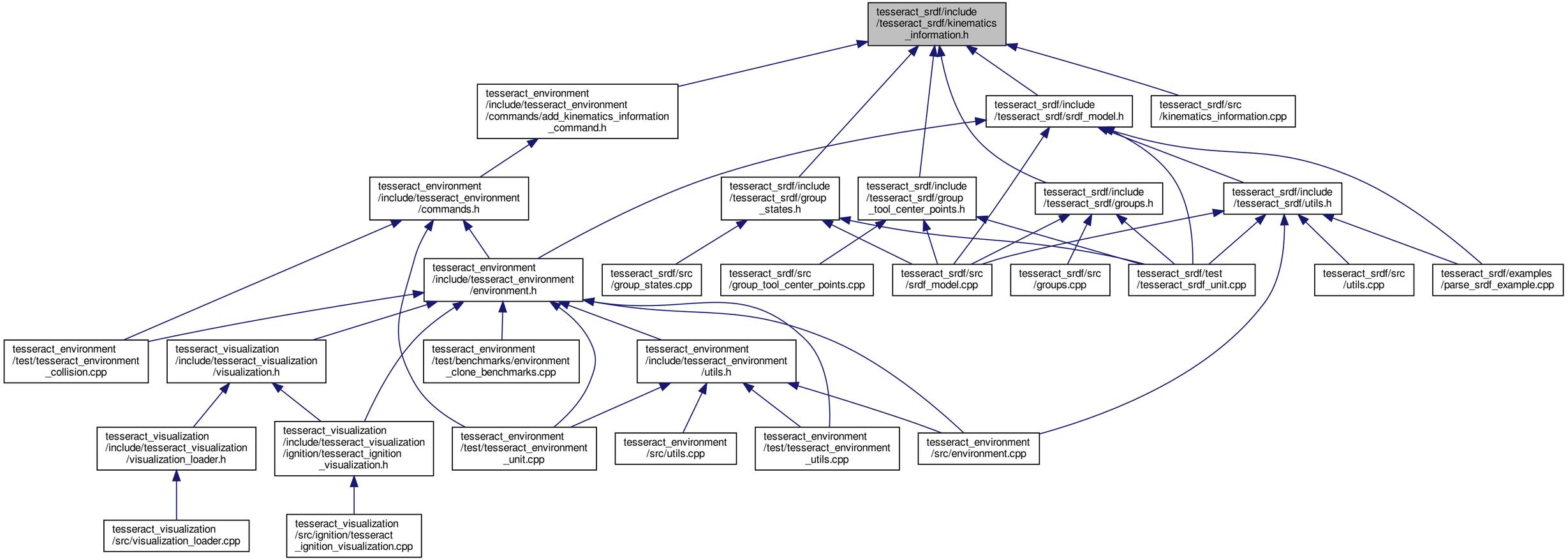
tesseract_srdf/include/tesseract_srdf/kinematics_information.h
tesseract_environment/include/tesseract_environment/commands/add_kinematics_information_command.h
tesseract_srdf/include/tesseract_srdf/srdf_model.h
tesseract_srdf/src/kinematics_information.cpp
tesseract_environment/include/tesseract_environment/commands.h
tesseract_srdf/include/tesseract_srdf/group_states.h
tesseract_srdf/include/tesseract_srdf/group_tool_center_points.h
tesseract_srdf/include/tesseract_srdf/groups.h
tesseract_srdf/include/tesseract_srdf/utils.h
tesseract_environment/include/tesseract_environment/environment.h
tesseract_srdf/src/group_states.cpp
tesseract_srdf/src/group_tool_center_points.cpp
tesseract_srdf/src/srdf_model.cpp
tesseract_srdf/src/groups.cpp
tesseract_srdf/test/tesseract_srdf_unit.cpp
tesseract_srdf/src/utils.cpp
tesseract_srdf/examples/parse_srdf_example.cpp
tesseract_environment/test/tesseract_environment_collision.cpp
tesseract_visualization/include/tesseract_visualization/visualization.h
tesseract_environment/test/benchmarks/environment_clone_benchmarks.cpp
tesseract_environment/include/tesseract_environment/utils.h
tesseract_visualization/include/tesseract_visualization/visualization_loader.h
tesseract_visualization/include/tesseract_visualization/ignition/tesseract_ignition_visualization.h
tesseract_environment/test/tesseract_environment_unit.cpp
tesseract_environment/src/utils.cpp
tesseract_environment/test/tesseract_environment_utils.cpp
tesseract_environment/src/environment.cpp
tesseract_visualization/src/visualization_loader.cpp
tesseract_visualization/src/ignition/tesseract_ignition_visualization.cpp