

On Transfer Learning using a MAC model variant

T.S. Jayram

Vincent Albouy

Tomasz Kornuta

Almaden Research Center

Vincent Marois

Younes Bouhadjar Ahmet S. Ozcan {vmarois, jayram, tkornut, byounes, asozcan}@us.ibm.com, {vincent.albouy}@ibm.com

Contributions

- We introduce a *simplified* variant of the MAC model [HM18], which achieves comparable accuracy while training *faster*.
- We evaluate the MAC model and the simplified variant on CLEVR & CoGenT, and show that, transfer learning with fine-tuning results in a 15 point increase in accuracy, matching the state of the art.
- We also demonstrate that *improper* fine-tuning can reduce a model's accuracy.

The MAC Model [HM18]

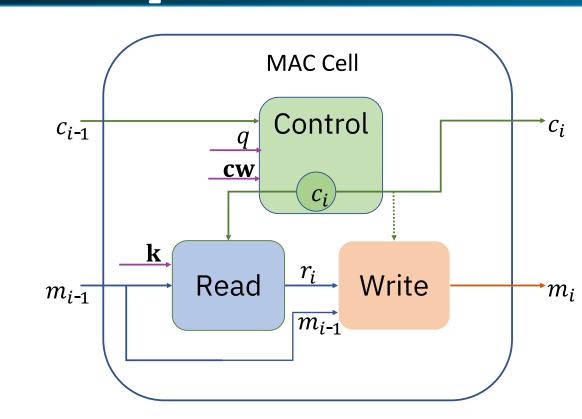


Figure 1: The MAC cell, based on [HM18].

- MAC network: a recurrent model performing sequential reasoning. At each step, it analyzes the question and shifts the attention over the image.
- Recurrent MAC cell: consists of a control unit, a read unit & a write unit. The control unit updates the control state c_i & drives the attention over the question words.
- \bullet The read unit, guided by c_i extracts information from the image. The write unit uses this information to update the memory state m_i .

Simplified MAC Model (S-MAC)

The simplifications are based on two heuristics:

- Taking the MAC cell equations as a whole, consecutive linear layers (with no non-linear activation in-between) can be combined as one linear layer.
- We assume that dimension-preserving linear layers are invertible so as to avoid information loss.

This allows, with a careful reorganization, to apply a single linear layer to the knowledge base (feature map extracted from the image) prior to all the reasoning steps and work with this projection throughout the reasoning steps.

MAC

S-MAC

Control unit: The question q is first made position-aware in each reasoning step using an i-dependent projection: $q_i = U_i^{[d \times 2d]} q + b_i^{[d]}$.

$$cq_{i} = W_{cq}^{[d \times 2d]}[c_{i-1}, q_{i}] + b_{cq}^{[d]}$$

$$ca_{is} = W_{ca}^{[1 \times d]}(cq_{i} \odot \mathbf{cw}_{s}) + b_{ca}^{[1]}$$

$$cv_{is} = \operatorname{softmax}(ca_{is})$$

$$(c1)$$

$$cv_{is} = \operatorname{softmax}(ca_{is})$$

$$(c2.1)$$

$$cq_i = W_{cq}^{[d \times d]} c_{i-1} + q_i \qquad (c1)$$

$$ca_{is} = W_{ca}^{[1 \times d]} (cq_i \odot \mathbf{cw}_s) \qquad (c2.1)$$

$$\operatorname{softmax}(ca_{is})$$
 (c2.2)

$$cu_{is} = vv_{ca} \quad (cq_i \odot cw_s) \qquad (c2.1)$$

$$cv_{is} = \operatorname{softmax}(ca_{is}) \qquad (c2.2)$$

$$\mathbf{c}_i = \sum_s cv_{is} \, \mathbf{cw}_s \tag{c2.3}$$

$$\mathbf{c}_i = \sum cv_{is} \, \mathbf{cw}_s \tag{c2.3}$$

Read and write units:

$$I_{ihw} = (W_m^{[d \times d]} \mathbf{m}_{i-1} + b_m^{[d]})$$

$$\odot (W_k^{[d \times d]} \mathbf{k}_{hw} + b_k^{[d]}) \qquad (r1)$$

$$I'_{ihw} = W_{I'}^{[d \times 2d]}[I_{ihw}, \mathbf{k}_{hw}] + b_{I'}^{[d]}$$
 (r2)

