Assignment 2: Build a CNN for image recognition.

Due Date: March 31, 11:59PM

Name: [Bhargavi Katta]

Introduction:

1. In this assignment, you will build Convolutional Neural Network to classify CIFAR-10 Images.

- 2. You can directly load dataset from many deep learning packages.
- 3. You can use any deep learning packages such as pytorch, keras or tensorflow for this assignment.

Requirements:

- 1. You need to load cifar 10 data and split the entire training dataset into training and validation.
- 2. You will implement a CNN model to classify cifar 10 images with provided structure.
- 3. You need to plot the training and validation accuracy or loss obtained from above step.
- 4. Then you can use tuned hyper-parameters to train using the entire training dataset.
- 5. You should report the testing accuracy using the model with complete data.
- 6. You may try to change the structure (e.g, add BN layer or dropout layer,...) and analyze your findings.

Google Colab

• If you do not have GPU, the training of a CNN can be slow. Google Colab is a good option.

Batch Normalization (BN)

Background:

• Batch Normalization is a technique to speed up training and help make the model more stable.

- In simple words, batch normalization is just another network layer that gets inserted between a hidden layer and the next hidden layer. Its job is to take the outputs from the first hidden layer and normalize them before passing them on as the input of the next hidden layer.
- For more detailed information, you may refer to the original paper: https://arxiv.org/pdf/1502.03167.pdf.

BN Algorithm:

- Input: Values of x over a mini-batch: $\mathbf{B} = \{x_1, \dots, x_m\};$
- ullet Output: $\{y_i=BN_{\gamma,eta}(x_i)\}$, γ,eta are learnable parameters

Normalization of the Input:

$$\mu_{\mathbf{B}} = rac{1}{m} \sum_{i=1}^m x_i$$

$$\sigma_{ extbf{B}}^2 = rac{1}{m} \sum_{i=1}^m (x_i - \mu_{ extbf{B}})^2$$

$$\hat{x_i} = rac{x_i - \mu_{ extbf{B}}}{\sqrt{\sigma_{ extbf{B}}}^2 + \epsilon}$$

Re-scaling and Offsetting:

$$y_i = \gamma \hat{x_i} + eta = BN_{\gamma,eta}(x_i)$$

Advantages of BN:

- 1. Improves gradient flow through the network.
- 2. Allows use of saturating nonlinearities and higher learning rates.
- 3. Makes weights easier to initialize.
- 4. Act as a form of regularization and may reduce the need for dropout.

Implementation:

- The batch normalization layer has already been implemented in many packages. You may simply call the function to build the layer. For example: torch.nn.BatchNorm2d() using pytroch package, keras.layers.BatchNormalization() using keras package.
- The location of BN layer: Please make sure BatchNormalization is between a Conv / Dense layer and an activation layer.

1. Data preparation

1.1. Load data

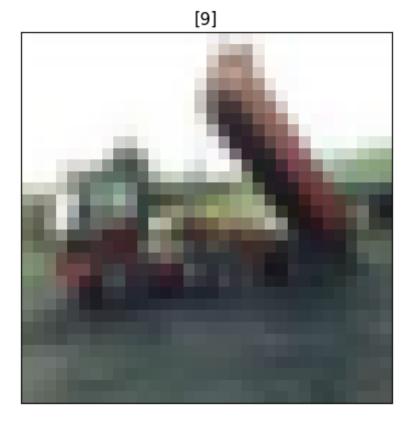
```
In [1]:
        import numpy as np
        import tensorflow
        import tensorflow.keras as keras
In [2]:
        # Load Cifar-10 Data
        # This is just an example, you may load dataset from other packages.
        import tensorflow.keras as keras
        import numpy as np
        ### If you can not load keras dataset, un-comment these two lines.
        #import ssl
        #ssl. create default https context = ssl. create unverified context
        (x train, y train), (x test, y test) = keras.datasets.cifar10.load data()
        print('shape of x train: ' + str(x train.shape))
        print('shape of y_train: ' + str(y_train.shape))
        print('shape of x_test: ' + str(x_test.shape))
        print('shape of y_test: ' + str(y_test.shape))
        print('number of classes: ' + str(np.max(y train) - np.min(y train) + 1))
        #np.max(y train),np.min(y train) + 1
        Downloading data from https://www.cs.toronto.edu/~kriz/cifar-10-python.tar.gz
        shape of x train: (50000, 32, 32, 3)
        shape of y train: (50000, 1)
        shape of x test: (10000, 32, 32, 3)
        shape of y test: (10000, 1)
       number of classes: 10
```

```
In [3]: y_train.shape[0]

Out[3]: 50000

In [4]: import matplotlib.pyplot as plt
    # Display the first image in the training set
    plt.imshow(x_train[2])
    # Set the plot title to the corresponding label
    plt.title(y_train[2])
    # Remove the x and y axis ticks
    plt.xticks([])
    plt.yticks([])
    # Show the plot
    plt.show()
```

/usr/local/lib/python3.9/dist-packages/matplotlib/text.py:1279: FutureWarning: elementwise comparison failed; r eturning scalar instead, but in the future will perform elementwise comparison if s != self._text:



1.2. One-hot encode the labels (5 points)

In the input, a label is a scalar in $\{0, 1, \dots, 9\}$. One-hot encode transform such a scalar to a 10-dim vector. E.g., a scalar y_train[j]=3 is transformed to the vector y_train_vec[j]=[0, 0, 0, 0, 0, 0, 0, 0, 0].

- 1. Implement a function to_one_hot that transforms an n imes 1 array to a n imes 10 matrix.
- 2. Apply the function to y_train and y_test.

```
In [5]:

def to_one_hot(y, num_class=10):
    y_vect=np.zeros((y.shape[0],num_class))
    for i in range(len(y)):
        y_vect[i][y[i]]=1
    return y_vect

y_train_vec = to_one_hot(y_train)
```

```
y_test_vec = to_one_hot(y_test)

print('Shape of y_train_vec: ' + str(y_train_vec.shape))
print('Shape of y_test_vec: ' + str(y_test_vec.shape))

print(y_train[0])
print(y_train_vec[0])
```

```
Shape of y_train_vec: (50000, 10)
Shape of y_test_vec: (10000, 10)
[6]
[0. 0. 0. 0. 0. 0. 1. 0. 0. 0.]
```

Remark: the outputs should be

- Shape of y_train_vec: (50000, 10)
- Shape of y_test_vec: (10000, 10)
- [6]
- [0. 0. 0. 0. 0. 0. 1. 0. 0. 0.]

1.3. Randomly partition the training set to training and validation sets (5 points)

Randomly partition the 50K training samples to 2 sets:

- a training set containing 40K samples: x_tr, y_tr
- a validation set containing 10K samples: x_val, y_val

```
In [6]:
# Generating 50k random numbers splitting first 40k as train and rest 10k as test by using rand indices
rand_index=np.random.permutation(50000)
train_index=rand_index[0:40000]
valid_index=rand_index[40000:50000]

x_tr=x_train[train_index,:]
y_tr=y_train_vec[train_index,:]

x_val=x_train[valid_index,:]
y_val=y_train_vec[valid_index,:]

print('Shape of x_tr: ' + str(x_tr.shape))
print('Shape of y_tr: ' + str(y_tr.shape))
print('Shape of x_val: ' + str(x_val.shape))
print('Shape of y_val: ' + str(y_val.shape))
```

```
Shape of x_tr: (40000, 32, 32, 3)
Shape of y_tr: (40000, 10)
Shape of x_val: (10000, 32, 32, 3)
Shape of y val: (10000, 10)
```

2. Build a CNN and tune its hyper-parameters (50 points)

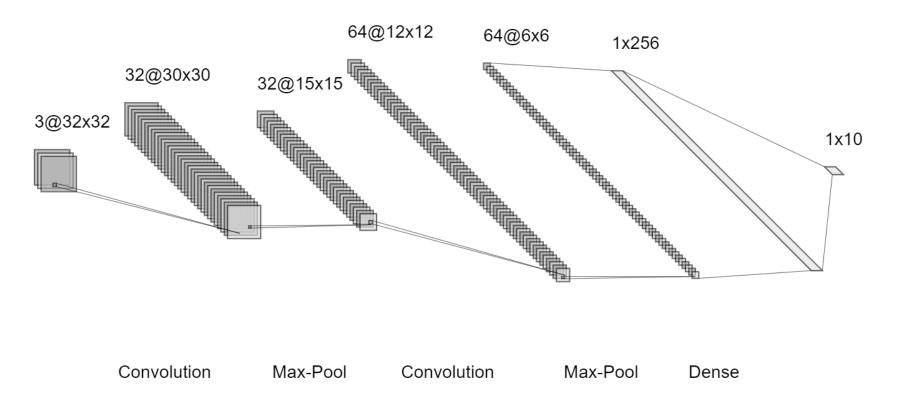
- Build a convolutional neural network model using the below structure:
- It should have a structure of: Conv ReLU Max Pool ConV ReLU Max Pool Dense ReLU Dense Softmax
- In the graph 3@32x32 means the dimension of input image, 32@30x30 means it has 32 filters and the dimension now becomes 30x30 after the convolution.
- All convolutional layers (Conv) should have stride = 1 and no padding.
- Max Pooling has a pool size of 2 by 2.



- You may use the validation data to tune the hyper-parameters (e.g., learning rate, and optimization algorithm)
- Do NOT use test data for hyper-parameter tuning!!!
- Try to achieve a validation accuracy as high as possible.

```
In [7]:  # Build the model
    from tensorflow.keras.layers import Conv2D,MaxPooling2D,Flatten,Dense,Dropout,Activation,BatchNormalization
    from tensorflow.keras.models import Sequential
```

```
In [8]:  # padding='valid'means no. padding
    # padding='same' means padding will be added to make the IP and OP shapes same
```



Basic CNN model with no BatchNormalization and No dropout Layers

```
In [9]:
    model=Sequential()
    model.add(Conv2D(32,(3,3),padding='valid',input_shape=(32,32,3)))
    #model.add(BatchNormalization())
    model.add(Activation('relu'))
    model.add(MaxPooling2D((2,2)))

    model.add(BatchNormalization())
    model.add(Activation('relu'))
    model.add(MaxPooling2D((2,2)))

    model.add(Flatten())
    model.add(BatchNormalization())
    model.add(BatchNormalization())
    model.add(BatchNormalization())
    model.add(BatchNormalization())
    model.add(BatchNormalization())
    model.add(Activation("relu"))
```

```
model.add(Dense(10))
model.add(Activation('softmax'))
model.summary()
```

Model: "sequential"

Layer (type)	Output Shape	Param #
conv2d (Conv2D)	(None, 30, 30, 32)	896
activation (Activation)	(None, 30, 30, 32)	0
<pre>max_pooling2d (MaxPooling2D)</pre>	(None, 15, 15, 32)	0
conv2d_1 (Conv2D)	(None, 12, 12, 64)	32832
<pre>activation_1 (Activation)</pre>	(None, 12, 12, 64)	0
<pre>max_pooling2d_1 (MaxPooling 2D)</pre>	(None, 6, 6, 64)	0
flatten (Flatten)	(None, 2304)	0
dense (Dense)	(None, 256)	590080
activation_2 (Activation)	(None, 256)	0
dense_1 (Dense)	(None, 10)	2570
activation_3 (Activation)	(None, 10)	0
Total params: 626,378 Trainable params: 626,378 Non-trainable params: 0		

```
In [10]:
```

```
# Define model optimizer and loss function
from keras import optimizers
learning_rate = 1e-4 # tuned one
model.compile(loss='categorical_crossentropy',
```

```
optimizer=optimizers.RMSprop(learning_rate=learning_rate),
metrics=['acc'])
```

```
In [11]:
  # Train the model and store model parameters/loss values
  history = model.fit(x tr,y tr, epochs=50, validation data=(x val,y val))
  Epoch 1/50
  1 acc: 0.4676
  Epoch 2/50
  1 acc: 0.5488
  Epoch 3/50
  1 acc: 0.5787
  Epoch 4/50
  1 acc: 0.5938
  Epoch 5/50
  1 acc: 0.6241
  Epoch 6/50
  1 acc: 0.5986
  Epoch 7/50
  1 acc: 0.6315
  Epoch 8/50
  1 acc: 0.6342
  Epoch 9/50
  1 acc: 0.6330
  Epoch 10/50
  1 acc: 0.6363
  Epoch 11/50
  1 acc: 0.6508
  Epoch 12/50
```

