#### SINGLE STAGE AMPLIFIER

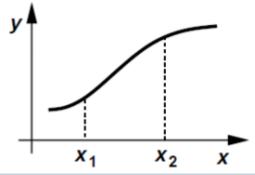
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BASIC CONCEPTS, COMMON SOURCE STAGE, SOURCE FOLLOWER, COMMON GATE STAGE, CASCODE STAGE

# **Ideal vs Non-ideal Amplifier**

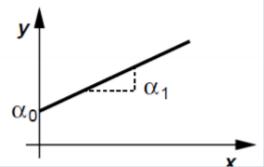
The input and output characteristics of an amplifier is generally a nonlinear function as shown in fig.(Nonlinear amplifier)

$$y(t) = \alpha_0 + \alpha_1 x(t) + \alpha_2 x^2(t) + \dots + \alpha_n x^n(t).$$



- Input and output may be current or voltage quantities
- For an ideal amplifier

$$y(t) = \alpha_0 + \alpha_1 x(t)$$



- 3
- $\alpha_0$  is the "dc bias" (operating point)
- $\alpha_1$  is the "small signal gain"

$$y(t) = \alpha_0 + \alpha_1 x(t)$$

• As long as  $\alpha_1 x(t) << \alpha_0$ , the bias point is disturbed negligibly and higher order terms are insignificant.

$$y(t) = \alpha_0 + \alpha_1 x(t) + \alpha_2 x^2(t) + \dots + \alpha_n x^n(t)$$

- $\Delta y = \alpha_1 \Delta x$ , indicating a linear relationship between the increments at the input and output.
- As x(t) increases in magnitude, higher order terms manifest themselves. Leading to nonlinearity and necessitating large signal analysis.
- Causes distortion of signal of interest

# Analog Design Trade off

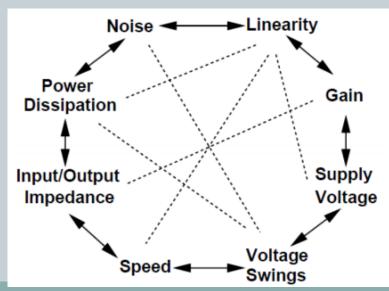
(What aspects of the performance of an amplifier are important?)

- Along with gain and speed, such parameters as power dissipation, supply voltage, linearity, noise or maximum voltage swing may be important.
- Input and output impedances decide interaction with preceding and subsequent stages
- Performance parameters trade with each other
- Multi-dimensional optimization problem

design of analog circuits is the art of finding the right trade-off between conflicting constraints or specifications such as power, noise, linearity, gain, supply voltage, voltage swing, speed and input/output impedance as illustrated by the "analog design octagon"

**Analog-Design Octagon -**

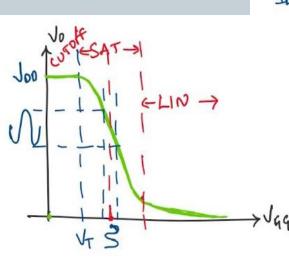
Such trade-offs present many challenges in the design of high-performance amplifiers, requiring intuition and experience to arrive at an acceptable compromise

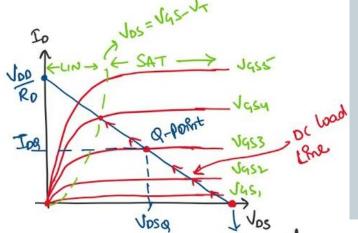


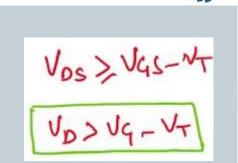
By virtue of MOSFET's transconductance,, a MOSFET changes in its gatesource voltage to a small-signal drain current, which can pass through a resistor to generate an output voltage  $V_{DD}$ 

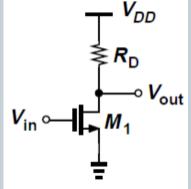


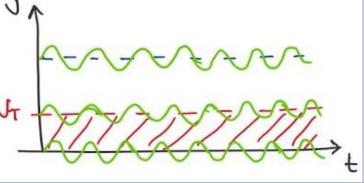
 in Linear region MOSFET works as linear voltage controlled resistor
 so, MOSFET should be in saturation to works as amplifier











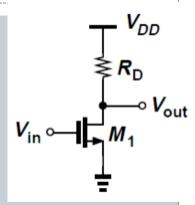
- For Vin < VTH,</li>
  - M1is off
  - o and Vout = VDD
- When Vin is slightly greater then Vth,
  - M1is ON and operates in saturation



As Vin approaches Vth, M1 begins to turn on, drawing current from Rd and lowering Vout.

M1 turns ON in saturation regardless of the Values of Vdd and Rd.
 Vout = Vdd − IdRd

$$V_{out} = V_{DD} - R_D \frac{1}{2} \mu_n C_{ox} \frac{W}{L} (V_{in} - V_{TH})^2$$



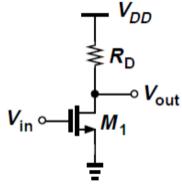
 $V_{\text{out}}$ 

 $V_{DD}$ 

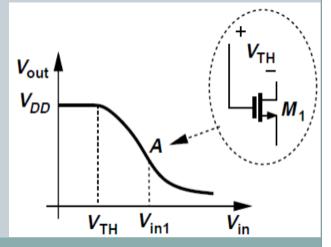


- Further increase in Vin, Vout drops more and the transistor continues to operates in saturation until Vin exceeds Vout by Vth.
- At point A Vout = Vin1 -Vth
- When Vin > Vin1
  - M1is ON and operates in Linear / Triode
  - Vout decreases

$$V_{out} = V_{DD} - R_D \frac{1}{2} \mu_n C_{ox} \frac{W}{L} \left[ 2(V_{in} - V_{TH}) V_{out} - V_{out}^2 \right] - (2)$$



• When Vin is high enough  $\rightarrow$ 



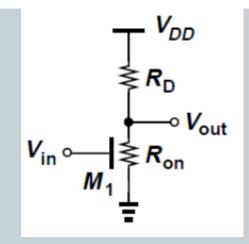
8

#### When Vin is high enough →

M1 drive into deep triode region, Vout << 2(vgs-Vth) and the equivalent circuit is

$$V_{out} = V_{DD} \frac{R_{on}}{R_{on} + R_D}$$

$$= \frac{V_{DD}}{1 + \mu_n C_{ox} \frac{W}{L} R_D (V_{in} - V_{TH})}$$
(3)



But 
$$g_m = \mu_n C_{ox} \frac{W}{L} (V_{GS} - V_{TH})$$

$$\begin{aligned} & \text{Ron} = \underline{\text{Vout}} \\ & \text{ID} \\ & \text{Rout} = \underline{\text{Vout}} \\ & \frac{1}{2} \mu_n C_{ox} \, \frac{W}{L} \, [2(V_{GS} - V_{TH}) V_{DS} - V_{DS}^2]. \end{aligned}$$
 Since Vout is very low after point A in input and output characteristics

$$\left(R_{on} = \frac{1}{\mu_n C_{ox} \frac{W}{L} (V_{GS} - V_{TH})}\right)$$

9

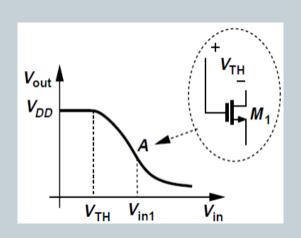
• Taking derivative of ID equation in saturation region, small-signal gain is obtained

$$A_v = \frac{\partial V_{out}}{\partial V_{in}}$$

Using equation (1)

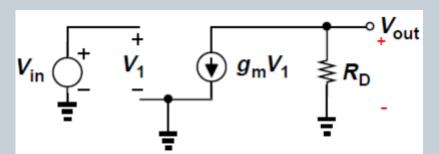
$$A_{v} = -R_{D}\mu_{n}C_{ox}\frac{W}{L}(V_{in} - V_{TH})$$

$$A_{v} = -g_{m}R_{D}.$$
(4)



10

• Same result is obtained from small-signal equivalent circuit



this result can be directly derived from the observation that, M1 converts an input voltage change  $\Delta$ Vin to a drain current change gm  $\Delta$ Vin, and hence an output voltage change

$$V_{out} = -g_m V_1 R_D = -g_m V_{in} R_D$$

$$A_v = -g_m R_D$$

- Since gm itself varies with the input signal according to  $\mu_n C_{ox} \frac{W}{L} (V_{in} V_{TH})$  the gain of the circuit changes substantially if the signal is large.
- The dependence of the gain upon the signal level leads to nonlinearity usually an undesirable effect.
- A key result here is that to minimize
  - o the nonlinearity,
  - o the gain equation must be a weak function of signal dependent parameters such as gm.
- For a good stability, gm should not change
- Input impedance of the circuit is very high at a low frequencies.



How do we maximize the voltage gain of a common source stage?

$$A_v = -g_m R_D$$

$$A_{v} = -g_{m}R_{D} \qquad A_{v} = -\sqrt{2\mu_{n}C_{ox}\frac{W}{L}I_{D}}\frac{V_{RD}}{I_{D}} \qquad A_{v} = -\sqrt{2\mu_{n}C_{ox}\frac{W}{L}\frac{V_{RD}}{\sqrt{I_{D}}}}$$

$$A_v = -\sqrt{2\mu_n C_{ox} \frac{W}{L}} \frac{V_{RD}}{\sqrt{I_D}}$$

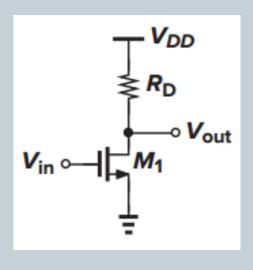
- Thus, the magnitude of Av can be increased by increasing W/L or  $V_{RD}$  or decreasing I<sub>D</sub> if other parameters are constant.
- It is important to understand the trade-offs resulting from this equation.
- A larger device size leads to greater device capacitances, and
- A higher  $V_{RD}$  limits the maximum voltage swings
  - For example, if VDD-VRD = Vin-VTH,
  - then M1is at the edge of the triode region, allowing only very small swings at the output (and input).
- If  $V_{RD}$  remains constant and  $I_{D}$  is reduced, then  $R_{D}$  must increase, thereby leading to a greater time constant at the output node.
- In other words, as noted in the analog design octagon, the circuit exhibits trade-offs between gain, bandwidth, and voltage swings.
- Lower supply voltages further tighten these trade-offs

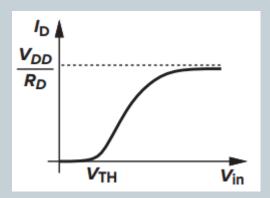
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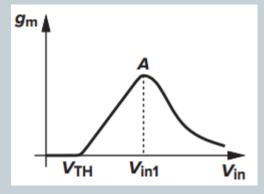
| Cut-off   | Saturation  | Triode / Linear   |
|-----------|---|---|
| Vin < Vth | Vin1>Vin > Vth  | Vin>Vin1  |
| ID = o    |   |   |
|           | $V_{out} = V_{DD} - R_D \frac{1}{2} \mu_n C_{ox} \frac{W}{L} (V_{in} - V_{TH})^2$ | $V_{out} = V_{DD} - R_D \frac{1}{2} \mu_n C_{ox} \frac{W}{L} \left[ 2(V_{in} - V_{TH}) V_{out} - V_{out}^2 \right]$ |
|           |   |   |
|           | $A_v = \frac{\partial V_{out}}{\partial V_{in}}$                                  | $A_v = \frac{\partial V_{out}}{\partial V_{in}}$  |
|           | $= -R_D \mu_n C_{ox} \frac{W}{L} (V_{in} - V_{TH})$                               | $\frac{-\mu_n C_{ox}(W/L) R_D V_{out}}{1 + \mu_n C_{ox}(W/L) R_D (V_{in} - V_{TH} - V_{out})}$                      |
|           |   |   |

14

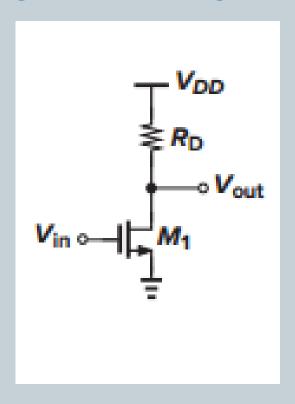
P 1. Sketch the drain current and transconductance of M1in below Fig. as a function of the input voltage

