



FUSION B0

SE Host Services API and User Guide

V 0.0.39

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TODO

- OSPI needs example code to show setting of EXTERNAL / INTERNAL Keys usage.
- Power example needs updating with latest tests and aiPM APIs
- SERVICES APIS to add
 - Dynamic
 - Interrupt muxing
 - Event routing
 - Image loading
 - Deferred boot
 - PSA



Introduction

The Fusion product series is a scalable SoC solution for IoT Edge Computing platforms.

SERVICES provide a method for the Application CPUs (M55_HE, HP, A32) to communicate with the Secure Enclave. This secure communication path is achieved using the MHU (Message Handling Unit) hardware block.

The SERVICES library consists of C code that interfaces with an MHU driver to facilitate this communication.

Services fall into the following categories:

- Maintenance Services
- Crypto Services
- Update Services
- Secure Debug Service
- Application Services

The library source code is provided along with a test harness showing the invocation of each SERVICE library call.

The example (test harness) can be used as a framework to copy for integrating SERVICES into your application code. You should only need to include the SERVICE header files and link with the pre-built SERVICE libraries provided.

The examples can be built for all Application cores in XIP and Non-XIP mode. ATOC configuration files are also provided. The examples are stand-alone but can be built using the ALIF Ensemble CMSIS delivery.

ARM Clang and ARM GNU CC are both supported. **Note:** that the pre-built libraries are compiled using ARM Clang. Just run `make realclean` and rebuild everything.

The pre-built libraries were intended to quicken the process of integrating SERVICES into an application. For real development it is recommended to add the SERVICES to your build process

Version History

Version	Type	Change	
V0.0.39		CMSISV0.9.4	
V0.0.38		CMSISV0.9.3	
V0.0.37		CMSISV0.9.2 aiPM Clock changes (Header)	
V0.0.36		CMSISV0.9.1 Global to Local: address translation removal. Use CMSIS	SE-1961 SE-1947
V0.0.35		aiPM SERVICE RUN SERVICES build switch to CMake	SE-1923 SE-1924
V0.0.34	Feature	aiPM SERVICE introduction CMSIS V0.9.0 updates	SE-1887 SE-1886
V0.0.33			
V0.0.31			
V0.0.30	BUG	[JIRA] (SE-1796) [SE-Services] Issue in PinMux and padcontrol error code	SE-1796
V0.0.29	Clean API	Consistent Error code handling in SERVICES transport layer SRAM0,1, MRAM Power enable	SE-1731 SE-1696
V0.0.28	API	Rename standby API Corstone clocks configuration as services	SE-1447 SE-1684
V0.0.27	BUG	Fix warnings in service release	SE-1709
V0.0.26	Feature	PLL Service API exposure Service for global standby mode added APIs for Finer grain Retention control clean up Makefiles CMSIS 0.5.2 updates	SE-1660 SE-1609 SE-1608 SE-1658 SE-1676
V0.0.25	Feature	CMake M55_power added	SE-1645
V0.0.24		REV_B0 release including Power example	SE-1612
V0.0.23	Feature	API Support for RTSS 0.5.0 CMSIS release	SE-1585
V0.0.22	Feature	Error codes are transport related only LocalToGlobal address translation changes Split actual message sending from SERVICES_send_msg()	
V0.0.21	Feature	Adding SPARK build flag	
V0.0.20	Feature	Update license headers	SE-1512
		RISC-V reset SERVICE	SE-1511
V0.0.19	Feature	Adding CMake build option, README.md file added	
V0.0.18	BUG Fixes	See limitations	
V0.0.17	BUG Fixes	See limitations	

V0.0.16	<>		
V0.0.15	BUG Fixes	See limitations	
V0.0.14	Example	Test harness updated	
V0.0.13	Startup	Updated m55 startup code	
V0.0.12	API	Added SERVICES_system_read_otp	
V0.0.11	API	Added SERVICES_system_get_toc_data	
V0.0.10	API	standardized variables for send/resp	
V0.0.9	API	SERVICES_uart_write added size parameter	
		New Error code SERVICES_REQ_BAD_PRINT_LENGTH	
		New Error code SERVICES_REQ_NULL_PARAMETER	

Limitations

Current releases support

- A32 (Not until REV_B2 devices)
- M55-HE, M55-LE Application CPUs
- Bare metal systems
- LINUX

Known limitations:

SE-UART Spamming

When using CONTINUOUS modes via the SE-UART print SERVICE the amount of print traffic can be very heavy and make the system unresponsive. We recommend you use a local UART (UART 2 or 4) dedicated to the M55_HE or M55_HP.

The SERVICES print capability using the SE-UART was added as a convenience to save having to set up external UARTs.

Known release issues:

0.0.39

- A32 builds do not work.
- XIP with CMSISV0.9.4 does not work. Default / use CMSIS V0.9.3

0.0.38

- <>

0.0.37

- BASIC3 EXAMPLE – reports of Hard faults seen on Wake up. -> FIXED

0.0.36

- <>

0.0.35

- [JIRA] (SE-1960) [SERVICES] XIP arm clang examples are no longer running -> NEW

0.0.34

- [JIRA] (SE-1909) [SERVICES] makefile under MS-DOS -> RESOLVED.
- [JIRA] (SE-1891) [SERVICES] Issue with the cmsis_version name is SE-Services pack -> RESOLVED.
- [JIRA] (SE-1910) [SERVICES] Remove Makefile traces -> RESOLVED.
- [JIRA] (SE-1896) [Services] Issue with Cmake build process -> RESOLVED.
- [JIRA] (SE-1886) [SERVICES] Updates for CMSIS V0.9.0 -> NEW
- [JIRA] (SE-1900) [SERVICES] SERVICES_system_get_otp_data() needs implementing

0.0.33

- [JIRA] (SE-1913) [SE-Services] Issue in cpu boot sequence -> RESOLVED.
- [JIRA] (SE-1910) [SERVICES] Remove Makefile traces – makefile debug enabled.
- [JIRA] (SE-1909) [SERVICES] makefile under MS-DOS – use of DEL command
- [JIRA] (SE-1878) [Services] M55_HE XIP=off showing an Error during boot -> RESOLVED

- [JIRA] (SE-1900) [SERVICES] SERVICES_system_get_otp_data() needs implementing -> NEW
- [JIRA] (SE-1896) [Services] Issue with Cmake build process -> NEW.
- [JIRA] (SE-1878) [Services] M55_HE XIP=off showing an Error during boot -> NEW

0.0.32

- [JIRA] (SE-1813) [Services] Warnings during the compilation of services images using cmake and ARM-GCC
- [JIRA] (SE-1843) Calling SERVICES_system_set_services_debug with debug_enable false breaks subsystem off
- [JIRA] (SE-1853) Incomplete examples for SERVICES_xxx
- [JIRA] (SE-1851) Invalid example code in SERVICES documentation
- [JIRA] (SE-1822) [SERVICES] M55_HP showing Error on boot.
- [JIRA] (SE-1815) LPTimer or LPGPIO does not work as a stop mode wake up sources.

0.0.31

- [JIRA] (SE-1822) [SERVICES] M55_HP showing Error on boot -> RESOLVED.
- [JIRA] (SE-1844) [SERVICES] Add disable service for memory power control - Currently RESOLVED by removing SERVICES_power_memory_req() as a test.
- [JIRA] (SE-1847) Calling SERVICES_pll_initialize breaks subsystem off test.
- [JIRA] (SE-1843) Calling SERVICES_system_set_services_debug with debug_enable false breaks subsystem off
- [JIRA] (SE-1813) [Services] Warnings during the compilation of services images using cmake and ARM-GCC -> RESOLVED.

0.0.30

- [JIRA] (SE-1822) [SERVICES] M55_HP showing Error on boot.
- [JIRA] (SE-1813) [Services] Warnings during the compilation of services images using cmake and ARM-GCC
- [JIRA] (SE-1649) [SERVICES] hardfault when writing to RTC_A register.
- [JIRA] (SE-1582) [SERVICES][REV_B0] Services examples do not run from MRAM or TCM

0.0.29

- [JIRA] (SE-1782) [SERVICES] Need to change the address of HP in the JSON file of "services-he-hp-a32-xip"
- [JIRA] (SE-1731) [SERVICES] Consistent Error handling -> RESOLVED

0.0.28

- <>

0.0.27

- [JIRA] (SE-1709) [SERVICES] Fix warnings in service release -> RESOLVED

0.0.26

- [JIRA] (SE-1676) [SERVICES] CMSIS 0.5.2 updates -> RESOLVED
- [JIRA] (PSBT-150) RTSS 0.5.0 compiler warning -> RESOLVED (With CMSIS V0.5.2)
- [JIRA] (PSBT-149) Spelling mistakes -> RESOLVED
- [JIRA] (SE-1658) [SERVICES] clean up Makefiles -> RESOLVED
- [JIRA] (SE-1631) [SERVICES] build all (GNU) fails with A32 build -> RESOLVED. Now skips the A32 build rather than Fail.
- [JIRA] (SE-1509) [SERVICES] GNU C Compilations lack XIP examples -> RESOLVED

0.0.25

- GCC sample ld files added for XIP
- [JIRA] (SE-1680) [SERVICES] makefile.gnu all install - HP image is missing
- [JIRA] (SE-1628) [SERVICES] Standby mode SRAM0 SRAM1 retention -> RESOLVED
- [JIRA] (SE-1674) [SERVICES] Overlap regions for HE-HP example -> RESOLVED
- [JIRA] (SE-1497) [SERVICES] TEST Services initialize polling -> RESOLVED
- [JIRA] (SE-1644) [SERVICES] Unsupported build matrix options should error not fail -> RESOLVED
- [JIRA] (SE-1645) [SERVICES] power example GCC build -> RESOLVED
- [JIRA] (PSBT-150) RTSS 0.5.0 compiler warning

0.0.24

- [JIRA] (SE-1674) [SERVICES] Overlap regions for HE-HP example
- Make option (cmsis override) – HELP banner shows ‘make cmsis CMSIS=x.y.z’, syntax is make cmsis=x.y.z
- [JIRA] (SE-1652) [SETOOLS] APP release builder uses wrong cfg for REV_B0 – app-cpu.cfg has wrong address 0x60000000 instead of 0x58000000. This is a bug in the release builder copying the REV_A1 JSON file instead of REV_B0 to the release.
- [JIRA] (PSBT-150) RTSS 0.5.0 compiler warning – during the build there is a –noreturn warning printed.
- [JIRA] (SE-1649) [SERVICES] hardfault when writing to RTC_A register – temporarily commented out (example still runs) until this is fixed.
- [JIRA] (SE-1631) [SERVICES] build all (GNU) fails with A32 build – use Make clean and rebuild.
- [JIRA] (SE-1612) [SERVICES] Not able to see the cpu id information for M55_HP -> RESOLVED

0.0.23

- [JIRA] (SE-1612) [SERVICES] Not able to see the cpu id information for M55_HP
- [JIRA] (PSBT-150) RTSS 0.5.0 compiler warning – You will see a compiler warning for the Reset_Handler regarding NoRETURN.
- [JIRA] (PSBT-151) L6242E: Cannot link object services_host_handler.o as its attributes are incompatible with the image attributes.
- [JIRA] (PSBT-149) Spelling mistakes
- [JIRA] (SE-1447) [SERVICES] Spelling errors (In the LD files from APPS) -> RESOLVED

0.0.22

- [JIRA] (SE-1582) [SERVICES][REV_B0] Services examples do not run from MRAM
- [JIRA] (SE-1576) [SERVICES] Services UART print is always enabled
- [JIRA] (SE-1553) [SERVICES] make all for GNU still using ARM-Clang

0.0.21

- <>

0.0.20

- [JIRA] (SE-1502) [SERVICES] Extra bracket character in services_lib_api.h causing build failure with C++ -> RESOLVED

0.0.19

- CMake - builds *only* for M55_HE TCM load (SE-1509)
- [JIRA] (SE-1526) [SERVICES] A32 XIP example fails -> NEW

0.0.18

- [JIRA] (SE-1496) [SERVICES] GCC Compilation warning [-Wunused-variable] -> RESOLVED
- [JIRA] (SE-1487) [SERVICES] A32 example missing json file -> RESOLVED

- [JIRA] (SE-1442) [SERVICES] unused function in MHU driver -> RESOLVED
 - [JIRA] (SE-1427) [SERVICES] A32 example crashes when run from MRAM
- 0.0.17
- [JIRA] (SE-1487) [SERVICES] A32 example missing json file -> NEW
 - [JIRA] (SE-1465) [SERVICES] debug output is enabled -> RESOLVED
 - [JIRA] (SE-1471) [SERVICES] DOS based make issue -> RESOLVED
 - [JIRA] (SE-1443) [SERVICES] newlib link warnings -> RESOLVED
- 0.0.16
- A32 example is not part of the GNU C compilation.
 - [JIRA] (SE-1439) [SERVICES] Compiler warnings with GCC -> RESOLVED
 - [JIRA] (SE-1442) [SERVICES] unused function in MHU driver -> RESOLVED
- 0.0.15
- A32 example is not part of the GNU C compilation. This was not done as there were issues with A32 example fixed in this sprint.
 - [JIRA] (SE-1443) [SERVICES] newlib link warnings - with GNU C warnings are seen with SERVICES library link
 - [JIRA] (SE-1442) [SERVICES] unused function in MHU driver – warning seen with GNU about unused function
 - [JIRA] (SE-1349) [SERVICES] A32 example output incorrect
- 0.0.14
- [JIRA](SE-1423) TTY Output - <unknown> is passed for CPU type in Library revision output
- 0.0.13
- A32 crash seen when booting from MRAM
- 0.0.12
- <>
- 0.0.11
- OTP read is “not implemented”, awaiting SES change for OTP API reads.
- 0.0.10
- <>
- 0.0.9
- UART prints via Services are maximum size of 256 bytes.
 - Pin and Pad control messages can be seen as part of the SE-UART output even if the SERVICE debug is DISABLED. This is a bug and will be fixed.
- 0.0.8
- RTSS / CMSIS require edits to be made to the SERVICES example to work under ARM-DS (MiniTOC). Integration of a unified MHU driver is still not completed for CMSIS.
- 0.0.7
- RTSS / CMSIS builds do not support REV_B0 devices. It will build, but execution fails.
- 0.0.6
- RTSS / CMSIS build causes compiler error with redefinition of M55_HE preprocessor flag.
- V46
- <>
- V42
- <>

V41

- Other running applications can interfere with operation of the Services. The MHU interrupts can stop. Suggest that other Applications, such as the Blinky, are removed and replaced with a debug stub
- Stepping over the init() function in the M55 Examples actually enters the function, if this happens just jump out of this function

In V42 it is no longer needed to put a debug stub on an M55 core before running the Services example on it. An Arm DS debugger script was added that initializes certain M55 registers, and combined with a change in the code, puts the M55 in a known state that doesn't cause issues. The details are in the section 'Running the M55 HE Host Example'.

