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Using napari from Jupyter notebooks

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With material from

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“Classic” software vs. notebooks

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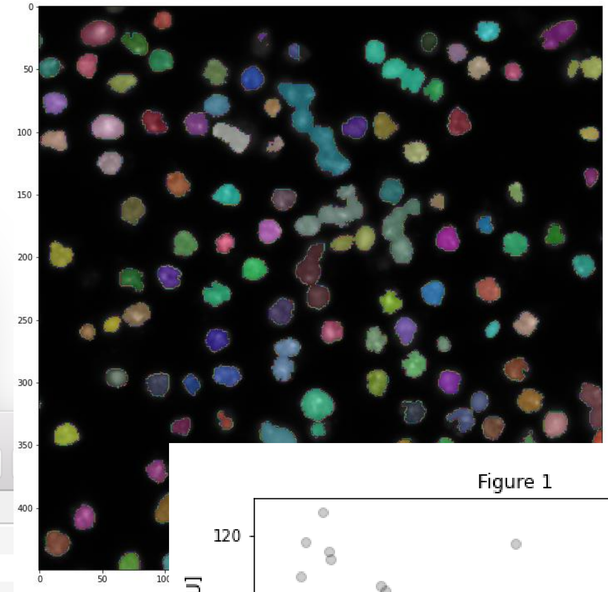
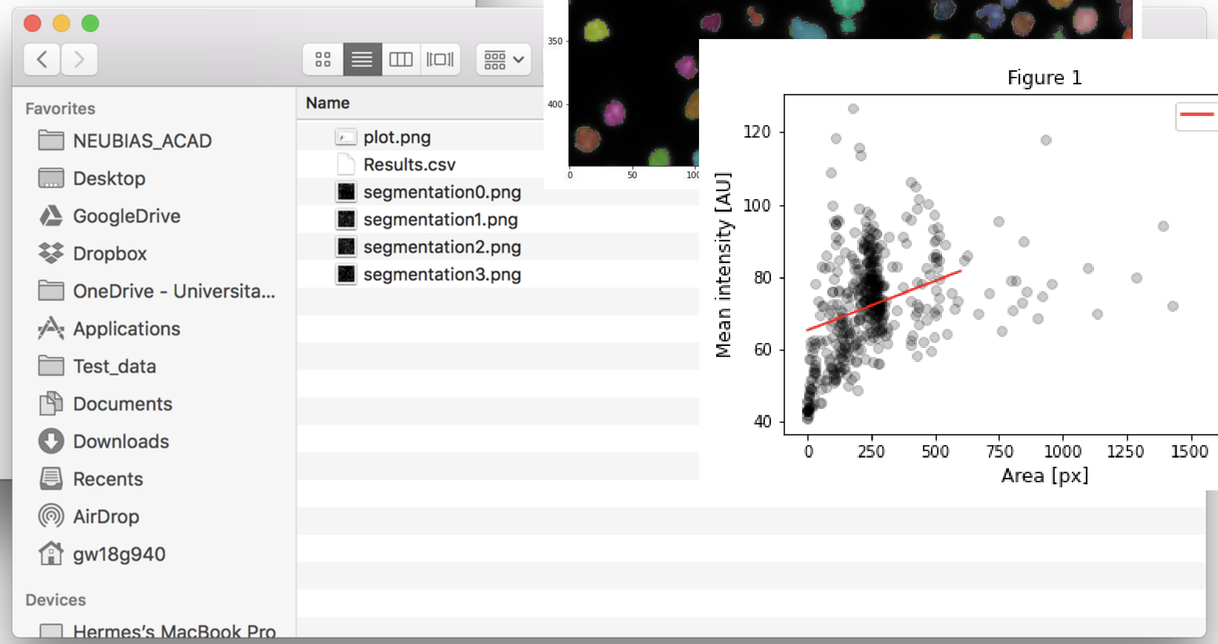
course_functions.py

```
import skimage.morphology
import skimage.filters
import numpy as np
from skimage.measure import label, regionprops_table
import matplotlib

def detect_nuclei(image, si

    # filtering
    image = skimage.filters
    # local thresholding
    image_local_threshold =
    image_local = image > i
    # remove tiny features
    image_local_open = skim
    # label image
    image_labeled = label(i
    # analyze regions
    our_regions = regionpro
    # create a new mask wit
    newimage = np.zeros(ima
    # fill in using region
    for x in range(len(our_
        if our_regions['are
            newimage[our_re

    return newimage
```

gw18g940 — -bash — 72×21

```
Last login: Thu Apr 30 10:41:20 on ttys002
(base) Hermess-MacBook-Pro:~ gw18g940$ python course_functions.py
```





