```
    HU21CSEN0300296, T.BHAVYA SHREE
```

```
1 # @title HU21CSEN0300296, T.BHAVYA SHREE
 2 from google.colab import drive
 3 drive.mount('/content/drive')
→ Mounted at /content/drive
loading the data
 1 # @title loading the data
 2 #loading the data
 3 import numpy as np
 4 import pandas as pd
 5 import os
 6 print(os.listdir("/content/drive/MyDrive/Dl"))
== ['test_dataset', 'validation_dataset', 'train_dataset', 'vgg_model.h5']

    Importing required libraries

 1 # @title Importing required libraries
 2 import numpy as np
 3 import matplotlib.pyplot as plt
 4 from tensorflow.keras.preprocessing import image
 5 import os
 6 from tensorflow.keras.preprocessing.image import ImageDataGenerator
 7 from tensorflow.keras.applications import VGG16
 8 from tensorflow.keras.models import Sequential
 9 from tensorflow.keras.layers import GlobalAveragePooling2D, Dense, Dropout
10 from tensorflow.keras.optimizers import Adam
11 from tensorflow.keras.callbacks import EarlyStopping
12 from tensorflow.keras.applications import InceptionV3
13
 1 !pip install python-resize-image

→ Collecting python-resize-image

       Downloading python_resize_image-1.1.20-py2.py3-none-any.whl (8.4 kB)
     Requirement already satisfied: Pillow>=5.1.0 in /usr/local/lib/python3.10/dist-packages (from python-resize-image) (9.4.0)
     Requirement already satisfied: requests>=2.19.1 in /usr/local/lib/python3.10/dist-packages (from python-resize-image) (2.31.0)
     Requirement already satisfied: charset-normalizer<4,>=2 in /usr/local/lib/python3.10/dist-packages (from requests>=2.19.1->python-re
     Requirement already satisfied: idna<4,>=2.5 in /usr/local/lib/python3.10/dist-packages (from requests>=2.19.1->python-resize-image)
     Requirement already satisfied: urllib3<3,>=1.21.1 in /usr/local/lib/python3.10/dist-packages (from requests>=2.19.1->python-resize-i
     Requirement already satisfied: certifi>=2017.4.17 in /usr/local/lib/python3.10/dist-packages (from requests>=2.19.1->python-resize-i
     Installing collected packages: python-resize-image
     Successfully installed python-resize-image-1.1.20
     4
 1 train_ds = train_datagen.flow_from_directory(
       train_dataset,
 2
 3
       class_mode='categorical',
 4
       shuffle=True,
 5
       batch_size=32,
       color_mode='rgb',
 7
       target_size=(224, 224),
 8
       subset='training
Found 18 images belonging to 3 classes.

    Exploratory data analysis

 1 # @title Exploratory data analysis
 2 # Checking class distribution in the training dataset
 3 class_counts = train_ds.classes
 4 unique_classes, class_counts = np.unique(class_counts, return_counts=True)
 5 class_distribution = dict(zip(train_ds.class_indices.keys(), class_counts))
 7 print("Class Distribution:")
 8 for cls, count in class_distribution.items():
       print(f"{cls}: {count} images")
\rightarrow Class Distribution:
     drone: 6 images
     flight: 6 images
     helicopter: 6 images
```

```
1 # Displaying sample images from each class
 2 plt.figure(figsize=(15, 10))
3 for i in range(len(train_ds.class_indices)):
      cls_name = list(train_ds.class_indices.keys())[i]
      cls_dir = os.path.join(train_dataset, cls_name)
      sample_img = os.listdir(cls_dir)[0]
6
7
      img_path = os.path.join(cls_dir, sample_img)
8
      plt.subplot(1, len(train_ds.class_indices), i+1)
9
10
      plt.imshow(image.load_img(img_path))
      plt.title(cls_name)
11
12
      plt.axis('off')
13 plt.show()
```

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drone







```
1 # Checking image dimensions
2 sample_img, _ = train_ds[0]
3 img_shape = sample_img[0].shape
4 print(f"Image Shape: {img_shape}")

Timage Shape: (224, 224, 3)

1 # Visualizing augmented images
2 augmented_images = [train_ds[0][0][0] for _ in range(5)]
3
4 plt.figure(figsize=(15, 5))
5 for i, img in enumerate(augmented_images):
6    plt.subplot(1, 5, i+1)
7    plt.imshow(img)
8    plt.axis('off')
9 plt.show()
```











```
1 # path to the test dataset
 2 test_dataset = "/content/drive/MyDrive/Dl/test_dataset/test_dataset/test_dataset"
3 class_name = list(os.listdir(test_dataset)[0])
5 # Initialize the ImageDataGenerator for testing (only rescaling)
 6 test_datagen = ImageDataGenerator(rescale=1./255)
8 # Load Test Data
9 test_ds = test_datagen.flow_from_directory(
      test_dataset,
10
11
      class_mode='categorical',
      shuffle=False,
12
      batch_size=1, # Adjust to the actual number of images in your test dataset
13
      color_mode='rgb',
```

```
target_size=(224, 224) # Adjust the target size for VGG16
16)
17
18 # Get a batch of images for visualization
19 sample_images, _ = next(test_ds)
20
21 # Visualize a few sample images
22 plt.figure(figsize=(15, 10))
23 for i in range(len(sample_images)):
      plt.subplot(1, len(sample_images), i + 1)
24
25
      plt.imshow(sample_images[i])
26
      plt.title(f"Class: {class_name[i]}")
27
      plt.axis('off')
28
29 plt.show()
```

Found 6 images belonging to 3 classes.

