# **Boot Sequence of Zynq ultrascale mpsoc (ZCU106):**

The Zynq UltraScale+ MPSoC ZCU106 board boot sequence involves several stages, including power-up initialization, boot ROM execution, loading the boot image, and executing the application. Here is a more detailed step-by-step explanation:

### • Power-Up Initialization:

- When the ZCU106 board is powered up, the power management system initializes the power supplies and sequencing for the different components on the board.
- Configuration voltages and clocks are set up to ensure proper functioning of the device.

#### • Boot ROM Execution:

- The Boot ROM (Read-Only Memory) is a small piece of on-chip memory that contains the initial boot code.
- Upon power-up, the processor executes code from the Boot ROM.
- The Boot ROM performs basic initialization, configures essential settings, and sets up the memory controller.

#### • FSBL (First Stage Boot Loader):

- The Boot ROM loads the First Stage Boot Loader (FSBL) into the on-chip RAM.
- The FSBL is responsible for initializing the DDR memory, configuring the PS (Processing System) peripherals, and setting up the boot environment.
- It also loads the second stage boot loader, usually U-Boot, into memory.

#### • U-Boot Execution:

- U-Boot is a flexible and widely used second stage bootloader.
- U-Boot initializes further system components, such as additional peripherals and external memory interfaces.
- It provides a command-line interface for basic user interaction and loading the Linux kernel.

### • Device Tree and Linux Kernel Loading:

- U-Boot loads the Linux kernel image into memory.
- The device tree blob (DTB) file, which contains information about the hardware configuration, is also loaded into memory.
- U-Boot passes the memory addresses of the kernel image and the device tree blob to the Linux kernel.

#### • Linux Kernel Initialization:

- The Linux kernel initializes the system, sets up memory management, and brings up essential subsystems.
- It mounts the root filesystem, initializes device drivers, and performs other necessary tasks.

#### • User Space Initialization:

- Once the kernel is up and running, it starts the user space initialization.
- The init process is launched, which, in turn, initializes the rest of the user space, including system daemons and user applications.

# • User Application Execution:

• Finally, the user applications or scripts specified in the startup configuration are executed.

It's important to note that the exact details of the boot sequence may vary depending on the specific configuration and requirements of your application. The above steps provide a general overview of the Zynq UltraScale+ MPSoC ZCU106 board boot process. It's recommended to refer to the official documentation and reference manuals for the ZCU106 and the Xilinx tools for more detailed and up-to-date information.

# **Detailed explanation of every step:**

# **Step 1:**(Power-Up Initialization):

Power-up initialization is a critical phase in the boot sequence of the ZCU106 board. During this phase, the power management system takes control to ensure that all the components receive the required power supplies and that they are sequenced properly. The objective is to establish a stable and controlled power distribution to enable correct operation of the entire system. Here's a more detailed explanation:

# • Power Supplies Initialization:

- The ZCU106 board contains various components such as the Processing System (PS), Programmable Logic (PL), memory, peripherals, and interfaces. Each of these components may require different voltage levels for proper operation.
- The power management system on the board ensures that the power supplies for each component are initialized in a controlled manner.
- Voltage regulators may be employed to generate the required voltage levels for different subsystems, and they are sequenced to avoid voltage spikes or other issues during power-up.

### • Sequencing of Power Rails:

- Sequencing involves controlling the order in which different power supplies are turned on to avoid issues like excessive current draw or voltage overshoot.
- For example, the voltage rails for the FPGA fabric (PL) and the Processing System (PS) may need to be powered up in a specific order to prevent potential issues during initialization.
- The power management system typically uses dedicated sequencing logic or programmable sequencers to achieve this controlled power-up sequence.

#### • Clock Initialization:

- Configuration of clocks is crucial for the proper functioning of digital systems.
   The ZCU106 board has multiple clock domains, each serving different components.
- Clocks for the PS, PL, and various peripherals need to be initialized with the correct frequency and phase relationships.
- Phase-Locked Loops (PLLs) or other clock generation circuits may be employed to generate the required clock frequencies, and their configuration is part of the power-up initialization.

