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/*
 * assembly.s
 *
 */

@ DO NOT EDIT
.syntax unified
.text
.global ASM_Main
.thumb_func

@ DO NOT EDIT
vectors:
    .word 0x20002000
    .word ASM_Main + 1

@ DO NOT EDIT label ASM_Main
ASM_Main:

    @ Some code is given below for you to start with
    LDR R0, RCC_BASE           @ Enable clock for GPIOA and B by setting bit 17 and
18 in RCC_AHBENR
    LDR R1, [R0, #0x14]
    LDR R2, AHBENR_GPIOAB     @ AHBENR_GPIOAB is defined under LITERALS at the end
of the code
    ORRS R1, R1, R2
    STR R1, [R0, #0x14]

    LDR R0, GPIOA_BASE         @ Enable pull-up resistors for pushbuttons
    MOVS R1, #0b01010101
    STR R1, [R0, #0x0C]
    LDR R1, GPIOB_BASE         @ Set pins connected to LEDs to outputs
    LDR R2, MODER_OUTPUT
    STR R2, [R1, #0]
    MOVS R2, #0                @ NOTE: R2 will be dedicated to holding the value on
the LEDs

@ TODO: Add code, labels and logic for button checks and LED patterns

main_loop:
    B      button_check @Branch to check for button press

button_check:
    LDR    R3, [R0, #0x10] @ Load IDR to check for SW0 press
    MOVS   R4, #1
    ANDS   R3, R3, R4
    CMP    R3, #0
    BEQ    led_counter_SW0

    LDR    R3, [R0, #0x10] @ Load IDR to check for SW2 press
    MOVS   R4, #4
    ANDS   R3, R3, R4
    CMP    R3, #0
    BEQ    write_leds_SW2

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        LDR    R3, [R0, #0x10] @ Load IDR to check for SW3 press
        MOVS   R4, #8
        ANDS   R3, R3, R4
        CMP    R3, #0
        BEQ    write_leds_SW3

        B      led_counter_Norm

led_counter_Norm:
        ADDS   R2, R2, #1 @ Implement normal led increase
        B      write_leds

led_counter_SW0:
        ADDS   R2, R2, #2 @ Implement fast-mode led increase(+2)
        B      write_leds

write_leds_SW2:
        MOVS   R5, #0xAA
        STR    R5, [R1, #0x14] @ Display 10101010 upon pressing SW2
        B      main_loop

write_leds_SW3:
        STR    R2, [R1, #0x14] @ Hold the display to most recent value
        B      main_loop

write_leds:
        STR    R2, [R1, #0x14] @ Display the current led pattern
        LDR    R3, [R0, #0x10] @ Load idr data to check if SW1 is pressed
        MOVS   R4, #2
        ANDS   R3, R3, R4
        CMP    R3, #0
        BEQ    load_delay_fast @ Implement the corresponding delay depending on button
press
        B      load_delay_slow

load_delay_fast:
        LDR    R5, =SHORT_DELAY_CNT @ Load corresponding delay data
        LDR    R6, [R5]
        B      delay

load_delay_slow:
        LDR    R5, =LONG_DELAY_CNT @ Load corresponding delay data
        LDR    R6, [R5]
        B      delay

delay:
        subs   R6, R6, #1 @ Implement a do nothing loop to act as a delay
        BNE    delay
        B      main_loop

@ LITERALS; DO NOT EDIT
        .align
RCC_BASE:                .word 0x40021000
AHBENR_GPIOAB:          .word 0b11000000000000000000
GPIOA_BASE:              .word 0x48000000

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GPIOB_BASE:      .word 0x48000400
MODER_OUTPUT:    .word 0x5555
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@ TODO: Add your own values for these delays
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LONG_DELAY_CNT:  .word 1400000
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SHORT_DELAY_CNT: .word 600000
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