

A First Course in
LINEAR ALGEBRA

Lecture Notes
by Karen Seyffarth

Spectral Theory: Diagonalization

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A First Course in Linear Algebra

Lecture Notes

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Definition (Similar Matrices)

Let A and B be $n \times n$ matrices. A is similar to B , written $A \sim B$, if there exists an invertible matrix P such that $B = P^{-1}AP$.

Lemma

Similarity is an equivalence relation, i.e., for $n \times n$ matrices A , B and C

- ① $A \sim A$ (reflexive);
- ② if $A \sim B$, then $B \sim A$ (symmetric);
- ③ if $A \sim B$ and $B \sim C$, then $A \sim C$ (transitive).

Proof that similarity is transitive.

Since $A \sim B$ and $B \sim C$, there exist invertible $n \times n$ matrices P and Q such that

$$B = P^{-1}AP \text{ and } C = Q^{-1}BQ.$$

Thus

$$C = Q^{-1}BQ = Q^{-1}(P^{-1}AP)Q = (Q^{-1}P^{-1})A(PQ) = (PQ)^{-1}A(PQ),$$

where PQ is invertible, and hence $A \sim C$. □

Definition

If $A = [a_{ij}]$ is an $n \times n$ matrix, then the **trace of A** is

$$\text{tr}(A) = \sum_{i=1}^n a_{ii}.$$

Lemma (Properties of trace)

For $n \times n$ matrices A and B , and any $k \in \mathbb{R}$,

- ❶ $\text{tr}(A + B) = \text{tr}(A) + \text{tr}(B)$;
- ❷ $\text{tr}(kA) = k \cdot \text{tr}(A)$;
- ❸ $\text{tr}(AB) = \text{tr}(BA)$.

The proofs of these are exercises in manipulating sums.

Reminder (Characteristic Polynomial)

For any $n \times n$ matrix A , the **characteristic polynomial** of A is

$$c_A(x) = \det(xI - A),$$

and is a polynomial of degree n .

Theorem (Properties of Similar Matrices)

If A and B are $n \times n$ matrices and $A \sim B$, then

- 1 $\det(A) = \det(B)$;
- 2 $\text{rank}(A) = \text{rank}(B)$;
- 3 $\text{tr}(A) = \text{tr}(B)$;
- 4 $c_A(x) = c_B(x)$;
- 5 A and B have the same eigenvalues.

Proof.

Since $A \sim B$, there exists an $n \times n$ invertible matrix P so that $B = P^{-1}AP$.

① $\det(B) = \det(P^{-1}AP) = \det(P^{-1}) \cdot \det(A) \cdot \det(P)$.

Since P is invertible, $\det(P^{-1}) = \frac{1}{\det(P)}$, so

$$\det(B) = \frac{1}{\det(P)} \cdot \det(A) \cdot \det(P) = \frac{1}{\det(P)} \cdot \det(P) \cdot \det(A) = \det(A).$$

Therefore, $\det(B) = \det(A)$.

② $\text{rank}(B) = \text{rank}(P^{-1}AP)$.

Since P is invertible, $\text{rank}(P^{-1}AP) = \text{rank}(P^{-1}A)$, and since P^{-1} is invertible, $\text{rank}(P^{-1}A) = \text{rank}(A)$. Therefore, $\text{rank}(B) = \text{rank}(A)$.

③ $\text{tr}(B) = \text{tr}[(P^{-1}A)P] = \text{tr}[P(P^{-1}A)] = \text{tr}[(PP^{-1})A] = \text{tr}(IA) = \text{tr}(A)$.

Proof (continued).

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$$\begin{aligned}c_B(x) = \det(xI - B) &= \det(xI - P^{-1}AP) \\&= \det(xP^{-1}P - P^{-1}AP) \\&= \det(P^{-1}xP - P^{-1}AP) \\&= \det[P^{-1}(xI - A)P] \\&= \det(P^{-1}) \cdot \det(xI - A) \cdot \det(P) \\&= \det(P^{-1}) \cdot \det(P) \cdot \det(xI - A)\end{aligned}$$

Since P is invertible, $\det(P^{-1}) = \frac{1}{\det(P)}$, so

$$c_B(x) = \frac{1}{\det(P)} \cdot \det(P) \cdot \det(xI - A) = \det(xI - A) = c_A(x).$$

- 5 Since the eigenvalues of a matrix are the roots of the characteristic polynomial, $c_B(x) = c_A(x)$ implies that A and B have the same eigenvalues.