“Classic” software vs. notebooks

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Code divided in parts

Dynamic: easy to test

Rich output: processing + visualisation + analysis in one place

Code + formatted text: easy documentation

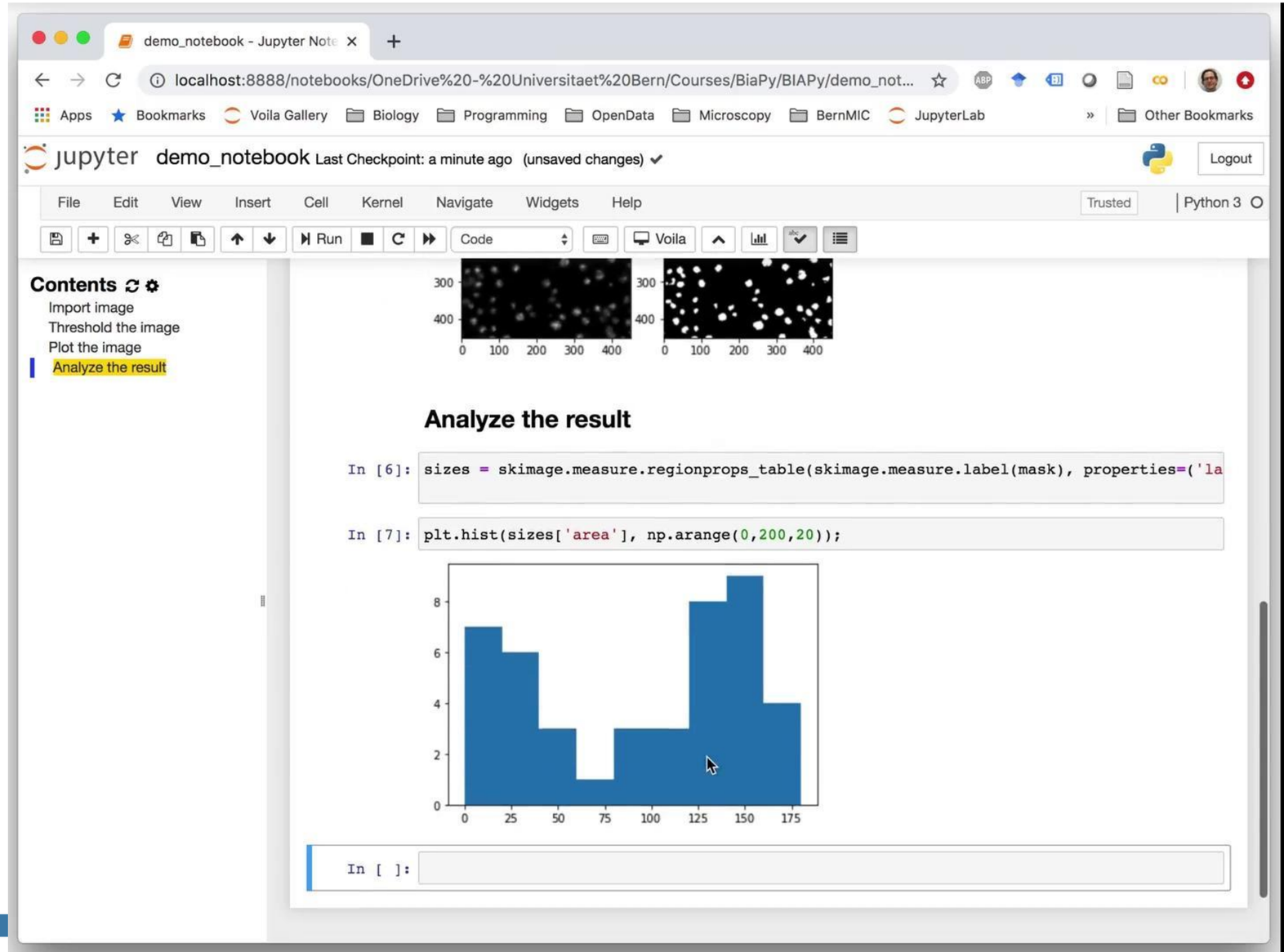

Illustration: load an image, threshold it, analyze object size

What is a jupyter notebook?

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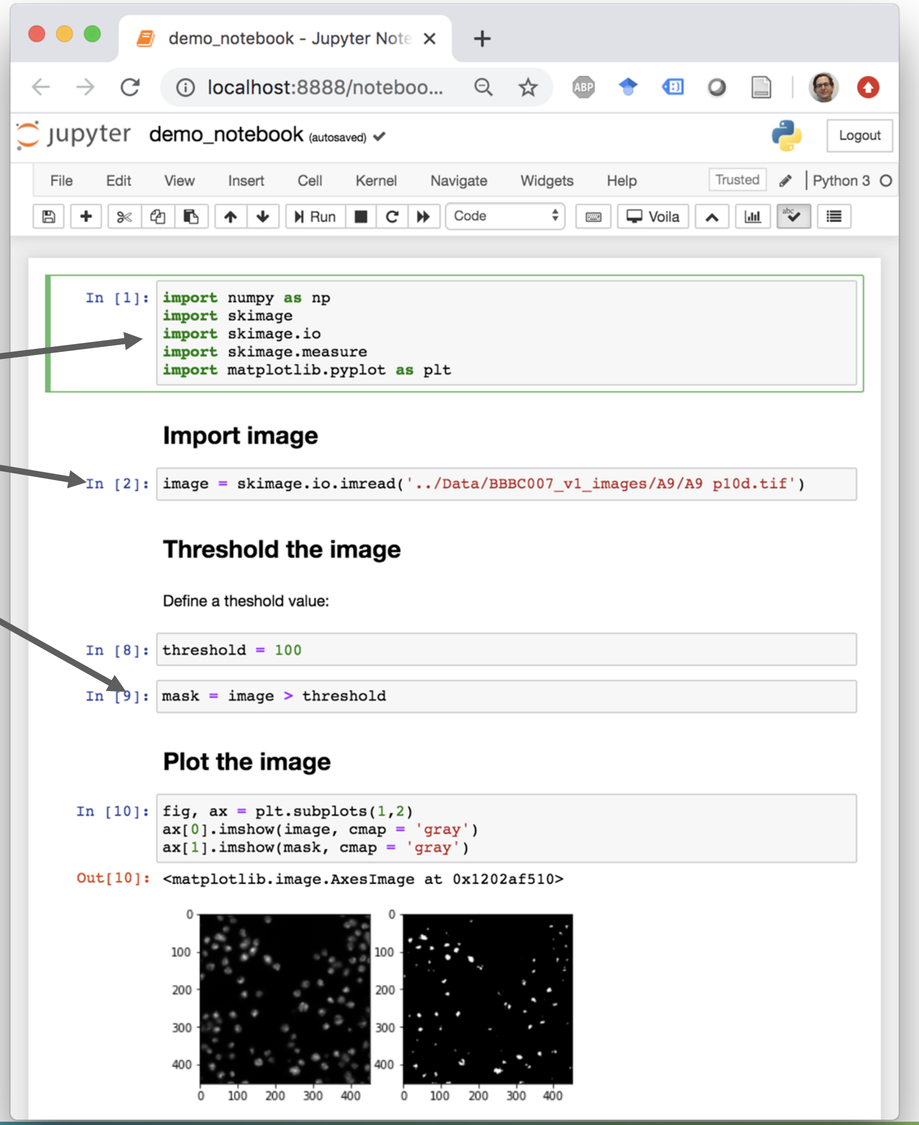
A text file (easily sent around)

Rendered by Jupyter in the browser

Split into sections called cells



What is a jupyter notebook?

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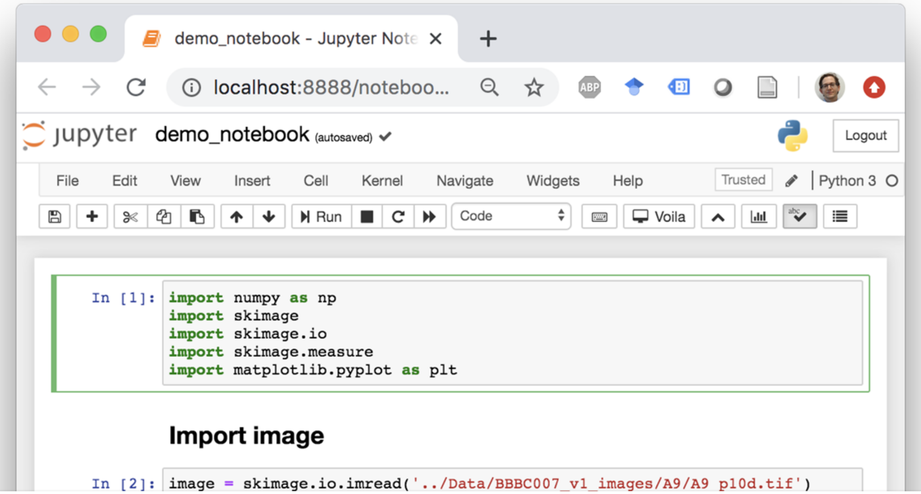
A text file (easily sent around)

Rendered by Jupyter in the browser

Split into sections called cells

Cells can contain:

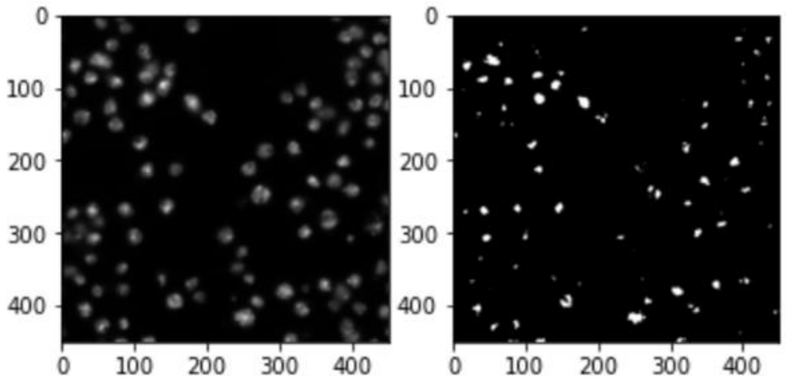
- Code
- Formatted text
- Rich output



In [2]: imag

In [10]:
```
fig, ax = plt.subplots(1,2)
ax[0].imshow(image, cmap = 'gray')
ax[1].imshow(mask, cmap = 'gray')
```

Out[10]: <matplotlib.image.AxesImage at 0x1202af510>



Why using notebooks?

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Documenting (for your-(future)-self and for others) and enhanced reproducibility

"First, we applied a Gaussian filter from scikit-image with sigma = 1. Then, we applied another Gaussian filter to the original image with sigma = 10. After that, we subtracted the first result from the second..."

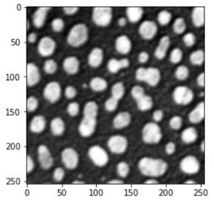
Image Processing Workflow

```
[6]: from skimage.filters import gaussian
     from skimage.io import imread
     import matplotlib.pyplot as plt

[5]: image = imread(r'..\data\image.tif')

[7]: plt.imshow(image, cmap = 'gray')

[7]: <matplotlib.image.AxesImage at 0x1900ad27b50>
```



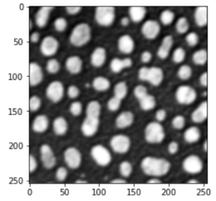
1. Apply a gaussian filter with a small sigma

We used `sigma = 1` in this example.

```
[14]: image_gauss1 = gaussian(image, sigma = 1)

[15]: plt.imshow(image_gauss1, cmap = 'gray')

[15]: <matplotlib.image.AxesImage at 0x1900bf56670>
```



2. Apply a gaussian filter with a large sigma

We used `sigma = 10` in this example.

```
[16]: image_gauss2 = gaussian(image, sigma = 10)

[17]: plt.imshow(image_gauss2, cmap = 'gray')

[17]: <matplotlib.image.AxesImage at 0x1900bfbd5b0>
```

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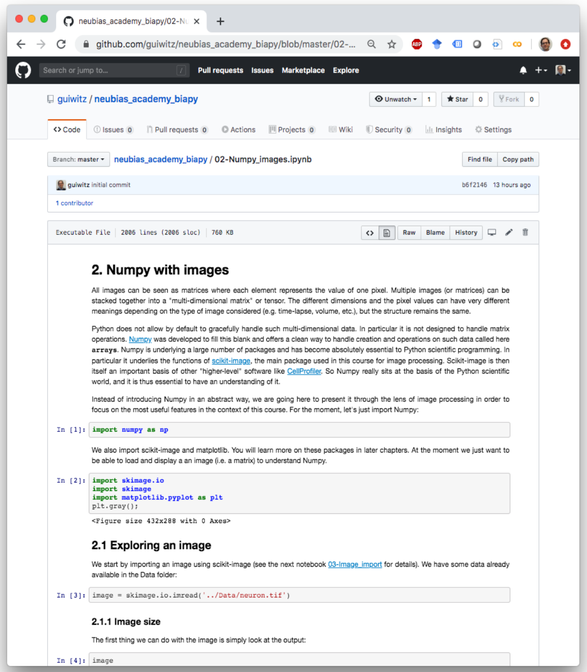
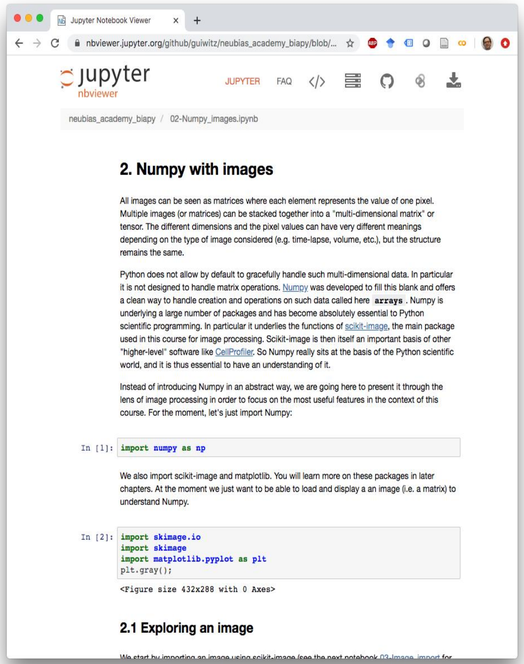
Sharing