SE Host SERVICES Versions with SERAM Pairings

Version	SERAM	Notes
0.039	V81	
0.038	V80	
0.037	V79	
0.036	V78	
0.035	V77	
0.034	V76	
0.033	V75	
0.032	V74	
0.029	V71	REV_B0 PLL, Clock updates
0.028	V69	
0.027	V68	
0.026		
0.025	V67	
0.024	V66	
0.023	V65	
0.022	V64	
0.021	V63	SPARK flag build
0.020	V62	Add FUSION_EXTERNAL_SYS0
0.0.16	V58	OTP addition
0.0.11	V51	Get all TOC data
0.0.10	V50	EWiC configuration call
0.0.9	V49	
0.0.8	V47	Header file change
0.0.7	V47	Mbed TLS accelerators
0.0.6	V46	API for enable / disable SES debug status
0.0.5	V46	API changes for Error code
0.0.4		Boot reset addition
0.0.3		RPC Parameter changes
0.0.2		First refactoring
0.0.1		First implementation

Supported SE Host Services summary

Service Group	Ax	B0		Notes
Maintenance				
	•	•	SERVICES_heartbeat	Health status
	•	•	SERVICES_heartbeat_async	
System Management				
	•	•	SERVICES_system_get_toc_data	
	•	•	SERVICES_system_get_toc_number	
	•	•	SERVICES_system_get_toc_via_name	
	•	•	SERVICES_system_get_toc_version	N/I
	•	•	SERVICES_system_get_toc_via_cpuid	
	•	•	SERVICES_system_get_device_part_number	
	•	•	SERVICES_system_get_device_data	
	•	•	SERVICES_system_set_services_debug	Debug toggle
	•	•	SERVICES_system_get otp_data	N/I
	•	•	SERVICES_system_read_otp	
	•	•	SERVICES_get_se_revision	
Application / Pin mux management				
	•	•	SERVICES_pinmux	
	•	•	SERVICES_padcontrol	
	•	•	SERVICES_uart_write	
		•	SERVICES_application_ospi_write_key	
	•	•	SERVICES_SRAM_retention_config	
Power				
		•	SERVICES_power_stop_mode_request	
		•	SERVICES_power_ewic_config	
		•	SERVICES_power_wakeup_config	
		•	SERVICES_power_mem_retention_config	
		•	SERVICES_power_m55_he_vtor_save	
		•	SERVICES_power_m55_hp_vtor_save	
		•	SERVICES_power_memory_req	
		•	SERVICES_global_standby_mode	
		•	SERVICES_get_run_cfg	aiPM
		•	SERVICES_set_run_cfg	aiPM
		•	SERVICES_get_off_cfg	aiPM
		•	SERVICES_set_off_cfg	aiPM

Security /Crypto				
	•	•	SERVICES_cryptocell_get_lcs	
	•	•	SERVICES_cryptocell_get_rnd	TRNG
	•	•	SERVICES_cryptocell_mbedtls_aes_init	
	•	•	SERVICES_cryptocell_mbedtls_aes_set_key	
	•	•	SERVICES_cryptocell_mbedtls_aes_crypt	
	•	•	SERVICES_cryptocell_mbedtls_sha_starts	
	•	•	SERVICES_cryptocell_mbedtls_sha_process	
	•	•	SERVICES_cryptocell_mbedtls_sha_update	
	•	•	SERVICES_cryptocell_mbedtls_sha_finish	
	•	•	SERVICES_cryptocell_mbedtls_ccm_gcm_set_key	
	•	•	SERVICES_cryptocell_mbedtls_ccm_gcm_crypt	
	•	•	SERVICES_cryptocell_mbedtls_ccm_gcm_chachapoly_crypt	
	•	•	SERVICES_cryptocell_mbedtls_ccm_gcm_poly1305_crypt	
	•	•	SERVICES_cryptocell_mbedtls_cmac_init_setkey	
	•	•	SERVICES_cryptocell_mbedtls_cmac_update	
	•	•	SERVICES_cryptocell_mbedtls_cmac_finish	
	•	•	SERVICES_cryptocell_mbedtls_cmac_reset	
Boot				
	•	•	<u>SERVICES boot process toc entry</u>	
	•	•	<u>SERVICES boot cpu</u>	
	•	•	<u>SERVICES set vtor</u>	
	•	•	<u>SERVICES boot reset cpu</u>	
	•	•	<u>SERVICES boot release cpu</u>	
	•	•	<u>SERVICES boot reset soc</u>	
Clock				
		•	<u>SERVICES clocks select osc source</u>	
		•	<u>SERVICES clocks select pll source</u>	
		•	<u>SERVICES clocks enable clock</u>	
		•	<u>SERVICES clocks set ES0 frequency</u>	
		•	<u>SERVICES clocks set ES1 frequency</u>	
		•	<u>SERVICES clocks select a32 source</u>	
		•	<u>SERVICES clocks select aclk source</u>	
		•	<u>SERVICES clocks set divider</u>	

N/I - Not implemented means the SERVICE exists but is not fully completed in SES.



SE Host Services Delivery Components

A release package from ALIF consists of the following components:

- Source code SERVICES library
 - Public header files
- Makefile(s) for ARM Clang and ARM GNU C builds
- Example ports for Bare metal and Linux
 - Example SERVICE library initializations.
- Example use cases for M55_HE, M55_HP, A32 and M55_HE+M55_HP
 - Example runs a test program calling all available SERVICES API.
 - Output is sent via the SE-UART to save having to install extra UART debug ports.
- Example use cases for Low Power






























Pre-requisites

The following components are required to be installed before using / building SE SERVICES:

- ALIF Ensemble RTSS Release \geq Version 0.5.0
 - CMSIS Packs for Ensemble devices
 - Following the installation instructions for this package
- GNU Make V4.4
- Cmake V3.22.2
- Security Toolkit (SETOOLS)
 - Not required for building, but for generating the ATOC packages for the Target

Building SE Services – Windows / LINUX

Unpack the se-host-services-release-SE_FW_0.<version#>.000_DEV.zip

Name	Date modified	Type	Size
 a32_startup	7/11/2023 4:15 PM	File folder	
 build	7/7/2023 7:51 AM	File folder	
 drivers	7/7/2023 7:51 AM	File folder	
 example	7/11/2023 4:15 PM	File folder	
 include	7/11/2023 6:01 AM	File folder	
 lib	7/7/2023 7:51 AM	File folder	
 RTE	7/11/2023 4:15 PM	File folder	
 services_lib	7/11/2023 4:15 PM	File folder	
 A32_MRAM	7/11/2023 4:15 PM	Windows Script C...	
 A32_TCM	7/11/2023 4:15 PM	Windows Script C...	
 CMakeLists	7/11/2023 4:15 PM	Text Document	
 CMakePresets	7/11/2023 4:15 PM	JSON File	
 gcc_A32_MRAM	7/11/2023 4:15 PM	LD File	
 gcc_A32_TCM	7/11/2023 4:15 PM	LD File	
 gcc_M55_HE_MRAM	7/11/2023 4:15 PM	LD File	
 gcc_M55_HE_TCM	7/11/2023 4:15 PM	LD File	
 gcc_M55_HP_MRAM	7/11/2023 4:15 PM	LD File	
 gcc_M55_HP_TCM	7/11/2023 4:15 PM	LD File	
 License	7/7/2023 7:51 AM	Text Document	
 M55_HE_MRAM	7/11/2023 4:15 PM	Windows Script C...	
 M55_HE_TCM	7/11/2023 4:15 PM	Windows Script C...	
 M55_HP_MRAM	7/11/2023 4:15 PM	Windows Script C...	
 M55_HP_TCM	7/11/2023 4:15 PM	Windows Script C...	
 Makefile_linux	7/7/2023 7:51 AM	File	
 README	7/11/2023 4:15 PM	Markdown Source...	
 toolchain-armclang	7/11/2023 4:15 PM	CMake Source File	
 toolchain-gnu	7/11/2023 4:15 PM	CMake Source File	

The release archive consists of the following target components.

Name	Purpose	Notes
a32_startup	A32 startup code	
Build		
include	Services header files	
lib		
services_lib	Host source code for Services	
Example	SERVICES test harnesses	
README.md	instructions	

CMAKE is used.



Building with ARM GNU C

```
$ cd se-host-service-release
$ mkdir build_he_gcc_tcm
$ cd build_he_he_gcc_tcm
$ cmake .. -G "Unix Makefiles" -DENSEMBLE_CORE=M55_HE -
DCMAKE_TOOLCHAIN_FILE=toolchain-gnu.cmake
$ make install
```

```
$ cd se-host-service-release
$ mkdir build_he_power_gcc_tcm
$ cd build_he_power_gcc_tcm
$ cmake .. -G "Unix Makefiles" -DENSEMBLE_CORE=M55_HE -
DCMAKE_TOOLCHAIN_FILE=toolchain-gnu.cmake -DPOWER=ON
$ make install
```

The SERVICE library is built as part of these builds.

Building with ARM CLANG

```
$ cd se-host-services-release
$ mkdir build_he_power_clang_tcm
$ cd build_he_power_clang_tcm
$ cmake .. -G "Unix Makefiles" -DENSEMBLE_CORE=M55_HE -DPOWER=ON
DCMAKE_TOOLCHAIN_FILE=toolchain-armclang.cmake
$ make install -j 8
```

```
$ cd se-host-services-release
$ mkdir build_he_clang_tcm
$ cd build_he_clang_tcm
$ cmake .. -G "Unix Makefiles" -DENSEMBLE_CORE=M55_HE -
DCMAKE_TOOLCHAIN_FILE=toolchain-armclang.cmake
$ make install -j 8
```

NOTE: Parallel make (using -j <job#>) is available



SERVICES Library Dependencies

The SERVICES library and support file for starting SERVICES has a few dependencies.

- CMSIS Package installation location
- CMSIS Package source and include locations.
- Compiler flags

CMSIS Package

CMSIS dependency is mainly for header files for the targeted Application CPU e.g., "M55_HE.h"

The SERVICE example uses the CMSIS startup sequences for booting the Application cores.

CMSIS packages consist of an ARM and ALIF component. The ARM components is specific for the various types of cores. The ALIF components contain specific ALIF Device and Board components.

CMSIS RTSS V0.9.x Release

There is no backwards compatibility with previous RTSS releases.

- The interrupt handler names for Secure Enclave communication over MHU have changed again.
- Makefile updates for different include and source directory paths.

JSON Configurations

The examples can be built for the following Application cores:

- M55_HE
- M55_HP
- A32

Sample ATOC JSON files are provided for:

- Code running from MRAM (XIP).
- Code running from TCM memory.
- M55_HE
- M55_HP
- M55_HE + M55_HP

JSON File	TCM	MRAM
services_a32	✓	
services_a32-xip		✓
services_he	✓	
services_he_hp	✓	
services_he_hp_a32	✓	
services_he_hp_a32_xip		✓
services_he_hp_xip	✓	
services_he_xip		✓
services_hp	✓	
services_hp_xip		✓

Power Example

The Power examples demonstrate how to use SERVICES to achieve low power states.

The SERVICES are used to configure the device and enable STOP mode.

Power Example features

Features	RUN mode	OFF mode
Memory Retention	Supported	Supported only in STOP
Wake up	Supported	Supported only in STOP
EWIC	Supported	Supported only in STOP
Power domain	Supported	Supported only in STOP
VDD ioflex 3V3	Supported	Supported only in STOP
VTOR	Supported	Supported only in STOP
DCDC	TBD	TBD
Clocks	TBD	TBD

Feature	M55-HP	M55-HE	Support	Comments
Stop mode	Vote	Vote	Supported	Both CPUs must vote NOTE: If a CPU goes OFF, its vote is counted. If it wakes up (before STOP mode), its vote is not revoked - TBD
Stop mode	Vote	No vote	TBD	Not booted/not running/wounded cases not checked - TBD
Stop mode	No vote	Vote	TBD	Not booted/not running/wounded cases not checked - TBD
Stop mode	No vote	No vote	No STOP mode	
Wake up from STOP TCM	TBD	Supported (m55 retained only)		M55-HE TCM must be retained
Wake up from STOP XIP	TBD	Supported (SERAM not retained only)		Fast boot only
Wake up from STOP SERAM (retained)			Supported	SEROM skips SERAM image verification
Wake up from STOP SERAM (not retained)			Supported	Fast boot - M55-HE released from reset by SEROM. - TCM must be reinitiated - XIP not supported
Subsystem OFF settings	TBD	TBD	Only STOP	When a subsystem powers off, the OFF settings are not currently applied. OFF setting are applied only in STOP mode

Power Example Use Cases

Please refer to the README.md file in the SERVICES release for details of the Example use cases e.g., how to build and run.

BASIC1/2

- Keeps device ON after wake-up from STOP mode.
- M55_HE is booted on wake-up.

BASIC3

- Continually cycles from STOP->WAKE.

BASIC4

- Example
 - Make a Set RUN Config call, to change the clock settings to something different from the default.
 - Measure the CPU speed, to verify that the above call was executed successfully.
 - Make a Set OFF Config call.
 - Make the PM calls to go OFF. It seems now that is Alif CMSIS functionality.
- Can be configured (built) for continuous or limited run (10) mode.
- **NOTE:** There is an issue when measuring the CPU speeds of both M55s at the same time. It seems it is caused by the shared usage of RTC_A, which is also used for wakeup logic.

BASIC5

- FASTBOOT with SE not retained.

BASIC6

- Global standby example in TCM.

BASIC7

- IDLE mode example in TCM

BASIC8 to BASIC13 – Clock configuration examples

Each of these examples perform a single aiPM call to set the RUN clock configuration of the device.

- BASIC8 – run the device off the PLL at full CPU frequencies.
- BASIC9 – run the device off the PLL at reduced M55 CPUs frequencies.
- BASIC10 – run the device off the HFXO at full HFXO frequency.
- BASIC11 – run the device off the HFXO at scaled down HFXO frequency.
- BASIC12 – run the device off the HFRC at full HFRC frequency.
- BASIC13 – run the device off the HFRC at scaled down HFRC frequency.

BASIC14 – GET request examples

- Shows use of the get_off and get_run APIs.

BASIC15 – Clock Source Cycling

- Cycles the device between PLL, HFXO and HFRC clock sources.
- Can be continuous or limited to 10 cycles.

BASIC16 – M55s run in TCM not retained.

- SES loads M55 code from MRAM to it's TCM. M55-HE is not retained.
- M55 does a set_run() request
- M55 does a set_off() request
- SES puts the device in STOP mode when both m55s go OFF
- RTC_A expiry causes wake up
- PLL not enabled on wake up
 - Run at RC clock speed 76 MHz
- SES wakes up
 - Starts PLL
 - Run at 100 Mhz
 - Initializes m55-he TCM memory
- SES boots both m55-he and m55-hp from ATOC
 - As both CPUs are booted, you will see the chip cycle.

SES Power Policies

- Both M55 cores *must* be running to go into STOP mode.
 - Requires **two** votes to power down the chip.
 - In future, other conditions will be considered, e.g., wounding, not booted etc.
- Logic added to process ATOC and boot M55_HE and M55_HP in case the M55_HE TCM was not retained.
- SES will apply retention settings as soon as a service request is received because they cannot be applied after a subsystem goes OFF.

Power Example Running – Notes / Limitations

ISP not responding.

- [ERROR] Target not responding causes:
 - If you have the device in a Power OFF state be aware that commands sent from the SETOOLS maintenance command will return [ERROR] Target not responding as the device is turned off. ISP is not running / listening on the target when the Power is off.
- Cannot use UpdateSystemPackage
 - If you have programmed the device to disable the PLL then using Bulk MRAM transfer commands such as UpdateSystemPackage or app-write-mram will probably fail. The reason is that these commands automatically raise the baud rate for ISP which assumes the PLL is enabled. To use these commands

```
$ updatesystempackage -s  
$ app-write-mram -s
```

The -s option suppresses the baud rate increase.

To gain control of the device again you will need to enter Hard Maintenance mode.

Power Examples Limitations

- Wakeup timers that expire before you enter STOP mode.
 - You will not enter stop mode.
- The booting of specific CPU core as per requested wake up event is not yet supported.
 - On any configured wake up event the m55-he is booted if its TCM is retained or ATOC is processed, and bootable images are booted (potentially both m55-he and m55-hp if the ATOC has bootable images for both)

The wake up from STOP mode has *many* scenarios e.g., XIP, retained, not all these scenarios are implemented yet.



SES Clock Policies

- SES COLD Boot
 - SES checks for presence of Application DCT objects specifying Clock directions.
 - If no DCT object is present, SES will set the LF Clock Source to the LFXO (Default)

SERVICES test harness example

A test harness example is provided showing calls to all the SERVICES APIs.

See `example\common\services_test.c`.

There are numerous build options available. Not all tests can be run at once as they either do not return or they reboot the system.

Examples customization options.

Output of the results from the example test can be via the ARM-DS Console or the SE-UART.

In `services_test.c` there are the following defines

```
#define TEST_PRINT_ENABLE      1  /* Enable printing from Test harness */
#define PRINT_VIA_CONSOLE     0  /* Print via Debugger console      */
#define PRINT_VIA_SE_UART     1  /* Print via SE UART terminal       */
```

Flag	Meaning
TEST_PRINT_ENABLE	Turn on output from the test
PRINT_VIA_CONSOLE	Print messages to arm-ds (printf())
PRINT_VIA_SE_UART	Print messages to the SE-UART

You can enable both Console and SE-UART.

If you want to run the test from MRAM the PRINT_VIA_CONSOLE must be disabled.

Changing CMSIS Packs

The SERVICES examples use ALIF CMSIS mainly for:

- M55_HE and HP startup sequences.
- MHU interrupt vectors and numbers
- Global Standby APIs for Low Power example

The SERVICES examples build defaults to the latest ALIF CMSIS Packs.

Changing CMSIS versions is as follows:

```
$ cmake .. -G "Unix Makefiles" -DENSEMBLE_CORE=M55_HE -
DCMAKE_TOOLCHAIN_FILE=toolchain-armclang.cmake -DAlifcmsis="0.9.2"
```



Building and running the Examples

Building the M55 HE Example - run from TCM.

There are two json files supplied in the Services release:

- services-he.json
 - Single Core
- services-he-hp.json
 - Dual Core

Follow the instructions to build the M55_HE or HP example.

```
$ cd <host-release directory>
$ mkdir build_he
$ cd build_he
$ cmake .. -G "Unix Makefiles" -DENSEMBLE_CORE=M55_HE -
DCMAKE_TOOLCHAIN_FILE=toolchain-armclang.cmake
$ make install
```

To boot M55_HE application CPUs you need these steps:

```
$ cd <release directory>/app-release-exec
$ ./app-gen-toc -f build/config/service-he.json
$ ./app-write-mram
```



Building the M55 HE Example - run from MRAM.

There are two json files supplied in the Services release:

- services-he-xip.json
 - Single Core
- services-he-hp-xip.json
 - Dual Core

Follow the instructions to build the M55_HE or HP example.

```
$ cd <host-release directory>
$ mkdir build_he_mram
$ cd build_he_mram
$ cmake .. -G "Unix Makefiles" -DENSEMBLE_CORE=M55_HE -
DCMAKE_TOOLCHAIN_FILE=toolchain-armclang.cmake -DXIP=1
$ make install
```

To boot M55_HE application CPU you need these steps:

```
$ cd <release directory>/app-release-exec
$ ./app-gen-toc -f build/config/service-he-xip.json
$ ./app-write-mram
```



Building the A32 Example

<TBD>



Building the A32 XIP Example

<TBD>

Building and running the M55_HE Power Example (ARM Clang)

```
$ cd se-host-service-release
$ mkdir build_he_power
$ cd build_he_power
$ cmake .. -G "Unix Makefiles" -DENSEMBLE_CORE=M55_HE -
DCMAKE_TOOLCHAIN_FILE=toolchain-armclang.cmake -DPOWER=ON
$ make install

$ cd ../app-release-exec
$ ./app-gen-toc -f build/config/service-he.json
$ ./app-write-mram
```

Building and running the M55_HE Power Example (ARM GNUC)

```
$ cd se-host-service-release
$ mkdir build_he_power
$ cd build_he_power
$ cmake .. -G "Unix Makefiles" -DENSEMBLE_CORE=M55_HE -
DCMAKE_TOOLCHAIN_FILE=toolchain-gnu.cmake -DPOWER=ON
$ make install

$ cd ../app-release-exec
$ ./app-gen-toc -f build/config/service-he.json
$ ./app-write-mram
```

Building and running the M55_HP Power Example (ARM Clang)

```
$ cd se-host-service-release
$ mkdir build_hp_power
$ cd build_hp_power
$ cmake .. -G "Unix Makefiles" -DENSEMBLE_CORE=M55_HP -
DCMAKE_TOOLCHAIN_FILE=toolchain-armclang.cmake -DPOWER=ON
$ make install

$ cd ../app-release-exec
$ ./app-gen-toc -f build/config/service-hp.json
$ ./app-write-mram
```

Building and running the M55_HP Power Example (ARM GNUC)

```
$ cd se-host-service-release
$ mkdir build_hp_power
$ cd build_hp_power
$ cmake .. -G "Unix Makefiles" -DENSEMBLE_CORE=M55_HP -
DCMAKE_TOOLCHAIN_FILE=toolchain-gnu.cmake -DPOWER=ON
$ make install
```



```
$ cd ../app-release-exec  
$ ./app-gen-toc -f build/config/service-hp.json  
$ ./app-write-mram
```




Building SE Host Services – LINUX

Unpack the se-host-services-release-SE_FW_0.<version#>.000_DEV.zip

There is a separate makefile file for building the Services library for Linux - 'Makefile_linux', so that file should be used instead of the default 'Makefile' –

```
$ make -f Makefile_linux lib
```

By default, things are set up to use the native GCC compiler in Cygwin.

To use the Alif Yocto cross compiler toolchain and generate binaries for the Alif Linux distribution, a couple of changes are needed.

- comment out the compiler definitions (like 'CC = gcc') in Makefile_linux. The Yocto toolchain provides its own definitions.
- modify the file services_lib\services_host_handler_linux.c and replace '#if 0' with '#if 1', to include the Linux kernel header file for the MHU driver.



Installing examples

The examples come with supplied JSON files for A32, M55_HE and M55_HP processors including variants for MRAM (XIP) and TCM running.

There is an option to install these examples into your Application Release to enable building an ATOC for putting into MRAM. To build the ATOC you need the JSON file and the binary image for Application. These files are copied from the se-host-services-release into your application release.

```
$ cd se-host-services-release
```

Note the use of the `INSTALL_DIR` to specify where your application release lives.

When you unpack your application release you will get a directory structure as follows:

```
app-release-exec-windows-SE-FW_0.<version>
+ app-release-exec
+ build
+ config
+ images
```

The JSON files will be copied to the config directory and the binaries will be copied to images. This is where the ATOC generation tools will look.

A sample sequence would be as follows:

```
$ cd se-host-services-release
$ mkdir build_he
$ cd build_he
$ cmake .. -G "Unix Makefiles" -DENSEMBLE_CORE=M55_HE -
DCMAKE_TOOLCHAIN_FILE=toolchain-armclang.cmake
$ make install -j 8
```

Installing examples to a different location

An example of using the `INSTALL_DIR` is as follows:

```
-DINSTALL_DIR=<some path>
```

If you do not specify the `INSTALL_DIR` then the default is `app-release-exec`

Use the following to override the default:

```
$ cd se-host-services-release
$ mkdir build_he
$ cd build_he
$ cmake .. -G "Unix Makefiles" -DENSEMBLE_CORE=M55_HE -
DCMAKE_TOOLCHAIN_FILE=toolchain-armclang.cmake -DINSTALL_DIR=<some
location>
$ make install -j 8
```

```
$ cmake .. -G "Unix Makefiles" -DENSEMBLE_CORE=M55_HE -DCMAKE_TOOLCHAIN_FILE=toolchain-armclang.cmake -DINSTALL_DIR=./junk
-- [INFO] Version=9
-- [INFO] installation override, using ../junk
-- The C compiler identification is ARMClang 6.18.2
-- The CXX compiler identification is ARMClang 6.18.2
-- The ASM compiler identification is ARMClang
```

A message shows that installation override is enabled.

Running with SERVICES Debug disabled

The test harness has a call to `SERVICES_system_set_services_debug()` which can disable or enable the debug traffic from SES for the SERVICE traffic.

With the SERVICES debug set to false:

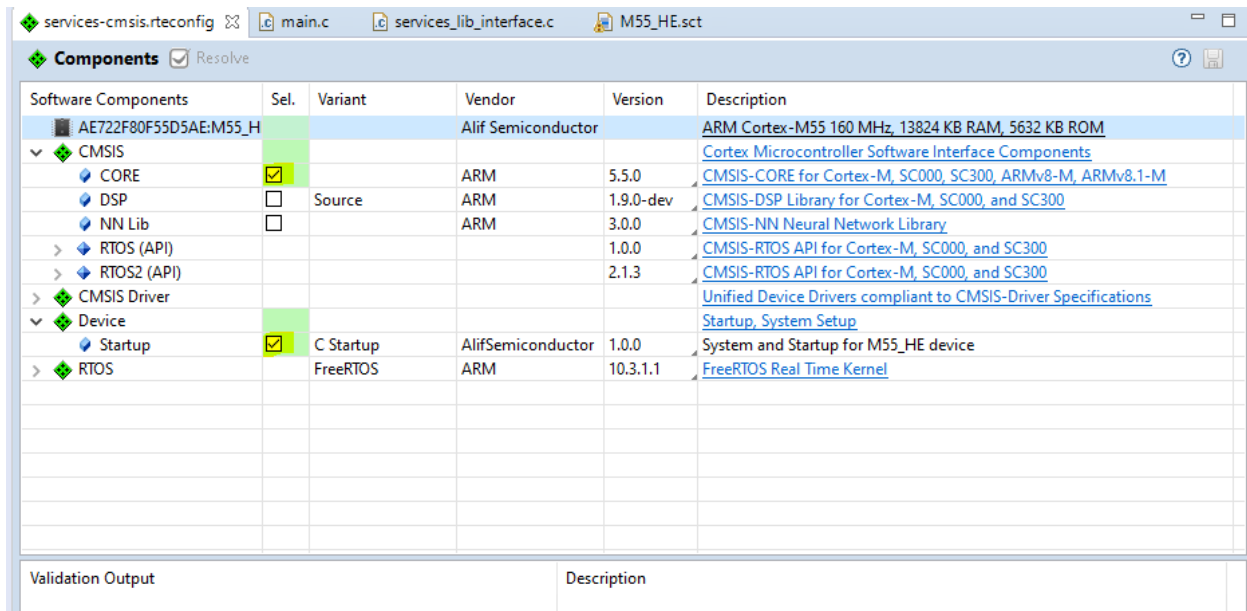
```
[SES] CMB+ frequency is 100 MHz
[SES] os Kernel U10-4.2
[SES] Main Task - looping forever...
[SRU] RX<-- SID= 0x0CE, Receiver ID=4, Address=0x9083FFA8
[TTV] SERVICES version 0.0.6
[TTV] ** TEST heartbeat error_code=SERVICES_REQ_SUCCESS service_resp=0x00000000
[TTV] ** TEST pinmux error_code=SERVICES_REQ_SUCCESS service_resp=0x00000000
[TTV] ** TEST padcontrol error_code=SERVICES_REQ_SUCCESS 64-bit Random value = 0xicfed9edc1501c20 service_resp=0
[TTV] ** TEST crypto TRNG 64 error_code=SERVICES_REQ_SUCCESS 32-bit Random value = 0xa479c88f service_resp=0
[TTV] ** TEST crypto TRNG 32 error_code=SERVICES_REQ_SUCCESS 64-bit Random value = 0xbc3fcf15f8479420 service_resp=0
[TTV] ** TEST crypto TRNG 64 error_code=SERVICES_REQ_SUCCESS 32-bit Random value = 0x5cfbb90c service_resp=0
[TTV] ** TEST crypto TRNG 32 error_code=SERVICES_REQ_SUCCESS LCS State 0x0 service_resp=0
[TTV] ** TEST crypto LCS error_code=SERVICES_REQ_SUCCESS Application TOC number = 0 service_resp=0x00000000
[TTV] ** TEST get ATOC error_code=SERVICES_REQ_SUCCESS service_resp=0x00000000
[TTV] ** TEST TOC via name HE error_code=SERVICES_REQ_SUCCESS service_resp=0x00000000
[TTV] ** TEST TOC via name HP error_code=SERVICES_REQ_SUCCESS service_resp=0x00000000
[TTV] ** TEST TOC via cpuid error_code=SERVICES_REQ_SUCCESS id HE_DBG flags 63 1 0 0 service_resp=0x00000000
[TTV] ** TEST TOC via cpuid error_code=SERVICES_REQ_SUCCESS id HE_DBG flags 63 1 0 0 service_resp=0x00000000
[TTV] ** TEST soc id error_code=SERVICES_REQ_SUCCESS Device number 0xA100 service_resp=0x00000000
[TTV] ** TEST Boot TOC A32 error_code=SERVICES_REQ_SUCCESS service_resp=0x00000000
```

The SERVICE call to set the debug output off can be seen (the default is enabled in SES). After that, there is no SERVICE debug traffic from SES.

