

tesseract_environment
::Command



```
graph BT; A[tesseract_environment::ChangeLinkVisibilityCommand] --> B[tesseract_environment::Command];
```

The diagram consists of two rectangular boxes. The top box is white with a black border and contains the text 'tesseract_environment' followed by '::Command' on the next line. The bottom box is gray with a black border and contains the text 'tesseract_environment' followed by '::ChangeLinkVisibilityCommand' on the next line. A blue arrow points vertically from the top center of the bottom box to the bottom center of the top box, indicating an inheritance or specialization relationship.

tesseract_environment
::ChangeLinkVisibilityCommand