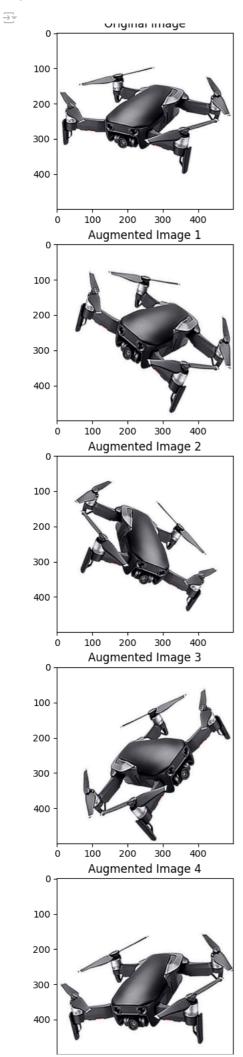


```
\ensuremath{\mathbf{1}} from keras.preprocessing import image
    2 from keras.preprocessing.image import ImageDataGenerator
    3 import numpy as np
   4 import matplotlib.pyplot as plt
   6 # Path to your model and sample image
   7 model_path = '/content/drive/MyDrive/Dl/your_model.h5' # Replace with the path to your model
    8 sample_image_path = '/content/drive/MyDrive/Dl/test_dataset/test_dataset/ship/677562.jpg' # Replace with the path to your sample image_path = '/content/drive/MyDrive/Dl/test_dataset/test_dataset/ship/677562.jpg' # Replace with the path to your sample image_path = '/content/drive/MyDrive/Dl/test_dataset/test_dataset/ship/677562.jpg' # Replace with the path to your sample image_path = '/content/drive/MyDrive/Dl/test_dataset/test_dataset/ship/677562.jpg' # Replace with the path to your sample image_path = '/content/drive/MyDrive/Dl/test_dataset/test_dataset/ship/677562.jpg' # Replace with the path to your sample image_path = '/content/drive/MyDrive/Dl/test_dataset/ship/677562.jpg' # Replace with the path to your sample image_path = '/content/drive/MyDrive/Dl/test_dataset/ship/677562.jpg' # Replace with the path to your sample image_path = '/content/drive/MyDrive/Dl/test_dataset/ship/677562.jpg' # Replace with the path to your sample image_path = '/content/drive/MyDrive/Dl/test_dataset/ship/677562.jpg' # Replace with the path to your sample image_path = '/content/drive/MyDrive/Dl/test_dataset/ship/677562.jpg' # Replace with the path to your sample image_path = '/content/drive/MyDrive/Dl/test_dataset/ship/677562.jpg' # Replace with the path to your sample image_path = '/content/drive/MyDrive/Dl/test_dataset/ship/677562.jpg' # Replace with the your sample image_path = '/content/drive/MyDrive/Dl/test_dataset/ship/677562.jpg' # Replace with the your sample image_path = '/content/drive/MyDrive/Dl/test_dataset/ship/677562.jpg' # Replace with the your sample image_path = '/content/drive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/MyDrive/M
   9
10 # Load your model
11 from keras.models import load model
12 model = load_model(model_path)
13
14 # Load the sample image
15 sample_image = image.load_img(sample_image_path)
16 img_array = image.img_to_array(sample_image)
17 img_array = np.expand_dims(img_array, axis=0)
19 # ImageDataGenerator
20 datagen = ImageDataGenerator(
                       rotation range=40,
```

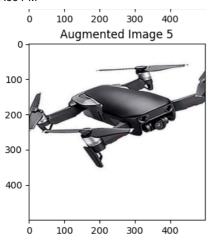
```
22
      width_shift_range=0.2,
23
      height shift range=0.2,
24
      shear range=0.2,
25
      zoom_range=0.2,
26
      horizontal flip=True,
27
      fill_mode='nearest'
28 )
29
30 # Generate augmented images
31 augmented_images = []
32
33 for batch in datagen.flow(img_array, batch_size=1):
       augmented_images.append(image.array_to_img(batch[0]))
34
35
       if len(augmented_images) >= 5: # Generate 5 augmented images
          break
36
37
38 # Display original and augmented images
39 plt.figure(figsize=(27, 4 * (len(augmented_images) + 1)))
40
41 # Original image
42 plt.subplot(len(augmented_images) + 1, 6, 1)
43 plt.imshow(sample_image)
44 plt.title('Original Image')
45
46 # Augmented images on separate lines
47 for i, augmented img in enumerate(augmented images):
      plt.subplot(len(augmented_images) + 1, 6, 6 * (i + 1) + 1)
      plt.imshow(augmented_img)
49
50
       plt.title(f'Augmented Image {i + 1}')
52 # Prediction on original and augmented images
53 plt.subplot(len(augmented_images) + 1, 6, 6)
54 original prediction = model.predict(img array)
55 \ plt.text(0,\ 0.5,\ f'Prediction:\ \{original\_prediction\}',\ fontsize=12,\ va='center'\}
57 for i, augmented_img in enumerate(augmented_images):
58
      plt.subplot(len(augmented_images) + 1, 6, 6 * (i + 1) + 6)
      augmented_img_array = image.img_to_array(augmented_img)
60
       augmented_img_array = np.expand_dims(augmented_img_array, axis=0)
61
       augmented_prediction = model.predict(augmented_img_array)
62
      plt.text(0, 0.5, f'Prediction: {augmented prediction}', fontsize=12, va='center')
63
64 plt.show()
65
1 from keras.preprocessing import image
 2 from keras.preprocessing.image import ImageDataGenerator
 3 import numpy as np
4 import matplotlib.pyplot as plt
6 sample_image_path = '/content/drive/MyDrive/Dl/train_dataset/train_dataset/train_dataset/drone/drone 1.png'
 7 sample_image = image.load_img(sample_image_path)
 8 img array = image.img to array(sample image)
9 img_array = np.expand_dims(img_array, axis=0)
11 #ImageDataGenerator
12 datagen = ImageDataGenerator(
      rotation_range=40,
13
14
      width_shift_range=0.2,
15
      height_shift_range=0.2,
      shear range=0.2,
16
17
      zoom_range=0.2,
      horizontal_flip=True,
18
      fill_mode='nearest'
19
20)
21
22 # Generate augmented images
23 augmented_images = []
24
25 for batch in datagen.flow(img_array, batch_size=1):
26
      augmented_images.append(image.array_to_img(batch[0]))
27
       if len(augmented_images) >= 5: # Generate 5 augmented images
28
          break
29
30 #original and augmented images
31 plt.figure(figsize=(27, 4 * (len(augmented_images) + 1))) # Adjust the height
32
33 #original image
34 plt.subplot(len(augmented images) + 1, 6, 1)
35 plt.imshow(sample_image)
36 plt.title('Original Image')
37
```

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```
38 # augmented image are then displayed on seperate lines for better visibility
39 for i, augmented_img in enumerate(augmented_images):
40    plt.subplot(len(augmented_images) + 1, 6, 6 * (i + 1) + 1)
41    plt.imshow(augmented_img)
42    plt.title(f'Augmented Image {i + 1}')
43
44 #The augmentation includes random rotations, shifts, shearing, zooming, and horizontal flipping
45 plt.show()
```



 $\overline{\Rightarrow}$ 



```
1 from PIL import Image
  2 \text{ image\_path = '/content/drive/MyDrive/Dl/train\_dataset/train\_dataset/train\_dataset/drone/drone 1.png'} \\
 3 pil_image = Image.open(image_path)
 5 #PIL image to NumPy array
 6 image_array = np.array(pil_image)
8 #plot of original ship image
 9 plt.figure(figsize=(10, 5))
10 plt.subplot(1, 2, 1)
11 plt.imshow(image_array)
12 plt.title('Original Image')
13 plt.axis('off')
14
15 #The second plot with interpolation (has smoothing effect applied by the 'hanning' interpolation)
16 plt.figure(figsize=(5, 4))
17 plt.imshow(image_array, interpolation='hanning')
18 plt.axis('off')
19 plt.show()
```

### Original Image





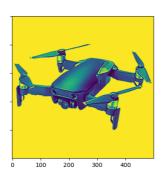
```
1 i, (im1, im2, im3, im4) = plt.subplots(1, 4, sharey=True)
2 i.set_figwidth(20)
```

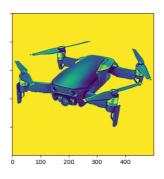
```
3
4 im1.imshow(image_array,interpolation='hanning') #Original image
5 im2.imshow(image_array[:, : , 0],interpolation='hanning') #Red channel
6 im3.imshow(image_array[:, : , 1],interpolation='hanning') #Green channel
7 im4.imshow(image_array[:, : , 2],interpolation='hanning') #Blue channel
8 i.suptitle('Original & RGB image channels')
```

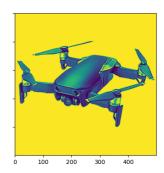
→ Text(0.5, 0.98, 'Original & RGB image channels')

#### Original & RGB image channels



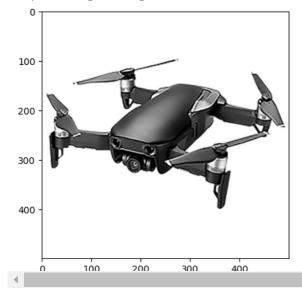






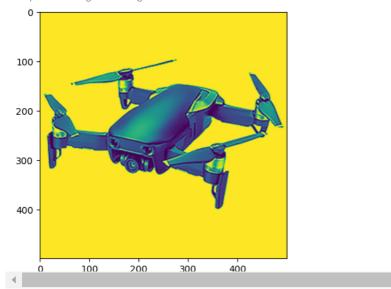
```
1 #convert the original RGB image to a grayscale image
2 # used to visualize the intensity (luminance) of an image without considering color information
3 from skimage import io
4 import skimage
5 gray_image = skimage.color.rgb2gray(image_array[:,:,:3])
6 plt.imshow(gray_image, cmap = 'gray',interpolation='hanning')
```

<matplotlib.image.AxesImage at 0x7bb87e0bf9d0>

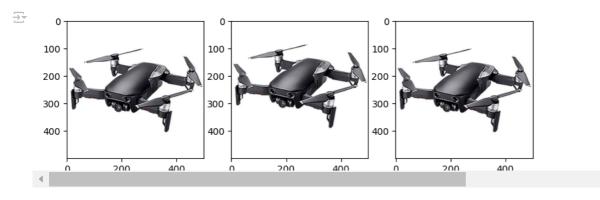


