

QM Course 2024
Charles University, Prague

Machine Learning with napari-plugins (+ extra flim plugin)

Marcelo Leomil Zoccoler

Re-using materials from:

Robert Haase, ScaDS.AI Leipzig

Deborah Schmidt, Jug Lab, MPI CBG

Johannes Soltwedel, PoL, TU Dresden

Uwe Schmidt, Myers Lab, MPI CBG

Cornelia Wetzker, TU Dresden and NFDI4BIOIMAGE

Martin Weigert, EPFL

Till Korten, Helmholtz AI

Ignacio Arganda-Carreras, Universidad del País Vasco

Ryan Savill, MPI CBG

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Laura Zigutyte, EKFZdigital

Wei Ouyang, KTH Royal Institute of Technology, Stockholm and

Mara Lampert, TU Dresden

The Scikit-Learn community

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- Let's practice some conda environment configuration!
 - more into how environments work:
 - <https://jni.github.io/using-python-for-science/intro-to-environments.html>
 - https://hackmd.io/@talley/SJB_lObBi#Python-environments-workshop
- We actually need to create 2 environments to run some of the exercises today. Please follow the instructions here:
 - https://zoccoler.github.io/QM Course Bio Image Analysis with napari 2024/Machine Learning with napari/00_intro.html

First environment: devbio-napari

Open a terminal and type (or copy the line below):

```
mamba create --name devbio-napari-env python=3.9 devbio-napari pyqt -c conda-forge -c pytorch
```

Hit **ENTER** to answer yes when asked to install packages. Activate your environment with:

```
mamba activate devbio-napari
```

Second environment: napari-flim-phasor-env

Open a terminal and type (or copy the line below):

```
mamba create -n napari-flim-phasor-env python=3.9 napari==0.4.17 napari-clusters-plotter git pyqt  
devbio-napari
```

Hit **ENTER** to answer yes when asked to install packages.

Activate your environment with:

```
mamba activate napari-flim-phasor-env
```

Then install `napari-flim-phasor-plotter` with pip:

```
pip install napari-flim-phasor-plotter
```

Image segmentation using thresholding

- Recap: Finding the right workflow towards a good segmentation takes time

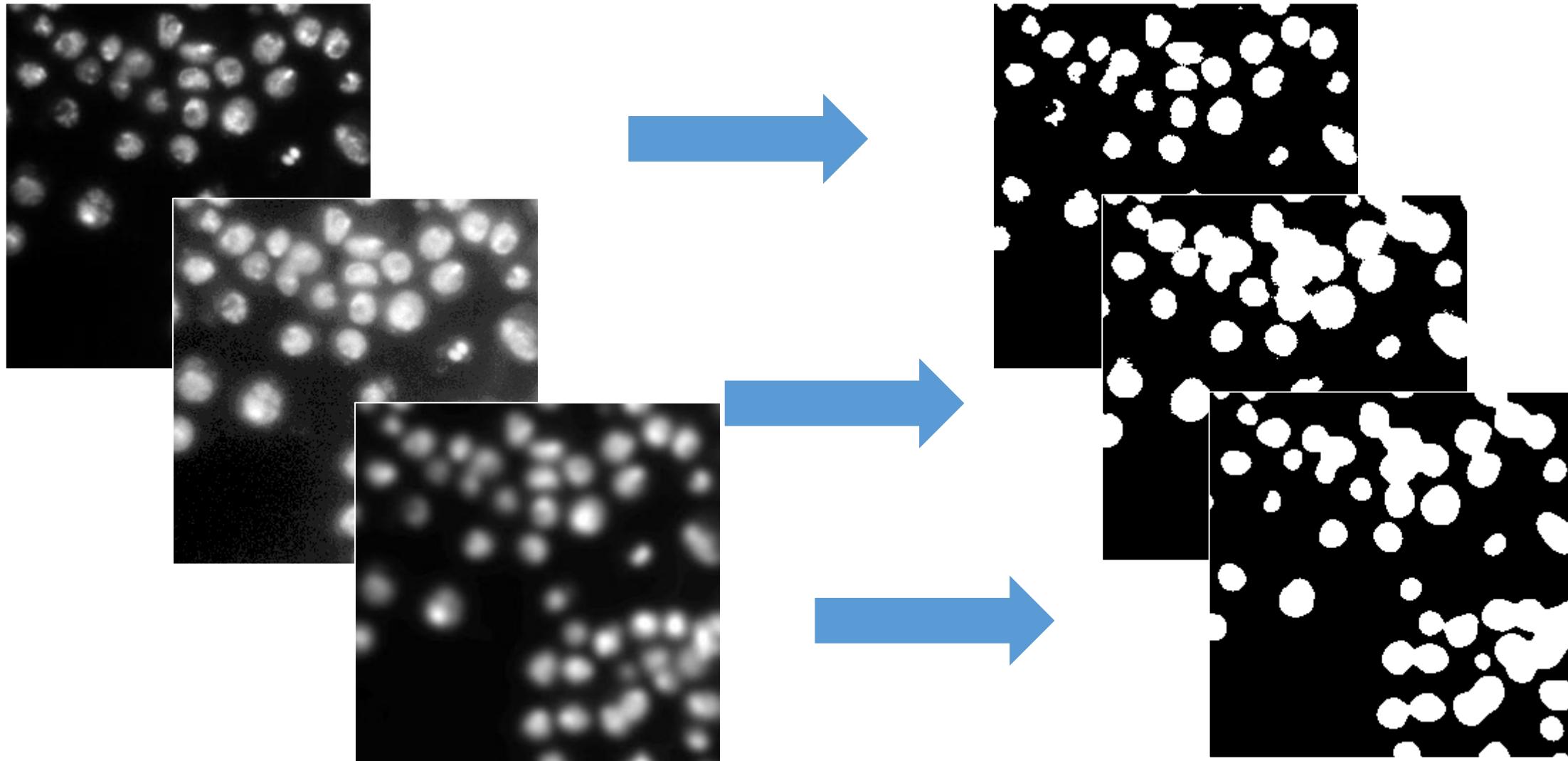


Image data source: [BBBC038v1](#), available from the Broad Bioimage Benchmark Collection (Caicedo et al., Nature Methods, 2019).

Image segmentation using thresholding

- Recap: Combining images, e.g. using Difference of Gaussian (DoG)

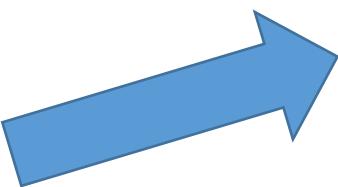
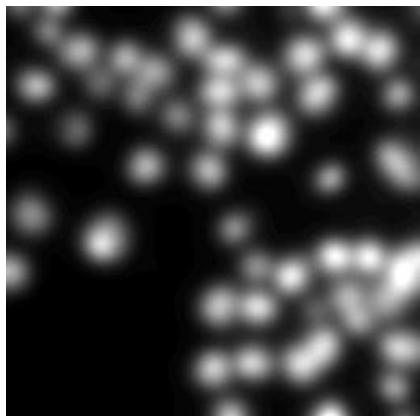
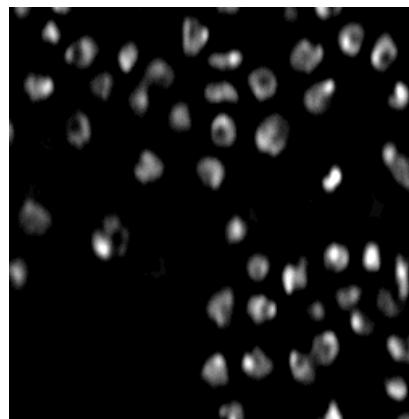
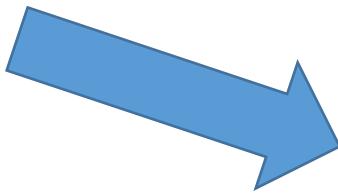
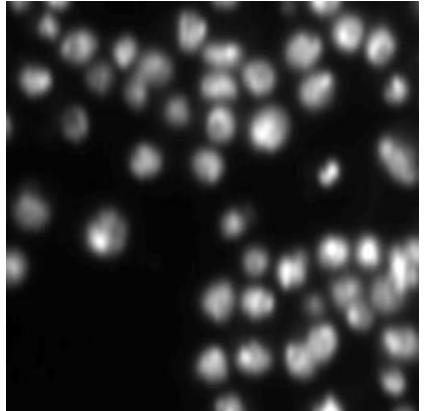
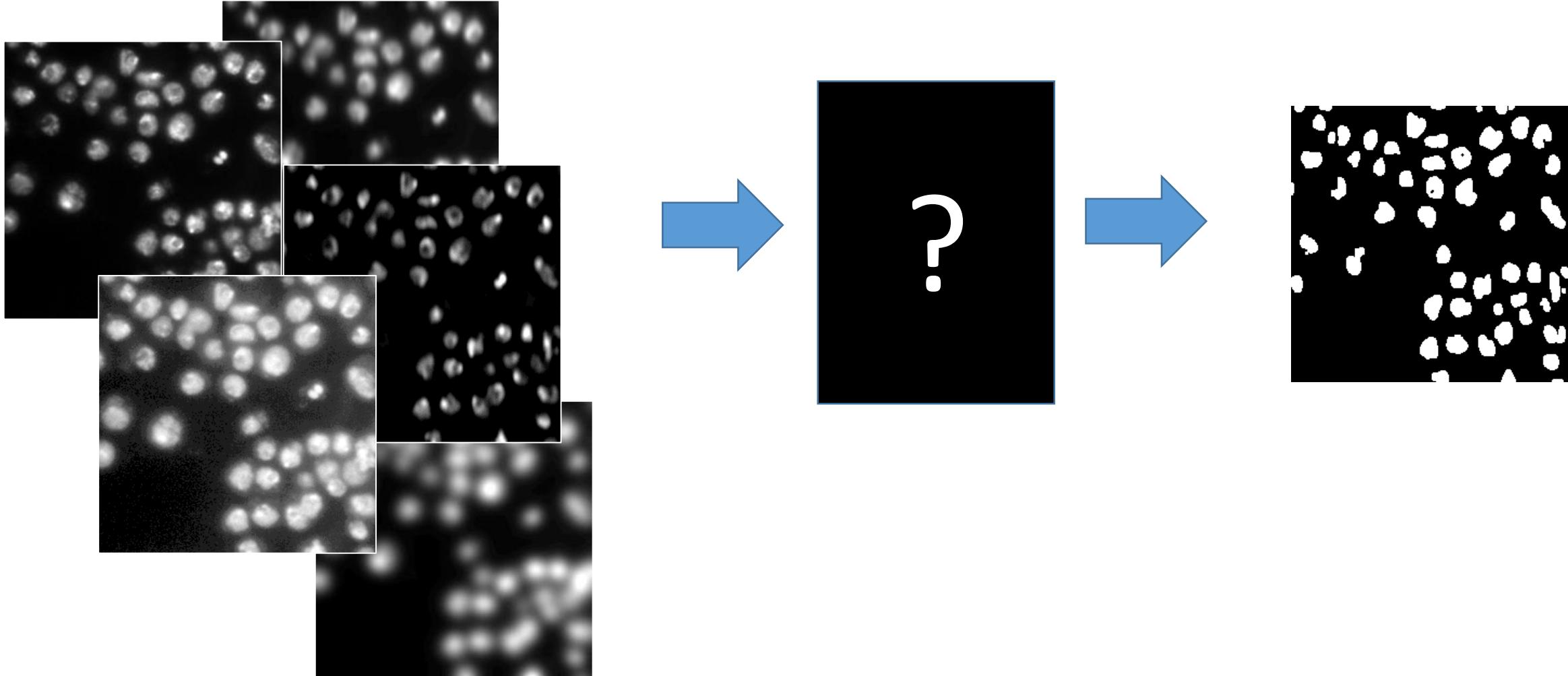


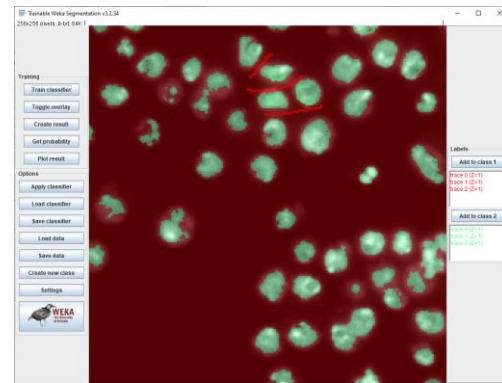
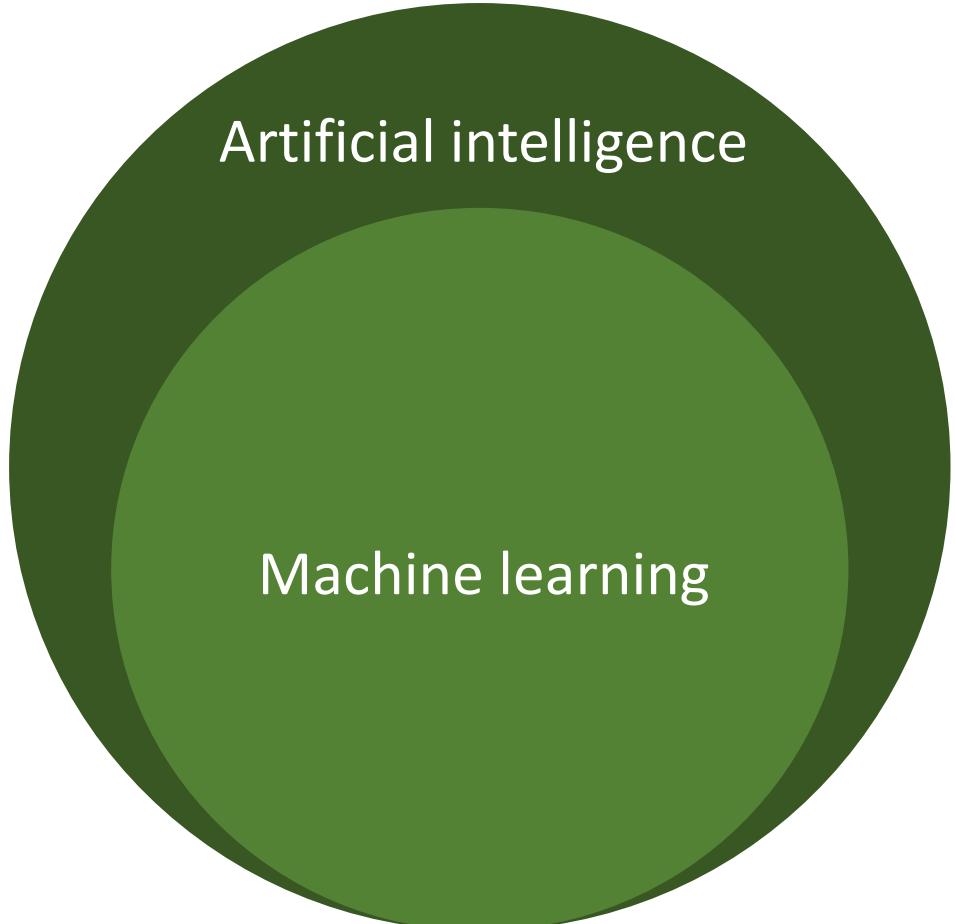
Image segmentation using thresholding

- Might there be a technology for optimization which combination of images can be used to get the best segmentation result?

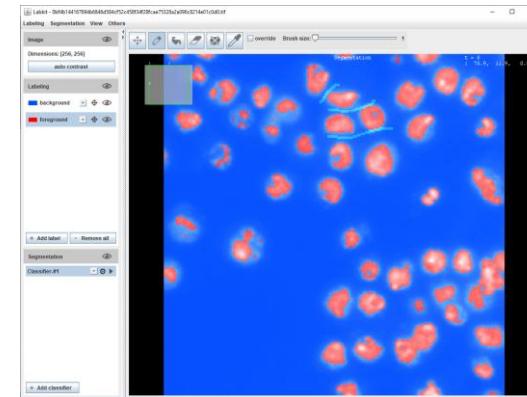


Machine learning

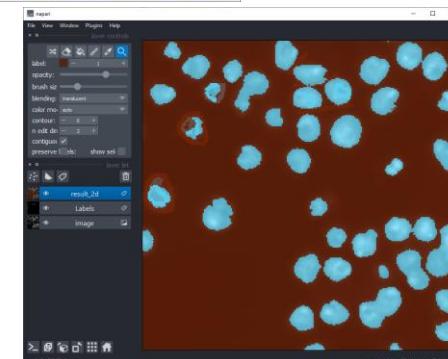
- A research field in computer science
- Finds more and more applications, also in life sciences.



Trainable Weka Segmentation
<https://imagej.net/plugins/tws/>



LabKit
<https://imagej.net/plugins/labkit/>

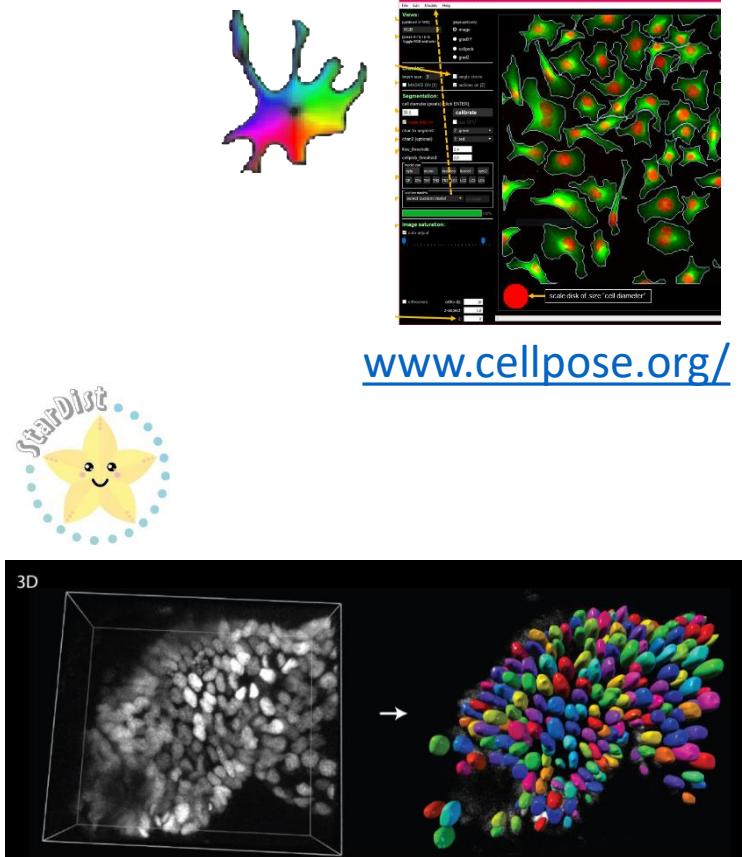
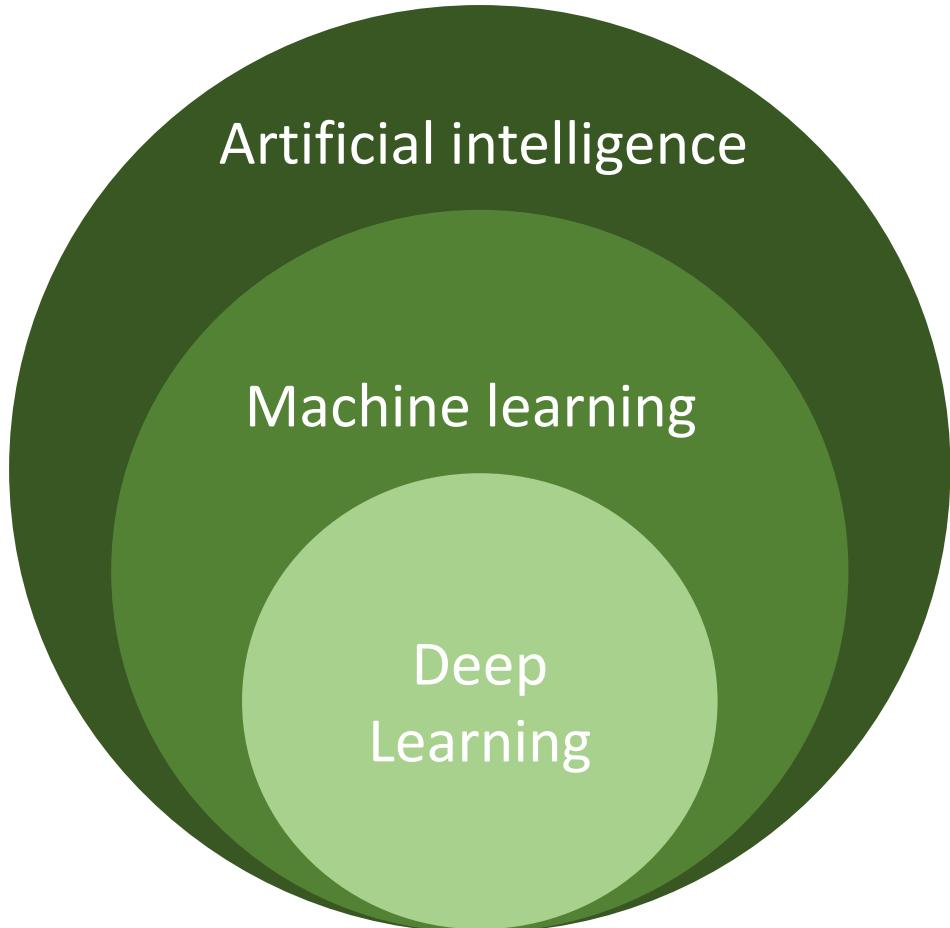


Python /
scikit-learn /
napari /
apoc

Image data source: [BBBC038v1](#), available from the Broad Bioimage Benchmark Collection [Caicedo et al., Nature Methods, 2019].

Machine learning

- A research field in computer science
- Finds more and more applications, also in life sciences.



<https://github.com/stardist/stardist>

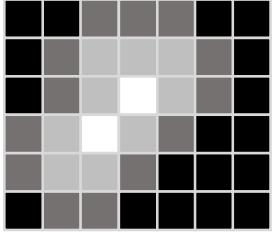
<https://bioimage.io/>

Logos and screenshots are taken from the github repositories / websites provided under BSD and MIT licenses.

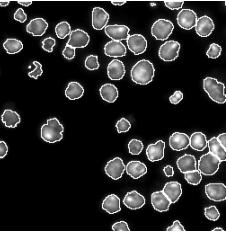
Machine learning

- Automatic construction of predictive models from given data

Pixels,



Objects,

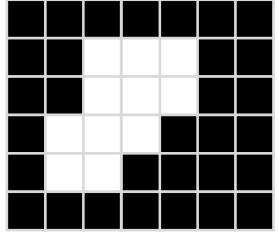


Images, Audio, Text, Measurements, ...



Annotated raw data, usually generated by humans

Dense Segmentation / Binarization



Object classification

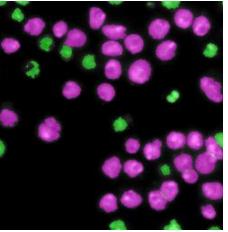
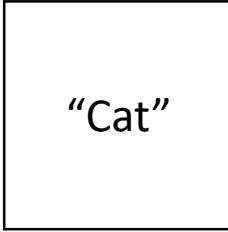
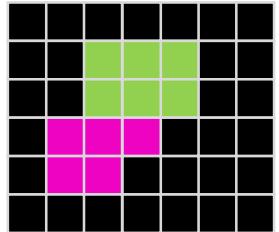


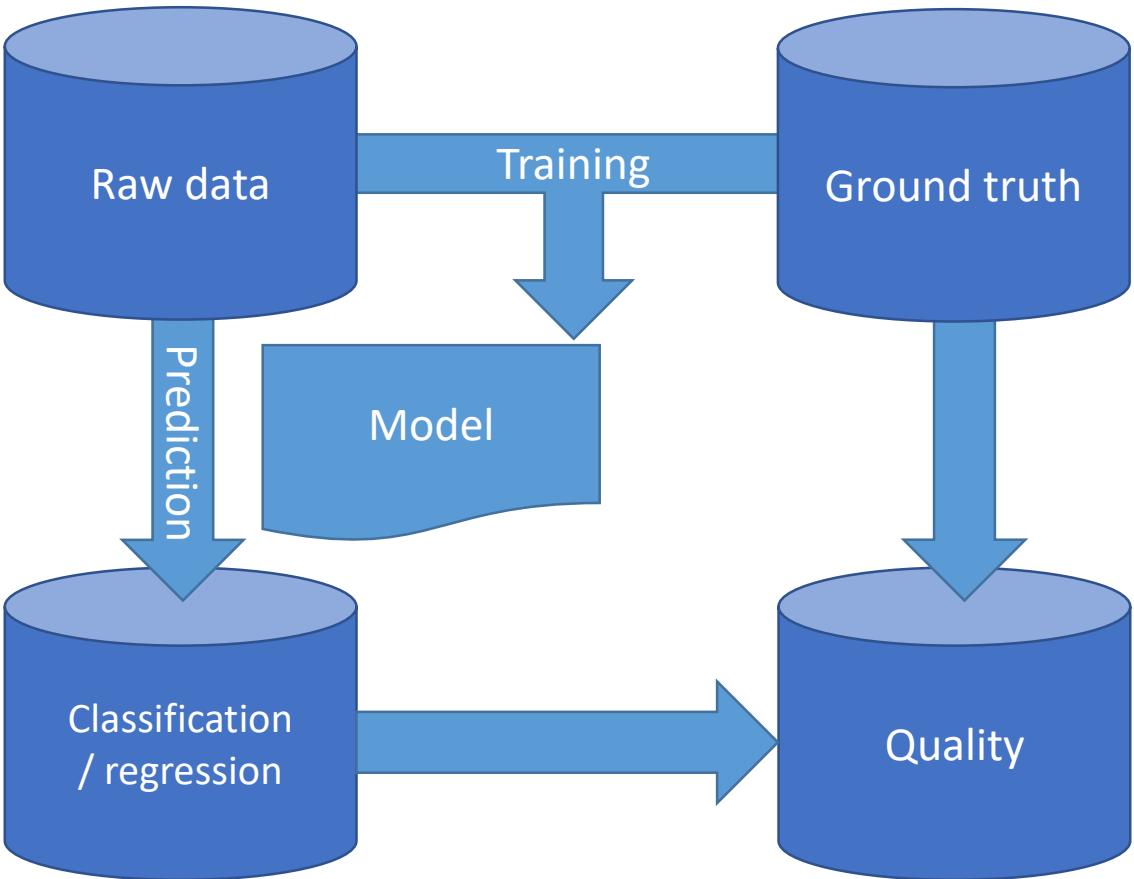
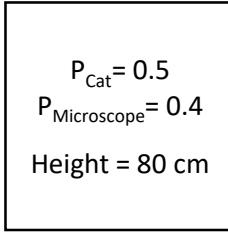
Image classification
“Cat”



Instance segmentation

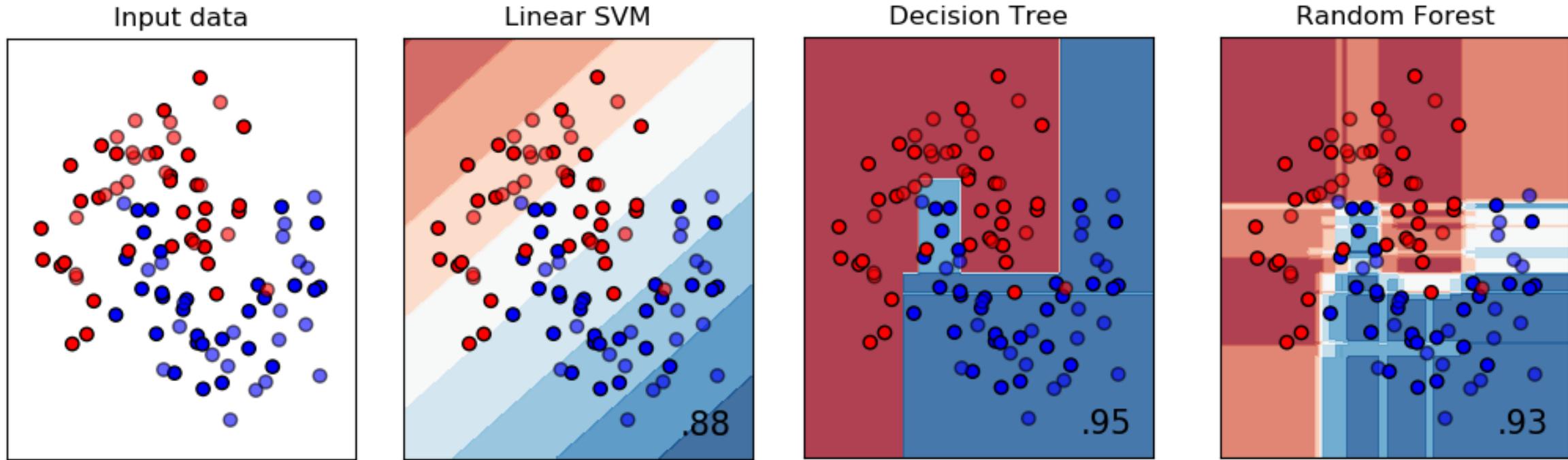


Cont. quantity



Precision,
Recall

- Guess classification (**color**) from position of a sample in parameter space.

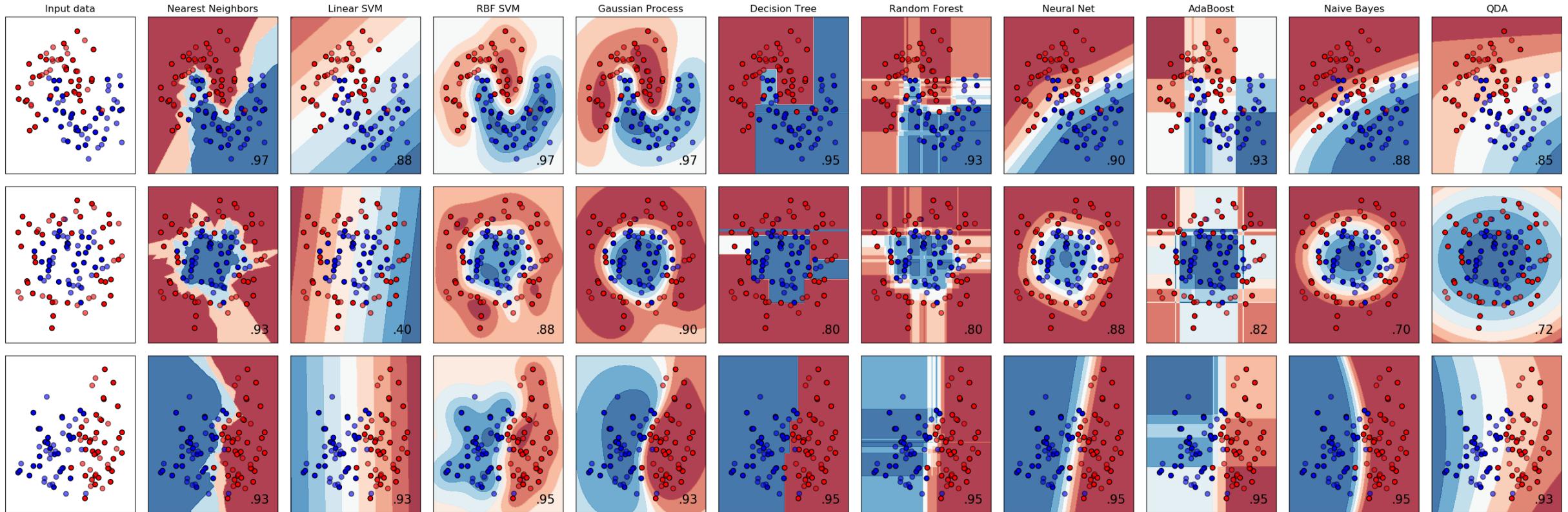


Adapted from https://scikit-learn.org/stable/auto_examples/classification/plot_classifier_comparison.html

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Approaches

- The right approach depends on data, computational resources and desired quality

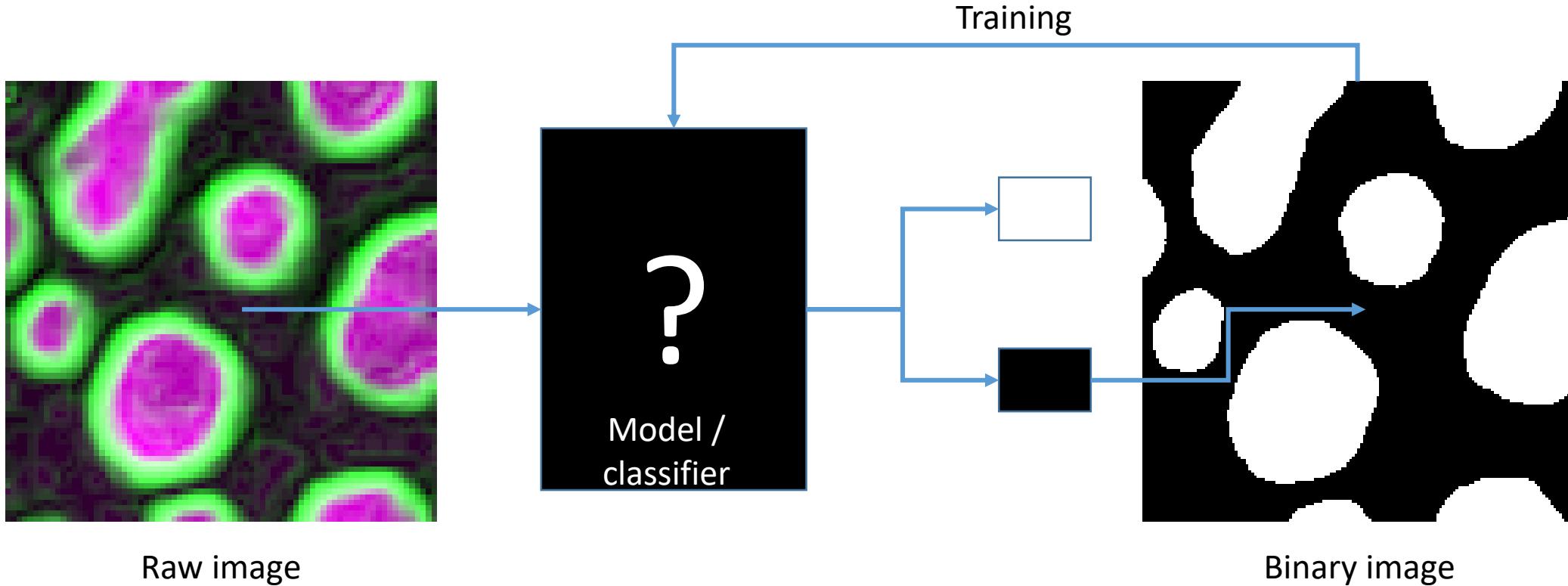


Adapted from https://scikit-learn.org/stable/auto_examples/classification/plot_classifier_comparison.html

© 2007 - 2019, scikit-learn developers (BSD License).

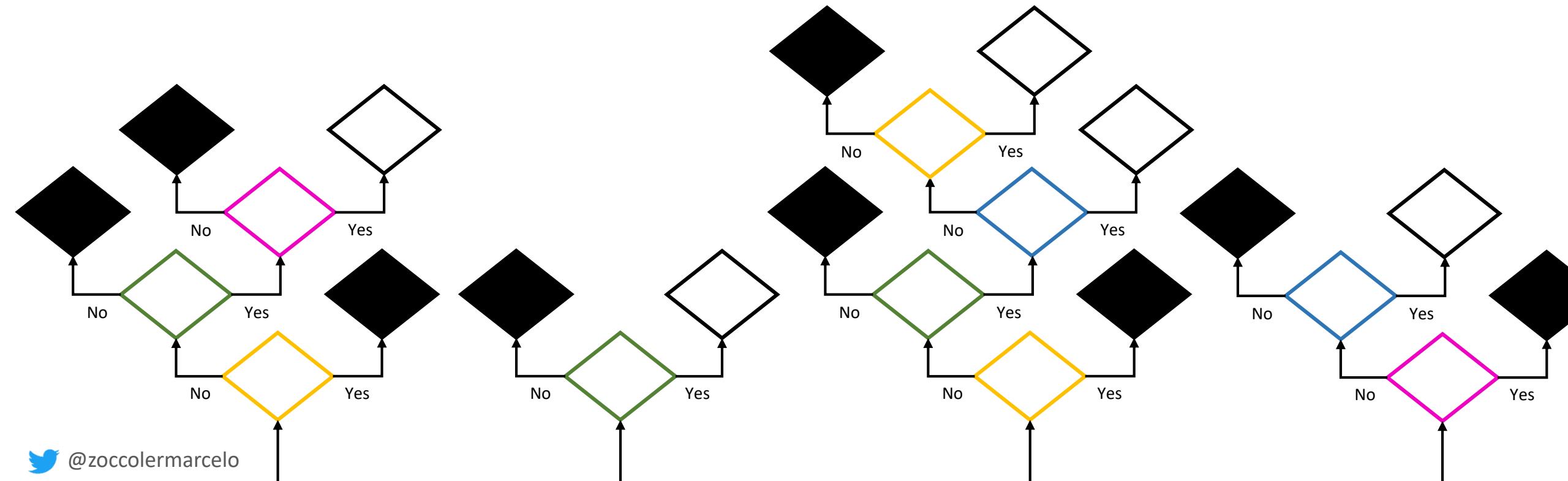
Machine learning for image segmentation

- *Supervised* machine learning: We give the computer some ground truth to learn from
- The computer derives a *model* or a *classifier* which can judge if a pixel should be foreground (white) or background (black)
- Example: Binary classifier



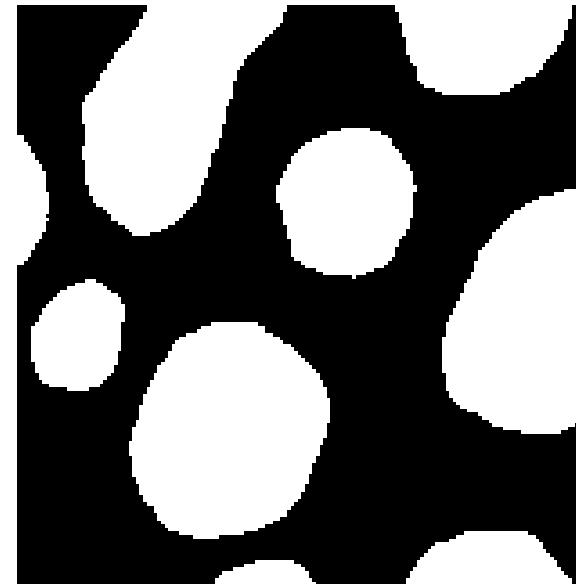
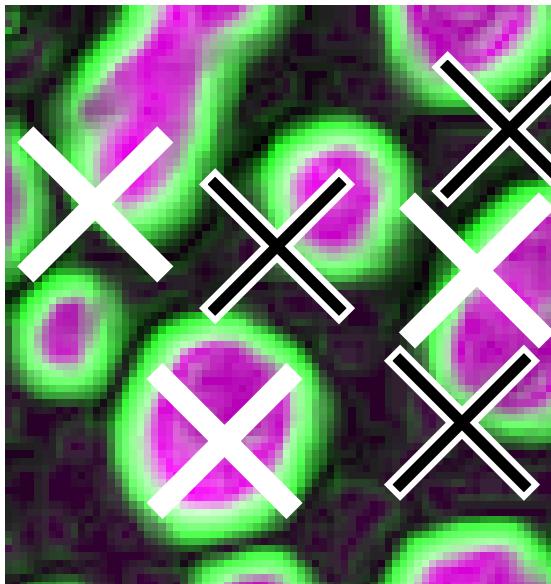
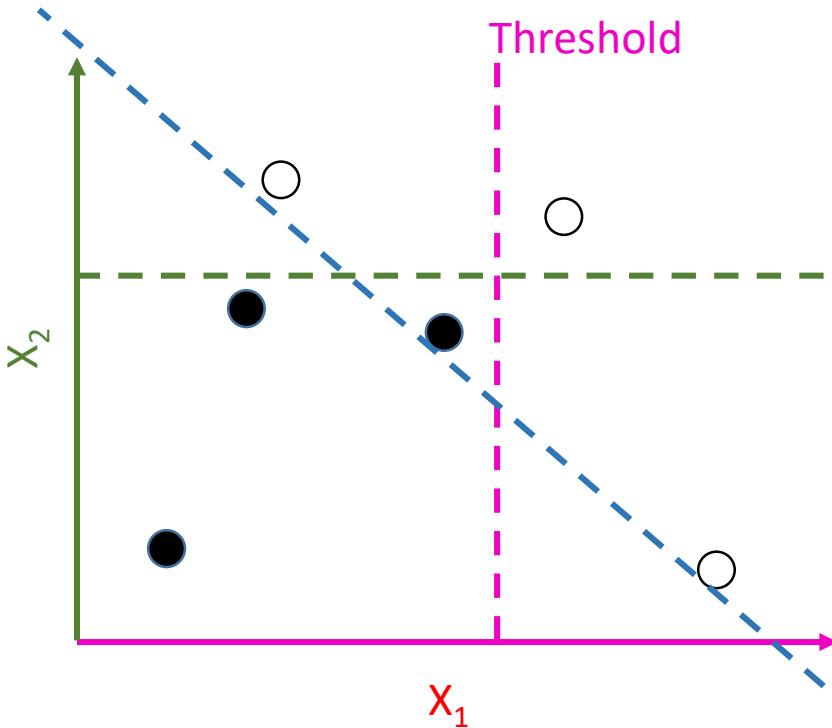
Random forest based image segmentation

- Decision trees are classifiers, they decide if a pixel should be white or black
 - Random decision trees are randomly initialized, afterwards evaluated and selected
 - Random forests consist of many random decision trees
-
- Example: Random forest of binary decision trees



Deriving random decision trees

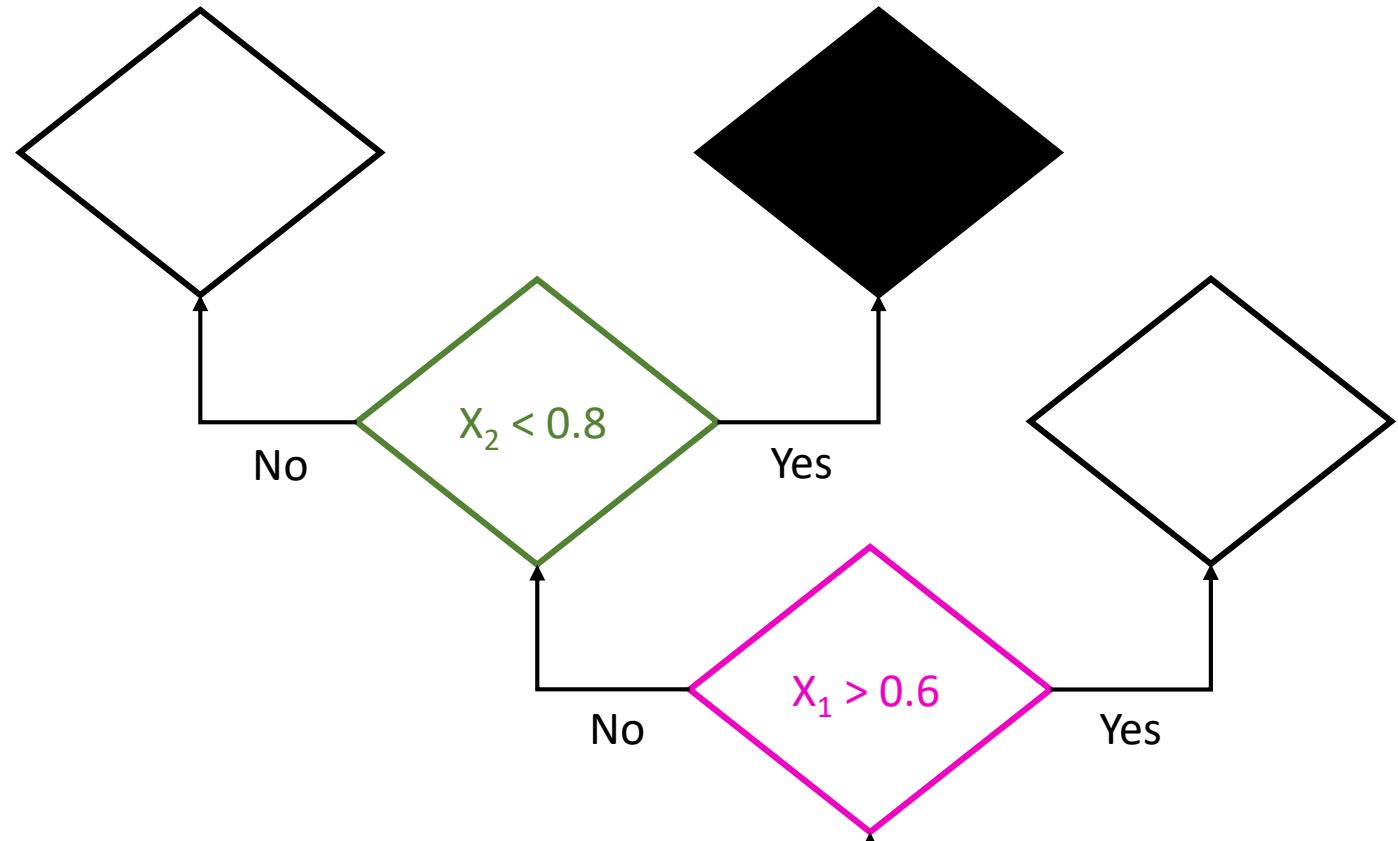
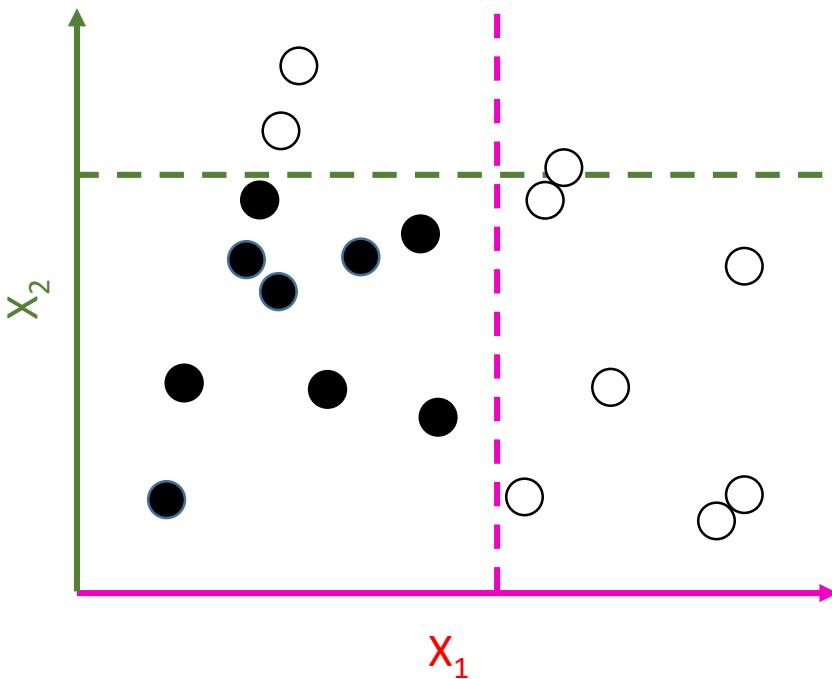
- For efficient processing, we randomly *sample* our data set
 - Individual pixels, their intensity and their classification