#### • Monitoring and Fault Handling:

- During power-up, the power management system may monitor various parameters, such as voltages and temperatures, to ensure they are within acceptable ranges.
- Fault detection and handling mechanisms are implemented to respond to any anomalies, such as over-voltage, under-voltage, or over-temperature conditions.
- If a fault is detected, the power management system may take corrective actions, such as shutting down certain components or triggering an alert.

#### • Initialization Complete Signal:

- Once the power supplies are stable, and all necessary initialization steps are completed, a signal or flag may be generated to indicate that the power-up initialization phase has finished successfully.
- This signal can be used to trigger the next stage of the boot process, such as the execution of the Boot ROM code.

Overall, the power-up initialization phase is crucial for ensuring a reliable and controlled start-up of the ZCU106 board, laying the foundation for subsequent stages in the boot sequence. The details may vary based on the specific design and configuration of the ZCU106 board and its associated power management components. It's essential to refer to the board's technical documentation and Xilinx documentation for specific details regarding power-up sequences and configuration.

# **Step 2:**(Boot ROM Execution):

The Boot ROM (Read-Only Memory) execution is a critical step in the boot sequence of the Zynq UltraScale+ MPSoC ZCU106. The Boot ROM contains a small piece of on-chip memory with initial boot code, and its role is to initialize essential components and set the stage for the subsequent stages of the boot process. Here's a detailed explanation of the Boot ROM execution phase:

#### • Power-On Reset (POR):

- When the ZCU106 board is powered up, the processor (ARM Cortex-A53 in the Processing System or PS) starts executing code from a fixed location in the Boot ROM.
- This execution is initiated by a Power-On Reset (POR) signal, which is generated during power-up.

# • Boot ROM Initialization:

- The Boot ROM contains a small amount of code that is hard-wired into the chip during manufacturing.
- This initial code is responsible for basic initialization tasks before the system can execute more complex boot loaders or the operating system.
- The Boot ROM may set up the stack pointer and initialize other essential registers.

# • Configuration of Memory System:

• The Boot ROM configures the Memory Interface Generator (MIG) or other memory controller units to initialize the external DDR memory.

- DDR initialization is crucial because it provides the primary storage for the subsequent boot loader, operating system, and user applications.
- The Boot ROM sets up parameters such as memory type, size, and timing settings to ensure proper communication with external memory.

### • Processor Configuration:

- The Boot ROM configures the processor, including setting up the cache, enabling the Memory Management Unit (MMU), and configuring other processor-specific settings.
- These configurations are essential for efficient and secure operation of the processor during subsequent stages of the boot process.

# • Peripheral Initialization:

- The Boot ROM initializes essential peripherals and interfaces required for the boot process.
- This may include configuring UART (Universal Asynchronous Receiver/Transmitter) interfaces for communication, initializing timers, and setting up other peripheral devices that are necessary for the boot sequence.

#### • Boot Device Selection:

- The Boot ROM determines from which boot device the next stage of the boot process will be loaded. Common boot devices include Flash memory, SD card, or other storage media.
- The Boot ROM may use configuration settings (e.g., boot mode pins) to determine the boot device and initiate the loading process.

# • Handover to the First Stage Boot Loader (FSBL):

- Once the basic initialization tasks are complete, the Boot ROM hands over control to the First Stage Boot Loader (FSBL).
- The FSBL is responsible for more advanced initialization tasks, such as configuring additional peripherals, loading the second stage boot loader (e.g., U-Boot), and preparing the system for loading the operating system.

In summary, the Boot ROM execution phase sets the foundation for the subsequent boot stages by initializing critical components, configuring the memory system, and preparing the processor for more advanced tasks. The specific details of Boot ROM behavior may vary depending on the hardware configuration and settings on the ZCU106 board. It's recommended to refer to the board's technical documentation and Xilinx documentation for precise information on Boot ROM behavior and initialization.

# Step 3:(FSBL (First Stage Boot Loader))

The First Stage Boot Loader (FSBL) is a crucial component in the boot sequence of the Zynq UltraScale+ MPSoC ZCU106. It is loaded into on-chip RAM by the Boot ROM, and its primary responsibility is to perform more advanced initialization tasks, including configuring memory, peripherals, and setting up the environment for the subsequent stages of the boot process. Here's a detailed explanation of the FSBL's role:

#### • Loading FSBL into On-Chip RAM:

- After the Boot ROM performs basic initialization and sets up the memory controller, it loads the FSBL code into on-chip RAM.
- On-chip RAM is a small amount of memory available within the FPGA, which is used to store critical code that needs to be accessed quickly during the boot process.

# • Basic Initialization and Configuration:

- The FSBL builds upon the work of the Boot ROM by performing more detailed initialization of the system.
- It continues the configuration of the Processor System (PS) peripherals, setting up registers, and configuring additional components that may not have been fully initialized in the Boot ROM phase.

# • DDR Memory Initialization:

- One of the primary tasks of the FSBL is to initialize the external DDR memory.
- DDR initialization involves configuring the Memory Interface Generator (MIG) or other memory controllers to ensure proper communication with the external DDR memory devices.
- Correct DDR initialization is crucial for reliable and efficient operation of the system, as DDR memory serves as the primary storage for the subsequent boot loader, kernel, and user applications.

### • Configuration of Boot Environment:

- The FSBL sets up the boot environment, including the configuration of the boot mode and source. This may involve checking configuration pins or registers to determine the desired boot source (e.g., SD card, QSPI flash, etc.).
- It may also configure boot parameters, such as kernel load addresses and command line options, which are later used by the second stage boot loader and the operating system.

# • Loading the Second Stage Boot Loader (U-Boot):

- Once the DDR memory is initialized and the boot environment is set up, the FSBL loads the second stage boot loader into memory.
- U-Boot is a widely used second stage boot loader in many embedded systems.
   It provides additional features such as a command-line interface and flexible boot options.
- The FSBL transfers control to U-Boot by passing the necessary information, including the memory addresses where U-Boot is loaded.

#### • Handover to the Second Stage Boot Loader:

- After loading U-Boot into memory, the FSBL hands over control to U-Boot.
- U-Boot takes over the boot process and continues with the loading of the Linux kernel or another operating system.

In summary, the FSBL bridges the gap between the Boot ROM and the second stage boot loader (U-Boot) by performing advanced initialization tasks, configuring memory and peripherals, and setting up the boot environment. It plays a crucial role in preparing the system for the execution of the main operating system. The specific details of the FSBL's behavior may vary based on the configuration and settings of the ZCU106 board. It's advisable to consult the board's technical documentation and Xilinx documentation for accurate information on the FSBL and its initialization process.

# **Step 4**:(U-Boot Execution)

U-Boot (Universal Bootloader) is a widely used second-stage bootloader in embedded systems, including the Zynq UltraScale+ MPSoC ZCU106. Its primary role is to continue the boot process initiated by the earlier stages (Boot ROM and FSBL) and provide additional functionality, including system initialization and user interaction. Here's a detailed explanation of U-Boot's execution and functionality:

### • Loading by FSBL:

The First Stage Boot Loader (FSBL) is responsible for loading U-Boot into memory. After initializing the DDR memory and setting up the boot environment, FSBL transfers control to U-Boot by passing necessary information, such as the memory address where U-Boot is loaded.

#### • Flexible and Configurable:

- U-Boot is known for its flexibility and configurability. It supports a wide range of hardware architectures and configurations, making it a versatile choice for various embedded systems.
- It is often configured to support specific peripherals, memory devices, and boot sources based on the requirements of the target system.

### • System Component Initialization:

- U-Boot takes on the responsibility of initializing additional system components beyond what the Boot ROM and FSBL have already configured. This may include peripheral devices, external memory interfaces, and other hardware components.
- U-Boot's initialization ensures that the system is properly configured for subsequent stages, such as loading the Linux kernel.

#### • Command-Line Interface (CLI):

- One of the key features of U-Boot is its command-line interface (CLI). It provides a shell-like interface, allowing users to interact with and control various aspects of the system.
- Users can enter commands to configure settings, load files, inspect memory, and perform other operations. The CLI is valuable for debugging, testing, and configuring the system during development.

#### • Environment Variables:

- U-Boot uses environment variables to store configuration settings and parameters. These variables can be customized to adapt U-Boot to the specific requirements of the system.
- Commonly used environment variables include boot arguments, memory addresses, and boot sources.