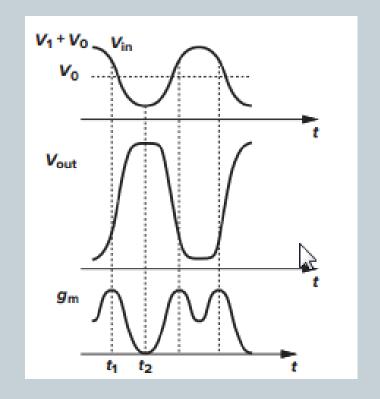






P 2. A CS stage is driven by a sinusoid, Vin =V1cos $\omega$ 1t+V0, whereV0is the bias value andV1is large enough to drive the transistor into the off and triode regions. Sketch the gm of the transistor as a function of time.





• For large values of R<sub>D</sub>, the effect of channel-length modulation in M1 becomes significant

$$V_{out} = V_{DD} - R_D \frac{1}{2} \mu_n C_{ox} \frac{W}{L} (V_{in} - V_{TH})^2 (1 + \lambda V_{out})$$

$$\frac{\partial V_{out}}{\partial V_{in}} = -R_D \mu_n C_{ox} \frac{W}{L} (V_{in} - V_{TH}) (1 + \lambda V_{out}) \\ -R_D \frac{1}{2} \mu_n C_{ox} \frac{W}{L} (V_{in} - V_{TH})^2 \lambda \frac{\partial V_{out}}{\partial V_{in}}$$

Let 
$$(1/2)\mu_n C_{ox}(W/L)(V_{in}-V_{TH})^2\lambda=1/r_O$$
  
ro is output resistance

$$A_v = -R_D g_m - \frac{R_D}{r_O} A_v$$

$$A_v = -R_D g_m - rac{R_D}{r_O} A_v$$
 Thus  $A_v = -g_m rac{r_O R_D}{r_O + R_D}$   $A_v = -g_m$  (  $r_O \parallel R_D$  )

$$A_v = -g_m \ (\ r_O \ | \ R_D \ )$$

17

• For large values of RD, the effect of channel-length modulation in M1becomes significant 1 W

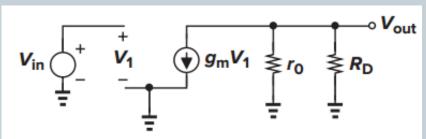
$$V_{out} = V_{DD} - R_D \frac{1}{2} \mu_n C_{ox} \frac{W}{L} (V_{in} - V_{TH})^2 (1 + \lambda V_{out})$$

$$\frac{\partial V_{out}}{\partial V_{in}} = -R_D \mu_n C_{ox} \frac{W}{L} (V_{in} - V_{TH}) (1 + \lambda V_{out}) - R_D \frac{1}{2} \mu_n C_{ox} \frac{W}{L} (V_{in} - V_{TH})^2 \lambda \frac{\partial V_{out}}{\partial V_{in}}$$

Let 
$$(1/2)\mu_n C_{ox}(W/L)(V_{in} - V_{TH})^2 \lambda = 1/r_O$$

ro is output resistance

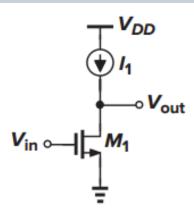
$$A_v = -R_D g_m - rac{R_D}{r_O} A_v$$
 Thus  $A_v = -g_m rac{r_O R_D}{r_O + R_D}$   $A_v = -g_m$  (  $r_O \parallel R_D$  )



Small-signal model of CS stage including the transistor output resistance.

18

P3. Assuming thatM1in Fig. is biased in saturation, calculate the small-signal voltage gain of the circuit.



# Since I1 introduces an infinite impedance (RD= $\infty$ ), # the gain is limited by the output resistance of M1

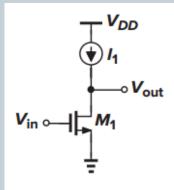
$$A_v = -g_m r_O$$

Called the "intrinsic gain" of a transistor, this quantity represents the maximum voltage gain that can be achieved using a single device

• In today's CMOS technology, gm  $r_0$  of short-channel devices is between roughly 5 and 10. We usually assume (1/gm) << ro

(19)

P3. Assuming thatM1in Fig. is biased in saturation, calculate the small-signal voltage gain of the circuit.



By applying KCL @ Vout node

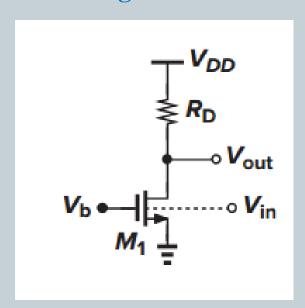
$$I_{D1} = I_1$$

$$I_{D1} = \frac{1}{2} \mu_n C_{ox} \frac{W}{L} (V_{in} - V_{TH})^2 (1 + \lambda V_{out})$$

$$= I_1$$

Vin appears in the square term and Vout in the linear term. As Vin increases, Vout must decrease such that the product remains constant

P4. It is possible to use the bulk (back gate) of a MOSFET as the terminal controlling the channel. Shown in Fig. Determine the voltage gain if  $\lambda$ =0.

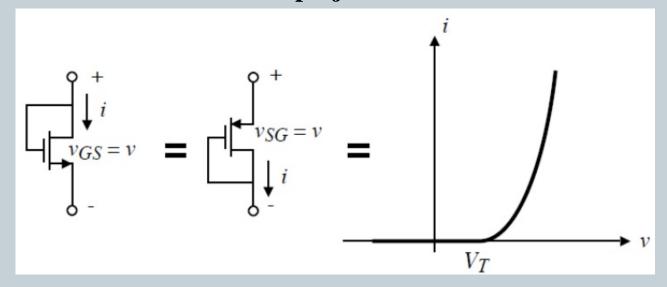


The drain current is given by  $g_{mb}V_{in}$ Thus,  $Av = -g_{mb} R_D$ .

21

#### **MOS** as Diode

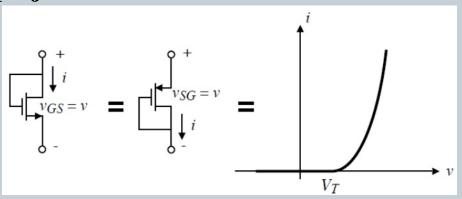
 When a gate of MOSFET is connected to the drain, it acts like a diode with characteristics similar to a pn-junction diode.



22

#### **MOS** as Diode

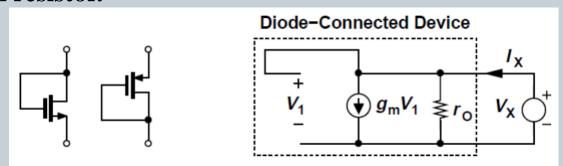
• When a gate of MOSFET is connected to the drain, it acts like a diode with characteristics similar to a pn-junction diode.



• When the gate is connected to the drain of an enhancement MOSFET, the MOSFET is always in the saturation region.  $v_{DS} \ge v_{GS} - V_T$ 

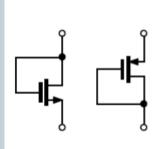
$$v_{DS} \ge v_{GS} - V_T$$
  
 $\Rightarrow v_D - v_S \ge v_G - v_S - V_T$ 
  
 $\Rightarrow v_D - v_G \ge -V_T$ 
  
 $\Rightarrow v_{DG} \ge -V_T$ 

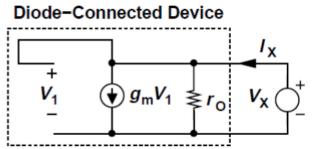
- In many CMOS technologies, it is difficult to fabricate resistors because it requires large area on a silicon wafer.
- A MOSFET can operate as a small-signal resistor if its gate and drain are shorted as shown in fig below
- Called a "Diode connected " device in analogy with its bipolar counterpart, this configuration exhibits a small-signal behavior to a two-terminal resistor.



• Transistor always operates in saturation because the drain and the gate have the same potential.







$$V_1 = V_X$$
 
$$I_X = V_X/r_O + g_m V_X$$
 
$$V_X/I_X = (1/g_m)||r_O \approx 1/g_m$$

• The voltage gain of CS stage with diode connected (without body effect)

load is

