**Practical No. 2**

import ch.aplu.robotsim.\*;

public class MoveWithMotors

{

public MoveWithMotors()

{

NxtRobot robot=new NxtRobot();

Motor motA=new Motor(MotorPort.A);

Motor motB=new Motor(MotorPort.B);

robot.addPart(motA);

robot.addPart(motB);

motA.forward();

motB.forward();

Tools.delay(2000);

motA.stop();

Tools.delay(1050);

motA.forward();

Tools.delay(2000);

motB.stop();

Tools.delay(1050);

motB.forward();

Tools.delay(2000);

robot.exit();

}

public static void main(String args[])

{

new MoveWithMotors();

}

}

### Output:

