# Applied Mathematics TW324 Assignment 04

https://github.com/BhekimpiloNdhlela/TW324NumericalMethods Bhekimpilo Ndhlela (18998712)

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## Python Source Code For Both a.) and b.):

```
def question_a (steps, x=0.0, debug=False):
    fp = lambda x, h : ((f(x+2*h)+8*f(x+h)) * *f(x h)+f(x 2*h))/(12*h))
    f = lambda x : sqrt(1  2 * sin(x))
    exact = [abs(fp(x, h) + 1.0) for h in steps]
    if debug is True:
        print "DEBUG_MODE: _ [ON] _QUESTION_1_a.)"
        print "i","\t" ,"Step_Size", "\t", "Exact_Error"
        for i, (h, err) in enumerate(zip(steps, exact)):
            print (i+1), "\t"," {:.7 f}".format(h), "\t", "{:.10 f}".format(err)
    return exact
def question_b (steps, M=11.0, debug=False):
    machine\_eps = finfo(float).eps
    bound = [(18.0 * machine_eps)/(12.0*h) + M*(h**4) for h in steps]
    if debug is True:
        print "DEBUG_MODE: _ [ON] _QUESTION_3_bii.)"
        print "i","\t" ,"Step_Size", "\t", "Bound"
        for i, (h, err) in enumerate(zip(steps, bound)):
            print (i+1), "\t", "\{:.7 f}".format(h), "\t", "\{:.10 f}".format(err)
    return bound
def plot_err_functs(steps, exact, bound):
    #loglog plot to display the error as function of the step size
    plt.title("Plot_of_the_Exact_Error_and_Bound_as_h(Step_size)_Changes")
    plt.xlabel("h_(Step_Size)")
    plt.ylabel("Exact_vs_Bound")
    plt.yscale('log')
    plt.xscale('log')
    plt.plot(steps, exact, "k", label="Exact")
    plt.plot(steps, bound, "k", label="Bound")
    plt.legend(bbox_to_anchor=(.65, .9))
    plt.show()
if __name__ == "__main__":
    from numpy import (abs, cos, sin, sqrt, logspace)
    from numpy import (finfo, float)
    import matplotlib.pyplot as plt
    from math import pow
    steps = logspace(7, 1, num=100)
    exact, bound = question_a(steps), question_b(steps)
    plot_err_functs(steps, exact, bound)
```

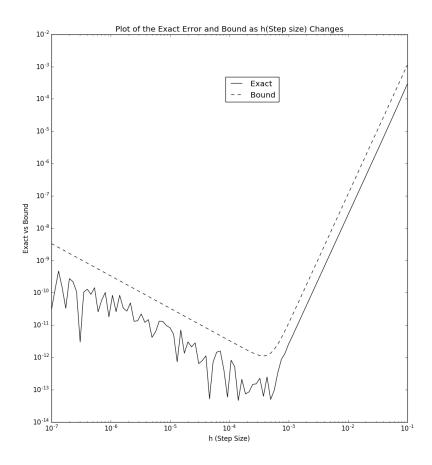


Figure 1: approximation of the first derivative of f(x) with the error bound

Conclusion: The conclusion matchs the  $O(h^4)$  convergence predicted by the theory?

**Required To Prove That:**  $\int_a^b x^3 dx = \frac{h}{3}(y_0 + 4y_1 + y_2) - \frac{h^5}{90}f^{(iv)}(c)$ 

We Know That The Exact Integral is:  $\int_a^b x^3 dx = \frac{1}{4} x^4 |_a^b = \frac{1}{4} (b^4 - a^4)$ 

The Simpson's Rule States That:

$$\int_{x_0}^{x_2} x^3 dx = \frac{h}{3} (y_0 + 4y_1 + y_2) - \frac{h^5}{90} f^{(iv)}(c)$$

but:  $y_0 = a^3$ ,  $y_2 = b^3$  and  $y_1 = (\frac{a+b}{2})^3$  also:  $-\frac{b^5}{90}f^{(iv)}(c) = 0$  because:

$$f(x)=x^3,\ f\prime(x)=3x^2,\ f\prime\prime(x)=6x,\ f^{(iiv)}(x)=6\ {
m and}\ f^{(iv)}(x)=0$$

we also know that:  $h = \frac{b-a}{2} \implies \frac{h}{3} = \frac{b-a}{6}$  Then:

$$\int_{a}^{b} f(x)dx = \frac{b-a}{6}(b^{3} + 4(\frac{a+b}{2})^{3} + a^{3})$$

$$\int_{a}^{b} f(x)dx = \frac{b-a}{6}(b^{3} + 4(\frac{a^{3} + 3a^{2}b + 3ab^{2} + b^{3}}{8}) + a^{3})$$

$$\int_{a}^{b} f(x)dx = \frac{b-a}{6}(b^{3} + (\frac{a^{3} + 3a^{2}b + 3ab^{2} + b^{3}}{2}) + a^{3})$$

$$\int_{a}^{b} f(x)dx = \frac{b-a}{6}(\frac{2b^{3} + b^{3} + a^{3} + 3a^{2}b + 3ab^{2} + 2a^{3}}{2})$$

$$\int_{a}^{b} f(x)dx = \frac{b-a}{6}(\frac{3b^{3} + 3a^{2}b + 3ab^{2} + 3a^{3}}{2})$$

$$\int_{a}^{b} f(x)dx = \frac{(b-a)(3b^{3} + 2a^{2}b + 2ab^{2} + 3a^{3})}{12}$$

$$\int_{a}^{b} f(x)dx = \frac{(b-a)(3b^{3} + 2a^{2}b + 2ab^{2} + 3a^{3})}{12}$$

$$\int_{a}^{b} f(x)dx = \frac{3b^{4} - 3a^{4}}{12}$$

$$\int_{a}^{b} f(x)dx = \frac{3(b^{4} - a^{4})}{12}$$

$$\int_{a}^{b} f(x)dx = \frac{1}{4}(b^{4} - a^{4})$$

Conclusion: Since  $\int_a^b f(x)dx$  (Exact Solution) =  $\int_a^b f(x)dx$  (Simpsons Method) then I have proved that the Simpson's rule has polynomial degree of precision since i have shown exact for the integral

a.)

Required To Prove: 
$$f''(x) = \frac{-f(x-2h)+16f(x+h)-30f(x)+16f(x-h)-f(x-2h)}{12h^2} + O(h^4)$$
 by the sid of Extrapolation

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Consider Case 1: use h

$$f \prime \prime (x) = \tfrac{f(x+h) - 2f(x) + f(x-h)}{h^2} - \tfrac{h^2}{12} f^{(iiv)}(c) + O(h^4)$$

Consider Case 2: use 2h

$$f \prime \prime (x) = \tfrac{f(x+2h) - 2f(x) + f(x-2h)}{4h^2} - \tfrac{4h^2}{12} f^{(iiV)}(c) + O(h^4)$$

now we use: 4\*case 1 - case 2

$$4f''(x) - f''(x) = \frac{4f(x+h) - 8f(x) + 4f(x-h)}{h^2} - \frac{4h^2}{12}f^{(iiv)}(c) + O(h^4) - (\frac{f(x+2h) - 2f(x) + f(x-2h)}{4h^2} + \frac{4h^2}{12}f^{(iiv)}(c) + O(h^4))$$

$$3f {\it H}(x) = \frac{16f(x+h) - 32f(x) + 16f(x-h) - f(x+2h) - 2f(x) - f(x-2h)}{4h^2} + O(h^4)$$

$$f \prime \prime (x) = \tfrac{-f(x-2h) + 16f(x+h) - 30f(x) + 16f(x-h) - f(x-2h)}{12h^2} + O(h^4)$$

I have used the method of extrapolation to derive the second derivative approximation

b.)

#### Python Source Code For:

```
def exact (steps, x=0.0, debug=False):
    fpp = lambda x, h : ((f(x+2*h)+16*f(x+h))30*f(x)+16*f(x h))f(x 2*h))
                                                /(12*h*h)
    f = lambda x : sqrt(1  2 * sin(x))
    exact = [abs(fpp(x, h) + 1.0) for h in steps]
    if debug is True:
        print "DEBUG_MODE: _ [ON] _QUESTION_3 _ bi .)"
        print "i","\t" ,"Step_Size", "\t", "Exact_Error"
        for i, (h, err) in enumerate(zip(steps, exact)):
             print (i+1), "\t"," \{:.7 f}".format(h), "\t", "\\{:.10 f\}".format(err)
    return exact
def bound (steps, M=11.0, debug=False):
    machine_eps = finfo(float).eps
    bound = [(18.0 * machine_eps)/(12.0*(h**2)) + M*(h**4) for h in steps]
    if debug is True:
        print "DEBUG_MODE: _ [ON] _QUESTION_3_bii.)"
        print "i","\t", "Step_Size", "\t", "Bound"
        for i, (h, err) in enumerate(zip(steps, bound)):
              \mathbf{print} \ \ (\,i\,+1)\,, \ \ "\,\,\,\,t\,"\,\,,"\,\,\{\,:\,.\,7\,\,f\,\}"\,\,.\, \mathbf{format}\,(\,h\,)\,\,,\;\; "\,\,\,\,\,t\,"\,\,,\;\; "\,\,\,\{\,:\,.\,10\,\,f\,\}"\,\,.\, \mathbf{format}\,(\,err\,) 
    return bound
def plot_error_functions(steps, exact, bound):
    #loglog plot to display the error as function of the step size
    plt.title("Plot_of_the_Exact_Error_and_Bound_as_h(Step_size)_Changes")
    plt.xlabel("h_(Step_Size)"); plt.ylabel("Exact_vs_Bound")
    plt.yscale('log'); plt.xscale('log')
    plt.plot(steps, exact, "k", label="Exact")
    plt.plot(steps, bound, "k", label="Bound")
    plt.legend(bbox_to_anchor = (.65, .9))
    plt.show()
if \quad -name_- = "-main_-":
    from numpy import (abs, cos, sin, sqrt, logspace)
    from numpy import (finfo, float)
    import matplotlib.pyplot as plt
    from math import pow
    steps = logspace(7, 1, num=100)
    exact , bound = exact(steps), bound(steps)
    plot_error_functions (steps, exact, bound)
```

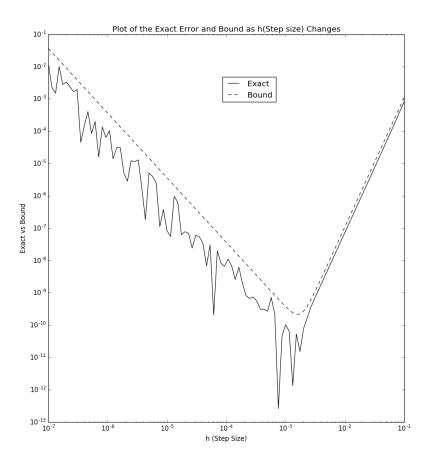


Figure 2: approximation of the second derivative of f(x) from Question 1(a) with the error bound of f(x)

Conclusion: The conclusion matches the  $O(h^4)$  convergence predicted by the theory?

## Python Source Code:

```
def trapezium (exact_I, H, x0=0., debug=True):
    apprx_I = array([h/2. * (exp(x0) + exp(h)) for h in H])
    return array([abs(apI exI) for apI, exI in zip(apprx_I, exact_I)])
def midpoint (exact_I, H, x0=0., debug=True):
   W = array([x0 + (h / 2.0) \text{ for } h \text{ in } H])
    apprx_I = array([h * exp(w) for h, w in zip(H, W)])
    return array([abs(apI exI) for apI, exI in zip(apprx_I, exact_I)])
def simpson (exact_I, H, x0=0., debug=True):
    apprx_I = array([h/6.*(exp(x0)+(4.*exp(h/2.))+exp(h))) for h in H])
                             exI) for apI, exI in zip(apprx_I, exact_I)])
    return array ([abs(apI
def debug(abs_err_s, abs_err_m, abs_err_t, debug=True):
    if debug is True:
        print "DEBUG_MODE: _ [ON] _ [ Question _4_Simpson 's _method]"
        print "SIMPSONS_METHOD\ t\tMIDPOINT_METHOD\ t\tTRAPEZIUM_METHOD"
        for s, m, t in zip(abs_err_s, abs_err_m, abs_err_t):
             print "{:.20 f}" . format(s), "{:.20 f}" . format(m), "{:.20 f}" . format(t)
    else:
        print "DEBUG_MODE: _ [OFF] _ [ Question _4 _ Simpson 's _method]"
def plot_abs_errs(abs_err_t, abs_err_m, abs_err_s):
    #loglog plot to display the error as function of the step size
    plt.title("|xc x|_of:_The_Midpoint,_Simpson_&_Trapezium_Methods_against_h")
    plt.ylabel("Midpoint_vs_Simpson_vs_Trapezium")
    plt.xlabel("h"); plt.yscale('log'); plt.xscale('log')
    plt.plot([1., .1, .01], abs_err_t, "k", label="Trapezium")
plt.plot([1., .1, .01], abs_err_m, "r", label="Midpoint")
plt.plot([1., .1, .01], abs_err_s, "g", label="Simpson")
    plt.legend(bbox_to_anchor=(.65, .9))
    plt.show()
if __name__ == "__main__":
    from numpy import (exp, abs, array)
    import matplotlib.pyplot as plt
    H, exact_I = array([1., .1, .01]), array([exp(h) 1 for h in H])
    abs_err_t = trapezium (exact_I, H)
    abs_err_m = midpoint(exact_I, H)
    abs\_err\_s = simpson(exact\_I, H)
    debug(abs_err_s, abs_err_m, abs_err_t)
    plot_abs_errs (abs_err_t, abs_err_m, abs_err_s)
```

SIMPSONS METHOD	MIDPOINT METHOD	TRAPEZIUM METHOD
0.00057932341754773908	0.06956055775891689663	0.14085908577047745460
0.00000000365068135444	0.00004380843804530077	0.00008762782813467873
0.00000000000003500325	0.00000004187557393898	0.00000008375125289117

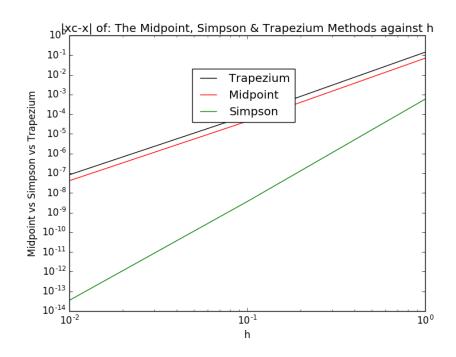


Figure 3:  $|x_c-x| {\rm Absolute~Errors}$  for the SIMPSONS, MIDPOINT and the TRAPEZIUM METHOD

Conclusion: The rates of convergence agree with the theoretical approximations derived in lectures

## Python Source Code:

```
def question_a (n=8.0, debug=True):
    h = (1.0 / (n 1.0))
    f = array([exp(x) for x in linspace(0.0, 1.0, 8.0)])
    A = \text{matrix}([[1, 2, 1, 0, 0, 0, 0, 0], \\ [0, 1, 2, 1, 0, 0, 0, 0], \\
                   [0, 0, 1, 2, 1, 0, 0, 0], \setminus
                   [0, 0, 0, 1, 2, 1, 0, 0], \setminus
                   [0, 0, 0, 0, 1, 2, 1, 0], \
                   [0, 0, 0, 0, 0, 1, 2, 1]]
    f_{-} = (1.0 / h**2.0) * matmul(A, f).T
    if debug is True:
         \mathbf{print} "DEBUG_MODE: _ [ON] _\t_ [QUESTION_5_A.)]"
         print "f \setminus "(x) = ",
         for i in f_:
              print i,
if \quad -name = "-main = ":
    from numpy import (linspace, exp, array, shape, matrix, matmul)
    import matplotlib.pyplot as plt
    question_a()
                         Answer/ Result:
```

$$f''(x) = \begin{bmatrix} 1.15552818 \\ 1.33297685 \\ 1.53767544 \\ 1.77380856 \\ 2.04620346 \\ 2.36042868 \end{bmatrix}$$