# • Loading the Linux Kernel:

- One of the critical tasks performed by U-Boot is loading the Linux kernel into memory. U-Boot supports various file systems and boot sources, such as TFTP (Trivial File Transfer Protocol), NFS (Network File System), or storage devices like SD cards and USB drives.
- The user can issue commands to load the kernel image and device tree blob (DTB) into memory, specifying the source and destination addresses.

#### • Handover to the Linux Kernel:

- Once the Linux kernel and associated files are loaded into memory, U-Boot hands over control to the Linux kernel by initiating the kernel's execution.
- At this point, the Linux kernel takes charge of the system, continues with its initialization, and proceeds to launch the user space, bringing up the complete operating system.

In summary, U-Boot serves as a versatile and configurable second-stage bootloader that initializes system components, provides a command-line interface for user interaction, and loads the Linux kernel into memory. Its flexibility makes it suitable for a wide range of embedded systems, and its CLI facilitates development, debugging, and system configuration.

# **Step 5**:(Device Tree and Linux Kernel Loading)

The process of loading the Linux kernel and the Device Tree Blob (DTB) into memory by U-Boot is a crucial step in the boot sequence of embedded systems. Here's a detailed explanation of this phase:

#### • Loading the Linux Kernel Image:

- After U-Boot initializes system components and peripherals, its next task is to load the Linux kernel image into memory.
- The Linux kernel image is typically a compressed binary file, often named **zImage** or **uImage**, containing the executable code of the Linux kernel.

# • Choosing the Boot Source:

- U-Boot provides flexibility in choosing the source from which to load the Linux kernel image. Common sources include:
  - Local Storage: The kernel image might be stored on an SD card, eMMC, USB drive, or other local storage devices.
  - **Network:** U-Boot supports booting over the network using protocols like TFTP or NFS.
  - Other Boot Methods: Depending on the configuration, U-Boot may support booting from various sources.

# • Loading the Device Tree Blob (DTB):

- Alongside the Linux kernel, U-Boot also loads the Device Tree Blob (DTB) into memory.
- The DTB is a binary file that contains information about the hardware configuration of the system. It describes the layout and properties of the various peripherals, memory regions, and other hardware components.
- The DTB is crucial for the Linux kernel to understand the hardware environment it is running on.

#### • Passing Memory Addresses to the Linux Kernel:

- Once both the Linux kernel image and the DTB are loaded into memory, U-Boot passes the memory addresses of these loaded images to the Linux kernel.
- The memory addresses are crucial for the Linux kernel to know where to find its executable code (kernel image) and the hardware configuration details (DTB).

 U-Boot typically uses specific environment variables, such as kernel\_addr for the kernel image and fdt\_addr for the DTB, to store and communicate these memory addresses.

# • Booting the Linux Kernel:

- With the memory addresses of the kernel image and DTB provided by U-Boot, the Linux kernel can now start its execution.
- The Linux kernel uses the information from the DTB to configure and initialize the hardware components based on the specifics of the embedded system.

#### • Kernel Initialization:

- The Linux kernel continues with its initialization process, configuring device drivers, mounting the root filesystem, and starting user space processes.
- The information provided by the DTB is crucial for the kernel to correctly set up the hardware environment.

In summary, U-Boot plays a central role in loading both the Linux kernel image and the Device Tree Blob into memory. It provides flexibility in choosing the boot source and passes the necessary memory addresses to the Linux kernel, enabling a smooth transition to the kernel initialization phase. The DTB is particularly essential for the Linux kernel to understand the hardware configuration and initialize the system appropriately.

# **Step 6**:(Linux Kernel Initialization)

The initialization of the Linux kernel is a critical phase in the boot process, transitioning the system from a minimalistic state to a fully functional operating system. This phase involves various tasks such as setting up memory management, bringing up essential subsystems, mounting the root filesystem, initializing device drivers, and more. Here's a detailed explanation of the Linux kernel initialization process:

#### • Processor Initialization:

- The Linux kernel starts by initializing the processor, configuring it for the target architecture.
- It sets up essential registers, initializes the task scheduler, and prepares the processor for executing kernel code.