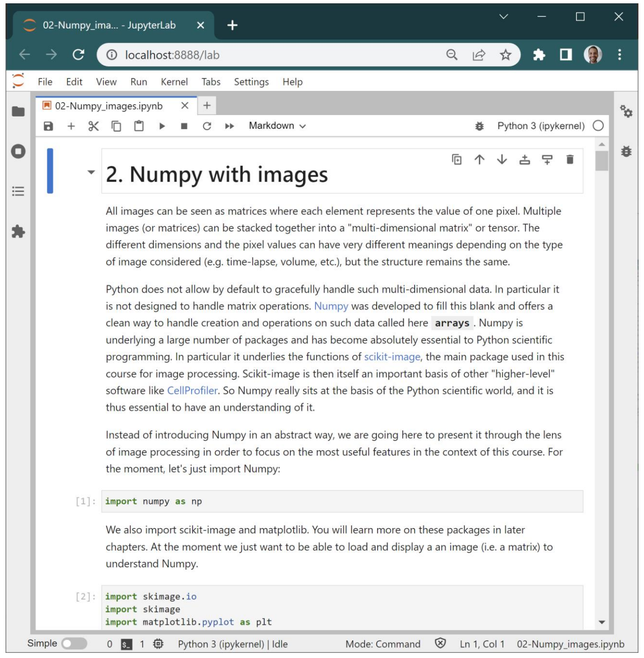
- Send a single file with code, intermediary outputs and rich text explanations



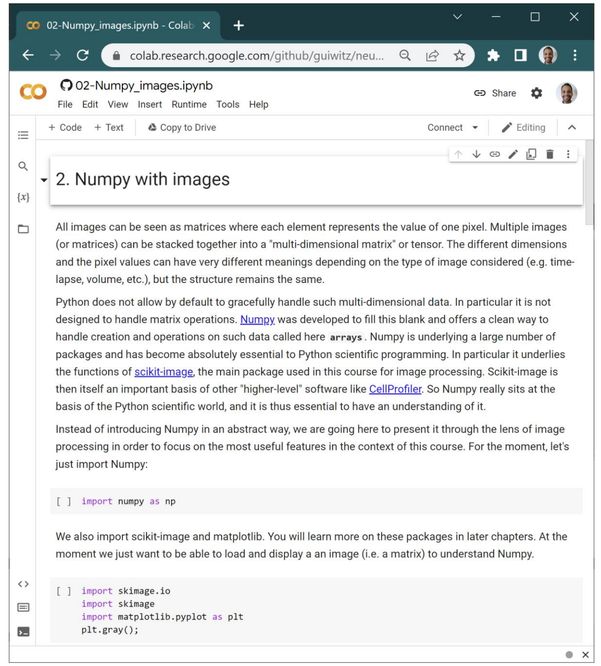
Github rendering



Nbviewer rendering



Jupyter lab (local or Binder)



Google Colab

Why using notebooks?

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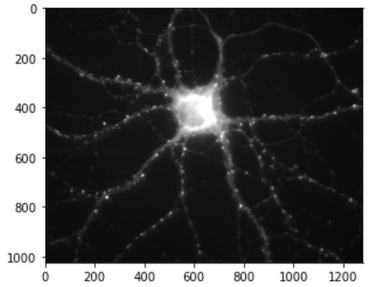
Teaching

- Small blocks of code with intermediary results are easier to understand than scripts that spit tons of outputs in sequence

This means that we have an image of 1024 rows and 1280 columns. We can now look at it using matplotlib (see next chapter for details) using the `plt.imshow()` function:

```
[6]: plt.imshow(image);
```



2.1.2 Image type

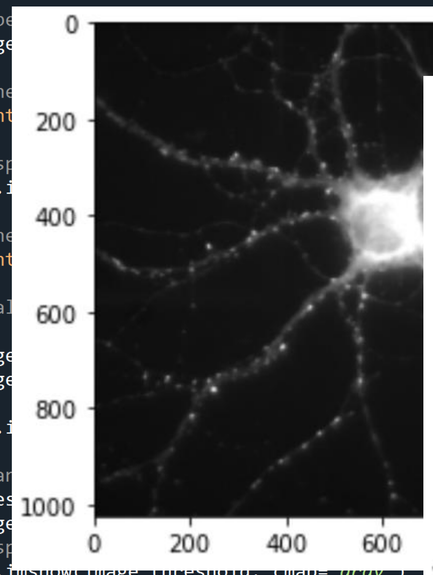
```
[7]: image
```

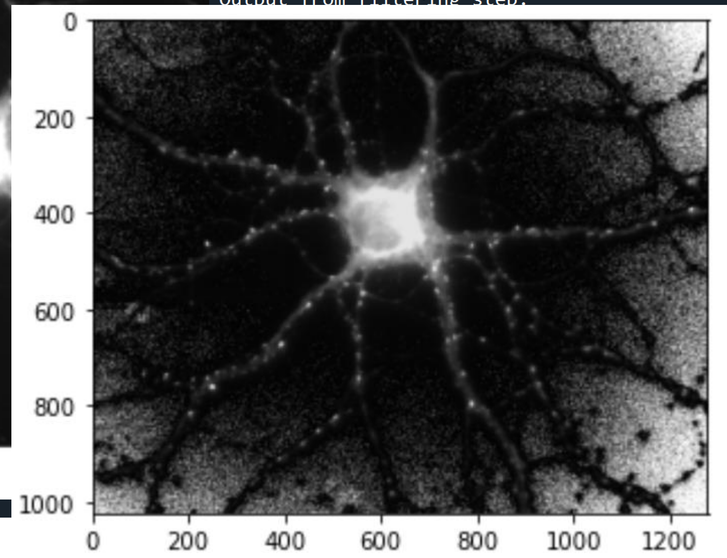
```
[7]: array([[32, 31, 31, ..., 18, 20, 22],
       [27, 24, 25, ..., 24, 24, 23],
       [26, 25, 25, ..., 17, 19, 20],
       ...,
       [25, 23, 24, ..., 19, 23, 23],
       [25, 25, 25, ..., 19, 18, 19],
       [26, 21, 23, ..., 19, 18, 22]], dtype=uint8)
```

