

## Contributions

- We introduce a *simplified* variant of the MAC model [HM18], which achieves comparable accuracy while training *faster*.
- We evaluate the MAC model and the simplified variant on CLEVR & CoGenT, and show that, *transfer learning with fine-tuning* results in a 15 point increase in accuracy, matching the state of the art.
- We also demonstrate that *improper* fine-tuning can reduce a model's accuracy.

## The MAC Model [HM18]

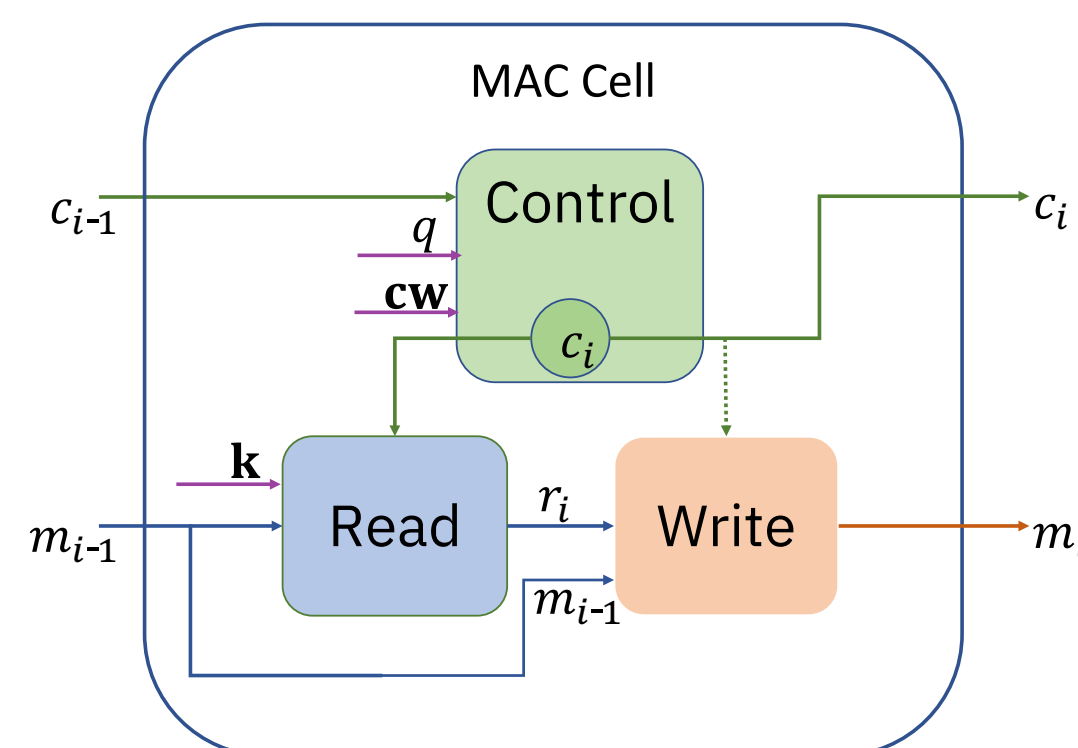


Figure 1: The MAC cell, based on [HM18].

- MAC network: a recurrent model performing sequential reasoning. At each step, it analyzes the question and shifts the attention over the image.
- Recurrent MAC cell: consists of a control unit, a read unit & a write unit. The control unit updates the control state  $c_i$  & drives the attention over the question words.
- The read unit, guided by  $c_i$  extracts information from the image. The write unit uses this information to update the memory state  $m_i$ .

## Simplified MAC Model (S-MAC)

The simplifications are based on two heuristics:

- Taking the MAC cell equations as a whole, consecutive linear layers (with no activation in-between) can be combined as one linear layer.
- We assume that dimension-preserving linear layers are invertible so as to avoid information loss. **VM: To reformulate?**

This allows, with a careful reorganization, to apply a single linear layer to the *knowledge base* (feature map extracted from the image) prior to all the reasoning steps and work with this projection throughout the reasoning steps.

