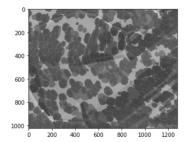
```
In [1]: # import all relevant libraries
          import numpy as np
from PIL import Image
           import matplotlib.pyplot as plt
           from skimage import util
from sklearn.cluster import KMeans, MiniBatchKMeans
```

## **Import the image**

Now, we import the image as a numpy n-dimensional array and display the image and its resolution.

```
In [2]: img_in = np.array(Image.open('../data/test_kmeans2.tif').convert('L')) # import the grayscale image as an array
                                                                                                       \label{limited_print}  \text{print("Resolution of Image: ", img_in.shape)} \ \textit{\# display the resolution of the image} \\ \text{img_plot} = \text{plt.imshow(img_in, cmap='gray')} \ \textit{\# display the image} \\ \\ \text{print("Resolution of Image: ", img_in.shape)} \ \textit{\# display the image} \\ \text{print("Resolution of Image: ", img_in.shape)} \ \textit{\# display the image} \\ \text{print("Resolution of Image: ", img_in.shape)} \ \textit{\# display the image} \\ \text{print("Resolution of Image: ", img_in.shape)} \ \textit{\# display the image} \\ \text{print("Resolution of Image: ", img_in.shape)} \ \textit{\# display the image} \\ \text{print("Resolution of Image: ", img_in.shape)} \ \textit{\# display the image} \\ \text{print("Resolution of Image: ", img_in.shape)} \ \textit{\# display the image} \\ \text{print("Resolution of Image: ", img_in.shape)} \ \textit{\# display the image} \\ \text{print("Resolution of Image: ", img_in.shape)} \ \textit{\# display the image} \\ \text{print("Resolution of Image: ", img_in.shape)} \ \textit{\# display the image} \\ \text{print("Resolution of Image: ", img_in.shape)} \ \textit{\# display the image} \\ \text{print("Resolution of Image: ", img_in.shape)} \ \textit{\# display the image} \\ \text{print("Resolution of Image: ", img_in.shape)} \ \textit{\# display the image} \\ \text{print("Resolution of Image: ", img_in.shape)} \ \textit{\# display the image} \\ \text{print("Resolution of Image: ", img_in.shape)} \ \textit{\# display the image} \\ \text{print("Resolution of Image: ", img_in.shape)} \ \textit{\# display the image} \\ \text{print("Resolution of Image: ", img_in.shape)} \ \textit{\# display the image} \\ \text{print("Resolution of Image: ", img_in.shape)} \ \textit{\# display the image} \\ \text{print("Resolution of Image: ", img_in.shape)} \ \textit{\# display the image} \\ \text{print("Resolution of Image: ", img_in.shape)} \ \textit{\# display the image} \\ \text{print("Resolution of Image: ", img_in.shape)} \ \textit{\# display the image} \\ \text{print("Resolution of Image: ", img_in.shape)} \ \text{print("Resolution of Im
```

Resolution of Image: (1024, 1280)



## Define the parameters

We define all the parameters that we can change.

```
wsize = 30  # define the window size in pixels. This is the side length of the tiles.
n_clusters = 5  # define the number of clusters. This is the "K" in "K-Means".
stride = 3  # define the stride length. This is the number of pixels moved right or down between two tiles.
In [3]: wsize = 30
              seed = 197208 # define a random seed which will be used to determine the inital position of the centroids. This can be any random integer.
```

