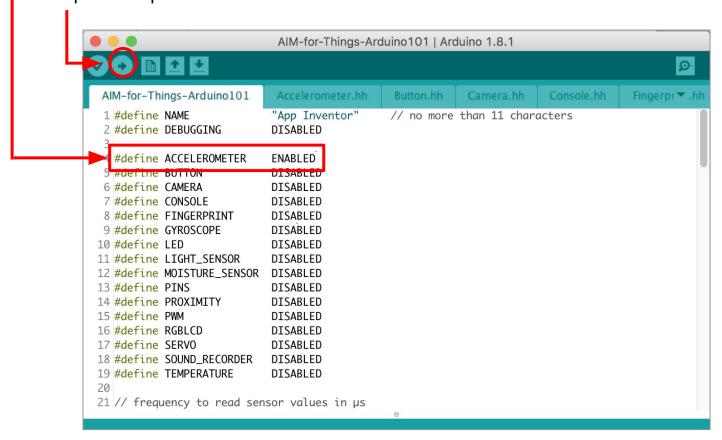
App Inventor + IoT: Accelerometer



This tutorial will help you get started with App Inventor + IoT and the built-in accelerometer on the <u>Arduino 101</u> controller. Accelerometers measure acceleration, which is the rate of change of the velocity of an object (the Arduino). Before you start you should first complete the <u>App Inventor + IoT Setup tutorial</u> to set up your Arduino device.

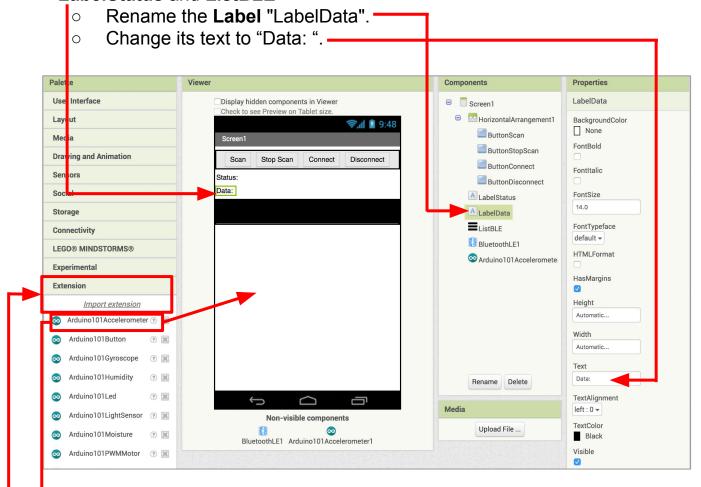
- For this tutorial make sure
 ACCELEROMETER is set to ENABLED and
 all others are set to DISABLED.
- You should also click the arrow button in the top left to upload the code.



Next, you should complete the <u>App Inventor + IoT Basic Connection</u> tutorial to make a basic connection to the Arduino device. If you prefer, you can download the completed .aia file <u>here</u>.

The remaining steps all build off of the the starter code for Basic Connection tutorial and .aia:

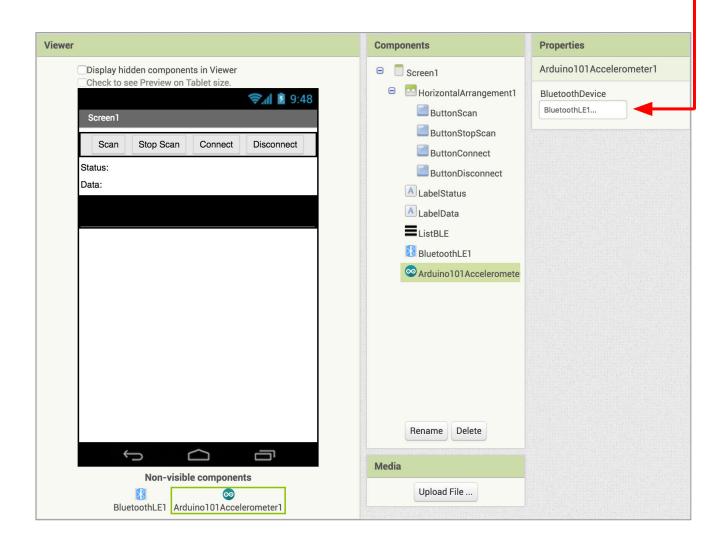
 Drag a Label from the User Interface Palette and drop it between LabelStatus and ListBLE



- In the Palette window, click on Extension at the bottom, and then select "Import extension" and click on "URL."
 - Copy this URL and paste it in: http://iot.appinventor.mit.edu/assets/edu.mit.appinventor.iot.arduino101.aix
- Add the Arduino101Accelerometer extension to your app by dragging it onto the Viewer.