Note: You cannot use a single threshold to make the decision correctly

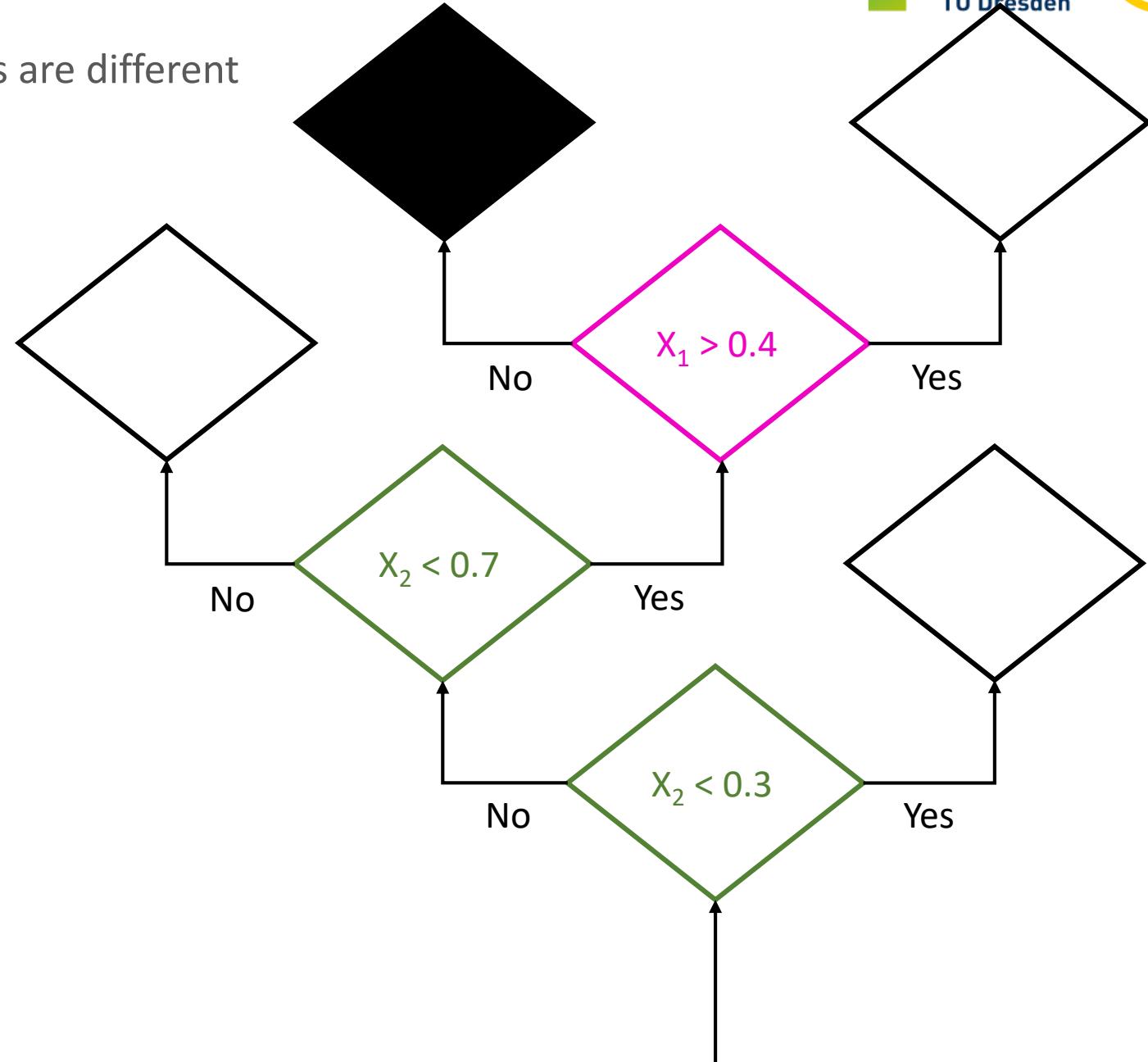
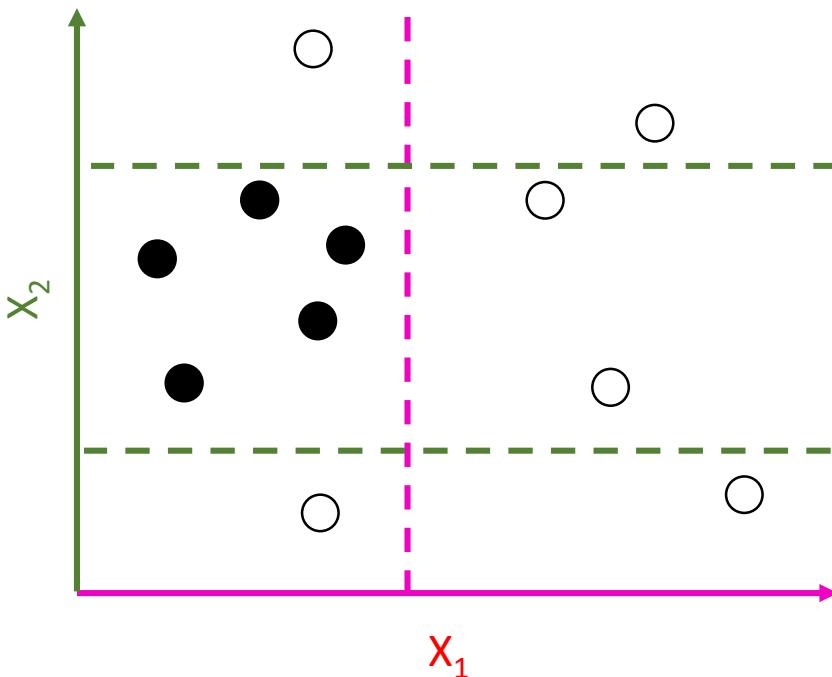
Deriving random decision trees

- Decision trees combine several thresholds on several parameters



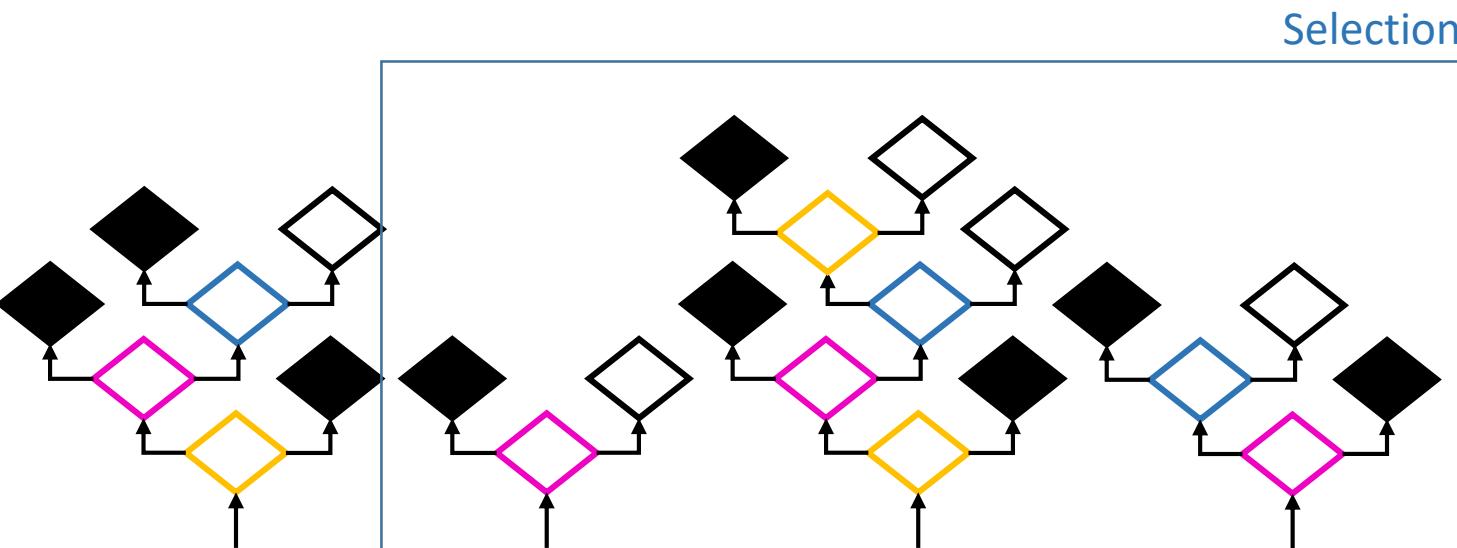
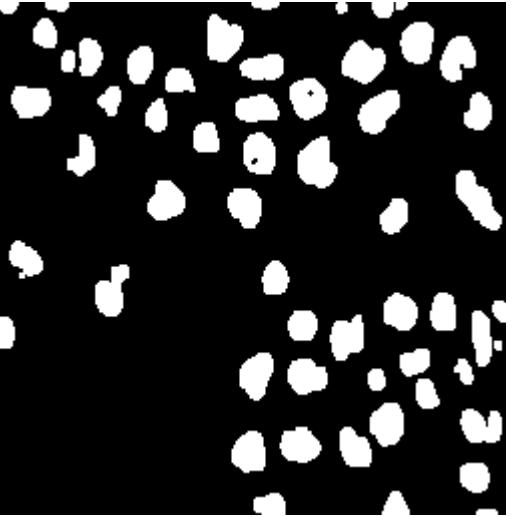
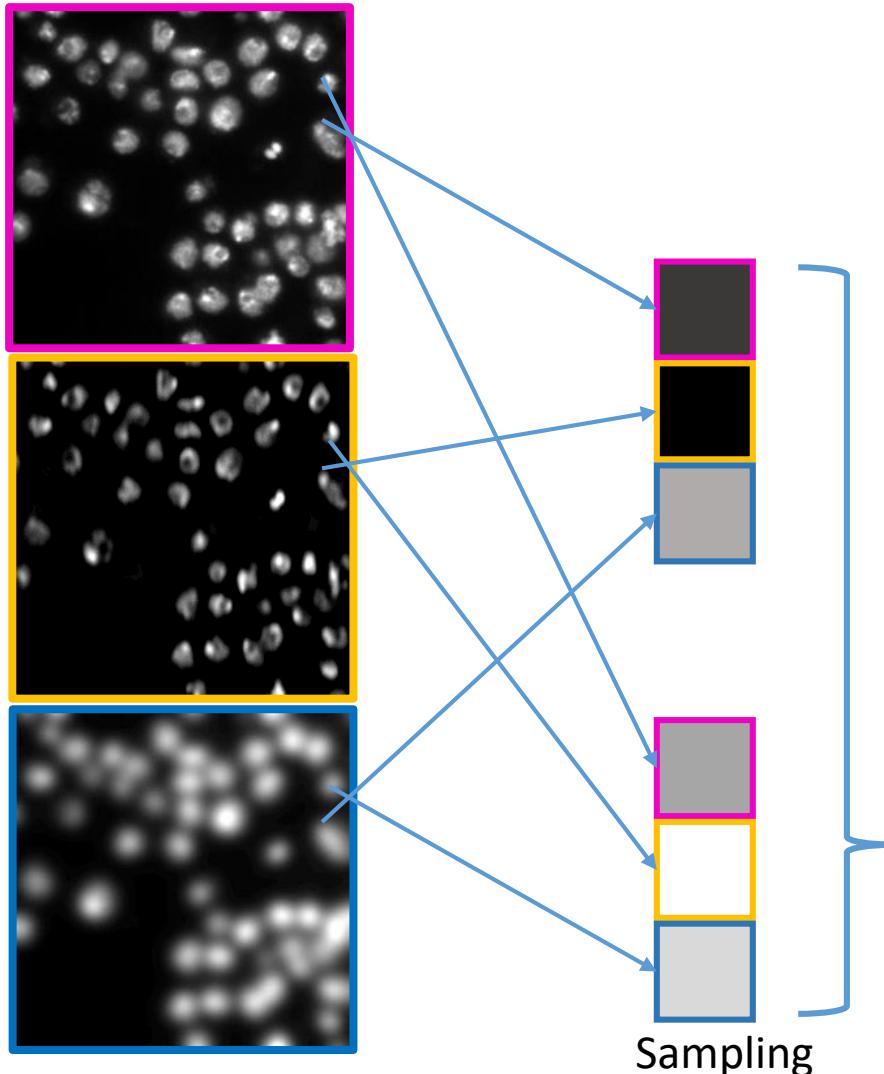
Deriving random decision trees

- Depending on sampling, the decision trees are different



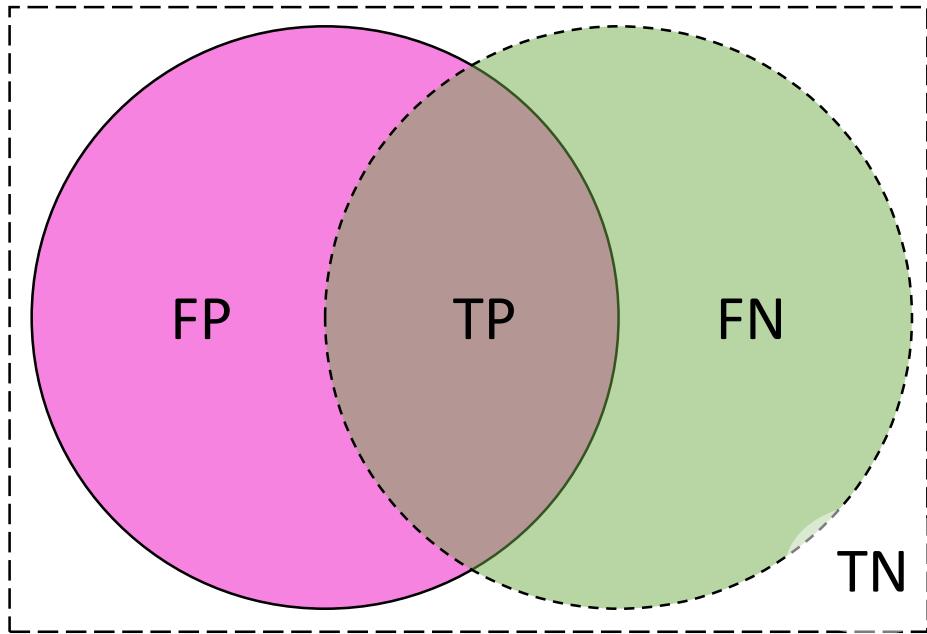
Random Forest Pixel Classifiers

- By comparing performance of individual decision trees, good ones can be selected, bad ones excluded.



Segmentation quality estimation

- In general
 - Define what's positive and what's negative.
 - Compare with a reference to figure out what was true and false



A	Prediction A
B	Reference B (ground truth)
ROI	Region of interest
TP	True-positive
FN	False-negative
FP	False-positive
TN	True-negative

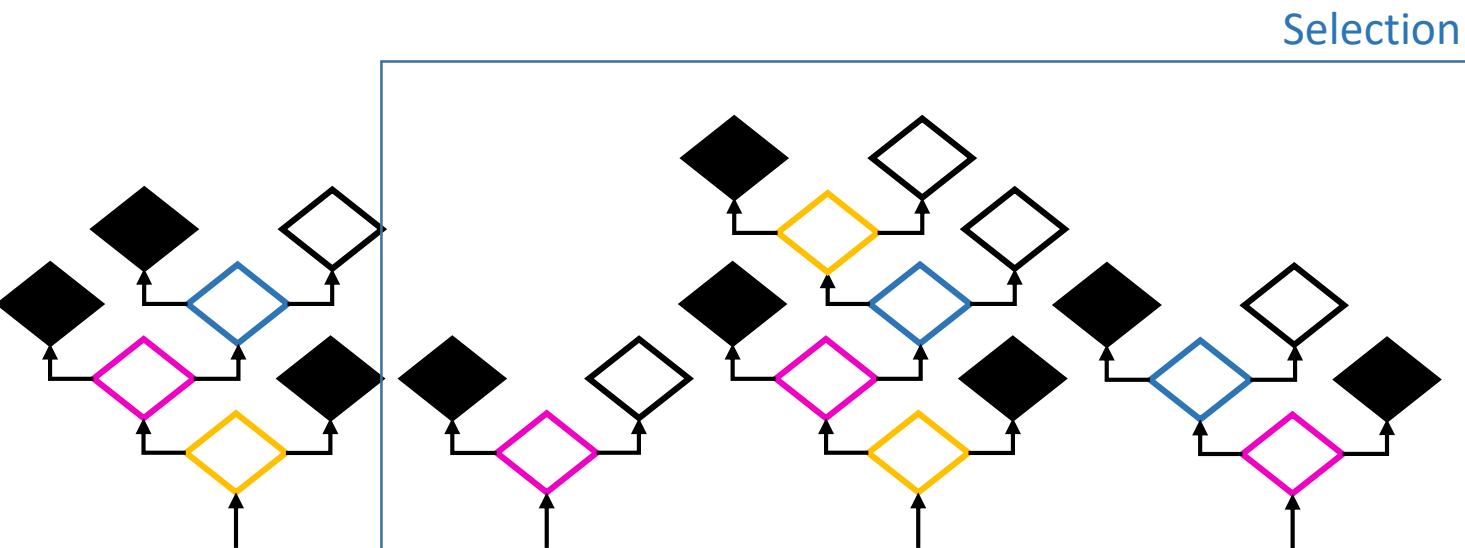
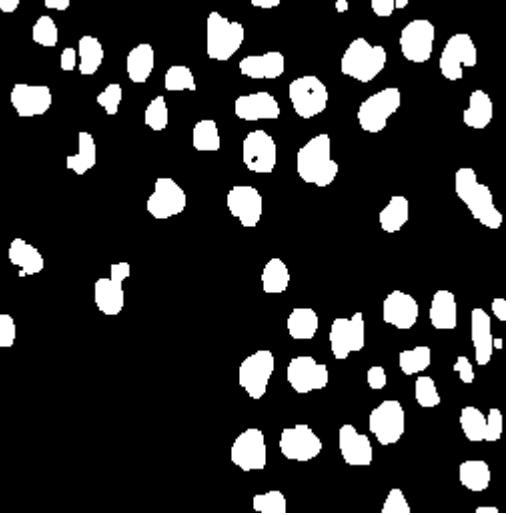
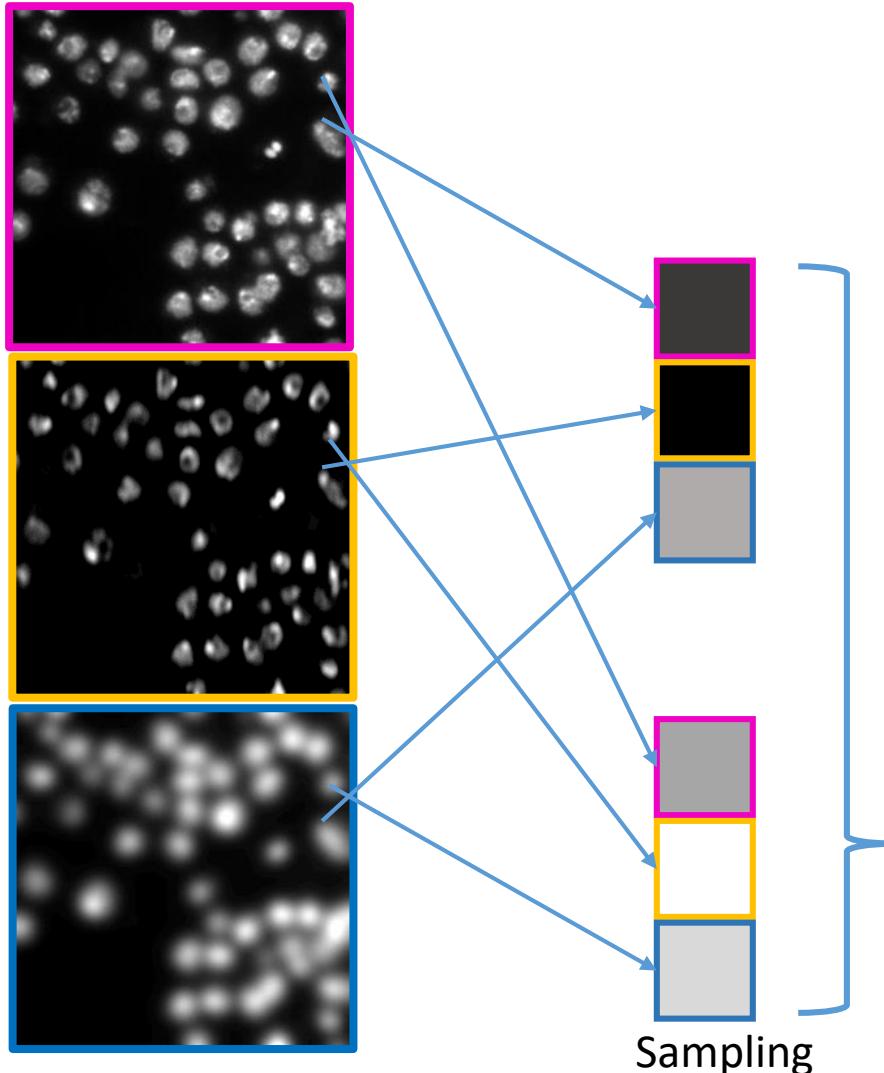
Overlap
(a.k.a. Jaccard index) $\frac{TP}{TP + FN + FP}$ How much do A and B overlap?

Precision $\frac{TP}{TP + FP}$ What fraction of points that were predicted as positives were really positive?

Recall
(a.k.a. sensitivity) $\frac{TP}{TP + FN}$ What fraction of positives points were predicted as positives?

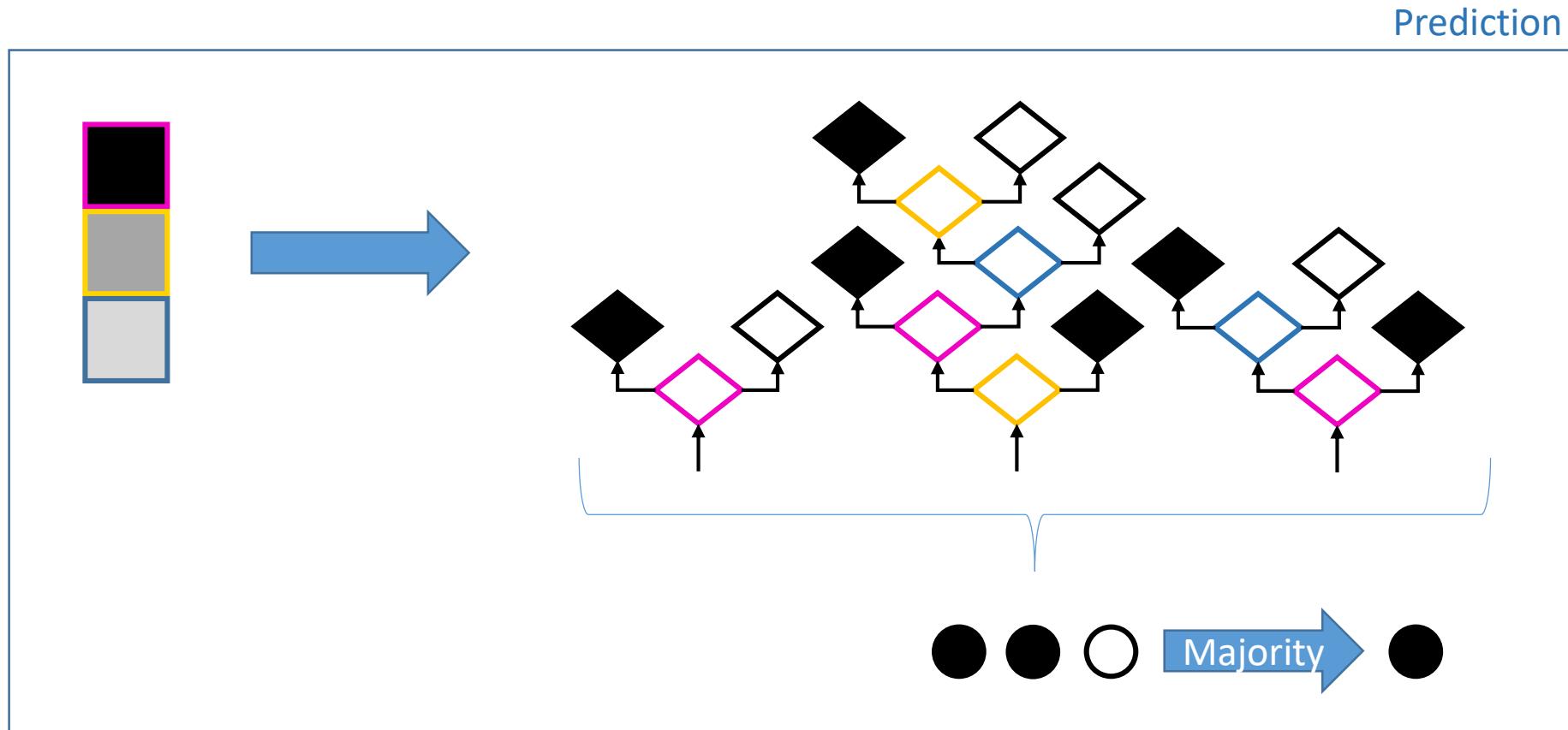
Random Forest Pixel Classifiers

- By comparing performance of individual decision trees, good ones can be selected, bad ones excluded.