```
1 norm_image = (gray_image - np.min(gray_image)) / (np.max(gray_image) - np.min(gray_image))
2 plt.imshow(norm_image,interpolation='hanning')
```

<matplotlib.image.AxesImage at 0x7bb878733820>



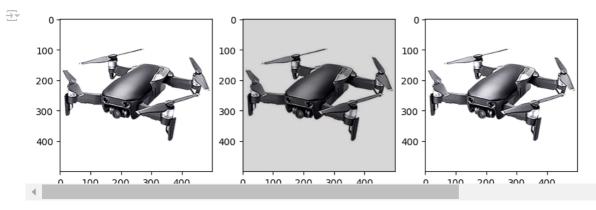
```
1 # Import libraries and use Keras' ImageDataGenerator for image data augmentation
 2 from numpy import expand_dims
 3 from keras.preprocessing.image import load_img
4 from keras.preprocessing.image import ImageDataGenerator
 5 import matplotlib.pyplot as plt
7 # Expand dimension to one sample
 8 samples = expand dims(image array, 0)
10 # Create image data augmentation generator
11 datagen = ImageDataGenerator(width_shift_range=[5, 10])
12
13 # Create an iterator
14 it = datagen.flow(samples, batch_size=1)
15 fig, im = plt.subplots(nrows=1, ncols=3, figsize=(9, 5))
16
17 # Generate batch of images
18 for i in range(3):
19
      # Convert to unsigned integers
20
      images = next(it)[0].astype('uint8')
21
       # Plot image
22
23
       im[i].imshow(images, interpolation='hanning')
24
25 plt.show()
26
```



```
1 datagen = ImageDataGenerator(horizontal_flip=True, vertical_flip=True)
3 # create an iterator
4 it = datagen.flow(samples, batch_size=1)
5 fig, im = plt.subplots(nrows=1, ncols=3, figsize=(10,10))
6
7 # generate batch of images
8 for i in range(3):
9
10
      # convert to unsigned integers
11
      images = next(it)[0].astype('uint8')
12
13
      # plot image
      im[i].imshow(images,interpolation='hanning')
14
```

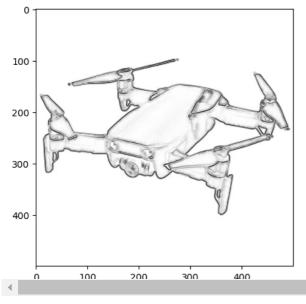
```
\overline{z}
                                                  0
                                                                                            0
                                                100
       100
                                                                                          100
      200
                                                200
                                                                                          200
                                                                                          300
       300
                                                300
       400
                                                400
                                                                                          400
                 100
                        200
                               300
                                      400
                                                          100
                                                                 200
                                                                        300
                                                                               400
                                                                                                    100
                                                                                                           200
                                                                                                                  300
                                                                                                                         400
     - ◀
```

```
1 # ImageDataGenerator for brightness
2 datagen = ImageDataGenerator(brightness_range=[0.3,2.0])
3 # create an iterator
4 it = datagen.flow(samples, batch_size=1)
5 fig, im = plt.subplots(nrows=1, ncols=3, figsize=(10,10))
7 # generate batch of images
8 for i in range(3):
10
      # convert to unsigned integers
11
      images = next(it)[0].astype('uint8')
12
13
      # plot image
14
      im[i].imshow(images,interpolation='hanning')
```



```
1 from skimage import io, filters, color, data
2 import os
3 plt.figure(figsize=(5,5))
4 img_sobel = filters.sobel(norm_image)
5 plt.imshow(1-img_sobel, cmap="gray")
```

<matplotlib.image.AxesImage at 0x7bb877b28280>



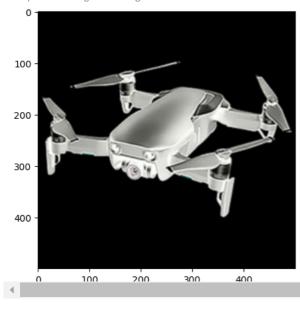
```
1 plt.figure(figsize=(5,5))
2 img_prewit = filters.prewitt(norm_image)
3 plt.imshow(1-img_prewit, cmap="gray")
```

<matplotlib.image.AxesImage at 0x7bb8785372e0>

```
200 - 300 - 400
```

```
1 plt.figure(figsize=(5,5))
2 img_gau = filters.gaussian(image_array,channel_axis=-1)
3 plt.imshow(1-img_gau)
```

#### <matplotlib.image.AxesImage at 0x7bb8786d43d0>



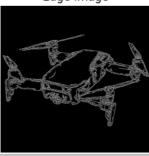
```
1 #canny edge detection
 2 import cv2 as cv
3 def hist(histimg):
4
       ycrcb = cv.cvtColor(image_array, cv.COLOR_RGB2YCR_CB)
5
       channels = cv.split(ycrcb)
6
      cv.equalizeHist(channels[0], channels[0])
      cv.merge(channels, ycrcb)
      cv.cvtColor(ycrcb, cv.COLOR_YCR_CB2RGB, histimg)
8
9
       return histimg
10
11 dehizing = hist(norm_image)
12
13 edges = cv.Canny(image_array,50,100)
14
15 plt.subplot(121),plt.imshow(image_array,cmap = 'gray')
16 plt.title('Original Image'), plt.xticks([]), plt.yticks([])
17 plt.subplot(122),plt.imshow(edges,cmap = 'gray')
18 plt.title('Edge Image'), plt.xticks([]), plt.yticks([])
19
20 plt.show()
```



## Original Image



### Edge Image



## Path for traning, testing and validation datasets

```
1 # @title Path for traning,testing and validation datasets
2 train_dataset = "/content/drive/MyDrive/Dl/train_dataset/train_dataset/train_dataset"
3 test_dataset = "/content/drive/MyDrive/Dl/test_dataset/test_dataset/test_dataset"
4 validation_dataset = "/content/drive/MyDrive/Dl/validation_dataset/validation_dataset/validation_dataset
```

#### Image preprocessing

```
1 # @title Image preprocessing
2 train_datagen = ImageDataGenerator(
3    rescale=1./255,
4    rotation_range=20,
5    horizontal_flip=True,
6    validation_split=0.1
7 )
```

## loading data