Building the M55 Host Example under ARM-DS

Before starting, ensure you have the ALIFSemiconductor CMSIS Pack installed (See [AP002 Getting Started with Bare Metal & Azure RTOS](#))

- Create a new Project -> C Project -> CMSIS C/C++ Project
- Select Device -> Alif Semiconductor -> Ensemble -> E7 -> AE722F80F55D5AE (or the other one) -> AE722F80F55AE:M55_HE
- In the Project Components window,
 - Check the following highlighted boxes,
 - Then File -> Save



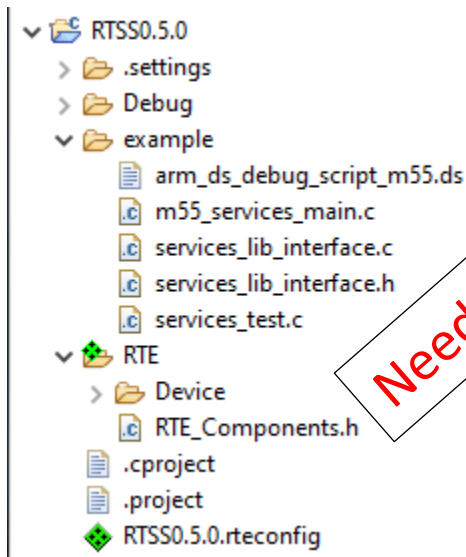
Select the SE Services

Components <input checked="" type="checkbox"/> Resolve					
Software Components	Sel.	Variant	Vendor	Version	Description
AE722F80F5D5AE:M55_H			Alif Semiconductor		ARM Cortex-M55 160 MHz, 13824 KB RAM, 5632 KB ROM
> BSP					
> CMSIS					Cortex Microcontroller Software Interface Components
> CMSIS Driver					Unified Device Drivers compliant to CMSIS-Driver Specifications
> Device					Startup, System Setup
> OSPI XIP					
> SE Services					
> MHU Driver	<input checked="" type="checkbox"/>		AlifSemiconductor	0.63.0	Message Handling Unit driver for Alif Soc
> SE RunTime services	<input checked="" type="checkbox"/>	Lib	AlifSemiconductor	0.63.0	SE runtime Services library for RTSS cores
> SOC Peripherals					
> Startup	<input checked="" type="checkbox"/>	C Startup	AlifSemiconductor	1.0.0	System and Startup for M55_HE device
> FreeRTOS					
> RTOS		AzureRTOS	AlifSemiconductor	0.2.1	Alif Semiconductor port of AzureRTOS for its M55 device
Validation Output					
Description					

Creating a SERVICES based project in ARM-DS

- Copy the source files from your unpacked services release into your project or from the CMSIS Pack (RTSS V0.5.0 or above)
- Copy the following directories / files from the SE Services release over to the ARM-DS project.
 - ./example/m55_he
 - ./example/common
 - **NOTE:** Do not copy the A32 dir

In the below example, a New Project (RTSS0.5.0) has been created in



You can copy the services library and MHU driver source as well.

The example source has been included as this contains the main() entry point.

Adding ALIF SERVICES to your Application code

Calling SERVICES from your Application requires the following:

- Include the header file `/service-release/include/services_lib_api.h` into your code.
- Link with
 - `/service-release/lib/libservices_m55_lib.a` (or `_a32_`)
 - `/service-release/lib/libmhu_m55_lib.a` (or `_a32_`)
- Link with pre-compiled libraries in the CMSIS release
- Copy or create your own `service_lib_interface.c` file and add it to your build.
 - Change any interrupt sources as required.
 - Implement wait function for your environment.
 - Implement print function for your environment.

SE Host Services Library API

The Host Service API is built on a transport protocol layer. This is to facilitate changing the underlying protocol without affecting the rest of the library.

The services library package consists of the following:

Component	Description
libservices_m55_lib.a	Host Services M55 Library
libservices_a32_lib.a	Host Services A32 Library
libmhu_m55_lib.a	Host Services M55 MHU Library (Baremetal)
libmhu_a32_lib.a	Host Services A32 MHU Library (Baremetal)
services_lib_api.h	APIs to access the services library
services_lib_interface.c	To be completed by the user. Compiled with the host CPU application program

There is a porting / abstraction interface component which the user must update depending upon their operating system choice and driver interface to the Message Handling hardware (MHU).

ALIF supply completed interfaces (currently) for

- Bare metal
- ~~FreeRTOS~~
- ~~ThreadX~~
- Linux

The Host services library provides APIs to facilitate service requests from a host CPU to the SE. it must be set up and initialized before dispatching a Host service request to the SE. It needs access to the MHU driver functions to facilitate MHU communication.

The Host services library also requires other generic functions:

SERVICES_wait_ms(uint32_t wait_time_ms)	Delay function
SERVICES_send_mhu_message_to_se(uint32_t message)	Interface to the MHU driver

This layer is intended for any Operating System abstraction.

Host Services Library Interface API Porting Layer

This needs to be updated by the user depending upon the operating system being used (or base metal) and the interface to the Message handling hardware. The requirements of the operating system are very light.

The file `services_lib_interface.c` is the porting interface which needs to be filled in by the user.

SERVICES_wait_ms

```
// Delay function
int wait_ms(uint32_t wait_time_ms)
```

SERVICES_send_mhu_message_to_se

```
// MHU send message to SE on MHU0 channel0
int send_mhu_message_to_se(uint32_t message)
```

The above functions must be configured in `services_init_params` structure and pass to the service library initialization function below.



Host Services Library API Layer

A Service call from an application processor looks like any other C function call, it can take parameters and return results via pass by reference parameters.

The Host Services library is responsible for taking the application Service call and communicating this to the Secure Enclave using the MHU.

SERVICES_initialize

The SERVICES library needs to be initialized before use. There are several parameters that are needed by the SERVICES library such as which MHU is being used, packet buffers etc.

Please refer to the SE Host Services API section for more details.

```
// Service library initialization
void SERVICES_initialize(services_lib_t * init_params)

SERVICES_initialize(services_lib_t * init_params);

// Service synchronization
int SERVICES_synchronize_with_se(uint32_t services_handle)

number_of_retries = SERVICES_synchronize_with_se(services_handle);
```

The M55-HE and M55-HP are started before SERAM is ready to process service calls. This function sends heartbeat requests until one of them succeeds. It returns the number of retries. The maximum number of retries is 100.

SERVICES_send_request

```
// Service request call
uint32_t SERVICES_send_request(uint32_t services_handle,
                               uint16_t service_id,
                               void * service_data,
                               SERVICES_sender_callback callback);

Error_code = SERVICES_send_request(handle, SERVICE_HEARTBEAT_ID,
&service_data, 0);
```

The service request dispatches the service request to the SE. If the callback parameter is NULL, the function waits for the SE to send a response back and then returns an error code. This is analogous to a remote procedure call. If a callback is provided, the call returns immediately after sending the request. The service's transport layer calls the provided back when the service response arrives. It needs access to the host CPUs MHU driver functions to send, receive and ACK messages over the MHU.

SERVICES_send_msg_acked_callback

```
// MHU message ACK callback function
void SERVICES_send_msg_acked_callback(void)
```

The above callback function must be passed to the MHU driver during initialization. It is called by the driver when an MHU message is ACKed by the SE. Channel clear interrupt CH_INT_ST is set when SE has received the MHU message and SE clears the channel status CH_ST bits by setting CH_CLR. This is assumed to be an ACK from SE that it has received an MHU message sent by the host CPU.

SERVICES_rx_msg_callback

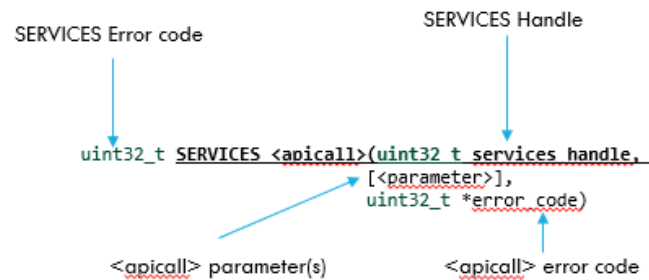
```
// MHU message received callback function
void SERVICES_rx_msg_callback(uint32_t message);
```

The above callback function must be passed to the MHU driver during initialization. It is called by the driver when an MHU message is received from the SE as a response to a service request earlier to the SE

```
// Pinmux service
int PINMUX_config(Port_t port_num, Pin_t pin_num, Pinfunction_t
function);
```

SE Host SERVICES Library - Anatomy of a SERVICE Call

A SERVICES API call takes the following format:



- SERVICES API are regular function calls taking the format SERVICES_<module>
- Returns Services error code.
 - This relates to the SERVICES transport layer.
- Other return values are passed in the function prototype.
 - These parameters can be IN and OUT and can be variable sized.
 - Results from the SERVICE call are returned via these variables.
 - The error_code return relates to the error returned from the actual SERVICE call.

SE Host Service Library Internal implementation

Each SERVICE defines a unique parameter block structure.

- See `example_service_t` in the diagram below.
- This always contains the Header and a return response error code,
- There may be passed parameters from the Caller.
- There may be return parameters to the Caller.

For each SERVICE call processed in SERAM the parameter block is dereferenced

- Sent parameters can be passed to the calling function.
- The Error code from the called function will be sent back as part of the parameter block.

```
typedef struct
{
    service_header_t header;
    volatile uint32_t send_<param>;    /*!< Send    parameter */
    volatile uint32_t resp_<param>;    /*!< Return parameter */
    volatile uint32_t resp_error_code; /*!< Call error code */
} example_service_t;

void SERVICES_example_call(services_req_t *service)
{
    example_service_t *p_svc =
        (example_service_t *)service->pkt_buffer_address; /* services request */
    uint32_t error_code;
    uint32_t local_result;

    error_code = function_call(p_svc->send_<param>, &local_result);

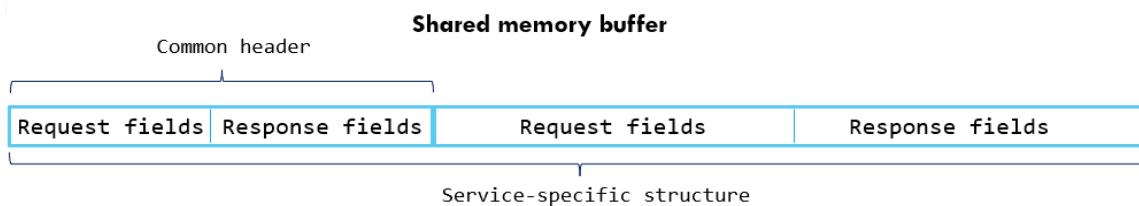
    p_svc->resp_<param>    = local_result;
    p_svc->resp_error_code = error_code;

    SERVICES_send_response_code(service, SERVICES_REQ_SUCCESS);
}
```

There is no copying of data between the Host Application CPU and the Secure enclave.

SE Host Service Library Transport Protocol details

The transport protocol is as follows:



Common header format

Service ID: req	uint16_t send_sid;
Flags: req	uint16_t send_flags;
Error Code: resp	uint16_t resp_error_code; // transport layer error code
Padding	uint16_t none_padding;
	} service_header_t;

Service-specific structure example

```
typedef struct
{
    service_header_t header;
    uint8_t send_port_num;
    uint8_t send_pin_num;
    uint8_t send_config_data;
    uint8_t resp_error_code; // service-specific error code
} pinmux_svc_t;
```

SE Host Service Library Transport Error Codes

The following are the valid return and Error codes for the services library.

Error Code	Value	Meaning
SERVICES_REQ_SUCCESS	0x00	
SERVICES_REQ_NOT_ACKNOWLEDGE	0xFF	
SERVICES_REQ_TIMEOUT	0xFD	
SERVICES_REQ_UNKNOWN_COMMAND	0xFC	

This error relates to any operation on the transport layer of the SERVICES library. Most SERVICES library APIs have a second error code which is the error code return from the called function.



SE Host Services Library Error Handling

There are two levels of Error with a SERVICES API call,

- SERVICES Transport layer error code
- Function call error code

SE Host Services API

The services provided by the SE via the MHU are as follows.

Miscellaneous

SERVICES_Initialize

Syntax:

```
uint32_t SERVICES_initialize(services_lib_t * init_params)
```

Description:

Initialize the services library.

A user needs to supply the following platform specific data and functions for the following operations.

- Global address of the CPU's local data memory 0x0 for A32, start of DTCMs for the M55 cores.
- Packet buffer
 - Defined in Application memory space.
 - Used by the SERVICES library.
- Send MHU message function – provided by the MHU driver.
- wait (delay) function – platform and OS specific.
- print function – platform and OS specific.

The examples source contains service_lib_interface.c which shows how to set up the SERVICES library. This is not part of the SERVICES Library code as it is expected to be customized by a User for their application, which is why this is included as source code in the examples.

Parameters:

init_params	Initialization parameters
-------------	---------------------------

Returns:

Restrictions:

None

Example:

```
#include "services_lib_api.h" /* services_lib_t lives here */

static uint8_t
    s_packet_buffer[SERVICES_MAX_PACKET_BUFFER_SIZE] __attribute__((aligned (4)));

int SERVICES_print(const char * fmt, ...)
{
    /* To be filled in by the user */
}
```

```
    return 0;
}

int32_t SERVICES_wait_ms(uint32_t wait_time_ms)
{
    /* To be filled in by the user */

    return 0;
}

int main (void)
{
    uint32_t ErrorCode = SERVICES_OK;

    services_lib_t services_init_params =
    {
        .global_offset          = DTCM_GLOBAL_ADDRESS - M55_DTCM_LOCAL_OFFSET,
        .packet_buffer_address = (uint32_t)s_packet_buffer,
        .fn_send_mhu_message    = send_message,
        .fn_wait_ms             = &SERVICES_wait_ms,
        .wait_timeout           = timeout,
        .fn_print_msg           = &SERVICES_print,
    };

    ErrorCode = SERVICES_initialize(&services_init_params);

    if (ErrorCode != SERVICES_REQ_SUCCESS)
    {
        return ErrorCode;
    }
}
```

SERVICES_version

Syntax:

```
const char *SERVICES_version(void)
```

Description:

Returns the version of the Host library.