$$ra_{ihw} = W_{ra}^{[1 \times d]}(\mathbf{c}_i \odot I'_{ihw}) + b_{ra}^{[1]}$$
 (r3.1)

$$rv_{ihw} = \operatorname{softmax}(ra_{ihw})$$
 (r3.2)
 $\mathbf{r}_i = \sum rv_{ihw} \mathbf{k}_{hw}$ (r3.3)

$$\mathbf{m}_i = W_{rm}^{[d imes 2d]}[\mathbf{r}_i, \mathbf{m}_{i-1}] + b_{rm}^{[d]} \qquad ext{(w1)}$$

$$I_{ihw} = \mathbf{m}_{i-1} \odot \mathbf{k}_{hw} \tag{r1}$$

$$I'_{ihw} = W_{I'}^{[d \times d]} I_{ihw} + b_{I'}^{[d]} + \mathbf{k}_{hw} \qquad (r2)$$

$$ra_{ihw} = W_{ra}^{[1 \times d]}(\mathbf{c}_i \odot I'_{ihw})$$
 (r3.1)
 $rv_{ihw} = \operatorname{softmax}(ra_{ihw})$ (r3.2)

$$\mathbf{r}_i = \sum r v_{ihw} \, \mathbf{k}_{hw} \tag{r3.3}$$

$$\mathbf{m}_i = W_{rm}^{[d \times d]} \mathbf{r}_i + b_{rm}^{[d]} \tag{w1}$$

Model	Read Unit	Write Unit	Control Unit
MAC S-MAC	787,969 263,168	524,800 262,656	525,313 263,168
Reduction by [%]	67%	50%	50%

Table 1: Comparing the number of position-independent parameters between MAC & S-MAC cells.

Links



How to reproduce the experiments.





CLEVR Dataset.

The CLEVR & CoGenT datasets

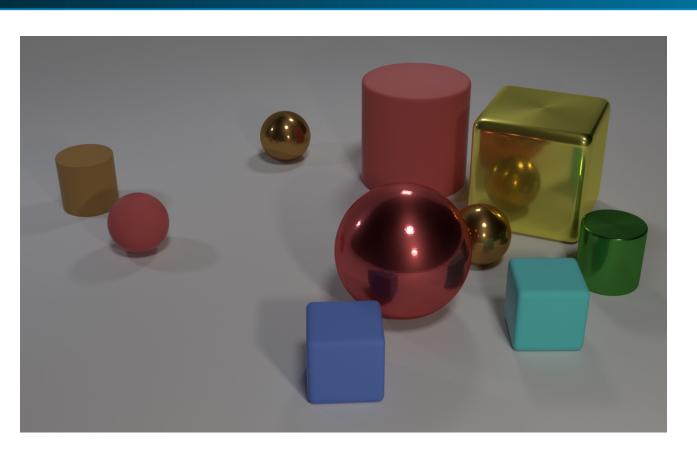


Figure 2: Q: How many objects are either small cylinders or red things? – **A**: 5.

- The authors [JHvdM⁺17] also introduced CLEVR-CoGenT, to evaluate how well a model can learn relations and compositional concepts.
- Similar to CLEVR, but with two conditions, as follows:

Dataset	Cubes	Cylinders	Spheres
	, , ,	any color red / green / purple / cyan gray / blue / brown / yellow	any color any color any color

Table 2: Colors/shapes combinations present in CLEVR, CoGenT-A and CoGenT-B datasets.

