

# Homework 2: Conditional WGAN-GP on MNIST

CSC 8851 – Deep Learning - Fall 2025

## Learning Objectives

- Implement and train a class-conditional Wasserstein GAN with Gradient Penalty (WGAN-GP) on MNIST.
- Use a projection discriminator and a label-conditional generator.
- Plot the critic scores, gradient penalty, and losses.
- Produce high-quality conditional samples, and explore latent interpolations and truncation.

## Assignment Tasks (100 pts)

### Part 1: Model and Losses (40 pts)

- (20 pts) Implement a conditional generator  $G(z, y)$  and a projection critic  $D(x, y)$  for MNIST resized to  $32 \times 32$  resolution.

– **Generator  $G(z, y)$**  (MNIST  $32 \times 32$ ). Label embedding  $e_g(y) \in \mathbb{R}^{32}$  concatenated with noise  $z \in \mathbb{R}^{64}$ , then:

- \* FC:  $(64+32) \rightarrow 4 \times 4 \times 128$ ; reshape to  $(128, 4, 4)$ .
- \* Upsample  $\times 2$  (nearest)  $\rightarrow \text{Conv}(128 \rightarrow 64, 3 \times 3, s=1, p=1) \rightarrow \text{BN} \rightarrow \text{ReLU}$  (4 $\rightarrow$ 8)
- \* Upsample  $\times 2 \rightarrow \text{Conv}(64 \rightarrow 32, 3 \times 3) \rightarrow \text{BN} \rightarrow \text{ReLU}$  (8 $\rightarrow$ 16)
- \* Upsample  $\times 2 \rightarrow \text{Conv}(32 \rightarrow 16, 3 \times 3) \rightarrow \text{BN} \rightarrow \text{ReLU}$  (16 $\rightarrow$ 32)
- \* Conv(16 $\rightarrow$ 1,  $3 \times 3$ )  $\rightarrow \text{Tanh}$  (output in  $[-1, 1]$ ).

*Notes:* BatchNorm (BN) only in  $G$ ; activations ReLU; initialize Conv/Linear with Kaiming (He) normal; no spectral/weight norm needed for this assignment.

– **Critic  $D(x, y)$  with projection.** Input  $x \in \mathbb{R}^{1 \times 32 \times 32}$  with pixels normalized to  $[-1, 1]$ . Trunk (before projection) produces  $h \in \mathbb{R}^{B \times C \times 4 \times 4}$  with  $C = \text{proj\_dim} = 128$ :

- \* Conv(1 $\rightarrow$ 32,  $4 \times 4$ ,  $s=2$ ,  $p=1$ )  $\rightarrow \text{LeakyReLU}(0.2)$  (32 $\rightarrow$ 16)
- \* Conv(32 $\rightarrow$ 64,  $4 \times 4$ ,  $s=2$ ,  $p=1$ )  $\rightarrow \text{LeakyReLU}(0.2)$  (16 $\rightarrow$ 8)
- \* Conv(64 $\rightarrow$ 128,  $4 \times 4$ ,  $s=2$ ,  $p=1$ )  $\rightarrow \text{LeakyReLU}(0.2)$  (8 $\rightarrow$ 4)
- \* Global sum pool over  $4 \times 4$ :  $f(x) = \sum_{u,v} h_{:::,u,v} \in \mathbb{R}^{B \times C}$ .
- \* **Projection:** learn a class embedding  $e(y) \in \mathbb{R}^C$  and a linear head  $w \in \mathbb{R}^C$ . The final score is

$$D(x, y) = w^\top f(x) + \langle f(x), e(y) \rangle \in \mathbb{R}^B.$$

*Notes:* Do *not* use sigmoid in  $D$  (WGAN-GP needs raw scores). Keep critic norm-free.