```
1 # @title loading data
3 train_ds = train_datagen.flow_from_directory(
4
      train_dataset,
5
      class_mode='categorical',
6
      shuffle=True,
      batch_size=32,
8
      color_mode='rgb',
9
      target_size=(224, 224), # Adjust the target size for VGG16
10
      subset='training'
11 )
12
13 valid_ds = train_datagen.flow_from_directory(
14
      validation_dataset,
15
      class_mode='categorical',
      shuffle=True,
16
17
      batch_size=32,
18
      color mode='rgb',
      target_size=(224, 224), # Adjust the target size for VGG16
19
       subset='validation'
20
21 )
     Found 18 images belonging to 3 classes.
     Found 0 images belonging to 3 classes.
```

## ∨ VGG16 Model

```
1 # @title VGG16 Model
 2 from tensorflow.keras.applications import VGG16
 3 base_model = VGG16(include_top=False, input_shape=(224, 224, 3)) # Change the model to VGG16
4 base_model.trainable = False
6 # Model Architecture
7 model = Sequential([
     base_model,
9
      GlobalAveragePooling2D(),
10
      Dense(256, activation='relu', kernel_initializer='he_normal'),
11
      Dropout(0.4),
12
      Dense(len(train_ds.class_indices), activation='softmax')
13 ], name="VGG16-TL")
14
15 model.summary()
```

20

```
17 # Compiling Model
18 model.compile(
    loss='categorical_crossentropy',
19
    optimizer=Adam(),
    metrics=['accuracy']
21
22 )
23 callbacks = [EarlyStopping(patience=3, restore_best_weights=True)]
24 history = model.fit(train_ds, validation_data=valid_ds, epochs=10, callbacks=callbacks)
→ Model: "VGG16-TL"
    Layer (type)
                       Output Shape
                                          Param #
    vgg16 (Functional)
                       (None, 7, 7, 512)
                                          14714688
    global_average_pooling2d_6 (None, 512)
     (GlobalAveragePooling2D)
    dense_12 (Dense)
                       (None, 256)
                                          131328
    dropout 6 (Dropout)
                       (None, 256)
    dense 13 (Dense)
                       (None, 3)
                                          771
   Total params: 14846787 (56.64 MB)
   Trainable params: 132099 (516.01 KB)
   Non-trainable params: 14714688 (56.13 MB)
   1/1 [=========] - ETA: 0s - loss: 1.2802 - accuracy: 0.2778WARNING:tensorflow:Early stopping conditioned on met
   1/1 [==========] - ETA: 0s - loss: 1.2561 - accuracy: 0.2778WARNING:tensorflow:Early stopping conditioned on met
   1/1 [=========] - 12s 12s/step - loss: 1.2561 - accuracy: 0.2778
   Epoch 3/10
   1/1 [=========] - ETA: 0s - loss: 1.1706 - accuracy: 0.3889WARNING:tensorflow:Early stopping conditioned on me1
   Epoch 4/10
   1/1 [=========] - ETA: 0s - loss: 1.1109 - accuracy: 0.3889WARNING:tensorflow:Early stopping conditioned on med
   Epoch 5/10
   1/1 [===========] - ETA: 0s - loss: 0.8140 - accuracy: 0.7222WARNING:tensorflow:Early stopping conditioned on met
   Epoch 6/10
   1/1 [========] - ETA: 0s - loss: 1.1160 - accuracy: 0.4444WARNING:tensorflow:Early stopping conditioned on met
   Fnoch 7/10
   1/1 [========] - ETA: 0s - loss: 0.8825 - accuracy: 0.7778WARNING:tensorflow:Early stopping conditioned on med 1/1 [=======] - 12s 12s/step - loss: 0.8825 - accuracy: 0.7778
   Epoch 8/10
   1/1 [============] - ETA: 0s - loss: 0.8168 - accuracy: 0.6667WARNING:tensorflow:Early stopping conditioned on met
   1/1 [==========] - ETA: 0s - loss: 0.7871 - accuracy: 0.5556WARNING:tensorflow:Early stopping conditioned on met
   Enoch 10/10
   1/1 [=======] - ETA: 0s - loss: 0.9508 - accuracy: 0.6111WARNING:tensorflow:Early stopping conditioned on met
```

### Testing accuray and loss of VGG16 Model

```
1 # @title Testing accuray and loss of VGG16 Model
 2 # Load the test dataset
 3 test datagen = ImageDataGenerator(rescale=1./255)
 5 test_ds = test_datagen.flow_from_directory(
6
     test dataset.
7
     class_mode='categorical',
     shuffle=False,
 8
9
     batch size=32,
10
     color mode='rgb',
      target_size=(224, 224) # Adjust the target size for VGG16
11
12)
13
14 # Evaluate the model on the test dataset
15 test_loss, test_accuracy = model.evaluate(test_ds)
16
17 print(f'Test Loss: {test_loss:.4f}')
18 print(f'Test Accuracy: {test_accuracy * 100:.2f}%')
    Found 6 images belonging to 3 classes.
    Test Loss: 0.8455
```

Test Accuracy: 100.00%

# Testing the VGG16 Model

```
1 # @title Testing the VGG16 Model
 2 # Set the path to your test dataset
 3 test_dataset = "/content/drive/MyDrive/Dl/test_dataset/test_dataset/test_dataset"
5 # Initialize the ImageDataGenerator for testing (only rescaling)
 6 test_datagen = ImageDataGenerator(rescale=1./255)
8 # Load Test Data
9 test_ds = test_datagen.flow_from_directory(
10
     test dataset,
     class_mode='categorical',
     shuffle=False,
12
     batch_size=1, # Adjust to the actual number of images in your test dataset
13
14
     color mode='rgb',
15
      target_size=(224, 224) # Adjust the target size for VGG16
16)
17
18 # Get class indices
19 class_indices = {v: k for k, v in test_ds.class_indices.items()}
20
21 # Visualize predictions on a few test images
22 plt.figure(figsize=(15, 10))
23 for i in range(len(test_ds)):
     plt.subplot(4, 5, i+1)
      img, true_label = test_ds[i]
25
26
      pred_probs = model.predict(img)
27
      pred_label = np.argmax(pred_probs, axis=1)[0]
28
29
      plt.imshow(img[0])
      plt.title(f"True: {class_indices[true_label[0].argmax()]}\nPred: {class_indices[pred_label]}")
30
31
      plt.axis('off')
33 plt.tight_layout()
34 plt.show()
   Found 6 images belonging to 3 classes.
    1/1 [======] - 1s 933ms/step
    1/1 [======= ] - 0s 477ms/step
    1/1 [======] - 0s 492ms/step
    1/1 [======= 1 - 0s 481ms/sten
    1/1 [=======] - 0s 491ms/step
    1/1 [======] - 0s 495ms/step
                                                              True: flight
         True: drone
                                   True: drone
                                                                                         True: flight
                                                                                                                 True: helicopter
                                   Pred: drone
                                                              Pred: fliaht
                                                                                         Pred: fliaht
                                                                                                                 Pred: helicopter
        True: helicopter
        Pred: helicopter
```

## ∨ InceptionV3 Model

<sup>1</sup> from tensorflow.keras.applications import InceptionV3
2 # Set the paths to your dataset
3 train\_dataset = "/content/drive/MyDrive/Dl/train\_dataset/train\_dataset/train\_dataset"
4 test\_dataset = "/content/drive/MyDrive/Dl/test\_dataset/test\_dataset/test\_dataset"
5 validation\_dataset = "/content/drive/MyDrive/Dl/validation\_dataset/validation\_dataset/validation\_dataset

```
1 # @title InceptionV3 Model
 2 # Load Pretrained InceptionV3 Model
 3 base_model = InceptionV3(include_top=False, input_shape=(256, 256, 3))
 4 base model.trainable = False
 6 # Model Architecture
 7 model = Sequential([
 8
       base model.
9
        GlobalAveragePooling2D(),
        Dense(256, activation='relu', kernel_initializer='he_normal'),
10
11
        Dropout(0.4),
        Dense(len(train_ds.class_indices), activation='softmax')
13 ], name="Inception-TL")
14
15 model.summarv()
16
17 # Compile Model
18 model.compile(
19
       loss='categorical_crossentropy',
20
        optimizer=Adam(),
        metrics=['accuracy']
21
22 )
23
24 # Callbacks
25 callbacks = [EarlyStopping(patience=3, restore_best_weights=True)]
26
27 # Model Training
28 history = model.fit(train_ds, validation_data=valid_ds, epochs=10, callbacks=callbacks)
     Downloading data from <a href="https://storage.googleapis.com/tensorflow/keras-applications/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/inception_v3/ince
      87910968/87910968 [=========== ] - 1s Ous/step
      Model: "Inception-TL"
                                          Output Shape
       Layer (type)
       inception v3 (Functional) (None, 6, 6, 2048)
                                                                           21802784
       global_average_pooling2d_1 (None, 2048)
                                                                           0
        (GlobalAveragePooling2D)
       dense_2 (Dense)
                                          (None, 256)
                                                                           524544
       dropout_1 (Dropout)
                                          (None, 256)
                                                                           0
       dense 3 (Dense)
                                          (None, 3)
      ______
      Total params: 22328099 (85.17 MB)
      Trainable params: 525315 (2.00 MB)
      Non-trainable params: 21802784 (83.17 MB)
      Epoch 1/10
      =============] - ETA: 0s - loss: 0.6912 - accuracy: 0.7222WARNING:tensorflow:Early stopping conditioned on met
      1/1 [=====
      Epoch 3/10
      1/1 [=========] - ETA: 0s - loss: 0.3377 - accuracy: 0.8889WARNING:tensorflow:Early stopping conditioned on met
      Epoch 4/10
      1/1 [=========] - ETA: 0s - loss: 0.2638 - accuracy: 0.8889WARNING:tensorflow:Early stopping conditioned on met
      Epoch 5/10
      1/1 [=========] - ETA: 0s - loss: 0.1216 - accuracy: 0.9444WARNING:tensorflow:Early stopping conditioned on met
      1/1 [=====
                           ==========] - ETA: 0s - loss: 0.1675 - accuracy: 0.9444WARNING:tensorflow:Early stopping conditioned on met
      1/1 [========== ] - 3s 3s/step - loss: 0.1675 - accuracy: 0.9444
      Epoch 7/10
      1/1 [========] - ETA: 0s - loss: 0.0291 - accuracy: 1.0000WARNING:tensorflow:Early stopping conditioned on med 1/1 [=======] - 4s 4s/step - loss: 0.0291 - accuracy: 1.0000
      Epoch 8/10
      1/1 [=========] - ETA: 0s - loss: 0.0317 - accuracy: 1.0000WARNING:tensorflow:Early stopping conditioned on me1
      1/1 [============ ] - 5s 5s/step - loss: 0.0317 - accuracy: 1.0000
      1/1 [=====
                          ==========] - ETA: 0s - loss: 0.0120 - accuracy: 1.0000WARNING:tensorflow:Early stopping conditioned on met
      Epoch 10/10
                          1/1 [======
```

Testing the InceptionV3 Model

```
1 # @title Testing the InceptionV3 Model
 2 # Set the path to your test dataset
3 test_dataset = "/content/drive/MyDrive/D1/test_dataset/test_dataset/test_dataset"
 5 # Initialize the ImageDataGenerator for testing (only rescaling)
 6 test_datagen = ImageDataGenerator(rescale=1./255)
8 # Load Test Data
9 test_ds = test_datagen.flow_from_directory(
10
     test_dataset,
11
     class_mode='categorical',
     shuffle=False,
     batch_size=1, # Adjust to the actual number of images in your test dataset
13
14
     color_mode='rgb',
     target_size=(256, 256)
15
16)
17
18 # Evaluate the model on the test set
19 test_loss, test_accuracy = model.evaluate(test_ds)
20 print(f'InceptionV3 Test Loss: {inception_test_loss:.4f}')
21 print(f'InceptionV3 Test Accuracy: {inception_test_accuracy * 100:.2f}%')
22 # Get class indices
23 class indices = {v: k for k, v in test ds.class indices.items()}
24
25 # Visualize predictions on a few test images
26 plt.figure(figsize=(15, 10))
27 for i in range(len(test_ds)):
     plt.subplot(4, 5, i+1)
28
29
     img, true_label = test_ds[i]
30
     pred_probs = model.predict(img)
     pred_label = np.argmax(pred_probs, axis=1)[0]
31
32
33
      plt.imshow(img[0])
      plt.title(f"True: \{class\_indices[true\_label[0].argmax()]\} \\ \ \ \{class\_indices[pred\_label]\}")
34
35
      plt.axis('off')
36
37 plt.tight_layout()
38 plt.show()
   Found 6 images belonging to 3 classes.
    InceptionV3 Test Loss: 0.8455
    InceptionV3 Test Accuracy: 100.00%
    1/1 [======] - 1s 782ms/step
    1/1 [======] - 1s 640ms/step
    1/1 [======] - 1s 632ms/step
    1/1 [=======] - 1s 622ms/step
                                                          True: flight
                                                                                   True: flight
                                                                                                          True: helicopter
         True: drone
                                 True: drone
                                                                                   Pred: flight
                                                                                                          Pred: helicopter
                                 Pred: drone
       True: helicopter
       Pred: helicopter
```

#### Comparing the VGG16 and InceptionV3

```
1 # @title Comparing the VGG16 and InceptionV3
2 import numpy as np
3 import matplotlib.pyplot as plt
4 from sklearn.metrics import confusion_matrix, classification_report
5 # Evaluate the VGG16 model on the test set
```

```
6 vgg_test_loss, vgg_test_accuracy = model.evaluate(test_ds)
 7 print(f'VGG16 Test Loss: {vgg_test_loss:.4f}')
 8 print(f'VGG16 Test Accuracy: {vgg_test_accuracy * 100:.2f}%')
10 # Evaluate the InceptionV3 model on the test set
11 inception_test_loss, inception_test_accuracy = model.evaluate(test_ds)
12 print(f'InceptionV3 Test Loss: {inception_test_loss:.4f}')
13 print(f'InceptionV3 Test Accuracy: {inception_test_accuracy * 100:.2f}%')
   VGG16 Test Loss: 0.8455
    VGG16 Test Accuracy: 100.00%
    6/6 [===========] - 5s 837ms/step - loss: 0.8455 - accuracy: 1.0000
    InceptionV3 Test Loss: 0.8455
    InceptionV3 Test Accuracy: 100.00%
1 # VGG16 Model
3 # Load Pretrained VGG16 Model
4 base_model_vgg16 = VGG16(include_top=False, input_shape=(224, 224, 3)) # Change the model to VGG16
 5 base_model_vgg16.trainable = False
6
7 # Model Architecture
 8 model_vgg16 = Sequential([
     base_model_vgg16,
9
10
      GlobalAveragePooling2D(),
11
      Dense(256, activation='relu', kernel initializer='he normal'),
12
      Dropout(0.4),
      Dense(len(train_ds.class_indices), activation='softmax')
14 ], name="VGG16-TL")
15
16 model_vgg16.summary()
17
18 # Compile Model
19 model_vgg16.compile(
20
     loss='categorical_crossentropy',
21
      optimizer=Adam(),
      metrics=['accuracy']
22
23 )
24
25 # Training for VGG16
26 history_vgg16 = model_vgg16.fit(train_ds, validation_data=valid_ds, epochs=10, callbacks=callbacks)
27
28 # InceptionV3 Model
30 # Load Pretrained InceptionV3 Model
31 base_model_inception = InceptionV3(include_top=False, input_shape=(256, 256, 3))
32 base_model_inception.trainable = False
33
34 # Model Architecture
35 model inception = Sequential([
      base_model_inception,
36
37
      GlobalAveragePooling2D(),
38
      Dense(256, activation='relu', kernel_initializer='he_normal'),
39
      Dropout(0.4),
40
      Dense(len(train_ds.class_indices), activation='softmax')
41 ], name="Inception-TL")
43 model_inception.summary()
44
45 # Compile Model
46 model_inception.compile(
47
      loss='categorical_crossentropy',
48
      optimizer=Adam(),
49
      metrics=['accuracy']
50)
51
52 # Training for InceptionV3
53 history_inception = model_inception.fit(train_ds, validation_data=valid_ds, epochs=10, callbacks=callbacks)
54
55 # Evaluation
56
57 # Predict and evaluate on the training set for VGG16
58 train_accuracy_vgg16 = model_vgg16.evaluate(train_ds)[1]
59 print(f"Train Accuracy (VGG16): {train_accuracy_vgg16}")
61 # Predict and evaluate on the test set for VGG16
62 test_accuracy_vgg16 = model_vgg16.evaluate(test_ds)[1]
63 print(f"Test Accuracy (VGG16): {test_accuracy_vgg16}")
64
65 # Predict and evaluate on the training set for InceptionV3
66 train_accuracy_inception = model_inception.evaluate(train_ds)[1]
67 nnint/f"Thain Accuracy (Throntion)/2). Sthain accuracy incention)"
```