### MAC

### S-MAC

**Control unit:** The question  $q$  is first made *position-aware* in each reasoning step using an  $i$ -dependent projection:  $q_i = U_i^{[d \times 2d]} q + b_i^{[d]}$ .

$$cq_i = W_{cq}^{[d \times 2d]} [c_{i-1}, q_i] + b_{cq}^{[d]} \quad (c1)$$

$$ca_{is} = W_{ca}^{[1 \times d]} (cq_i \odot \mathbf{cw}_s) + b_{ca}^{[1]} \quad (c2.1)$$

$$cv_{is} = \text{softmax}(ca_{is}) \quad (c2.2)$$

$$\mathbf{c}_i = \sum_s cv_{is} \mathbf{cw}_s \quad (c2.3)$$

$$cq_i = W_{cq}^{[d \times d]} c_{i-1} + q_i \quad (c1)$$

$$ca_{is} = W_{ca}^{[1 \times d]} (cq_i \odot \mathbf{cw}_s) \quad (c2.1)$$

$$cv_{is} = \text{softmax}(ca_{is}) \quad (c2.2)$$

$$\mathbf{c}_i = \sum_s cv_{is} \mathbf{cw}_s \quad (c2.3)$$

### Read and write units:

$$I_{ihw} = (W_m^{[d \times d]} \mathbf{m}_{i-1} + b_m^{[d]}) \odot (W_k^{[d \times d]} \mathbf{k}_{hw} + b_k^{[d]}) \quad (r1)$$

$$I'_{ihw} = W_{I'}^{[d \times 2d]} [I_{ihw}, \mathbf{k}_{hw}] + b_{I'}^{[d]} \quad (r2)$$

$$ra_{ihw} = W_{ra}^{[1 \times d]} (\mathbf{c}_i \odot I'_{ihw}) + b_{ra}^{[1]} \quad (r3.1)$$

$$rv_{ihw} = \text{softmax}(ra_{ihw}) \quad (r3.2)$$

$$\mathbf{r}_i = \sum_s rv_{ihw} \mathbf{k}_{hw} \quad (r3.3)$$

$$\mathbf{m}_i = W_{rm}^{[d \times 2d]} [\mathbf{r}_i, \mathbf{m}_{i-1}] + b_{rm}^{[d]} \quad (w1)$$

$$I_{ihw} = \mathbf{m}_{i-1} \odot \mathbf{k}_{hw} \quad (r1)$$

$$I'_{ihw} = W_{I'}^{[d \times d]} I_{ihw} + b_{I'}^{[d]} + \mathbf{k}_{hw} \quad (r2)$$

$$ra_{ihw} = W_{ra}^{[1 \times d]} (\mathbf{c}_i \odot I'_{ihw}) \quad (r3.1)$$

$$rv_{ihw} = \text{softmax}(ra_{ihw}) \quad (r3.2)$$

$$\mathbf{r}_i = \sum_s rv_{ihw} \mathbf{k}_{hw} \quad (r3.3)$$

$$\mathbf{m}_i = W_{rm}^{[d \times d]} \mathbf{r}_i + b_{rm}^{[d]} \quad (w1)$$

Model	Read Unit	Write Unit	Control Unit
MAC	787,969	524,800	525,313
S-MAC	263,168	262,656	263,168
Reduction by [%]	67%	50%	50%

Table 1: Comparing the number of position-independent parameters between MAC & S-MAC cells.

