

tesseract\_collision  
::ConvexDecomposition



```
graph RL; A["tesseract_collision::ConvexDecompositionHACD"] --> B["tesseract_collision::ConvexDecomposition"]; C["tesseract_collision::ConvexDecompositionVHACD"] --> B;
```

The diagram illustrates inheritance relationships between three classes. On the left is a gray-shaded box representing the base class, `tesseract_collision::ConvexDecomposition`. To its right are two white boxes representing derived classes. The top box is `tesseract_collision::ConvexDecompositionHACD` and the bottom box is `tesseract_collision::ConvexDecompositionVHACD`. Blue arrows point from each of these two derived class boxes to the base class box, indicating that both derived classes inherit from the base class.

tesseract\_collision  
::ConvexDecompositionHACD

tesseract\_collision  
::ConvexDecompositionVHACD