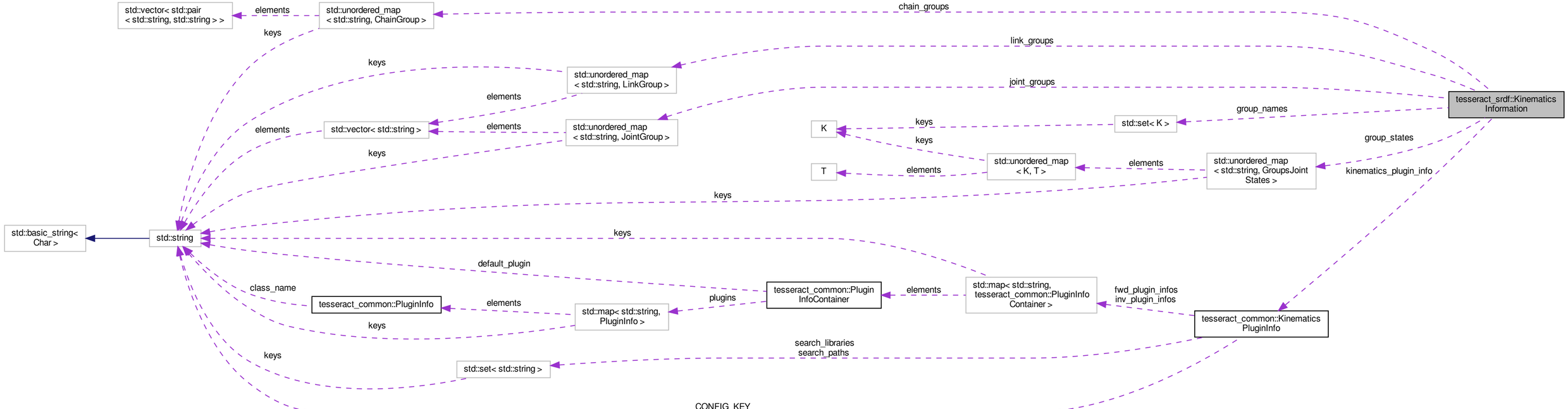
std::vector< std::pair < std::string, std::string > >
elements
std::unordered_map < std::string, ChainGroup >
chain_groups
keys
keys
std::unordered_map < std::string, LinkGroup >
link_groups
elements
joint_groups
elements
std::vector< std::string >
elements
std::unordered_map < std::string, JointGroup >
tesseract_srdf::Kinematics Information
keys
K
keys
std::set< K >
group_names
keys
T
elements
std::unordered_map < K, T >
elements
std::unordered_map < std::string, GroupsJoint States >
group_states
kinematics_plugin_info
keys
std::basic_string< Char >
std::string
keys
default_plugin
class_name
tesseract_common::PluginInfo
elements
std::map< std::string, PluginInfo >
plugins
tesseract_common::Plugin InfoContainer
elements
std::map< std::string, tesseract_common::PluginInfo Container >
fwd_plugin_infos
inv_plugin_infos
tesseract_common::Kinematics PluginInfo
keys
search_libraries
search_paths
keys
std::set< std::string >
CONFIG_KEY