l_acc: 0.6462
Epoch 13/50

```
1 acc: 0.6462
Epoch 14/50
1 acc: 0.6496
Epoch 15/50
1 acc: 0.6427
Epoch 16/50
1 acc: 0.6542
Epoch 17/50
1 acc: 0.6462
Epoch 18/50
1 acc: 0.6402
Epoch 19/50
1 acc: 0.6528
Epoch 20/50
1 acc: 0.6505
Epoch 21/50
1 acc: 0.6522
Epoch 22/50
1 acc: 0.6492
Epoch 23/50
1 acc: 0.6564
Epoch 24/50
1 acc: 0.6541
Epoch 25/50
1 acc: 0.6463
Epoch 26/50
1 acc: 0.6558
Epoch 27/50
1 acc: 0.6487
Epoch 28/50
```

```
1 acc: 0.6475
Epoch 29/50
1 acc: 0.6555
Epoch 30/50
1 acc: 0.6543
Epoch 31/50
1 acc: 0.6578
Epoch 32/50
1 acc: 0.6541
Epoch 33/50
1 acc: 0.6580
Epoch 34/50
1 acc: 0.6494
Epoch 35/50
1 acc: 0.6514
Epoch 36/50
1 acc: 0.6364
Epoch 37/50
1 acc: 0.6391
Epoch 38/50
1 acc: 0.6549
Epoch 39/50
1 acc: 0.6560
Epoch 40/50
1 acc: 0.6427
Epoch 41/50
1 acc: 0.6557
Epoch 42/50
1 acc: 0.6570
Epoch 43/50
```

```
1 acc: 0.6420
Epoch 44/50
1 acc: 0.6637
Epoch 45/50
l acc: 0.6510
Epoch 46/50
1 acc: 0.6524
Epoch 47/50
1 acc: 0.6616
Epoch 48/50
1 acc: 0.6473
Epoch 49/50
1 acc: 0.6509
Epoch 50/50
1 acc: 0.6565
```

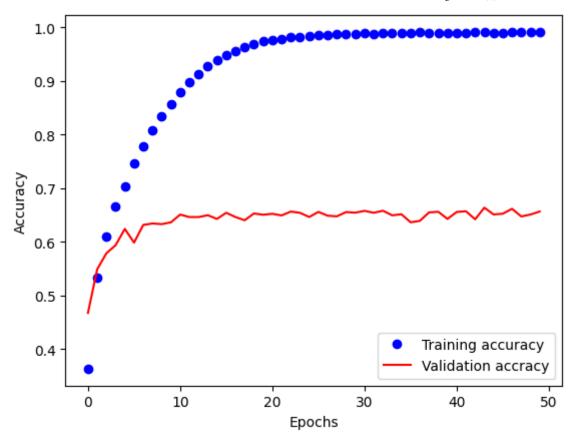
3. Plot the training and validation loss curve versus epochs. (5 points)

```
In [12]:
# plot the loss curve
import matplotlib.pyplot as plt
%matplotlib inline

acc = history.history['acc']
val_acc = history.history['val_acc']

epochs = range(len(acc))

plt.plot(epochs, acc, 'bo', label='Training accuracy')
plt.plot(epochs, val_acc, 'r', label='Validation accracy')
plt.xlabel('Epochs')
plt.ylabel('Accuracy')
plt.legend()
plt.show()
```



```
In [13]:
    val_acc = history.history['val_acc']
    train_acc=history.history['acc']
    avg_val_acc = sum(val_acc)/len(val_acc)
    avg_train_acc=sum(train_acc)/len(train_acc)
    print("Average validation accuracy:", avg_val_acc)
    print("Average train accuracy:", avg_train_acc)
```