Parameters:

None

Returns:

Version string

Restrictions:

None

Example:

```
#include <services_lib_api.h>

int main (void)
{
    uint32_t ErrorCode = SERVICES_OK;

    printf("SERVICES version %s\n", SERVICES_version());
}
```

SERVICES_register_channel

Syntax:

```
uint32_t SERVICES_register_channel(uint32_t mhu_id, uint32_t channel_number);
```

Description:

Returns a handle for a specific MHU and channel, to be used in subsequent service calls.

Parameters:

mhu_id	MHU ID
channel_number	Channel number (within the MHU)

Returns:

Service channel handle

Restrictions:

The MHU ID and channel number must be valid.

The maximum number of MHU Channels is 124.

Example:

```
#include <services_lib_api.h>

#define NUM_MHU                2

#define MHU_M55_SE_MHU0        0
#define MHU_M55_SE_MHU1        1

int main (void)
{
    mhu_initialize();
    SERVICES_Setup(s_mhu_driver_out.send_message, MAXIMUM_TIMEOUT);

    uint32_t services_handle = SERVICES_register_channel(MHU_M55_SE_MHU0, 0);

    printf("SERVICES handle %d\n", services_handle);
}
```

SERVICES_prepare_packet_buffer

Syntax:

```
uintptr_t SERVICES_prepare_packet_buffer(uint32_t size)
```

Description:

Prepares a packet buffer.

Used by the SERVICES library to allocate a packet buffer from the global Packet buffer memory.

Parameters:

Size	Packet buffer size
------	--------------------

Returns:

Pointer to packet buffer.

Restrictions:

Example:



SERVICES_local_to_global_addr

Syntax:

```
uintptr_t uint32_t SERVICES_local_to_global_addr(uint32_t local_addr)
```

Description:

Address translation – local to global

Used internally by the SERVICES library.

Parameters:

local_addr	address to translate
------------	----------------------

Returns:

Pointer to packet buffer.

Restrictions:

Example:

SERVICES_global_to_local_addr

Syntax:

```
uintptr_t uint32_t SERVICES_global_to_local_addr(uint32_t global_addr)
```

Description:

Address translation – global to local

Used internally by the SERVICES library.

Parameters:

global_addr	address to translate
-------------	----------------------

Returns:

Pointer to packet buffer.

Restrictions:

Example:

Maintenance Services

The maintenance services provide a mechanism to maintain a reliable connection between the sender and receiver and/or request general information from the receiver. The following maintenance services are supported by SE.

SERVICES_heartbeat

Syntax:

```
uint32_t SERVICES_heartbeat (uint32_t services_handle)
```

Description:

Heartbeat request.

This service is analogous to “ping”.

It is a message sent by the sender to tell the receiver that it is alive. It can also be sent by SE to check if another core is alive and responding. When this message is ACKed by the receiver, the sender knows that the receiver is alive. This message does not warrant a response from the receiver other than ACK.

Parameters:

services_handle

Returns:

Restrictions:

None

Example:

```
int main (void)
{
    uint32_t ErrorCode = SERVICES_OK;

    mhu_initialize();
    SERVICES_Setup(s_mhu_driver_out.send_message, MAXIMUM_TIMEOUT);

    //SERVICES wait ms(0x1000000);

    uint32_t services_handle = SERVICES_register_channel(MHU_M55_SE_MHU0, 0);

    ErrorCode = SERVICES_heartbeat(services_handle);
    if (ErrorCode != SERVICES_REQ_SUCCESS)
    {
        return ErrorCode;
    }
}
```




```
return ErrorCode;  
}
```

SERVICES_synchronize_with_se

Syntax:

```
int SERVICES_synchronize_with_se(uint32_t services_handle)
```

Description:

Wait for the SE to become available.

This function is built on top of SERVICES_heartbeat.

Parameters:

services_handle

Returns:

Restrictions:

None

Example:

```
int main (void)
{
    int retry_count;

    /* keep sending heartbeat services requests until one succeeds */
    retry_count = SERVICES_synchronize_with_se(services_handle);
}
```

System Management

SERVICES_system_set_services_debug

Syntax:

```
uint32_t SERVICES_system_set_services_debug (uint32_t services_handle,  
                                              bool debug_enable,  
                                              uint32_t *error_code)
```

Description:

Enable / Disable Service debug traffic from SES.

Parameters:

service_handle	Service Handle
debug_enable	Toggle debug output.
error_code	Service Error Code

Returns:**Restrictions:**

None

Example:

```
int main (void)
{
    uint32_t service_error_code;

    SERVICES_system_set_services_debug(services_handle,
                                       false, /* False = NO debug output */
                                       &service_error_code);

    if (service_error_code != SERVICES_REQ_SUCCESS)
    {
        /* Deal with error */
    }
}
```

SERVICES_system_read_otp

Syntax:

```
uint32_t SERVICES_system_read_otp (uint32_t services_handle,  
                                     uint32_t otp_offset,  
                                     uint32_t *otp_value_word,  
                                     uint32_t *error_code)
```

Description:

Read an OTP offset.

Parameters:

service_handle	Service Handle
otp_offset	OTP Byte offset to read.
otp_value_word	OTP value at otp_offset
error_code	Service Error Code

Returns:

SERVICES_REQ_INVALID_OTP_OFFSET

Restrictions:

Example:

```
int main (void)
{
    uint32_t ErrorCode = SERVICES_REQ_SUCCESS;
    uint32_t service_error_code;
    uint32_t otp_value;

    ErrorCode = SERVICES_system_read_otp(services_handle,
                                         0x51, /* Offset */
                                         &otp_value,
                                         &service_error_code);

    if (ErrorCode != SERVICES_REQ_SUCCESS)
    {
        return ErrorCode;
    }
}
```

SERVICES_system_get_otp_data

Syntax:

```
uint32_t SERVICES_system_get_otp_data (uint32_t services_handle,  
                                       SERVICES_otp_data_t *otp_info,  
                                       uint32_t * error_code)
```

Description:

Returns details of OTP data

Parameters:

service_handle	Service Handle
otp_info	Details of OTP contents
error_code	Service Error Code

Returns:

SERVICES_REQ_COMMAND_NOT_IMPLEMENTED (for now)

Restrictions:

OTP format is still under definition. This function returns SERVICES_REQ_COMMAND_NOT_IMPLEMENTED (for now). This function will be deprecated eventually.

Example:

```
int main (void)  
{  
    uint32_t ErrorCode = SERVICES_OK;  
    uint32_t service_error_code;  
    SERVICES_otp_data_t otp_info;  
  
    ErrorCode = SERVICES_system_get_otp_data(services_handle,  
                                             &otp_info,  
                                             &service_error_code);  
  
    if (ErrorCode != SERVICES_REQ_SUCCESS)  
    {  
        return ErrorCode;  
    }  
}
```

SERVICES_system_get_toc_data

Syntax:

```
uint32_t SERVICES_system_get_toc_data (uint32_t services_handle,
                                       SERVICES_toc_data_t *toc_info,
                                       uint32_t * error_code)
```

Description:

Returns details of TOC objects in MRAM.

typedef struct

```
{
    uint8_t    image_identifier[8];    /**< TOC name    */
    uint32_t   version;               /**< TOC Version */
    uint32_t   cpu;                   /**< TOC Cpu ID  */
    uint32_t   store_address;
    uint32_t   load_address;          /**< TOC load    */
    uint32_t   boot_address;
    uint32_t   image_size;
    uint32_t   flags;
} SERVICES_toc_info_t;

/**
 * @struct SERVICES_toc_data_t
 */
typedef struct
{
    uint32_t number_of_toc_entries;
    SERVICES_toc_info_t toc_entry[SERVICES_NUMBER_OF_TOC_ENTRIES];
} SERVICES_toc_data_t;
```

The number of TOC entries found is returned followed by the TOC entry details.

Parameters:

service_handle	Service Handle
toc_info	Details for all TOCs found
error_code	Service Error Code

Returns:

Restrictions:

None

Example:

```
int main (void)
{
    uint32_t ErrorCode = SERVICES_OK;
    uint32_t service_error_code;
    SERVICES_toc_data_t toc_info;

    ErrorCode = SERVICES_system_get_toc_data(services_handle,
                                             &toc_info,
                                             &service_error_code);

    if (ErrorCode != SERVICES_REQ_SUCCESS)
    {
        return ErrorCode;
    }
}
```

SERVICES_system_get_toc_number

Syntax:

```
uint32_t SERVICES_system_get_toc_number(uint32_t services_handle,  
                                         uint32_t *toc_number,  
                                         uint32_t * error_code)
```

Description:

Returns the number of Table of contents in MRAM

Parameters:

service_handle	Service Handle
toc_number	Number of TOCs
error_code	Service Error Code

Returns:

Restrictions:

None

Example:

```
int main (void)  
{  
    uint32_t ErrorCode = SERVICES_OK;  
    uint32_t number_of_tocs;  
    uint32_t service_error_code;  
  
    ErrorCode = SERVICES_system_get_toc_number(services_handle,  
                                              &number_of_tocs,  
                                              &service_error_code);  
    if (ErrorCode != SERVICES_REQ_SUCCESS)  
    {  
        return ErrorCode;  
    }  
}
```


SERVICES_system_get_toc_via_name

Syntax:

```
uint32_t SERVICES_system_get_toc_via_name(uint32_t services_handle,  
                                           const uint8_t *cpu_name,  
                                           uint32_t * error_code);
```

Description:

Returns the ??

Parameters:

service_handle	Service Handle
cpu_name	name of Application
error_code	Service Error Code

Returns:

Restrictions:

None

Example:

```
int main (void)  
{  
    uint32_t ErrorCode = SERVICES_OK;  
    uint32_t service_error_code;  
  
    ErrorCode = SERVICES_system_get_toc_via_name(services_handle,  
                                                (uint8_t *) "M55-HP",  
                                                &service_error_code);  
  
    if (ErrorCode != SERVICES_REQ_SUCCESS)  
    {  
        return ErrorCode;  
    }  
}
```

SERVICES_system_get_toc_via_cpuid

Syntax:

```
uint32_t SERVICES_system_get_toc_via_cpuid(uint32_t services_handle,  
                                           SERVICE_cpuid_t cpuid,  
                                           SERVICES_toc_data_t *toc_info,  
                                           uint32_t * error_code);
```

Description:

Returns the TOC information for a given CPU.

Valid CPUs are

```
typedef enum  
{  
    FUSION_A32_0    = 0,  
    FUSION_A32_1    = 1,  
    FUSION_M55_HP   = 2,  
    FUSION_M55_HE   = 3  
} SERVICE_cpuid_t;
```

If there is more than one TOC entry per CPUID this will be reflected in the toc_info structure returned from the SERVICE call.

Parameters:

service_handle	Service Handle
cpuid	Which Application CPU
toc_info	ATOC information
error_code	Service Error Code

Returns:

Restrictions:

Example:

```
int main (void)  
{  
    uint32_t ErrorCode = SERVICES_OK;  
    SERVICES_toc_data_t toc_info;  
    Uint32_t service_error_code;  
  
    error_code = SERVICES_system_get_toc_via_cpuid(services_handle,  
                                                  FUSION_M55_HE,
```

```
                                &toc_info,  
                                &service_error_code);  
  
if (ErrorCode != SERVICES_REQ_SUCCESS)  
{  
    return ErrorCode;  
}  
  
/* Process each TOC entry found */  
for (int each_toc = 0; each_toc < toc_info.number_of_toc_entries; each_toc++)  
{  
    SERVICES_toc_info_t *toc_entry_p;  
  
    toc_entry_p = (SERVICES_toc_info_t *)&toc_info.toc_entry[each_toc];  
  
    /* do something with the TOC information */  
}
```

SERVICES_system_get_device_part_number

Syntax:

```
uint32_t SERVICES_system_get_device_part_number(uint32_t services_handle,  
                                                uint32_t *device_part_number,  
                                                uint32_t * error_code)
```

Description:

Returns the SoC device identifier.

Parameters:

service_handle	Service Handle
device_part_number	Device id (Soc ID)
error_code	Service Error Code

Returns:

device_part_number as integer e.g., 0x0000B200

Restrictions:

None

Example:

```
int main (void)  
{  
    uint32_t ErrorCode = SERVICES_OK;  
    uint32_t device_id;  
    uint32_t service_error_code;  
  
    ErrorCode = SERVICES_system_get_device_part_number(services_handle,  
                                                       &device_part_number,  
                                                       &service_error_code);  
  
    if (ErrorCode != SERVICES_REQ_SUCCESS)  
    {  
        return ErrorCode;  
    }  
}
```

SERVICES_system_get_device_data

Syntax:

```
uint32_t SERVICES_system_get_device_data(uint32_t services_handle,
                                         SERVICES_version_data_t *device_info,
                                         uint32_t * error_code)
```

Description:

Retrieves the Device information.

The return is SERVICES_version_data_t as follows:

```
typedef struct
{
    uint32_t revision_id; /* SoC revision */
    uint8_t ALIF_PN[16]; /* SoC part number */
    uint8_t HBK0 [16]; /* ALIF Key */
    uint8_t HBK1 [16]; /* ALIF Key */
    uint8_t HBK_FW [20]; /* ALIF Firmware version */
    uint8_t config [4]; /* Wounding data */
    uint8_t DCU [16]; /* DCU settings */
    uint8_t MfgData[32]; /* Manufacturing data */
    uint8_t SerialN[8]; /* SoC Serial number */
    uint8_t LCS; /* SoC lifecycle state */
} SERVICES_version_data_t;
```

Parameters:

service_handle	Service Handle
device_info	Device info
error_code	Service Error Code

Returns:

Restrictions:

None

Example:

```
int main (void)
{
    uint32_t ErrorCode = SERVICES_OK;
    uint32_t device_id;
    SERVICES_version_data_t device_data;
    uint32_t service_error_code;
```

```
ErrorCode = SERVICES_system_get_device_info(services_handle,  
                                             &device_data,  
                                             &service_error_code);  
  
if (ErrorCode != SERVICES_REQ_SUCCESS)  
{  
    return ErrorCode;  
}  
}
```

SERVICES_get_se_revision

Syntax:

```
uint32_t SERVICES_get_se_revision(uint32_t services_handle,  
                                   uint8_t *revision_data,  
                                   uint32_t *error_code)
```

Description:

Retrieve the SES Banner string.