Random Forest Pixel Classifiers

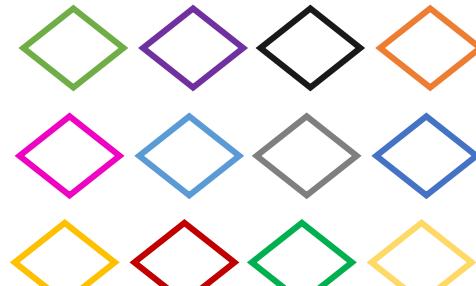
- Combination of individual tree decisions by voting or max / mean



Random Forest Pixel Classifiers

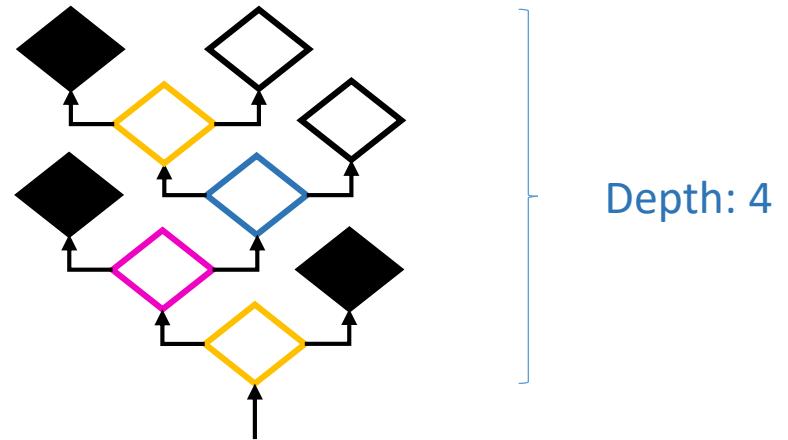
- Typical numbers for pixel classifiers in microscopy

Available features: > 20

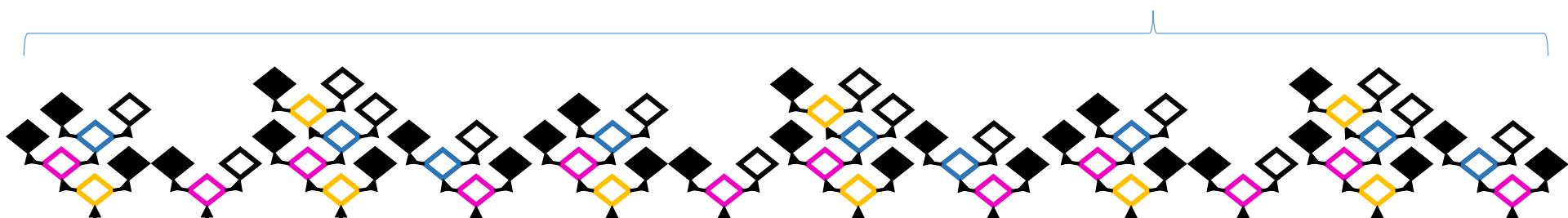


- Gaussian blur image
- DoG image
- LoG image
- Hessian
-

Selected features: <= depth

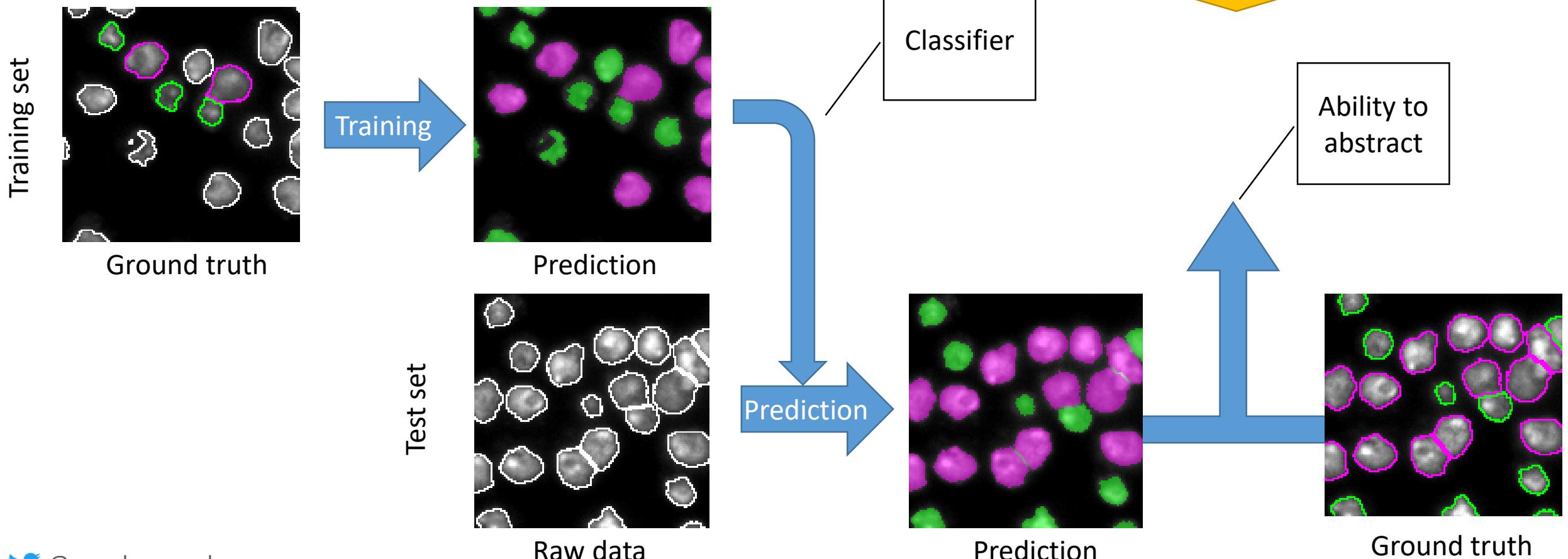


Number of trees: > 100

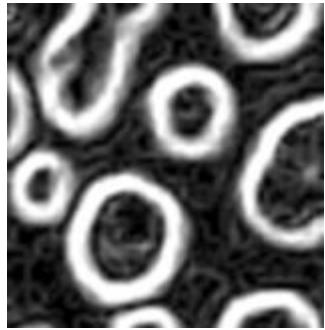


Model validation

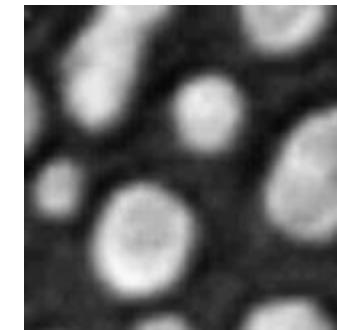
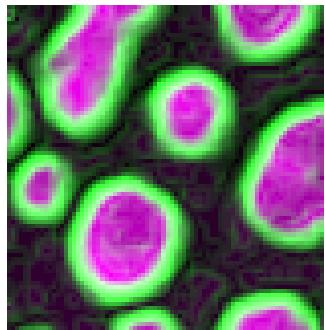
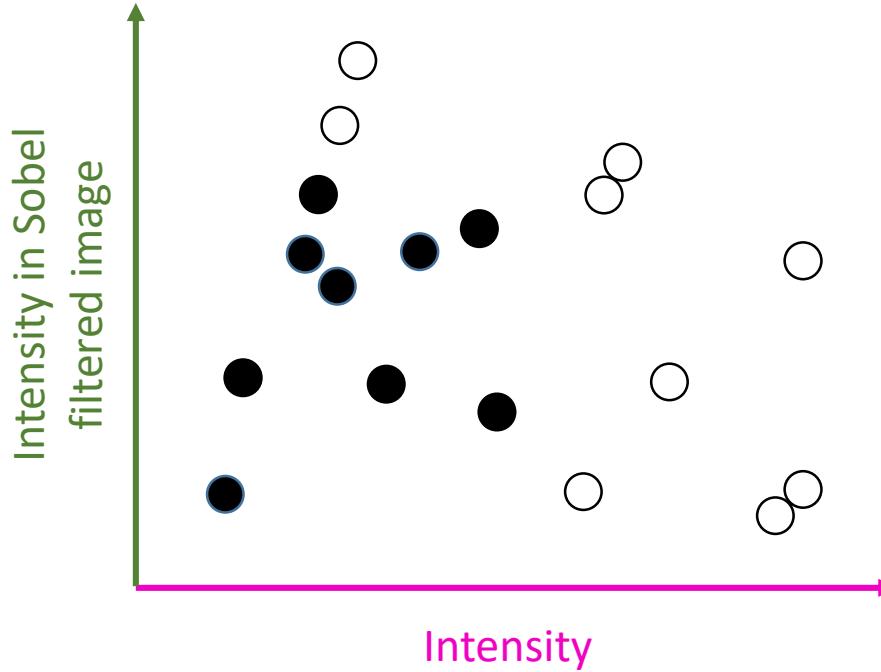
- A good classifier is trained on a hand full of datasets and works on thousands similarly well.
- In order to assess that, we split the ground truth into two set
 - Training set (50%-90% of the available data)
 - Test set (10%-50% of the available data)



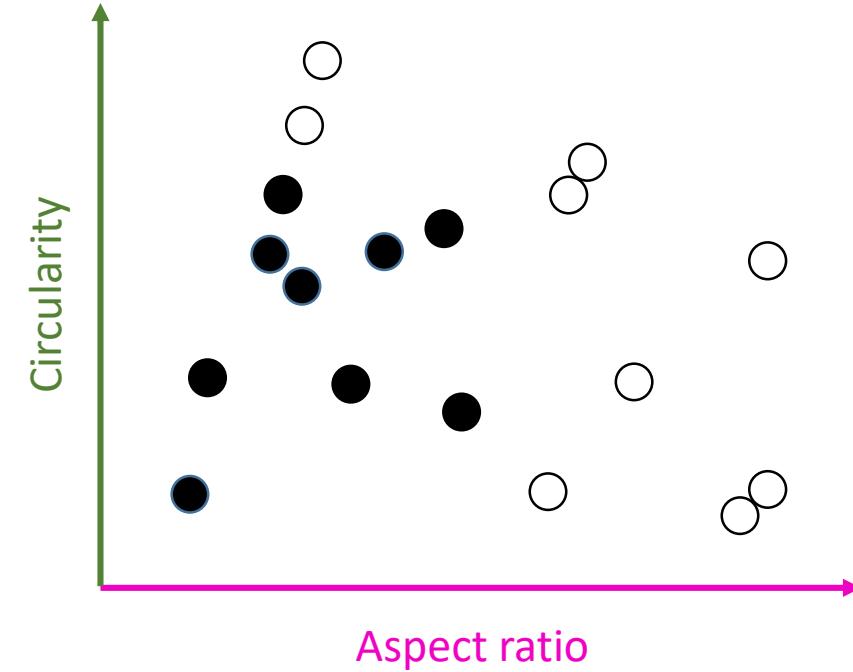
- What if we exchange pixel features with object features?



Pixel classification



Object classification

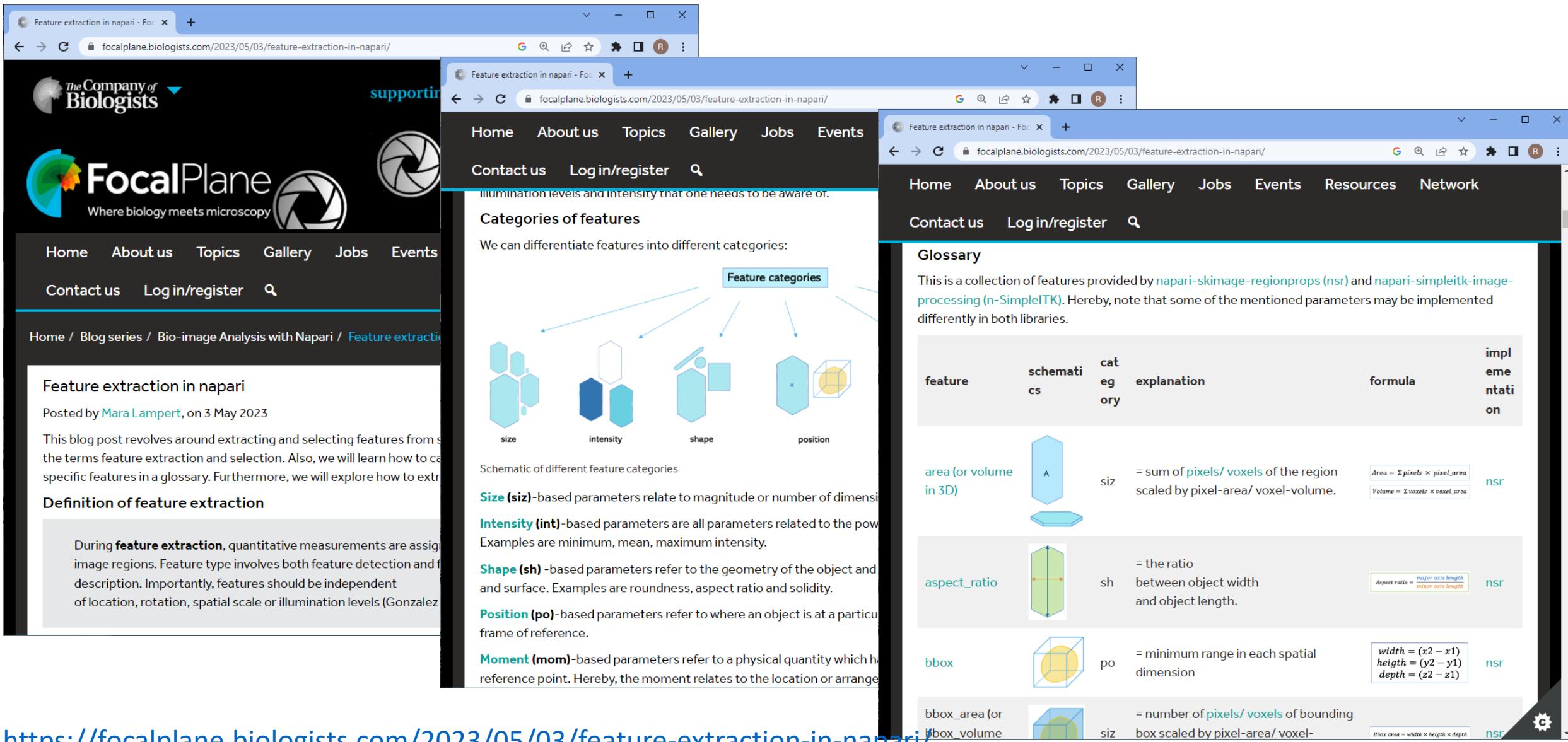


- The algorithms work the same but with different
 - Features
 - Number of features
 - Tree / forest parameters
 - Selection criteria

- A *feature* is a countable or measurable property of an image or object.
- Goal of feature extraction is finding a minimal set of features to describe an object well enough to differentiate it from other objects.

- **Intensity based**
 - Mean intensity
 - Standard deviation
 - Total intensity
 - Textures
- **Shape based /spatial**
 - Area / Volume
 - Roundness
 - Solidity
 - Circularity / Sphericity
 - Elongation
 - Centroid
 - Bounding box
- **Spatio-temporal**
 - Displacement,
 - Speed,
 - Acceleration
- **Others**
 - Overlap
 - Colocalization
 - Neighborhood
- **Mixed features**
 - Center of mass
 - Local minima / maxima

Further reading



The image shows three side-by-side screenshots of a blog post from [focalplane.biologists.com](https://focalplane.biologists.com/2023/05/03/feature-extraction-in-napari/). The left screenshot shows the main navigation bar and the start of the article. The middle screenshot displays a diagram of feature categories and their definitions. The right screenshot shows a glossary of terms.

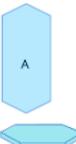
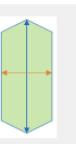
Categories of features

We can differentiate features into different categories:

- size**: Schematic of different feature categories
- intensity**: Schematic of different feature categories
- shape**: Schematic of different feature categories
- position**: Schematic of different feature categories

Glossary

This is a collection of features provided by [napari-skimage-regionprops \(nsr\)](#) and [napari-simpleitk-image-processing \(n-SimpleITK\)](#). Hereby, note that some of the mentioned parameters may be implemented differently in both libraries.

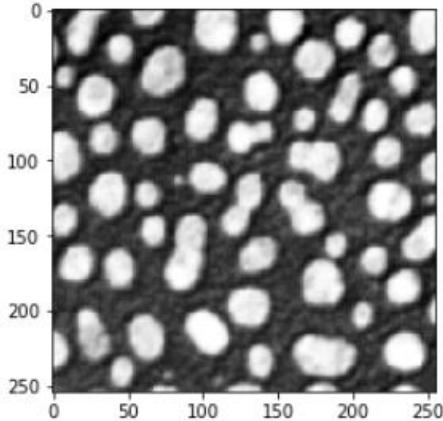
feature	schematics	category	explanation	formula	implementation
area (or volume in 3D)		siz	= sum of pixels/ voxels of the region scaled by pixel-area/ voxel-volume.	$Area = \sum \text{pixels} \times \text{pixel_area}$ $Volume = \sum \text{voxels} \times \text{voxel_area}$	nsr
aspect_ratio		sh	= the ratio between object width and object length.	$\text{Aspect ratio} = \frac{\text{major axis length}}{\text{minor axis length}}$	nsr
bbox		po	= minimum range in each spatial dimension	$\text{width} = (x_2 - x_1)$ $\text{height} = (y_2 - y_1)$ $\text{depth} = (z_2 - z_1)$	nsr
bbox_area (or bbox_volume)		siz	= number of pixels/ voxels of bounding box scaled by pixel-area/ voxel-volume	$Bbox\ area = \text{width} \times \text{height} \times \text{depth}$	nsr

<https://focalplane.biologists.com/2023/05/03/feature-extraction-in-napari/>

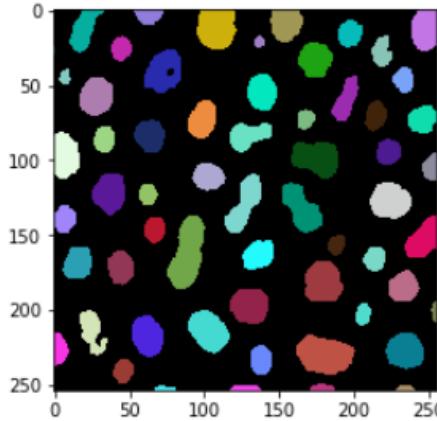
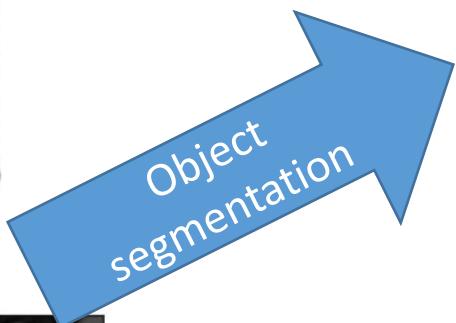
Accelerated pixel and object classification (APOC)

Accelerated pixel and object classification

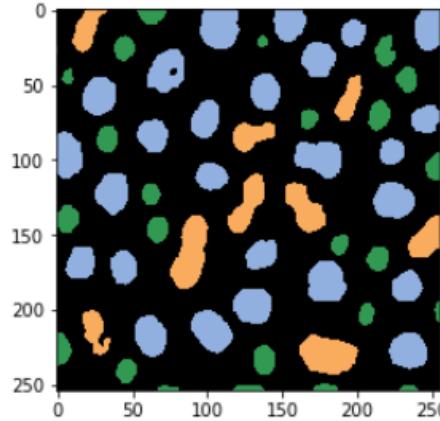
- APOC is a python library that makes use of OpenCL-compatible Graphics Cards to accelerate pixel and object classification



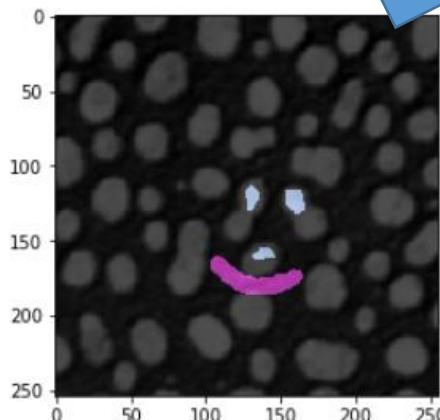
Raw image



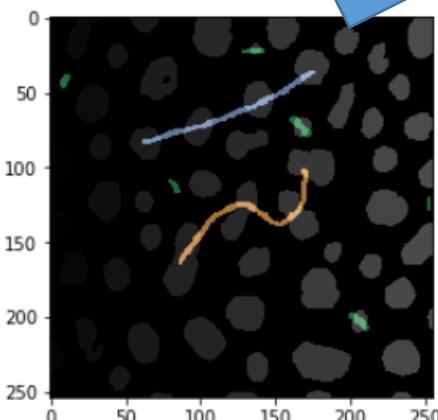
Object label image



Class label image



Pixel annotation

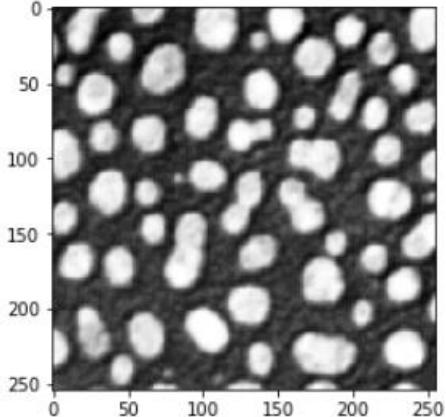


Object annotation

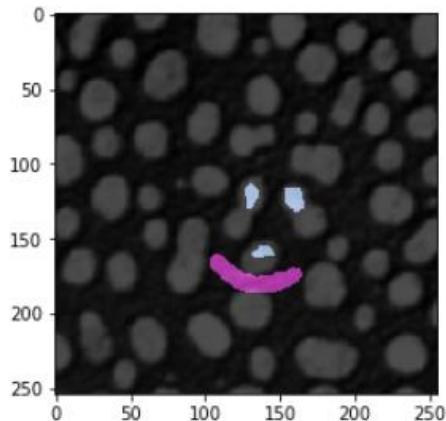


Object segmentation

- Pixel classification + connected component labeling



Raw image



Pixel annotation

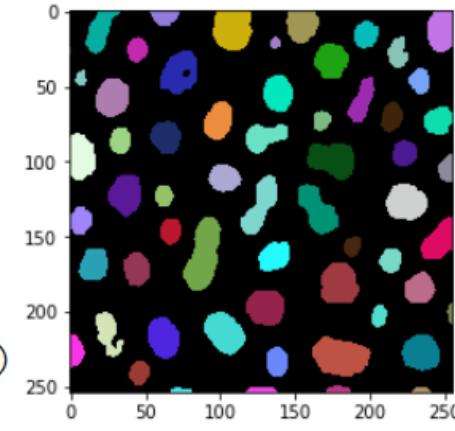
```
# define features
features = "gaussian_blur=1 gaussian_blur=5 sobel_of_gaussian_blur=1"

# this is where the model will be saved
cl_filename = 'my_object_segmenter.cl'

# delete classifier in case the file exists already
apoc.erase_classifier(cl_filename)

# train classifier
clf = apoc.ObjectSegmenter(opencl_filename=cl_filename, positive_class_identifier=2)
clf.train(features, manual_annotations, image)

segmentation_result = clf.predict(features=features, image=image)
cle.imshow(segmentation_result, labels=True)
```