## The CLEVR & CoGenT datasets

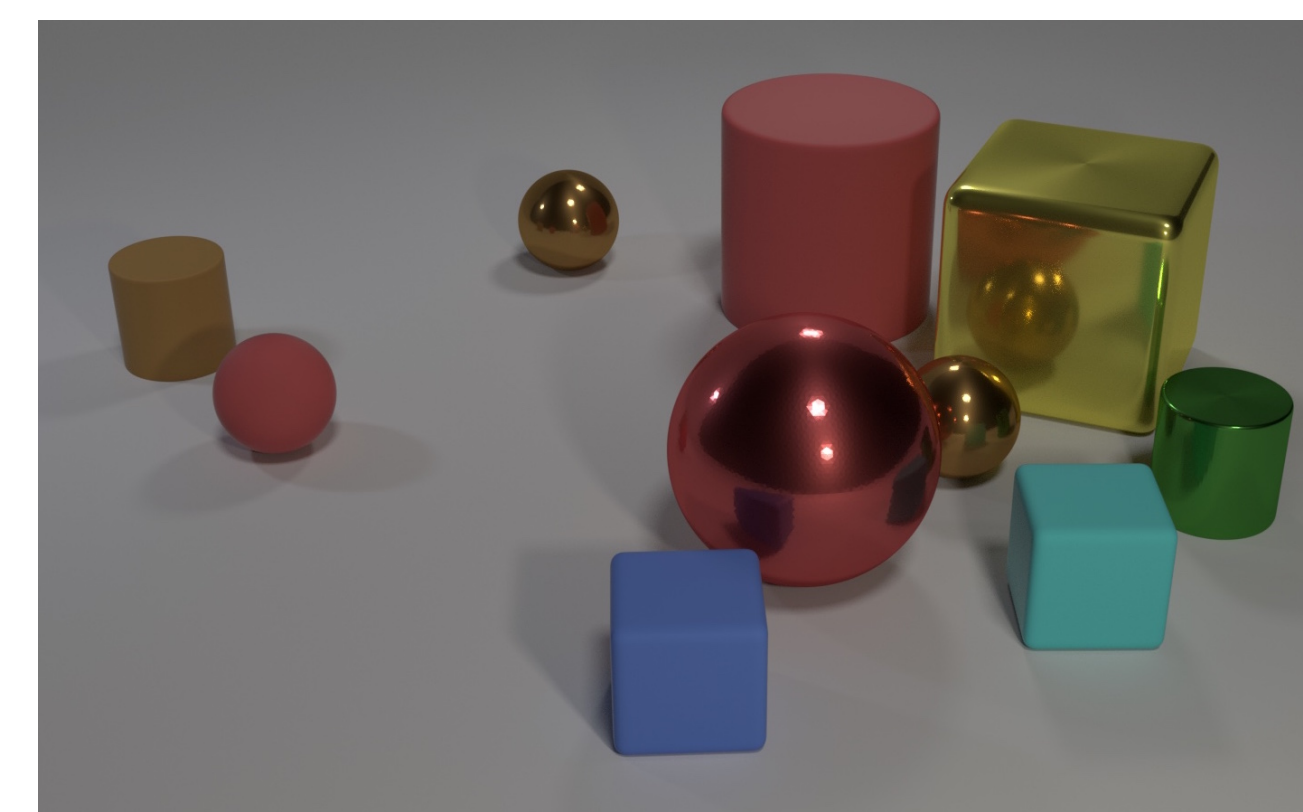


Figure 2: Q: How many objects are either small cylinders or red things? – A: 5.

- The authors [JHvdM<sup>+</sup>17] also introduced CLEVR-CoGenT, to evaluate how well a model can learn relations and compositional concepts.
- Similar to CLEVR, but with two conditions, as follows:

Dataset	Cubes	Cylinders	Spheres
CLEVR	any color	any color	any color
CLEVR CoGenT-A	gray / blue / brown / yellow	red / green / purple / cyan	any color
CLEVR CoGenT-B	red / green / purple / cyan	gray / blue / brown / yellow	any color

Table 2: Colors/shapes combinations present in CLEVR, CoGenT-A and CoGenT-B datasets.

## Experiments & Results

Model	Training			Fine-tuning		Test	
	Dataset	Time [h:m]	Acc [%]	Dataset	Acc [%]	Dataset	Acc [%]
MAC	CLEVR	30:52	96.70	–	–	CLEVR	96.17
	CLEVR	28:30	95.82	–	–	CLEVR	95.29
	CoGenT-A	28:33	96.09	–	–	CoGenT-A	95.91
	CLEVR	28:30	95.82	–	–	CoGenT-A	95.47
						CoGenT-B	95.58
S-MAC				–	–	CogenT-B	78.71
	CoGenT-A	28:33	96.09	CoGenT-B	96.85	CoGenT-A	91.24
						CoGenT-B	94.55
	CLEVR	28:30	95.82	CoGenT-B	97.67	CoGenT-A	92.11
						CoGenT-B	92.95

Table 3: CLEVR & CoGenT accuracies for the MAC & S-MAC models.

- Our experiments on *zero-shot learning* (CoGenT-A  $\rightarrow$  CoGenT-B) show that both models have poor performance, in line with the other models in the literature.
- With fine-tuning, both MAC models match state-of-the-art accuracy (a 15pts increase).
- **S-MAC presents a 10% speed-up in training time and comparable accuracy.**
- Finetuning CLEVR-trained models on CoGenT-A or -B hurts their generalization capabilities.

$\rightarrow$  *Zero-shot learning* remains an interesting problem to solve.