4. Train (again) and evaluate the model (5 points)

• To this end, you have found the "best" hyper-parameters.

Average validation accuracy: 0.6396780049800873 Average train accuracy: 0.9177804964780808

- Now, fix the hyper-parameters and train the network on the entire training set (all the 50K training samples)
- Evaluate your model on the test set.

Train the model on the entire training set

Why? Previously, you used 40K samples for training; you wasted 10K samples for the sake of hyper-parameter tuning. Now you already know the hyper-parameters, so why not using all the 50K samples for training?

```
In [14]:
   #<Compile your model again (using the same hyper-parameters you tuned above)>
   learning rate = 1e-4
   model.compile(loss='categorical crossentropy',
       optimizer=optimizers.RMSprop(learning rate=learning rate),
       metrics=['acc'])
In [15]:
   #<Train your model on the entire training set (50K samples)>
   history = model.fit(x train,y train vec, epochs=25)
  Epoch 1/25
  Epoch 2/25
  Epoch 3/25
  Epoch 4/25
  Epoch 5/25
  Epoch 6/25
  Epoch 7/25
  Epoch 8/25
  Epoch 9/25
  Epoch 10/25
  Epoch 11/25
  Epoch 12/25
  Epoch 13/25
```

```
Epoch 14/25
Epoch 15/25
Epoch 16/25
Epoch 17/25
Epoch 18/25
Epoch 19/25
Epoch 20/25
Epoch 21/25
Epoch 22/25
Epoch 23/25
Epoch 24/25
Epoch 25/25
```

5. Evaluate the model on the test set (5 points)

Do NOT use the test set until now. Make sure that your model parameters and hyper-parameters are independent of the test set.

CNN model without Batch Normalization and without dropout layer Accuracy: 64%

6. Building model with new structure (25 points)

- In this section, you can build your model with adding new layers (e.g., BN layer or dropout layer, ...).
- If you want to regularize a Conv/Dense layer, you should place a Dropout layer before the Conv/Dense layer.
- You can try to compare their loss curve and testing accuracy and analyze your findings.
- You need to try at lease two different model structures.

Model 2: Added both Batch Normalization and DropOut layers

```
In [17]:
          # Added both Batch-Normalization and DropoutLayers
          model1=Sequential()
          model1.add(Conv2D(32,(3,3),padding='valid',input shape=(32,32,3)))
          model1.add(BatchNormalization())
          model1.add(Activation('relu'))
          model1.add(MaxPooling2D((2,2)))
          model1.add(Conv2D(64,(4,4),padding='valid'))
          model1.add(BatchNormalization())
          model1.add(Activation('relu'))
          model1.add(MaxPooling2D((2,2)))
          model1.add(Flatten())
          model1.add(Dropout(0.5))
          model1.add(Dense(256))
          model1.add(BatchNormalization())
          model1.add(Activation("relu"))
          model1.add(Dropout(0.5))
          model1.add(Dense(10))
          model1.add(Activation('softmax'))
          model1.summary()
```