Diagonal Matrices

Definition

An $n \times n$ matrix A is **diagonal** if it is both upper triangular and lower triangular. Equivalently, all entries except those on the main diagonal are zeros.

Notation

An $n \times n$ diagonal matrix

$$D = \begin{bmatrix} a_1 & 0 & 0 & \cdots & 0 & 0 \\ 0 & a_2 & 0 & \cdots & 0 & 0 \\ 0 & 0 & a_3 & \cdots & 0 & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \cdots & a_{n-1} & 0 \\ 0 & 0 & 0 & \cdots & 0 & a_n \end{bmatrix}$$

is written $D = \text{diag}(a_1, a_2, a_3, \dots, a_{n-1}, a_n)$.

Diagonalizability

Definition

An $n \times n$ matrix A is said to be **diagonalizable** if there exists an invertible $n \times n$ matrix P such that $A = PDP^{-1}$.

Definition

An $n \times n$ matrix A is **diagonalizable** if $A \sim D$ for some **diagonal matrix** D .

Diagonalizing a Matrix

Let A be an $n \times n$ matrix. The process of finding an **invertible** matrix P and a **diagonal** matrix D so that $A = PDP^{-1}$ is referred to as **diagonalizing** the matrix A , and P is called the **diagonalizing** matrix for A .

The key to diagonalizing a matrix (finding the matrices P and D) lies in the eigenvectors and eigenvalues of the matrix A .

Reminder

Let A be an $n \times n$ matrix and λ a real number. If λ is an eigenvalue of A , then

$$AX = \lambda X$$

for some **nonzero** vector X in \mathbb{R}^n . Such a vector X is called a **λ -eigenvector of A** or an eigenvector of A corresponding to λ .

Theorem

Let A be an $n \times n$ matrix.

- 1 A is diagonalizable if and only if it has eigenvectors X_1, X_2, \dots, X_n so that $P = \begin{bmatrix} X_1 & X_2 & \cdots & X_n \end{bmatrix}$ is invertible.
- 2 If P is invertible, then

$$P^{-1}AP = \text{diag}(\lambda_1, \lambda_2, \dots, \lambda_n)$$

where λ_i is the eigenvalue of A corresponding to the eigenvector X_i , i.e., $AX_i = \lambda_i X_i$.

Example

Diagonalize, if possible, the matrix $A = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & -3 \end{bmatrix}$.

Solution

$$c_A(x) = \det(xI - A) = \begin{vmatrix} x-1 & 0 & -1 \\ 0 & x-1 & 0 \\ 0 & 0 & x+3 \end{vmatrix} = (x-1)^2(x+3).$$

Therefore, A has eigenvalues $\lambda_1 = 1$ of multiplicity two and $\lambda_2 = -3$ of multiplicity one.

Eigenvectors for $\lambda_1 = 1$: solve $(I - A)X = 0$.

$$\left[\begin{array}{ccc|c} 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 4 & 0 \end{array} \right] \rightarrow \left[\begin{array}{ccc|c} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right] \text{ so } X = \begin{bmatrix} s \\ t \\ 0 \end{bmatrix}, s, t \in \mathbb{R}.$$

Solution (continued)

Therefore, basic eigenvectors corresponding to $\lambda_1 = 1$ are $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ and $\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$.

Eigenvectors for $\lambda_2 = -3$: solve $(-3I - A)X = 0$.

$$\left[\begin{array}{ccc|c} -4 & 0 & -1 & 0 \\ 0 & -4 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right] \rightarrow \left[\begin{array}{ccc|c} 1 & 0 & \frac{1}{4} & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right] \text{ so } X = \begin{bmatrix} -\frac{1}{4}t \\ 0 \\ t \end{bmatrix}, t \in \mathbb{R}.$$

Therefore, a basic eigenvector corresponding to $\lambda_2 = -3$ is $\begin{bmatrix} -1 \\ 0 \\ 4 \end{bmatrix}$

Let

$$P = \begin{bmatrix} -1 & 1 & 0 \\ 0 & 0 & 1 \\ 4 & 0 & 0 \end{bmatrix}.$$

Then P is invertible (easily checked by computing $\det P$).

