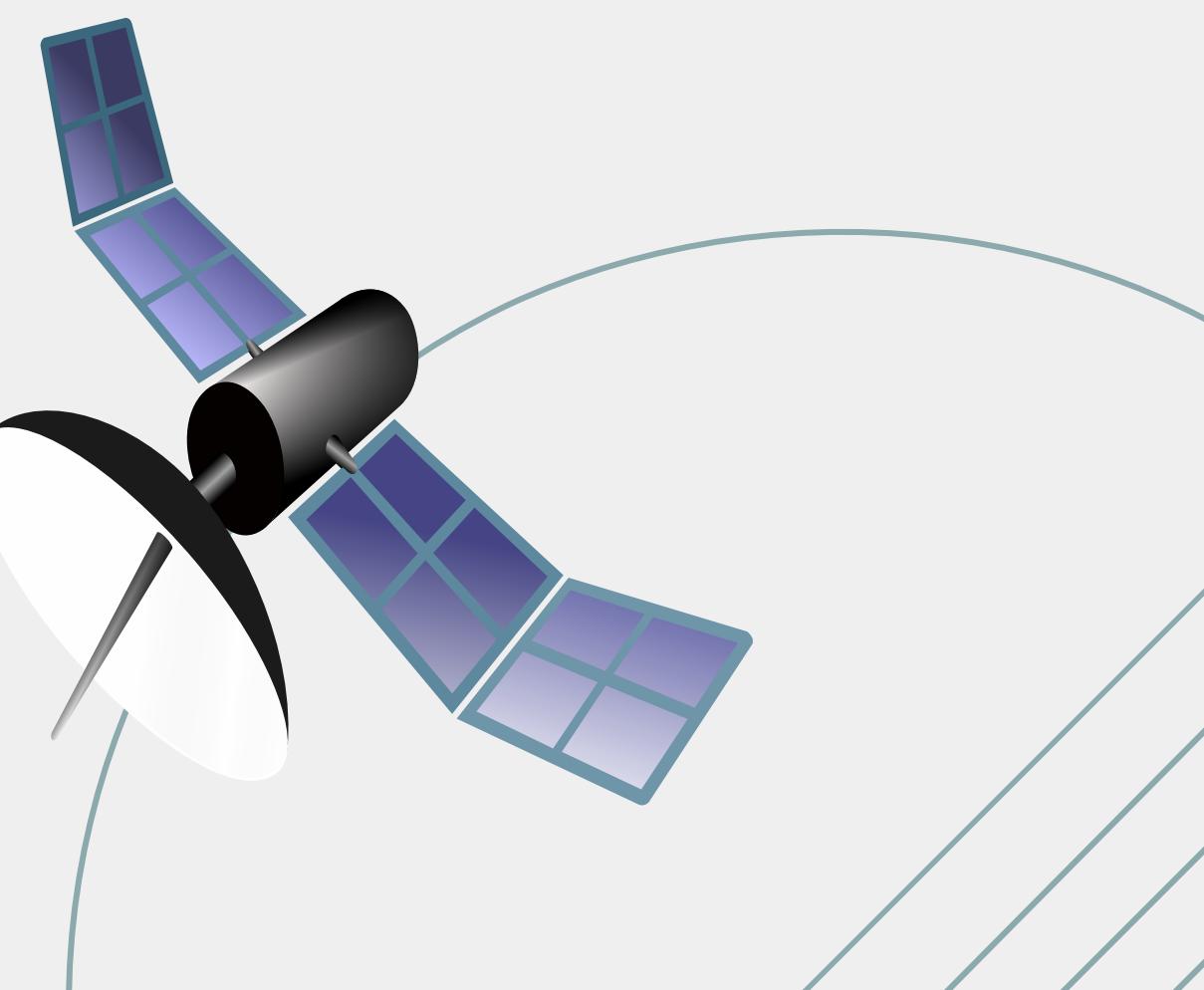




# GPS TOLL BASED SYSTEM SIMULATION USING PYTHON



# SOLUTION

```
import random
import pandas as pd
from datetime import datetime, timedelta

def generate_gps_data(num_points, lat_range, lon_range):
    data = []
    start_time = datetime.now()
    for _ in range(num_points):
        lat = random.uniform(lat_range[0], lat_range[1])
        lon = random.uniform(lon_range[0], lon_range[1])
        timestamp = start_time + timedelta(seconds=random.randint(1, 60))
        data.append((timestamp, lat, lon))
    return pd.DataFrame(data, columns=['timestamp', 'latitude', 'longitude'])

# Example usage
gps_data = generate_gps_data(10, (40.7128, 40.7486), (-74.0060, -73.9352))
print(gps_data)
from geopy.distance import geodesic

def calculate_total_distance(gps_data):
    total_distance = 0.0
    for i in range(1, len(gps_data)):
        coords_1 = (gps_data.iloc[i-1]['latitude'], gps_data.iloc[i-1]['longitude'])
        coords_2 = (gps_data.iloc[i]['latitude'], gps_data.iloc[i]['longitude'])
        total_distance += geodesic(coords_1, coords_2).miles
    return total_distance

# Example usage
total_distance = calculate_total_distance(gps_data)
print(f'Total distance: {total_distance} miles')

# Solution completed at 18:58
```

```
def calculate_total_distance(gps_data):
    total_distance = 0.0
    for i in range(1, len(gps_data)):
        coords_1 = (gps_data.iloc[i-1]['latitude'], gps_data.iloc[i-1]['longitude'])
        coords_2 = (gps_data.iloc[i]['latitude'], gps_data.iloc[i]['longitude'])
        total_distance += geodesic(coords_1, coords_2).kilometers
    return total_distance

# Example usage
total_distance = calculate_total_distance(gps_data)
print(f"Total Distance: {total_distance} km")
def calculate_toll(distance, rate_per_km=50):
    return distance * rate_per_km

# Example usage
toll = calculate_toll(total_distance)
print(f"Toll Charge: ruprees {toll:.2f}")
def simulate_multiple_vehicles(num_vehicles, num_points, lat_range, lon_range):
    results = []
    for vehicle_id in range(num_vehicles):
        gps_data = generate_gps_data(num_points, lat_range, lon_range)
        total_distance = calculate_total_distance(gps_data)
        toll = calculate_toll(total_distance)
        results.append((vehicle_id, total_distance, toll))
```

```
    return total_distance

# Example usage
total_distance = calculate_total_distance(gps_data)
print(f"Total Distance: {total_distance} km")
def calculate_toll(distance, rate_per_km=50):
    return distance * rate_per_km

# Example usage
toll = calculate_toll(total_distance)
print(f"Toll Charge: ruprees {toll:.2f}")
def simulate_multiple_vehicles(num_vehicles, num_points, lat_range, lon_range):
    results = []
    for vehicle_id in range(num_vehicles):
        gps_data = generate_gps_data(num_points, lat_range, lon_range)
        total_distance = calculate_total_distance(gps_data)
        toll = calculate_toll(total_distance)
        results.append((vehicle_id, total_distance, toll))
    return pd.DataFrame(results, columns=['vehicle_id', 'total_distance', 'toll_charge'])

# Example usage
simulation_results = simulate_multiple_vehicles(5, 10, (40.7128, 40.7486), (-74.0060, -73.9352))
print('simulation results:', simulation_results)
```

# OUTPUT

```
timestamp      latitude   longitude
0 2024-07-13 13:28:24.887806 40.734013 -73.997045
1 2024-07-13 13:28:17.887806 40.729783 -73.991091
2 2024-07-13 13:28:30.887806 40.739193 -73.991585
3 2024-07-13 13:28:31.887806 40.732344 -73.988028
4 2024-07-13 13:28:47.887806 40.747743 -73.996519
5 2024-07-13 13:28:59.887806 40.741863 -73.970816
6 2024-07-13 13:28:40.887806 40.729337 -73.998544
7 2024-07-13 13:28:46.887806 40.739359 -73.947559
8 2024-07-13 13:28:38.887806 40.733468 -73.954462
9 2024-07-13 13:28:48.887806 40.742078 -74.001941
Total Distance: 18.844628521256443 km
Toll Charge: ruprees 942.23
simulation results: vehicle_id total_distance toll_charge
0          0        26.924594  1346.229679
1          1        28.322153  1416.107627
2          2        23.428516  1171.425789
3          3        20.040056  1002.002783
4          4        20.986151  1049.307565
```



# FEATURES OFFERED

- 1. GPS Data Generation: Generates random GPS data points with timestamps, latitude, and longitude within a specified range.
- 
- 2. Total Distance Calculation: Calculates the total distance traveled by a vehicle based on the generated GPS data points.
- 
- 3. Toll Charge Calculation: Calculates the toll charge based on the total distance traveled and a specified rate per kilometer.
- 
- 4. Multi-Vehicle Simulation: Simulates GPS data generation, total distance calculation, and toll charge calculation for multiple vehicles.
-

- 5. Data Storage: Stores the generated GPS data, total distance, and toll charge for each vehicle in a pandas DataFrame.
- 
- 6. Randomized Timestamps: Generates random timestamps for each GPS data point, simulating real-world GPS data collection.
- 
- 7. Geodesic Distance Calculation: Uses the geodesic distance formula to calculate the distance between two GPS coordinates, providing an accurate measurement of distance traveled.
- 
- 8. Customizable Parameters: Allows users to specify the number of GPS data points, latitude and longitude ranges, and toll rate per kilometer.
- 
- 9. Data Analysis: Enables analysis of the generated data, including total distance traveled and toll charges for each vehicle.