- (10 pts) Wasserstein loss with **Gradient Penalty**:

$$\mathcal{L}_C = -\left(\mathbb{E}[D(x, y)] - \mathbb{E}[D(G(z, y), y)]\right) + \underbrace{\lambda_{\text{gp}} \cdot \mathbb{E}\left[\left(\|\nabla_{\hat{x}} D(\hat{x}, y)\|_2 - 1\right)^2\right]}_{\text{GP}}, \quad (1)$$

$$\mathcal{L}_G = -\mathbb{E}[D(G(z, y), y)]. \quad (2)$$

where  $\hat{x} = \epsilon x + (1 - \epsilon)G(z, y)$  with  $\epsilon \sim \text{Uniform}(0, 1)$ .

- (10 pts) **Generator EMA** (Exponential Moving Average): Maintain a second, non-trainable copy of the generator  $G_{\text{ema}}$  whose weights track  $G$  via an exponential moving average. Generating using  $G_{\text{ema}}$  typically yields cleaner, less noisy images.
  - **Init.** At the start of training, set  $G_{\text{ema}} \leftarrow \text{deepcopy}(G)$  and make all of its parameters non-trainable (`requires_grad = False`).
  - **Update rule** (after each `opt.G.step()`). For each floating-point entry  $\theta \in \text{state\_dict}(G)$  with EMA counterpart  $\theta_{\text{ema}}$ :

$$\theta_{\text{ema}} \leftarrow \tau \theta_{\text{ema}} + (1 - \tau) \theta, \quad \text{with decay } \tau \in [0, 1) \text{ (e.g., } \tau = 0.999\text{)}.$$

Non-floating entries (e.g., integer counters) should be copied directly rather than averaged.

#### Example pseudocode for EMA:

```
def ema_update(model, ema_model, decay=0.999):
    with torch.no_grad():
        msd = model.state_dict()
        esd = ema_model.state_dict()
        for k in esd.keys():
            if k in msd:
                if esd[k].dtype.is_floating_point:
                    esd[k].mul_(decay).add_(msd[k] * (1.0 - decay))
                else:
                    esd[k] = msd[k]
        ema_model.load_state_dict(esd)
```

#### Example pseudocode for Gradient Penalty:

```
# real: [B, 1, H, W], labels y: [B]
# fake_det is detached from G for the critic update
z = torch.randn(B, z_dim, device=dev)
fake_det = G(z, y).detach()

# interpolate
eps = torch.rand(B, 1, 1, 1, device=dev)
x_hat = (eps * real + (1 - eps) * fake_det).requires_grad_(True)

# critic outputs
real_score = D(real, y).mean()
fake_score = D(fake_det, y).mean()
hat_score = D(x_hat, y).mean()

# gradients wrt inputs
grad = torch.autograd.grad(
    outputs=hat_score, inputs=x_hat,
    create_graph=True, retain_graph=True, only_inputs=True
)[0] # shape: [B, 1, H, W]
```

```
grad_norm = grad.view(B, -1).norm(2, dim=1) # L2 per sample

gp = ((grad_norm - 1.0) ** 2).mean()
loss_C = -(real_score - fake_score) + lambda_gp * gp
```

## Part 2: Training (20 pts)

- (10 pts) Train for 10–20 epochs. Recommended: Adam with  $\text{lr} = 2 \times 10^{-4}$ ,  $\text{betas}(0.0, 0.9)$ ;  $\lambda_{\text{gp}}=10$ ;  $n_{\text{critic}}=2-3$  (where you update the critic  $D(x, y)$   $n_{\text{critic}}$  times for every update of  $G(z, y)$ ); batch size  $\approx 128$ . Plot a set of generated samples after every epoch of training using the same latents  $z$  using  $G_{\text{ema}}$ .
- (10 pts) Plot curves for:  $\mathbb{E}[D(x, y)]$ ,  $\mathbb{E}[D(G(z, y), y)]$ , GP,  $\mathcal{L}_C$ ,  $\mathcal{L}_G$  (see Fig. 1).

