1. UFF

The Person will be seeing a Force og $m_g \cdot g$ which is equal to $m_i \cdot a + F_{scale}$ meaning the Force, the scale and the person interact with. So the Force, the scale sees is $F_{scale} = -m_i \cdot a + m_g \cdot g$

2. energy conservation

The total momentum is given by $p = p_1 + p_2$. This is preserved, if $\frac{\partial p}{\partial t} = 0$:

$$\frac{\partial p_1}{\partial t} = F_{1,2} = -G m_{1,p} m_{2,a} \frac{x_1 - x_2}{|x_1 - x_2|^3}$$
$$\frac{\partial p_2}{\partial t} = F_{2,1} = -G m_{2,p} m_{1,a} \frac{x_2 - x_1}{|x_2 - x_1|^3}$$

So that now we have equivalences:

$$\frac{\partial p}{\partial t} = 0$$

$$\Leftrightarrow F_{1,2} + F_{2,1} = 0$$

$$\Leftrightarrow -G \frac{1}{|x_2 - x_1|^3} (m_{1,p} m_{2,a} (x_1 - x_2) + m_{2,p} m_{1,a} (x_2 - x_1)) = 0$$

$$\Leftrightarrow m_{1,p} m_{2,a} = m_{2,p} m_{1,a}$$

$$\Leftrightarrow \frac{m_{1,p}}{m_{1,a}} = \frac{m_{2,p}}{m_{2,a}}$$

3. gravitational field of a mass distribution

With the definition of M, we have the following:

$$\begin{split} M &:= \lim_{r \to \infty} \left\{ \frac{1}{4\pi G} \int\limits_{S^2(r)} \nabla \phi \cdot \vec{n} \, \mathrm{d}o \right\} \\ &= \lim_{r \to \infty} \left\{ \frac{1}{4\pi G} \int\limits_{B_0(r)} \nabla \nabla \phi \, \mathrm{d}v \right\} \\ &= \lim_{r \to \infty} \left\{ \frac{1}{4\pi G} \int\limits_{B_0(r)} \Delta \phi \, \mathrm{d}v \right\} \\ &= \lim_{r \to \infty} \left\{ \frac{1}{4\pi G} \int\limits_{B_0(r)} 4\pi G \rho \, \mathrm{d}v \right\} \\ &= \lim_{r \to \infty} \left\{ \int\limits_{B_0(r)} \rho \, \mathrm{d}v \right\} \\ &= \int\limits_{\mathbb{R}} \rho \, \mathrm{d}v \end{split}$$

which needed to be shown.

To show the next identity, one just has to write out and use the definitions.

$$\begin{split} f_{a} &= - \, \triangledown^{b} t_{ab} \\ &= - \, \triangledown^{b} \frac{1}{4\pi G} \left(\, \triangledown_{a} \phi \, \, \triangledown_{b} \phi - \frac{1}{2} \delta_{ab} \, \, \triangledown_{c} \phi \, \, \triangledown^{c} \phi \right) \\ &= \frac{1}{4\pi G} \left(\, \nabla^{b} \, \, \triangledown_{a} \Phi \, \, \nabla_{b} \phi + \, \nabla_{a} \phi \, \, \nabla^{b} \, \, \nabla_{b} \phi - \frac{1}{2} \, \, \nabla^{a} \, \, \nabla_{c} \phi \, \, \nabla^{c} \phi - \frac{1}{2} \, \, \nabla_{c} \phi \, \, \nabla_{a} \, \, \nabla^{c} \phi \right) \\ &= \frac{1}{4\pi G} \left(\, \nabla_{a} \phi \, \, \nabla^{b} \, \, \nabla_{b} \phi \right) \\ &= \frac{1}{4\pi G} \left(\, \nabla_{a} \phi \, \, \triangle \phi \right) \\ &= \rho \, \, \nabla_{a} \end{split}$$

the result, as was expected. The tensor t is symmetric, because all tensors in the definition of t are symmetric.

The total force vanishes because of the gaussian integral theorem:

$$\int\limits_{\mathbb{R}} \nabla^b t_{ab} \, \mathrm{d} v = \int\limits_{\partial \mathbb{R}} t_{ab} \, n^b \, \mathrm{d} a = 0$$

Same for the total torque:

$$\int\limits_{\mathbb{R}} \nabla^b t_{ab} x^a \, \mathrm{d} v = \int\limits_{\partial \mathbb{R}} t_{ab} x^a n^b \, \mathrm{d} a = 0$$

where in both cases the point being is, that $\partial \mathbb{R}$, the border of \mathbb{R} is empty.