# PROCESS FLOW

- Generate\_GPS\_data
  - 1. Start
  - 2. Initialize data list
  - 3. Set start time to current datetime
  - 4. Loop num\_points times
    - Generate random lat and lon within ranges
    - Calculate timestamp with random offset
    - Append (timestamp, lat, lon) to data list
  - 5. Return DataFrame from data list

- Calculate\_total\_distance

1. Start
2. Initialize total\_distance to 0
3. Loop through gps\_data rows (starting from 2nd row)
  - Calculate geodesic distance between current and previous points
  - Add distance to total\_distance
4. Return total\_distance

- Calculate\_toll

1. Start
2. Return distance \* rate\_per\_km

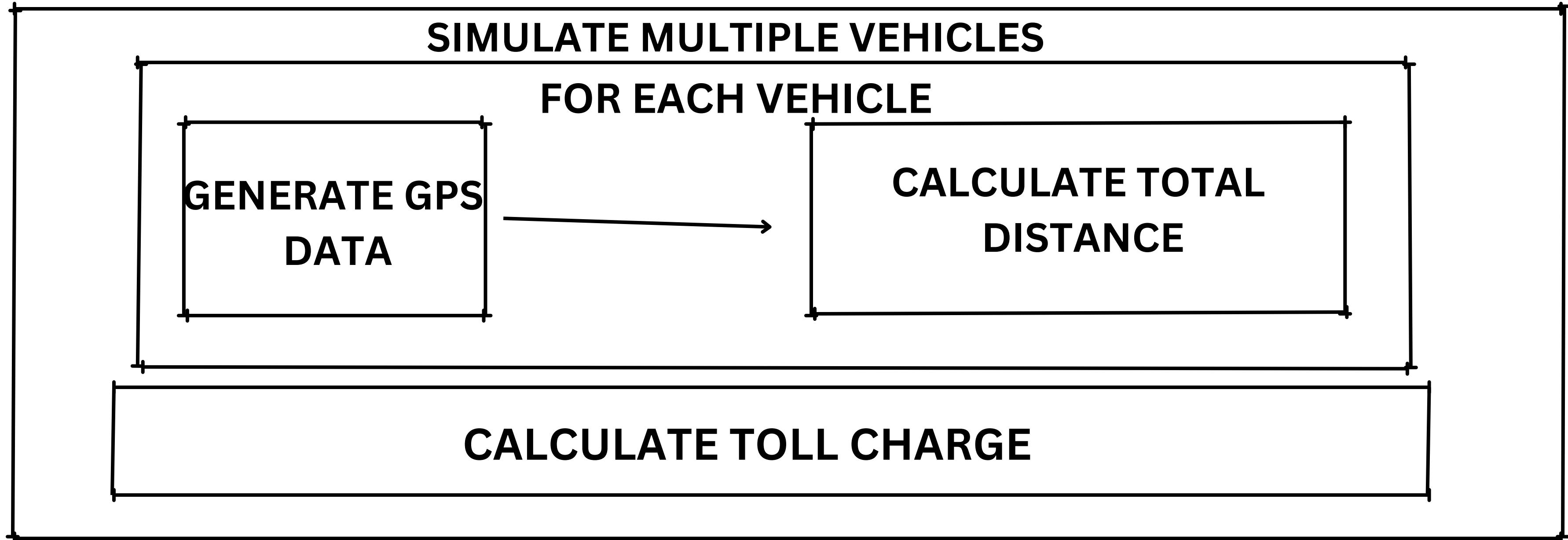
- simulate\_multiple\_vehicles

1. Start
2. Initialize results list
3. Loop num\_vehicles times
  - Generate gps\_data for current vehicle
  - Calculate total\_distance for current vehicle
  - Calculate toll for current vehicle
  - Append (vehicle\_id, total\_distance, toll) to results list
4. Return DataFrame from results list

- Main Program

1. Start
2. Generate gps\_data for 10 points
3. Calculate total\_distance for gps\_data
4. Calculate toll for total\_distance
5. Simulate multiple vehicles (5 vehicles, 10 points each)
6. Print results

# ARCHITECTURE DIAGRAM



MAIN PROGRAM

SIMULATE  
MULTIPLE  
VEHICLES



# TECHNOLOGIES USED

- 1. Python:** The program is written in Python, a popular high-level programming language.
- 2. Pandas:** The program uses the Pandas library to handle data manipulation and analysis.
- 3. Geopy:** The program uses the Geopy library to calculate geodesic distances between GPS coordinates.
- 4. DateTime:** The program uses the DateTime library to handle timestamp calculations.
- 5. Random:** The program uses the Random library to generate random GPS coordinates and timestamps.
- 6. Timedelta:** The program uses the Timedelta library to calculate time differences.



**Additionally, the program uses various Python features, such as:**

- 1. Functions:** The program defines several functions to organize and reuse code.
- 2. Loops:** The program uses for loops to iterate over data and perform calculations.
- 3. Conditional statements:** The program uses if statements to handle different scenarios and edge cases.
- 4. Data structures:** The program uses lists and DataFrames to store and manipulate data.

**Overall, the program leverages a combination of Python libraries and features to simulate GPS data generation, distance**

TEAM MEMBER

BHAVANI V R

USN:1AT22EC013

MENTOR:

SHILPA MN

**ATRIA INSTITUTE OF  
TECHNOLOGY  
BENGALURU**

# THANK YOU