### • Memory Management Initialization:

- The kernel initializes the Memory Management Unit (MMU) and sets up the initial memory mappings.
- It configures the kernel's page tables, enabling virtual memory support and providing a translation layer between virtual and physical addresses.

#### • Early Kernel Initialization:

- Early kernel initialization involves setting up basic structures and subsystems before the kernel fully transitions to normal execution.
- This includes initializing the kernel command line parameters, parsing configuration options, and performing architecture-specific setup tasks.

#### • Kernel Command Line Processing:

• The kernel examines the command line parameters passed to it by the bootloader (e.g., U-Boot).

 Command line options can influence various aspects of kernel behavior, such as choosing the root filesystem, specifying kernel parameters, or enabling specific features.

### • Kernel Parameter Processing:

- Parameters specified on the kernel command line can influence the kernel's behavior
- Common parameters include those related to debugging, specifying the root filesystem, configuring device drivers, and setting kernel options.

#### • Root Filesystem Mounting:

- The kernel mounts the root filesystem, which contains the initial set of files and directories needed for the system to function.
- The root filesystem can be located on various storage devices, such as an SD card, eMMC, or a network file system (NFS).

#### • Kernel Initialization Proper:

- With the root filesystem mounted, the kernel proceeds to initialize the core subsystems and components.
- It initializes the process scheduler, task scheduler, and other fundamental structures required for the functioning of the operating system.

#### • Device Driver Initialization:

- The kernel initializes device drivers for essential hardware components.
- Device drivers enable communication between the kernel and hardware devices, allowing the kernel to interact with peripherals such as storage devices, network interfaces, and input/output devices.

#### • Subsystem Initialization:

- Subsystems such as networking, file systems, and the Virtual File System (VFS) are initialized.
- Networking subsystem initialization includes configuring network interfaces, assigning IP addresses, and setting up routing tables.

# • User Space Interface:

- The kernel prepares to transition to user space by setting up the initial usermode environment.
- The first user space process, usually the init process, will take control from the kernel and continue the system initialization in user space.

#### • Init Process Execution:

- The kernel hands over control to the init process, which becomes the first user space process with Process ID (PID) 1.
- The init process is responsible for further system initialization, launching system services, and starting user applications.

# • User Space Initialization:

• Following the init process execution, the system progresses to user space initialization, as described in a previous response.

In summary, the Linux kernel initialization process involves a series of steps, starting from processor and memory setup, moving through core subsystem and device driver initialization, and culminating in the mounting of the root filesystem and transitioning to user space. This initialization establishes the foundation for the fully operational Linux operating system.

# **Step 7**:(User Space Initialization)

User space initialization is the process that occurs after the Linux kernel has successfully booted and gained control of the system. During this phase, the kernel transitions from its early bootstrapping activities to the initialization of user space, which includes launching the init process. The init process, traditionally the first user space process, is responsible for initializing the entire user space environment, including system daemons and user applications. Here's a detailed explanation of the user space initialization process:

#### • Kernel Initialization:

- The Linux kernel initializes essential components such as memory management, task scheduler, and device drivers during its startup.
- Kernel initialization sets up the groundwork for managing processes, handling interrupts, and providing services to user space applications.

# • Initramfs (Initial RAM File System):

• In some cases, an initial root file system, known as initramfs, may be used. Initramfs is a temporary file system loaded into memory during the initial stages of the kernel boot. It contains tools and utilities needed for mounting the actual root file system.

### • Root File System Mounting:

- The kernel proceeds to mount the actual root file system. This can be located on different storage devices, such as an SD card, an eMMC, or a network file system (NFS).
- The root file system contains the directory structure, libraries, binaries, and configuration files necessary for the operation of the user space.

#### • Init Process Launch:

- The kernel identifies the user space initialization process (init) and launches it as the first user space process.
- The init process is assigned the process ID (PID) of 1, and it becomes the ancestor (parent) process of all subsequent user space processes.

#### • Init System (SysVinit, systemd, or Others):

- The init process is responsible for starting the init system, which coordinates the initialization of the user space environment.
- Traditional init systems include SysVinit, while more modern systems might use systemd or other alternatives. The init system is responsible for launching system services, managing dependencies, and coordinating the startup sequence.

