09/07/2021

1. MoveIt! Setup Assistant:

roscd open\_manipulator\_support\_description/urdf

ls open\_manipulator\_support.urdf.xacro

ws#1

cd ~/catkin\_ws/src

roslaunch moveit\_setup\_assistant setup\_assistant.launch

cd ~/catkin\_ws

source devel/setup.bash;rospack profile

roslaunch openmanipulator\_ep2\_movit\_config demo.launch rviz\_tutorial:=true

2. Rviz + Gazebo

roscd openmanipulator\_morpheus\_chair\_tutorials

#mkdir launch

#mkdir worlds

#mkdir config

touch launch/start\_simulation.launch

touch worlds/empty\_kinect.world

touch launch/trajectory\_controller.launch

touch config/trajectory\_controller.yaml

roslaunch openmanipulator\_morpheus\_chair\_tutorials start\_simulation.launch

1/1