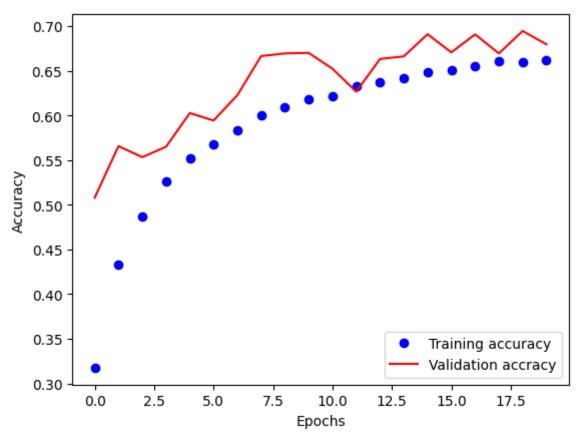
Model: "sequential 1"

```
activation_4 (Activation) (None, 30, 30, 32)
                                                        0
 max pooling2d 2 (MaxPooling (None, 15, 15, 32)
                                                        0
 2D)
 conv2d 3 (Conv2D)
                             (None, 12, 12, 64)
                                                        32832
batch_normalization_1 (Batc (None, 12, 12, 64)
                                                        256
 hNormalization)
 activation 5 (Activation) (None, 12, 12, 64)
                                                        0
 max pooling2d 3 (MaxPooling (None, 6, 6, 64)
                                                        0
 2D)
 flatten 1 (Flatten)
                                                        0
                             (None, 2304)
 dropout (Dropout)
                             (None, 2304)
                                                        0
 dense 2 (Dense)
                             (None, 256)
                                                        590080
 batch_normalization_2 (Batc (None, 256)
                                                        1024
 hNormalization)
 activation 6 (Activation) (None, 256)
                                                        0
                                                        0
 dropout 1 (Dropout)
                             (None, 256)
                                                        2570
 dense 3 (Dense)
                             (None, 10)
 activation 7 (Activation)
                             (None, 10)
                                                        0
Total params: 627,786
Trainable params: 627,082
Non-trainable params: 704
```

```
In [18]:
```

In [19]: history1 = model1.fit(x_tr,y_tr, epochs=20, validation_data=(x_val,y_val)) Epoch 1/20 al acc: 0.5080 Epoch 2/20 al acc: 0.5656 Epoch 3/20 al acc: 0.5533 Epoch 4/20 al acc: 0.5649 Epoch 5/20 al acc: 0.6026 Epoch 6/20 al acc: 0.5943 Epoch 7/20 al acc: 0.6227 Epoch 8/20 al acc: 0.6664 Epoch 9/20 al acc: 0.6694 Epoch 10/20 al acc: 0.6700 Epoch 11/20 al acc: 0.6522 Epoch 12/20 al acc: 0.6266 Epoch 13/20 al acc: 0.6632 Epoch 14/20 al acc: 0.6661

```
Epoch 15/20
    al acc: 0.6909
    Epoch 16/20
    al acc: 0.6706
    Epoch 17/20
    al acc: 0.6907
    Epoch 18/20
    al acc: 0.6694
    Epoch 19/20
    al acc: 0.6945
    Epoch 20/20
    al acc: 0.6796
In [32]:
    import matplotlib.pyplot as plt
    %matplotlib inline
    acc = history1.history['acc']
    val acc = history1.history['val acc']
    epochs = range(len(acc))
    plt.plot(epochs, acc, 'bo', label='Training accuracy')
    plt.plot(epochs, val acc, 'r', label='Validation accracy')
    plt.xlabel('Epochs')
    plt.ylabel('Accuracy')
    plt.legend()
    plt.show()
```



optimizer=optimizers.RMSprop(learning rate=learning rate),

model1.compile(loss='categorical crossentropy',

metrics=['acc'])

```
In [36]:
```

history2 = model1.fit(x_train,y_train_vec, epochs=25)

```
Epoch 1/25
Epoch 2/25
Epoch 3/25
Epoch 4/25
Epoch 5/25
Epoch 6/25
Epoch 7/25
Epoch 8/25
Epoch 9/25
Epoch 10/25
Epoch 11/25
Epoch 12/25
Epoch 13/25
Epoch 14/25
Epoch 15/25
Epoch 16/25
Epoch 17/25
Epoch 18/25
Epoch 19/25
Epoch 20/25
Epoch 21/25
```

```
Epoch 22/25
    1563/1563 [========
               Epoch 23/25
    Epoch 24/25
    Epoch 25/25
    In [37]:
    loss acc = model1.evaluate(x_test, y_test_vec)
    print('loss = ' + str(loss acc[0]))
    print('accuracy = ' + str(loss acc[1]))
    313/313 [========================== ] - 11s 36ms/step - loss: 0.7722 - acc: 0.7559
    loss = 0.7721715569496155
    accuracy = 0.7559000253677368
```

