



INTRODUCTION TO COMMUNICATION SYSTEMS **(CT216)**

Matlab code and Results :

Lab Group - 2 : Project Group - 2

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TOPIC : CONVOLUTIONAL CODING

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Honor code :

- The work that we are presenting is our own work.
- We have not copied the work (the code, the results, etc.) that someone else has done.
- Concepts, understanding and insights we will be describing are our own.
- We make this pledge truthfully.
- We know that violation of this solemn pledge can carry grave consequences.

```

%Encoding
function ans = encoding(kc, generation_polynomials, inp)
    n = length(generation_polynomials);
    ans = [];
    regval = 0;
    for i = 1:length(inp)
        curbit = inp(i);
        regval = bitor(bitshift(regval, -1), bitshift(curbit, (kc - 1)));
        for j = 1:n
            cur_poly = generation_polynomials(j);
            output = 0;
            p=dec2bin(cur_poly,kc);
            p=fliplr(p)-'0';
            rv=dec2bin(regval,kc)-'0';
            output=0;
        for k=1:kc
            output=xor(output,(p(k) & rv(k)));
        end
        ans = [ans, output];
    end
end
end

%soft_decoding
function ans = decoding_soft(kc, generation_polynomials, inp)
    ns = bitshift(1, (kc-1));
    n = length(generation_polynomials);
    mtr = ones(floor(length(inp)/n) + 1, ns) * 1e9;
    previous_states = cell(floor(length(inp)/n) + 1, 1);
    for i = 1:length(previous_states)
        previous_states{i} = cell(ns, 1);
    for j = 1:ns
        previous_states{i}{j} = {1e9, 1e9};
    end
    end
    idx = 0;
    for t = 1:(length(inp)/n)
        for st = 0:ns-1
            if (t == 1) && (st == 0)
                mtr(t, st+1) = 0;
            end
            for input_bits = 0:1
                curstate = st;
                next_state = bitor(bitshift(curstate, -1),(input_bits * ...
bitshift(1, (kc-2))));
                euclidian_distance = 0;
            for i = 1:n
                output = 0;
                poly = generation_polynomials(i);

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        regvalue = bitor(curstate, bitshift(input_bits, (kc-1)));
    for k = 0:(kc-1)
        output = bitxor(output, bitand(bitshift(poly, -k),
        ...
        1) & bitand(bitshift(regvalue, -(kc-k-1)), 1));
    end
        output=1-2*output;
        euclidian_distance=euclidian_distance+(abs(output-...
inp(idx+i))*abs(output-inp(idx+i)));
    end
        euclidian=sqrt(euclidian_distance);
        a = mtr(t+1, next_state+1);
        b = mtr(t, curstate+1);
    if a > b + euclidian_distance
        mtr(t+1, next_state+1) = b + euclidian_distance;
        previous_states{t+1}{next_state+1} =
{curstate,input_bits};
    end
end
end
    idx = idx + n;
end
    ans = [];
    temp = previous_states{(length(inp)/n)+1}{1};
    ans = [temp{2} ans];
    cur = (length(inp)/n);
    while cur >1
        temp = previous_states{cur}{temp{1}+1};
        ans = [temp{2} ans];
        cur = cur - 1;
    end
end

%modulator
function modulated_op = modulator(encoded_message,sigma)
    s = 1 - 2 * encoded_message; % BPSK modulation
    modulated_op= s + sigma * randn(1, length(encoded_message));
end

%hard_decoding
function ans = decoding(kc, generation_polynomials, inp)
    ns = bitshift(1, (kc-1));
    n = length(generation_polynomials);
    mtr = ones(floor(length(inp)/n) + 1, ns) * 1e9;
    previous_states = cell(floor(length(inp)/n) + 1, 1);
    for i = 1:length(previous_states)
        previous_states{i} = cell(ns, 1);
        for j = 1:ns

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        previous_states{i}{j} = {1e9, 1e9};
    end
end
idx = 0;
for t = 1:(length(inp)/n)
    for st = 0:ns-1
        if (t == 1) && (st == 0)
            mtr(t, st+1) = 0;
        end
        for input_bits = 0:1
            curstate = st;
            next_state = bitor(bitshift(curstate, -1), (input_bits *
bitshift(1, (kc-2))));
            hamming_distance = 0;
            for i = 1:n
                output = 0;
                poly = generation_polynomials(i);
                regvalue = bitor(curstate, bitshift(input_bits, (kc-1)));
                for k = 0:(kc-1)
                    output = bitxor(output, bitand(bitshift(poly, -k),
1) & bitand(bitshift(regvalue, -(kc-k-1)), 1));
                end
                if output ~= inp(idx+i)
                    hamming_distance = hamming_distance + 1;
                end
            end
            a = mtr(t+1, next_state+1);
            b = mtr(t, curstate+1);
            if a > b + hamming_distance
                mtr(t+1, next_state+1) = b + hamming_distance;
                previous_states{t+1}{next_state+1} =
{curstate,input_bits};
            end
        end
    end
    idx = idx + n;
end
ans = [];
temp = previous_states{(length(inp)/n)+1}{1};
ans = [temp{2} ans];
cur = (length(inp)/n);
while cur > 1
    temp = previous_states{cur}{temp{1}+1};
    ans = [temp{2} ans];
    cur = cur - 1;
end
end

```

```

EbNodB = 0:0.5:10;
R = 1/2;
k =1;
n =2;
kc = 3;
practical_error = zeros(1,length(EbNodB));
theoratical_error = zeros(1,length(EbNodB));
soft_error=zeros(1,length(EbNodB));
idx =1;
idx2=1;
N = 5000;
for j=EbNodB
    EbNo = 10^(j/10);
    sigma = sqrt (1/(2*R*EbNo));
    BER_th = 0.5*erfc(sqrt(EbNo));
    Nerrs = 0;
    Nerr_soft=0;
    for i = 1 : N
        msg = randi ([0 1],1,100); %generate random message
        msg=[msg zeros(1,kc-1)];
        encoded_array=encoding(kc,[5 7],msg);
        modulated_message=modulator(encoded_array,sigma);
        demodualted_message=modulated_message<0;
        decoded_message=decoding(kc,[5 7],demodualted_message);
        soft_decoded_message=decoding_soft(kc,[5 7],modulated_message);
        Nerr_soft=Nerr_soft+sum(soft_decoded_message~=msg);
        Nerrs=Nerrs+sum(msg ~= decoded_message);
    end
    soft_error(idx)=(Nerr_soft)/(N*length(msg));
    practical_error(idx) = (Nerrs/(N*length(msg)));
    theoratical_error(idx2) = theoratical_error(idx2)+BER_th;
    idx = idx+1;
    idx2 = idx2+1;
end
semilogy(EbNodB,practical_error,'LineWidth',2.0);
hold on;
semilogy(EbNodB,theoratical_error,'LineWidth',2.0);
semilogy(EbNodB,soft_error,'LineWidth',2.0);
legend('Hard error','Theoretical error','Soft error');
title('kc=3 rate=1/2');
%xlim([0 1]);
xlabel('EbNo(dB)');
ylabel('BER');
hold off;

```