# Pre-process the image

We make changes to the image to be able to run the method effectively.

```
In [4]: # define a function to add a some padding to the image so that we can have an integer number of tiles.
           def pad(img,wsize,stride=1):
                """Adds a few pixels to the image as padding so that we can have an integer number of tiles.
                     ing (np.array of shape(img.shape)): Array containg the image. wsize (int): side length of tile. stride (int): number of pixels between two tiles (default=1).
                ing (np.array): Padded image i.e. image with a few additional pixels.
                height,width = img.shape
if stride == 'block':
adj = 0
                     stride = wsize
                else:
                    adj = 1
                px = wsize - height % stride - adj
                if px % 2 == 0:
px = int(px/2)
                     px = (px, px)
                else:
                     px = int((px-1)/2)
                     px = (px,px+1)
                py = wsize - width % stride - adj
if py % 2 == 0:
    py = int(py/2)
    py = (py,py)
                else:
                     py = int((py-1)/2)
                     py = (py,py+1)
                return np.pad(img,pad_width=(px,py),mode='symmetric')
```

```
In [5]: # define a variable "X" which is a numpy array where each element is a tile.

X = util.view_as_windows(
    pad(img_in,wsize-wsize,stride-stride), # add padding to the original image
    window shape(wsize,wsize), # define the tile size
    step-stride)

# define the stride length

# ask_dim = X.shape[:2] # pick the first two values in the shape which correspond to the number of tiles.

# This can be called the reduced image where each pixel represents one tile.

X=X.reshape(-1,wsize=*2) # reshape "X" to get an array of the tiles as vectors. The resulting array has
    # the dimensions 'number of tiles x number of pixels per tile'.
```

## Run the model

We define the standard and mini-batch k-means models and fit them to our data.

## Post-process the fitted data

 $\textbf{Each of the models return certain attributes that contain all the relevant data. See more: \underline{KMeans}, \underline{MiniBatchKMeans}$ 

```
In [8]: mask = kmeans.labels_.reshape("mask_dim) # reshape the "labels_" attribute to match the dimensions of the reduced image
mask = Image.fromarray(mask) # convert the mask into an Image object

mb_mask = mb_kmeans.labels_.reshape("mask_dim) # reshape the "labels_" attribute to match the dimensions of the reduced image
mb_mask = Image.fromarray(mb_mask) # convert the mask into an Image object

In [9]: clusters = np.array(mask.resize(img_in.shape(::-1]))+1 # scale the reduced image to the size of the input image
mb_clusters = np.array(mask.resize(img_in.shape(::-1]))+1 # scale the reduced image to the size of the input image

# mod_ins_clusters" to match the colour scheme in "clusters". This is only for visual comparison between the two.
mod_mb_clusters = np.where(mb_clusters == 5, 2,0) + np.where(mb_clusters == 4, 4,0) + np.where(mb_clusters == 1, 1,0) + np.where(mb_clusters == 3, 5,0) + np.where(mb_clusters == 2, 3,0)
```

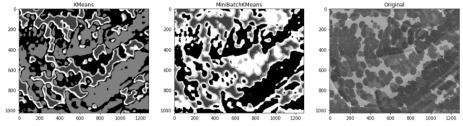
## Plot the segmented images

```
In [10]: fig, ax = plt.subplots(nrows=1,ncols=3, figsize=(18,6)) # create a figure with sub-plots

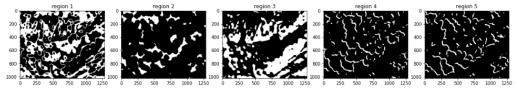
# show the images segemented by KMeans and MiniBatchKMeans respectively
ax[0].imshow(clusters, cmap='gray');
ax[1].imshow(om_b_clusters, cmap='gray');
ax[2].imshow(img_in, cmap='gray')

# Label the images
ax[0].set_title('KMeans')
ax[1].set_title('MiniBatchKMeans')
ax[2].set_title('Original')
```

Out[10]: Text(0.5, 1.0, 'Original')



```
In [11]: # create a figure where each of the regions are plotted separately
fig, ax = plt.subplots(nrows=1,ncols=n_clusters, figsize=(4*n_clusters,4))
for ncl in range(1,n_clusters*1):
    ax[ncl=1].imshow(np.where*c(lusters == ncl, 1, 0), cmap='gray')
    ax[ncl=1].set_title('region %i' %ncl)
```