CNN model with Dropout Layers and Batch Normalization: Accuracy=75.5%**

Third Model with only Dropout Layers

```
In [38]:
          # Only dropout Layers
          model2=Sequential()
          model2.add(Conv2D(32,(3,3),padding='valid',input shape=(32,32,3)))
          #model2.add(BatchNormalization())
          model2.add(Activation('relu'))
          model2.add(MaxPooling2D((2,2)))
          model2.add(Conv2D(64,(4,4),padding='valid'))
          #model2.add(BatchNormalization())
          model2.add(Activation('relu'))
          model2.add(MaxPooling2D((2,2)))
          model2.add(Flatten())
          model2.add(Dropout(0.5))
          model2.add(Dense(256))
          #model2.add(BatchNormalization())
          model2.add(Activation("relu"))
          model2.add(Dropout(0.5))
          model2.add(Dense(10))
          model2.add(Activation('softmax'))
```

model2.summary()

Model: "sequential_3"

Layer (type)	Output Shape	Param #
conv2d_6 (Conv2D)		896
activation_12 (Activation)	(None, 30, 30, 32)	0
<pre>max_pooling2d_6 (MaxPooling 2D)</pre>	(None, 15, 15, 32)	0
conv2d_7 (Conv2D)	(None, 12, 12, 64)	32832
activation_13 (Activation)	(None, 12, 12, 64)	0
<pre>max_pooling2d_7 (MaxPooling 2D)</pre>	(None, 6, 6, 64)	0
flatten_3 (Flatten)	(None, 2304)	0
dropout_4 (Dropout)	(None, 2304)	0
dense_6 (Dense)	(None, 256)	590080
activation_14 (Activation)	(None, 256)	0
dropout_5 (Dropout)	(None, 256)	0
dense_7 (Dense)	(None, 10)	2570
activation_15 (Activation)	(None, 10)	0
Total params: 626,378 Trainable params: 626.378		:=======

Trainable params: 626,378 Non-trainable params: 0

In [39]:

learning_rate = 1e-4

model2.compile(loss='categorical_crossentropy',

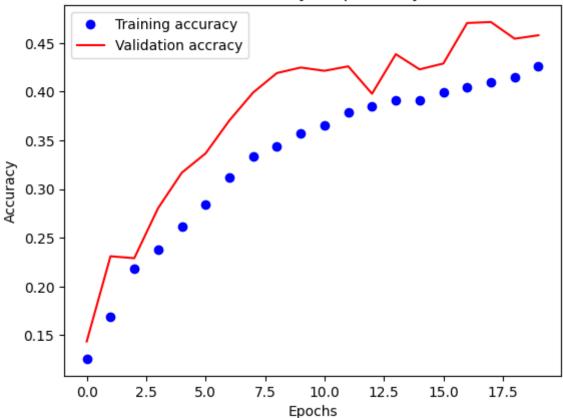
```
optimizer=optimizers.RMSprop(learning_rate=learning_rate),
metrics=['acc'])
```

```
In [40]:
  history2 = model2.fit(x tr,y tr, epochs=20, validation data=(x val,y val))
  Epoch 1/20
  1 acc: 0.1436
  Epoch 2/20
  1 acc: 0.2311
  Epoch 3/20
  1 acc: 0.2291
  Epoch 4/20
  1 acc: 0.2804
  Epoch 5/20
  1 acc: 0.3169
  Epoch 6/20
  1 acc: 0.3367
  Epoch 7/20
  1 acc: 0.3705
  Epoch 8/20
  1 acc: 0.3992
  Epoch 9/20
  1 acc: 0.4192
  Epoch 10/20
  1 acc: 0.4249
  Epoch 11/20
  1 acc: 0.4215
  Epoch 12/20
  1 acc: 0.4261
  Epoch 13/20
```