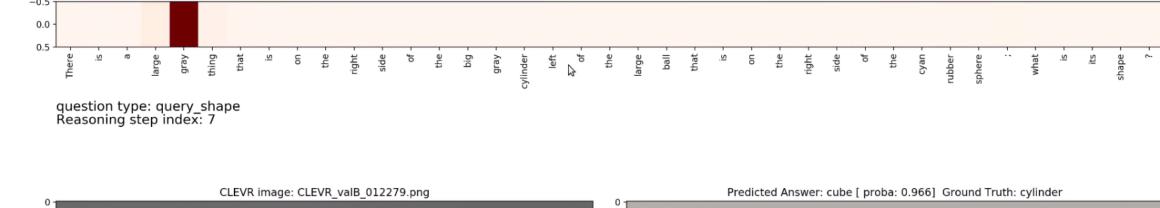
Experiments & Results

Model .	Training		Fine-tuning		Test		
	Dataset	Time [h:m]	Acc [%]	Dataset	Acc [%]	Dataset	Acc [%]
MAC	CLEVR	30:52	96.70	_	_	CLEVR	96.17
S-MAC	CLEVR	28:30	95.82		_	CLEVR	95.29
	CoGenT-A	28:33	96.09		_	CoGenT-A	95.91
	CLEVR	28:30	95.82			CoGenT-A	95.47
						CoGenT-B	95.58
	CoGenT-A	28:33	96.09		_	CogenT-B	78.71
				CoGenT-B	96.85	CoGenT-A	91.24
						CoGenT-B	94.55
	CLEVR	28:30	95.82	CoGenT-B	97.67	CoGenT-A	92.11
						CoGenT-B	92.95

Table 3: CLEVR & CoGenT accuracies for the MAC & S-MAC models.

- ullet Our experiments on zero-shot learning (CoGenT-A o CoGenT-B) show that both models have poor performance, in line with the other models in the literature.
- With fine-tuning, both MAC models match state-of-the-art accuracy (a 15pts increase).
- S-MAC presents a 10% speed-up in training time and comparable accuracy.
- Finetuning CLEVR-trained models on CoGenT-A or -B hurts their generalization capabilities.
- \rightarrow Zero-shot learning remains an interesting problem to solve.

Compositional generalization of the MAC model



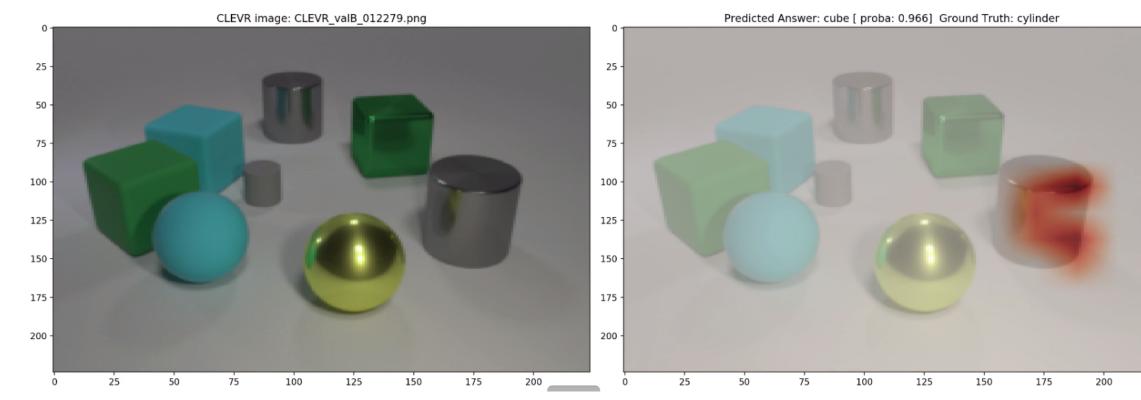


Figure 3: There is a large gray thing that is on the right side of the big gray cylinder left of the large ball that is on the right side if the cyan rubber sphere; what is its shape?

- Asked about the shape of the leftmost gray cylinder, the model correctly finds it, (cf. visual attention map), and refers to it using its color (attention over the question words).
- Yet, predicts the shape as cube, as it never saw gray cylinders during training, but saw gray cubes.
- ightarrow This indicates that MAC does not separate shape from color, but has a better understanding of colors (as found the object by its color).

References

[HM18] Drew A. Hudson and Christopher D. Manning. Compositional attention networks for machine reasoning. International Conference on Learning Representations, 2018.

Justin Johnson, Bharath Hariharan, Laurens van der Maaten, Li Fei-Fei, C Lawrence Zitnick, and Ross Girshick. Clevr: A diagnostic dataset for compositional language and elementary visual reasoning. In Computer Vision and Pattern Recognition (CVPR), 2017 IEEE Conference on, pages 1988–1997. IEEE, 2017.