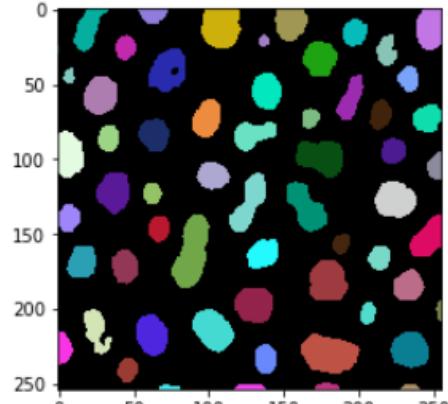


Object label image

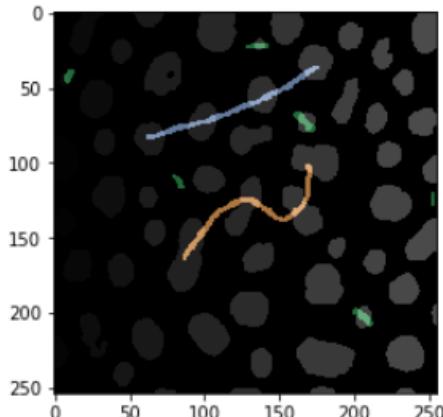
Object segmentation

Object classification

- Feature extraction + tabular classification



Object label image



Object annotation

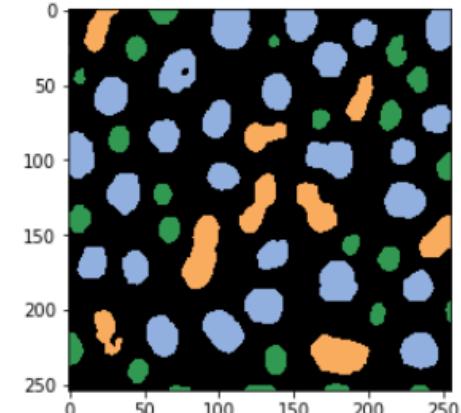
```
# for the classification we define size and shape as criteria
features = 'area mean_max_distance_to_centroid_ratio'

# This is where the model will be saved
cl_filename_object_classifier = "my_object_classifier.cl"

# delete classifier in case the file exists already
apoc.erase_classifier(cl_filename_object_classifier)

# train the classifier
classifier = apoc.ObjectClassifier(cl_filename_object_classifier)
classifier.train(features, segmentation_result, annotation, image)

# determine object classification
classification_result = classifier.predict(segmentation_result, image)
cle.imshow(classification_result, labels=True)
```

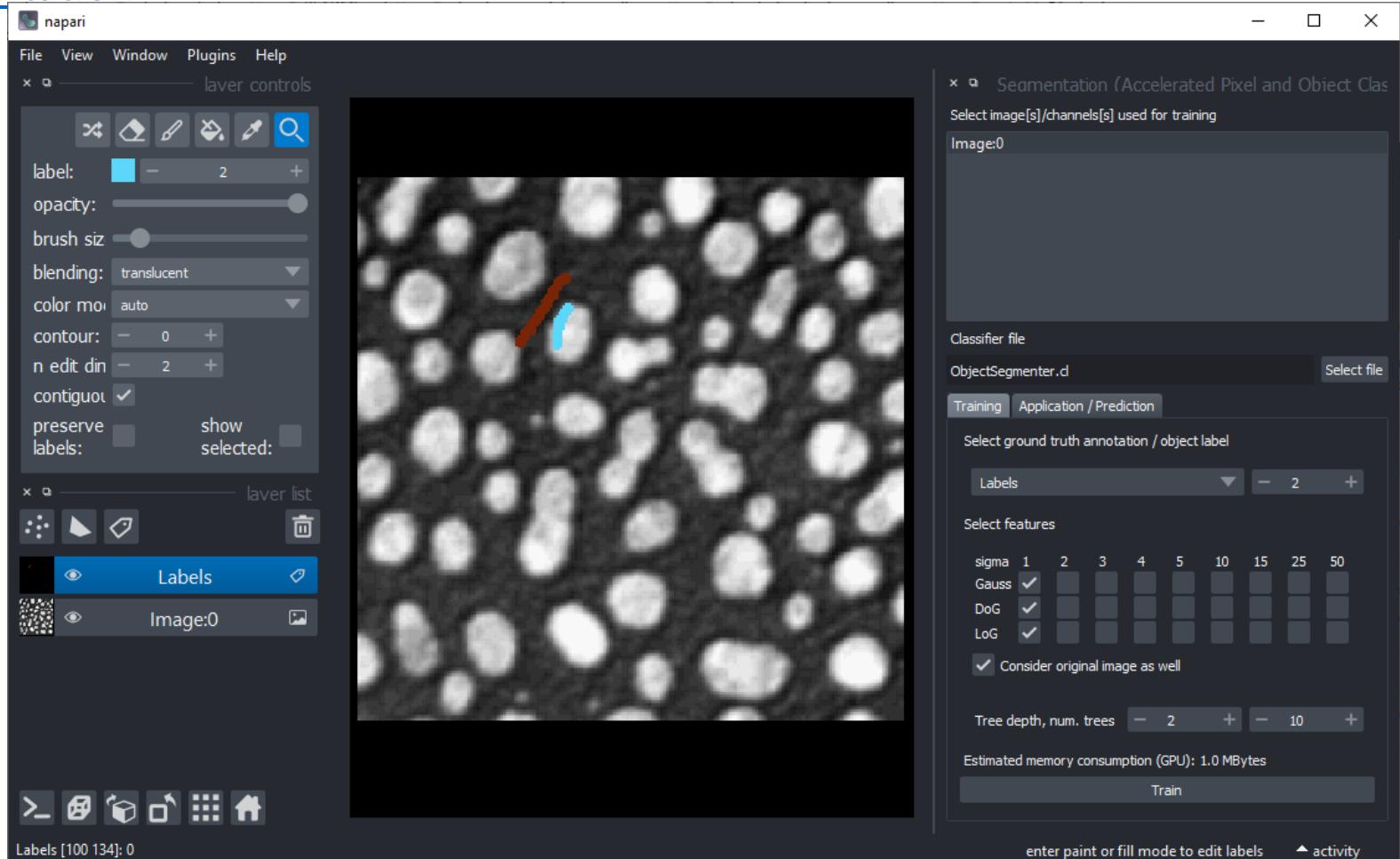


Class label image

Object classification

Graphical user interface

- Object segmentation
- <https://github.com/haesleinhuepf/napari-accelerated-pixel-and-object-classification#object-and-semantic-segmentation>



Exercises

Pixel classification / object segmentation

- Use Napari to segment objects

Interactive pixel classification and object segmentation in Napari

In this exercise we will train a [Random Forest Classifier](#) for pixel classification and convert the result in an instance segmentation. We will use the napari plugin [napari-accelerated-pixel-and-object-classification](#).

Getting started

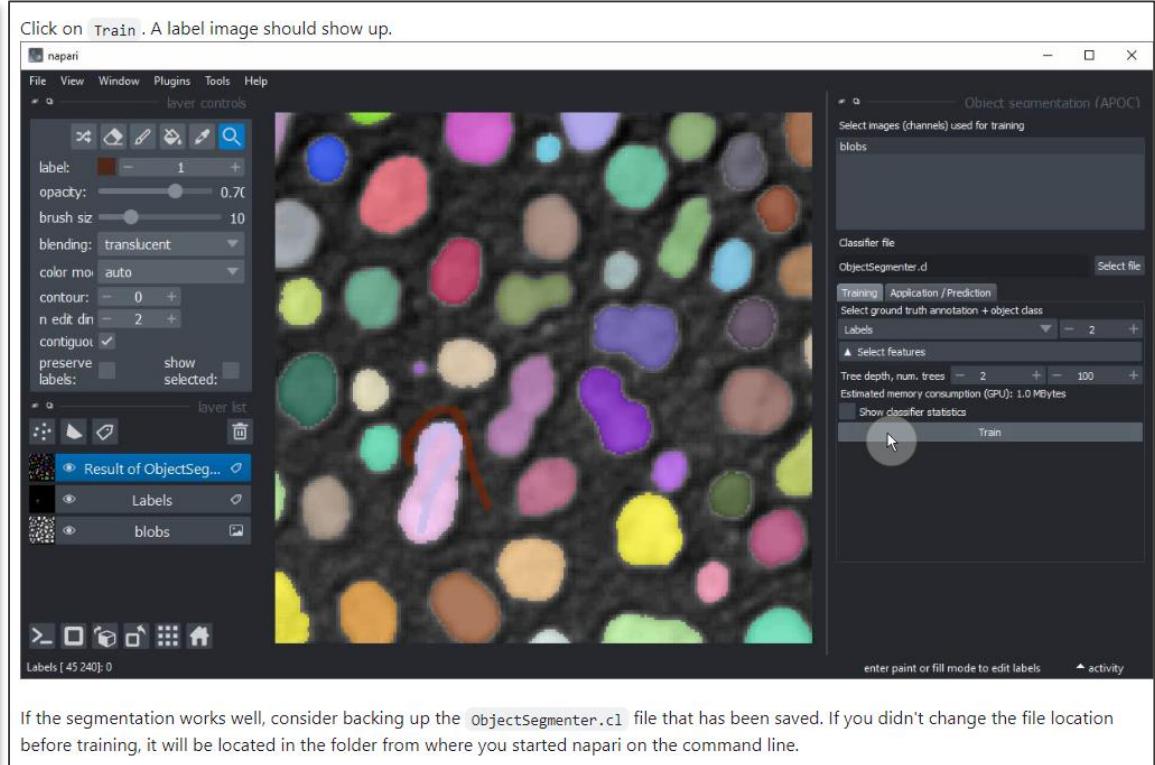
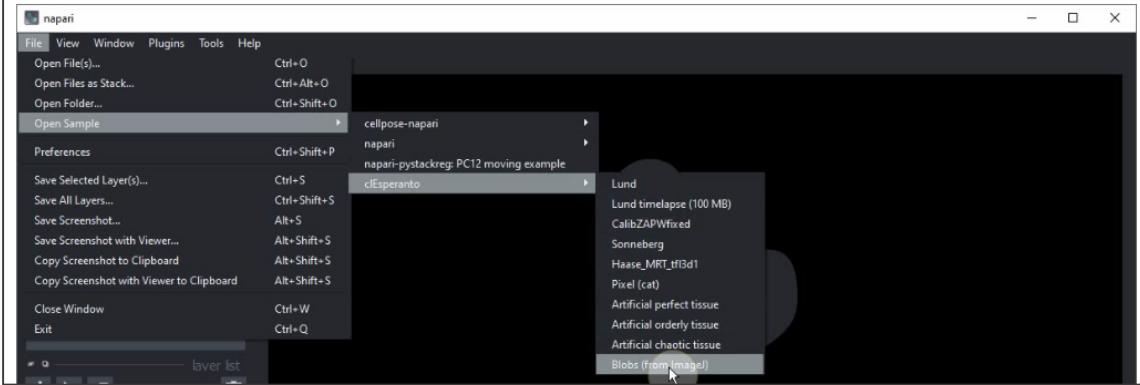
Open a terminal window and activate your conda environment:

```
conda activate devbio-napari-env
```

Afterwards, start up Napari:

```
napari
```

Load the "Blobs" example dataset from the menu `File > Open Sample > c1Esperanto > Blobs (from ImageJ)`



If the segmentation works well, consider backing up the `ObjectSegmenter.c1` file that has been saved. If you didn't change the file location before training, it will be located in the folder from where you started napari on the command line.

https://zoccoler.github.io/QM_Course_Bio_Image_Analysis_with_napari_2024/Machine_Learning_with_napari/interactive_pixel_classification/readme.html

Object classification

- Use Napari to group round and elongated objects

Interactive object classification in Napari

In this exercise we will train a [Random Forest Classifiers](#) for classifying segmented objects. We will use the napari plugin [napari-accelerated-pixel-and-object-classification](#).

Getting started

Open a terminal window and activate your conda environment:

```
conda activate devbio-napari-env
```

Afterwards, start up Napari:

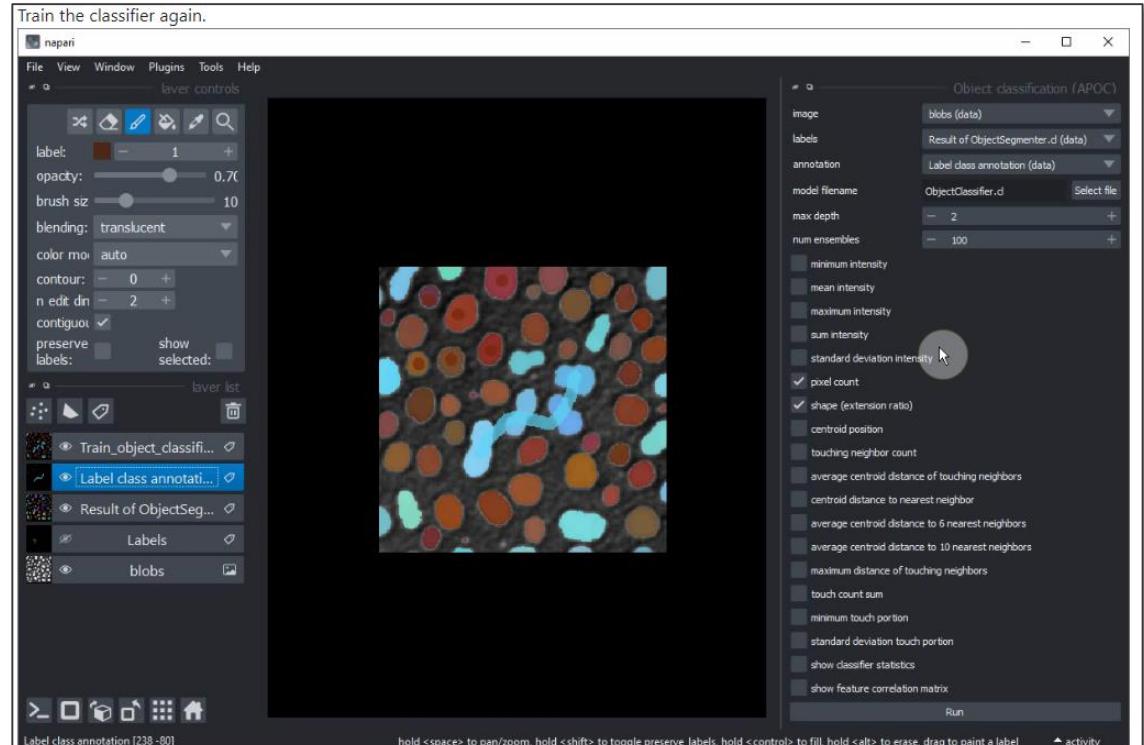
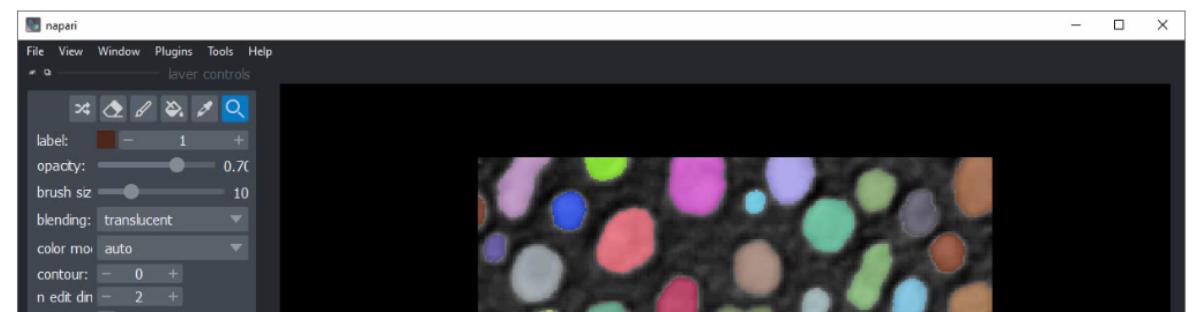
```
napari
```

Load the "Blobs" example dataset from the menu [File > Open Sample > c1Esperanto > Blobs \(from Image\)](#)

We furthermore need a label image. You can create it using the pixel classifier trained earlier or using the menu [Tools > Segmentation / labeling > Gauss-Otsu Labeling \(clesperanto\)](#).

Object classification

Our starting point is a loaded image and a label image with segmented objects. The following procedure is also shown in [this video](#).



If you are happy with the trained classifier, copy the file to a safe place. When training the next classifier this one might be overwritten.

Extra exercise

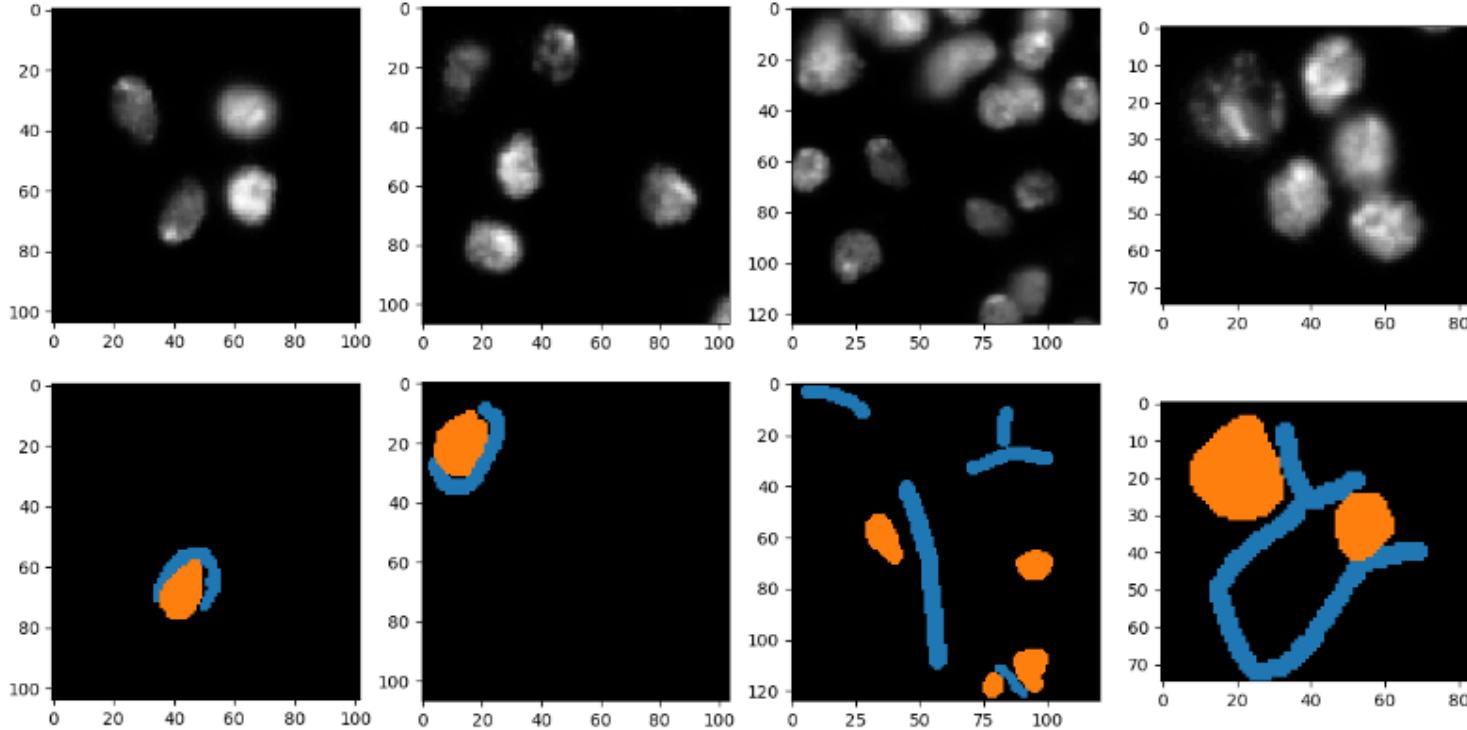
Retrain the classifier so that it can differentiate three different classes:

- Small round objects
- Large round objects
- Large elongated objects

https://zoccoler.github.io/QM_Course_Bio_Image_Analysis_with_napari_2024/Machine_Learning_with_napari/interactive_object_classification/readme.html

Pixel classifier on multiple images

- Use apoc to train on multiple images in a folder
- Run jupyter notebook below with Jupyter Lab

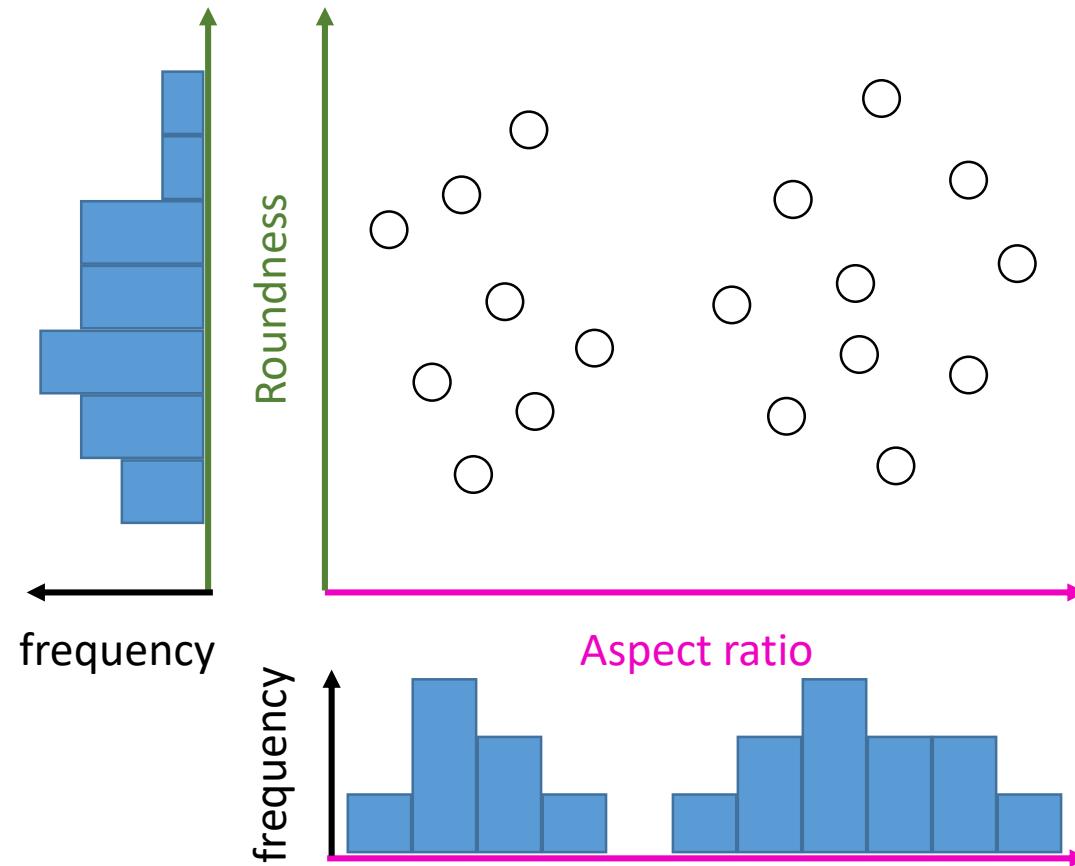


https://github.com/zoccoler/QM_Course_Bio_Image_Analysis_with_napari_2024/blob/main/docs/Machine_Learning_with_apoc_train_on_folders.ipynb (original source: apoc repository - https://github.com/haesleinhuepf/apoc/blob/main/demo/demp_pixel_classifier_continue_training.ipynb)

Unsupervised Machine Learning for Object Characterization

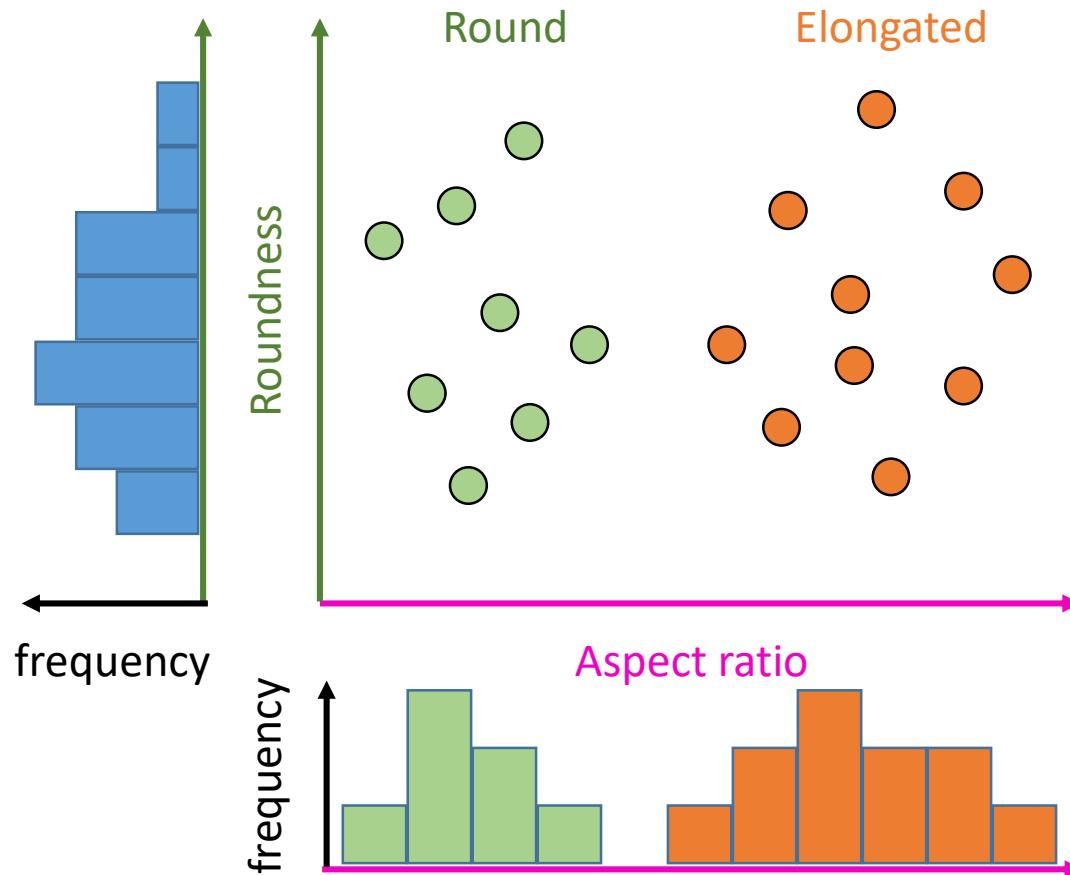
Unsupervised machine learning

- If you don't provide ground truth, the algorithm is *unsupervised*.



Unsupervised machine learning

- If you don't provide ground truth, the algorithm is unsupervised.
- Nevertheless, algorithms can tell us something about the data



- Hypothesis: Cell shape can be influenced by modifying X.
- Null-Hypothesis: Circularity of modified cells is similar to cells in the control group.

- Sample preparation

Should we use a different segmentation algorithm?

- Imaging

Shall we use a different microscope?

- Cell segmentation

- Circularity measurement

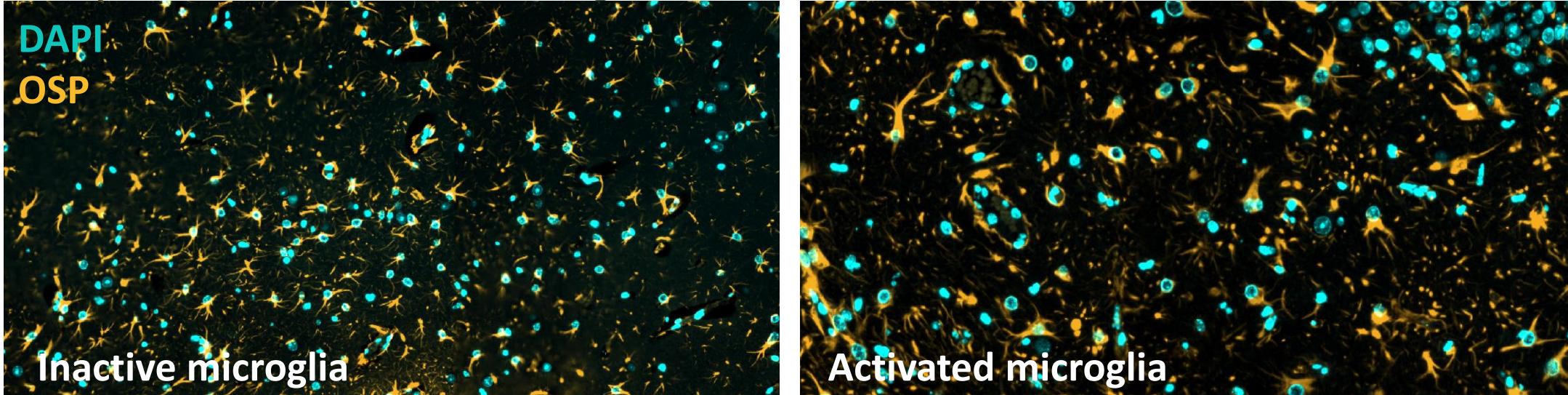
Is circularity the right parameter to measure?

- Statistics

- Hypothesis: Cell shape can be influenced by modifying X.
 - Question: Which image-derived parameter is influenced when modifying X?
 - Sample preparation
 - Imaging
 - Cell segmentation algorithm A, algorithm B, algorithm C
 - Measurement of circularity, solidity, elongation, extend, texture, intensity, topology ...
 - Statistics
- Which segmentation algorithms allow measurements that show a relationship with X?
- Why?
- Which parameter shows any relationship with X?

Identifying features to measure

Example: Inactive vs. activated microglia in mouse brain



Challenge: Which of these features reflect biological properties?

	label	area	bbox_area	convex_area	quivalent_diameter	max_intensity	mean_intensity	min_intensity	solidity	extent	eret_diameter_max	local_centroid-0	l
1	1	3379	13949	5120	18.61786412639...	613.0	345.6717963894...	259.0	0.6599609375	0....	37.3496987939662	15.77952056821...	18
2	2	2319	7448	3491	16.42230229224...	421.0	297.8434670116...	240.0	0....	0....	38.65229618017...	4....	12
3	3	2304	14415	4281	16.38681751812...	456.0	300.8298611111...	245.0	0....	0....	34.19064199455...	17.73828125	13
4	4	3278	13804	5139	18.43048549951...	467.0	316.1446003660...	249.0	0....	0....	34.84250278036...	15.52287980475...	10
5	5	1501	3315	1681	14.20563625190...	458.0	302.147235176549	236.0	0....	0....	17.97220075561...	6....	6.
6	6	2341	6061	2714	16.47407088948...	594.0	355.4446817599...	261.0	0....	0....	30.67572330035...	16.54250320375...	6.
7	7	1725	3584	1940	14.87979081163...	568.0	343.786666666...	257.0	0....	0....	17.72004514666...	7.80463768115942	7.
8	8	1502	3840	1753	14.20879025650...	431.0	290.0659121171...	235.0	0....	0....	18.57417562100...	8....	6.



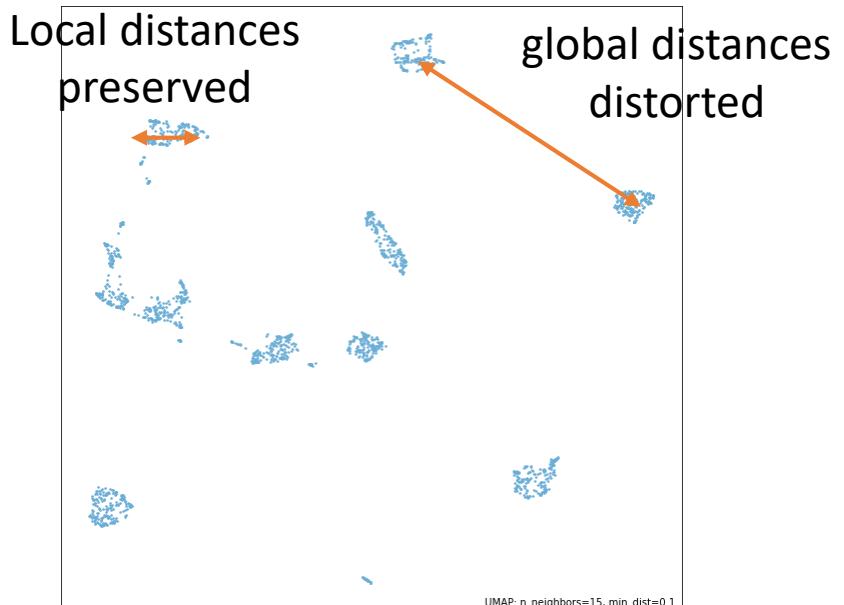
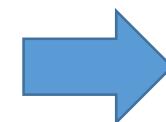
@zoccolermarcelo

Dimensionality reduction

- Challenge: Find a representation (embedding) of your data that represents the data in fewer dimensions
- Preserve local distances at the expense of global distortions

	label	area	bbox_area	convex_area	equivalent_diameter	max_intensity	mean_intensity	min_intensity	solidity	extent	eret_diameter_ma	local_centroid-0	l...
1	1	3379	13949	5120	18.61786412639...	613.0	345.6717963894...	259.0	0.6599609375	0....	37.3496987939662	15.77952056821...	18...
2	2	2319	7448	3491	16.4223022924...	421.0	297.8434670116...	240.0	0....	0....	38.65229618017...	4....	12...
3	3	2304	14415	4281	16.38681751812...	456.0	300.8298611111...	245.0	0....	0....	34.1906419455...	17.73828125	13...
4	4	3278	13804	5139	18.43048549951...	467.0	316.1446003660...	249.0	0....	0....	34.84250278036...	15.52287980475...	10...
5	5	1501	3315	1681	14.20563625190...	458.0	302.147235176549	236.0	0....	0....	17.97220075561...	6....	6...
6	6	2341	6061	2714	16.47407088948...	594.0	355.4446817599...	261.0	0....	0....	30.67572330035...	16.54250320375...	6...
7	7	1725	3584	1940	14.87979081163...	568.0	343.7866666666...	257.0	0....	0....	17.72004514666...	7.80463768115942	7...
8	8	1502	3840	1753	14.20879025650...	431.0	290.0659121171...	235.0	0....	0....	18.57417562100...	8....	6...
9	9	1602	4080	1894	14.51737058294...	475.0	297.8008739076...	241.0	0....	0....	18.70828693386...	8....	8...
10	10	1395	3600	1624	13.86304166283...	424.0	304.8494623655...	247.0	0....	0.3875	17.60681686165...	7....	7...
11	11	609	1100	697	10.51654029260...	323.0	274.2528735632...	241.0	0....	0....	13.45362404707...	3....	4...
12	12	1686	3757	1894	14.76679738567...	460.0	303.8303677342...	240.0	0....	0....	17.97220075561...	9....	7...
13	13	2157	5184	2531	16.03062694504...	576.0	339.990264255911	270.0	0....	0....	19.54482028569...	8....	8...
14	14	863	2340	1032	11.81237949737...	327.0	272.4449594438...	237.0	0....	0....	16.0312195418814	6....	5...

Many dimensions



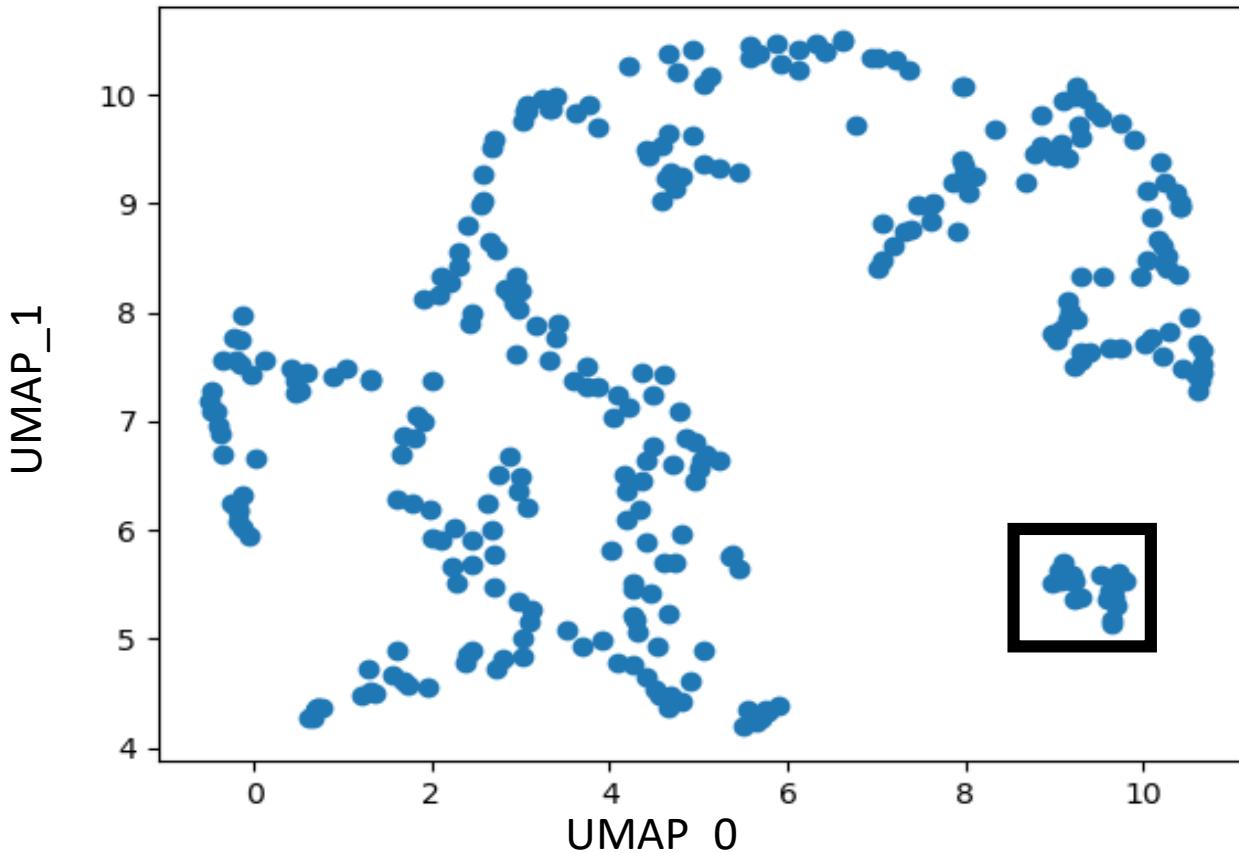
Few dimensions

Learn more: https://umap-learn.readthedocs.io/en/latest/how_umap_works.html



<https://umap-learn.readthedocs.io/en/latest/index.html>

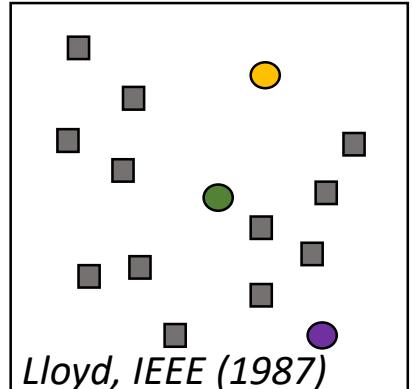
- Starting point: Feature space or dimensionality reduction reveals “groups” in our data
- Can we automatically identify these groups?



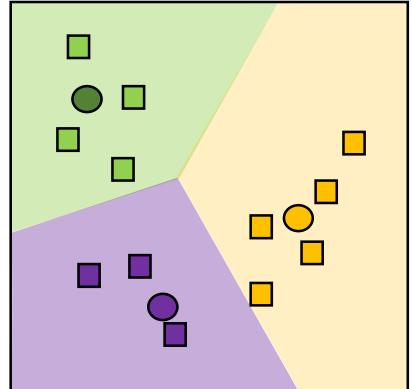
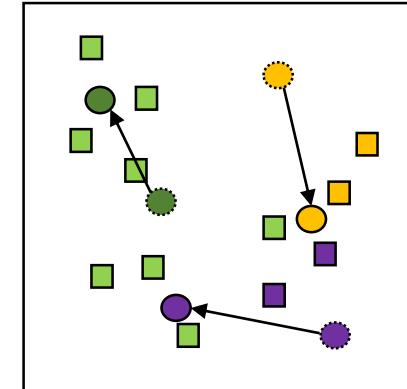
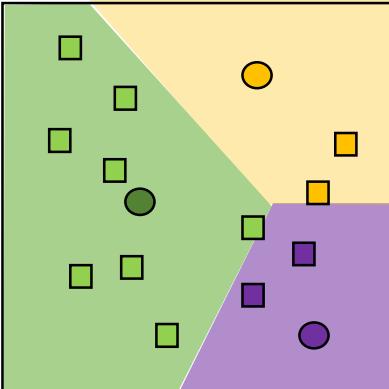
→ Clustering allows to stratify data into groups *without previous annotations*

K-means clustering

Strategy: Group data points into n groups so that variance within group is minimal

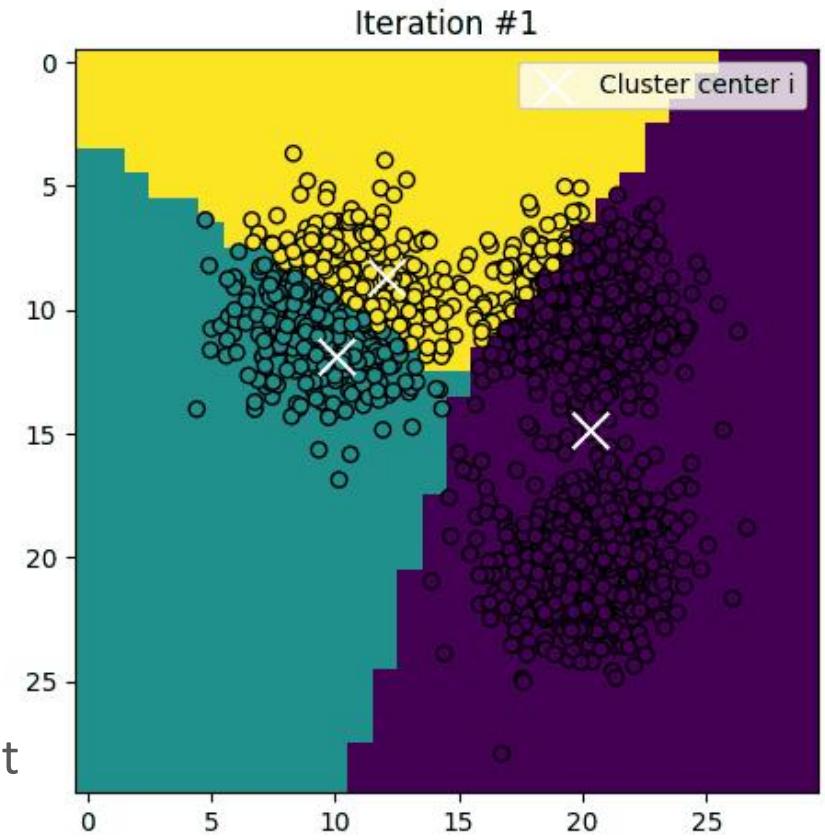


Step1: Random initialization of cluster centers



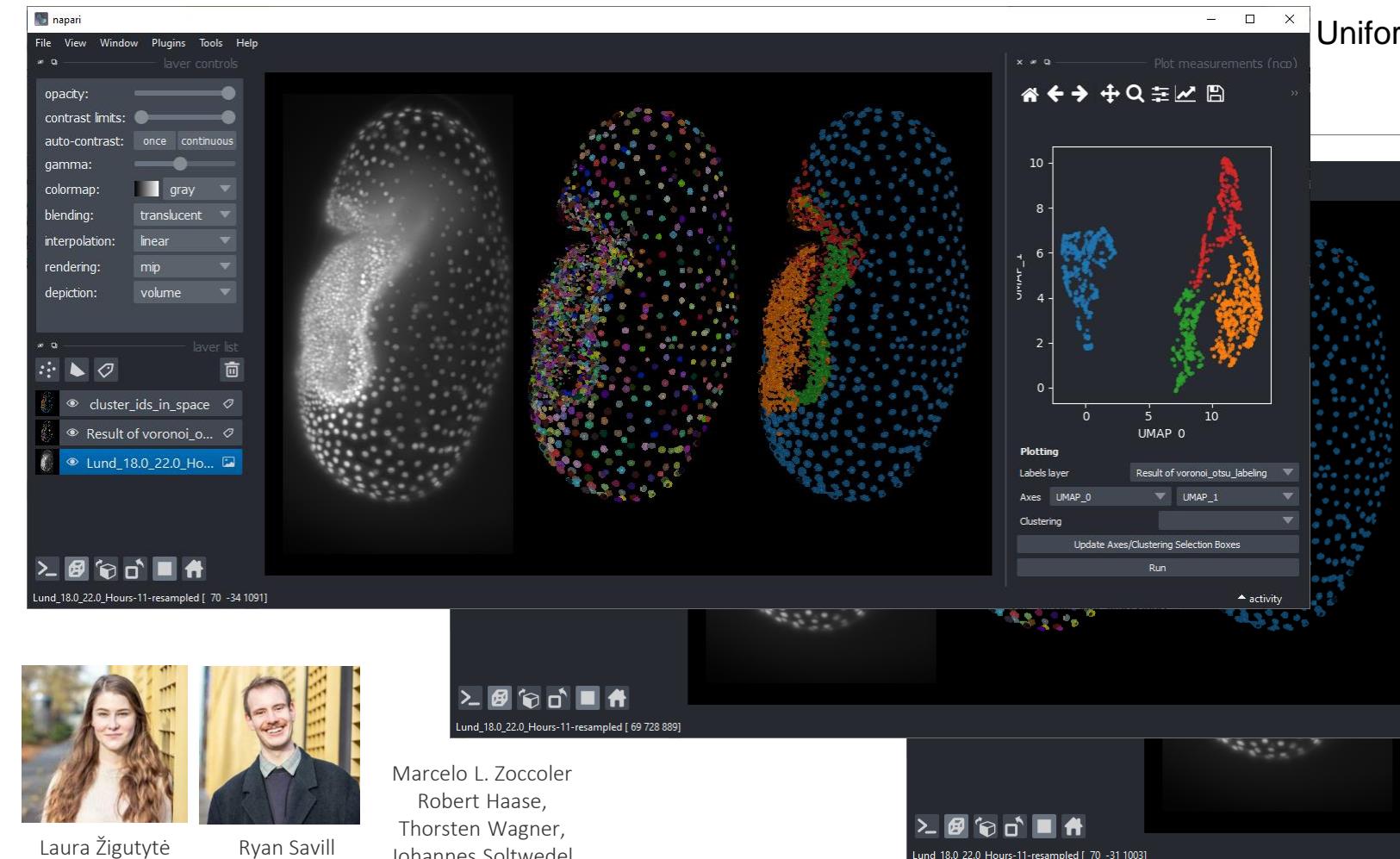
Strength and weaknesses

- Number of clusters needs to be known
- Clusters can not capture more complex topologies
- Based on Euclidian metrics → every new point can be assigned to a cluster



