# CSE 30: Computer Organization and Systems Programming

Lecture 11: Memory map of C programs

ARM Programmer's Model

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# Typical ARM Memory Map

**OxFFFFFFC** 

OS and Memory-Mapped IO Dynamic Data BSS Data Text **Exception Handlers** 

## Program Memory Map

- "Text" (instructions in machine language)
- "Data" contains any global or static variables which have a pre-defined value and can be modified. That is any variables that are not defined within a function (and thus can be accessed from anywhere) or are defined in a function but are defined as static so they retain their value across subsequent calls.
- "BSS" also known as uninitialized data, is usually adjacent to the data segment. The BSS segment contains all global variables and static variables that are initialized to zero or do not have explicit initialization in source code
- "Heap" (for dynamically allocated data)
- "Stack" (for function local variables)

Heap and stack change in size as the program executes

## Viewing the memory map with 'size'

 You can use the size command to check the memory map of your executable

```
mem.c:
void foo() {
}
```

```
text data bss dec hex filename 20 0 0 20 14 hello.o
```

# Checking the memory map

```
void foo() {
   int i=10; //line 1
}
Output of size before adding line 1
text data bss dec hex filename
```

20 0 0 20 14 hello.o

The size of which section of the memory map of the program will increase on adding line 1?

- A. Text
- B. Data
- C. BSS
- D. None of the above
- E. All of the above

# Checking the memory map

```
void foo() {
    static int i=10; //line 1
  }
Output of size before adding line 1
```

```
text data bss dec hex filename 20 0 0 20 14 hello.o
```

The size of which section of the memory map of the program will increase on adding line 1?

- A. Text
- B. Data
- C. BSS
- D. None of the above
- E. All of the above

# Checking the memory map

```
int i=0; //line 1

void foo() {
}
Output of size before adding line 1

text data bss dec hex filename
20 0 0 20 14 hello.o
```

The size of which section of the memory map of the program will increase on adding line 1?

- A. Text
- B. Data
- C. BSS
- D. None of the above
- E. All of the above

### **Translations**

High-level language program (in C)

```
swap (int v[], int k)
{    int temp;
    temp = v[k];
    v[k] = v[k+1];
    v[k+1] = temp;
}
one-to-many
C compiler
```

Assembly language program (for MIPS)

```
swap: sll $2, $5, 2
  add $2, $4, $2
  lw $15, 0($2)
  lw $16, 4($2)
  sw $16, 0($2)
  sw $15, 4($2)
  jr $31

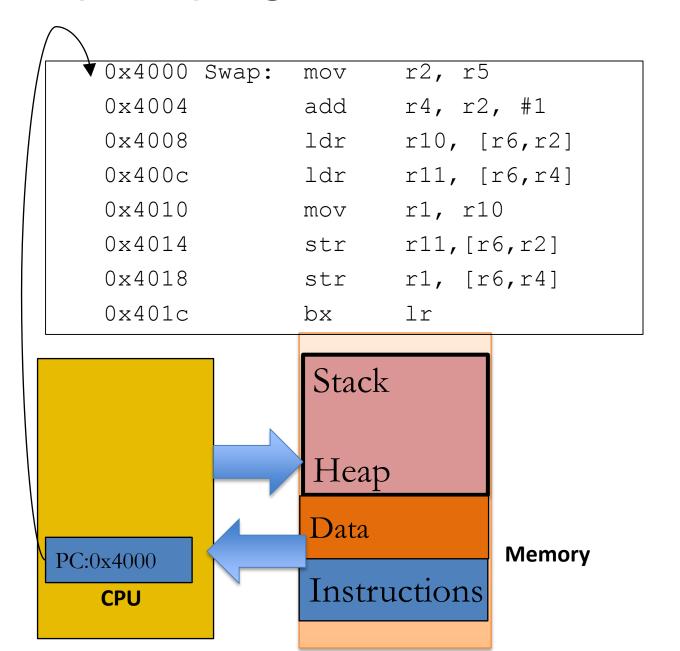
one-to-one
assembler
```

Machine (object, binary) code (for MIPS)

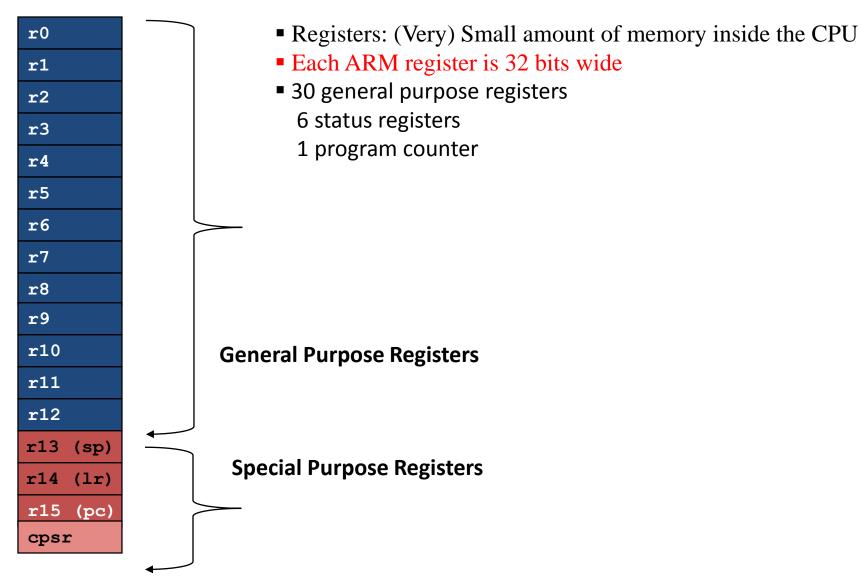
```
000000 00000 00101 000100001000000
000000 00100 00010 000100000100000
```

. . .

#### Steps in program execution



# The ARM Register Set



# ARM Assembly Variables: Registers

- Unlike HLL like C or Java, assembly cannot use variables
  - Why not? Keep Hardware Simple
- Data is put into a register before it is used for arithmetic, tested, etc.
- Result is stored in a register (later stored to memory)
- Benefit: Since registers are directly in hardware, they are very fast
- In C (and most High Level Languages) variables declared first and given a type
  - Example: int fahr, celsius; char a, b, c, d, e;
- Each variable can ONLY represent a value of the type it was declared as (cannot mix and match int and char variables)
- In Assembly Language, the registers have no type; operation determines how register contents are treated

#### PA2 ARM Skeleton code

```
.syntax unified
.text
.align 8
.global get min ARM
.func get min ARM, get min ARM
.type get min ARM, %function
get min ARM:
    @ Save caller's registers on the stack
    push \{r4-r11, ip, lr\}
    @ YOUR CODE GOES HERE (list *ls is in r0)
    @ (your code)
    @ put your return value in r0 here:
    @ restore caller's registers
    pop {r4-r11, ip, lr}
    @ ARM equivalent of return
    BX 1r
.endfunc
.end
```

# Basic Types of Instructions

- 1. Arithmetic: Only involves processor and registers
  - compute the sum (or difference) of two registers, store the result in a register
  - move the contents of one register to another
- Memory Instructions: Transfer of data between registers and memory
  - load a word from memory into a register
  - store the contents of a register into a memory word
- 3. Control Transfer Instructions: Change flow of execution
  - jump to another instruction
  - conditional jump (e.g., branch if register == 0)
  - jump to a subroutine

#### **Arithmetic Instructions**

In C:

a=b+c;

In ARM:

ADD r0, r1, r2

# Specifying constants in Arithmetic Instructions

In C:

a=b+10;

In ARM:

ADD r0, r1, #10

- Immediates are numerical constants.
- They appear often in code, so there are ways to indicate their existence

# How big can immediates be?

Q: What is a plausible range for the immediate in the instruction ADD r0, r1, <immediate>?

- A. 0 to  $(2^{32}-1)$
- B. 0 to 255

# **Assignment Instructions**

In C: In ARM:

a=b;

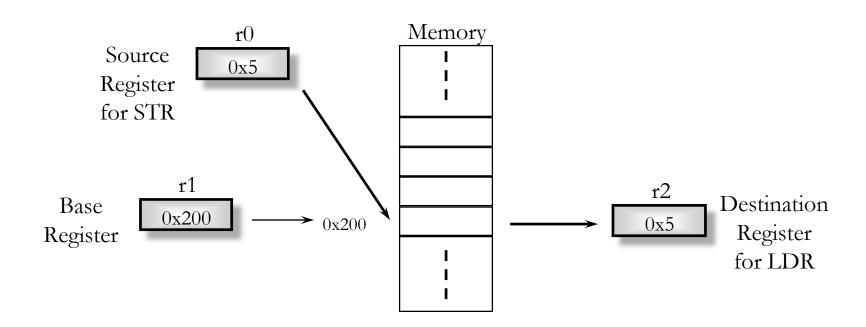
a=10;

### Data transfer (memory) Instructions

- Separate instructions to transfer data between registers and memory:
  - –Memory to register (load)
  - —Register to memory (store)
- Load/store usage (Base register addressing mode)

# Base Register Addressing Mode

- The memory location to be accessed is held in a base register
  - STR r0, [r1] @Store contents of r0 to location pointed to
    @ by contents of r1.
  - LDR r2, [r1] @Load r2 with contents of memory location @pointed to by contents of r1.



#### Data Transfer Instructions

In C:

```
void foo (int *p) {
    *p=10;
}
```

In ARM:

#### Data Transfer Instructions

In C:

```
void foo (int *p) {
   int a=*p;
}
```

In ARM: