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LAB REPORT
on

Artificial Intelligence (23CS5PCAIN)

Submitted by

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in partial fulfillment for the award of the degree of

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in

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CERTIFICATE

This is to certify that the Lab work entitled “Artificial Intelligence (23CS5PCAIN)” carried out by **Bhoomi Suresh Kota (1BM23CS065)**, who is a bonafide student of **B.M.S. College of Engineering**. It is in partial fulfillment for the award of **Bachelor of Engineering in Computer Science and Engineering** of the Visvesvaraya Technological University, Belgaum. The Lab report has been approved as it satisfies the academic requirements in respect of an Artificial Intelligence (23CS5PCAIN) work prescribed for the said degree.

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Github Link:

<https://github.com/BhoomiSuresh/AI-LAB.git>

Program 1

Implement Tic – Tac – Toe Game Implement vacuum cleaner agent

Algorithm:

priscilla

LAB 1

TIC TAC TOE

Steps:

- ① Consider a 3×3 matrix
- ② Input can either be 'X' or 'O'
- ③ If the player chooses 'X', system should automatically take 'O' as its input, and vice versa.
- ④ The first moves of the human and system are random.
- ⑤ When human makes the second move, system should check all combinations to check which combination the human can complete and try to block that sequence ~~with~~ by making its move
- ⑥ If none of the sequence can be completed by human, the system should constantly check ~~for~~ if it could complete its sequence and try making a move accordingly

✓ ✓ Status change

Vacuum Cleaner					
Working:	(27B) problem				
① The vacuum cleaner is placed at a point.	It moves in a straight line indefinitely until it encounters an obstacle.				
② It checks right and left directions for dirt. If dirt is detected, moves to that direction and cleans it.	→ Loop				
③ Upon collision, it moves few steps back, and again the directions for dirt.	→ Loop				
④ Direction of rotation is clockwise.	→ Loop				
⑤ This process goes on in a loop.	→ Loop				
<table border="1"> <tr> <td>0</td><td>0</td> </tr> <tr> <td>0</td><td>0</td> </tr> </table>	0	0	0	0	Starts at position 0. Checks left direction If dirt is detected moves left. Status changes to 1 (cleaned)
0	0				
0	0				
<table border="1"> <tr> <td>1</td><td>0</td> </tr> <tr> <td>0</td><td>0</td> </tr> </table>	1	0	0	0	Checks left direction for dirt. Dirt is detected & status changed to 1
1	0				
0	0				
<table border="1"> <tr> <td>1</td><td>1</td> </tr> <tr> <td>0</td><td>0</td> </tr> </table>	1	1	0	0	While moving in clockwise direction, it goes back to initial position, moves through different position for 1 more round. If status of all positions are 1. Then it stops
1	1				
0	0				

Code:

Tic Tac Toe:

```
def computer_move():
    best_move = minimax_recurse(game_board, active_player, 0)
    print("The best move is ", best_move)
    make_move(game_board, best_move, active_player)

    print("COMPUTER MOVE DONE")
```

```
def minimax_recurse(game_board, player, depth):
```

```
    winner = is_winner(game_board)
    if winner == active_player:
        return 1
    elif winner is not None and winner != active_player:
        return -1
    elif len(get_move_list(game_board)) == 0:
```

```

return 0

if player == player1:
    other_player = player2
else:
    other_player = player1

if player == active_player:
    alpha = -1
else:
    alpha = 1

movelist = get_move_list(game_board)
best_move = None

for move in movelist:
    board2 = [list(row) for row in game_board] # Create a copy of the board

    make_move(board2, move, player)

    subalpha = minimax_recurse(board2, other_player, depth + 1)

    if player == active_player:
        if depth == 0 and alpha <= subalpha:
            best_move = move
            alpha = max(alpha, subalpha)
        if alpha == 1: # Alpha-beta pruning
            if depth == 0:
                return best_move
            return alpha
    else:
        alpha = min(alpha, subalpha)
        if alpha == -1: # Alpha-beta pruning
            return alpha

    if depth == 0:
        return best_move
    return alpha


# BOARD FUNCTIONS
game_board = [['1','2','3'],['4','5','6'],['7','8','9']] # Changed to strings to avoid confusion with available moves
def print_board(board) :

    for row in board :

```

```

print(row)

def make_move(game_board, player_move, active_player):
    x = 0
    y = 0
    try:
        player_move = int(player_move)
    except ValueError:
        print("Invalid input. Please enter a number.")
        return game_board

    if player_move == 1 :
        x = 0
        y = 0
    elif player_move == 2 :
        x = 0
        y = 1
    elif player_move == 3 :
        x = 0
        y = 2
    elif player_move == 4 :
        x = 1
        y = 0
    elif player_move == 5 :
        x = 1
        y = 1
    elif player_move == 6 :
        x = 1
        y = 2
    elif player_move == 7 :
        x = 2
        y = 0
    elif player_move == 8 :
        x = 2
        y = 1
    elif player_move == 9 :
        x = 2
        y = 2
    else :
        print ("value is out of range")
        return game_board

    if game_board[x][y] == "O" or game_board[x][y] == "X" :
        print("move not available")
        return game_board

```

```

game_board[x][y] = str(active_player)
return game_board

def is_winner(board):
    for i in range (0,3) :
        if board[i][0] == player1 and board[i][1] == player1 and board[i][2] == player1 :
            return player1

        if board[i][0] == player2 and board[i][1] == player2 and board[i][2] == player2 :
            return player2

    # checking for columns
    for i in range(0,3):
        if board[0][i] == player1 and board[1][i] == player1 and board[2][i] == player1:
            return player1
        if board[0][i] == player2 and board[1][i] == player2 and board[2][i] == player2:
            return player2

    # checking for diagonals
    if board[0][0] == player1 and board[1][1] == player1 and board[2][2] == player1 :
        return player1
    if board[0][0] == player2 and board[1][1] == player2 and board[2][2] == player2 :
        return player2

    if board[2][0] == player1 and board[1][1] == player1 and board[0][2] == player1 :
        return player1
    if board[2][0] == player2 and board[1][1] == player2 and board[0][2] == player2 :
        return player2

    return None

def get_move_list (game_board) :

    move = []

    for row in game_board :
        for i in row :
            if i.isdigit():
                move.append(int(i))
    return move

# Main Loop
player1 = "X"
player2 = "O"
print_board(game_board)
while True :

```

```

active_player = player1
# this is for player move
print(get_move_list(game_board))
player_move = input("Please insert your move >>> ")
game_board = make_move(game_board,player_move,active_player)
print_board(game_board)

if is_winner(game_board) == player1 :
    print("Player1 is the winner")
    break
if is_winner(game_board) == player2 :
    print("Player2 is the winner")
    break
if len(get_move_list(game_board)) == 0:
    print("It's a tie!")
    break

print(get_move_list(game_board))
# computer time
active_player = player2
computer_move()
print_board(game_board)

if is_winner(game_board) == player1 :
    print("Player1 is the winner")
    break
if is_winner(game_board) == player2 :
    print("Player2 is the winner")
    break
if len(get_move_list(game_board)) == 0:
    print("It's a tie!")
    break

```

Vacuum Cleaner:

```

import random

def vacuum_cleaner_agent(location, status_A, status_B):
    """
    Simulates a simple vacuum cleaner agent in a two-location environment (A and B).
    Args:
        location (str): The current location of the vacuum ('A' or 'B').
        status_A (str): The cleanliness status of location A ('Dirty' or 'Clean').
        status_B (str): The cleanliness status of location B ('Dirty' or 'Clean').
    Returns:
        tuple: A tuple containing the updated location and statuses after the agent's action.
    """

```

```

print(f"Vacuum cleaner is at {location}.")

if location == 'A':
    if status_A == 'Dirty':
        print("Location A is Dirty. Sucking dirt...")
        status_A = 'Clean'
        print("Location A is now Clean.")
        # Move to B after cleaning A
        print("Moving to Location B.")
        return 'B', status_A, status_B
    else:
        print("Location A is Clean. Moving to Location B.")
        return 'B', status_A, status_B
elif location == 'B':
    if status_B == 'Dirty':
        print("Location B is Dirty. Sucking dirt...")
        status_B = 'Clean'
        print("Location B is now Clean.")
        # Move to A after cleaning B
        print("Moving to Location A.")
        return 'A', status_A, status_B
    else:
        print("Location B is Clean. Moving to Location A.")
        return 'A', status_A, status_B

# Initializing the environment
initial_location = random.choice(['A', 'B'])
initial_status_A = random.choice(['Dirty', 'Clean'])
initial_status_B = random.choice(['Dirty', 'Clean'])

print(f"Initial state: Vacuum at {initial_location}, A is {initial_status_A}, B is {initial_status_B}\n")

current_location, current_status_A, current_status_B = initial_location, initial_status_A,
initial_status_B

# Running the simulation until both locations are clean
while current_status_A == 'Dirty' or current_status_B == 'Dirty':
    current_location, current_status_A, current_status_B = vacuum_cleaner_agent(
        current_location, current_status_A, current_status_B
    )
    print(f"Current state: Vacuum at {current_location}, A is {current_status_A}, B is {current_status_B}\n")

print("Both locations are clean. Vacuum cleaner has finished its task.")

```

Program 2

Implement 8 puzzle problems using Depth First Search (DFS)
Implement Iterative deepening search algorithm

Algorithm:

8 PUZZLE SOLVER

Working: (BFS) : firstrow

① Initial state with randomly positioned numbers and this goal state is provided below it.

② The 3 rows are checked breadth wise. It checks the firstline first. If its digits are fixed then it moves to the second row and so on.

③ Each digit is checked for its proximity to the goal state.

④ If the digits are already in the goal state, the sequence is fixed. Otherwise it moves to the next row.

⑤ Else, it tracks all the possible moves and finally takes the path that gives the goal state (optimal soln) based on proximity to the goal state.

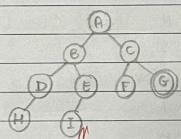
numbers first start 0 marking to second 1.
initial state: 1 2 3
Goal: 1 2 3
(current) ↓ at step 0 state: 4 5 6
6 7 8 7 8

↓
first row marking 1 2 3 4 5 6
↓ at step 1 state 3 4 5 6 7 8
4 5 6 7 8 9
↓
6 7
↓
1 2 3 4 5 6 7 8 9
marking symbols in 4th row 8. while 8
marked lastini ot' and loop if
marked 3 times it's work when
to state 3 it is working & it is
goal if not. L and 4 5 6 7 8 9. In
6 7
↓
1 2 3
5 8
4 6 7

IDDFS Graph Algorithm:

- 1: Initialize the start and goal node
- 2: Starting from start node till goal node:
 - Start traversing using BFS
 - From the first node, traverse to ~~the~~ its child nodes in the next depth level (DFS)
 - Further, traverse to its child nodes
 - Once we reach the end of the child nodes, move to the next node in the previous breadth.
- 3: If the goal node is found, return the path
Else, if max_depth is reached, return goal not found.

Eq:



Sol: Start from A (BFS[A])

DFS(A) gives B, C

DFS[B] gives D, E

DFS[C] gives F, G

G is the goal state

~~C~~ Path: A → B → D → E → C → F → G

A → B → D → E → C → F → G → H → I

For I :

A → B → D → H → E → I → C → F → G

Output:

1	2	3	4	5	6	7	8	9
4	10	9	8	7	6	5	4	3
7	5	8	6	0	8	0	7	2

pride@pride-OptiPlex-5070:~/Desktop\$ python3 10queens.py

1	2	3	4	5	6	7	8
4	3	2	1	0	5	6	7
7	5	8	6	0	8	0	7

pride@pride-OptiPlex-5070:~/Desktop\$ python3 10queens.py

1	2	3	4	5	6	7	8
4	3	2	1	0	5	6	7
7	5	8	6	0	8	0	7

[i,j]no = no[i,j]

valov_no < wochip_no ?

wochip_no = valov_no

4 5 6 valov_no: 0 0 0 0 0 0 0 0 0

7 8

Code:

BFS

```
# Import necessary libraries
from collections import deque

# Define the dimensions of the puzzle
N = 3

# Class to represent the state of the puzzle
class PuzzleState:
    def __init__(self, board, x, y, depth):
        self.board = board
        self.x = x
        self.y = y
        self.depth = depth

    # Possible moves: Left, Right, Up, Down
    row = [0, 0, -1, 1]
    col = [-1, 1, 0, 0]

    # Function to check if the current state is the goal state
    def is_goal_state(board):
        goal = [[1, 2, 3], [4, 5, 6], [7, 8, 0]]
        return board == goal

    # Function to check if a move is valid
    def is_valid(x, y):
        return 0 <= x < N and 0 <= y < N

    # Function to print the puzzle board
    def print_board(board):
        for row in board:
            print(''.join(map(str, row)))
        print('-----')

    # BFS function to solve the 8-puzzle problem
    def solve_puzzle_bfs(start, x, y):
        q = deque()
        visited = set()

        # Enqueue initial state
        q.append(PuzzleState(start, x, y, 0))
        visited.add(tuple(map(tuple, start)))

        while q:
```

```

curr = q.popleft()

# Print the current board state
print(f'Depth: {curr.depth}')
print_board(curr.board)

# Check if goal state is reached
if is_goal_state(curr.board):
    print(f'Goal state reached at depth {curr.depth}')
    return

# Explore all possible moves
for i in range(4):
    new_x = curr.x + row[i]
    new_y = curr.y + col[i]

    if is_valid(new_x, new_y):
        new_board = [row[:] for row in curr.board]
        new_board[curr.x][curr.y], new_board[new_x][new_y] = new_board[new_x][new_y],
        new_board[curr.x][curr.y]

        # If this state has not been visited before, push to queue
        if tuple(map(tuple, new_board)) not in visited:
            visited.add(tuple(map(tuple, new_board)))
            q.append(PuzzleState(new_board, new_x, new_y, curr.depth + 1))

print('No solution found (BFS Brute Force reached depth limit)')

# Driver Code
if __name__ == '__main__':
    start = [[1, 2, 3], [4, 0, 5], [6, 7, 8]] # Initial state
    x, y = 1, 1

    print('Initial State:')
    print_board(start)

    solve_puzzle_bfs(start, x, y)

```

IDDFS:

```

from collections import deque

# Goal state
GOAL = (1, 2, 3,
        4, 5, 6,
        7, 8, 0)

```

```

# Moves: up, down, left, right
MOVES = {
    'U': -3,
    'D': 3,
    'L': -1,
    'R': 1
}

def is_valid_move(pos, move):
    """Check if blank can move in given direction."""
    if move == 'U' and pos < 3: return False
    if move == 'D' and pos > 5: return False
    if move == 'L' and pos % 3 == 0: return False
    if move == 'R' and pos % 3 == 2: return False
    return True

def neighbors(state):
    """Generate valid neighbor states from current state."""
    new_states = []
    pos = state.index(0) # blank position
    for move, offset in MOVES.items():
        if is_valid_move(pos, move):
            new_pos = pos + offset
            new_state = list(state)
            new_state[pos], new_state[new_pos] = new_state[new_pos], new_state[pos]
            new_states.append((tuple(new_state), move))
    return new_states

def dls(state, depth, visited, path):
    """Depth-limited DFS."""
    if state == GOAL:
        return path
    if depth == 0:
        return None
    visited.add(state)

    for neighbor, move in neighbors(state):
        if neighbor not in visited:
            result = dls(neighbor, depth - 1, visited, path + [move])
            if result is not None:
                return result
    return None

def iddfs(start, max_depth=50):
    """Iterative Deepening DFS."""
    for depth in range(max_depth):

```

```

visited = set()
path = dls(start, depth, visited, [])
if path is not None:
    return path
return None

# --- MAIN PROGRAM ---
if __name__ == "__main__":
    print("Enter the start state of the 8-puzzle (use 0 for blank):")
    nums = []
    for i in range(9):
        nums.append(int(input(f"Tile {i+1}: ")))
    start = tuple(nums)

solution = iddfs(start, max_depth=30)
if solution:
    print(f"\nSolution found in {len(solution)} moves:")
    print(" -> ".join(solution))
else:
    print("No solution found within depth limit.")

```

Program 3

Implement A* search algorithm

Algorithm:

A* Algorithm	
Algorithm:	: problem with 1 0 2 0 0
1: initial puzzle state	0 0 0 0
2: priority queue min-heap ordered by $f(n) = g(n) + h(n)$	g(n) ← cost from start to curr-state h(n) ← heuristic (Manhattan distance)
3: if min = f(n) $f(n)$	pilou and pilou with 3 (3) x = min-heap.pop() 0 2 0 0
4: if x = goal state	0 0 0 0 return path 0 0 2 0
else	update position
5: for state in not visited:	calculate $g(n) + h(n)$ $f(n) = g(n) + h(n)$ min-heap.push($f(n)$)
Output	
Initial: [1, 2, 3, 4, 5, 6, 0, 7, 8]	
Move: None	1 2 3 4 5 6 7 8 Solve
Move: R	1 2 3 4 5 6 7 8
Move: R	1 2 3 4 5 6 7 8

Code:

```
import heapq
from termcolor import colored

# Class to represent the state of the 8-puzzle
class PuzzleState:
    def __init__(self, board, parent, move, depth, cost):
        self.board = board # The puzzle board configuration
        self.parent = parent # Parent state
        self.move = move # Move to reach this state
        self.depth = depth # Depth in the search tree
        self.cost = cost # Cost (depth + heuristic)
```

```

def __lt__(self, other):
    return self.cost < other.cost

# Function to display the board in a visually appealing format
def print_board(board):
    print("+-+---+-+")
    for row in range(0, 9, 3):
        row_visual = "|"
        for tile in board[row:row + 3]:
            if tile == 0: # Blank tile
                row_visual += f" {colored(' ', 'cyan')} |"
            else:
                row_visual += f" {colored(str(tile), 'yellow')} |"
        print(row_visual)
    print("+-+---+-+")

# Goal state for the puzzle
goal_state = [1, 2, 3, 4, 5, 6, 7, 8, 0]

# Possible moves for the blank tile (up, down, left, right)
moves = {
    'U': -3, # Move up
    'D': 3, # Move down
    'L': -1, # Move left
    'R': 1 # Move right
}

# Function to calculate the heuristic (Manhattan distance)
def heuristic(board):
    distance = 0
    for i in range(9):
        if board[i] != 0:
            x1, y1 = divmod(i, 3)
            x2, y2 = divmod(board[i] - 1, 3)
            distance += abs(x1 - x2) + abs(y1 - y2)
    return distance

# Function to get the new state after a move
def move_tile(board, move, blank_pos):
    new_board = board[:]
    new_blank_pos = blank_pos + moves[move]
    new_board[blank_pos], new_board[new_blank_pos] = new_board[new_blank_pos],
    new_board[blank_pos]
    return new_board

# A* search algorithm
def a_star(start_state):

```

```

open_list = []
closed_list = set()
heapq.heappush(open_list, PuzzleState(start_state, None, None, 0, heuristic(start_state)))

while open_list:
    current_state = heapq.heappop(open_list)

    if current_state.board == goal_state:
        return current_state

    closed_list.add(tuple(current_state.board))

    blank_pos = current_state.board.index(0)

    for move in moves:
        if move == 'U' and blank_pos < 3: # Invalid move up
            continue
        if move == 'D' and blank_pos > 5: # Invalid move down
            continue
        if move == 'L' and blank_pos % 3 == 0: # Invalid move left
            continue
        if move == 'R' and blank_pos % 3 == 2: # Invalid move right
            continue

        new_board = move_tile(current_state.board, move, blank_pos)

        if tuple(new_board) in closed_list:
            continue

        new_state = PuzzleState(new_board, current_state, move, current_state.depth + 1,
                               current_state.depth + 1 + heuristic(new_board))
        heapq.heappush(open_list, new_state)

return None

# Function to print the solution path
def print_solution(solution):
    path = []
    current = solution
    while current:
        path.append(current)
        current = current.parent
    path.reverse()

    for step in path:
        print(f"Move: {step.move}")
        print_board(step.board)

```

```
# Initial state of the puzzle
initial_state = [1, 2, 3, 4, 0, 5, 6, 7, 8]

# Solve the puzzle using A* algorithm
solution = a_star(initial_state)

# Print the solution
if solution:
    print(colored("Solution found:", "green"))
    print_solution(solution)
else:
    print(colored("No solution exists.", "red"))
```

Program 4

Implement Hill Climbing search algorithm to solve N-Queens problem

Algorithm:

①	Hill Climbing: Algorithm: initialize arr[] with the graph points curr_value = arr[0] while & for (i=0; i<n; i++) neighbour = arr[i+1] if neighbour > curr_value: curr_value = neighbour return curr_value
---	---

Output:	SAJ Hill climbing A * A Tracing - Hill Climbing ① Hill climbing: 0 0 0 0 0 0 1 0 n 0 0 0 0 0 0 : attacking pairs 3 0 0 0 0 starts attacking 0 leftmost 0 0 0 0 attack count 0 at first most free ↓ → (0) P 0 0 0 0 0 0 0 0
---------	--

Code:

import random

```
def calculate_attacks(board):  
    """Calculates the number of attacking pairs on the board."""  
    n = len(board)  
    attacks = 0  
    for i in range(n):  
        for j in range(i + 1, n):  
            # Check row attacks  
            if board[i] == board[j]:  
                attacks += 1  
            # Check diagonal attacks  
            elif abs(board[i] - board[j]) == abs(i - j):  
                attacks += 1  
    return attacks
```

```
def hill_climbing_n_queens(n):  
    """Solves the N-Queens problem using Hill Climbing."""
```

```

# Initialize with a random board
current_board = [random.randint(0, n - 1) for _ in range(n)]
current_attacks = calculate_attacks(current_board)

while current_attacks > 0:
    best_neighbor_board = list(current_board)
    best_neighbor_attacks = current_attacks

    found_better_neighbor = False
    for col_to_move in range(n):
        for row_new_pos in range(n):
            if current_board[col_to_move] == row_new_pos:
                continue # Don't move to the same position

            temp_board = list(current_board)
            temp_board[col_to_move] = row_new_pos
            temp_attacks = calculate_attacks(temp_board)

            if temp_attacks < best_neighbor_attacks:
                best_neighbor_attacks = temp_attacks
                best_neighbor_board = list(temp_board)
                found_better_neighbor = True
            elif temp_attacks == best_neighbor_attacks and not found_better_neighbor:
                # If multiple neighbors have the same best attack count,
                # choose one randomly to avoid always picking the same one
                if random.random() < 0.5: # Simple tie-breaking
                    best_neighbor_board = list(temp_board)

    if not found_better_neighbor:
        # Stuck in a local optimum or reached a solution
        break
    current_board = best_neighbor_board
    current_attacks = best_neighbor_attacks

return current_board, current_attacks

# Example for 4-Queens
n = 4
solution, attacks = hill_climbing_n_queens(n)

print(f"Final board: {solution}")
print(f"Number of attacks: {attacks}")

if attacks == 0:
    print("Solution found!")
else:
    print("Stuck in a local optimum.")

```

Program 5

Simulated Annealing to Solve 8-Queens problem

Algorithm:

(2)	<u>Simulated Annealing:</u> <u>Algorithm:</u> given: arr[] of temperatures curr-temp = 40 next-temp \leftarrow neighbouring random value $T \leftarrow$ random largest integer while $T > 0$: $\Delta E \leftarrow$ curr-temp - next-temp if $\Delta E > 0$: curr-temp \leftarrow next-temp else: curr-temp \leftarrow next-temp with $p = e^{\Delta E/T}$ decrease T return curr-temp
-----	--

(2)	<u>Simulating annealing</u> 0 0 Q 0 (0)q0q.q0 Q, 0 0 0 0 0 0 Q state.00 0 Q 0 0 (0)00
-----	--

Code:

```
import random
import math

def calculate_attacks(board):
    """Calculates the number of attacking queen pairs on the board."""
    n = len(board)
    attacks = 0
    for i in range(n):
```

```

for j in range(i + 1, n):
    # Check horizontal attacks
    if board[i] == board[j]:
        attacks += 1
    # Check diagonal attacks
    if abs(board[i] - board[j]) == abs(i - j):
        attacks += 1
return attacks

def get_neighbor(board):
    """Generates a neighboring state by randomly moving one queen."""
    n = len(board)
    new_board = list(board)
    queen_to_move = random.randint(0, n - 1)
    new_position = random.randint(0, n - 1)
    new_board[queen_to_move] = new_position
    return tuple(new_board)

def simulated_annealing(n, initial_temperature, cooling_rate, iterations):
    """Solves the N-Queens problem using Simulated Annealing."""
    current_board = tuple(random.randint(0, n - 1) for _ in range(n))
    current_energy = calculate_attacks(current_board)
    best_board = current_board
    best_energy = current_energy
    temperature = initial_temperature

    for i in range(iterations):
        if temperature <= 0:
            break

        neighbor_board = get_neighbor(current_board)
        neighbor_energy = calculate_attacks(neighbor_board)

        # If neighbor is better, accept it
        if neighbor_energy < current_energy:
            current_board = neighbor_board
            current_energy = neighbor_energy
            if current_energy < best_energy:
                best_energy = current_energy
                best_board = current_board
        # If neighbor is worse, accept with a probability
        else:
            probability = math.exp((current_energy - neighbor_energy) / temperature)
            if random.random() < probability:
                current_board = neighbor_board
                current_energy = neighbor_energy

```

```

temperature *= cooling_rate

if current_energy == 0: # Found a solution
    break

return best_board, best_energy

def print_board(board):
    """Prints the N-Queens board."""
    n = len(board)
    for row in range(n):
        line = ["Q" if board[col] == row else "." for col in range(n)]
        print(" ".join(line))

if __name__ == "__main__":
    N = 4 # For the 4-Queens problem
    initial_temp = 100
    cooling_rate = 0.99
    num_iterations = 10000

    solution_board, solution_attacks = simulated_annealing(N, initial_temp, cooling_rate,
num_iterations)

    print(f"Final board configuration: {solution_board}")
    print(f"Number of attacks: {solution_attacks}")

    if solution_attacks == 0:
        print("\nSolution found:")
        print_board(solution_board)
    else:
        print("\nNo perfect solution found within iterations. Best found:")
        print_board(solution_board)

```

Program 6

Create a knowledge base using propositional logic and show that the given query entails the knowledge base or not.

Algorithm:

	KNOWLEDGE BASE						$\alpha \leftarrow \text{query}$	(S)
	FOR PROPOSITIONAL LOGIC						$\neg\neg\alpha \leftarrow \alpha$	
							$\alpha \vee \beta$	
Algorithm:	$\alpha \vee \beta$	$\neg\neg\alpha \leftarrow \alpha$	$\neg\beta \leftarrow \beta$	$\alpha \wedge \beta$	α	β	$\alpha \vee \beta$	$\neg\alpha \rightarrow \beta$
	0 1	1 0	1 1	1 0 1	1 0	1 1	1 1 0	0 1 1
function TT-checkenumeration					0 1	1 1		
return true or false					1 1	0 1		
inputs:	KB \leftarrow Knowledge Base of propositional logic!							
$\alpha \leftarrow$ query symbol	0 1	1 0						
symbols \leftarrow list of propositional logic symbols	0 1	1 0						
return TTcheckall (KB, α , symbols)	1 0 0							
	0 0 0	1 1	1 0	0 0 0				
function TTcheckall return true or false								
if Empty?								
symbols (true)	0 0 1	1 1 0	0 1 1	1 0 0				
if true then return True? (α ; model)	0 0 1	1 1 0	0 1 1	1 0 0				
else return \neg True	0 0 1	1 1 0	0 1 1	1 0 0				
else do								
P \leftarrow First(symbols)	0 0 1	1 1 0	0 1 1	1 0 0				
rest \leftarrow Rest(symbols)	0 0 1	1 1 0	0 1 1	1 0 0				
return TTcheckall (KB, α) $\cup \{P = \text{True}\}$	0 0 1	1 1 0	0 1 1	1 0 0				
and TTcheckall (KB, α) $\cup \{P = \text{False}\}$	0 0 1	1 1 0	0 1 1	1 0 0				
Output: True \rightarrow if KB $\models \alpha$	1 1 0							
false \rightarrow otherwise	1 1 0							

T-SAT								
(2)	$R \rightarrow P$							
	$P \rightarrow \neg Q$							
	$Q \vee R$							
	Truth Table							
	P	Q	R	$Q \rightarrow P$	$P \rightarrow \neg Q$	$Q \vee R$	$R \rightarrow P$	$\neg Q \wedge P$
1	1	1	1	1	0	1	0	0
1	1	0	0	1	1	1	1	1
1	0	1	1	0	1	1	1	1
0	1	0	0	1	0	0	0	0
0	0	0	0	1	1	0	0	0
0	0	1	0	0	1	1	0	1
0	0	0	1	1	0	1	1	1
0	0	0	1	1	1	1	1	1
	KB entails α							
(3)	$KB = (AVC) \wedge (B \vee \neg C)$							
	$\alpha = A \vee B$							
A	B	C	AVC	$B \vee \neg C$	KB	α		
0	0	0	0	1	0	0	0	0
0	0	1	0	1	0	0	0	0
0	1	0	0	1	1	1	1	1
0	1	1	0	0	1	1	1	1
1	0	0	0	1	0	0	1	1
1	0	1	0	1	0	1	1	1
1	1	0	0	1	1	1	1	1
1	1	1	0	1	1	1	1	1
	KB entails α $\{ (A, B) \} \wedge \{ (B, \neg C) \}$							
	Model 1: $\{ (A, B) \} \wedge \{ (B, \neg C) \}$							
	Model 2: $\{ (B, \neg C) \} \wedge \{ (A, B) \}$							
	Model 3: $\{ (A, B) \} \wedge \{ (B, \neg C) \} \wedge \{ (\neg C, C) \}$							
	Model 4: $\{ (B, \neg C) \} \wedge \{ (A, B) \} \wedge \{ (\neg C, C) \}$							
	Model 5: $\{ (A, B) \} \wedge \{ (\neg C, C) \}$							
	Model 6: $\{ (\neg C, C) \} \wedge \{ (A, B) \}$							
	Model 7: $\{ (\neg C, C) \} \wedge \{ (\neg C, C) \}$							
	Model 8: $\{ (A, B) \} \wedge \{ (B, \neg C) \} \wedge \{ (\neg C, C) \} \wedge \{ (\neg C, C) \}$							
	Model 9: $\{ (B, \neg C) \} \wedge \{ (A, B) \} \wedge \{ (\neg C, C) \} \wedge \{ (\neg C, C) \}$							
	Model 10: $\{ (\neg C, C) \} \wedge \{ (A, B) \} \wedge \{ (\neg C, C) \}$							
	Model 11: $\{ (\neg C, C) \} \wedge \{ (\neg C, C) \} \wedge \{ (A, B) \}$							
	Model 12: $\{ (\neg C, C) \} \wedge \{ (\neg C, C) \} \wedge \{ (\neg C, C) \}$							
	Model 13: $\{ (A, B) \} \wedge \{ (B, \neg C) \} \wedge \{ (\neg C, C) \} \wedge \{ (\neg C, C) \} \wedge \{ (\neg C, C) \}$							
	Model 14: $\{ (B, \neg C) \} \wedge \{ (A, B) \} \wedge \{ (\neg C, C) \} \wedge \{ (\neg C, C) \} \wedge \{ (\neg C, C) \}$							
	Model 15: $\{ (\neg C, C) \} \wedge \{ (A, B) \} \wedge \{ (\neg C, C) \} \wedge \{ (\neg C, C) \}$							
	Model 16: $\{ (\neg C, C) \} \wedge \{ (\neg C, C) \} \wedge \{ (A, B) \} \wedge \{ (\neg C, C) \}$							
	Model 17: $\{ (\neg C, C) \} \wedge \{ (\neg C, C) \} \wedge \{ (\neg C, C) \} \wedge \{ (\neg C, C) \}$							

Code:

```
import pandas as pd
import itertools

# Define propositions
props = ['P', 'Q', 'R']

# Generate all truth assignments for P, Q, R
truth_values = list(itertools.product([False, True], repeat=3))

def implies(a, b):
    return (not a) or b

# Evaluate KB sentences and entailments
rows = []
for (P, Q, R) in truth_values:
    sentence1 = implies(Q, P)      # Q -> P
    sentence2 = implies(P, not Q)   # P -> ¬Q
    sentence3 = Q or R            # Q ∨ R

    kb_true = sentence1 and sentence2 and sentence3

    entail_R = R
    entail_R_implies_P = implies(R, P)
    entail_Q_implies_R = implies(Q, R)

    rows.append({
        'P': P, 'Q': Q, 'R': R,
        'Q->P': sentence1,
        'P->¬Q': sentence2,
        'Q ∨ R': sentence3,
        'KB True': kb_true,
        'Entail R': entail_R,
        'Entail R->P': entail_R_implies_P,
        'Entail Q->R': entail_Q_implies_R
    })

# Create DataFrame
df = pd.DataFrame(rows)

# Filter models where KB is true
models_where_KB_true = df[df['KB True']]

# Print full truth table
print("Full Truth Table:\n")
```

```

print(df.to_string(index=False))

# Checking entailments (whether KB entails each sentence)
# KB entails a sentence if the sentence is true in all models where KB is true
entail_R_result = models_where_KB_true['Entail R'].all()
entail_R_implies_P_result = models_where_KB_true['Entail R->P'].all()
entail_Q_implies_R_result = models_where_KB_true['Entail Q->R'].all()

print("\nModels where KB is True:")
print(models_where_KB_true.to_string(index=False))

print("\nEntailment Results:")
print(f"Does KB entail R? {'Yes' if entail_R_result else 'No'}")
print(f"Does KB entail R -> P? {'Yes' if entail_R_implies_P_result else 'No'}")
print(f"Does KB entail Q -> R? {'Yes' if entail_Q_implies_R_result else 'No'}")

```

Program 7

Implement unification in first order logic

Algorithm:

zoholas		LAB 8	SV A = 70	(S)
24	35 40 35 A	3 8 A		
3	Unification Algorithm:	0 0 0		
4	0 0 0	1 0 0		
5	1: If ψ_1 or ψ_2 is a variable or constant then:			
6	a. If ψ_1 & ψ_2 are identical then return NIL			
7	b. Else if ψ_1 is a variable then:			
8	i. If ψ_1 occurs in ψ_2 then: return FAILURE			
9	ii. Else return $\{\psi_1 / \psi_2\}$			
10	iii. Else if ψ_2 is a variable then:			
11	If ψ_2 occurs in ψ_1 then: return FAILURE			
12	Else return $\{\psi_1 / \psi_2\}$			
13	d. Else return FAILURE			
14	2: If initial predicate symbols ψ_1 & ψ_2 are not same then return FAILURE			
15	3: If ψ_1 & ψ_2 have different no. of arguments then, return FAILURE			
16	4: Set substitution set(SUBST) to NIL			
17	5: For i=1 to no. of elements in ψ_1 :			
18	→ call unification function with i^{th} ele of ψ_1 & i^{th} ele of ψ_2 and put the result			
19	→ If S=FAIL return FAILURE			
20	→ If S ≠ NIL then do:			
21	a) Apply S to the remainder of both L1 & L2			
22	b) SUBST = APPEND(S, SUBST)			
23	6: Return SUBST			

①	P(f(x), g(y), z)	Date: 2023-07-17
	P(f(g(z)), g(f(a)), f(a))	Initials: f, g, P, a, z
	P = P	(a + no. of args) \rightarrow v
	same number of arguments	no. of args with numbers
	$x f(g(z)) \Rightarrow x g(z)$	$f(g(z)) \rightarrow f(g(z))$ \rightarrow v
	$y f(a) \rightarrow y f(a)$	$f(a) \rightarrow f(a)$ \rightarrow v
	∴ Unifiable $\Theta = \{x g(z), y f(a)\}$	$\Theta = \{x g(z), y f(a)\}$
②	R(x, f(x))	$(x a) \rightarrow v$
	R(f(y), y)	v: number
	$x f(y) \rightarrow (x a) \rightarrow v$	$x f(y) \rightarrow (x a) \rightarrow v$
	$\Rightarrow y, \text{in } \psi_2 \rightarrow \text{FAILS}$	$y, \text{in } \psi_2 \rightarrow \text{FAILS}$
	$\Theta = \{x a\} \rightarrow v$	$\Theta = \{x a\} \rightarrow v$
③	R(x, g(x))	$(x a) \rightarrow v$
	R(g(y), g(g(z)))	v: number
	$x g(y) \rightarrow (x a) \rightarrow v$	$x g(y) \rightarrow (x a) \rightarrow v$
	$g(y) g(g(z)) \rightarrow g(y) g(z) \rightarrow v$	$g(y) g(z) \rightarrow v$
	∴ Unifiable $\Theta = \{y z\}$	$\Theta = \{y z\}$

Code:

```
import re

def is_variable(x):
    return isinstance(x, str) and x[0].islower() and x.isalpha()

def parse_term(term):
    # Parses a function or constant or variable into structured form
    term = term.strip()
    if '(' not in term:
        return term
    functor, args_str = term.split('(', 1)
    args = []
    depth = 0
```

```

current = ""
for ch in args_str[:-1]: # skip last ')'
    if ch == ',' and depth == 0:
        args.append(parse_term(current.strip()))
        current = ""
    else:
        if ch == '(':
            depth += 1
        elif ch == ')':
            depth -= 1
        current += ch
if current:
    args.append(parse_term(current.strip()))
return (functor.strip(), args)

def occurs_check(var, x, subst):
    if var == x:
        return True
    elif isinstance(x, str):
        if x in subst:
            return occurs_check(var, subst[x], subst)
        return False
    elif isinstance(x, tuple):
        return any(occurs_check(var, arg, subst) for arg in x[1])
    return False

def substitute(x, subst):
    if isinstance(x, str):
        # If x is a variable and has a substitution, apply it recursively.
        # This handles chained substitutions like x -> y, y -> f(z).
        if x in subst:
            return substitute(subst[x], subst)
        else:
            # If it's not in the substitution, it's either a constant string
            # or a variable that hasn't been substituted yet.
            return x
    elif isinstance(x, tuple):
        functor, args = x
        return (functor, [substitute(arg, subst) for arg in args])
    return x

def unify(x, y, subst=None):
    if subst is None:
        subst = {}
    x = substitute(x, subst)
    y = substitute(y, subst)
    if x == y:

```

```

        return subst
    elif is_variable(x):
        if occurs_check(x, y, subst):
            raise ValueError(f"Occurs check failed for {x} in {y}")
        subst[x] = y
        return subst
    elif is_variable(y):
        if occurs_check(y, x, subst):
            raise ValueError(f"Occurs check failed for {y} in {x}")
        subst[y] = x
        return subst
    elif isinstance(x, tuple) and isinstance(y, tuple):
        if x[0] != y[0] or len(x[1]) != len(y[1]):
            raise ValueError(f"Functor mismatch: {x[0]} vs {y[0]}")
        for a, b in zip(x[1], y[1]):
            subst = unify(a, b, subst)
        return subst
    else:
        raise ValueError(f"Cannot unify {x} with {y}")

# ----- Test -----
x = parse_term("P(f(x), g(y), y)")
y = parse_term("P(f(g(z)), g(f(a)), f(a))")

print("Parsed terms:")
print("x =", x)
print("y =", y)

try:
    result = unify(x, y)
    print("\nUnification successful!")
    print("Substitution set:")
    for var, val in result.items():
        print(f" {var} = {val}")
except ValueError as e:
    print("\nUnification failed:", e)

```

Program 8

Create a knowledge base consisting of first order logic statements and prove the given query using forward reasoning.

Algorithm:

10.	CNF form of Q + (assumption) rules
	$\forall x \neg \forall y \neg (\text{Animal}(y) \vee \text{Loves}(x, y)) \vee \exists y \text{Loves}(y, x)$
	$\forall x \neg \forall y (\neg \text{Animal}(y) \wedge \neg \text{Loves}(x, y)) \vee \exists y \text{Loves}(y, x)$
	$\forall x \exists y (\text{Animal}(y) \vee \text{Loves}(x, y)) \vee \exists y \text{Loves}(y, x)$
	$\forall x \exists y \exists z [\text{Animal}(y) \vee \text{Loves}(x, y) \vee \text{Loves}(z, x)]$
	$\forall x [\text{Animal}(g(x)) \vee \text{Loves}(x, g(x)) \vee \text{Loves}(f(x), x)]$
	$\text{Animal}(g(x)) \vee \text{Loves}(x, g(x)) \vee \text{Loves}(f(x), x)$
11.	Knowledge Base
	$\text{Man}(\text{Marcus})$
	$\text{Pompeian}(\text{Marcus})$
	$\forall x (\text{Pompeian}(x) \rightarrow \text{Roman}(x))$
	$\forall x (\text{Roman}(x) \rightarrow \text{Loyal}(x))$
	$\forall x (\text{Man}(x) \rightarrow \text{Person}(x))$
	$\forall x (\text{Person}(x) \rightarrow \text{Mortal}(x))$
	Query $\text{mortal}(\text{marcus})$
	Sol: $\forall x (\text{Pompeian}(x) \rightarrow \text{Roman}(x)) \text{ and } \text{Pompeian}(\text{marcus})$
	$\Rightarrow \text{Roman}(\text{marcus})$
	$\forall x (\text{Roman}(x) \rightarrow \text{Loyal}(x)) \text{ and } \text{Roman}(\text{marcus})$
	$\Rightarrow \text{Loyal}(\text{marcus})$
	$\forall x (\text{man}(x) \rightarrow \text{Person}(x)) \text{ and } \text{man}(\text{marcus})$
	$\Rightarrow \text{Person}(\text{marcus})$
	$\forall x (\text{Person}(x) \rightarrow \text{Mortal}(x)) \text{ and } \text{person}(\text{marcus})$
	$\Rightarrow \text{mortal}(\text{marcus})$

man (marcus)	$\forall x [\text{man}(x) \rightarrow \text{Person}(x)]$
	$\text{Person}(\text{marcus})$
	$\forall x [\text{Person}(x) \rightarrow \text{Mortal}(x)]$
	$\text{mortal}(\text{marcus})$
	$(\text{man}(\text{marcus}) \wedge \forall x [\text{man}(x) \rightarrow \text{Person}(x)]) \rightarrow \text{Person}(\text{marcus})$
	$(\text{Person}(\text{marcus}) \wedge \forall x [\text{Person}(x) \rightarrow \text{Mortal}(x)]) \rightarrow \text{mortal}(\text{marcus})$
	$(\text{man}(\text{marcus}) \wedge \forall x [\text{man}(x) \rightarrow \text{Person}(x)] \wedge \forall x [\text{Person}(x) \rightarrow \text{Mortal}(x)]) \rightarrow \text{mortal}(\text{marcus})$
	$(\text{man}(\text{marcus}) \wedge \forall x [\text{man}(x) \rightarrow \text{Person}(x)] \wedge \forall x [\text{Person}(x) \rightarrow \text{Mortal}(x)]) \rightarrow \text{mortal}(\text{marcus})$

Code:

```
import re

# -----
# Helper functions
# -----

def eliminate_implications(expr):
    """Eliminate implications (A -> B becomes ~A | B)."""
    expr = re.sub(r'\((.*?))->\((.*?))', r'(\1)|\2)', expr)
    return expr

def move_not_inwards(expr):
    """Apply De Morgan's laws and double negation elimination."""
    expr = expr.replace("~~", "")
    expr = expr.replace("~(A&B)", "(~A|~B)")
    expr = expr.replace("~(A|B)", "(~A&~B)")
    return expr

def standardize_variables(expr):
    """Rename variables to avoid clashes."""
    # For demo, just ensure lowercase vars get unique suffixes
    var_map = {}
    count = 0
    new_expr = ""
    for ch in expr:
        if ch.islower() and ch.isalpha():
            if ch not in var_map:
                var_map[ch] = chr(ord('a') + count)
                count += 1
            new_expr += var_map[ch]
        else:
            new_expr += ch
    return new_expr

def skolemize(expr):
    """Replace existential quantifiers with Skolem constants/functions."""
    expr = re.sub(r'\exists [a-z]\.', "", expr) # Remove existential quantifier
    return expr.replace("x", "c") # Replace var with Skolem constant (simple demo)

def drop_universal(expr):
    """Remove universal quantifiers (implicit in CNF)."""
    expr = re.sub(r'\forall [a-z]\.', "", expr)
    return expr

def distribute_or_over_and(expr):
```

```

"""Simplified distribution (only handles basic patterns)."""
# In a full implementation you'd need a tree structure, not regex.
return expr.replace("|", "\vee").replace("&", "\wedge")

# -----
# Main CNF conversion function
# -----


def fol_to_cnf(expr):
    print("Original:", expr)
    expr = eliminate_implications(expr)
    print("→ No implications:", expr)
    expr = move_not_inwards(expr)
    print("→ Negations inward:", expr)
    expr = standardize_variables(expr)
    print("→ Standardized vars:", expr)
    expr = skolemize(expr)
    print("→ Skolemized:", expr)
    expr = drop_universal(expr)
    print("→ Dropped universals:", expr)
    expr = distribute_or_over_and(expr)
    print("→ CNF form:", expr)
    return expr

# -----
# Example usage
# -----


formula = "∀ x.(P(x) -> ∃ y.(Q(y) & R(x,y)))"
cnf = fol_to_cnf(formula)
print("\nFinal CNF:", cnf)

# Simple Forward Reasoning (Forward Chaining) in FOL

# Knowledge Base (Facts + Rules)
# Rules are written in the form: (premises, conclusion)
# Facts are just single statements

def forward_chaining(kb, query):
    facts = set()
    rules = []

    # Separate facts and rules
    for statement in kb:
        if "=>" in statement:
            premises, conclusion = statement.split("=>")
            premises = set(p.strip() for p in premises.split("&"))

    # Add facts to the knowledge base
    kb.add(facts)

```

```

        rules.append((premises, conclusion.strip()))
else:
    facts.add(statement.strip())

print("Initial Facts:", facts)
print("Rules:", rules)
print("Query:", query)

inferred = True
while inferred:
    inferred = False
    for premises, conclusion in rules:
        # Check if all premises are in facts
        if premises.issubset(facts) and conclusion not in facts:
            facts.add(conclusion)
            print(f"Inferred: {conclusion}")
            inferred = True
            if conclusion == query:
                print("Query proven!")
                return True

print("Query cannot be proven.")
return False

# Example Knowledge Base
kb = [
    "A",                      # Fact
    "A & B => C",          # Rule 1
    "C => D",                # Rule 2
    "D & E => F",          # Rule 3
    "B"                      # Fact
]
query = "D"

# Run forward chaining
forward_chaining(kb, query)

```

Program 9

Create a knowledge base consisting of first order logic statements and prove the given query using Resolution

Algorithm:

$(x \text{ likes}(x)) \vee (x \text{ boot}) \vdash \text{RESOLUTION}$	
For start?	
Algorithm:	
$\neg S \vee (S) \text{ boot} \vdash (\neg S) \text{ boot} \vdash \text{ (Answer)}$	
1: Convert all sentences to CNF	
2: Negate conclusion $S \neg \&$ Convert result to CNF	
3: Add negated conclusion ($\neg S$) to the premise clauses	
4: Repeat until contradiction or no progress is made	
a. Select 2 clauses (call them parent clauses)	
b. Resolve them together, performing all required unifications	
c. If resolvent is the empty clause, a contradiction has been found	
d. If not, add resolvent to premises	
Example: having result	
Premises: $\neg \text{food}(x) \vee \text{likes}(\text{John}, x)$	
$\text{food}(\text{Apple})$	
$\text{food}(\text{vegetables})$	
$\neg \text{eats}(y, z) \vee \text{killed}(y) \vee \text{food}(z)$	
$\text{eats}(\text{Anil}, \text{Peanuts})$	
$\text{alive}(\text{Anil})$	
$\neg \text{eats}(\text{Anil}, w) \vee \text{eats}(\text{Harry}, w)$	
$\text{killed}(g) \vee \text{alive}(g)$	
$\neg \text{alive}(k) \vee \neg \text{killed}(k)$	
$\text{likes}(\text{John}, \text{Peanuts})$	

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Resolution:

$\neg \text{likes}(\text{John}, \text{Peanuts}) \quad \neg \text{food}(x) \vee \text{likes}(\text{John}, x)$

$\neg \text{Food}(\text{Peanuts}) \quad \neg \text{eats}(y, z) \vee \text{killed}(y) \vee \text{food}(z)$

$\neg \text{eats}(y, \text{Peanuts}) \vee \text{killed}(y) \quad \neg \text{eats}(\text{Anil}, \text{peanuts})$

$\neg \text{killed}(\text{Anil}) \quad \neg \text{alive}(k) \vee \neg \text{killed}(k)$

$\neg \text{alive}(\text{Anil}) \quad \text{alive}(\text{Anil})$

{ } Hence proved

Code:

```
# Simple Forward Reasoning (Forward Chaining) in FOL
# Knowledge Base (Facts + Rules)
# Rules are written in the form: (premises, conclusion)
# Facts are just single statements
```

```
def forward_chaining(kb, query):
    facts = set()
    rules = []

    # Separate facts and rules
    for statement in kb:
        if "=>" in statement:
            premises, conclusion = statement.split("=>")
            premises = set(p.strip() for p in premises.split("&"))
            rules.append((premises, conclusion.strip()))
        else:
            facts.add(statement.strip())
```

```

print("Initial Facts:", facts)
print("Rules:", rules)
print("Query:", query)

inferred = True
while inferred:
    inferred = False
    for premises, conclusion in rules:
        # Check if all premises are in facts
        if premises.issubset(facts) and conclusion not in facts:
            facts.add(conclusion)
            print(f"Inferred: {conclusion}")
            inferred = True
        if conclusion == query:
            print("Query proven!")
            return True

print("Query cannot be proven.")
return False

# Example Knowledge Base
kb = [
    "A",           # Fact
    "A & B => C",   # Rule 1
    "C => D",       # Rule 2
    "D & E => F",   # Rule 3
    "B"           # Fact
]
query = "D"

# Run forward chaining
forward_chaining(kb, query)

Resolution:
!pip install sympy

from sympy import symbols, Or, Not, And
from sympy.logic.inference import satisfiable

# Define propositional atoms (grounded)
food_Apple, food_Veg, food_Peanuts = symbols('food_Apple food_Veg food_Peanuts')
likes_John_Apple, likes_John_Veg, likes_John_Peanuts = symbols('likes_John_Apple'
                                                               'likes_John_Veg likes_John_Peanuts')
eats_Anil_Peanuts, killed_Anil, alive_Anil = symbols('eats_Anil_Peanuts killed_Anil alive_Anil')


```

```

# --- Knowledge Base (grounded CNF clauses) ---
KB = [
    Or(Not(food_Peanuts), likes_John_Peanuts),    # a.  $\neg$ food(Peanuts)  $\vee$  likes(John, Peanuts)
    food_Apple,                                # b. food(Apple)
    food_Veg,                                   # c. food(vegetables)
    Or(Not(eats_Anil_Peanuts), killed_Anil, food_Peanuts), # d.  $\neg$ eats(Anil, Peanuts)  $\vee$  killed(Anil)
    \ food(Peanuts)
    eats_Anil_Peanuts,                      # e. eats(Anil, Peanuts)
    alive_Anil,                            # f. alive(Anil)
    Or(killed_Anil, Not(alive_Anil)),      # h. killed(Anil)  $\vee$   $\neg$ alive(Anil)
    Or(Not(alive_Anil), Not(killed_Anil))  # i.  $\neg$ alive(Anil)  $\vee$   $\neg$ killed(Anil)
]
# --- Negated conclusion ---
negated_conclusion = Not(likes_John_Peanuts)
KB.append(negated_conclusion)

# --- Check satisfiability ---
result = satisfiable(And(*KB))

if result is False:
    print("Conclusion PROVED by resolution: likes(John, Peanuts)")
else:
    print("Conclusion NOT proved.")
    print("Satisfying model (means no contradiction):")
    print(result)

```

Program 10

Implement Alpha-Beta Pruning.

Algorithm:

ALPHA-BETA PRUNING:

Function Alpha-Beta-Search (state) returns an action
 $v \leftarrow \text{MAX-VALUE} (\text{state}, -\infty, +\infty)$
return the action in ACTIONS (state) with value v

function MAX-VALUE (state, α , β) returns a utility value
if TERMINAL-TEST (state) then return UTILITY (state)
 $v \leftarrow -\infty$
for each a in ACTIONS (state) do
 $v \leftarrow \max (v, \text{MIN-VALUE} (\text{RESULT} (s, a), \alpha, \beta))$
if $v \geq \beta$ then return v
 $\alpha \leftarrow \max (\alpha, v)$
return v

function MIN-VALUE (state, α , β) returns a utility value
if TERMINAL-TEST (state) then return UTILITY (state)
 $v \leftarrow +\infty$
for each a in ACTIONS (state) do
 $v \leftarrow \min (v, \text{MAX-VALUE} (\text{RESULT} (s, a), \alpha, \beta))$
if $v \leq \alpha$ then return v
 $\beta \leftarrow \min (\beta, v)$
return v

Output: Initial State : [1, 2, 0, 3, 4, 5, 6, 7, 8] \rightarrow
Initial Depth: 5 \rightarrow
Best Value found: 11
The return of the alpha-beta pruning is: 11

Code:

```
import math

def alpha_beta_pruning(state, depth, alpha, beta, maximizing_player):
    # Base case: leaf node or maximum depth reached
    if depth == 0 or is_goal_state(state):
        return heuristic_value(state)
```

```

if maximizing_player:
    max_eval = -math.inf
    for child_state in get_possible_moves(state):
        eval = alpha_beta_pruning(child_state, depth - 1, alpha, beta, False)
        max_eval = max(max_eval, eval)
        alpha = max(alpha, eval)
        if beta <= alpha:
            break # Beta cutoff
    return max_eval
else: # Minimizing player
    min_eval = math.inf
    for child_state in get_possible_moves(state):
        eval = alpha_beta_pruning(child_state, depth - 1, alpha, beta, True)
        min_eval = min(min_eval, eval)
        beta = min(beta, eval)
        if beta <= alpha:
            break # Alpha cutoff
    return min_eval

def is_goal_state(state):
    """Checks if the current state is the solved 8-puzzle."""
    # Assuming the goal state is a flattened list [1, 2, 3, 4, 5, 6, 7, 8, 0]
    return state == [1, 2, 3, 4, 5, 6, 7, 8, 0]

def heuristic_value(state):
    """Calculates the Manhattan distance heuristic for the 8-puzzle."""
    goal_state = {
        1: (0, 0), 2: (0, 1), 3: (0, 2),
        4: (1, 0), 5: (1, 1), 6: (1, 2),
        7: (2, 0), 8: (2, 1), 0: (2, 2)
    }
    manhattan_distance = 0
    for i in range(3):
        for j in range(3):
            tile = state[i * 3 + j]
            if tile != 0:
                goal_pos = goal_state[tile]
                manhattan_distance += abs(i - goal_pos[0]) + abs(j - goal_pos[1])
    return manhattan_distance

def get_possible_moves(state):
    """Returns a list of all possible next states from the current state."""
    possible_moves = []
    zero_index = state.index(0)
    zero_row, zero_col = divmod(zero_index, 3)

    # Define possible movements (up, down, left, right)

```

```

movements = [(-1, 0), (1, 0), (0, -1), (0, 1)]

for move_row, move_col in movements:
    new_row, new_col = zero_row + move_row, zero_col + move_col

    # Check if the new position is within the board boundaries
    if 0 <= new_row < 3 and 0 <= new_col < 3:
        new_state = list(state) # Create a mutable copy of the state
        swap_index = new_row * 3 + new_col
        # Swap the blank tile with the tile at the new position
        new_state[zero_index], new_state[swap_index] = new_state[swap_index],
        new_state[zero_index]
        possible_moves.append(new_state)

return possible_moves
initial_state = [1, 2, 0, 3, 4, 5, 6, 7, 8]
initial_depth = 5

print(f"Initial State: {initial_state}")
print(f"Initial Depth: {initial_depth}")
best_value = alpha_beta_pruning(initial_state, initial_depth, -math.inf, math.inf, True)
print(f"Best value found: {best_value}")
print(f"The result of the alpha-beta pruning (best value from the initial state) is: {best_value}")

```

Minimax:

```

import math

# Represents the players
X = 'X'
O = 'O'
EMPTY = ''

def check_winner(board):
    """
    Checks if there's a winner on the board.
    Returns X if X wins, O if O wins, None if no winner yet, or 'Tie' if full and no winner.
    """
    # Check rows
    for row in board:
        if row[0] == row[1] == row[2] and row[0] != EMPTY:
            return row[0]
    # Check columns
    for col in range(3):
        if board[0][col] == board[1][col] == board[2][col] and board[0][col] != EMPTY:
            return board[0][col]
    # Check diagonals

```

```

if board[0][0] == board[1][1] == board[2][2] and board[0][0] != EMPTY:
    return board[0][0]
if board[0][2] == board[1][1] == board[2][0] and board[0][2] != EMPTY:
    return board[0][2]

# Check for tie (no winner and board is full)
if all(cell != EMPTY for row in board for cell in row):
    return 'Tie'

return None

def minimax(board, is_maximizing_player):
    """
    Implements the Minimax algorithm to find the optimal move.
    is_maximizing_player is True for 'X' (AI), False for 'O' (opponent).
    """
    winner = check_winner(board)
    if winner == X:
        return 1 # X wins, maximizing player gets a high score
    elif winner == O:
        return -1 # O wins, minimizing player gets a low score
    elif winner == 'Tie':
        return 0 # Tie game

    if is_maximizing_player:
        best_score = -math.inf
        for r in range(3):
            for c in range(3):
                if board[r][c] == EMPTY:
                    board[r][c] = X # Make the move
                    score = minimax(board, False)
                    board[r][c] = EMPTY # Undo the move
                    best_score = max(best_score, score)
        return best_score
    else: # Minimizing player
        best_score = math.inf
        for r in range(3):
            for c in range(3):
                if board[r][c] == EMPTY:
                    board[r][c] = O # Make the move
                    score = minimax(board, True)
                    board[r][c] = EMPTY # Undo the move
                    best_score = min(best_score, score)
        return best_score

def find_best_move(board):
    """
    """

```

```

Finds the best move for the AI (X) using the Minimax algorithm.
"""

best_score = -math.inf
best_move = None

for r in range(3):
    for c in range(3):
        if board[r][c] == EMPTY:
            board[r][c] = X # Try the move
            score = minimax(board, False) # Evaluate the board state
            board[r][c] = EMPTY # Undo the move

            if score > best_score:
                best_score = score
                best_move = (r, c)
return best_move

def print_board(board):
    """Prints the Tic-Tac-Toe board."""
    for row in board:
        print("|".join(row))
    print("----")

# Example usage:
if __name__ == "__main__":
    # Initial empty board
    board = [[EMPTY, EMPTY, EMPTY],
              [EMPTY, EMPTY, EMPTY],
              [EMPTY, EMPTY, EMPTY]]

    current_player = X

    while check_winner(board) is None:
        print_board(board)
        if current_player == X:
            print("AI's turn (X)")
            move = find_best_move(board)
            if move:
                board[move[0]][move[1]] = X
            else:
                print("No valid moves left for AI.")
                break
        else:
            print("Human's turn (O)")
            while True:
                try:
                    row = int(input("Enter row (0-2): "))

```

```
col = int(input("Enter column (0-2): "))
if 0 <= row <= 2 and 0 <= col <= 2 and board[row][col] == EMPTY:
    board[row][col] = O
    break
else:
    print("Invalid move. Try again.")
except ValueError:
    print("Invalid input. Please enter numbers.")

current_player = O if current_player == X else X

print_board(board)
final_result = check_winner(board)
if final_result == 'Tie':
    print("It's a Tie!")
elif final_result:
    print(f"Player {final_result} wins!")
else:
    print("Game ended unexpectedly.")
```