# Varying the parameters

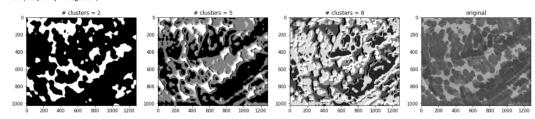
Now, we vary the stride length, number of clusters and the window size and see how it affects our result.

```
In [12]: # define a function that does MiniBatchKMeans and directly outputs an array of the cluster values
         def mbkmeans(n_clusters, seed, stride, wsize):
             mb_kmeans = MiniBatchKMeans(
                 n_clusters=n_clusters,
                 random_state=seed)
             mb_X = util.view_as_windows(
                 pad(img_in,wsize=wsize,stride=stride),
                 window_shape=(wsize,wsize),
                 step=stride)
             mb_mask_dim = mb_X.shape[:2]
             mb_X=mb_X.reshape(-1,wsize**2)
             mb_kmeans = mb_kmeans.fit(mb_X)
             mb_mask = mb_kmeans.labels_.reshape(*mb_mask_dim)
             mb_mask = Image.fromarray(mb_mask)
             mb_clusters = np.array(mb_mask.resize(img_in.shape[::-1]))+1
             return mb_clusters
```

# Vary the number of clusters:

See the difference between having 2, 5 and 8 clusters. Note the differences in the time taken to execute the segmentation.

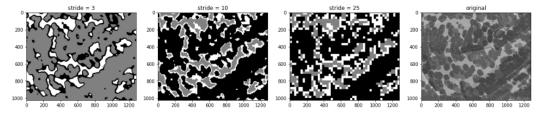
```
In [13]: wsize = 30
         nclusters = [2, 5, 8]
         stride = 3
         seed = 197208
         fig, ax = plt.subplots(ncols=4, nrows=1, figsize=(20,5))
         for iter, ncl in enumerate(nclusters):
             %time mb_cluster=mbkmeans(ncl,seed,stride,wsize)
             ax[iter].imshow(mb_cluster, cmap='gray');
             ax[iter].set_title('# clusters = %i' %ncl)
         ax[3].imshow(img_in, cmap='gray')
         ax[3].set_title('original')
         CPU times: user 11.3 s, sys: 2.48 s, total: 13.8 s
         Wall time: 1.46 s
         CPU times: user 11.4 s, sys: 2.13 s, total: 13.5 s
         Wall time: 1.32 s
         CPU times: user 12.1 s, sys: 2.26 s, total: 14.4 s
         Wall time: 1.39 s
Out[13]: Text(0.5, 1.0, 'original')
```



## Vary the stride: ¶

See the difference between having a stride length of 3, 10 and 25 pixels. Note the differences in the time taken to execute the segmentation.

```
In [14]: wsize = 30
nclusters = 3
stride = [3,10,25]
seed = 197208
                            fig, ax = plt.subplots(ncols=4, nrows=1, figsize=(20,5))
for iter, nst in enumerate(stride):
    %time mb_cluster=mbkmeans(nclusters,seed,nst,wsize)
    ax[iter].imshow(mb_cluster, cmap='gray');
    ax[iter].set_title('stride = %i %nst)
    ax[3].imshow(ing_in, cmap='gray')
    ax[3].set_title('original')
                            CPU times: user 8.94 s, sys: 1.8 s, total: 10.7 s
                            CPU times: user 8.94 s, sys: 1.8 s, total: 10.7 s Wall time: 1.3 s CPU times: user 1.64 s, sys: 853 ms, total: 2.49 s Wall time: 156 ms CPU times: user 80.2 ms, sys: 605 ms, total: 1.41 s Wall time: 88.3 ms
Out[14]: Text(0.5, 1.0, 'original')
```



# Vary the window size (wsize):

See the difference between having a window side length of 10, 30 and 50 pixels. Note the differences in the time taken to execute the segmentation.

```
In [15]: wsize = [10,30,50]
nclusters = 3
stride = 3
seed = 197208
                          fig, ax = plt.subplots(ncols=4, nrows=1, figsize=(20,5))
for iter, nws in enumerate(wsize):
    %time mb_cluster=mbkmeans(nclusters,seed,stride,nws)
    ax[iter].inshow(mb_cluster, cmap='gray');
    ax[iter].set_title('wsize = %i' %nws)
    ax[3].imshow(ing_in, cmap='gray')
    ax[3].set_title('original')
                          CPU times: user 739 ms, sys: 1.26 s, total: 2 s
Wall time: 414 ms
CPU times: user 9.54 s, sys: 2.12 s, total: 11.7 s
Wall time: 1.32 s
                          CPU times: user 2min 24s, sys: 43.5 s, total: 3min 8s Wall time: 4min 16s
 Out[15]: Text(0.5, 1.0, 'original')
```