#### • Service Initialization:

- The init system initializes various system services, daemons, and user applications defined in its configuration.
- Services can include networking services, logging daemons, system monitoring tools, and other essential components.

#### • Runlevels or Targets:

- Traditional Unix-like systems use runlevels, while modern systems often use targets to define different system states.
- Runlevels or targets specify the set of services and daemons that should be running in a particular system state.

• The init system transitions between these states based on system events, user commands, or configuration changes.

# • User Login and Interactive Environment:

- Once the core system services and daemons are initialized, the system is ready for user login.
- Users can log in through a text-based console or graphical user interface (GUI), and the init system is responsible for launching the user's shell or desktop environment.

# • User Applications:

With the user space fully initialized, users can start their applications.
 Applications can range from command-line utilities to graphical applications, depending on the system configuration.

In summary, user space initialization involves transitioning from the kernel's early bootstrapping activities to launching the init process, which then initializes the init system, system services, and user applications. The init system plays a crucial role in coordinating the startup sequence and managing the user space environment on a Linux system.

# **Step 8:**(User Application Execution)

Once the user space has been initialized and the system is ready for user interaction, user applications and scripts specified in the startup configuration may be executed. The exact details of how this occurs can depend on the specific configuration of the Linux system, including the init system in use (such as SysVinit or systemd) and the startup scripts defined for the system. Here's a detailed explanation of the process:

#### • Init System Execution:

- The init system, whether it's SysVinit, systemd, or another alternative, typically includes scripts and configuration files that define the startup sequence of the system.
- These scripts are responsible for launching various system services, daemons, and user applications.

#### • Startup Scripts:

- System administrators can define startup scripts that specify which user applications or scripts should be executed during the system's boot process.
- These scripts are usually located in specific directories (e.g., /etc/init.d/ for SysVinit or /etc/systemd/system/ for systemd) and are associated with specific runlevels or targets.

# • Runlevels or Targets:

- In traditional Unix-like systems that use SysVinit, runlevels define different system states, each with a specific set of services and daemons.
- Modern systems using systemd often use targets, which are similar to runlevels but more flexible. Targets represent a system state with a defined set of services.

#### • Service Start Order:

 The init system starts services, daemons, and user applications in a defined order based on dependencies.  Each service or application may have dependencies on other services, and the init system ensures that these dependencies are satisfied before starting the respective service.

# • Parallelization:

- Many modern init systems, such as systemd, support parallelization, meaning that services can start concurrently when their dependencies are met.
- This improves system boot times by allowing multiple services to start simultaneously, reducing the overall startup time.

#### • User-Level Startup:

- After system-level services and daemons are started, the init system may proceed to start user-level services or applications.
- These could include background processes, user-specific services, or scripts specified in user-specific configuration files.

#### • User Session Initialization:

- For graphical environments, the display manager (e.g., GDM, LightDM) starts a graphical login screen.
- When a user logs in, a user session is initialized, and user-specific scripts or applications defined in the user's configuration (such as .bashrc for Bash) may be executed.

# • User Applications Execution:

- Finally, as part of the user's session initialization, user applications specified in startup configuration files or scripts are executed.
- These applications could be tools, utilities, or scripts that the user wants to run automatically when their session starts.

#### • Autostart Configurations:

- Desktop environments often provide mechanisms for users to define autostart configurations, specifying applications that should automatically launch when the user logs in.
- This can be managed through graphical tools or by editing specific configuration files.

In summary, user application execution during the system boot process involves the initiation of user-level services, daemons, and scripts defined in the system's startup configuration. The init system, runlevels or targets, and user-specific configurations play key roles in determining which applications are launched and in what order during the system's startup sequence.

# Flow diagram for boot sequence:

```
Power On/Reset
BootROM Execution
Boot Mode Selection
Loading First Stage Bootloader (FSBL)
Execution of U-Boot
Loading Linux Kernel (Image) and Device Tree Blob (system.dtb)
Linux Kernel Initialization
Root File System Initialization (rootfs.cpio.gz.u-boot)
System Initialization
User Space
```