In the output above we see that we have one additional piece of information: the array has `dtype`

```
4  import numpy as np
5  import skimage.io
6  import skimage
7  import matplotlib.pyplot as plt
8  plt.gray();
9
10 # Ope
11 image
12
13 # Che
14 print
15
16 #Disp
17 plt.i
18
19 # Che
20 print
21
22 # Cal
23
24 image
25 image
26
27 plt.i
28
29 # Mar
30 thres
31 image
32 #Disp
33 plt.imshow(image_threshold, cmap='gray')
```

```
Pre-processing ouput: [[ 4 15  5 ... 69 83 86]
 [ 5 10  8 ... 69 65 91]
 [ 9  9  7 ... 42 67 73]
 ...
 [ 8  8 13 ... 12 28 51]
 [ 6  6 10 ... 21 21 49]
 [ 9  6  9 ... 10 19 44]]
Image type: uint8
Model accuracy: 98%
Output from filtering step:
```





Why using notebooks?

Keep all the benefits from using code:

- Batch processing

- Running python functions/tools that do not have UI

Why using notebooks with napari?

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- Easy data interaction and visualization with napari:
  - Great for visualizing 3D (and more) data
  - Each processing step result can be displayed as a separate layer
- Data annotation

Example: Trying out a workflow in napari

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1. Start napari from the command line

2. Open an image

3. Establish a segmentation workflow

What were the steps I did again?

Scripting napari in notebooks

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Start napari from a jupyter notebook

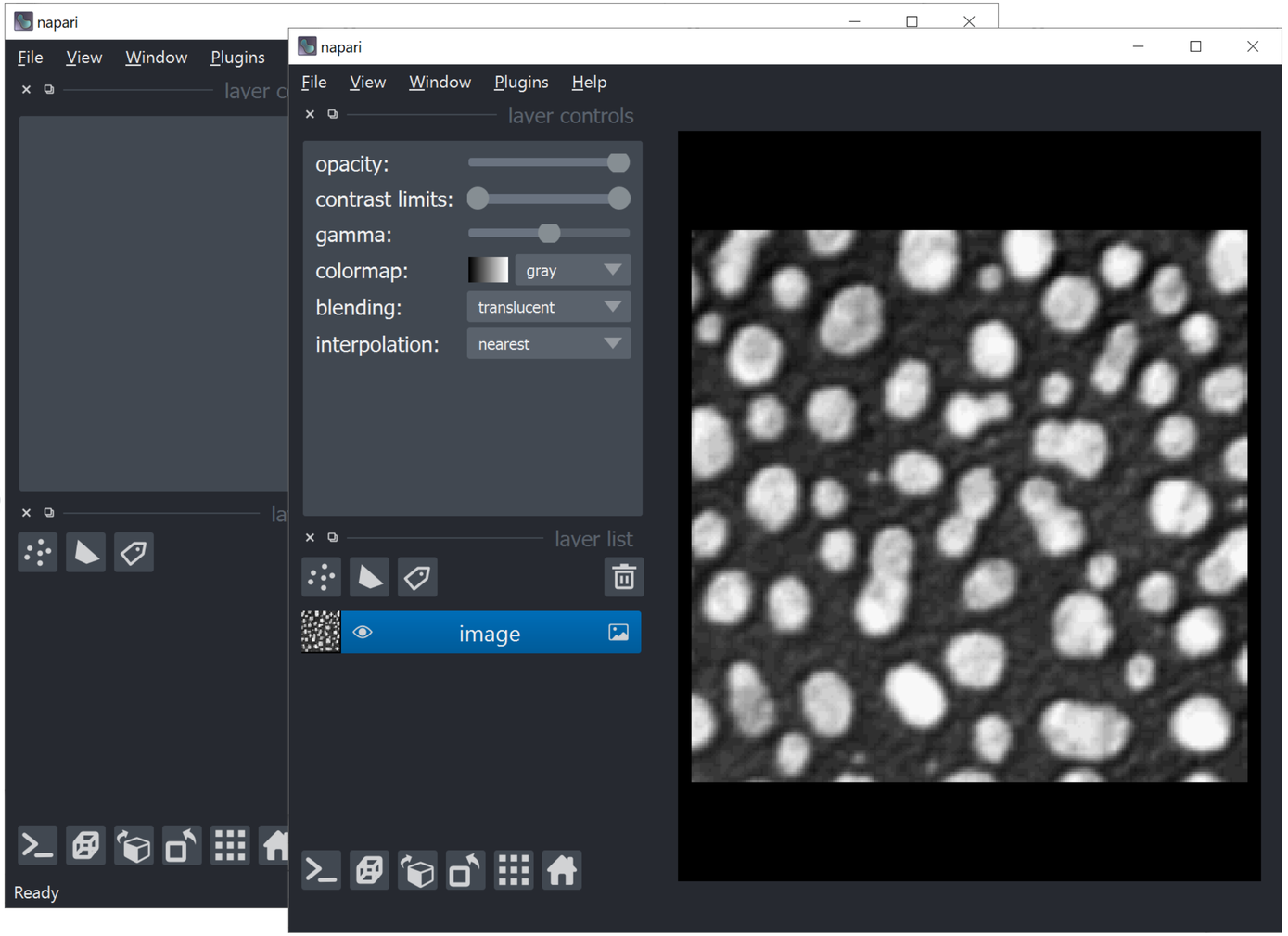
```
import napari

# Create an empty viewer
viewer = napari.Viewer()
```

viewer.add_image(image, name = ‘image’)

Load image from notebook to napari (and back): flexibility!

image = viewer.layers[‘image’].data



Scripting napari in notebooks

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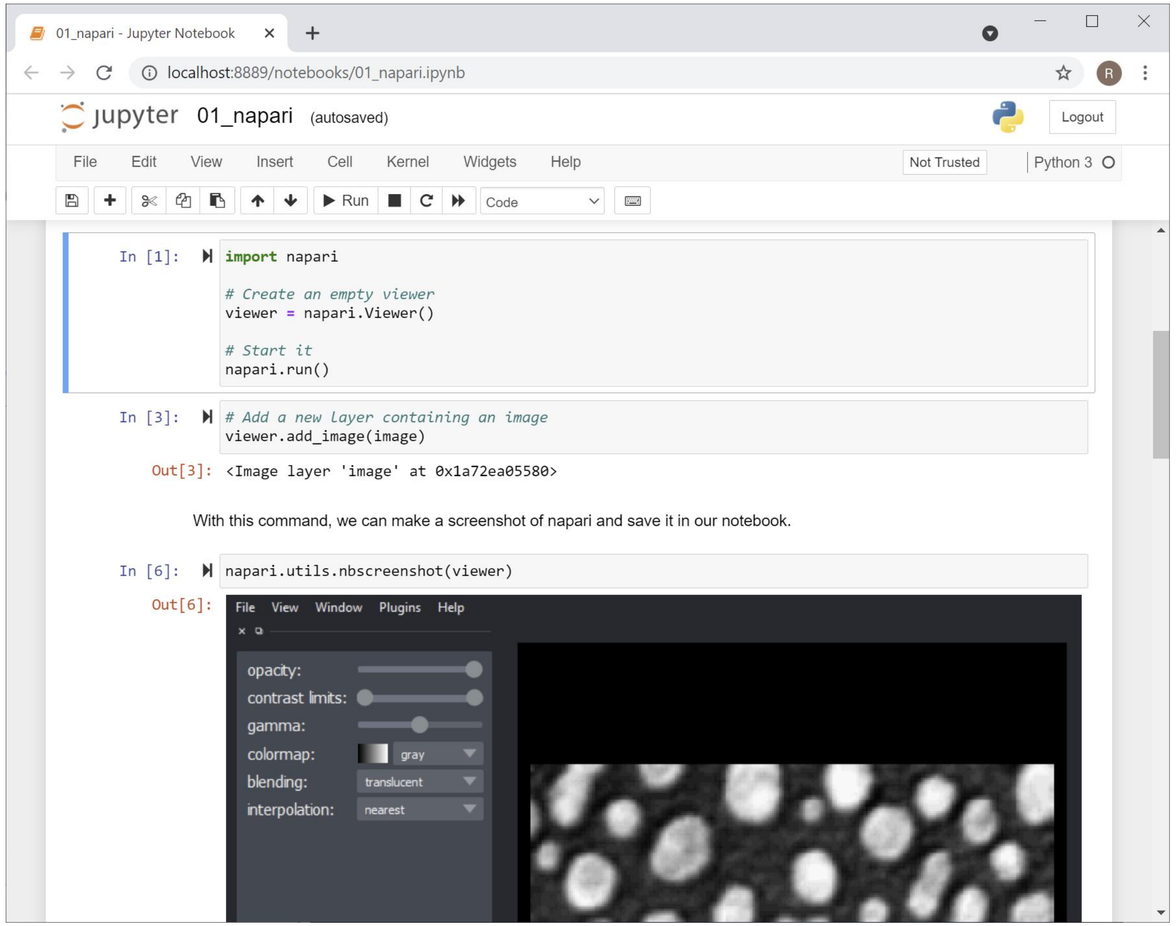
Make screenshots from napari and put them in your jupter notebook

```
napari.utils.nbscreenshot(viewer)
```



Scripting napari in notebooks

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- **Add layers to napari to visualize intermediate processing results on top of each other or side by side.**
- **Change layer visualization within napari…**

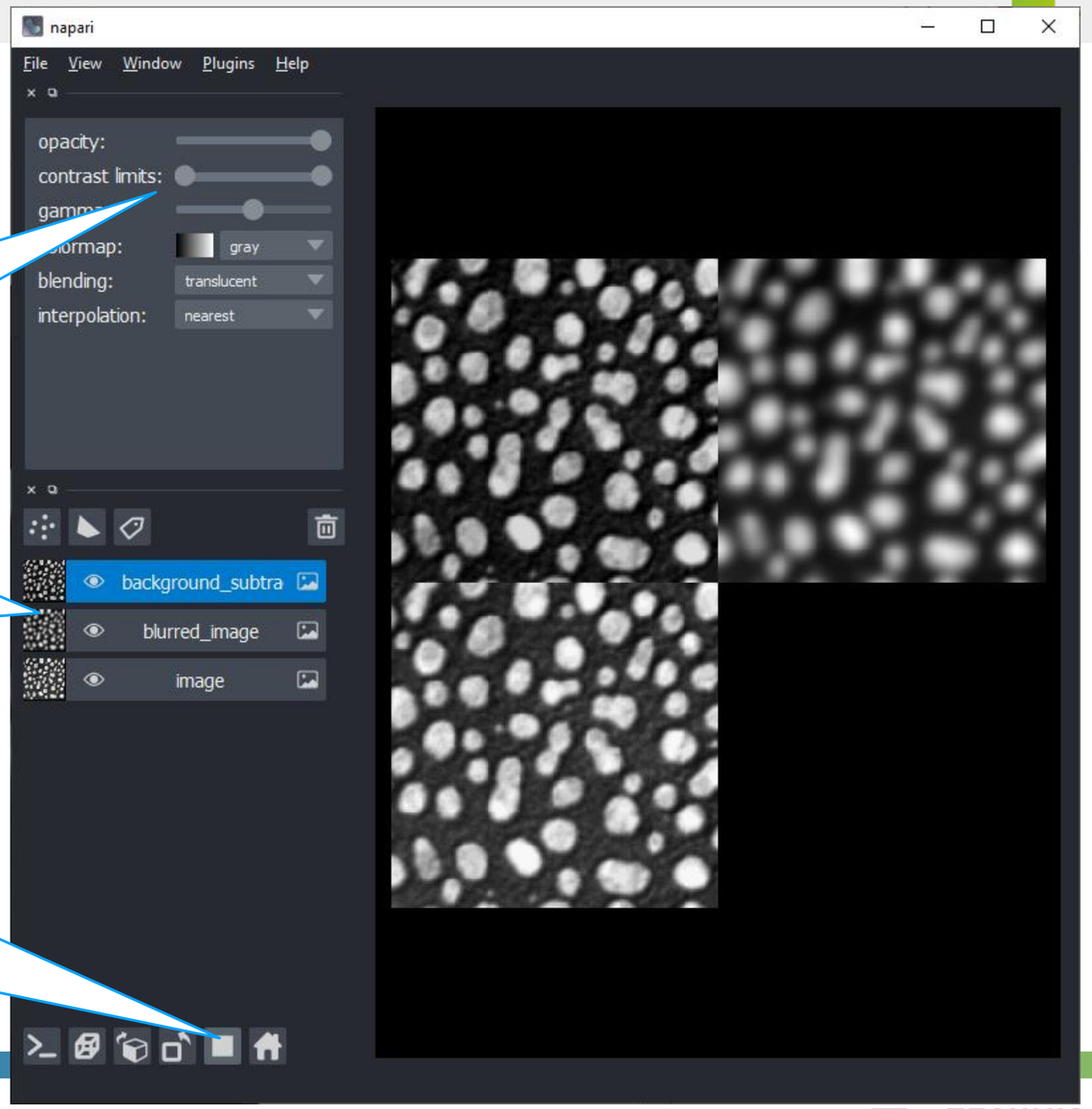
… or via code in a jupyter notebook:

```
viewer.layers[0].contrast_limits
```

```
[0, 255]
```

