

# Graphics programming

## Exercise 11

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# Exercise 11

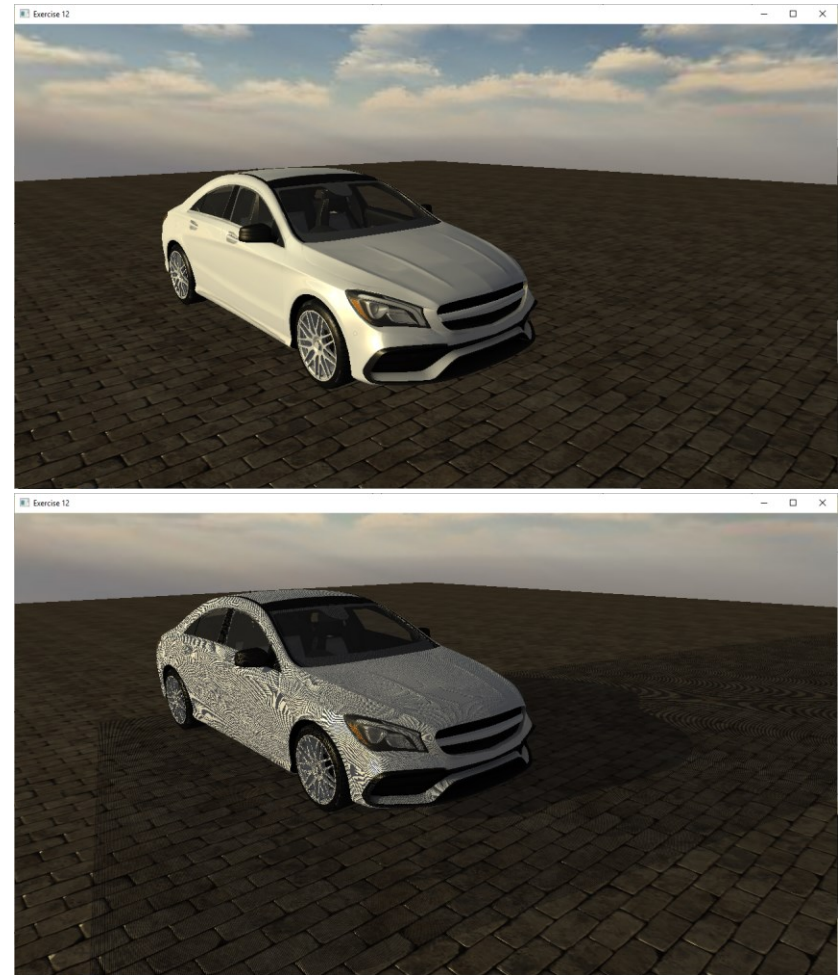
- Learning objectives
  - Implement the shadow mapping algorithm
  - Perform shadow computations in light space
  - Explore the render passes and pipeline of deferred shading.
  - Describe the implementation differences between forward shading and deferred shading.
  - Implement simple image post-processing with deferred shading.

# References

- Render to texture
  - <https://learnopengl.com/Advanced-OpenGL/Framebuffers>
- Shadow mapping
  - <https://learnopengl.com/Advanced-Lighting/Shadows/Shadow-Mapping>
  - Cube map for point light in a closed environment:  
<https://learnopengl.com/Advanced-Lighting/Shadows/Point-Shadows>
  - <https://docs.microsoft.com/en-us/windows/win32/dxtecharts/cascaded-shadow-maps>
  - <https://docs.microsoft.com/en-us/windows/win32/dxtecharts/common-techniques-to-improve-shadow-depth-maps>
- Deferred shading
  - <https://learnopengl.com/Advanced-Lighting/Deferred-Shading>

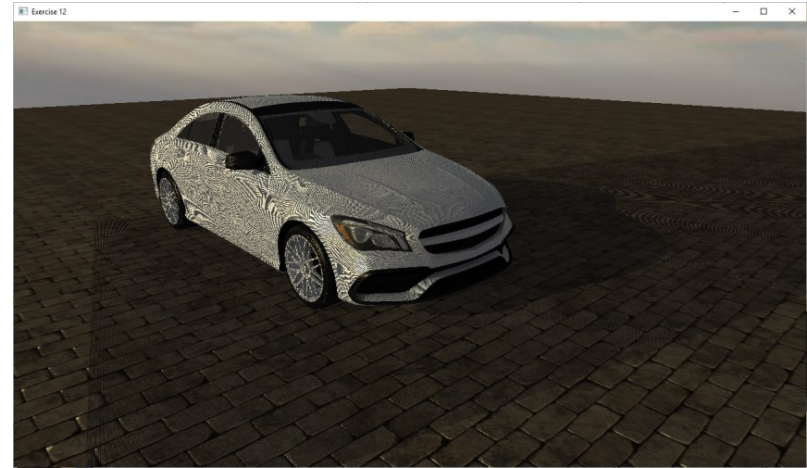
# Exercise 11.1 – depth comparison

- Implement the basic shadow mapping algorithm.
- Vertex shader: Transform the vertex position from local space to light space.
- Fragment shader: Implement the ShadowCalculation function. You will need to:
  - Change the (x,y) value range from NDC  $[-1, 1]$  to uv texture coordinates  $[0, 1]$ ;
  - Sample the shadowmap with the coordinates;
  - Check if the current fragment depth in the scene is bigger than the depth sampled in the shadow map;
  - If it is, then the fragment is in shadow. Set shadow to 1.0.
- Add the shadow value to modulate your FragColor computation.



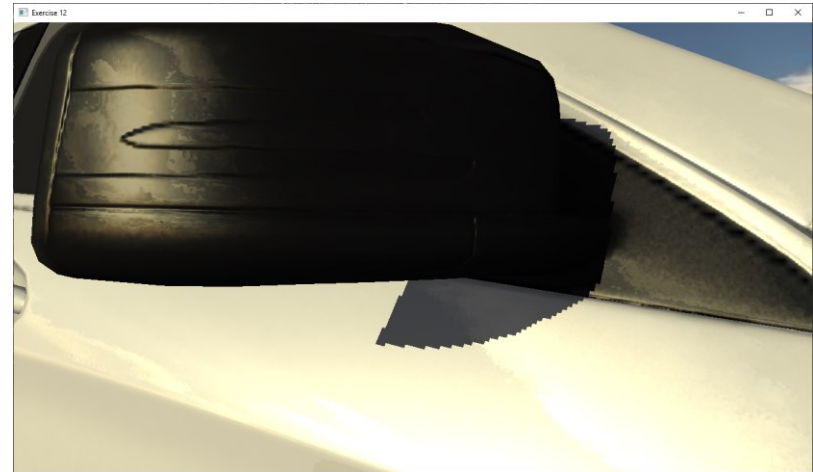
# Exercise 11.2 – the acne problem

- Solve the acne problem
  - Use the shadowBias variable to offset the value stored in the shadowMap before comparing the distances.
  - Once you get the expected result, play with the bias slider in the GUI to see how the shadows behave.



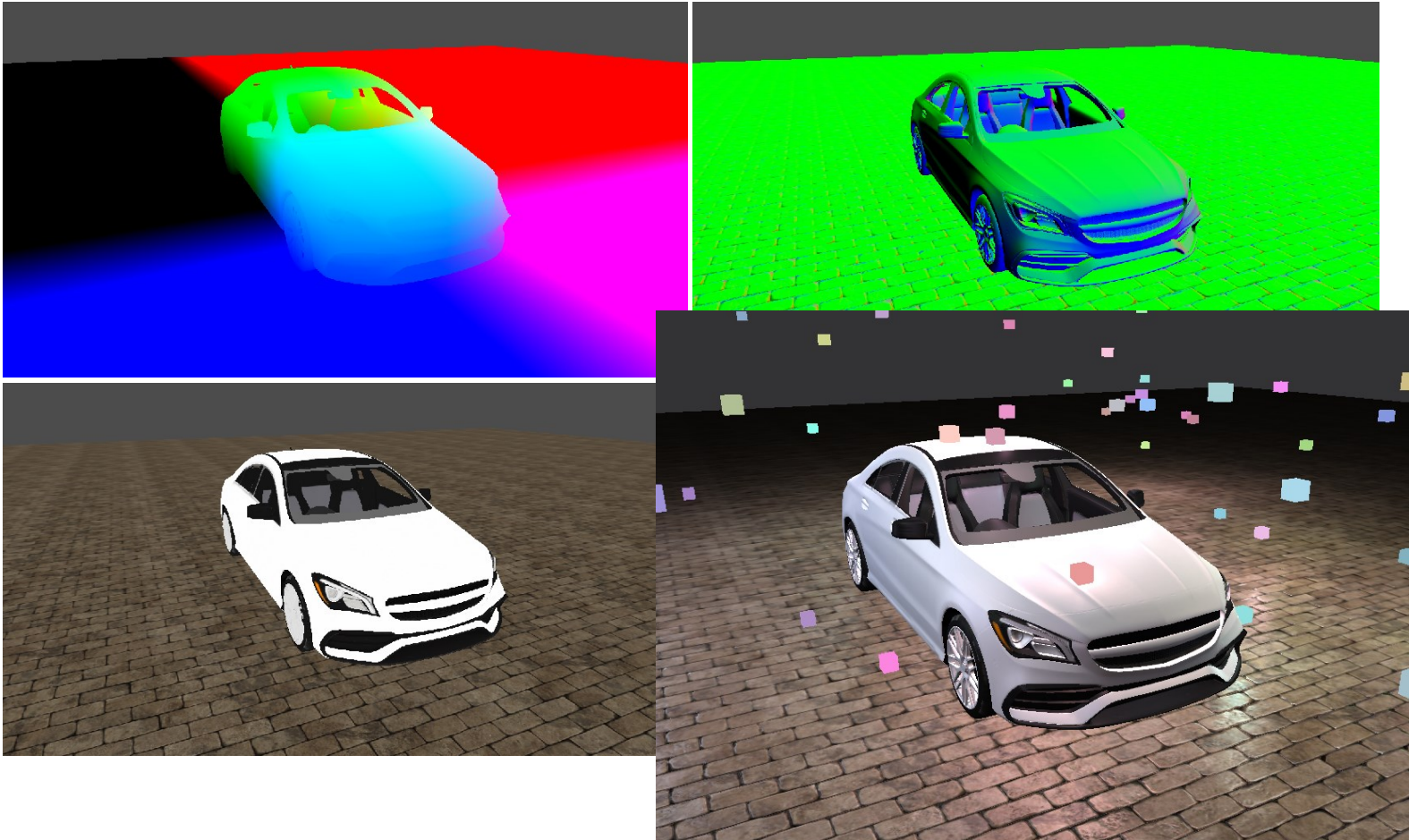
# Exercise 11.3 – soft shadows

- Percentage closer filtering
- In the ShadowCalculation function:
  - Sample a 3 x 3 grid of texels (instead of single texel);
  - Set shadow as a weighted contribution of the 9 samples.





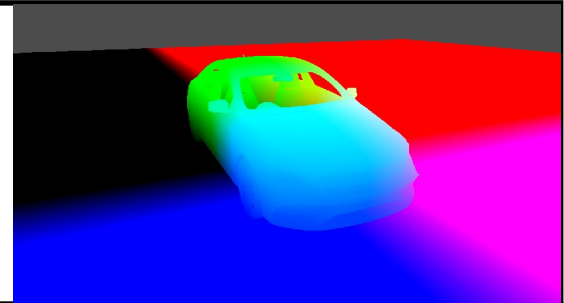
# Exercise 11.4-11.6 - G-buffer



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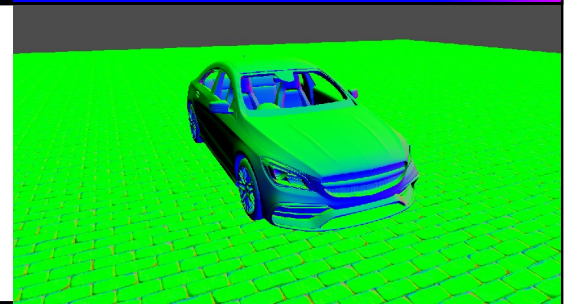
- Position

- 3 channels - rgb/xyz
- 16 bits per channel
- World space



- Normals

- 3 channels - rgb/xyz
- 16 bits per channel
- World space



- Diffuse + specular

- 4 channels – rgba
- 8 bits per channel
- rgb = diffuse / a = specular map





# G-Buffer in practice

- **No world pos texture:** The world position can be computed using depth and the screen position
- **Depth buffer texture.** Using z-buffer we get the depth for free.
- **Packed normals.** If normal are in camera space, we can store X and Y and find Z in the shading pass (i.e. we assume Z is positive).  
<http://aras-p.info/texts/CompactNormalStorage.html>
- **Pack remaining data:** Use as little data as possible to store remaining attributes: Albedo-color, speculariry-power, speculariry-intensity

# Exercise 11.4 code structure

- Explore code structure
  - The code was copied from <https://learnopengl.com/Advanced-Lighting/Deferred-Shading>
  - With the addition of forward shading (forward\_shading.vert/frag)
  - (optional) Read through the tutorial to get familiar with the deferred shading implementation.
  - Read the render loop code and comments. Notice how, in the deferred rendering option, g\_buffer.vert and .frag are used to generate the gbuffer (step 1).
  - Then preprocessed info is send to deferred\_shading.vert and .frag and rendered with a quad (step 2)

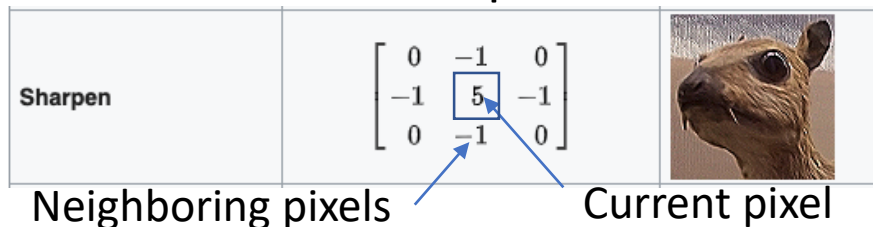
# Exercise 11.5 blinn-phong reflection

- Implementing the blinn-phong reflection model
  - Implement it in `deferred_shading.frag`;
  - There is an implementation in `forward_shading.frag`, use it as a reference;
  - Did you have to do any modification?



# Exercise 11.6 post processing 1

- Apply a sharpen filter (convolution kernel) to the diffuse and specular components of the gBuffer
  - Implement it in deferred\_shading.frag;
  - Use [https://en.wikipedia.org/wiki/Kernel\\_\(image\\_processing\)](https://en.wikipedia.org/wiki/Kernel_(image_processing)) as a reference;
  - Like in the shadow mapping exercise, you will need to sample the buffer multiple times.

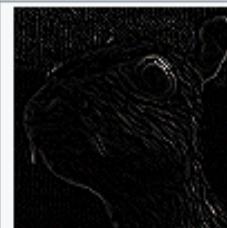


## Exercise 11.6 post processing 2

- Apply an **edge detection** filter (convolution kernel) to the **normal** component of the gBuffer
  - Implement it in deferred\_shading.frag;
  - Use [https://en.wikipedia.org/wiki/Kernel\\_\(image\\_processing\)](https://en.wikipedia.org/wiki/Kernel_(image_processing)) as a reference;
  - You will use a Laplacian operator to obtain the weighted sum of normal vectors.
  - If the magnitude of the resulting vector is high, it indicates high curvature or surface discontinuity. You want to paint these surfaces black.

Edge detection

$$\begin{bmatrix} 0 & 1 & 0 \\ 1 & -4 & 1 \\ 0 & 1 & 0 \end{bmatrix}$$



# Edge detection

- Second order derivative, a discrete Laplace operator

[https://en.wikipedia.org/wiki/Discrete\\_Laplace\\_operator](https://en.wikipedia.org/wiki/Discrete_Laplace_operator)

- Large scalar values indicates edge
- Large magnitude values (for vectors) indicates edge

0	1	0
1	-4	1
0	1	0

Current pixel

Neighbour pixels



# Result with post effects