```
DL USECASE 1 HU21CSEN0300296.ipynb - Colab
or prince ir air accuracy (inceptions). [crain_accuracy_inception]
68
69 # Predict and evaluate on the test set for InceptionV3
70 test_accuracy_inception = model_inception.evaluate(test_ds)[1]
71 print(f"Test Accuracy (InceptionV3): {test_accuracy_inception}")
72
→ Model: "VGG16-TL"
       Layer (type)
                                         Output Shape
                                                                         Param #
      _____
       vgg16 (Functional)
                                         (None, 7, 7, 512)
                                                                         14714688
       global_average_pooling2d_9 (None, 512)
        (GlobalAveragePooling2D)
       dense 18 (Dense)
                                         (None, 256)
                                                                         131328
       dropout 9 (Dropout)
                                         (None, 256)
       dense 19 (Dense)
                                                                         771
                                         (None, 3)
      Total params: 14846787 (56.64 MB)
      Trainable params: 132099 (516.01 KB)
      Non-trainable params: 14714688 (56.13 MB)
      1/1 [==========] - ETA: 0s - loss: 1.1013 - accuracy: 0.2778WARNING:tensorflow:Early stopping conditioned on
      Enoch 2/10
                       ==========] - ETA: 0s - loss: 1.1338 - accuracy: 0.3889WARNING:tensorflow:Early stopping conditioned on
      1/1 [=====
      Epoch 3/10
      Epoch 4/10
      1/1 [=========] - ETA: 0s - loss: 0.9937 - accuracy: 0.3333WARNING:tensorflow:Early stopping conditioned on
      Epoch 5/10
      1/1 [========] - ETA: 0s - loss: 0.9740 - accuracy: 0.5556WARNING:tensorflow:Early stopping conditioned on
      Epoch 6/10
      1/1 [=========] - ETA: 0s - loss: 0.7966 - accuracy: 0.6111WARNING:tensorflow:Early stopping conditioned on 1/1 [========] - 10s 10s/step - loss: 0.7966 - accuracy: 0.6111
      Epoch 7/10
      1/1 [=========] - ETA: 0s - loss: 0.8530 - accuracy: 0.5556WARNING:tensorflow:Early stopping conditioned on
      1/1 [=====
      Epoch 9/10
      Enoch 10/10
      1/1 \; [\texttt{===========}] \; - \; \texttt{ETA: 0s - loss: 0.9792 - accuracy: 0.5556WARNING:} \\ \texttt{tensorflow:Early stopping conditioned on loss: 0.9792 - accuracy: 0.5556WARNING:} \\ \texttt{tensorflow:Early stopping conditioned on loss: 0.9792 - accuracy: 0.5556WARNING:} \\ \texttt{tensorflow:Early stopping conditioned on loss: 0.9792 - accuracy: 0.5556WARNING:} \\ \texttt{tensorflow:Early stopping conditioned on loss: 0.9792 - accuracy: 0.5556WARNING:} \\ \texttt{tensorflow:Early stopping conditioned on loss: 0.9792 - accuracy: 0.5556WARNING:} \\ \texttt{tensorflow:Early stopping conditioned on loss: 0.9792 - accuracy: 0.5556WARNING:} \\ \texttt{tensorflow:Early stopping conditioned on loss: 0.9792 - accuracy: 0.5556WARNING:} \\ \texttt{tensorflow:Early stopping conditioned on loss: 0.9792 - accuracy: 0.5556WARNING:} \\ \texttt{tensorflow:Early stopping conditioned on loss: 0.9792 - accuracy: 0.5556WARNING:} \\ \texttt{tensorflow:Early stopping conditioned on loss: 0.9792 - accuracy: 0.5556WARNING:} \\ \texttt{tensorflow:Early stopping conditioned on loss: 0.9792 - accuracy: 0.5556WARNING:} \\ \texttt{tensorflow:Early stopping conditioned on loss: 0.9792 - accuracy: 0.5556WARNING:} \\ \texttt{tensorflow:Early stopping conditioned on loss: 0.9792 - accuracy: 0.979
      Model: "Inception-TL"
       Layer (type)
                                         Output Shape
                                                                         Param #
      _____
       inception_v3 (Functional) (None, 6, 6, 2048)
                                                                         21802784
```

```
1 # Classification metrics and confusion matrix
 2 from sklearn.metrics import classification_report, confusion_matrix
 3 import matplotlib.pyplot as plt
4 import seaborn as sns
 5 import numpy as np
6
7 # Function to plot training history
 8 def plot_training_history(history, model_name):
9
      plt.figure(figsize=(12, 4))
10
11
       # Plot training & validation accuracy values
12
      plt.subplot(1, 2, 1)
13
       plt.plot(history.history['accuracy'])
      plt.plot(history.history['val accuracy'])
14
15
      plt.title(f'{model_name} Model Accuracy')
16
      plt.xlabel('Epoch')
      plt.ylabel('Accuracy')
17
18
      plt.legend(['Train', 'Validation'], loc='upper left')
19
       # Plot training & validation loss values
20
      plt.subplot(1, 2, 2)
```

global average pooling2d 1 (None, 2048)

4