

## Hidden Markov Models - Practical Session 8

### Exercise 1: Model checking, part II

We will continue working with the 3-state HMM fitted in the Practical Session 7 with `moveHMM`. Use the following code or your own code from last week to load the data and get the 3-state HMM results.

```
#install.packages("moveHMM")
library(moveHMM)
rawdata <- read.table("elephant_rawdata.txt", header = T)
data <- prepData(rawdata, type = "UTM")
N = 3
stepMean <- seq(10, 300, length = N)
stepSD <- seq(10, 100, length = N)
stepPar <- c(stepMean, stepSD)
mod3 <- fithMM(data, nbStates = N, stepPar0 = stepPar, angleDist = "none", stationary = T)
```

- a) Extract the relevant parameters from the `mod3` object and plot a histogram of the empirical distribution of step lengths together with the estimated marginal distribution. You can compare your plot to the same one generated by `moveHMM::plot(mod3)`.
- b) Perform simulation-based model checks.  
*Hints:* Copy your HMM simulation code from Practical Session 3 and adapt it to simulate from a gamma distribution with parameters shape and scale.  
To compare the elephant data to the simulated data you could look at time series plots, autocorrelation, summary statistics, ...

### Exercise 2: State decoding

- a) What is the difference between local and global decoding? What are the main advantages of each state decoding strategy?
- b) Use the function `plotStates()` on your fitted model to plot the decoded state sequence and the state probabilities.
- c) Compute the state probabilities with `stateProbs()`.
- d) Compute the most likely state sequence by running the function `viterbi()` on a fitted model.

- e) Plot the time series of step lengths and use colour coding to indicate the decoded state sequence.
- f) Create a sequence of the most likely states based on local decoding. Check for which observations the results from global decoding and local decoding differ.

## **Bonus exercise**

Rewrite the Viterbi function given on lecture slide 203 for the general N-state case and calculate the most likely state sequence given this function. Create a plot similar to the first one on lecture slide 207.