GATE EE23 27

EE23BTECH11043 - BHUVANESH SUNIL NEHETE*

2)

Question: Which of the following statement(s) is/are true?

a) If an LTI system is causal, it is stable.

b) A discrete time LTI system is causal if and only if its response to a step input u[n] is 0 for n < 0.

c) If a discrete time LTI system has an impulse response h[n] of finite duration the system is stable.

d) If the impulse response 0 < |h[n]| < 1 for all n, then the LTI system is stable.

Solution:

1)

Assume
$$h(t) = e^{2t} \cdot u(t)$$
 (1)

$$\mathcal{L}\lbrace e^{2t}\rbrace = \frac{1}{s-2} \quad Re(s) > 2 \quad (2)$$

This system is causal but not stable because ROC does not contian imaginary axis.

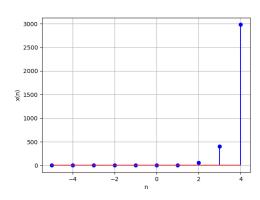


Fig. 1. graph of $h(t) = e^{2t} \cdot u(t)$

Therefore, this statement does not hold true.

Assume $h[n] = \begin{cases} \frac{1}{3} & 0 \le n \le 2\\ 0 & \text{otherwise} \end{cases}$ (3)

$$y[n] = h[n] * u[n]$$
 (4)

$$y[n] = \sum_{k=-\infty}^{+\infty} h[k] \cdot u[n-k] \quad (5)$$

$$=\sum_{k=0}^{n} \left(\frac{1}{3}\right) \tag{6}$$

Therefore, in this example, the system's response to a step input is indeed 0 for n < 0, fulfilling condition for causality.

Therefore, this statement is true.

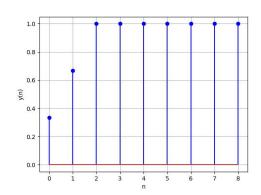


Fig. 2. graph of y[n]

3)

Assume
$$h[n] = \begin{cases} 1 & n = 0 \\ -2 & n = 1 \\ 0 & \text{otherwise} \end{cases}$$
 (7)

$$y[n] = h[n] * u[n]$$
 (8)

$$y[n] = \begin{cases} 1 & n = 0 \\ -1 & n \ge 1 \end{cases}$$
 (9)

The input response is finite but the output response in not BIBO stable.

Therefore, this statement does not hold true.

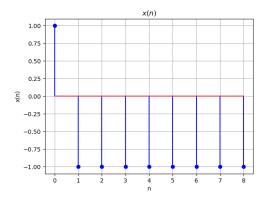


Fig. 3. graph of y[n]

4)

Assume
$$h[n] = \frac{1}{2}u[n]$$
 (10)

$$g[n] = \sum_{n=0}^{\infty} |h[n]|$$
 (11)

$$=\sum_{n=0}^{\infty} \frac{1}{2}$$
 (12)

$$= \sum_{n=0}^{\infty} \frac{1}{2}$$

$$\Longrightarrow \sum_{n=0}^{\infty} |h[n]| \to \infty$$
(12)

Hence it is unstable.

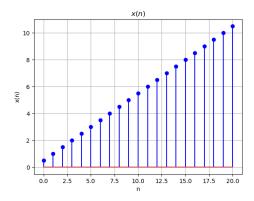


Fig. 4. graph of g[n]

Therefore, this statement does not hold true. So, the answer is option (B).