

tesseract_collision
/bullet/include/tesseract
_collision/bullet/tesseract
_convex_convex_algorithm.h

```
graph BT; A["tesseract_collision  
/bullet/src/tesseract  
_collision_configuration.cpp"] --> C["tesseract_collision  
/bullet/include/tesseract  
_collision/bullet/tesseract  
_convex_convex_algorithm.h"]; B["tesseract_collision  
/bullet/src/tesseract  
_convex_convex_algorithm.cpp"] --> C;
```

The diagram illustrates a file dependency structure. At the top is a header file box. Below it are two source file boxes. Blue arrows point from each source file box up to the header file box, indicating that both source files include the header.

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/bullet/src/tesseract
_collision_configuration.cpp

tesseract_collision
/bullet/src/tesseract
_convex_convex_algorithm.cpp