Parameters:

service_handle	Service Handle
revision_data	banner string return
error_code	Service Error Code

Returns:

String containing the banner data. Maximum size is 80 characters.

Restrictions:

None

Example:

```
int main (void)
{
    uint32_t error_code = SERVICES_REQ_SUCCESS;
    uint32_t service_error_code;
    uint8_t se_revision[80];

    error_code = SERVICES_get_se_revision(services_handle,
                                         (uint8_t*)&se_revision[0],
                                         &services_error_code);

    if (error_code != SERVICES_REQ_SUCCESS)
    {
        /* deal with error */
    }
}
```

Application Services

Application services provide mechanisms to configure certain functions. The SE can be requested to make these configuration changes.

SERVICES_uart_write

Syntax:

```
uint32_t SERVICES_uart_write(uint32_t services_handle, size_t size, const uint8_t *uart_data)
```

Description:

SE-UART write. The buffer provided is printed via the Secure enclave UART (SE-UART) port.

Parameters:

services_handle	Service handle
size	Number of bytes to write
uart_data	Buffer containing print data

None

Returns:

Restrictions:

None

Example:

```
int main (void)
{
    uint32_t ErrorCode = SERVICES_OK;
    uint8_t buffer[256];

    ... <format print buffer>

    ErrorCode = SERVICES_uart_write(services_handle,
                                   sizeof(buffer),
                                   (uint8_t *)buffer);

    if (ErrorCode != SERVICES_REQ_SUCCESS)
    {
        return ErrorCode;
    }
}
```


SERVICES_pinmux

Refer document [se-mhu-pinmux-pad_configuration](#)

Syntax:

```
uint32_t SERVICES_pinmux(uint32_t services_handle, uint8_t port_number,  
                          uint8_t pin_number, uint8_t configuration_value,  
                          uint32_t * error_core)
```

Description:

Pinmux request

Parameters:

services_handle	
port_number	Port Number
pin_number	Pin Number
configuration_value	?
error_code	Service Error Code

Returns:

Restrictions:

None

Example:

```
int main (void)  
{  
    uint32_t ErrorCode = SERVICES_OK;  
    uint32_t service_error_code;  
  
    ErrorCode = SERVICES_pinmux(services_handle, 1, 14, 0, &service_error_code);  
    if (ErrorCode != SERVICES_REQ_SUCCESS)  
    {  
        return ErrorCode;  
    }  
}
```

SERVICES_padcontrol

NOTE: Refer to document [se-mhu-pinmux-pad_configuration](#)

Syntax:

```
uint32_t SERVICES_padcontrol(uint32_t services_handle, uint8_t port_number,  
                             uint8_t pin_number, uint8_t configuration_value,  
                             uint32_t * error_core)
```

Description:

Pad control request.

Parameters:

services_handle	
port_number	Port Number
pin_number	Pin Number
configuration_value	?
error_code	Service Error Code

Returns:

Restrictions:

None

Example:

```
int main (void)  
{  
    uint32_t ErrorCode = SERVICES_OK;  
    uint32_t service_error_code;  
  
    ErrorCode = SERVICES_padcontrol(services_handle, 1, 14, 0, &service_error_code);  
    if (ErrorCode != SERVICES_REQ_SUCCESS)  
    {  
        return ErrorCode;  
    }  
}
```

SERVICES_application_ospi_write_key

Syntax:

```
uint32_t SERVICES_application_ospi_write_key(uint32_t services_handle, uint32_t command, uint8_t *key, uint32_t * error_code)
```

Description:

Write an AES decryption key to the OSPI registers. The command field indicates whether to use an externally provided key or a key stored in the OTP, and which OSPI to apply it to – OSPI0 or OSPI1.

```
#define OSPI_WRITE_OTP_KEY_OSPI0          0
#define OSPI_WRITE_OTP_KEY_OSPI1          1
#define OSPI_WRITE_EXTERNAL_KEY_OSPI0     2
#define OSPI_WRITE_EXTERNAL_KEY_OSPI1     3
```

Parameters:

services_handle	Service handle
command	Indicates OSPI0/OSPI1 and external/OTP key
key	Buffer containing print data
error_code	Service error code

Returns:

Restrictions:

None

Example:

SERVICES_SRAM_retention_config

Syntax:

```
uint32_t SERVICES_SRAM_retention_config(uint32_t services_handle,  
                                         uint32_t sram_mem_retention,  
                                         uint32_t *service_error_code);
```

Description:

Configure retention for global SRAM0 or SRAM1

Parameters:

services_handle	Service handle
sram_mem_retention	Which SRAM
service_error_code	Return error code

```
#define POWER_MEM_RETENTION_SRAM0 0x30
```

```
#define POWER_MEM_RETENTION_SRAM1 0x31
```

Returns:

ErrorCode - SERVICES_REQ_SUCCESS, SERVICES_REQ_CANNOT_EXECUTE_SERVICE

Service_error_code ERROR_POWER_SRAM_RETENTION_INVALID Incorrect SRAM bank specified.

Restrictions:

REV_A1 does not configure any retention.

Example:

```
int main (void)  
{  
    uint32_t error_code = SERVICES_REQ_SUCCESS;  
  
    uint32_t service_error_code;  
  
    error_code = SERVICES_SRAM_retention_config(services_handle,  
                                                POWER_MEM_RETENTION_SRAM0,  
                                                &service_error_code);  
  
    if (error_code != SERVICES_REQ_SUCCESS)  
    {
```



```
    return error_code;  
}  
}
```



Clock Management

Set or Get System Clock settings



Interrupt muxing

<Action: Add more details>



Event routing

<Action: Add more details>

Power Services

SERVICES_power_stop_mode_request

Syntax:

```
uint32_t SERVICES_power_stop_mode_request(uint32_t services_handle)
```

Description:

Request the Secure Enclave to enter stop mode.

Parameters:

services_handle

Returns:

ErrorCode - SERVICES_REQ_SUCCESS, SERVICES_REQ_CANNOT_EXECUTE_SERVICE

Restrictions:**Example:**

```
int main (void)
{
    uint32_t ErrorCode = SERVICES_OK;

    error_code = SERVICES_power_stop_mode_request(services_handle);
    if (ErrorCode != SERVICES_REQ_SUCCESS)
    {
        return ErrorCode;
    }
}
```

SERVICES_power_ewic_config

Syntax:

```
uint32_t SERVICES_power_ewic_config(uint32_t services_handle,  
                                     uint32_t ewic_source);
```

Description:

Configure the EWIC

Parameters:

services_handle

ewic_source EWIC source

Returns:

ErrorCode - SERVICES_REQ_SUCCESS, SERVICES_REQ_CANNOT_EXECUTE_SERVICE

Restrictions:

Example:

```
int main (void)  
{  
    uint32_t error_code = SERVICES_REQ_SUCCESS;  
    uint32_t ewic_config;  
  
    ewic_config &= (1 << 6);  
    error_code = SERVICES_power_ewic_config(services_handle,  
                                           ewic_config);  
  
    if (error_code != SERVICES_REQ_SUCCESS)  
    {  
        return error_code;  
    }  
}
```

SERVICES_power_wakeup_config

Syntax:

```
uint32_t SERVICES_power_wakeup_config(uint32_t services_handle,
                                       uint32_t vbat_wakeup_source,
                                       services_power_profile_t power_profile)
```

Description:

Configure the wake up source

Parameters:

services_handle

vbat_wakeup_source Wake up source

typedef enum

```
{
    VBAT_WAKEUP_MDM                = 0x1,           // bit0
    VBAT_WAKEUP_RTC_SE              = 0x10,          // bit4
    VBAT_WAKEUP_RTC_A               = 0x20,          // bit5
    VBAT_WAKEUP_LPCMP               = 0x40,          // bit6
    VBAT_WAKEUP_BROWN_OUT           = 0x80,          // bit7
    VBAT_WAKEUP_LPTIMER              = 0XF00,         // bit11:8
    VBAT_WAKEUP_LPGPIO               = 0XFF0000,      // bit23:16
} SERVICES_wakeup_cfg_t;
```

power_profile Power profile

typedef enum

```
{
    LOWEST_POWER_PROFILE = 0,           /**< LOWEST_POWER_PROFILE */
    HIGH_PERFORMANCE_POWER_PROFILE, /**< HIGH_PERFORMANCE_POWER_PROFILE */
    USER_SPECIFIED_PROFILE,           /**< USER_SPECIFIED_PROFILE */
    DEFAULT_POWER_PROFILE,             /**< DEFAULT_POWER_PROFILE */
    NUMBER_OF_POWER_PROFILES           /**< NUMBER_OF_POWER_PROFILES */
} services_power_profile_t;
```

Returns:

ErrorCode - SERVICES_REQ_SUCCESS, SERVICES_REQ_CANNOT_EXECUTE_SERVICE

Restrictions:

Example:

```
int main (void)
{
    __uint32_t error_code = SERVICES_REQ_SUCCESS;

    error_code = SERVICES_power_wakeup_config(services_handle,
                                              VBAT_WAKEUP_RTC_SE
                                              | VBAT_WAKEUP_RTC_A,
                                              LOWEST_POWER_PROFILE);

    if (error_code != SERVICES_REQ_SUCCESS)
    {
        return error_code;
    }
}
```

SERVICES_power_mem_retention_config

Syntax:

uint32_t

```
SERVICES_power_mem_retention_config(uint32_t services_handle,
                                     uint32_t mem_retention,
                                     services_power_profile_t power_profile)
```

Description:

Configure memory retention.

Parameters:

services_handle

mem_retention Memory to be retained.

```
// Memory retention bit encoding for mem_retention_enable
#define POWER_MEM_RET_FIREWALL_RAM      0x01UL
#define POWER_MEM_RET_SE_SRAM          0x02UL
#define POWER_MEM_RET_BACKUP_RAM_4KB    0x04UL
// M55-HE TCM RET1: ITCM 0-128kb; DTCM 0-128kb
#define POWER_MEM_RET_ES1_TCM_RET1      0x08UL
// M55-HE TCM RET1: ITCM 128-256kb; DTCM 128-256kb
#define POWER_MEM_RET_ES1_TCM_RET2      0x10UL
// XTENSA TCM RET1: ITCM 128-512kb
#define POWER_MEM_RET_XTENSA_TCM_RET1    0x20UL
// XTENSA TCM RET1: ITCM 64-128kb
#define POWER_MEM_RET_XTENSA_TCM_RET2    0x40UL
// XTENSA TCM RET1: ITCM 0-64kb
#define POWER_MEM_RET_XTENSA_TCM_RET3    0x80UL
// M55-M TCM RET1: ITCM 1MB; DTCM 384kb
#define POWER_MEM_RET_M55_M_TCM_RET1     0x100UL
#define POWER_MEM_RET_MODEM_BACKUP_RAM_16KB 0x200UL
```

power_profile Power profile

```
typedef enum
{
    LOWEST_POWER_PROFILE = 0,           /**< LOWEST_POWER_PROFILE */
    HIGH_PERFORMANCE_POWER_PROFILE,     /**< HIGH_PERFORMANCE_POWER_PROFILE */
    USER_SPECIFIED_PROFILE,             /**< USER_SPECIFIED_PROFILE */
    DEFAULT_POWER_PROFILE,               /**< DEFAULT_POWER_PROFILE */
    NUMBER_OF_POWER_PROFILES             /**< NUMBER_OF_POWER_PROFILES */
} services_power_profile_t;
```

Returns:

ErrorCode - SERVICES_REQ_SUCCESS, SERVICES_REQ_CANNOT_EXECUTE_SERVICE

Restrictions:**Example:**

```
int main (void)
{
    uint32_t error_code = SERVICES_REQ_SUCCESS;

    error_code = SERVICES_power_mem_retention_config(services_handle,
                                                    POWER_MEM_RETENTION_SE_RAM,
                                                    LOWEST_POWER_PROFILE);

    if (error_code != SERVICES_REQ_SUCCESS)
    {
        return error_code;
    }
}
```

SERVICES_power_m55_he_vtor_save

Syntax:

```
SERVICES_power_m55_he_vtor_save(uint32_t services_handle,  
                                uint32_t ns_vtor_addr,  
                                uint32_t se_vtor_addr,  
                                services_power_profile_t power_profile)
```

Description:

m55-he VTOR value save for wake up

Parameters:

services_handle

ns_vtor_addr Non-secure VTOR address

se_vtor_addr Secure VTOR address

power_profile Power profile

typedef enum

```
{  
    LOWEST_POWER_PROFILE = 0,              /**< LOWEST_POWER_PROFILE */  
    HIGH_PERFORMANCE_POWER_PROFILE,       /**< HIGH_PERFORMANCE_POWER_PROFILE */  
    USER_SPECIFIED_PROFILE,               /**< USER_SPECIFIED_PROFILE */  
    DEFAULT_POWER_PROFILE,                /**< DEFAULT_POWER_PROFILE */  
    NUMBER_OF_POWER_PROFILES              /**< NUMBER_OF_POWER_PROFILES */  
} services_power_profile_t;
```

Returns:

ErrorCode - SERVICES_REQ_SUCCESS, SERVICES_REQ_CANNOT_EXECUTE_SERVICE

Restrictions:

Example:

```
int main (void)  
{  
    uint32_t error_code = SERVICES_REQ_SUCCESS;  
  
    error_code = SERVICES_power_m55_he_vtor_save(services_handle,  
                                                0x0,
```

```
0x0,  
LOWEST_POWER_PROFILE);
```

```
if (error_code != SERVICES_REQ_SUCCESS)  
{  
    return error_code;  
}  
}
```


SERVICES_power_m55_hp_vtor_save

Syntax:

```
SERVICES_power_m55_hp_vtor_save(uint32_t services_handle,  
                                uint32_t ns_vtor_addr,  
                                uint32_t se_vtor_addr,  
                                services_power_profile_t power_profile)
```

Description:

m55-hp VTOR value save for wake up

Parameters:

services_handle

ns_vtor_addr Non-secure VTOR address

se_vtor_addr Secure VTOR address

power_profile Power profile

typedef enum

```
{  
    LOWEST_POWER_PROFILE = 0,            /**< LOWEST_POWER_PROFILE */  
    HIGH_PERFORMANCE_POWER_PROFILE, /**< HIGH_PERFORMANCE_POWER_PROFILE */  
    USER_SPECIFIED_PROFILE,            /**< USER_SPECIFIED_PROFILE */  
    DEFAULT_POWER_PROFILE,            /**< DEFAULT_POWER_PROFILE */  
    NUMBER_OF_POWER_PROFILES           /**< NUMBER_OF_POWER_PROFILES */  
} services_power_profile_t;
```

