^3$$

$$\begin{aligned} r_{12}^3 &= r_{13}^2 (r_{33}^2)^* r_{32}^2 + r_{12}^2 \\ &= 0^* 1 (E + (0+1)0^* 1)^* (0+1)(00)^* + 0(00)^* \\ &= 0^* 1 ((0+1)0^* 1)^* (0+1)(00)^* + 0(00)^* \end{aligned}$$

$$\begin{aligned} r_{13}^3 &= r_{13}^2 (r_{33}^2)^* r_{33}^2 + r_{13}^2 \\ &= 0^* 1 (E + (0+1)0^* 1)^* (E + (0+1)0^* 1) \\ &= 0^* 1 ((0+1)0^* 1)^* \end{aligned}$$

Hence

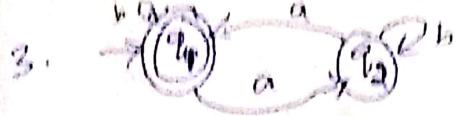
$$\begin{aligned} r_{12}^3 + r_{13}^3 &= 0^* 1 ((0+1)0^* 1)^* (0+1)(00)^* + 0(00)^* + \\ &\quad 0^* 1 ((0+1)0^* 1)^* (0+1)(00)^* + 0(00)^* \\ &= 0^* 1 ((0+1)0^* 1)^* (0+1)(00)^* + 0(00)^* \end{aligned}$$



$$k=0 \quad r_{11}^0 = E+0 \quad r_{12}^0 = 1 \quad r_{21}^0 = \emptyset \quad r_{22}^0 = E+0+1$$

$$\begin{aligned} k=1 \quad r_{11}^1 &= r_{11}^0 (r_{11}^0)^* r_{11}^0 + r_{11}^0 = E+0 (E+0)^* E+0 = 0^* \\ r_{12}^1 &= r_{12}^0 (r_{12}^0)^* r_{12}^0 + r_{12}^0 = E+0 (E+0)^* 1 = 0^* 1 \\ r_{21}^1 &= r_{21}^0 (r_{21}^0)^* r_{21}^0 + r_{21}^0 = \emptyset \\ r_{22}^1 &= r_{22}^0 (r_{22}^0)^* r_{22}^0 + r_{22}^0 = \emptyset + (E+0+1) = E+0+1 \end{aligned}$$

$$\begin{aligned} k=2 \quad r_{12}^2 &= r_{12}^1 (r_{12}^1)^* r_{12}^1 + r_{12}^1 = (0^* 1) (E+0+1)^* (E+0+1) \\ &= (0^* 1) (0+1)^* \end{aligned}$$



$$\text{For } k=0: \quad g_{11}^0 = a + b \quad g_{12}^0 = a \quad g_{21}^0 = a \quad g_{22}^0 = a + b$$

$$\begin{aligned} g_{11}^1 &= g_{11}^0 (g_{11}^0)^* g_{11}^0 + g_{21}^0 = (a+b)(a+b)^* (a+b) = b^2 \\ g_{12}^1 &= g_{11}^0 (g_{11}^0)^* g_{12}^0 + g_{21}^0 = (a+b)(a+b)^* a = b^2 a \\ g_{21}^1 &= g_{21}^0 (g_{11}^0)^* g_{11}^0 + g_{21}^0 = a(a+b)^* (a+b) = ab^2 \\ g_{22}^1 &= g_{21}^0 (g_{11}^0)^* g_{12}^0 + g_{22}^0 = a(a+b)^* a + (a+b) = ab^2 a + (a+b) \end{aligned}$$

$k=2$

$$\begin{aligned} g_{11}^2 &= g_{12}^1 (g_{22}^1)^* g_{21}^1 + g_{11}^1 = b^4 a (ab^2 a + (a+b))^* a b^2 + b^4 \\ &= b^4 a (ab^2 a + b)^* a b^2 + b^4 \end{aligned}$$



$$\text{For } k=0: \quad g_{11}^0 = a \quad g_{12}^0 = b \quad g_{13}^0 = 0 \quad g_{21}^0 = 0 \quad g_{22}^0 = c \quad g_{23}^0 = 1 \quad g_{32}^0 = 0 \quad g_{33}^0 = 0$$

$$\text{For } k=1: \quad g_{11}^1 = E \quad g_{12}^1 = b \quad g_{13}^1 = 0 \quad g_{21}^1 = 0 \quad g_{22}^1 = c \quad g_{23}^1 = 1 \quad g_{32}^1 = 0 \quad g_{33}^1 = 0$$