1 acc: 0.3980

```
Epoch 14/20
   1 acc: 0.4386
   Epoch 15/20
    1 acc: 0.4230
    Epoch 16/20
   1 acc: 0.4290
   Epoch 17/20
   1 acc: 0.4706
   Epoch 18/20
   l acc: 0.4716
   Epoch 19/20
    1 acc: 0.4545
   Epoch 20/20
   1 acc: 0.4580
In [41]:
    import matplotlib.pyplot as plt
    %matplotlib inline
    acc = history2.history['acc']
    val acc = history2.history['val acc']
    epochs = range(len(acc))
    plt.plot(epochs, acc, 'bo', label='Training accuracy')
    plt.plot(epochs, val acc, 'r', label='Validation accracy')
    plt.xlabel('Epochs')
    plt.ylabel('Accuracy')
    plt.title(" Model with only Drop-out Layers ")
    plt.legend()
    plt.show()
```

Model with only Drop-out Layers



```
In [42]:
    val_acc = history2.history['val_acc']
    train_acc=history2.history['acc']
    avg_val_acc = sum(val_acc)/len(val_acc)
    avg_train_acc=sum(train_acc)/len(train_acc)
    print("Average validation accuracy:", avg_val_acc)
    print("Average train accuracy:", avg_train_acc)
```

Average validation accuracy: 0.3771249994635582 Average train accuracy: 0.3305499993264675

```
In [43]:
#<Compile your model again (using the same hyper-parameters you tuned above)>
learning_rate = 1e-4
model2.compile(loss='categorical_crossentropy',
```

```
In [44]:
```

```
history2 = model2.fit(x_train,y_train_vec, epochs=25)
```

```
Epoch 1/25
Epoch 2/25
Epoch 3/25
Epoch 4/25
Epoch 5/25
Epoch 6/25
Epoch 7/25
Epoch 8/25
Epoch 9/25
Epoch 10/25
Epoch 11/25
Epoch 12/25
Epoch 13/25
Epoch 14/25
Epoch 15/25
Epoch 16/25
Epoch 17/25
Epoch 18/25
Epoch 19/25
Epoch 20/25
```

```
Epoch 21/25
  Epoch 22/25
  Epoch 23/25
  Epoch 24/25
  Epoch 25/25
  In [45]:
  loss__acc = model2.evaluate(x_test, y_test_vec)
  print('loss = ' + str(loss acc[0]))
  print('accuracy = ' + str(loss acc[1]))
  loss = 1.3696386814117432
  accuracy = 0.5295000076293945
```

CNN model with only Dropout Layers: Accuracy= 52.9%

Conclusion:

The testing accuracy using the model with complete data

- Basic CNN model(No dropout layers, No BatchNormalization): 0.64
- CNN Model with droput layers and batchNormalization is: 0.755
- CNN model with only dropout layers: 0.529

The accuracy of a model tested on complete data varies with the type of architecture used. In this study, we evaluated the performance of three CNN models with varying architectures: a basic CNN model without dropout layers or BatchNormalization achieved an accuracy of 0.64, while a CNN model with dropout layers and BatchNormalization achieved an accuracy of 0.755. In contrast, a CNN model with only dropout layers achieved an accuracy of 0.529, indicating poor performance compared to the other two models.

It is evident from our results that the inclusion of BatchNormalization and dropout layers had a positive impact on the accuracy of the CNN model. Specifically, **the model that included BatchNormalization** had the highest accuracy, thereby demonstrating the effectiveness of BatchNormalization in enhancing model performance.

In []: