

# Practical 2: The Unix shell and RPi Hardware

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## Abstract

In embedded systems development, engineers are concerned with both the software and hardware aspects of the system. In the implementation stage, a key decision to be made is the choice of programming language to implement the embedded software. This practical explores the significant things to consider when making such a decision. Furthermore this practical explores the concept of optimising programs execution time by using multiple threads, compiler flags, and data types. Hence finding the right combination of a number of threads, compiler flags, and data types to achieve great program speedup.

## 1 Introduction

This practical explores the core fundamental concepts of developing embedded systems used in the embedded systems industry. The main focus is to draw out the importance of choosing a programming language when developing embedded systems with limited resources. This practical will show how using different languages can impact the performance of the program. The key to take away from this practical is the awareness of the optimisation concepts and the ability to use good practise when bench-marking. When using threads to achieve speed up, using too many or too few threads is not always ideal, too many threads can lead to overhead, and using too few threads may not achieve any speed up at all. Finding the right number of threads to achieves speed up is crucial.

## 2 Methodology

### 2.1 Hardware

The hardware used is raspberry pi Zero, which has a 1GHz single-core CPU, 512MB RAM, Mini HDMI port, Micro USB OTG port, Micro USB power, HAT-compatible 40-pin header, Composite video and reset headers, and CSI camera connector (v1.3 only).

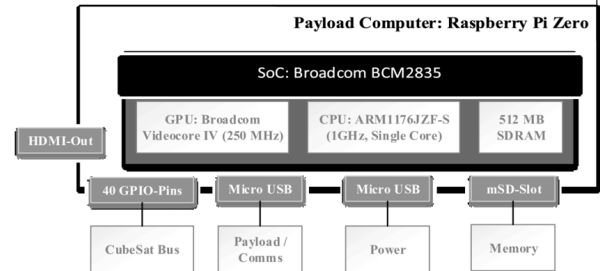


Figure 1: A Raspberry pi Zero

### 2.2 Implementation

Firstly a golden measure was established in python. This is the program used as a point of comparison, comparing its execution speed to the same program written in C/C++. This helps in showing how using different programming languages can impact the performance of a program. A quest to try and improve the performance of the C/C++ code as much as possible, by using different bit widths, compiler flags and threading is the end goal.

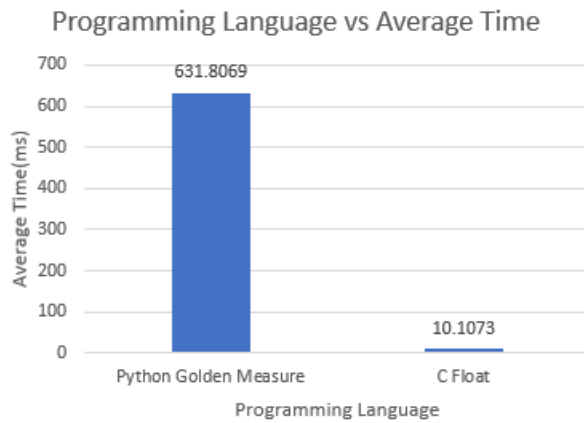
### 2.3 Experiment Procedure

Steps:

1. Run the Python code 10 times, record time for each run and calculate the average to establish a golden measure. See the table [3.2]
2. Compile and Run the unthreaded C code 10 times, record time for each run and calculate the average. See the table [3.2]
3. Compile and Run the threaded C code for 2 threads, 4 threads, 8 threads, 16 threads, and 32 threads 10 times, record time for each run, and calculate the average. See the table [3.2]
4. Compile and Run the C code using 7 different compiler flags, record time for each run and calculate the average. See the table [3.2]
5. Compile and Run the C code using 3 bit-widths: double, float, and \_\_fp16 data types 10 times, record time for each run and calculate the average. See the table [3.2]

## 3 Results

### 3.1 Figures



The figure 2 on the left shows how the C programming language outperforms the python program even though these are the exact same programs written in different programming languages. This is because when running the Python script, its interpreter will interpret the script line by line and generate output but in C, the compiler will first compile it and generate an output which is optimized with respect to the hardware and operating system.

Figure 2: Program execution time of python golden measure compared to the C program

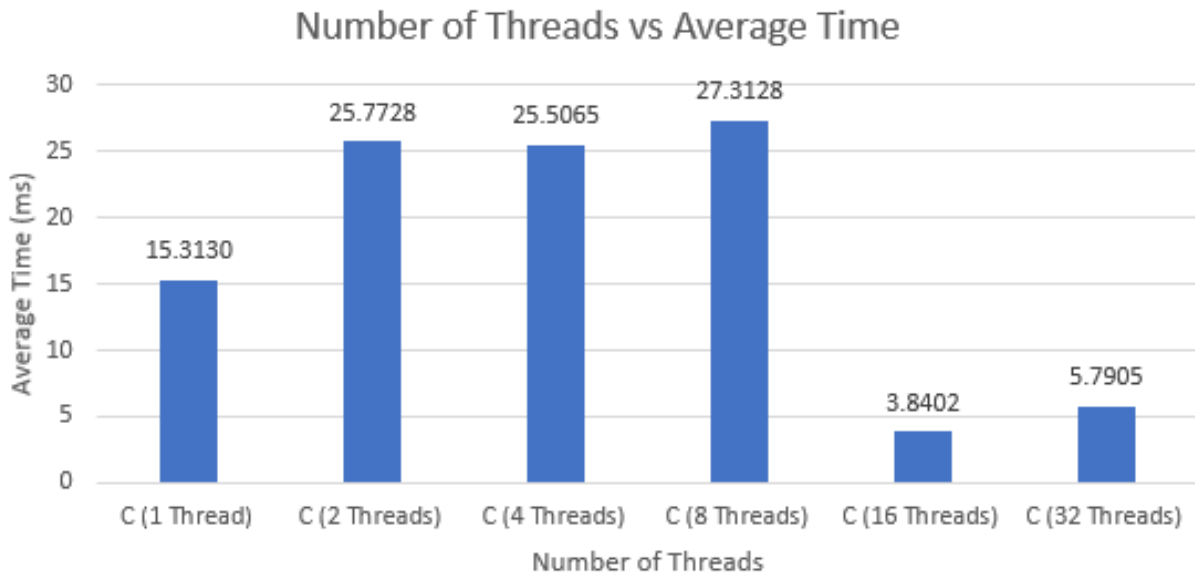


Figure 3: Program Speed at different number of threads

The above figure 3 represents how the program execution speed varies depending on how many threads the program is using. From the figure, it is clear that just increasing the number of threads a program is using does not guarantee speedup. Too many threads used can cause overhead, that is it can slow down the program execution time. Using too few threads is not ideal, as the probability of achieving speed up is very low. The key is finding just the right amount of threads that achieve the speed up. From Figure 2 the ideal number of threads to achieve a significant speedup is 8 threads. Using threads less than or greater than the ideal number of threads can impact the program speed up negatively.

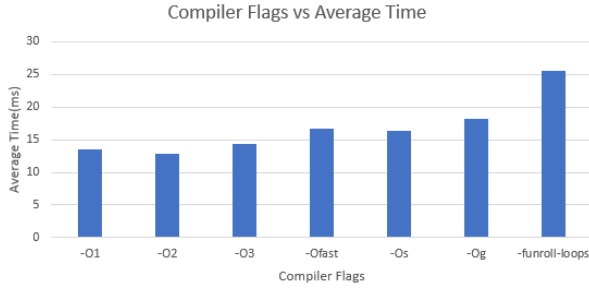


Figure 4: Program execution average Time for different compiler flags

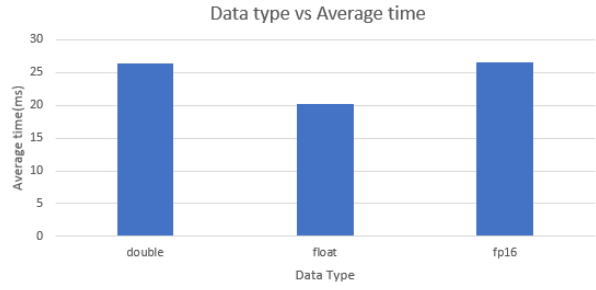


Figure 5: Average time for tens runs of each data type

The above figure 4 represents how the program execution speed varies depending on which compiler flag is used to optimise it. These flags are ranging from safe to use flags to dangerous to use. This is because some other flags compromised the program's accuracy. An example of a dangerous flag is the -Ofast flag because it breaks a few rules to go much faster. Code might not behave as expected. The -O2 flags outperform the other compiler flags.

Figure 5 above displays the average time is taken for running the program 10 times for each data type. Each program has 8 threads. From the diagram we can see that float has the lowest average time for ten runs compared to other data types (double and fp16), this shows that the float program has a high execution speed compared to others, hence faster.

### 3.2 Tables

Table 1: Comparing speed of the C program using different number of threads

Run No.	Python Float (ms)	C float 32 bits (ms)	C program float 64 bit (ms)					
			1 Threads	2 Threads	4 Threads	8 Threads	16 Threads	32 Threads
1	666.083	11.134	16.950	27.472	28.608	28.664	4.788	3.643
2	602.740	11.373	14.247	28.097	28.285	21.043	3.483	12.978
3	609.573	10.774	16.059	27.632	20.374	28.678	3.860	4.802
4	552.083	9.453	16.127	16.760	28.149	30.500	4.509	6.044
5	542.791	8.889	15.688	27.812	26.596	30.248	2.762	3.708
6	938.347	11.306	16.191	27.548	26.859	28.506	3.574	9.366
7	667.237	7.367	12.814	27.352	19.665	21.032	2.261	5.196
8	590.083	8.165	15.106	27.791	26.732	28.547	4.863	3.616
9	574.800	11.286	15.672	27.455	23.530	27.192	3.863	3.584
10	574.332	11.327	14.276	19.809	26.267	28.718	4.439	4.968
Average	631.8069	10.1073	15.3130	25.7728	25.5065	27.3128	3.8402	5.7905

Table 2: C program with 8 threads: Comparing different compiler flags

	Compiler Flags						
Run No:	-O1	-O2	-O3	-Ofast	-Os	-Og	-funroll-loops
1	13.963	16.709	13.491	15.879	15.737	15.657	25.092
2	16.053	14.374	16.808	18.023	18.210	21.391	21.092
3	12.887	17.999	16.964	18.143	15.703	20.023	21.640
4	10.962	10.113	19.815	15.813	17.942	14.029	29.015
5	12.680	9.114	13.898	17.607	13.067	15.750	25.412
6	11.246	10.508	11.076	15.964	14.760	21.325	29.112
7	19.661	16.707	14.061	18.205	13.463	15.573	28.916
8	13.822	11.968	11.869	13.485	18.067	21.338	25.241
9	9.570	11.698	12.757	17.817	18.171	21.350	28.870
10	13.809	9.958	13.147	15.612	17.732	15.566	21.096
Average	13.4653	12.9148	14.3886	16.6548	16.2852	18.2002	25.5486

Table 3: Comparing different data type.

	Data type		
Run No:	double	float	fp16
1	29.172	18.169	31.047
2	21.100	17.331	30.627
3	28.975	20.869	23.677
4	29.217	23.815	27.400
5	28.824	23.824	22.325
6	25.647	17.102	14.455
7	20.991	21.104	31.150
8	28.972	25.287	27.317
9	21.784	17.394	30.789
10	28.795	17.035	27.588
Average	26.348	20.193	26.638

## 4 Conclusion

This experiment shows that the golden measure python program is slower than the exact same program written in C/C++, which then concludes that C or C++ should be chosen over python when trying to develop embedded systems in the industry, but furthermore, the C/C++ program can still be optimized to even execute much faster, using flags, threads, and data type. The data from the experiment shows that a program with 16 threads is faster compared to other programs with different threads, the data also shows Compiler flag -O2 produces high speed, and lastly, data type float produces faster speed compared to double and fp16.