1. Access the viewer
2. Access the layers
3. Choose a layer (by index or name)
4. “Press TAB” and check out available properties

```
viewer.layers[0].contrast_limits = [30,170]
```



Change Brightness and contrast here

Toggle visualization of layers here

Gallery view

Visualizing image segmentation

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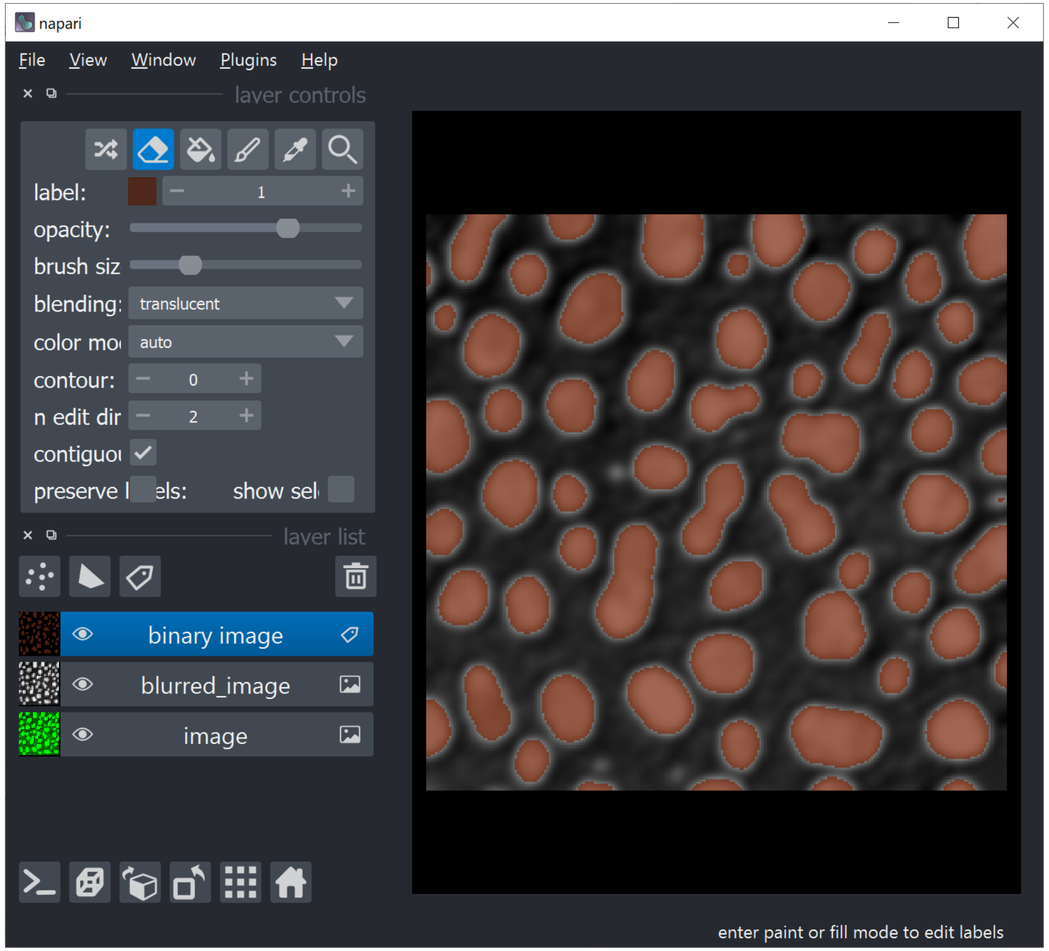
Binary images and label images visualized as label layers

```
from skimage.filters import threshold_otsu
threshold = threshold_otsu(blurred_image)
binary_image = blurred_image > threshold

# Add a new labels layer containing an image
viewer.add_labels(binary_image,
                  name="binary image")
```