Solution (continued)

Furthermore,

$$P^{-1}AP = D = \text{diag}(-3, 1, 1) = \begin{bmatrix} -3 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}.$$

The eigenvalues of A in D (from left to right) occur in the same order as their corresponding eigenvectors as columns of P .

Example

Diagonalize the matrix $A = \begin{bmatrix} 3 & -4 & 2 \\ 1 & -2 & 2 \\ 1 & -5 & 5 \end{bmatrix}$

Solution

You can check that A has eigenvalues and corresponding basic eigenvectors:

$$\lambda_1 = 3 \text{ and } X_1 = \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix}; \lambda_2 = 2 \text{ and } X_2 = \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix}; \lambda_3 = 1 \text{ and } X_3 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}.$$

Let $P = [X_1 \ X_2 \ X_3] = \begin{bmatrix} 1 & 2 & 1 \\ 1 & 1 & 1 \\ 2 & 1 & 1 \end{bmatrix}$. Then P is invertible (check this!), so by the previous theorem,

$$P^{-1}AP = \begin{bmatrix} 3 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{bmatrix}.$$

Eigenvalues, Eigenvectors, and Diagonalization

Theorem

Let A be an $n \times n$ matrix, and suppose that A has distinct eigenvalues $\lambda_1, \lambda_2, \dots, \lambda_m$. For each i , let X_i be a λ_i -eigenvector of A . Then $\{X_1, X_2, \dots, X_m\}$ is linearly independent.

Diagonalizability

Determining whether or not a square matrix A is diagonalizable can be done using **eigenvalues** and **eigenvectors** of the matrix A .

Theorem

Let A be an $n \times n$ matrix and suppose it has n distinct eigenvalues. Then it follows that A is diagonalizable.

Proof.

Let $\{\lambda_1, \lambda_2, \dots, \lambda_n\}$ denote the n (distinct) eigenvalues of A , and let X_i be an eigenvector of A corresponding to λ_i , $1 \leq i \leq n$. Then $\{X_1, X_2, \dots, X_n\}$ is an independent set.

A subset of n linearly independent vectors of \mathbb{R}^n also spans \mathbb{R}^n , and thus $\{X_1, X_2, \dots, X_n\}$ is a basis of \mathbb{R}^n . Therefore A is diagonalizable. □

Example

Show that the matrix

$$A = \begin{bmatrix} 0 & -1 & 1 \\ 8 & 6 & -2 \\ 0 & 0 & -3 \end{bmatrix}$$

is diagonalizable.

Solution

A has characteristic polynomial

$$c_A(x) = (x + 3)(x - 2)(x - 4),$$

and thus A has distinct eigenvalues $-3, 2$ and 4 .

Since A is 3×3 and has three distinct eigenvalues, A is diagonalizable.

Definition

Let A be an $n \times n$ matrix and $\lambda \in \mathbb{R}$. The eigenspace of A corresponding to λ , written $E_\lambda(A)$ is the set of all eigenvectors corresponding to λ .

In other words, the eigenspace $E_\lambda(A)$ is all X such that $AX = \lambda X$. Notice that this set can be written $E_\lambda(A) = \text{null}(\lambda I - A)$, showing that $E_\lambda(A)$ is a subspace of \mathbb{R}^n .

Definition

Let A be an $n \times n$ matrix with characteristic polynomial given by $\det(\lambda I - A)$. Then, the multiplicity of an eigenvalue λ of A is the number of times λ occurs as a root of that characteristic polynomial.

Lemma

If A is an $n \times n$ matrix, then

$$\dim(E_\lambda(A)) \leq m$$

where λ is an eigenvalue of A of multiplicity m .

This result tells us that if λ is an eigenvalue of A , then the number of linearly independent λ -eigenvectors is never more than the multiplicity of λ .