## Part 3: Conditional Samples (20 pts)

- At the end of training, generate a  $10 \times N$  grid of conditional samples using your best sampler (e.g., EMA generator). See Fig. 2.

## Part 4: Latent Exploration and Truncation (20 pts)

- (10 pts) Latent interpolations for all digits: for each class  $c \in \{0, \dots, 9\}$ , interpolate  $z$  between two random endpoints and show a row of  $K$  images. Aggregate into a  $10 \times K$  panel. See Fig. 3.
- (10 pts) Truncation sweep: for each class, generate samples by scaling  $z \leftarrow \psi z$  with  $\psi \in \{3.0, 2.5, 2.0, 1.5, 1.0, 0.8, 0.6, 0.4, 0.2, 0.1\}$ . See Fig. 4.

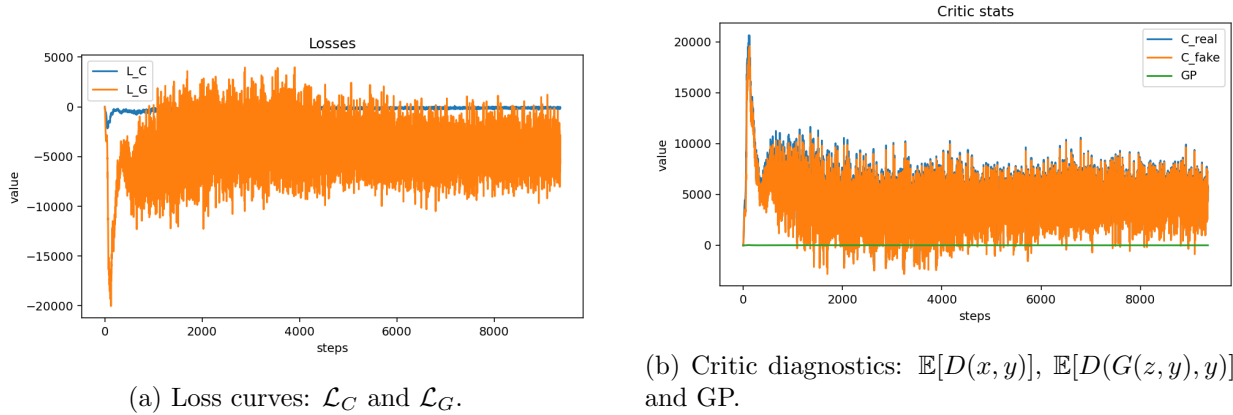


Figure 1: Training curves.

## Submission Instructions

1. Submit a Jupyter Notebook named `CSC8851_F2025_HW2_<YourName>.ipynb`. Include all code, plots, and generated images. The notebook must run top-to-bottom.



Figure 2: Conditional generation grid at the end of training (rows = labels 0–9), produced with EMA generator.

2. Submit a PDF export of your notebook named `CSC8851_F2025_HW2_<YourName>.pdf`. DO NOT paste images of your code in the PDF. It will fail the plagiarism check. :

- Using **nbconvert**:

```
jupyter nbconvert --to pdf CSC8851_F2025_HW2_<YourName>.ipynb
```

- Or convert to HTML then print to PDF:

```
jupyter nbconvert --to html CSC8851_F2025_HW2_<YourName>.ipynb
```

Open the HTML in a browser and print to PDF.

- Or use the Jupyter/Colab menu: File → Download as → PDF.

3. Upload both files (`.ipynb` and `.pdf`) to the assignment on iCollege.

*You may include additional qualitative results (e.g., failure cases). Cite any external code sources used. Keep your code and discussion concise and clear.*



Figure 3: Latent interpolations: rows = classes 0–9, columns = steps along the interpolation.



Figure 4: Truncation sweep per class with  $\psi \in \{3.0, 2.5, 2.0, 1.5, 1.0, 0.8, 0.6, 0.4, 0.2, 0.1\}$ .