Returns:

ErrorCode - SERVICES_REQ_SUCCESS, SERVICES_REQ_CANNOT_EXECUTE_SERVICE

Restrictions:

Example:

```
int main (void)  
{  
    uint32_t error_code = SERVICES_REQ_SUCCESS;  
  
    error_code = SERVICES_power_m55_hp_vtor_save(services_handle,  
                                                0x0,
```

```
0x0,  
LOWEST_POWER_PROFILE);
```

```
if (error_code != SERVICES_REQ_SUCCESS)  
{  
    return error_code;  
}  
}
```

SERVICES_corestone_standby_mode

Syntax:

```
SERVICES_corestone_standby_mode (uint32_t services_handle,  
                                host_cpu_clus_pwr_req_t host_cpu_clus_pwr_req,  
                                bsys_pwr_req_t bsys_pwr_req,  
                                uint32_t *error_code)
```

Description:

Function to configure corestone standby mode

Parameters:

services_handle

host_cpu_clus_pwr_req Host CPU cluster power state request configuration

bsys_pwr_req Base system power request configuration

power_profile Power profile

Returns:

ErrorCode - SERVICES_REQ_SUCCESS, SERVICES_REQ_CANNOT_EXECUTE_SERVICE

Restrictions:

Example:

```
int main (void)  
{  
    uint32_t error_code = SERVICES_REQ_SUCCESS;  
    host_cpu_clus_pwr_req_t host_cpu_clus_pwr_req;  
    bsys_pwr_req_t bsys_pwr_req;  
  
    host_cpu_clus_pwr_req.word = 0;  
    host_cpu_clus_pwr_req.bits.mem_ret_req = 0;  
    host_cpu_clus_pwr_req.bits.pwr_req = 1;  
  
    bsys_pwr_req.word = 0;  
    bsys_pwr_req.bits.systop_pwr_req = 1;  
    bsys_pwr_req.bits.dbgtop_pwr_req = 0;  
    bsys_pwr_req.bits.refclk_req = 1;  
    bsys_pwr_req.bits.wakeup_en = 0;
```

```
error_code = SERVICES_corestone_standby_mode(services_handle,  
                                              host_cpu_clus_pwr_req,  
                                              bsys_pwr_req,  
                                              &service_error_code);  
  
if (error_code != SERVICES_REQ_SUCCESS)  
{  
    return error_code;  
}  
}
```

SERVICES_power_memory_req

Syntax:

```
uint32_t SERVICES_power_memory_req(uint32_t services_handle,  
                                   uint32_t memory_request,  
                                   uint32_t *error_code)
```

Description:

Function to disable power to SERAM0, SERAM1 or MRAM

The following are Memory requests:

```
POWER_MEM_SRAM_0_ENABLE  
POWER_MEM_SRAM_1_ENABLE  
POWER_MEM_SRAM_0_ISOLATION_ENABLE  
POWER_MEM_SRAM_1_ISOLATION_ENABLE  
POWER_MEM_MRAM_ENABLE
```

NOTE: This is subject to change

Parameters:

services_handle

memory_request, Which Memory to deal with

Returns:

ErrorCode - SERVICES_REQ_SUCCESS, SERVICES_REQ_CANNOT_EXECUTE_SERVICE

Restrictions:

MRAM may not be able to be disabled directly (To be checked on real device).

Example:

```
int main (void)  
{  
    error_code = SERVICES_power_memory_req(services_handle,  
                                           (POWER_MEM_SRAM_0_ENABLE |  
                                            POWER_MEM_SRAM_1_ISOLATION_ENABLE),  
                                           &return_error_code);  
  
    if (error_code != SERVICES_REQ_SUCCESS)  
    {  
        return error_code;  
    }  
}
```



}
}

SERVICES_get_run_cfg

Syntax:

```
uint32_t SERVICES_get_run_cfg(uint32_t services_handle,  
                               run_profile_t *pp,  
                               uint32_t *error_code);
```

Description:

Retrieve the current RUN mode status.

Parameters:

services_handle

pp Run mode parameter block.

error_code Return error code

Returns:

ErrorCode - SERVICES_REQ_SUCCESS, SERVICES_REQ_CANNOT_EXECUTE_SERVICE

Restrictions:

Example:

```
int main (void)  
{  
    uint32_t error_code = SERVICES_REQ_SUCCESS;  
    run_profile_t runp;  
  
    error_code = SERVICES_get_run_cfg(services_handle, &runp,  
                                     &service_error_code);  
  
    if (error_code != SERVICES_REQ_SUCCESS)  
    {  
        return error_code;  
    }  
}
```

SERVICES_set_run_cfg

Syntax:

```
uint32_t SERVICES_set_run_cfg(uint32_t services_handle,  
                               run_profile_t *pp,  
                               uint32_t *error_code);
```

Description:

Set the RUN mode parameters.

Parameters:

services_handle

pp Run mode parameters.

error_code Return error code

Returns:

ErrorCode - SERVICES_REQ_SUCCESS, SERVICES_REQ_CANNOT_EXECUTE_SERVICE

Restrictions:

Example:

```
int main (void)  
{  
    uint32_t error_code = SERVICES_REQ_SUCCESS;  
    run_profile_t runp;  
  
    error_code = SERVICES_set_run_cfg(services_handle, &runp,  
                                     &service_error_code);  
  
    if (error_code != SERVICES_REQ_SUCCESS)  
    {  
        return error_code;  
    }  
}
```


SERVICES_get_off_cfg

Syntax:

```
uint32_t SERVICES_get_off_cfg(uint32_t services_handle,  
                              off_profile_t *wp,  
                              uint32_t *error_code);
```

Description:

Retrieved the current OFF mode parameters.

Parameters:

services_handle

wp Off mode parameter block

error_code Return error code

Returns:

ErrorCode - SERVICES_REQ_SUCCESS, SERVICES_REQ_CANNOT_EXECUTE_SERVICE

Restrictions:

Example:

```
int main (void)  
{  
    __uint32_t error_code = SERVICES_REQ_SUCCESS;  
                                ewic_config);  
    off_profile_t off_mode;  
  
    error_code = SERVICES_set_off_cfg(services_handle,  
                                     &off_mode,  
                                     &service_error_code);  
  
    if (error_code != SERVICES_REQ_SUCCESS)  
    {  
        return error_code;  
    }  
}
```

SERVICES_set_off_cfg

Syntax:

```
uint32_t SERVICES_set_off_cfg(uint32_t services_handle,  
                               off_profile_t *wp,  
                               uint32_t *error_code);
```

Description:

Set the OFF-mode parameters.

Parameters:

services_handle

wp off mode parameter block

error_code Return error

Returns:

ErrorCode - SERVICES_REQ_SUCCESS, SERVICES_REQ_CANNOT_EXECUTE_SERVICE

Restrictions:

Example:

```
int main (void)  
{  
    uint32_t error_code = SERVICES_REQ_SUCCESS;  
    off_profile_t off_mode;  
  
    error_code = SERVICES_get_off_cfg(services_handle,  
                                     &runp,  
                                     &service_error_code);  
  
    if (error_code != SERVICES_REQ_SUCCESS)  
    {  
        return error_code;  
    }  
}
```



Reset Services

Set or Get system reset.

<ACTION: Define policy>

SERVICES_boot_cpu

Syntax:

```
uint32_t SERVICES_boot_cpu(uint32_t services_handle, uint32_t cpu_id, uint32_t address, uint32_t *  
error_code)
```

Description:

Request to boot a CPU core. This service does not perform image loading, verification, etc., it just boots the core, specifying the boot address.

It is recommended to use this service only for booting the A32 cores but not for the M55 cores.

For the M55 cores, there are cases in which this service does not work. The currently known case is the M55-HP core in FUSION REV_Bx devices, where resetting the core also invalidates its TCM content. For that reason, it is recommended that the M55 cores are booted using one of the following methods –

- SERVICES_boot_process_toc_entry().
- SERVICES_set_vtor(), SERVICES_reset_cpu(), and SERVICES_release_cpu(), described in the next sections.

Parameters:

services_handle	
cpu_id	ID of the CPU to boot
address	Boot address for the CPU
error_code	Service Error Code

Returns:

SERVICES_REQ_SUCCESS
SERVICES_REQ_NOT_ACKNOWLEDGE
SERVICES_REQ_ACKNOWLEDGE
SERVICES_REQ_TIMEOUT
SERVICES_RESP_UNKNOWN_COMMAND
SERVICES_REQ_BAD_PACKET_SIZE
SERVICES_REQ_CANNOT_EXECUTE_SERVICE
SERVICES_REQ_BAD_PAYLOAD
SERVICES_REQ_BAD_PAYLOAD_LENGTH
SERVICES_REQ_PAYLOAD_OK
SERVICES_REQ_PIN_LOCKED

Restrictions:

None

SERVICES_boot_set_vtor

Syntax:

```
uint32_t SERVICES_boot_set_vtor(uint32_t services_handle, uint32_t cpu_id, uint32_t address, uint32_t * error_code)
```

Description:

Request to initialize the VTOR value for a M55 CPU core.

Note that the address value is stored in a Global register, not in the CPU's internal VTOR register. To transfer the address to the internal VTOR, call SERVICES_reset_cpu() after this call.

Parameters:

services_handle	
cpu_id	ID of the CPU to boot
address	The address to be stored in the VTOR
error_code	Service Error Code

Returns:

Restrictions:

FUSION_EXTERNAL_SYS0 is not a valid operation on FUSION Ensemble or Crescendo devices.

SERVICES_boot_reset_cpu

Syntax:

```
uint32_t SERVICES_boot_reset_cpu(uint32_t services_handle, uint32_t cpu_id, uint32_t * error_code)
```

Description:

Request to reset a CPU core, which effectively stops the core. For M55 cores, it also transfers the VTOR value from the Global VTOR register to the CPU's internal VTOR.

Parameters:

services_handle	
cpu_id	ID of the CPU to boot
error_code	Service Error Code

Returns:

Restrictions:

None

SERVICES_boot_release_cpu

Syntax:

```
uint32_t SERVICES_boot_release_cpu(uint32_t services_handle, uint32_t cpu_id, uint32_t * error_code)
```

Description:

Request to release a CPU core. This service does not perform image loading, verification, etc., and does not reset the CPU or specify the boot address, it just releases the core.

If the CPU is not running, this function can be called to release it.

If the CPU is running, SERVICES_boot_reset_cpu() must be called before this function to stop the core.

Notes on releasing M55 cores –

- in some cases, resetting the core also invalidates its TCM. A known case is the M55-HP core in FUSION REV_Bx devices. Because of that, after calling SERVICES_boot_reset_cpu() to stop the core, the image in the TCM must be reloaded, before calling SERVICES_boot_release_cpu() to start the core.
- If the VTOR value of the core needs to be changed, that too requires calling SERVICES_boot_reset_cpu(), to transfer the new address value to the core's internal VTOR. So, the call order of services in this case is – 1. SERVICES_boot_set_vtor(), 2. SERVICES_boot_reset_cpu(), 3. load the image in the TCM, 3. SERVICES_boot_release_cpu().

Parameters:

services_handle	
cpu_id	ID of the CPU to boot
error_code	Service Error Code

Returns:**Restrictions:**

FUSION_EXTERNAL_SYS0 is not a valid operation on FUSION Ensemble or Crescendo devices.



SERVICES_boot_reset_soc

Syntax:

```
uint32_t SERVICES_boot_reset_soc(uint32_t services_handle)
```

Description:

Request to reset the entire SoC.

Parameters:

services_handle

Returns:

Restrictions:

None



Image loading

Image loading, release, run.

<Action: Add more details>



Deferred boot

Request to boot another CPU.

<Action: Add more details>

Crypto Services

The SE provides several crypto services to other cores as detailed below.

SERVICES_cryptocell_get_rnd

Syntax:

```
uint32_t SERVICES_cryptocell_get_rnd(uint32_t services_handle, uint16_t rnd_length, void * rnd_value,
uint32_t * error_code)
```

Description:

Request random number

The service SERVICES_cryptocell_get_rnd returns a random vector generated by the cryptocell-rt library using the MbedTLS API call mbedtls_ctr_drbg_random().

The desired length of the vector to generate is passed as an input parameter. Currently, the maximum supported vector length is 128 bytes.

Parameters:

services_handle

rnd_length Length of random number vector

rnd_value returned Random number

error_code Service Error Code

None

Returns:

Restrictions:

None

Example:

```
int main (void)
{
    uint32_t ErrorCode = SERVICES_OK;
    uint64_t rnd_value;
    uint32_t service_error_code;

    ErrorCode = SERVICES_cryptocell_get_rnd(services_handle,
    sizeof(uint64_t), /* random number/vector length in bytes*/
    &rnd_value,
```

```
        &service_error_code);  
if (ErrorCode != SERVICES_REQ_SUCCESS)  
{  
    return ErrorCode;  
}  
}
```

SERVICES_cryptocell_get_lcs

Syntax:

```
uint32_t SERVICES_cryptocell_get_lcs(uint32_t services_handle, uint32_t *lcs_state, uint32_t *error_code)
```

Description:

The service SERVICES_cryptocell_get_lcs returns the current Life Cycle State.

Parameters:

services_handle

lcs_state Life cycle state

error_code Service Error Code

Returns:

Restrictions:

None

Example:

```
int main (void)
{
    uint32_t ErrorCode = SERVICES_OK;
    uint32_t lcs_state;
    uint32_t service_error_code

    ErrorCode = SERVICES_cryptocell_get_lcs(services_handle, &lcs_state,
    &service_error_code);
    if (ErrorCode != SERVICES_REQ_SUCCESS)
    {
        return ErrorCode;
    }
}
```



MbedTLS Services

These services expose the hardware accelerated functionality provided by the Arm CryptoCell-RT library in SES.

Arm has chosen to use MbedTLS as the public API to that functionality. For that reason, the exposed Services correspond to MbedTLS public APIs.

IMPORTANT: These Services are not intended to be used directly by applications. Instead, they should be used by a client-side MbedTLS library implementation in which hardware acceleration is done by calling the Services.

To simplify the Services APIs and to avoid introducing MbedTLS types into them, all parameters of the MbedTLS functions are passed as `uint32_t`. The client-side MbedTLS implementation must convert them to the appropriate types. Also, to reduce the number of Service APIs, some of them cover multiple MbedtTLS API functions.

Please refer to the MbedTLS documentation for more information on these APIs, usage and parameters.