## Compositional generalization of the MAC model

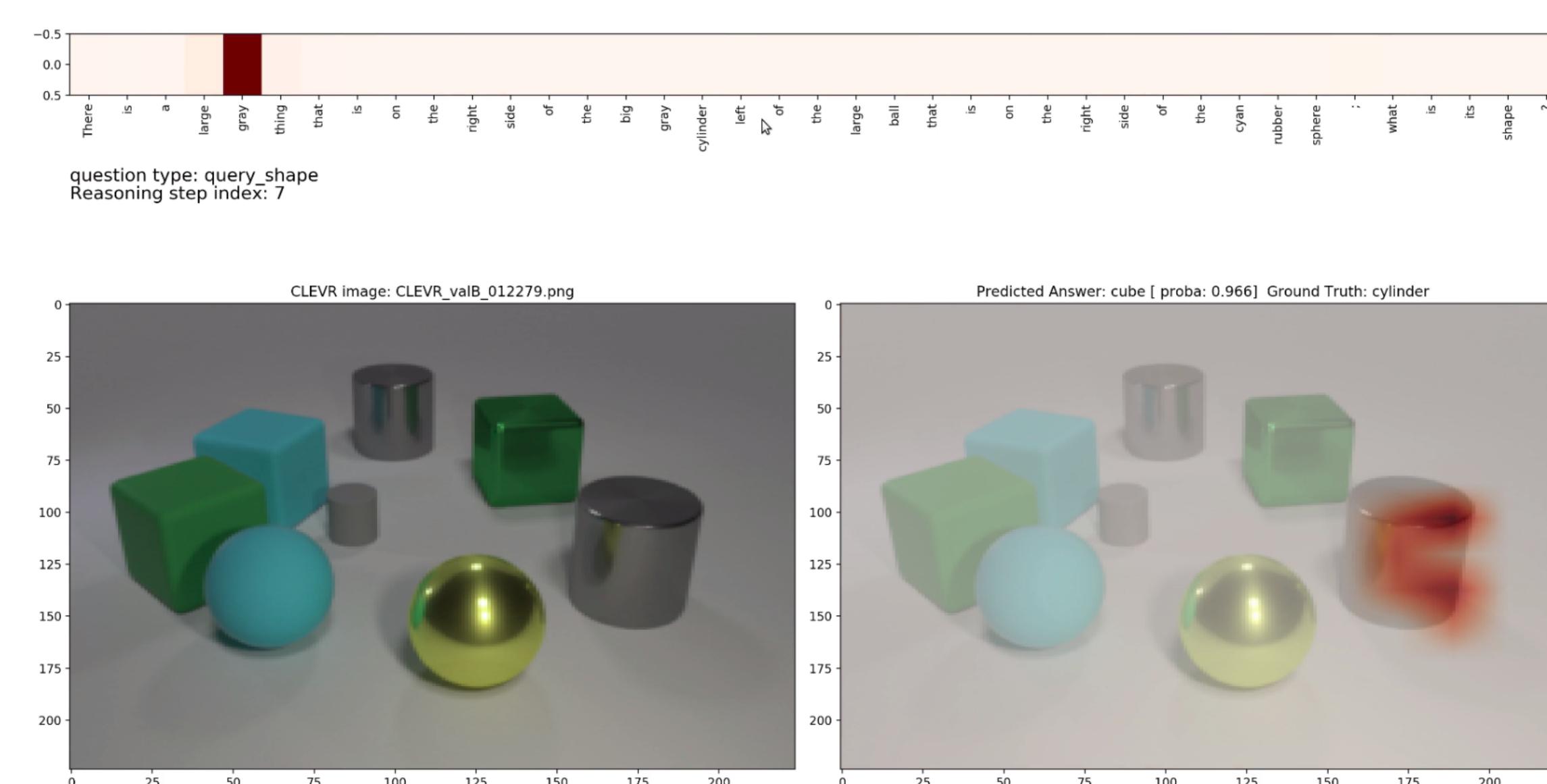


Figure 3: There is a large gray thing that is on the right side of the big gray cylinder left of the large ball that is on the right side if the cyan rubber sphere; what is its shape?

- Asked about the shape of the leftmost **gray cylinder**, the model correctly finds it, (cf. *visual attention map*), and refers to it using its color (*attention over the question words*).
- Yet, predicts the shape as **cube**, as it never saw **gray cylinders** during training, but saw **gray cubes**.

$\rightarrow$  This indicates that MAC does not separate shape from color, but has a better understanding of colors (as found the object by its color).

## Links



How to reproduce the experiments.



Paper on arXiv.



CLEVR Dataset.

## References

- [HM18] Drew A. Hudson and Christopher D. Manning. Compositional attention networks for machine reasoning. *International Conference on Learning Representations*, 2018.
- [JHvdM<sup>+</sup>17] Justin Johnson, Bharath Hariharan, Laurens van der Maaten, Li Fei-Fei, C Lawrence Zitnick, and Ross Girshick. Clevr: A diagnostic dataset for compositional language and elementary visual reasoning. In *Computer Vision and Pattern Recognition (CVPR), 2017 IEEE Conference on*, pages 1988–1997. IEEE, 2017.