

tesseract_collision
::ConvexDecomposition

```
graph RL; A["tesseract_collision::ConvexDecompositionHACD"] --> B["tesseract_collision::ConvexDecomposition"]; C["tesseract_collision::ConvexDecompositionVHACD"] --> B;
```

The diagram illustrates inheritance relationships between three C++ namespaces. On the left is a gray-shaded box representing the base namespace: `tesseract_collision::ConvexDecomposition`. To its right are two white boxes representing derived namespaces. The top box is `tesseract_collision::ConvexDecompositionHACD` and the bottom box is `tesseract_collision::ConvexDecompositionVHACD`. Blue arrows point from each of these two derived boxes to the base box, indicating that both derived namespaces inherit from the base namespace.

tesseract_collision
::ConvexDecompositionHACD

tesseract_collision
::ConvexDecompositionVHACD