

tesseract\_environment  
::Command



```
graph BT; A[tesseract_environment::ChangeCollisionMarginsCommand] --> B[tesseract_environment::Command];
```

The diagram illustrates a class hierarchy. At the bottom is a gray-shaded box containing the text 'tesseract\_environment::ChangeCollisionMarginsCommand'. A blue arrow points vertically upwards from the top center of this box to the bottom center of a white box above it. The white box contains the text 'tesseract\_environment::Command'.

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::ChangeCollisionMarginsCommand