

GATE EE23 27

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Question: Which of the following statement(s) is/are true? 2)

- If an LTI system is causal, it is stable.
- A discrete time LTI system is causal if and only if its response to a step input $u[n]$ is 0 for $n < 0$.
- If a discrete time LTI system has an impulse response $h[n]$ of finite duration the system is stable.
- If the impulse response $0 < |h[n]| < 1$ for all n , then the LTI system is stable.

Solution:

1)

$$\text{Assume } h(t) = e^{2t} \cdot u(t) \quad (1)$$

$$\mathcal{L}\{e^{2t}\} = \frac{1}{s-2} \quad \text{Re}(s) > 2 \quad (2)$$

This system is causal but not stable because ROC does not contain imaginary axis.

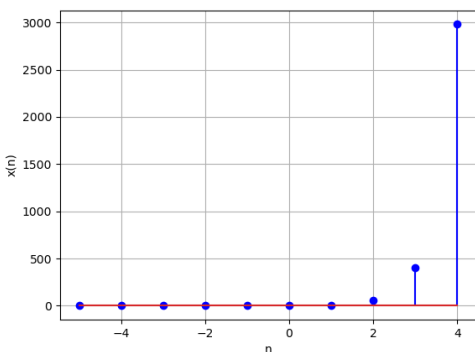


Fig. 1. graph of $h(t) = e^{2t} \cdot u(t)$

Therefore, this statement does not hold true.

$$\text{Assume } h[n] = \begin{cases} \frac{1}{3} & 0 \leq n \leq 2 \\ 0 & \text{otherwise} \end{cases} \quad (3)$$

$$y[n] = h[n] * u[n] \quad (4)$$

$$y[n] = \sum_{k=-\infty}^{+\infty} h[k] \cdot u[n-k] \quad (5)$$

$$= \sum_{k=0}^n \left(\frac{1}{3}\right) \quad (6)$$

Therefore, in this example, the system's response to a step input is indeed 0 for $n < 0$, fulfilling condition for causality.

Therefore, this statement is true.

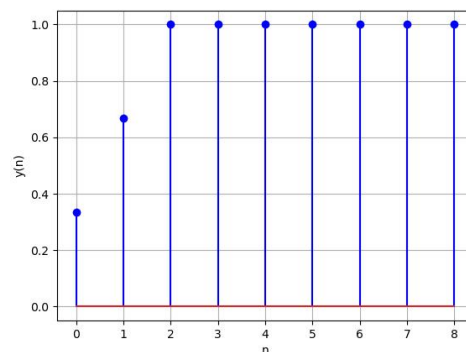


Fig. 2. graph of $y[n]$

3)

$$\text{Assume } h[n] = \begin{cases} n & \text{if } 0 \leq n \leq N \\ 0 & \text{otherwise} \end{cases} \quad (7)$$

$$y[n] = h[n] * u[n] \quad (8)$$

$$y[n] = \sum_{k=0}^n h[k] u[n-k] \quad (9)$$

$$= \sum_{k=0}^n k \quad (10)$$

The input response is finite but the output response is not BIBO stable.

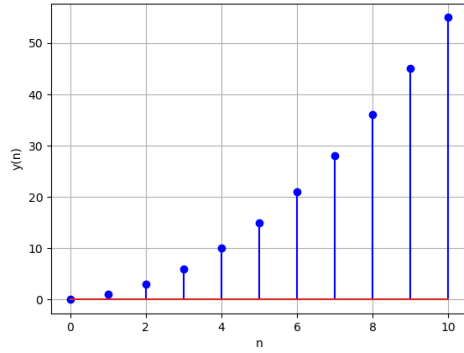


Fig. 3. graph of $y[n]$

Therefore, this statement does not hold true.

4)

$$\text{Assume } h[n] = \frac{1}{2}u[n] \quad (11)$$

$$g[n] = \sum_{n=0}^{\infty} |h[n]| \quad (12)$$

$$= \sum_{n=0}^{\infty} \frac{1}{2} \quad (13)$$

$$\Rightarrow \sum_{n=0}^{\infty} |h[n]| \rightarrow \infty \quad (14)$$

Hence it is unstable.

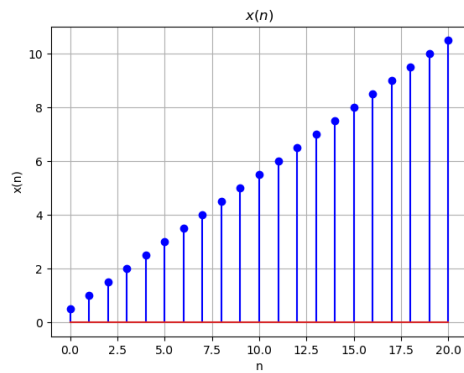


Fig. 4. graph of $g[n]$

Therefore, this statement does not hold true.

So, the answer is option (B).