$$\begin{aligned} g_{11}^1 &= g_{11}^0 (g_{11}^0)^* g_{11}^0 + g_{21}^0 = E(E)^* E = E^* E = E \\ g_{12}^1 &= g_{11}^0 (g_{11}^0)^* g_{12}^0 + g_{21}^0 = E(E)^* 1 = 1 \\ g_{13}^1 &= g_{11}^0 (g_{11}^0)^* g_{13}^0 + g_{21}^0 = E(E)^* 0 = 0 \\ g_{21}^1 &= g_{21}^0 (g_{11}^0)^* g_{11}^0 + g_{21}^0 = 0(E)^* E = 0 \\ g_{22}^1 &= g_{21}^0 (g_{11}^0)^* g_{12}^0 + g_{22}^0 = 0(E)^* 1 + E = 01+E \\ g_{23}^1 &= g_{21}^0 (g_{11}^0)^* g_{13}^0 + g_{23}^0 = 0(E)^* 0 + 1 = 00+1 \\ g_{31}^1 &= g_{31}^0 (g_{21}^0)^* g_{11}^0 + g_{32}^0 = \phi \\ g_{32}^1 &= g_{31}^0 (g_{21}^0)^* g_{12}^0 + g_{32}^0 = \phi \\ g_{33}^1 &= g_{31}^0 (g_{21}^0)^* g_{13}^0 + g_{33}^0 = \phi + (E+0+1) = E+0+1 \end{aligned}$$

$$\begin{aligned} \text{For } k=2: \quad g_{11}^2 &= g_{11}^1 (g_{11}^1)^* g_{11}^1 + g_{21}^1 = 1(01+E)^* 0 + E = 1(01)^* 0 + E \\ g_{12}^2 &= g_{12}^1 (g_{12}^1)^* g_{12}^1 + g_{21}^1 = 1(01+E)^* (01+E) = 1(01)^* \\ g_{13}^2 &= g_{12}^1 (g_{12}^1)^* g_{13}^1 + g_{21}^1 = 1(01+E)^* (00+1) + 0 = 1(01)^* (00+1) + 0 \\ g_{21}^2 &= g_{21}^1 (g_{11}^1)^* g_{11}^1 + g_{21}^1 = (01+E)(01+E)^* 0 = (01)^* 0 \\ g_{22}^2 &= g_{22}^1 (g_{11}^1)^* g_{12}^1 + g_{22}^1 = (01+E)(01+E)^* (01+E) = (01)^* \\ g_{23}^2 &= g_{22}^1 (g_{11}^1)^* g_{13}^1 + g_{23}^1 = (01+E)(01+E)^* (00+1) = (01)^* (00+1) \\ g_{31}^2 &= g_{31}^1 (g_{21}^1)^* g_{11}^1 + g_{32}^1 = \phi(01+E)^* 0 + \phi = \phi \\ g_{32}^2 &= g_{32}^1 (g_{21}^1)^* g_{12}^1 + g_{32}^1 = \phi(01+E)^* (01+E)^* = \phi \\ g_{33}^2 &= g_{32}^1 (g_{21}^1)^* g_{13}^1 + g_{33}^1 = \phi 00 + (E+0+1) = (E+0+1) \end{aligned}$$

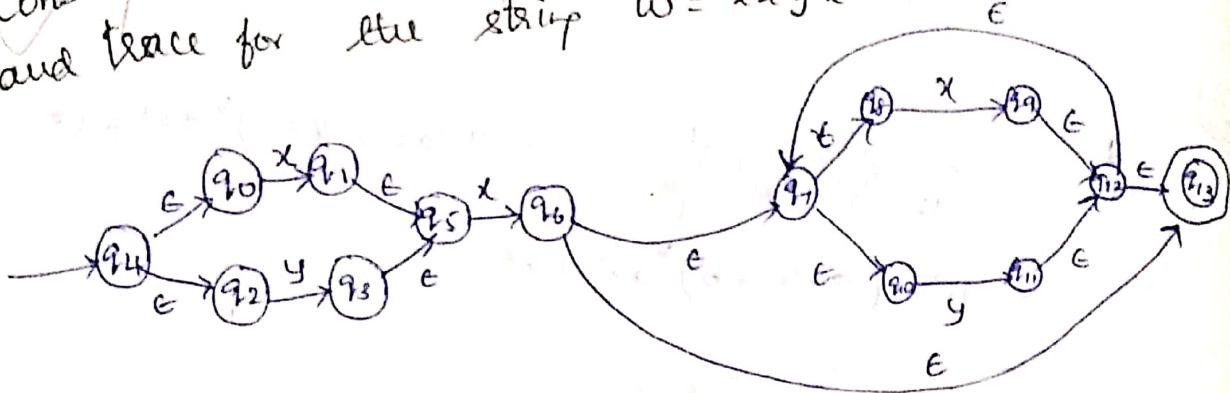
k=3

$$q_{13}^3 = q_{13}^2 (q_{33}^2)^* q_{33}^2 + q_{13}^3$$

$$= 1(01)^* (00+1) + 0 (\epsilon + 0+1)^* (\epsilon + 0+1)$$

$$= 1(01)^* (00+1) + 0 (0+1)^*$$

Construct minimized DFA from RE $(x+y)x(x+y)^*$
and trace for the string $w = xxyx$