Next, we need to let App Inventor know which BLE device is reading the accelerometer data.

- Click on **Ardunio101Accelerometer1** in the Components pane. •
- In the Properties pane, click on BluetoothDevice and select **BluetoothLE1**.



Now switch to the Blocks Editor view

First, we want to request data updates when the accelerometer sensor values on the Arduino change.

 from Arduino101Accelerometer1 in the Blocks pane, add call Arduino101Accelerometer1.RequestAccelerometerDataUpdates to the existing when BluetoothLE1.Connected block from the Basic Connection tutorial.

```
when BluetoothLE1 . Connected

do set LabelStatus . Text to "Status: Connected "

set ListBLE . Visible to false

call Arduino101Accelerometer1 .RequestAccelerometerDataUpdates
```

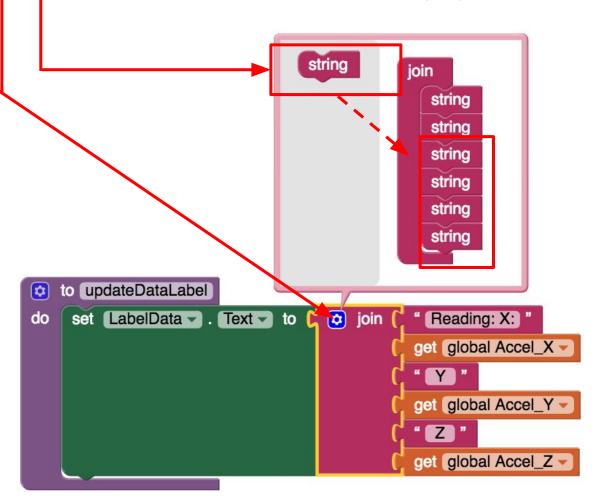
Next, we need to store the data we receive from the accelerometer. From the Variables drawer in the Blocks pane, drag an **initialize global name to** block and name it "Accel_X". From the Math drawer add a number block and set it to "0". We'll use this to keep track of the X-Axis value.

- Do this again, and rename the second variable "Accel_Y".
- Repeat a third time, and rename the third variable "Accel_Z".



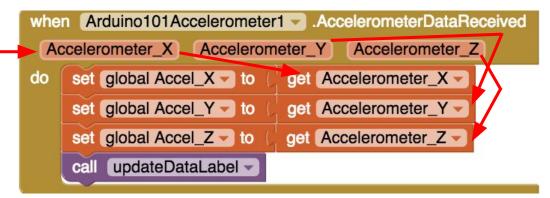
Let's make a new procedure to display the current readings in the **LabelData** when we get new data. You can create a procedure by dragging out a purple procedure block from the Procedures drawer in the Blocks pane. Let's rename it **updateDataLabel**.

- o from LabelData in the Blocks pane, add set LabelData.Text to.
- from the Text drawer connect a join block.
 - From the Text drawer, connect a text block and type"Reading: ".
 - From the Text drawer, connect a text block and type "X ". (note the extra space after the X)
 - We need 4 more slots in our **join** block.
 - Hover over the *gear* on the **join** block **5**
 - In the popup, attach four of the string blocks the two already there.
 - From the Variables drawer, connect a **get global Accel_X** block.
 - From the Text drawer, connect a text block and type "Y". (note the spaces before and after the Y)
 - From the Variables drawer, connect a get global Accel_Y block.
 - From the Text drawer, connect a text block and type " Z ". (note the spaces before and after the z)
 - From the Variables drawer, connect a **get global Accel_Z** block.



Finally, we need to call the procedure when this data is received.

- From the Arduino101Accelerometer1 drawer in the Blocks pane, drag when Ardunio101Accelerometer1.AccelerometerDataReceived
 - from the Variables drawer, add set global Accel_X to
 - Hover over the orange "Accelerometer_X" in
 .AccelerometerDataReceived to see the get Accelerometer_X block.
 Drag the get Accelerometer_X block from this window and snap to set global Accel_X.
 - Do the same thing for **Accel Y**.
 - Do the same thing for **Accel Z**.
 - from the Procedures drawer, add call updateDataLabel.



Your app should now be working! Connect your Android device using the MIT Al2 Companion (if you haven't already). Test it out by moving the Arduino around in the air. If it is working, you should see the data labels change.

