

①

Basic Blocks

↳ it is the set of statements which executes one after another.

Rules to find leader:

- ① first three address instr. of code is leader
- ② whenever the condition statmt is there, it will be leader
- ③ statmt following the condition statmt will be also leader

functions. preserving transformation:

(1) Compile time evaluation

(i) constant folding

(ii) constant propagation

(2) Common sub expression elimination

(3) Copy propagation

~~(4) Strength reduction~~

(4) Code Movement

(5) Strength Reduction

(6) Dead code elimination

(7) Loop optimization

(1) Compile Time evaluation

↳ shifting of computation from runtime to compile time.

(i) constant folding: computation of constant is done at compile time instead of execution time.

$$\text{example: length} = \left(\frac{22}{7}\right) * d$$

(ii) constant propagation: computation of expression is done at compile time instead of execution time

$$\text{example: } p_i = 3.14; r = 5;$$

$$\text{Area} = p_i * r * r$$

(2) Common subexpression elimination

↳ It is an expression which is appearing repeatedly in program.

↳ If the operands of this sub expression do not get changed then result of the expression is used instead of recomputing it each time.

example:

$$t_1 = 4 * i$$

$$t_2 = k[t_1]$$

$$t_3 = 4 * j$$

$$t_4 = 4 * i$$

$$t_5 = n$$

$$t_6 = b[t_4] + t_5$$

$$t_1 = 4 * i$$

$$t_2 = n[t_1]$$

$$t_3 = 4 * j$$

$$t_5 = n$$

$$t_6 = b[t_4] + t_5$$

⇒

Here, t_4 is repeated, so it is eliminated and result of the t_1 is taken

(3) Copy Propagation

↳ It is the type of propagation which uses one variable instead of another.

example: $x = p * i$

$$\Rightarrow \text{area} = p * i * r * r$$

$$\text{area} = x * r * r$$

Here, x is eliminated and only one variable is used

(4) Code Movement

↳ The two goals of code movement is :

(i) To obtain space complexity

(ii) To obtain time complexity

example: for($i=0$; $i < 10$; $i++$)

{ $x = y * 5$;

$k = (y * 5) + 50$; }

$$z = y * 5$$

⇒ for($i=0$; $i < 10$; $i++$) {

$x = z$; ; $k = z + 50$; }

Here, $(y * 5)$ is generated only once.

(5) Strength Reduction:

→ In strength reduction technique, the higher strength operators can be replaced by lower strength operator
* is higher than +

example:

<pre>for (i=1; i <= 50; i++) { ---- count = i * 7; --- }</pre>	⇒	<pre>temp = 7; for (i=1; i <= 50; i++) { ---- count = temp; temp = temp + 7; }</pre>
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(6) Dead code elimination:

↳ A variable is said to be live in a program if the value is used frequently.
↳ A variable is said to be dead in a program if the value is never used.

example:

<pre>i = j; ---- n = i + 10; ----</pre>

i=j can be eliminated, coz it is never used.

(7) Loop optimization:

↳ It is a technique in which the optimization is performed on inner loop

example

<pre>while (i <= max-1) { sum = sum + a[i] }</pre>	⇒	<pre>n = max-1 while (i <= n) { sum = sum + a[i] }</pre>
---	---	---

Optimize the code:

```

② i=1, s=0;
for(i=1; i=3; i++)
  for(j=1; j<=3; j++)
    c[i][j] = c[i][j] + a[i][j] + b[i][j]
  
```

Three address code:

Using common sub expression elimination

i = 1	s = 0
s = 0	i = 1
L1: j = 1	L2: j = 1
L1: t1 = 4 * i	L1: t1 = 4 * i
t1 = t1 + j	t1 = t1 + j
t2 = t1 * 4	t2 = t1 * 4
t3 = a[t2]	t3 = a[t2]
t4 = i * 20	t4 = t3 + t4
t5 = t4 + j	t5 = t3 + t4
t5 = t4 * 4	t6 = c[t2]
t6 = b[t5]	t7 = t5 + t6
t7 = t3 + t6	c[i][j] = t7
t8 = i * 20	j = j + 1
t9 = t8 + j	if j <= 3 goto L1
t10 = t8 * 4	i = i + 1
t11 = c[t9]	if j <= 3 goto L2
t12 = t7 + t11	
c[i][j] = t12	
j = j + 1	
if j <= 3 goto L1	
i = i + 1	
if i <= 3 goto L2	

③ Global Data Flow Analysis

- ↳ It is used for wide application
- ↳ Here a program is represented in the form of program flow graph
- ↳ Program flow graph is the graphical representation in which node is basic block and edge is the flow control

↳ Two types of flow analysis:

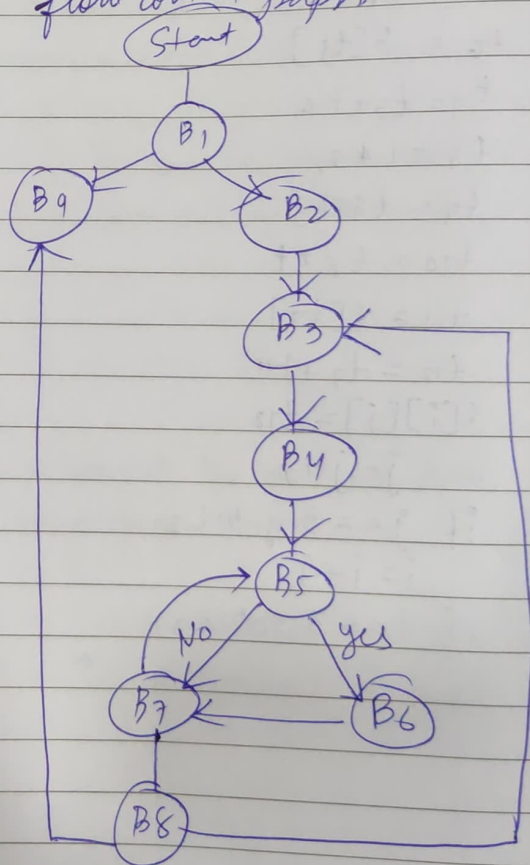
- (1) Control flow Analysis
- (2) Data flow Analysis

(1) Control flow Analysis: It is used to determine the information regarding arrangement, graph nodes, loops, nested loops of a specific code.

(2) Data flow Analysis: It is based on the data flow. It determines the information regarding the definition and use of data in program flow control graph.

```

if (i > 0) ] B1
{ sum = B[0]; ] B2
  i = 0; ]
L1: if (A[i] < B[i]) ] B3
    { i = 1; ] B4
L2: if (B[i] ≥ 0) ] B5
    { sum = sum + B[i]; ] B6
      j = j + 1; ] B7
      if (j < N) goto L2; ]
    }
    i = i + 1; ] B8
  }
  i = i + 1;
  if (i < N) goto L1; ]
}
printf("sum = %d\n", sum) ] B9
  
```



④ Storage Allocation strategies

There are 3 types of storage Allocation strategies

- (i) Static Allocation: It is for all the data at compile time
- (ii) Stack Allocation: It is used to manage the runtime storage.
- (iii) Heap Allocation: It is used to manage the dynamic memory allocation

(i) Static Allocation: Data structure cannot be created dynamically

→ It is for all the data at compile time

→ Size of every data item is determined by compiler

→ here the compiler can decide the amount of storage need for the data.

→ it is easy to identify the address of data.

Adv: easy to implement

Disadv: cannot use variables

: does not run out of memory

: not compatible with

: allows type checking

subprograms

(ii) Stack Allocation: Data struct. can be created dynamically

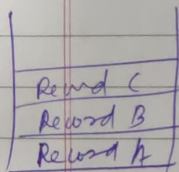
→ It is used to manage the runtime storage

→ It is based on stack

→ push() is used to start

→ pop() is used to end

→ uses LIFO



Adv: supports recursion

Disadv: it is slow.

: dynamic in nature

(iii) Heap allocation: Data struct can be created dynamically

→ used to manage the dynamic memory allocation

→ helpful for executing data

→ heap is allocated for activation record.



Adv: large blocks can be break into small blocks

Disadv: problem of fragmentation

: efficient

Activation Records

Temp var: used for the evaluation of expression

Local var: local data is stored here used for execution

Static link: This is optional field non local data in Activation Record

Dynamic link: This is also optional field Points to the AR

Actual para: has the info of actual param

they are passed to next field called procedures

Return value: stores the result

example:

```
main() {
```

```
    int f
```

```
    f = fact(3);
```

```
}
```

```
int fact(int n)
```

```
if (n == 1)
```

```
    return 1;
```

```
else
```

```
    return n * fact(n-1);
```

```
main()
```

```
fact(3)
```

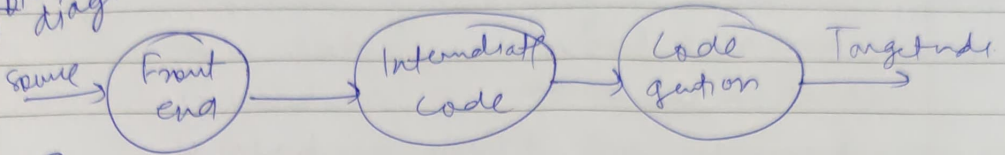
```
fact(2)
```

```
fact(1)
```

AR of fact(1)	Return value	1	
	Actual pointer	1	
	Dynamic link		
AR of fact(2)	Return value	2	1 * 2
	Actual pointer	2	
	Dynamic link		
AR of fact(3)	Return value	6	1 * 2 * 3
	Actual pointer	3	
	Dynamic link		
AR of main()	Return value	6	
	Local Variable		

Qm① code optimization

used to produce the efficient code

Pattern/block
diag.
for
code
optimization

Machine dependent: based on the char. of the target

Machine independent: based on prog. language such as algorithm etc.

② Peephole optimization

used to optimize the small part of code.

↳ it is performed on very small set of instructions

↳ this small set of instruction is called peephole

Objectives:

- To improve performance
- To reduce code size
- To optimize code

ex

$y = x + 5$		$y = x + 5$
$i = y + 1$	\Rightarrow	$w = i + 3$
$z = i$		
$w = z * 3$		