$$\epsilon\text{-closure}(q_4) = \{q_4, q_0, q_2\} = A$$

$$\epsilon\text{-closure}(1) = \{1, 5\} = B$$

$$\delta(A, x) = \delta(\{q_4, q_0, q_2, x\}) = \epsilon\text{-closure}(1) = \{1, 5\} = C$$

$$\delta(A, y) = \delta(\{q_4, q_0, q_2, y\}) = \epsilon\text{-closure}(3) = \{3, 5\} = D^*$$

$$\delta(B, x) = \delta(\{1, 5, 3, x\}) = \epsilon\text{-closure}(6) = \{6, 7, 8, 10, 13\} = E^*$$

$$\delta(B, y) = \delta(\{1, 5, 3, y\}) = \epsilon\text{-closure}(\emptyset) = E$$

$$\delta(C, x) = \delta(\{3, 5, 1, x\}) = \epsilon\text{-closure}(\emptyset, 6) = \{5, 6, 7, 8, 10, 13\} = F^*$$

$$\delta(C, y) = \delta(\{3, 5, 1, y\}) = \epsilon\text{-closure}(\emptyset) = F$$

$$\delta(D, x) = \delta(\{6, 7, 8, 10, 13, x\}) = \sim(q) = \{9, 12, 13, 7, 8, 10\} = G$$

$$\delta(D, y) = \delta(\{6, 7, 8, 10, 13, y\}) = \sim(11) = \{11, 12, 13, 7, 8, 10\} = G^*$$

$$\delta(E, x) = \delta(\emptyset, x) = E$$

$$\delta(E, y) = \delta(\emptyset, y) = E$$

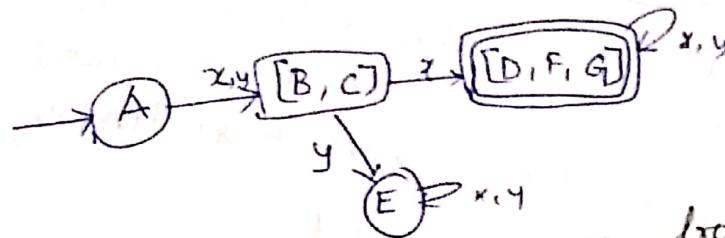
$$\delta(F, x) = \delta(\{7, 8, 9, 10, 12, 13, x\}, \sim(q)) = F^*$$

$$\delta(F, y) = \delta(\{7, 8, 9, 10, 12, 13, y\}, \sim(11)) = G^*$$

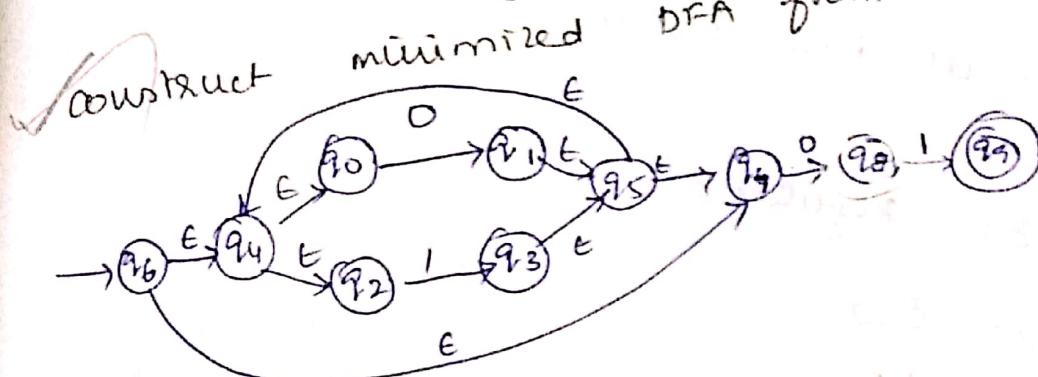
$$\delta(G, x) = \delta(\{7, 8, 10, 11, 12, 13, x\}, \sim(q)) = F^*$$

$$\delta(G, y) = \delta(\{7, 8, 10, 11, 12, 13, y\}, \sim(11)) = G^*$$

S	x	y	S	x	y
A	B	C			
B	D	E			
C	D	E			
D*	F	G	$[B, C]$	$[B, C]$	$[B, C]$
E	E	E			
F	F	G	$[D, F, G]$	$[D, F, G]$	$[D, F, G]$
G*	F	G			