SERVICES_cryptocell_mbedtls_hardware_poll

Syntax:

```
uint32_t SERVICES_cryptocell_mbedtls_hardware_poll(uint32_t services_handle,  
                                                    uint32_t * error_code,  
                                                    uint32_t data,  
                                                    uint32_t output,  
                                                    uint32_t len,  
                                                    uint32_t olen)
```

Description:

Service API replacement for mbedtls_hardware_poll()

SERVICES_cryptocell_mbedtls_aes_init

Syntax:

```
uint32_t SERVICES_cryptocell_mbedtls_aes_init(uint32_t services_handle,  
                                                uint32_t * error_code,  
                                                uint32_t ctx)
```

Description:

Service API replacement for mbedtls_aes_init()

SERVICES_cryptocell_mbedtls_aes_set_key

Syntax:

```
uint32_t SERVICES_cryptocell_mbedtls_aes_set_key(uint32_t services_handle,  
                                                  uint32_t * error_code,  
                                                  uint32_t ctx,  
                                                  uint32_t key,  
                                                  uint32_t keybits,  
                                                  uint32_t dir)
```

Description:

Service API replacement for mbedtls_aes_set_key_enc() and mbedtls_aes_set_key_dec()

SERVICES_cryptocell_mbedtls_aes_crypt

Syntax:

```
uint32_t SERVICES_cryptocell_mbedtls_aes_crypt(uint32_t services_handle,  
                                                uint32_t * error_code,  
                                                uint32_t ctx,  
                                                uint32_t crypt_type,  
                                                uint32_t mode,  
                                                uint32_t length,  
                                                uint32_t iv,  
                                                uint32_t input,  
                                                uint32_t output)
```

Description:

Service API replacement for the mbedtls_aes_crypt_XXX functions

SERVICES_cryptocell_mbedtls_sha_starts

Syntax:

```
uint32_t SERVICES_cryptocell_mbedtls_sha_starts(uint32_t services_handle,  
                                                  uint32_t * error_code,  
                                                  uint32_t ctx,  
                                                  uint32_t sha_type)
```

Description:

Service API replacement for mbedtls_sha_starts()

SERVICES_cryptocell_mbedtls_sha_process

Syntax:

```
uint32_t SERVICES_cryptocell_mbedtls_sha_process(uint32_t services_handle,  
                                                uint32_t * error_code,  
                                                uint32_t ctx,  
                                                uint32_t sha_type,  
                                                uint32_t data)
```

Description:

Service API replacement for mbedtls_sha_process()

SERVICES_cryptocell_mbedtls_sha_update

Syntax:

```
uint32_t SERVICES_cryptocell_mbedtls_sha_update(uint32_t services_handle,  
                                                uint32_t * error_code,  
                                                uint32_t ctx,  
                                                uint32_t sha_type,  
                                                uint32_t data,  
                                                uint32_t data_length)
```

Description:

Service API replacement for mbedtls_sha_update()

SERVICES_cryptocell_mbedtls_sha_finish

Syntax:

```
uint32_t SERVICES_cryptocell_mbedtls_sha_finish(uint32_t services_handle,  
                                                uint32_t * error_code,  
                                                uint32_t ctx,  
                                                uint32_t sha_type,  
                                                uint32_t data)
```

Description:

Service API replacement for mbedtls_sha_finish()

SERVICES_cryptocell_mbedtls_ccm_gcm_set_key

Syntax:

```
uint32_t SERVICES_cryptocell_mbedtls_ccm_gcm_set_key(uint32_t services_handle,  
    uint32_t * error_code,  
    uint32_t context_addr,  
    uint32_t key_type,  
    uint32_t cipher,  
    uint32_t key_addr,  
    uint32_t key_bits)
```

Description:

Service API replacement for mbedtls_ccm_set_key() and mbedtls_gcm_set_key()

SERVICES_cryptocell_mbedtls_ccm_gcm_crypt

Syntax:

```
uint32_t SERVICES_cryptocell_mbedtls_ccm_gcm_crypt(uint32_t services_handle,  
    uint32_t * error_code,  
    uint32_t context_addr,  
    uint32_t crypt_type,  
    uint32_t length,  
    uint32_t iv_addr,  
    uint32_t iv_length,  
    uint32_t add_addr,  
    uint32_t add_length,  
    uint32_t input_addr,  
    uint32_t output_addr,  
    uint32_t tag_addr,  
    uint32_t tag_length)
```

Description:

Service API replacement for the mbedtls CCM and GCM crypto functions

SERVICES_cryptocell_mbedtls_chacha20_crypt

Syntax:

```
uint32_t SERVICES_cryptocell_mbedtls_chacha20_crypt(uint32_t services_handle,  
    uint32_t * error_code,  
    uint32_t key_addr,  
    uint32_t nonce_addr,  
    uint32_t counter,  
    uint32_t data_len,  
    uint32_t input_addr,  
    uint32_t output_addr)
```

Description:

Service API replacement for mbedtls_chacha20_crypt()

SERVICES_cryptocell_mbedtls_chachapoly_crypt

Syntax:

```
uint32_t SERVICES_cryptocell_mbedtls_chachapoly_crypt(uint32_t services_handle,  
    uint32_t * error_code,  
    uint32_t context_addr,  
    uint32_t crypt_type,  
    uint32_t length,  
    uint32_t nonce_addr,  
    uint32_t aad_addr,  
    uint32_t aad_len,  
    uint32_t tag_addr,  
    uint32_t input_addr,  
    uint32_t output_addr)
```

Description:

Service API replacement for the mbedtls chachapoly crypto functions

SERVICES_cryptocell_mbedtls_poly1305_crypt

Syntax:

```
uint32_t SERVICES_cryptocell_mbedtls_poly1305_crypt(uint32_t services_handle,  
    uint32_t * error_code,  
    uint32_t key_addr,  
    uint32_t input_addr,  
    uint32_t ilen,  
    uint32_t mac_addr)
```

Description:

Service API replacement for mbedtlsl_poly1305_mac()

SERVICES_cryptocell_mbedtls_cmac_init_setkey

Syntax:

```
uint32_t SERVICES_cryptocell_mbedtls_cmac_init_setkey(uint32_t services_handle,  
    uint32_t * error_code,  
    uint32_t context_addr,  
    uint32_t key_addr,  
    uint32_t key_bits)
```

Description:

Service API replacement for mbedtls_cmac_init_setkey()

SERVICES_cryptocell_mbedtls_cmac_update

Syntax:

```
uint32_t SERVICES_cryptocell_mbedtls_cmac_update(uint32_t services_handle,  
    uint32_t * error_code,  
    uint32_t context_addr,  
    uint32_t input_addr,  
    uint32_t input_length)
```

Description:

Service API replacement for mbedtls_cmac_update()

SERVICES_cryptocell_mbedtls_cmac_finish

Syntax:

```
uint32_t SERVICES_cryptocell_mbedtls_cmac_finish(uint32_t services_handle,  
    uint32_t * error_code,  
    uint32_t context_addr,  
    uint32_t output_addr)
```

Description:

Service API replacement for mbedtls_cmac_finish()

SERVICES_cryptocell_mbedtls_cmac_reset

Syntax:

```
uint32_t SERVICES_cryptocell_mbedtls_cmac_reset(uint32_t services_handle,  
    uint32_t * error_code,  
    uint32_t context_addr)
```

Description:

Service API replacement for mbedtls_cmac_finish()

Clocks Services

Services to control the Clock, PLL and XTAL (High-frequency external oscillator) settings.

SERVICES_clocks_select_osc_source

Syntax:

```
uint32_t SERVICES_clocks_select_osc_source (uint32_t services_handle, oscillator_source_t source,  
oscillator_target_t target, uint32_t * error_code)
```

Description:

Selects between RC or XTAL clock source for various modules (HF or LF). The selected clock is referred to as the 'OSC' clock.

Parameters:

services_handle	
source	RC or XTAL (either HF or LF, depending on the target)
target	SYS clocks, PERIPH clocks, S32K clock
error code	Service error code

Returns:

Transport layer error code

SERVICES_clocks_select_pll_source

Syntax:

```
uint32_t SERVICES_clocks_select_pll_source(uint32_t services_handle, pll_source_t source, pll_target_t target, uint32_t * error_code)
```

Description:

Select OSC or PLL as the source clock for various modules.

Parameters:

services_handle

source OSC or PLL

target SYSREFCLK, SYSCLK, ES0, ES1

error code Service error code

Returns:

Transport layer error code

SERVICES_clocks_enable_clock

Syntax:

```
uint32_t SERVICES_clocks_enable_clock(uint32_t services_handle, clock_enable_t clock, bool enable,  
uint32_t * error_code)
```

Description:

Enable or disable a clock.

Parameters:

services_handle	
clock	Clock to enable or disable
enable	Enable/disable flag
error code	Service error code

Returns:

Transport layer error code



SERVICES_clocks_set_ESO_frequency

Syntax:

```
uint32_t SERVICES_clocks_set_ESO_frequency(uint32_t services_handle, clock_frequency_t frequency,  
uint32_t * error_code)
```

Description:

Set the frequency of External System 0 (M55-HP).

Parameters:

services_handle

frequency Frequency to set

error code Service error code

Returns:

Transport layer error code

SERVICES_clocks_set_ES1_frequency

Syntax:

```
uint32_t SERVICES_clocks_set_ES1_frequency(uint32_t services_handle, clock_frequency_t frequency,  
uint32_t * error_code)
```

Description:

Set the frequency of External System 1 (M55-HE).

Parameters:

services_handle

frequency Frequency to set

error code Service error code

Returns:

Transport layer error code



SERVICES_clocks_select_a32_source

Syntax:

```
uint32_t SERVICES_clocks_select_a32_source (uint32_t services_handle, a32_source_t source, uint32_t  
* error_code)
```

Description:

Selects the clock source for the A32 CPU cores.

Parameters:

services_handle

source Clock source – CPUPLL, SYSPLL, REFCLK, Clock gate

error code Service error code

Returns:

Transport layer error code

SERVICES_clocks_select_aclk_source

Syntax:

```
uint32_t SERVICES_clocks_select_aclk_source (uint32_t services_handle, aclk_source_t source, uint32_t  
* error_code)
```

Description:

Selects the clock source for the AXI bus.

Parameters:

services_handle

source Clock source – SYSPLL, REFCLK, Clock gate

error code Service error code

Returns:

Transport layer error code

SERVICES_clocks_set_divider

Syntax:

```
uint32_t SERVICES_clocks_set_divider (uint32_t services_handle, clock_divider_t divider, uint32_t value,  
uint32_t * error_code)
```

Description:

Selects the value of a clock divider.

Parameters:

services_handle

divider Which divider to set – CPUPLL, SYSPLL, ACLK (Corstone), HCLK, PCLK (Alif)

value Divider value. 0x0 to 0x1F for Corstone dividers, 0x0 to 0x2 for Alif divider

error code Service error code

Returns:

Transport layer error code



SERVICES_pll_xtal_start

Syntax:

```
uint32_t SERVICES_pll_xtal_start(uint32_t services_handle, bool faststart, bool boost, uint32_t delay_count, uint32_t * error_code)
```

Description:

Start the external HF crystal.

Parameters:

services_handle	
faststart	Enable 'fast start' mode
boost	Enable 'boost' mode
delay_count	Timeout to wait for crystal startup
error code	Service error code

Returns:

Transport layer error code



SERVICES_pll_xtal_stop

Syntax:

```
uint32_t SERVICES_pll_xtal_stop(uint32_t services_handle, uint32_t * error_code)
```

Description:

Stop the external HF crystal.

Parameters:

services_handle

error code Service error code

Returns:

Transport layer error code



SERVICES_pll_xtal_is_started

Syntax:

```
uint32_t SERVICES_pll_xtal_is_started(uint32_t services_handle, bool * is_started, uint32_t *  
error_code)
```

Description:

Check if the external HF Crystal is started.

Parameters:

services_handle

is_started External HF Crystal started status

error_code Service error code

Returns:

Transport layer error code



SERVICES_pll_clkpll_start

Syntax:

```
uint32_t SERVICES_pll_clkpll_start(uint32_t services_handle, bool faststart, uint32_t delay_count,  
uint32_t * error_code)
```

Description:

Start the PLL.

Parameters:

services_handle

faststart Enable 'fast start' mode

delay_count Timeout to wait for PLL lock

error code Service error code

Returns:

Transport layer error code



SERVICES_pll_clkpll_stop

Syntax:

```
uint32_t SERVICES_pll_clkpll_stop(uint32_t services_handle, uint32_t * error_code)
```

Description:

Stop the PLL.

Parameters:

services_handle

error code Service error code

Returns:

Transport layer error code

SERVICES_pll_clkpll_is_locked

Syntax:

```
uint32_t SERVICES_pll_clkpll_is_locked(uint32_t services_handle, bool * is_locked, uint32_t * error_code)
```

Description:

Check if the PLL is started and locked.

Parameters:

services_handle	
is_locked	PLL locked status
error code	Service error code

Returns:

Transport layer error code

SERVICES_pll_initialize

Syntax:

```
uint32_t SERVICES_pll_initialize(uint32_t services_handle, uint32_t * error_code)
```

Description:

Initialize the device to enable XTAL and PLL and switch all clocks to PLL.

Parameters:

services_handle	
error code	Service error code

Returns:

Transport layer error code

SERVICES_pll_deinit

Syntax:

```
uint32_t SERVICES_pll_deinit(uint32_t services_handle, uint32_t * error_code)
```

Description:

De-initialize the device – switch all clocks to TC and disable XTAL and PLL.

Parameters:



services_handle
error code Service error code

Returns:

Transport layer error code

Lifecycle control

<Action: TBD>



Update Services

<Action: Add more details>

Document History

Version	Date	Author	Change Log
0.1	Jan 2022	R. ONYETT	Initial concept and realization
0.2	Feb 2022	R. ONYETT	Screenshot updates
0.3	Feb 2022	R. ONYETT	Updated API docs, ARM-DS use
V43-03	Feb 2022	R. ONYETT	Added release version suffix
V44-03	Mar 2022	R. ONYETT	Added SERVICES_uart_write
V45.03	Mar 2022	R. ONYETT	Describe example builds and json files
V46 005	Apr 2022	R. ONYETT	API updates. Changed version
V0.0.6	Apr 2022	R. ONYETT	Added debug toggle API
V0.0.9	May 2022	R. ONYETT	UART write extra parameter
V0.0.10	May 2022	G. Stoykov	Add MbedTLS symmetric crypto services
V0.0.13	July 2022	S. KENKARE	Example restructure. A32 changes.
V0.0.20	Nov 2022	R. ONYETT	Formatting