Build kernel, BOOT.bin and image.ub by Petalinux

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Get the .hdf/.xsa file of your development board

If you have the same version board as mine, you can directly use my uploaded file design_1_wrapper.hdf.

If not, you can use Vivado to generate this file, there are many detailed guidance online that you can refer to.

Use Petalinux to create a project

Put the .hdf file in ./ax_peta/linux_base/ to make sure Petalinux could get the hardware description of you board.

source /opt/pkg/petalinux/settings.sh Run this command to set the environment for Petalinux before using it.

```
petalinux-create --type project --template zynq --name ax_peta
cd ax_peta
petalinux-config --get-hw-description ../linux_base.sdk
```

Run petalinux-config to re-configure this project if you need.

Image Packaging Configuration \rightarrow Root filesystem type Choose SD card, and write the correct path of the rootfs, which is mmcblk0p2 in this work.

Then choose Save, and Exit this window, wait for the ending of the generation.

Use Petalinux to configure the kernel

Run petalinux-config -c kernel to begin configure the kernel.

Configure the driver of PHY

```
Device Drivers \rightarrow Network device support \rightarrow PHY Device support and infrastructure then press Y to choose Micrel PHYs
```

Then choose Save and Exit to finish this configuration.

Configure the rootfs

Run petalinux-config -c rootfs , choose Save and Exit , nothing need to be changed in this work.

Compile and generate U-boot, kernel, dtb

Run petalinux-build to compile and generate U-boot, kernel, dtb. This may take about 30min.

Build BOOT.BIN

Run petalinux-package --boot --fsbl ./images/linux/zynq_fsbl.elf --fpga ./images/linux/system.bit --u-boot --force to generate the BOOT.bin file. Make sure you have the needed files in correct path.

At last, the BOOT.bin and image.ub are under the path /images/linux/.