2, 8, 19, 15



$$\sim(q_6) = \{q_6, 7, 4, 0, 2\} = A$$

$$\delta(A, 0) = \delta(\{0, 1, 2, 4, 6, 7\}, 0) = \sim(1, 8) = \{1, 5, 4, 0, 2, 7, 8\} = B$$

$$\delta(A, 1) = \delta(\{0, 1, 2, 4, 6, 7\}, 1) = \sim(3) = \{3, 5, 4, 0, 2, 7\} = C$$

$$\delta(B, 0) = \delta(\{0, 1, 2, 4, 5, 7, 8\}, 0) = \sim(1, 8) = B$$

$$\delta(B, 1) = \delta(\{0, 1, 2, 4, 5, 7, 8\}, 1) = \sim(3, 9) = \{3, 5, 4, 0, 2, 7, 9\} = D^*$$

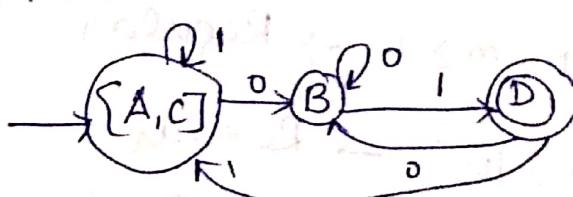
$$\delta(C, 0) = \delta(\{0, 1, 2, 3, 4, 5, 7\}, 0) = \sim(1, 8) = B$$

$$\delta(C, 1) = \delta(\{0, 1, 2, 3, 4, 5, 7\}, 1) = \sim(3) = C$$

$$\delta(D, 0) = \delta(\{0, 1, 2, 3, 4, 5, 7, 9\}, 0) = \sim(1, 8) = B$$

$$\delta(D, 1) = \delta(\{0, 1, 2, 3, 4, 5, 7, 9\}, 1) = \sim(3) = C$$

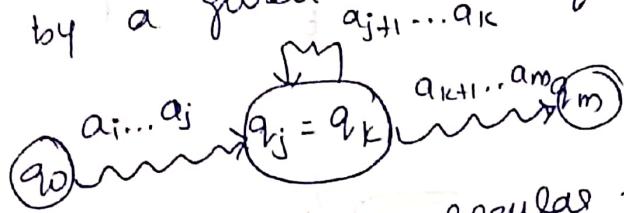
δ	0	1
A	B	C
B	B	D
C	B	C
D	B	C



reduced to 3 states

Pumping Lemma

Pumping lemma is a powerful tool for proving certain language regular or not. Development of algorithms, language accepted by a given FA is finite/infinite



- Let L be a regular set. There is a constant n such that if z is any word in L and $|z| \geq n$, $z = uvw$ such that $|uv| \leq n$, $|v| \geq 1$ for all $i \geq 0$, uv^iw is in L

1. $0^n \mid n \geq 1$ Regular

$$z = uvw$$

$$|uvw| \leq n$$

$$|v| \geq 1$$

for all $i \geq 0$ $uv^iw \in L$

when L is regular?

(i) No dependency in power

(ii) If dependent, limit should be bound

(iii) Power should be positive AP

$$uvw = a^n \quad z = uvw$$

$$\dots a^{n-2} a$$

$$|v| = n - 2$$

$$|v| \geq 1 \text{ true}$$

$$|uv| \leq n \text{ true}$$

2. $a^n b^m \mid n, m \geq 1 \rightarrow \text{Regular}$

3. $a^n b^n \mid n \leq 10^{10} \rightarrow \text{Regular}$

4. $a^n b^n \mid n \geq 1 \rightarrow \text{Not regular}$

5. $ww^R \mid |w|=2 \rightarrow \text{Regular}$

6. $ww^2 \mid w \in (a,b)^*$ → Not Regular
7. $ww \mid w \in (a,b)^*$ → Not Regular
8. $a^n b^m c^k \mid n, m, k \geq 1$ → Regular
9. $a^i b^{2^j} \mid i, j \geq 1$ → Regular
10. $a^i b^{4^j} \mid i, j \geq 1$ → Regular
11. $a^n \mid n$ is even Arithmetic progression → Regular
12. $a^n \mid n$ is odd AP → Regular
13. $a^n \mid n$ is prime not AP → not Regular
14. $a^{n^2} \mid n \geq 1$, not AP → not Regular
15. $a^{2^n} \mid n \geq 1$, not AP → not Regular
16. $L = \{b^n 10^n \mid n \geq 1\}$ → not Regular

UNIT II

GRAMMAR

- Study of human languages.
 - Defines programming languages.
 - String processing applications
 - Arithmetic expression → nesting of balanced {}'s.
 - A context free grammar is a finite set of rules relating variables (nonterminals) each of which represents a language. Languages represented by variables are described respectively by primitive symbols called terminals. Rules relating variables are called productions.
- (V, T, P, S)