**Practical no. 1(b)**

import ch.aplu.robotsim.\*;

class MoveWithoutGears

{

MoveWithoutGears()

{

TurtleRobot robot=new TurtleRobot();

robot.forward(100);

robot.left(45);

robot.forward(200);

robot.right(90);

robot.backward(100);

robot.exit();

}

public static void main(String args[])

{

MoveWithoutGears m=new MoveWithoutGears();

}

}

**Output :**