Napari-clusters-plotter plugin

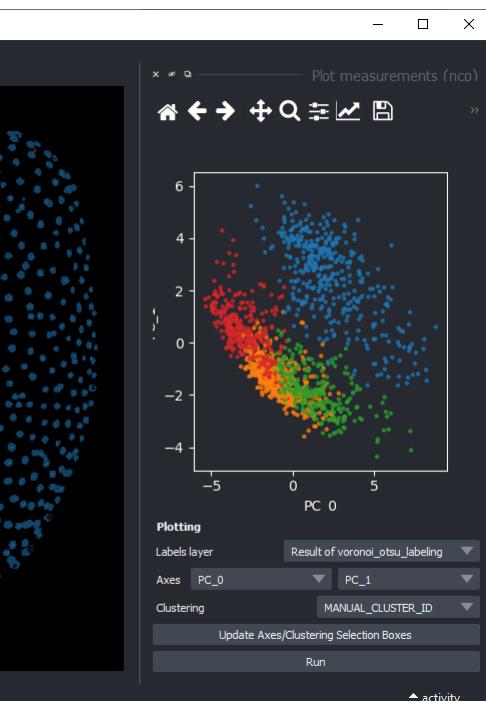
Dimensionality reduction



Uniform manifold approximation and projection (UMAP)

t-distributed stochastic neighbor embedding (t-SNE)

Principal component analysis (PCA)



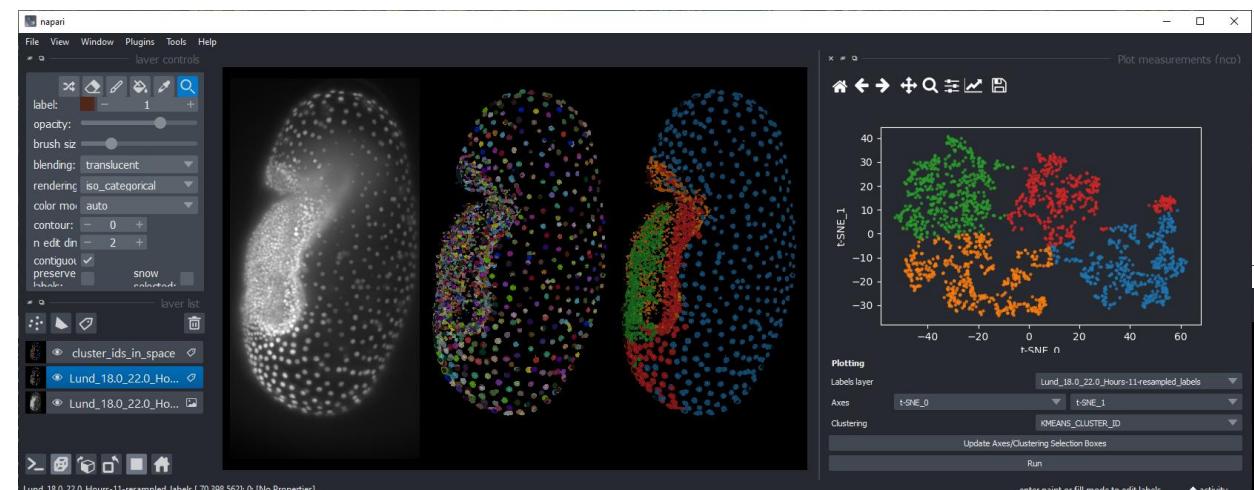
<https://github.com/BiAPoL/napari-clusters-plotter>

Image Data Source: Daniela Vorkel, Myers lab, MPI-CBG/CSBD Dresden

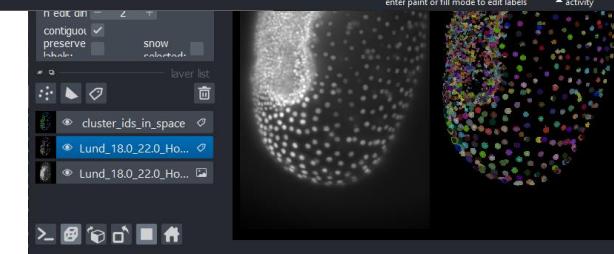
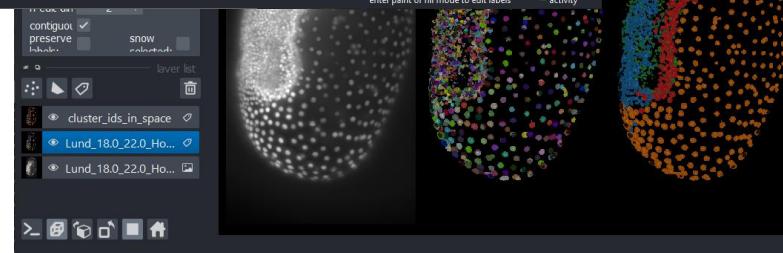
Clustering



PoL
Physics of Life
TU Dresden

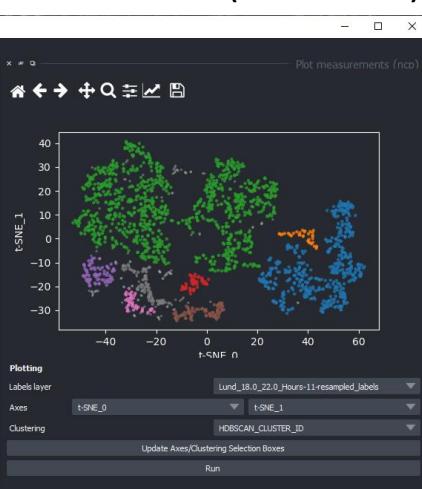


K-means clustering

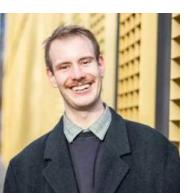


Agglomerative clustering

Hierarchical Density-Based Spatial Clustering of Applications with Noise (HDBSCAN)



Laura Žigutytė
@zigutyte



Ryan Savill
@RyanSavill4

Marcelo L. Zoccoler
Robert Haase,
Thorsten Wagner,
Johannes Soltwedel

@zoccolermarcelo

<https://github.com/BiAPoL/napari-clusters-plotter>

Image Data Source: Daniela Vorkel, Myers lab, MPI-CBG/CSBD Dresden

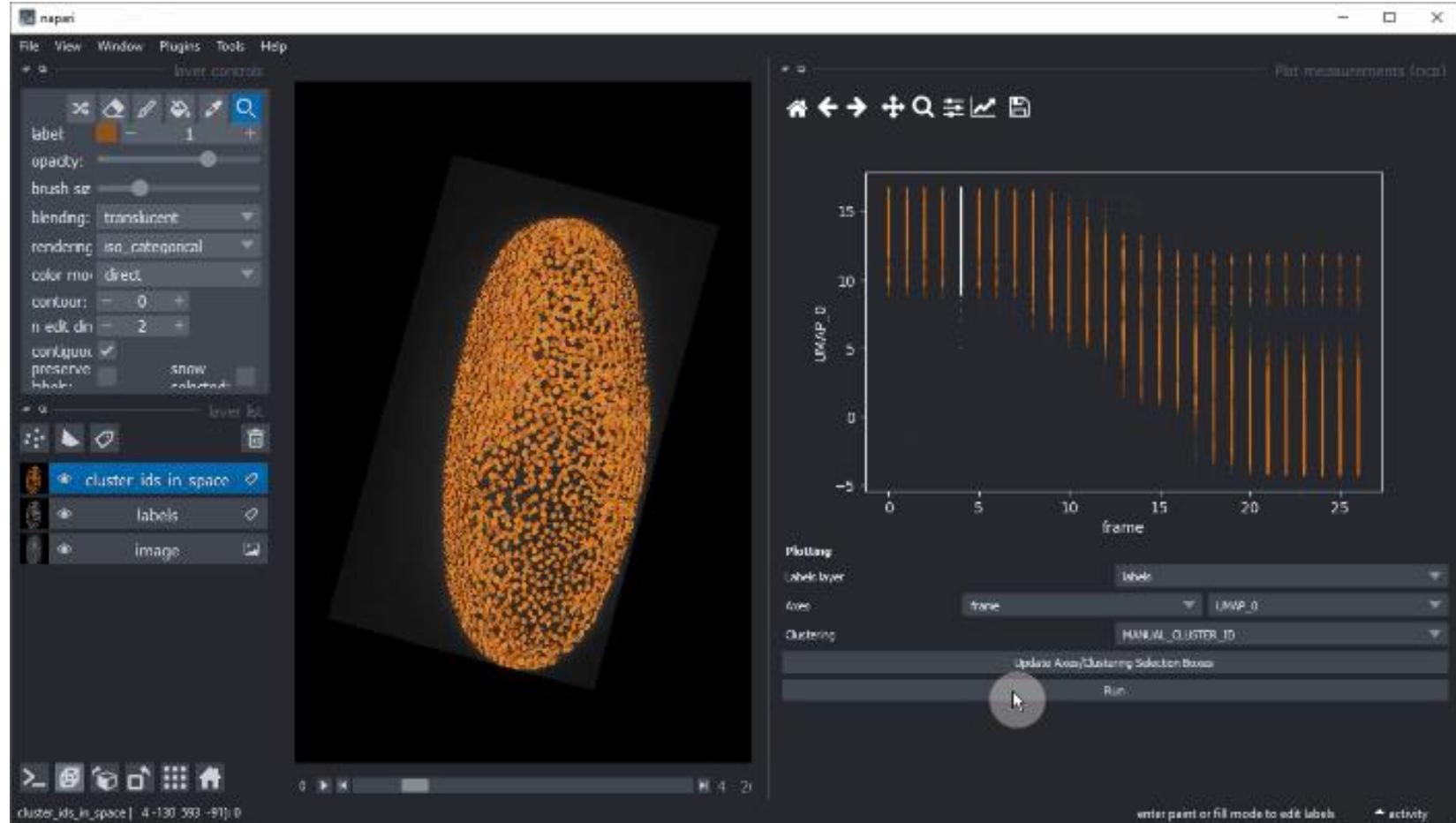
Data Exploration

- ... using interactive clustering



Laura Žigutytė Ryan Savill
@zigutyte @RyanSavill4

Marcelo L. Zoccoler
Robert Haase,
Thorsten Wagner,
Johannes Soltwedel

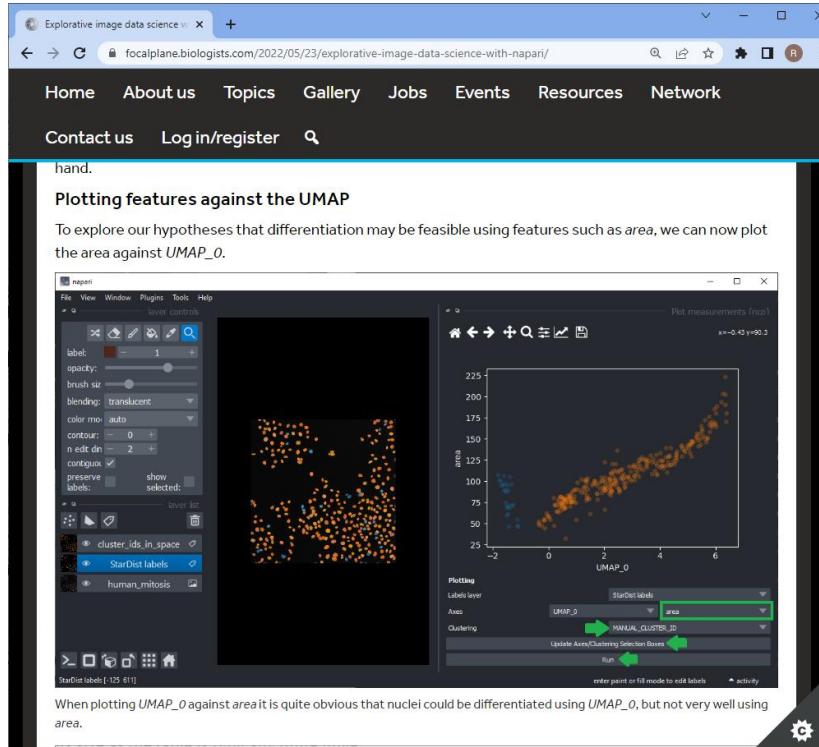


<https://github.com/BiAPoL/napari-clusters-plotter>

Image Data Source: Daniela Vorkel, Myers lab, MPI-CBG/CSBD Dresden

Further reading

- Blog posts on the Focalplane about Unsupervised Machine Learning



<https://focalplane.biologists.com/2022/05/23/explorative-image-data-science-with-napari/>

Exercise

Unsupervised Object Classification

- Use Napari to classify objects (nuclei) without ground-truth

Interactive unsupervised object classification in Napari

In this exercise we will perform Feature Extraction, Dimensionality Reduction with UMAP and Clustering with HDBSCAN to assign objects (nuclei) to different classes in napari. We will use the napari plugin napari-clusters-plotter plugin.

Getting started

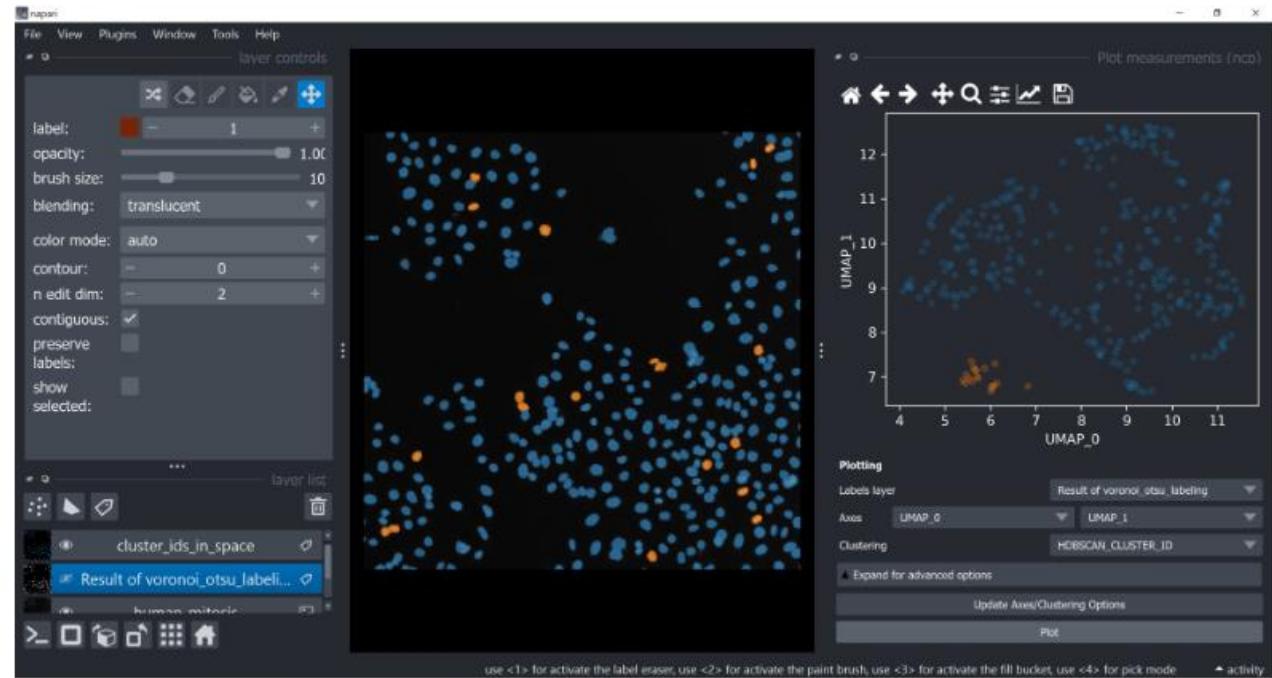
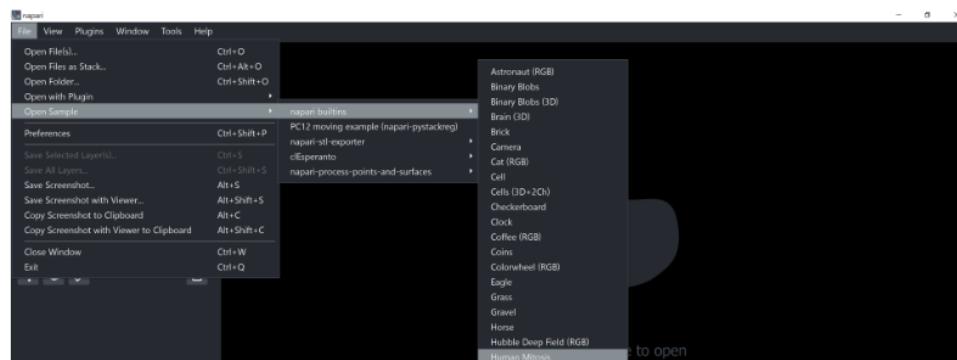
Open a terminal window and activate your conda environment:

```
mamba activate devbio-napari
```

Afterwards, start up Napari:

```
napari
```

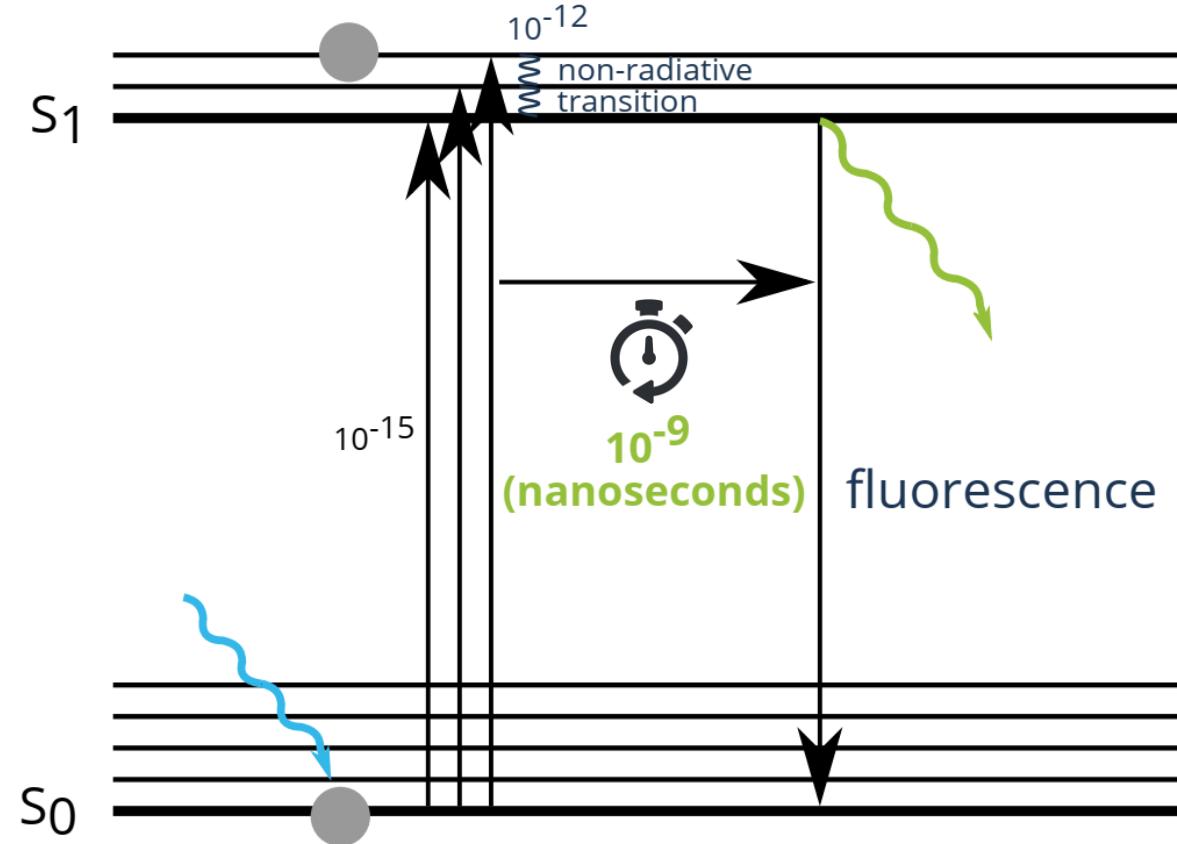
Load the "human-mitosis" example dataset from the menu **File > Open Sample > napari builtins > Human Mitosis**



https://zoccoler.github.io/QM_Course_Bio_Image_Analysis_with_napari_2024/Machine_Learning_with_napari/interactive_unsupervised_object_classification/readme.html

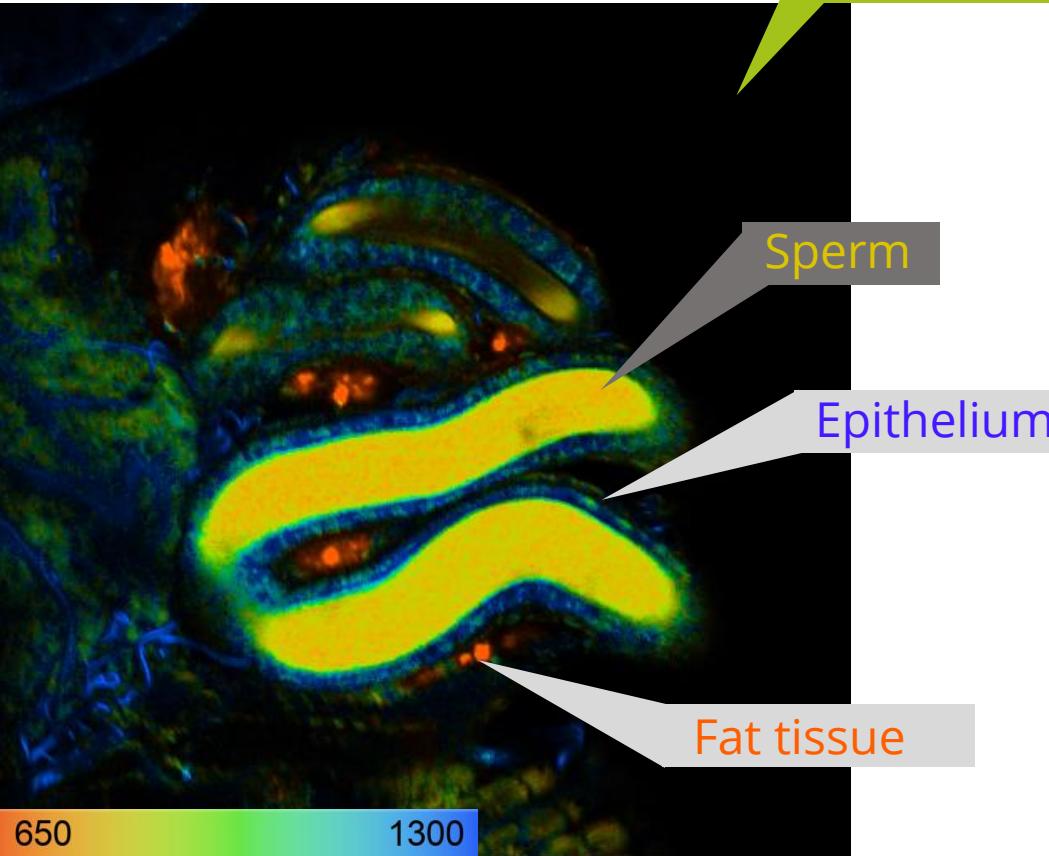
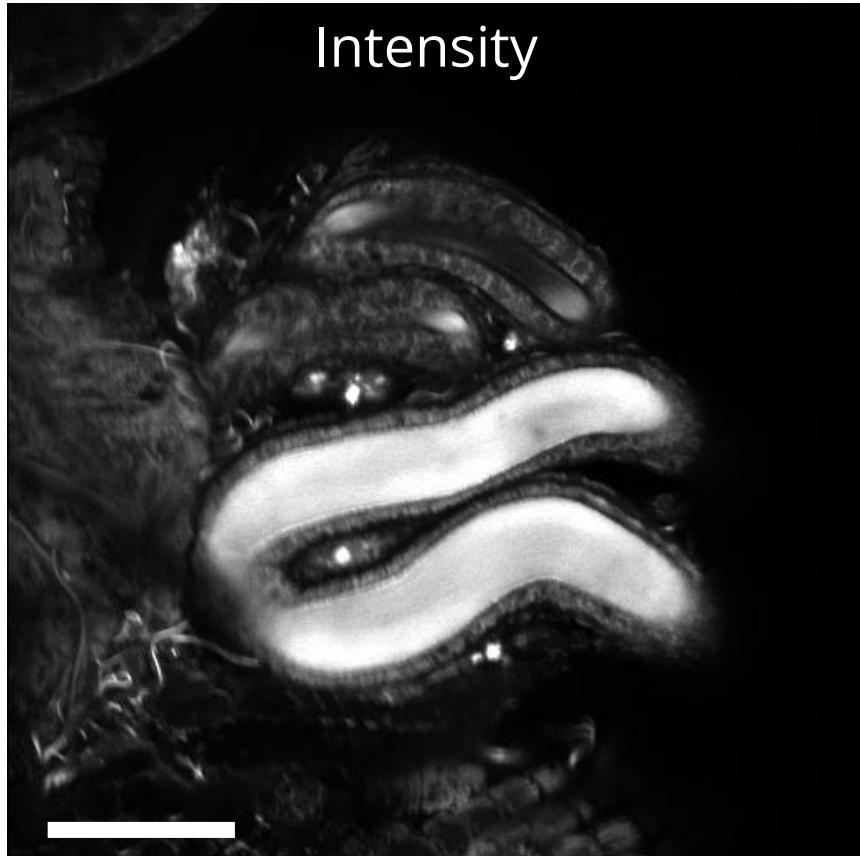
Fluorescence Lifetime Imaging Microscopy

FLIM measures the precise timing of fluorescence





NAD(P)H autofluorescence



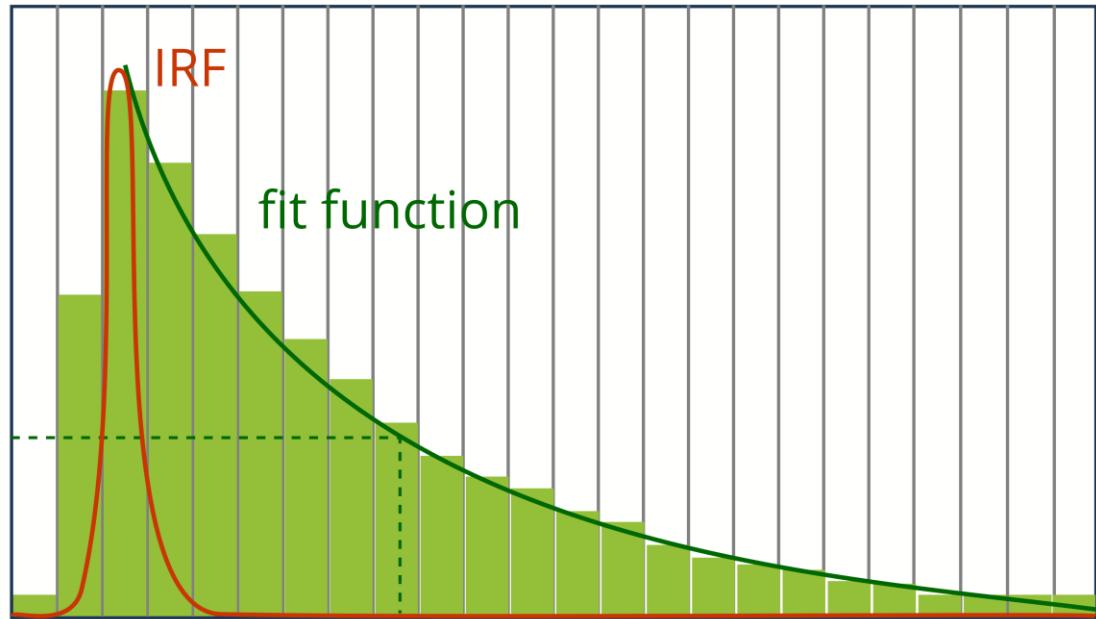
Probe cellular states:

Metabolism using intrinsic NAD(P)H

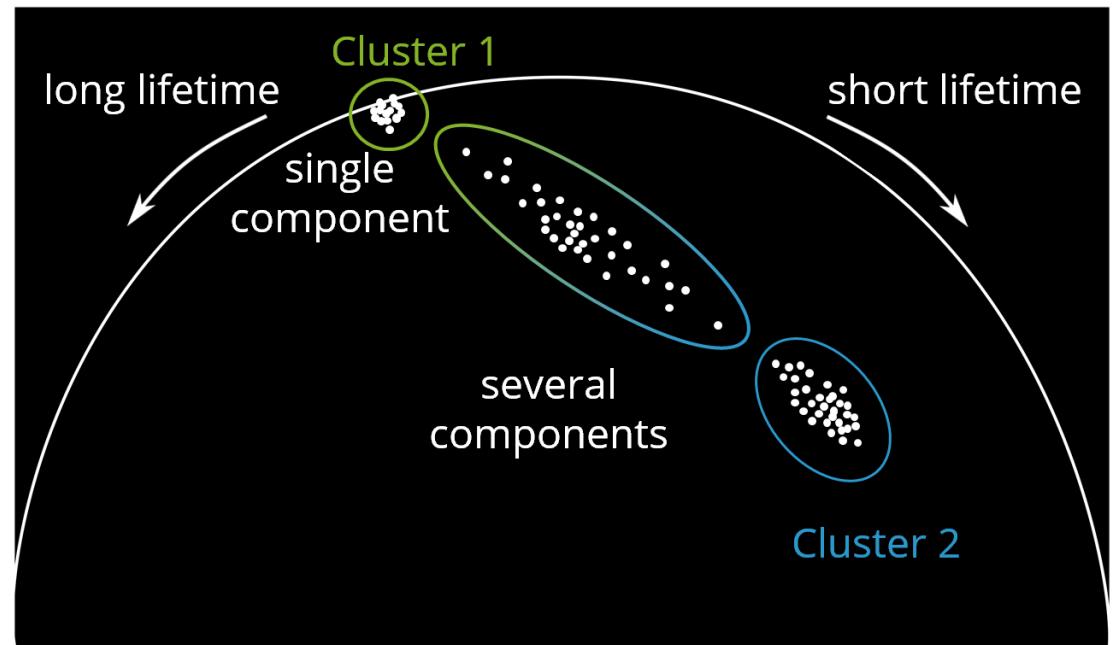
- Seminal receptacle of *Drosophila melanogaster*

An additional dimension of contrast = information

Curve fitting



Phasor plot



Napari-flim-phasor-plotter plugin

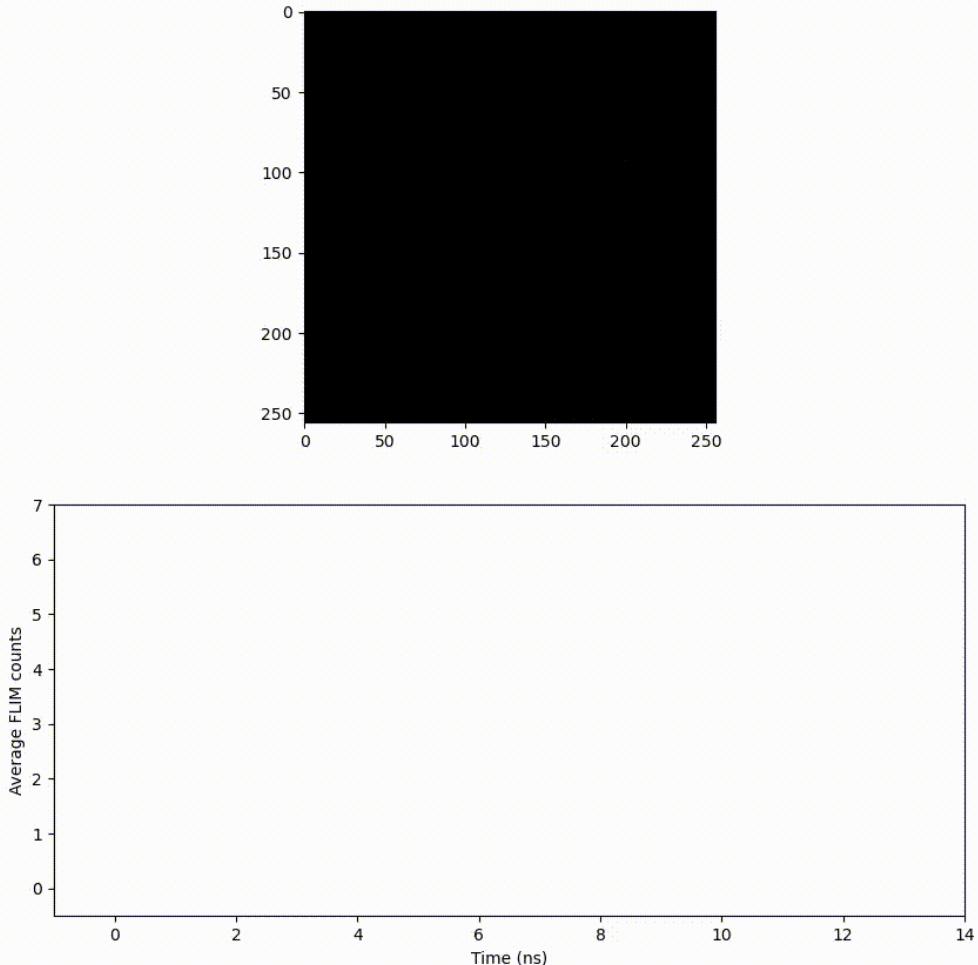
Visualizing FLIM raw data in napari



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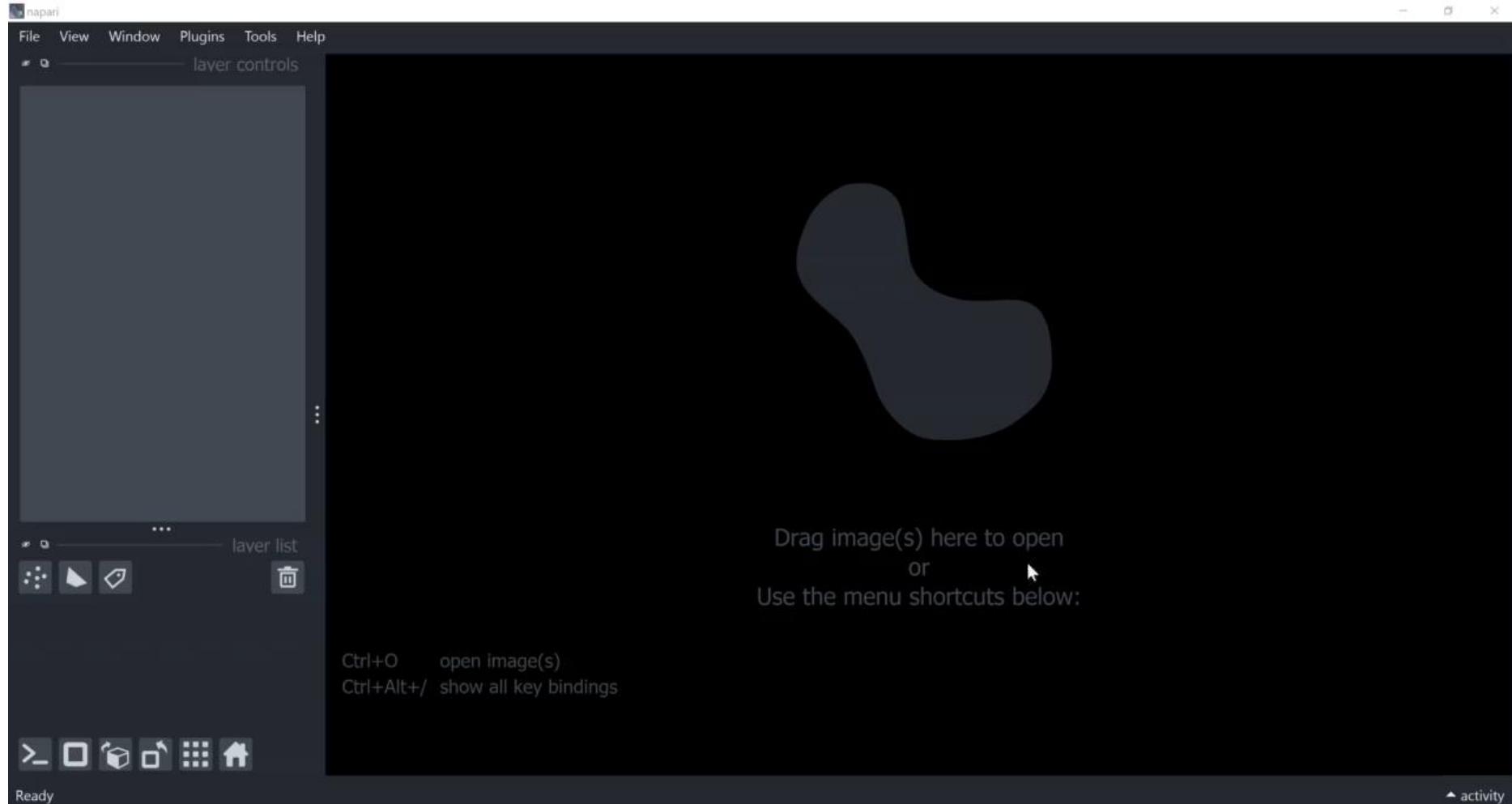
- Hazelnut example



Plugin demonstration with Synthetic Data



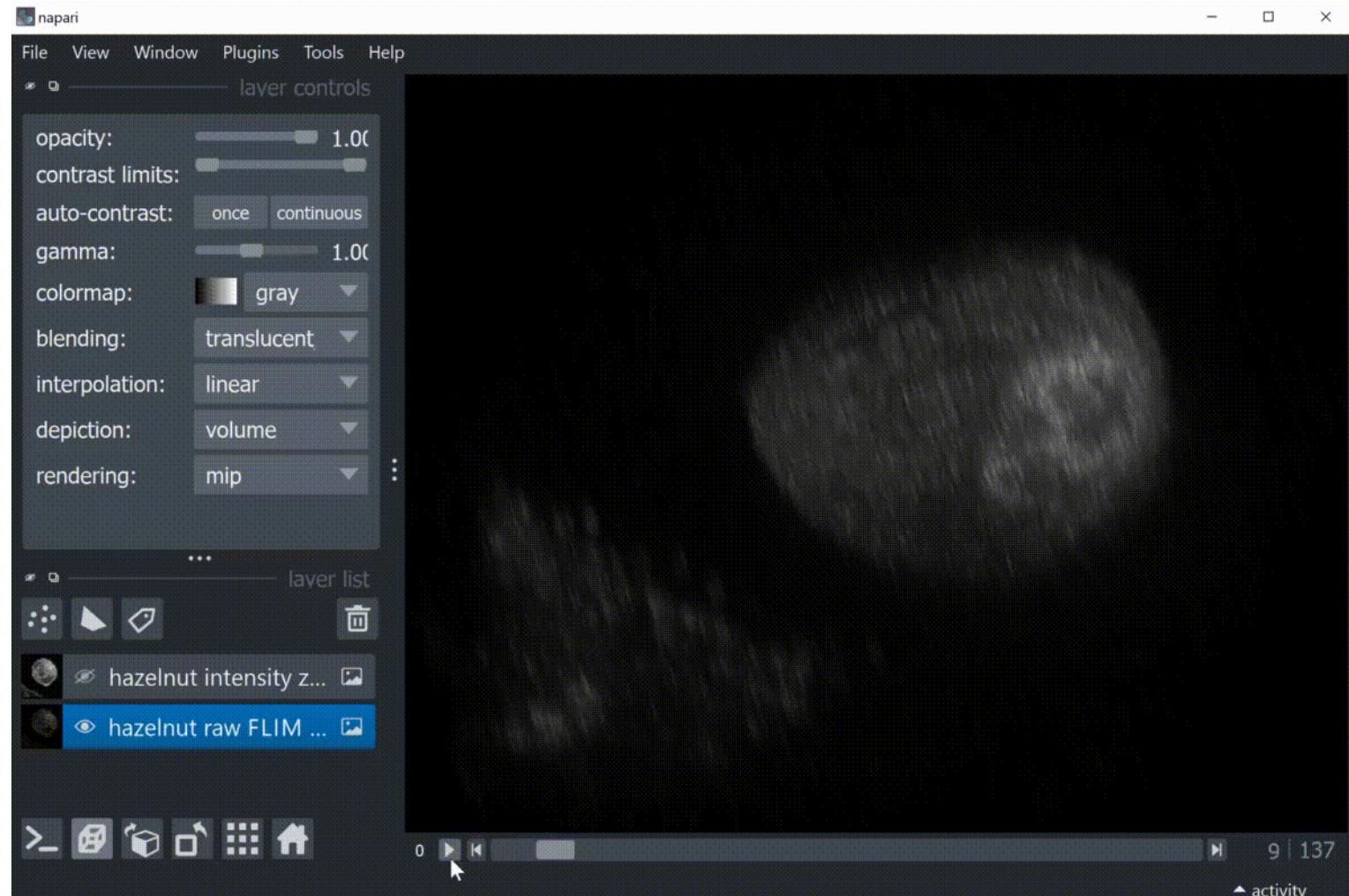
- Lifetime Cat



Data created by
Svetlana Iarovenko
(IMP Vienna)



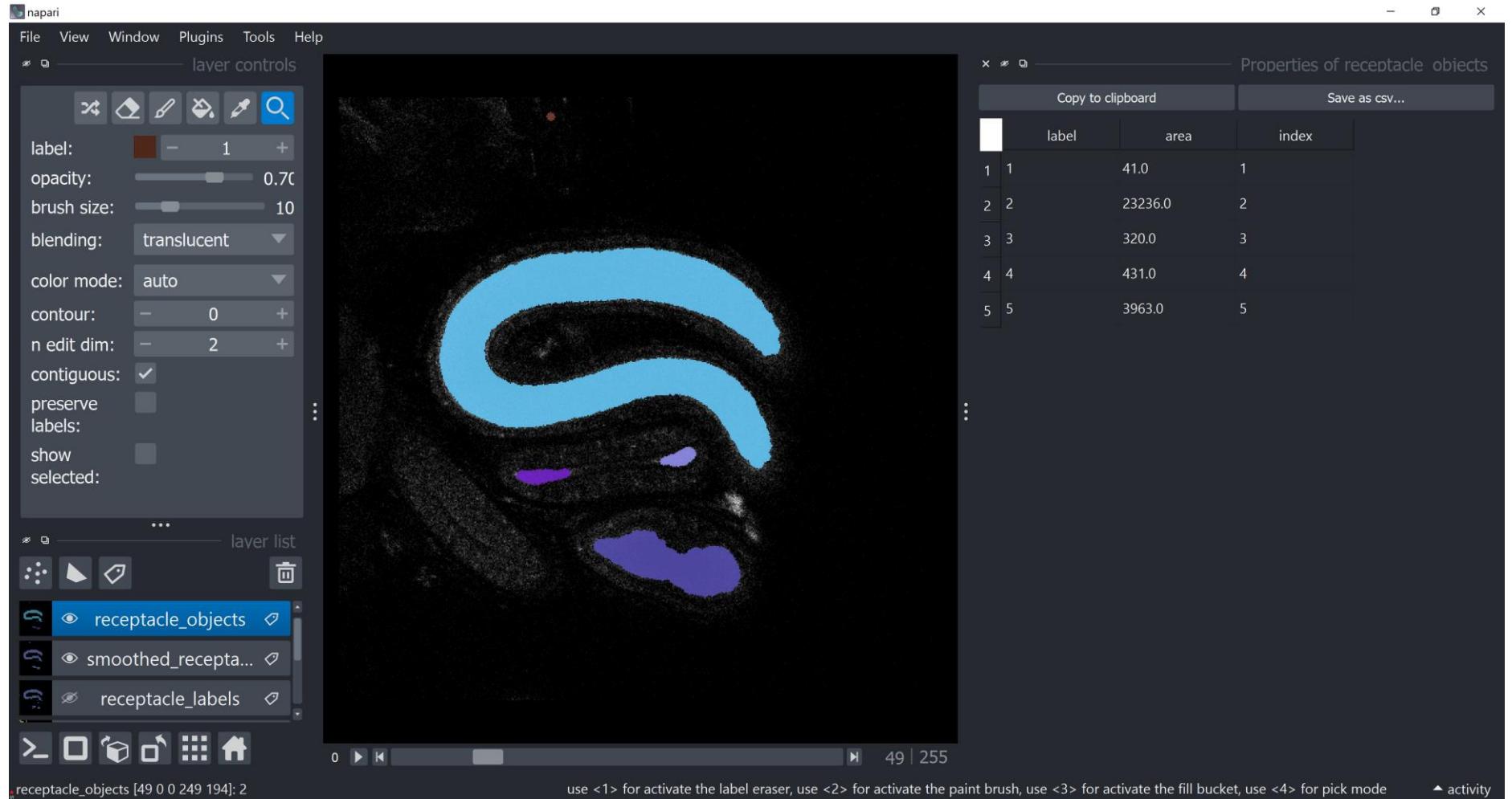
- Hazelnut 3D example



- Seminal receptacle example

Example workflow (under development):

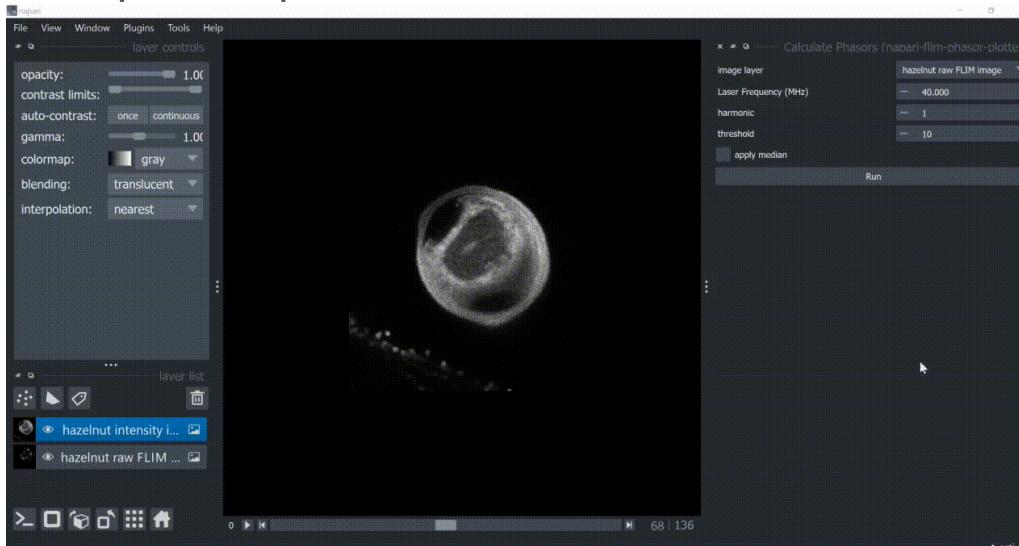
- Generate a Phasor Plot
- Change Phasor Plot display options
- Apply a clustering algorithm to the Phasor Plot (HDBSCAN)
- Extract cluster/class of interest
- Post-processing: apply morphological operations
- Perform instance segmentation
- Extract Features



Exercise

Segment another example image with the phasor plot

- Open the hazelnut 2D, hazelnut 3D or the synthetic lifetime cat sample data
- Calculate the phasor plot
- Select clusters and check the segmentation results
- Re-calculate the phasor plot exploring other parameters (median, harmonic, threshold) to improve clusters display in the phasor plot.



https://zoccoler.github.io/QM_Course_Bio_I mage_Analysis_with_napari_2024/Machine_Learning_with_napari/FLIM/readme.html

Acknowledgements



Networks



Funding



**Chan
Zuckerberg
Initiative** 

<https://physics-of-life.tu-dresden.de/bia>