Name your layers to keep track of what they contain



Visualizing image segmentation

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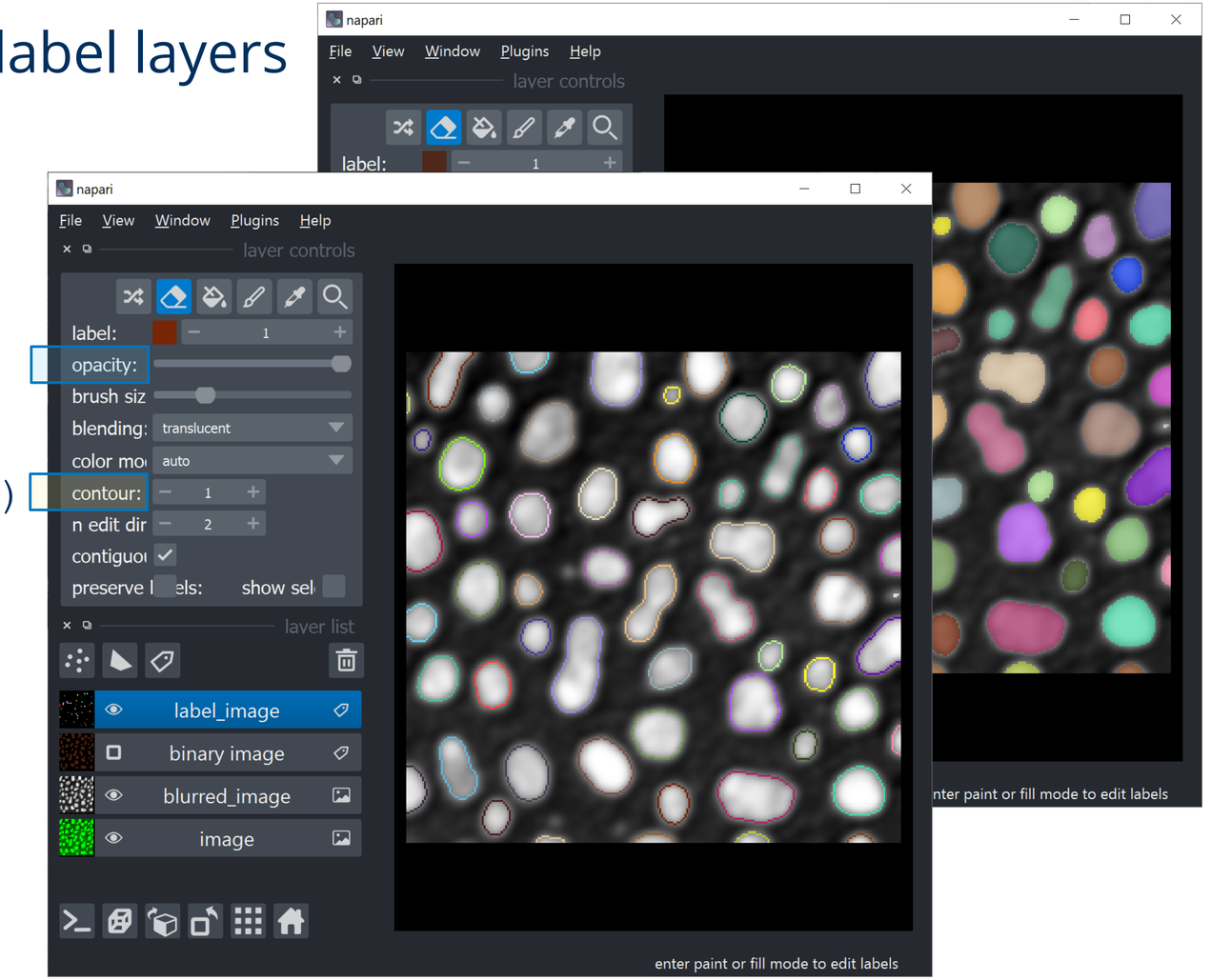
Binary images and label images visualized as label layers

```
from skimage.measure import label
label_image = label(binary_image)

# add labels to viewer
label_layer = viewer.add_labels(label_image)
```



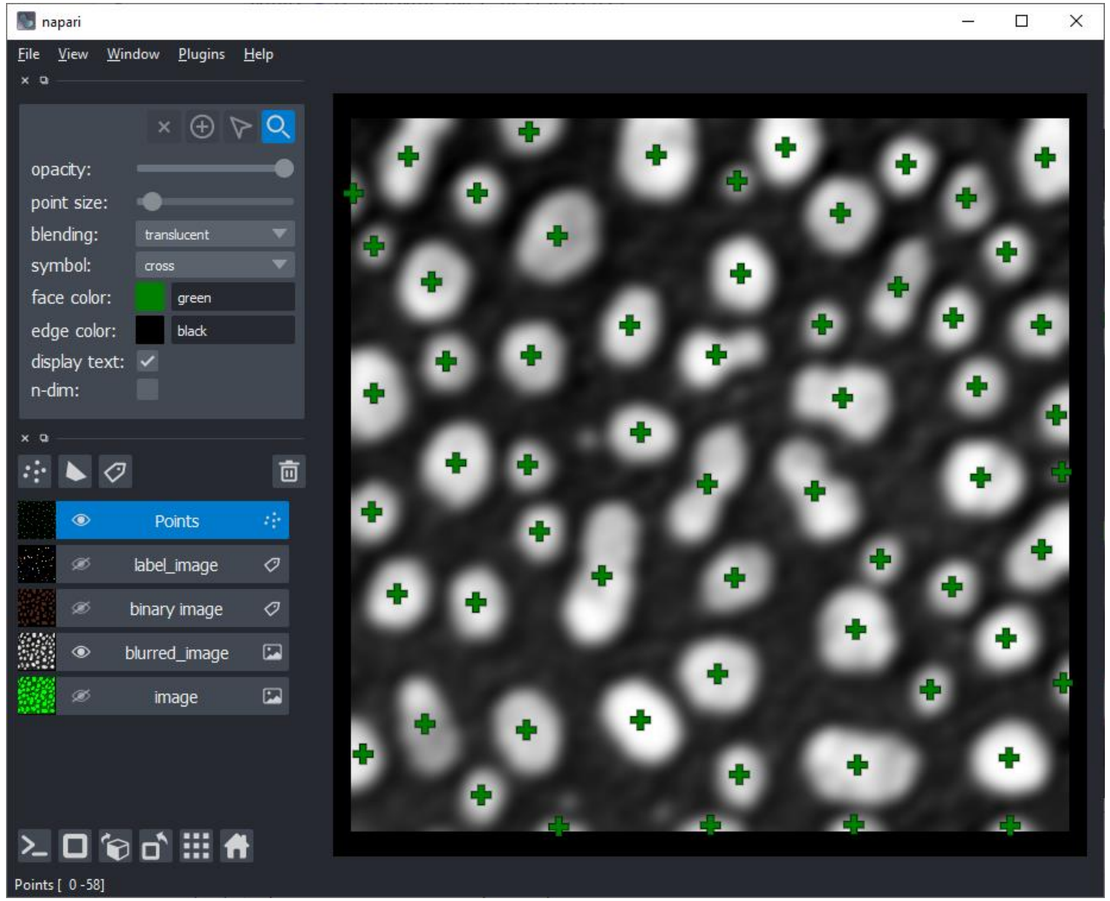
Visualize contours instead of the overlay

```
label_layer.contour = 1
label_layer.opacity = 1
```

Points layers

There is also other layer types

- Shapes
- Points
- Surfaces
- Tracks
- Vectors




```
from skimage.measure import regionprops

statistics = regionprops(label_image)

points = [s.centroid for s in statistics]

# add points to viewer
label_layer = viewer.add_points(points, face_color='green', symbol='cross', size=5)
```

Exercise: Interact with napari from notebook

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1. Open napari viewer and images from notebook and change their viualization

2. Run a 3D segmentation workflow notebook and visualize processing steps in napari. Put workflow inside a Python function.

3. Run a batch processing notebook for the established segmentation workflow