The crucial consequence of the above Lemma is the characterization of matrices that are diagonalizable.

Theorem

Let A be an $n \times n$ matrix A . Then A is diagonalizable if and only if for each eigenvalue λ of A , $\dim(E_\lambda(A))$ is equal to the multiplicity of λ .

Example

Let

$$A = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$$

Determine if A is diagonalizable

Solution

Through the usual procedure, we find that the eigenvalues of A are $\lambda_1 = 1, \lambda_2 = 1$. Solving as usual, we find that the eigenvectors are given by

$$t \begin{bmatrix} 1 \\ 0 \end{bmatrix} \text{ and the basic eigenvector is } X_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

This means that $\dim(E_\lambda(A)) = 1$, but the multiplicity of $\lambda = 1$ is 2. Therefore this matrix is not diagonalizable.

Complex Eigenvalues

If a matrix has eigenvalues that have imaginary parts (and aren't simply real numbers), we can still find eigenvectors and possibly diagonalize the matrix.

Problem

Diagonalize, if possible, the matrix $A = \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix}$.

Solution

$$c_A(x) = \det(xI - A) = \begin{vmatrix} x-1 & -1 \\ 1 & x-1 \end{vmatrix} = x^2 - 2x + 2.$$

The roots of $c_A(x)$ are **distinct complex numbers**: $\lambda_1 = 1 + i$ and $\lambda_2 = 1 - i$, so A is diagonalizable. Corresponding eigenvectors are

$$X_1 = \begin{bmatrix} -i \\ 1 \end{bmatrix} \text{ and } X_2 = \begin{bmatrix} i \\ 1 \end{bmatrix},$$

respectively.

Solution (continued)

A diagonalizing matrix for A is

$$P = \begin{bmatrix} -i & i \\ 1 & 1 \end{bmatrix},$$

and

$$P^{-1}AP = \begin{bmatrix} 1+i & 0 \\ 0 & 1-i \end{bmatrix}.$$

Notice that A is a real matrix, but has complex eigenvalues (and eigenvectors).

Eigenvalues of a Real Symmetric Matrix

Theorem

The eigenvalues of any **real symmetric** matrix are **real**.

Proof.

Let A be an $n \times n$ real symmetric matrix, and let λ be an eigenvalue of A . To prove that λ is real, it is enough to prove that $\bar{\lambda} = \lambda$, i.e., λ is equal to its (complex) conjugate.

We use \bar{A} to denote the matrix obtained from A by replacing each entry by its conjugate. Since A is real, $\bar{A} = A$.

Suppose

$$X = \begin{bmatrix} z_1 \\ z_2 \\ \vdots \\ z_n \end{bmatrix}$$

is a λ -eigenvector of A . Then $AX = \lambda X$.

Proof (continued).

$$\text{Let } y = X^T \bar{X} = \begin{bmatrix} z_1 & z_2 & \cdots & z_n \end{bmatrix} \begin{bmatrix} \bar{z}_1 \\ \bar{z}_2 \\ \vdots \\ \bar{z}_n \end{bmatrix}.$$

Then $y = z_1 \bar{z}_1 + z_2 \bar{z}_2 + \cdots + z_n \bar{z}_n = |z_1|^2 + |z_2|^2 + \cdots + |z_n|^2$; since $X \neq 0$, y is a positive real number. Now

$$\begin{aligned} \lambda y &= \lambda(X^T \bar{X}) = (\lambda X^T) \bar{X} = (\lambda X)^T \bar{X} \\ &= (AX)^T \bar{X} = X^T A^T \bar{X} \\ &= X^T A \bar{X} \quad (\text{since } A \text{ is symmetric}) \\ &= X^T \overline{AX} \quad (\text{since } A \text{ is real}) \\ &= X^T (\overline{\lambda X}) = X^T (\bar{\lambda} \bar{X}) = X^T \bar{\lambda} \bar{X} \\ &= \bar{\lambda} (X^T \bar{X}) \\ &= \bar{\lambda} y. \end{aligned}$$

Thus, $\lambda y = \bar{\lambda} y$. Since $y \neq 0$, it follows that $\lambda = \bar{\lambda}$, and therefore λ is real. \square