

Pointers :- \rightarrow

- ① Void Pointer \rightarrow Type linked to any particular data type.
- ② data Type Pointer \rightarrow Points to a particular type of data.
- ③ Null Pointer \rightarrow Points to null.
- ④ Dangling Pointer \rightarrow Pointing to an address which has been deleted or in a different scope.

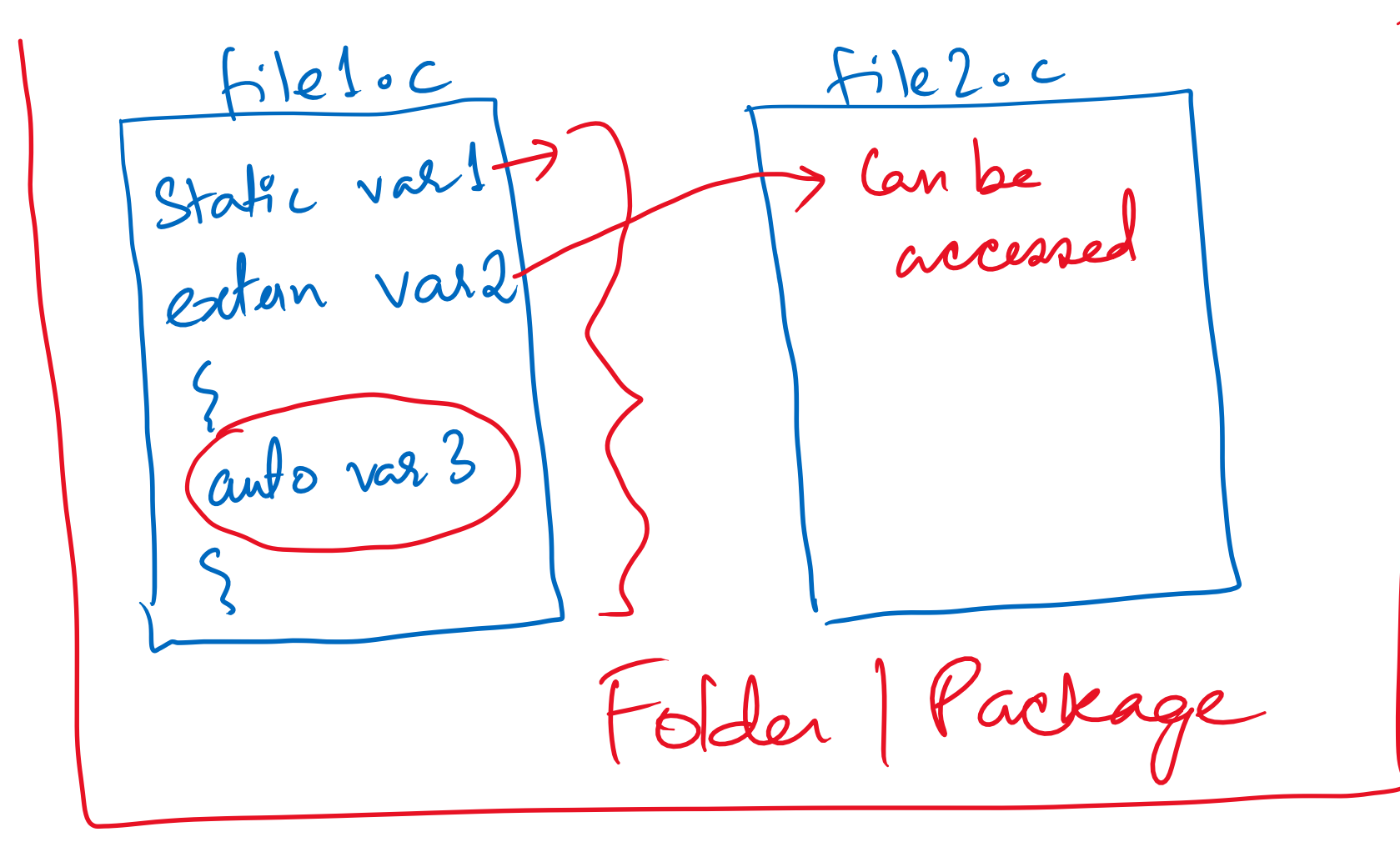
```
function()
    x = 10
    return x;

main()
    int *ptr = function();
    print("%d", *ptr); // 10
```

Diagram showing memory addresses:
 In function, x is at address 2000.
 In main, ptr is at address 2000 and points to the memory location where x was (2000).

Storage Classes	Scope	Lifetime
① Static	Global	File
② extern	Global	Folder/Package
③ register	RAM	RAM Memory
④ auto	Local	{ Block Scope }

\downarrow No Pointers Allowed.



Collection of Homogeneous Data : Array

- * Collection of Integers
- * Collection of Decimal Values
- * Collection of Names
- * Collection of Characters

* Zero Based Indexing: arr

9	6	5	2	1	0
0	1	2	3	4	5

Elements are at the top, and Indexes are at the bottom.

Note: The name of the array always points to the address of the first element of the array. Therefore the array name is also called "array pointer".

print(arr) \downarrow 2000

arr = [2 | 6 | 8 | 5]
 \downarrow [2000] address

TCS / Accenture Placement Drive Question:

Given an array of only zeros, ones & twos sort the array in ascending / descending order without using any sorting algorithm.

1/p \rightarrow [2 | 1 | 2 | 0 | 1]
 0/p \rightarrow [0 | 1 | 1 | 2 | 2]

[2 | 1 | 2 | 1 | 0] \rightarrow 1/p index = 0
 c0 \rightarrow 1
 c1 \rightarrow 2-1-0
 c2 \rightarrow 2

Diagram showing the array after the first step: [0 | 1 | 1 | |]

(While(c0 > 0))
 While(c1 > 0)

Searching & Sorting Algorithms:

- | | | |
|---------------------------------|------|------------------|
| ① Linear Search | 6LPA | ① Bubble Sort |
| ② Binary Search | | ② Insertion Sort |
| ③ Binary Search using Recursion | | ③ Selection Sort |
| ④ Jump Search | | ④ Merge Sort |
| ⑤ Interpolation Search | | ⑤ Quick Sort |
| | | ⑥ Shell Sort |
| | | ⑦ Heap Sort |
| | | ⑧ Count Sort |
| | | ⑨ Radix Sort |

Time Complexity

Binary Search: Key = 12

① Sorted Array key = 6
 ② Mid Value

Diagram showing an array [3 | 6 | 9 | 10 | 12 | 15] with indices 0 to 5. mid is calculated as 2.

① if arr[mid] == key return mid;
 ② if arr[mid] < key S = mid + 1;
 ③ if arr[mid] > key \rightarrow e = m - 1

Formula for mid: $mid = \frac{s+e}{2}$

Diagram showing the recursive splitting of an array of size N into two halves of size N/2, and then into quarters of size N/4.

Formula for K: $K = \log_2 N$
 Formula for K: $K = \log N$

Optimal Formula
 $mid = s + \frac{e-s}{2}$
 $= \frac{2s + e - s}{2} = \frac{s+e}{2}$

* Binary Search Important Questions:

- * Search in a 2D Matrix.
- * House Robbery I, II, III.
- * Book Allocation
- * Aggressive Cows
- * Square Root of a number using BS.